

**Amrita Vishwa Vidyapeetham**  
**Amrita School of Computing, Bangalore**  
**Department of Computer Science and Engineering**

**19CSE303 Embedded Systems**  
**Lab Worksheet - 7**  
**Analog to Digital Convertor**

**Exercise Problems**

1. Write a ARM embedded C program configure the AD0.1 to read analog voltage and record the latest converted digital value in a variable “dig” .

```
#include "lpc_2148.h"
#include "adc.h"

void init_adc0(void)
{
    // PINSEL1 = (PINSEL1 & ~(1 << 24)) | (1 << 24);    //select channel1 of AD0
    PINSEL1 = 0x01000000;
}

int adc_read(void)
{
    int i;
    AD0CR = 0x00200400 | (1<<1) ;    // select channel
    AD0CR |= 0x01000000; // Start A/D Conversion
    while ((AD0STAT & 0x00010002) == 0); // Wait for end of A/D Conversion
    i = AD0DR1; // Read A/D Data Register
    return i;
}

main() {
    int dig = 0;
    init_adc0();
    IODIR0 = 0x00FF0000;    /* P1.16..23 defined as
Outputs */
    while(1)
    {
        dig = adc_read();
        dig &= 0x0000ffff    ;

    }
}
```

2. Write a ARM embedded C program to control the multi LED array using analog controller.

Assume the analog controller is connected to AD0.6 and an 8 array LED is connected to P0.16 to P0.23. The control is based on analog controller voltage level

voltage is 0V to 1V = P0.16 and P0.17 LED's ON

voltage is 1.1V to 2V = P0.16 and P0.19 LED's ON

voltage is 2.1V to 2.5V = P0.16 and P0.21 LED's ON

voltage is 2.6V to 3V = P0.16 and P0.23 LED's ON

```
#include "lpc_2148.h"
#include "adc.h"
void init_adc0(void)
{
    PINSEL0 |= 0x3 << 8;           //select channel6 of AD0
}

int adc_read(void)
{
    int i;
    AD0CR = 0x00200400 | (1<<6); // select channel
    AD0CR |= 0x01000000; // Start A/D Conversion
    while ((AD0STAT & 0x00010002) == 0); // Wait for end of A/D Conversion
    i = AD0DR6; // Read A/D Data Register
    return i;
}

main() {
    int dig = 0;
    init_adc0();
    IODIR0 = 0x00FF0000;           /* P0.16..23 defined as Outputs */
    while(1)
    {
        dig = adc_read();
        dig &= 0x0000ffff;
        if(dig >= 0x00000000 && dig<=0x00004d80)
        {
            IOCLR0 |= 0x00ff0000;
            IOSET0 |= 0x00030000;
        }
        else if(dig >= 0x00004d81 && dig<=0x00009b00)
        {
            IOCLR0 |= 0x00ff0000;
            IOSET0 |= 0x000f0000;
        }
        else if(dig >= 0x00009b01 && dig<=0x0000c1c0)
        {
            IOCLR0 |= 0x00ff0000;
            IOSET0 |= 0x003f0000;
        }
        else if(dig >= 0x0000c1c1 && dig<=0x0000e880)
        {
            IOCLR0 |= 0x00ff0000;
            IOSET0 |= 0x00ff0000;
        }
        else
            IOCLR0 |= 0x00ff0000;
    }
}
```

### **Assignment Problem**

1. Write an ARM embedded C program to control the LED on/off delay time using Analog controller. Assume the LED is connected in P1.16 and analog controller is connected to AD1.1.