

# **Applied Deep Learning**

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#### Learning objectives of today

**Goals:** Creating neural networks – from logistic regression to feed-forward networks

- Use what we have learned about linear algebra and calculus to create a logistic regression algorithm from scratch
- Understand how what we learned generalizes to neural networks in general

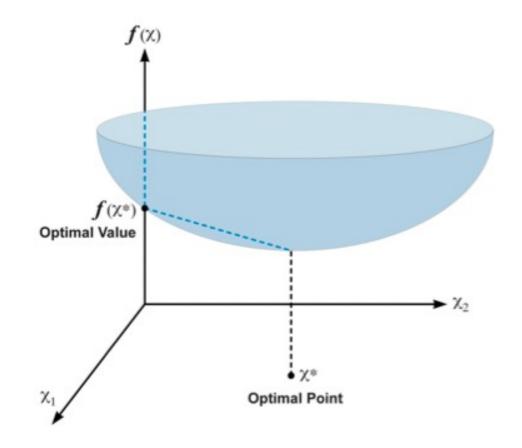
#### How will we do this?

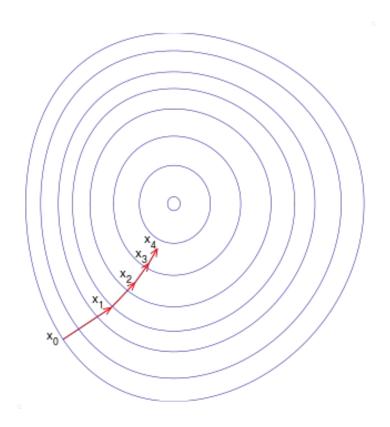
- We discuss the implementation of a logistic regression algorithm with numpy only
- Next, we visualize more general neural networks with the TensorFlow playground, before defining the concepts relevant for running our own networks
- In the tutorial, we will implement more complex networks



Recap – logistic regression

# **Gradient descent – the idea**







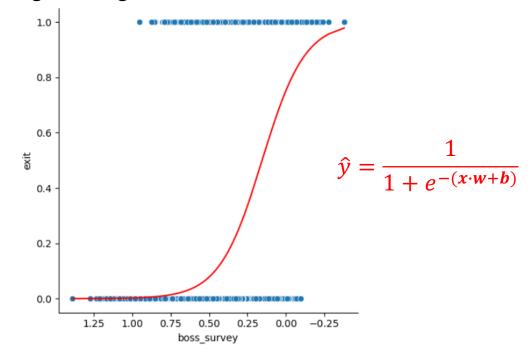
# What do we actually do when training a logistic regression model?

- We are given values  $(x^{(i)}, y^{(i)})$ , where  $x^{(i)} \in \mathbb{R}^m$  and  $y^{(i)} \in \{0,1\}$
- Our prediction  $\hat{y}^{(i)}$  should reflect the probability that  $y^{(i)} = 1$ :  $\hat{y}^{(i)} = P(y^{(i)} = 1 | x^{(i)})$
- We model this probability, using the sigmoid function:



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## The optimization part

- Remember that  $w \in \mathbb{R}^m$  and  $b \in \mathbb{R}$
- To get to the "right" model, we optimize our parameters w, b so that the  $\hat{y}^{(i)}$ s are "as close as possible" to the  $y^i$ s
- What we do is to minimize the "cost-function" J(w, b), where  $\hat{y}^{(i)} = \frac{1}{1 + e^{-(x^{(i)}w + b)}}$ :

$$J(\mathbf{w}, b) = -\frac{1}{n} \sum_{i=1}^{n} \left[ y^{(i)} \ln \hat{y}^{(i)} + (1 - y^{(i)}) \ln (1 - \hat{y}^{(i)}) \right]$$

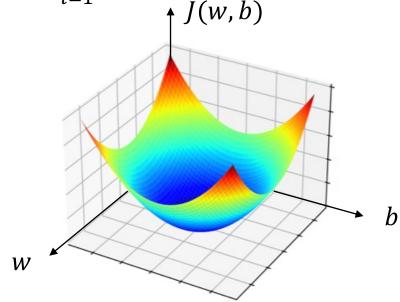


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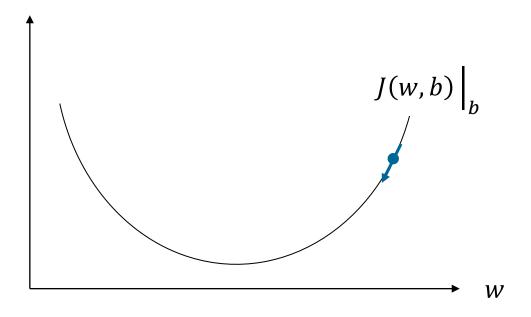
$$J(\mathbf{w}, b) = -\frac{1}{n} \sum_{i=1}^{n} \left[ y^{(i)} \ln \hat{y}^{(i)} + (1 - y^{(i)}) \ln(1 - \hat{y}^{(i)}) \right]$$

$$\uparrow J(\mathbf{w}, b)$$





# Solving the optimization problem through gradient descent





# Our first optimization algorithm

- Decide a "learning rate"  $\alpha$
- Start with some w and b and compute I(w, b)
- Until *J* "doesn't change" anymore:
  - Let  $w_1$ : =  $w_1 \alpha \frac{\partial J(w,b)}{\partial w_1}$ Let  $w_2$ : =  $w_2 \alpha \frac{\partial J(w,b)}{\partial w_2}$

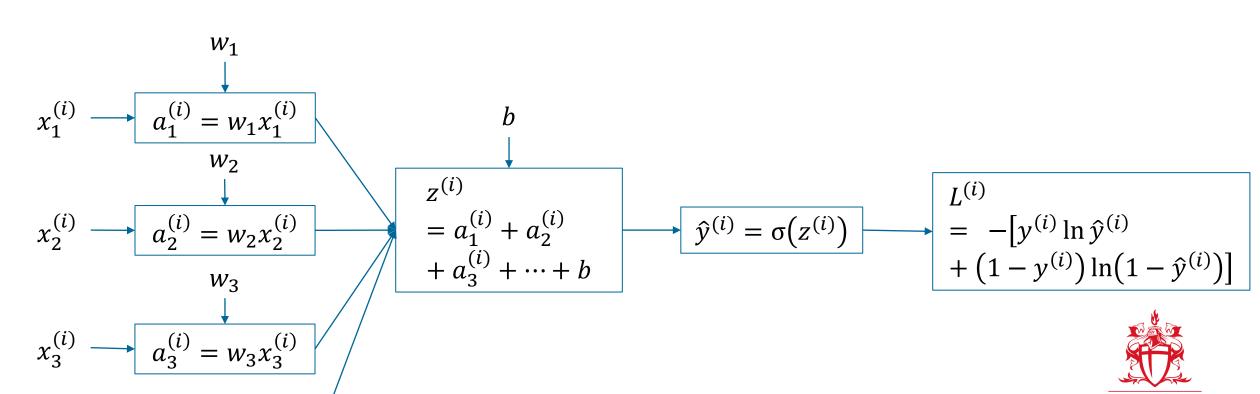
  - Let  $w_m$ : =  $w_m \alpha \frac{\partial J(w,b)}{\partial w_m}$ Let b: =  $b \alpha \frac{\partial J(w,b)}{\partial b}$

  - Recompute I(w, b)
- Enjoy the fruits of your labor: you have fit a logistic regression model manually!



#### Wait a second, how do we find all those derivatives?

- We can use again the computation graph!
- Recall that  $\hat{y}^{(i)} = \frac{1}{1+e^{-\left(x^{(i)}w+b\right)}} = \sigma\left(x^{(i)}w+b\right)$



# As the same parameters influence all examples, we have to consider one final step

• Recall that 
$$J(\mathbf{w}, b) = -\frac{1}{n} \sum_{i=1}^{n} \left[ y^{(i)} \ln \hat{y}^{(i)} + \left( 1 - y^{(i)} \right) \ln \left( 1 - \hat{y}^{(i)} \right) \right] = \frac{1}{n} \sum_{i=1}^{n} L^{(i)}$$

• We have that 
$$\frac{\partial J(w,b)}{\partial w_j} = \frac{1}{n} \sum_{i=1}^n \frac{\partial L^{(i)}}{\partial w_j}$$



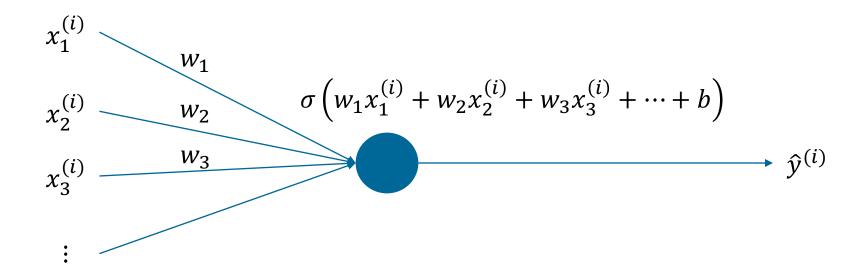
# We can now implement a logistic regression





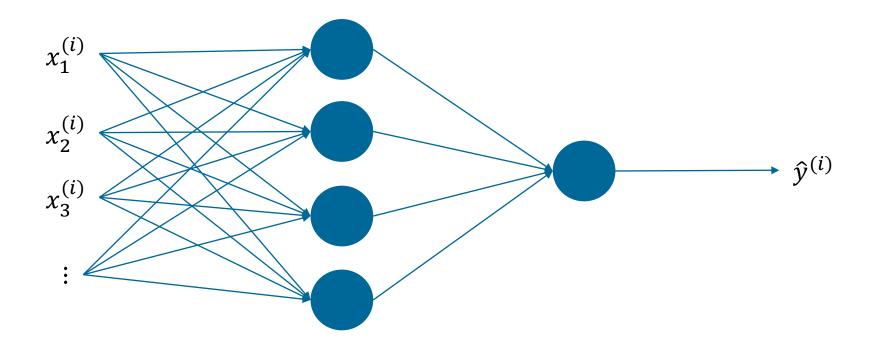
From logistic regression to neural network

# Schema of a logistic regression



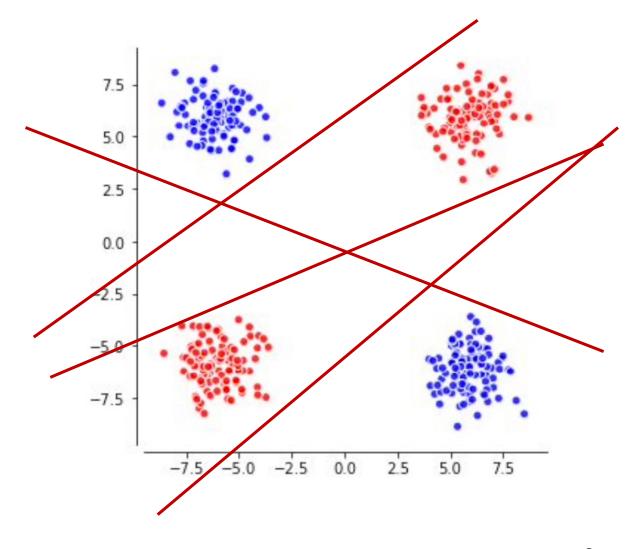


# Putting multiple neurons together





#### What neurons learn





## Training neural networks visually

#### Open <a href="https://playground.tensorflow.org/">https://playground.tensorflow.org/</a>

- 1. A simple case of binary classification:
  - Change to the pattern on the lower left
  - Set the level of "Noise" to 50
  - Set "Ratio of training to test data" to 50%
- Set up the neural network: 1 hidden layer, 1 neuron, then press play
- Answer the following questions:
  - Did the training eventually find a model that seems to capture the pattern in the data?
- How would you describe the pattern the model captured?
- Record the "Training loss" and "Test loss"
- How do your answers change when you select the pattern at the top right? What about setting the noise to 0?

## Training neural networks visually

#### 2. A shallow neural network:

- Stick with the pattern at the top right, a noise of 0 and a ratio of 50%
- Now use 3 neurons for your hidden layer
- Answer the three questions from before:
  - Did the training eventually find a model that seems to capture the pattern in the data?
  - How would you describe the pattern the model captured?
- Record the "Training loss" and "Test loss"
- How do your answers change when you use 6 neurons instead?

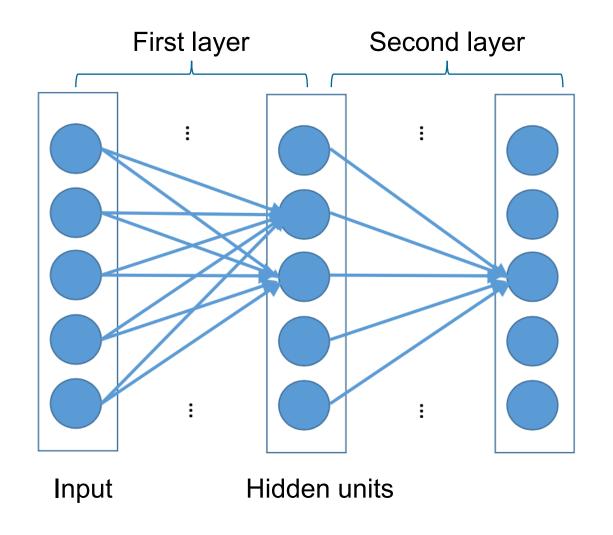
#### 3. A deep neural network:

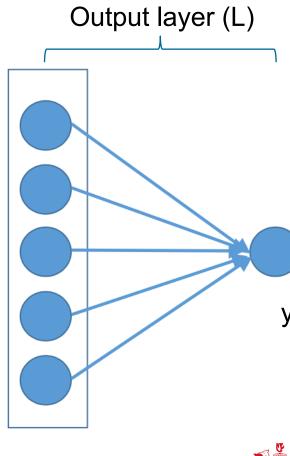
- Use a second hidden layer, with 3 neurons each (and the other setups from 2.)
- How do your answers change now?



Key components of a neural network

# Components



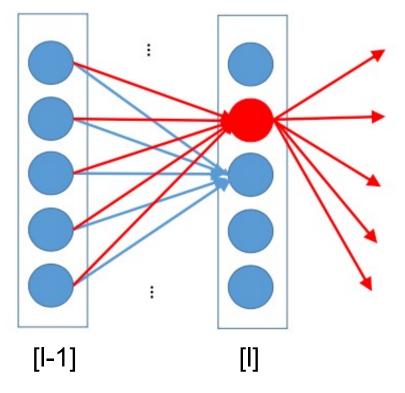




Source: Liang

# **Hidden layers**

"
$$x$$
" =  $a^{[l-1]}$   $z = a^{[l-1]}w + b$   $f(z)$ 

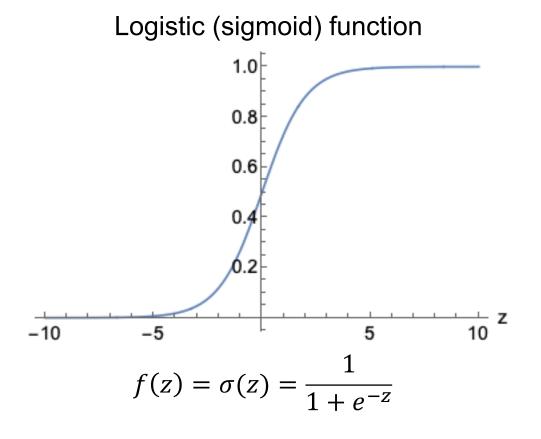


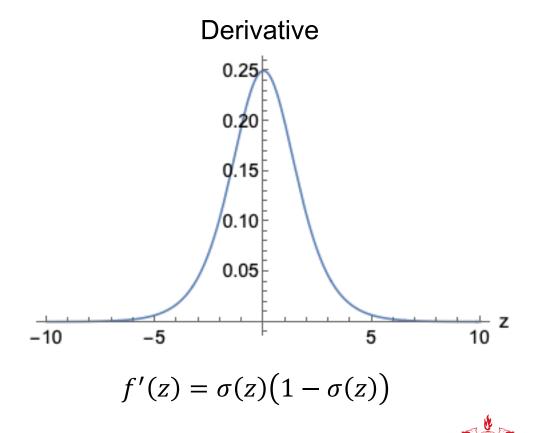
- *f* is what we call an "activation function"
- There are many activation functions, and new ones are invented all the time
- Many of these functions do just fine, or slightly better than existing ones



Source: Liang

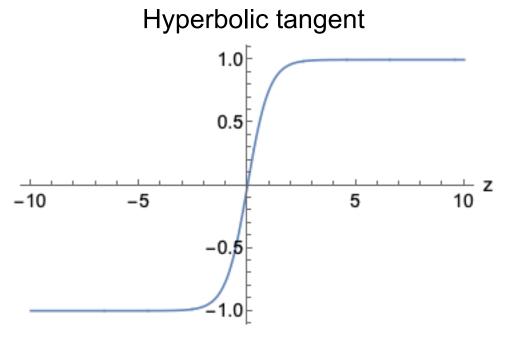
# Typical activation functions: logistic (sigmoid) function



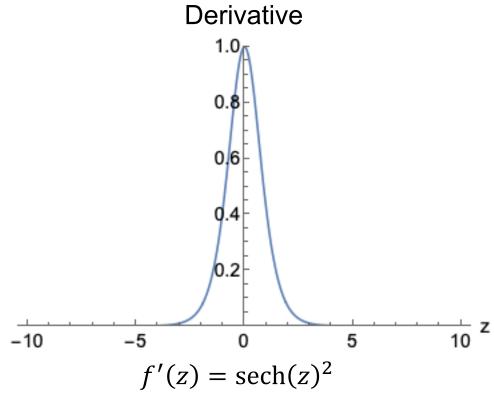


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# Typical activation functions: hyperbolic tangent

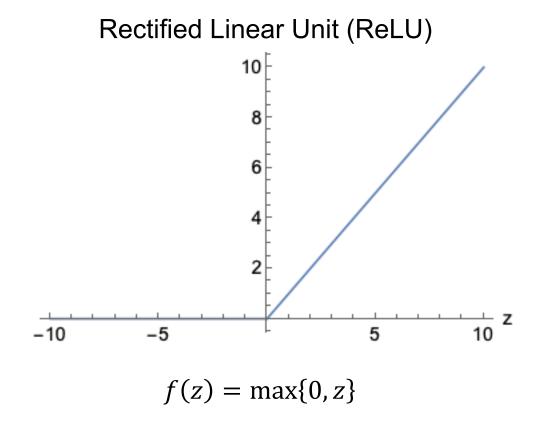


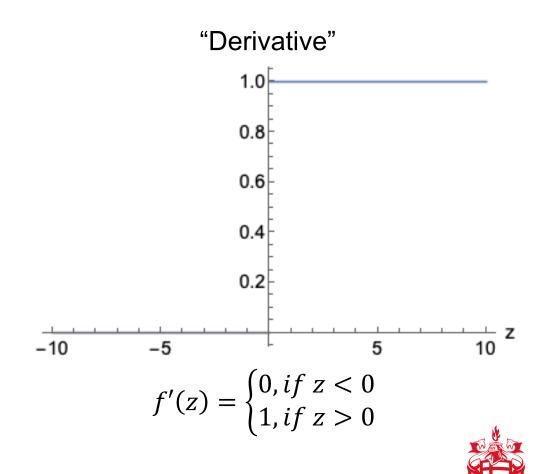
$$f(z) = \tanh(z) = \frac{e^{2z} - 1}{e^{2z} + 1}$$





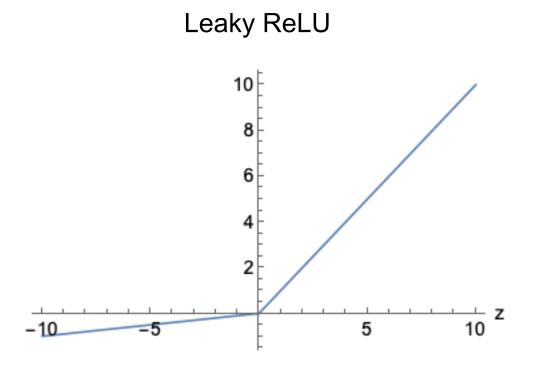
# **Typical activation functions: Rectified Linear Unit**



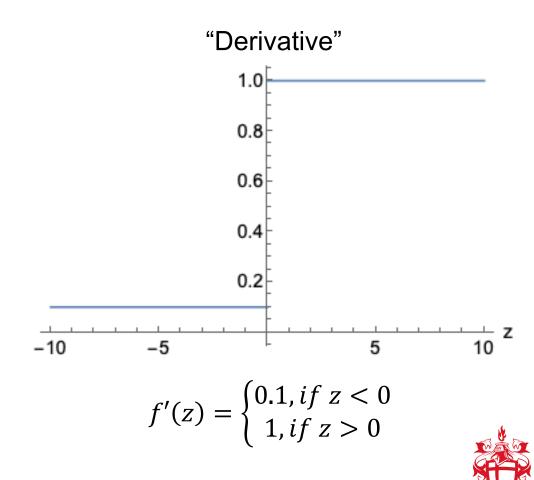


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# Typical activation functions: Leaky ReLU



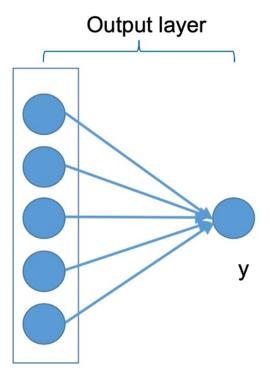
$$f(z) = \max\{0.1z, z\}$$



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# **Binary classification**

- Input:  $a^{[L-1](i)}$
- As usual, we make a linear transformation:  $z^{[L](i)} = a^{[L-1](i)} w^{[L]} + b^{[L]}$
- We then use the logistic sigmoid function  $\hat{y}^{(i)} = f(z^{[L](i)}) = \sigma(z^{[L](i)}) = \frac{1}{1 + e^{-z^{[L](i)}}}$
- We can interpret the output as the probability of  $y^{(i)} = 1$



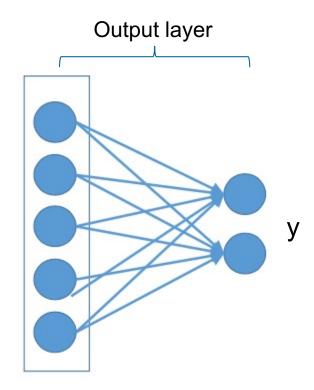


#### **Multi-class classification**

- We again make a linear transformation with a matrix of weights:  $\mathbf{z}^{[L](i)} = \mathbf{a}^{[L-1](i)} \mathbf{W}^{[L]} + \mathbf{b}^{[L]}$
- Note that  $\mathbf{z}^{[L](i)} = \begin{pmatrix} z_1^{[L](i)} & z_2^{[L](i)} & \cdots & z_K^{[L](i)} \end{pmatrix}$
- We then use the softmax function on each of the outputs:

$$\hat{y}_k^{(i)} = f(\mathbf{z}^{[L](i)}) = \frac{e^{-z_k^{[L](i)}}}{\sum_{k=1}^K e^{-z_k^{[L](i)}}}$$

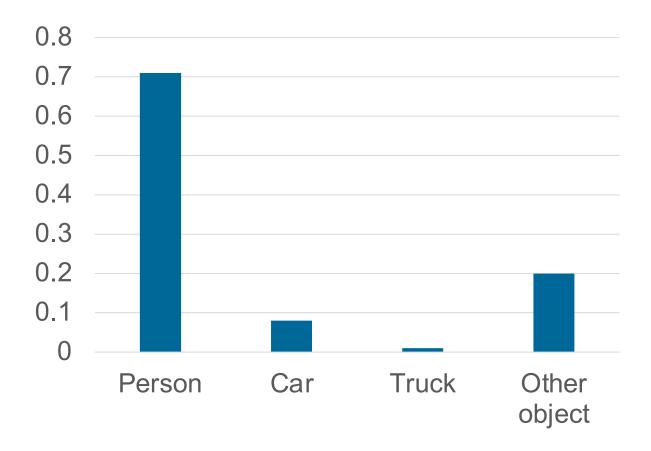
- This implies that  $\hat{y}_k^{(i)} \in (0,1)$  and  $\sum_{k=1}^K \hat{y}_k^{(i)} = 1$
- Hence, we can interpret  $\hat{y}_k^{(i)}$  as the probability that  $y^{(i)} = k$  ("belongs to class k")





## **Softmax output**

• E.g., when performing object recognition, we might represent our prediction  $\widehat{m{y}}^{(i)}$  as





#### **Cost functions**

Recall from logistic regression:

$$J(\mathbf{w}, b) = \frac{1}{n} \sum_{i=1}^{n} L^{(i)} = -\frac{1}{n} \sum_{i=1}^{n} \left[ y^{(i)} \ln \hat{y}^{(i)} + (1 - y^{(i)}) \ln (1 - \hat{y}^{(i)}) \right]$$

• Generally, to learn parameters  $\theta$ , we define the cross-entropy

$$J(\boldsymbol{\theta}) = \frac{1}{n} \sum_{i=1}^{n} L^{(i)} = -\frac{1}{n} \sum_{i=1}^{n} \ln p_{\boldsymbol{\theta}} (y^{(i)} | \boldsymbol{x}^{(i)})$$

- Also known as "maximum likelihood estimator"
- Mean square error tends to perform poorly, especially when we have activation functions with  $e^z$



Learning with gradient descent

## Generalizing our optimization algorithm

- Decide a "learning rate"  $\alpha$
- Start with some parameters  $\theta$  and compute  $J(\theta)$ (forward propagation)
- Until *J* "doesn't change" anymore:
  - Let  $\theta := \theta \alpha \nabla_{\theta} J(\theta)$
  - Recompute  $J(\theta)$

(back-propagation)

(forward propagation)

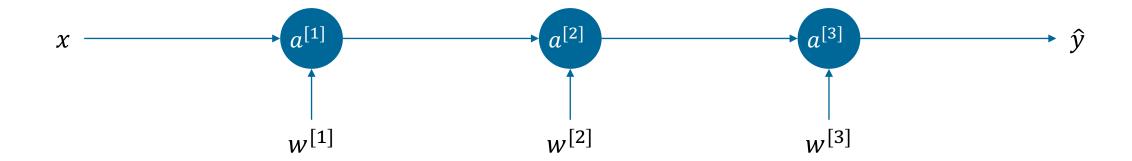


## **Initializing parameters**

- Initialize weights to small random values (e.g., np.random.randn(shape of W) \* 0.01)
- Bias terms can be initialized randomly, but can also just be initialized to zero (e.g., np.zeros(shape of b))

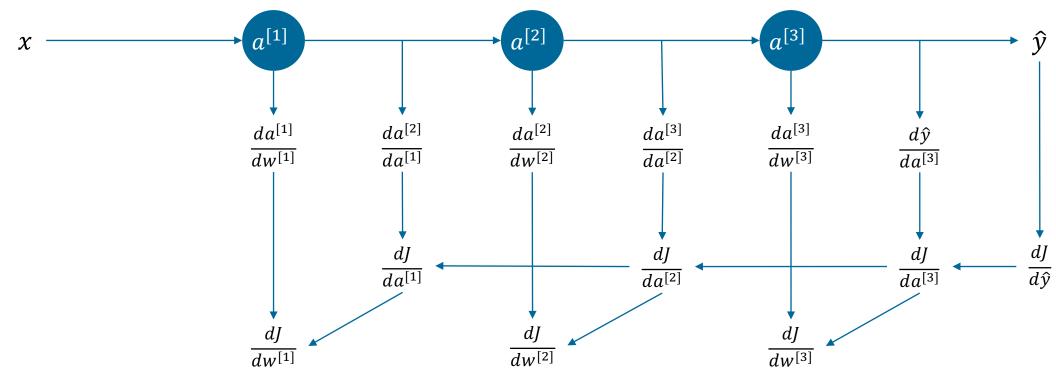


# Step 1: Forward propagation through the computational graph



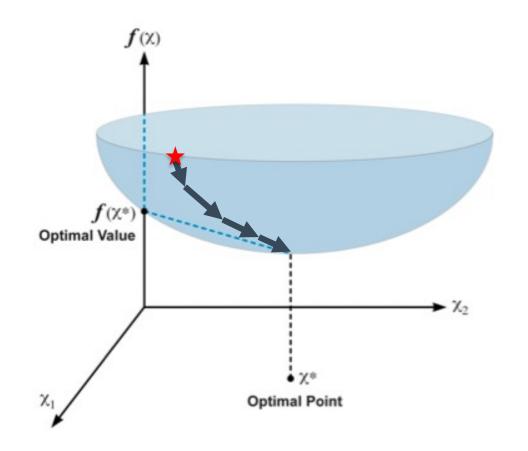


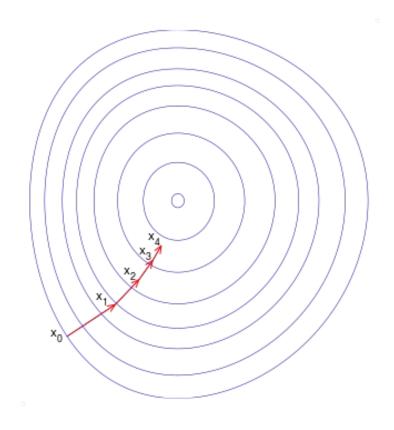
# Step 2: Back-propagation through the computational graph





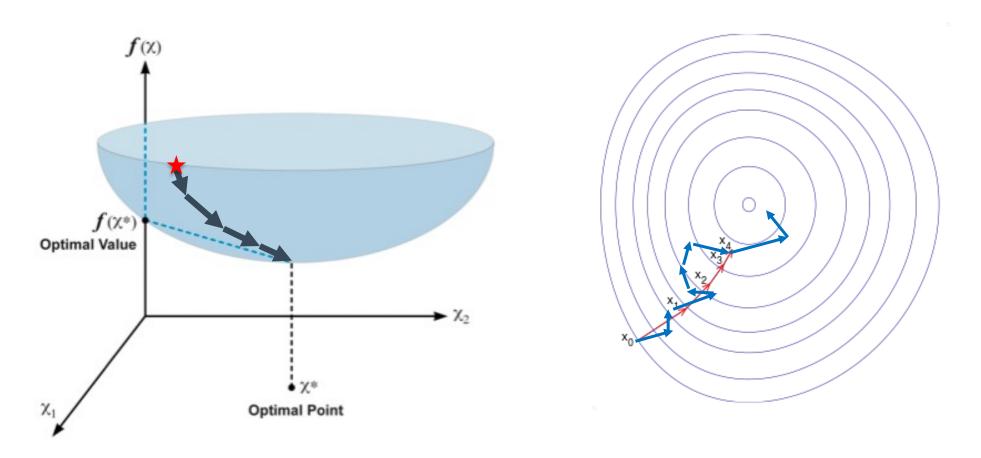
#### **Gradient descent**







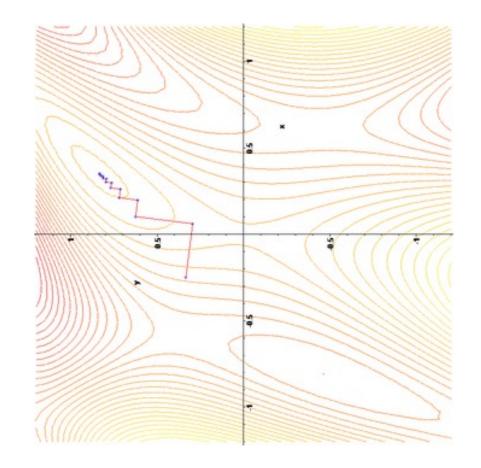
## Stochastic gradient descent: computing the gradient only for one observation

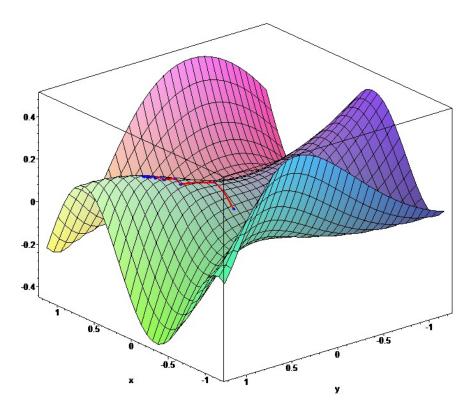


→ No matter which approach, when the function is convex, we will find a global minimum



# Pathological non-convex cases





(gradient ascend)





#### Sources

- Collins, 2012, Intensity Surfaces and Gradients:
   <a href="http://www.cse.psu.edu/~rtc12/CSE486/lecture02\_6pp.pdf">http://www.cse.psu.edu/~rtc12/CSE486/lecture02\_6pp.pdf</a>
- Goodfellow, Bengio, Courville, 2016, The Deep Learning Book: <a href="http://www.deeplearningbook.org">http://www.deeplearningbook.org</a>
- Liang, 2016, Introduction to Deep Learning: <a href="https://www.cs.princeton.edu/courses/archive/spring16/cos495/">https://www.cs.princeton.edu/courses/archive/spring16/cos495/</a>
- Wikipedia, n.d., Gradient ascent: <u>https://en.wikipedia.org/wiki/File:Gradient\_ascent\_(surface).png</u>

