

Review for heat equation.

Physical meaning.

(Assume $x \in \Omega$, $\partial\Omega$ is C^1 ...)

Consider $U(t, x)$, which represents something like energy at space x , time t .
And here, we can take $\int_{\Omega} U(t, x) dx$ as the whole energy.

$\Rightarrow \frac{d}{dt} \int_{\Omega} U(t, x) dx$ is the change of energy w.r.t. time.

And let $J(t, x)$ be the energy flux.

$$\Rightarrow \frac{d}{dt} \int_{\Omega} U(t, x) dx = - \int_{\partial\Omega} J(t, x) \cdot n ds = - \int_{\partial\Omega} \nabla U \cdot n ds$$

$$\text{Sometimes } J(x, t) = -k \nabla U(t, x), \Rightarrow \boxed{\text{?}}$$

Three kind of boundary condition

① $U|_{\partial\Omega} = \nu$ (Dirichlet).

(Here, assume $U_t = \alpha^2 \Delta U$
's $\alpha=1$, otherwise, $v(t, x) = U(t, \alpha x)$).

② $\frac{\partial U}{\partial n}|_{\partial\Omega} = \nu$ (Neumann)

③ $-k \frac{\partial U}{\partial n}|_{\partial\Omega} = H(U - \nu)|_{\partial\Omega}$ (Mixed)

I) Classical solution is unique:

$$\begin{cases} U_t = \Delta U + f \\ U(0, x) = \varphi(x) \end{cases}$$

$$\Leftrightarrow \begin{cases} U_t = \Delta U \\ U(0, x) = 0 \end{cases}$$

$U|_{\partial\Omega} = b$ dry condition. $U|_{\partial\Omega} = \text{homogeneous dry condition}$

classical.

only has \checkmark solution Q

Proof: Consider $e(t) = \frac{1}{2} \int_{\Omega} U^2(t, x) dx$, $e(0) = 0$

$$\Rightarrow e'(t) = \int_{\Omega} U(t, x) U_t(t, x) dx$$

$$= \int_{\Omega} U(t, x) \Delta U dx$$

$$= \int_{\partial\Omega} U \frac{\partial U}{\partial n} ds - \int_{\Omega} |\nabla U(t, x)|^2 dx$$

≤ 0

II. To give a way to deduce a solution, on \mathbb{R}^d .

It's natural to review some Fourier transform.

- $(f * g)^\wedge = \hat{f} \hat{g}$
- $\int f \bar{g} = \int f \hat{g}$ } First holds for $L^1(\mathbb{R}^d)$, other condition need some additional knowledge.
- If $f, \hat{f} \in L^1 \Rightarrow f = (\hat{f})^\vee$. (inversion formula).
- For $f \in C_c^\infty(\mathbb{R}^d)$, $(D^\alpha f)^\wedge = (2\pi i)^{|\alpha|} \varepsilon^\alpha \hat{f}$
(Just integration by parts)

$$\text{Now, } \begin{cases} U_t = \Delta U \\ U(0, x) = \phi(x) \end{cases} \Rightarrow \begin{cases} \hat{U}_t = -4\pi^2 \varepsilon^2 \hat{U} \\ \hat{U}(0, \varepsilon) = \hat{\phi}(\varepsilon) \end{cases}$$

$$\Rightarrow \hat{U}(\varepsilon) = e^{-4\pi^2 \varepsilon^2 t} \hat{\phi}(\varepsilon)$$

$$\text{So } (?)^\wedge = e^{-4\pi^2 \varepsilon^2 t}$$

By residue formula, one can show that in \mathbb{R}^d

$$\left(\frac{1}{(\sqrt{4\pi t})^d} e^{-\frac{|x|^2}{4t}} \right)^\wedge = e^{-4\pi^2 \varepsilon^2 t}$$

supposed to be

$$\text{Set } G_t(x) = \frac{1}{(\sqrt{4\pi t})^d} e^{-\frac{|x|^2}{4t}} \Rightarrow U(t, x) = G_t(x) * \phi(x)$$

(Thm): Consider on \mathbb{R}^d .

$$\begin{cases} U_t = \Delta U, t > 0, x \in \mathbb{R}^d \\ U(0, x) = \phi(x), \end{cases}, \phi \in C(\mathbb{R}^d) \cap L^\infty(\mathbb{R}^d)$$

$$\textcircled{1} \quad U(t, x) = G_t * \phi \in C^\infty((0, \infty) \times \mathbb{R}^d), U_t = \Delta U$$

$$\textcircled{2} \quad \lim_{t \rightarrow 0, x \rightarrow (0, x_0)} U(t, x) = \phi(x_0), x_0 \in \mathbb{R}^d.$$

Pf: Lemma: $f, g \in L^1(\mathbb{R}^d)$, $\partial_x f \in C(\mathbb{R}^d) \cap L^1(\mathbb{R}^d) \cap L^\infty(\mathbb{R}^d)$

Then $\partial_x(g * f) = g * \partial_x f$.

Lemma's pf: Consider $\frac{1}{h} \int (f(x-y+hei) - f(x-y)) g(y) dy$

From DCT: $h \rightarrow 0$, dominated by $2 \|\partial_x f\|_{L^\infty} g(y) \dots \Rightarrow \square$

So by this, we can just transform U_t, U_{xixi} to G_t, G_{xixi} :
 $\partial_t(G_t * \varphi) = G_t * \varphi, \dots \Rightarrow C^\infty$ and satisfies ①.

For the initial condition. Consider (Approximation identity).

(Lemma) $k_n(x)$ non-negative cts, s.t

$$① \int_{\mathbb{R}^d} k_n(x) dx = 1 \quad ② \forall \varepsilon > 0, \lim_{n \rightarrow \infty} \int_{|x| \geq \varepsilon} k_n(x) dx = 0.$$

Then $\forall g(x)$ is continuous^{new} and. bdd

$$\lim_{n \rightarrow \infty} \int_{\mathbb{R}^d} k_n(x) g(x) = g(0) = \int g(x) f(x) dx$$

Lemma's pf: consider $|\int_{\mathbb{R}^d} k_n(x) (g(x) - g(0))|$

$$\leq \int_{|x| \leq \varepsilon} |k_n(x)| |g(x) - g(0)| + \int_{|x| \geq \varepsilon} k_n(x) |g(x) - g(0)| \dots$$

Leverage g is cts

Leverage g is bdd.

From the Lemma, as $t \rightarrow 0$, we can take $G_t(x)$ as an approximation identity.

On \mathbb{R}^d , there exists non-homogeneous condition

$$\begin{cases} \partial_t u = \Delta u + f \\ u|_{t=0} = 0 \end{cases} \quad \textcircled{A}$$

Duhamel principle Let $f \in C^{1,2}([0,\infty) \times \mathbb{R}^d) \cap C_c([0,\infty) \times \mathbb{R}^d)$

$$U(t,x) = \int_0^t \int_{\mathbb{R}^d} G_{t-s}(x-y) f(s,y) dy ds \text{ solves } \textcircled{A}$$

(初值依赖于 f).

III) On bounded domain, the story is different.

Before introducing further, let's consider the Sturm-Liouville boundary problem:

$$\begin{cases} -\Delta u = \lambda u, & \text{in } \Omega \\ \alpha u + \beta \frac{\partial u}{\partial n} = 0, & \text{on } \partial\Omega, \alpha, \beta \geq 0, \alpha + \beta > 0 \end{cases} \Rightarrow (\lambda, u) \text{ is called an eigenpair.}$$

(Here, α, β can be changed to $\alpha(x), x \in \partial\Omega$ and $\beta(x), x \in \partial\Omega$)

We have:

① If $(\lambda_1, u_1), (\lambda_2, v)$ are eigenpairs, then we have:

$$\begin{aligned} \int_{\Omega} uv dx &= - \int_{\partial\Omega} \frac{\partial u}{\partial n} v dS + \int_{\Omega} \nabla u \cdot \nabla v dx \\ &= - \int_{\partial\Omega} \frac{\partial v}{\partial n} u dS + \int_{\Omega} \nabla u \cdot \nabla v dx = \int_{\Omega} -uv dx \\ \left(\begin{matrix} u \\ v \end{matrix} \right) \left(\begin{matrix} \frac{\partial u}{\partial n} \\ \frac{\partial v}{\partial n} \end{matrix} \right) = 0 \Rightarrow u \frac{\partial v}{\partial n} - v \frac{\partial u}{\partial n} = 0 \end{aligned}$$

② Each eigenvalue of Δ is real

③ Eigenvalues are countable, $0 \leq \lambda_1 \leq \lambda_2 \leq \lambda_3 \leq \dots$, $\lim_{n \rightarrow \infty} \lambda_n = \infty$

④ $\lambda_1 \neq \lambda_2$ are eigenvalues, $\lambda_1 \Leftrightarrow u_1, \lambda_2 \Leftrightarrow u_2 \Rightarrow \int_{\Omega} u_1 u_2 = 0$, i.e. they

are orthogonal in $L^2(\Omega)$.

In fact, the eigenfunction forms an orthogonal basis for $L^2(\Omega)$.

We only prove why eigenvalue $\lambda \geq 0$ and the orthogonality.

(i) Assume that (λ, u) is an eigenpair.

$$\begin{aligned}\lambda \int_{\Omega} u^2 dx &= \int_{\Omega} -\Delta u u dx \\ &= \int_{\partial\Omega} \frac{\partial u}{\partial n} u dS + \int_{\Omega} |\nabla u|^2 dx \geq 0\end{aligned}$$

(ii) $(\lambda, u), (\eta, v)$ is an eigenpair.

Then, we have: $\lambda \int_{\Omega} uv = \int_{\Omega} -\Delta u v dx$

$$\begin{aligned}&= - \int_{\Omega} \frac{\partial u}{\partial n} v dS + \int_{\Omega} \nabla u \cdot \nabla v \\ &= - \int_{\Omega} \frac{\partial v}{\partial n} u dS + \int_{\Omega} \nabla u \cdot \nabla v = \eta \int_{\Omega} uv \Rightarrow \square\end{aligned}$$

Now, we propose a method to solve HE in 1 dimension.

$$\begin{cases} U_t = \omega U + f \\ U(0, x) = g(x) \quad \text{for } x \\ \alpha_1 U_x(0) + \beta_1 U(0) = g_1(t) \\ \alpha_2 U_x(l) + \beta_2 U(l) = g_2(t) \end{cases} \quad x \in (0, l)$$

Naturally, we always focus $\begin{cases} U(t, 0) = g_1(t) \\ U(t, l) = g_2(t) \end{cases}$ or $\begin{cases} U'(t, 0) = g_1(t) \\ U'(t, l) = g_2(t) \end{cases}$ or mixed.

Use $\tilde{U}(t, x) = U(t, x) - \frac{l-x}{l} g_1(t) - \frac{x-l}{2l} g_2(t)$ deal respectively

So, we just need to deal with $g_1(t) \equiv g_2(t) \equiv 0$

Consider $X_n(x) T_n(t)$ which satisfies $\begin{cases} U_t = \Delta U \\ \alpha_1 U(x, 0) + \beta_1 U(0) = 0 \\ \alpha_2 U_x(1, t) + \beta_2 U(1, t) = 0 \end{cases}$

Then $\begin{cases} X_n(x) T_n'(t) = X_n''(x) T_n(t) \Rightarrow \frac{X_n''(x)}{X_n(x)} = \frac{T_n'(t)}{T_n(t)} = -\lambda_n \\ \alpha_1 X_n'(0) + \beta_1 X_n(0) = 0 \\ \alpha_2 X_n'(1) + \beta_2 X_n(1) = 0 \end{cases}$

From above, we have $\lambda_n > 0$ and for all eigenvalues λ , the eigenfunctions $\{X_n(x)\}$ forms a orthogonal basis in $L^2(0, 1)$

Hence, if $\varphi(x) \in L^2(0, 1) \Rightarrow$ we can decompose $\varphi(x) = \sum_{n=1}^{\infty} \varphi_n X_n(x)$
 $(\varphi_n = \frac{\int_0^1 \varphi(x) X_n(x) dx}{\int_0^1 X_n^2(x) dx})$.

if $f(x) \in L^2(0, 1) \Rightarrow$ We can decompose $f(x) = \sum_{n=1}^{\infty} f_n(t) X_n(x)$

Back to the original situation.

We just need to let $\begin{cases} T_n'(t) = -\lambda_n T_n(t) + f_n(t) \\ T_n(0) = \varphi_n \end{cases}$, then $\sum_{n=1}^{\infty} T_n(t) X_n(x)$ solves the HE.

IV). Maximum principle and related energy estimate. Comparison principle.

Maximum principle (HE version, and we will state a generalized version here). $\overset{\Delta}{U} \subseteq U$. For U is bounded and open
 If $U \in C^{1,2}([0, T] \times U) \cap C(\overline{U})$ and consider the operator:

$$L_U = \sum_{i,j=1}^n a_{ij}(t,x) \frac{\partial}{\partial x_i} U \frac{\partial}{\partial x_j} U + \sum_{i=1}^n b_i(t,x) \frac{\partial}{\partial x_i} U$$

$\dim U$

where $A = (a_{ij}(t,x))$ is positive semi-definite.

$$\text{If } U_t - L_U \leq 0, \text{ then } \max_{\bar{U}_T} U = \max_{\partial U_T} U$$

Proof: First, assume $U_t - L_U < 0$.

$$\begin{aligned} \text{If there exists } (t_0, x_0) \in [0, T] \times U, \text{ s.t. } U(t_0, x_0) = \max_{\bar{U}_T} U \\ \Rightarrow U_t \geq 0, \quad \nabla^2 U(t_0, x_0) \leq 0 \Rightarrow A \nabla^2 U(t_0, x_0) \leq 0 \quad \left. \begin{array}{l} \nabla^2 U(t_0, x_0) \leq 0 \\ \sum a_{ij} U = 0 \end{array} \right\} L_U \leq 0 \end{aligned}$$

$\Rightarrow U_t - L_U > 0 \Rightarrow \text{Contradiction.}$

If $U_t - L_U \leq 0$, consider $U_\varepsilon(t, x) = U - \varepsilon t \geq U$, (let $\varepsilon \rightarrow 0^+$ is enough).

As a particular example, we have: if $U_t - L_U \leq 0$ for $U \in C^{1,2} \cap C$.
 Then $\max_{\bar{U}_T} U = \max_{\partial U_T} U$

From this, we can get the comparison principle

For $U, V \in C^{1,2}(\bar{U}_T) \cap C(\bar{U}_T)$, if

$$\begin{cases} U_t - L_U \leq V_t - L_V \\ U|_{\partial U_T} \leq V|_{\partial U_T} \end{cases} \Rightarrow U \leq V \text{ in } \bar{U}_T.$$

Using this, we can give another proof of the uniqueness of heat equation.

Using this, it's easy to get:

L^∞ -stability: Let U_i be the classical solution $C^{1,2}(U_i)$
 $\cap C(\bar{U}_i)$, s.t $\begin{cases} \partial_t U_i - \Delta U_i + f_i, U_i \\ |U_i|_{\partial\Omega} = g_i, U_i|_{t=0} = \psi_i \end{cases}$

Then: $\max_{\bar{U}_i} |U_1 - U_2| \leq T \|f_1 - f_2\|_{L^\infty} + \|g_1 - g_2\|_{L^\infty} + \|\psi_1 - \psi_2\|_{L^\infty}$

Now, we propose L^∞ -stability for mixed boundary condition.
 Similarly, we need a comparison principle.

• $U \in C^{1,2}(U_T) \cap C^{0,1}(\bar{U}_T)$ satisfy

$$\begin{cases} \Delta U = U_t - \Delta U \geq 0 \text{ in } U \\ U|_{t=0} \geq 0 \text{ in } U \\ \frac{\partial U}{\partial n} + \beta U|_{\partial U} \geq 0, t \in [0, T] \end{cases} \quad \begin{array}{l} U \geq 0, \beta \\ \beta: \partial U \rightarrow [0, \infty) \end{array} \Rightarrow U \geq 0 \text{ in } \bar{U}_T$$

Proof: Since $\Delta U = U_t - \Delta U \geq 0$, we have $\min_{\bar{U}_T} U = \min_{\partial U} U$

If $\exists (t^*, x^*) \in \partial U$, s.t $U(t^*, x^*) \leq 0$

Notice that $D_u U(t^*, x^*) \cdot n \leq 0$, since (t^*, x^*) is minimal point.

So, $\frac{\partial U}{\partial n} + \beta U|_{\partial U} \leq 0$, if $\frac{\partial U}{\partial n} + \beta U|_{\partial U} > 0 \Rightarrow$ Contradiction

If not, consider $w(t, x) = 2t + (x - \frac{l}{2})^2$, $\begin{cases} \Delta w = 0, w|_{t=0} \geq 0 \text{ in } U \\ \frac{\partial w}{\partial n} + \beta w|_{\partial U} \geq c > 0. \end{cases}$

And, consider $U_\varepsilon = U + \varepsilon w \geq U$ as $\varepsilon \rightarrow 0^+$.

Hence, we get: If $U \in C^{1,2}(U_i) \cap C^{0,1}(\bar{U}_i)$, s.t.

$$\begin{cases} \Delta U = U_t - \Delta U = f(t, x) \\ U|_{t=0} = \psi \\ \frac{\partial U}{\partial n} + \beta U|_{\partial U} = g(t, x) \end{cases} \Rightarrow \max_{\bar{U}_i} U \leq C(T+1)(\|f\|_{L^\infty} + \|\psi\|_{L^\infty} + \|g\|_{L^\infty})$$

Proof: Consider $Ft + \underline{\phi} + \frac{G}{C} w(t, x) \leq U(t, x)$

◻

Here, we give an application of maximum principle to finish the discussion about HE.

For HE on the whole space, if $U \in C^{1,2}([0, T] \times \mathbb{R}^d) \cap C([0, T] \times \mathbb{R}^d)$ solves $\begin{cases} \partial_t U = \Delta U \\ U|_{t=0} = \varphi \end{cases}$ with $|U(t, x)| \leq Ae^{a|x|^2}$ for some $A > 0, a > 0$.

Then $\max_{[0,T] \times \mathbb{R}^d} |U| = \sup_{\mathbb{R}^d} |\varphi|$.

Proof: Notice that: $\frac{\nu}{(T+\varepsilon-t)^{\frac{d}{2}}} e^{\frac{|x|^2}{4(T+\varepsilon-t)}}$ is a solution of $U_t = \Delta U$

$$(U_t = -\frac{d}{2} \frac{\nu \cdot (-1)}{(T+\varepsilon-t)^{\frac{d}{2}+1}} e^{\frac{|x|^2}{4(T+\varepsilon-t)}} + \frac{\nu}{(T+\varepsilon-t)^{\frac{d}{2}}} e^{\frac{|x|^2}{4(T+\varepsilon-t)}} \cdot \frac{-|x|^2 \cdot (-1)}{4(T+\varepsilon-t)^2})$$

$$U_{xi} = \frac{\nu}{(T+\varepsilon-t)^{\frac{d}{2}}} e^{\frac{|x|^2}{4(T+\varepsilon-t)}} \cdot \frac{2x_i}{4(T+\varepsilon-t)} = \frac{\nu x_i}{2(T+\varepsilon-t)^{\frac{d}{2}+1}} e^{\frac{|x|^2}{4(T+\varepsilon-t)}}$$

$$U_{xx_i} = \frac{\nu}{2(T+\varepsilon-t)^{\frac{d}{2}+1}} e^{\frac{|x|^2}{4(T+\varepsilon-t)}} + \frac{\nu x_i^2}{4(T+\varepsilon-t)^{\frac{d}{2}+2}} e^{\frac{|x|^2}{4(T+\varepsilon-t)}} ?$$

$$\text{So, consider } V(t, x) = U(t, x) - \frac{\nu}{(T+\varepsilon-t)^{\frac{d}{2}}} e^{\frac{|x|^2}{4(T+\varepsilon-t)}}$$

Take $T+\varepsilon < \frac{1}{4a}$, take L big enough, consider $[0, T] \times B_L(0)$
Then, we have:

$$\partial_t V = \Delta V \Rightarrow \max_{[0, T] \times B_L(0)} V = \max_{\partial(\sim)} V$$

$$\text{When } t=0, V(0, x) \leq \varphi(x) \quad \text{On } \partial B_L(0), V(t, x) \leq Ae^{a|U|^2} - \frac{\nu}{(T+\varepsilon)^{\frac{d}{2}}} e^{\frac{|x|^2}{4(T+\varepsilon)}} \\ \leq Ae^{a|U|^2} - \frac{\nu}{(T+\varepsilon)^{\frac{d}{2}}} e^{\frac{|U|^2}{4(T+\varepsilon)}} \leq 0 \leq \sup_{\sim} (\varphi)$$

$$\Rightarrow \sup_{[0, T] \times B(0)} U(t, x) \leq \sup_{\mathbb{R}^d} \varphi. \quad N \rightarrow 0 \Rightarrow \sup_{[0, T] \times B(0)} U(t, x) \leq \sup_{\mathbb{R}^d} \varphi.$$

Similarly, let $\tilde{U}(t, x) = U(t, x) + \frac{\lambda}{(T-t)^2} e^{\frac{|x|}{4(T-t)}} \geq \inf_{\mathbb{R}^d}$ is minimum ...

$$\Rightarrow \min_{[0, T] \times B(0)} \tilde{U} \geq \min_{\mathbb{R}^d} \varphi \Rightarrow \min_{\mathbb{R}^d} U \geq \min_{\mathbb{R}^d} \varphi \quad \square$$

Finally, we give the energy estimate

$$\text{let } U \in C^{1,2}(U_T) \cap C(\bar{U}_T) \text{ solves } \begin{cases} (2t - \Delta) U = f, U_T \\ U|_{t=0} = \varphi \\ U|_{\partial U} = 0 \end{cases}$$

Then, $\exists C = C(T)$, s.t

$$\sup_{0 \leq t \leq T} \|U(t, \cdot)\|_{L^2(\omega)}^2 + 2 \int_0^T \|\nabla U(t, \cdot)\|_{L^2(\omega)}^2 dt \leq C (\|\varphi\|_{L^2(\omega)}^2 + \int_0^T \|f(t, \cdot)\|_{L^2(\omega)}^2 dt)$$

$$\text{Proof: } \int_U U(U_t - \Delta U) = \int_U Uf, \text{ fix } t.$$

$$\text{Consider LHS} = \frac{1}{2} \frac{d}{dt} \int_U U^2(t, x) dx + \int_U |\nabla U(t, x)|^2 dx$$

$$\text{RHS} \leq \frac{1}{2} \int_U U^2 + f^2 dx$$

$$\text{Let } e(t) = \int_U U^2(t, x) dx, \text{ then } \dot{e}(t) \leq e(t) + 2 \int_U f^2 dx, e(0) = \int_U \varphi^2 dx$$

$$\Rightarrow (e^{-t} e(t))' \leq e^{-t} \cdot 2 \int_U f^2(t, x) dx \leq 2 \int_U f^2(t, x) dx$$

$$\Rightarrow e^{-t} e(t) - \int_U \varphi^2 dx \leq 2 \int_0^T \int_U f^2(t, x) dx dt$$

Using this, the energy estimate is obvious. \square

