

CMSC5702 (Advanced Topics in Parallel / Distributed Systems)

Assignment 1: Parallel Programming with Sobel Filter

Objective

Apply the Sobel filter for edge detection on **large square grayscale images** using MPI and OpenMP, and compare the performance of shared-memory vs distributed-memory parallelization. Optionally, include a blurring step to reduce noise before applying the Sobel operator.

This assignment allows you to practice:

- Sequential programming
 - OpenMP parallelization on shared-memory systems
 - MPI parallelization on distributed-memory systems
 - Performance measurement, verification, and speedup analysis
-

Problem Description

The **Sobel filter** computes approximate image gradients to detect edges. For a grayscale image (I):

$$G_x = \begin{bmatrix} -1 & 0 & 1 \\ -2 & 0 & 2 \\ -1 & 0 & 1 \end{bmatrix} * I, \quad G_y = \begin{bmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ 1 & 2 & 1 \end{bmatrix} * I$$

The **gradient magnitude** at each pixel is:

$$G = \sqrt{G_x^2 + G_y^2}$$

Optional **blurring step**: compute the local average of pixels in a small neighborhood (e.g., 3x3) before applying the Sobel operator to reduce noise.

Part 1: Sequential Version

- Implement a standard sequential C program to apply the Sobel operator on a grayscale image.
- If including blurring, apply an average filter first (e.g., 3×3 kernel) before Sobel.

Question: Explain the algorithm you implemented and if you applied blurring, explain the blurring method.

Your Answer:

My implementation follows a two-stage process.

First, I implemented the optional **blurring step** to reduce image noise before edge detection. The method I used is the 3×3 **average filter**, which is also called a mean filter. As shown in my `blur_filter` function, this filter works by sliding a 3×3 window over the image. For each pixel, it calculates the average value of all 9 pixels in its 3×3 neighborhood (summing them up and dividing by 9.0) and uses this average as the new value for that pixel.

Second, I apply the **Sobel operator** to the *blurred* image. This is implemented in my `sobel_filter` function. This algorithm calculates two gradients for each pixel by convolving the image with two 3×3 kernels:

- G_x : Using the 3×3 Sobel kernel to detect horizontal changes.
- G_y : Using the 3×3 Sobel kernel to detect vertical changes.

Finally, the magnitude of the gradient is computed using the formula $G = \sqrt{G_x^2 + G_y^2}$ to get the final pixel intensity for the edge-detected image. In my implementation, for pixels on the 1-pixel border of the image, I set their output value to 0.0, as the 3×3 kernel cannot be fully applied there.

```
In [12]: !pip install pandas
```

```
Requirement already satisfied: pandas in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (2.2.3)
Requirement already satisfied: numpy>=1.26.0 in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (from pandas) (2.0.1)
Requirement already satisfied: python-dateutil>=2.8.2 in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (from pandas) (2.9.0.post0)
Requirement already satisfied: pytz>=2020.1 in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (from pandas) (2024.2)
Requirement already satisfied: tzdata>=2022.7 in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (from pandas) (2024.1)
Requirement already satisfied: six>=1.5 in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (from python-dateutil>=2.8.2->pandas) (1.16.0)
```

```
In [13]: !pip install matplotlib
```

```
Requirement already satisfied: matplotlib in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (3.9.2)
Requirement already satisfied: contourpy>=1.0.1 in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (from matplotlib) (1.3.1)
Requirement already satisfied: cycler>=0.10 in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (from matplotlib) (0.12.1)
Requirement already satisfied: fonttools>=4.22.0 in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (from matplotlib) (4.55.0)
Requirement already satisfied: kiwisolver>=1.3.1 in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (from matplotlib) (1.4.7)
Requirement already satisfied: numpy>=1.23 in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (from matplotlib) (2.0.1)
Requirement already satisfied: packaging>=20.0 in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (from matplotlib) (24.1)
Requirement already satisfied: pillow>=8 in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (from matplotlib) (10.4.0)
Requirement already satisfied: pyparsing>=2.3.1 in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (from matplotlib) (3.2.0)
Requirement already satisfied: python-dateutil>=2.7 in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (from matplotlib) (2.9.0.post0)
Requirement already satisfied: six>=1.5 in /opt/anaconda3/envs/hwpytorch/lib/python3.12/site-packages (from python-dateutil>=2.7->matplotlib) (1.16.0)
```

```
In [14]: import pandas as pd
import matplotlib.pyplot as plt
import numpy as np

seq_df = pd.read_csv("sequential_times.csv")
```

```
In [15]: seq_df
```

```
Out[15]:   image_size  run1_time  run2_time  run3_time
0           256    0.000933    0.001047    0.000888
1          1024    0.015544    0.014636    0.014826
2          4000    0.210384    0.194488    0.215198
3         16000    4.079864    3.984604    3.932855
```

```
In [16]: import pandas as pd
import matplotlib.pyplot as plt
import numpy as np

# Assuming your data is in a DataFrame called df
# Calculate average and standard deviation
seq_df['average_time'] = seq_df[['run1_time', 'run2_time', 'run3_time']].mean()
seq_df['std_dev'] = seq_df[['run1_time', 'run2_time', 'run3_time']].std(axis=1)

# Plot with error bars showing standard deviation
plt.figure(figsize=(8,5))
plt.errorbar(seq_df['image_size'], seq_df['average_time'],
             yerr=seq_df['std_dev'],
             marker='o',
             color='blue',
```

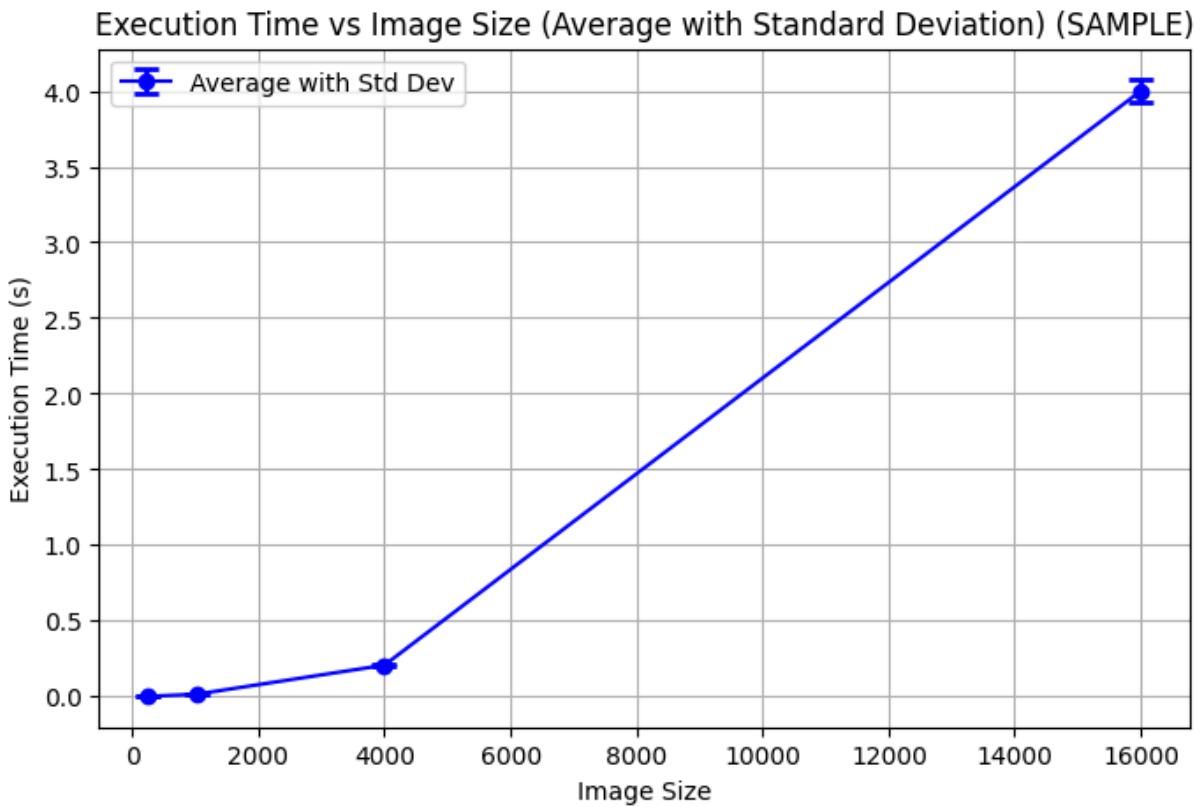
```

        label='Average with Std Dev',
        capsize=5, # Adds caps to the error bars
        capthick=2,
        elinewidth=2)

plt.xlabel('Image Size')
plt.ylabel('Execution Time (s)')
plt.title('Execution Time vs Image Size (Average with Standard Deviation) (S')
plt.legend()
plt.grid(True)
plt.show()

# Optional: Print the calculated values
print("Data with averages and standard deviations:")
print(seq_df[['image_size', 'average_time', 'std_dev']])

```



Data with averages and standard deviations:

	image_size	average_time	std_dev
0	256	0.000956	0.000082
1	1024	0.015002	0.000479
2	4000	0.206690	0.010838
3	16000	3.999108	0.074570

Part 2: OpenMP Programming

- Use `#pragma omp parallel for collapse(2)` for nested loops.
- Experiment with `schedule(static)` and other scheduling clauses.
- Process large images in tiles (e.g., 512×512 or 1024×1024) to reduce memory bandwidth issues.

- [Bonus Point] Optionally include a blurring step before the Sobel operator to reduce noise.

Question: Explain the algorithm you implemented and if you applied blurring, explain the blurring method.

Your Answer:

For the OpenMP implementation, my algorithm follows the same two-stage process as the sequential version, but the parallelization strategy is optimized for cache performance.

I implemented the **blurring step**. The method is the 3×3 **average filter**, where each pixel's new value is the average of its 9-pixel neighborhood (summing them up and dividing by 9.0) to reduce noise.

The core of my parallel implementation is a **tiling (or block-based) decomposition**. Here is the logic:

1. **Tiling:** Instead of parallelizing the image row by row, I divide the entire image into small, fixed-size square blocks.
2. **Parallelism:** I use OpenMP's `#pragma omp parallel for collapse(2)` directive. This directive assigns *entire tiles* to different threads. The `collapse(2)` tells OpenMP to merge the two outer loops (the one iterating tile rows and the one iterating tile columns) into one large loop, which provides many independent tasks (the tiles) for the threads to work on.

This tiling method is applied to both functions:

- First, `blur_filter_tiled` runs, with threads processing different tiles to create the blurred image.
- Second, `sobel_filter_tiled` runs on the blurred image, using the exact same parallel tiling strategy. Inside each tile, the standard Sobel logic is applied (convolving with Gx and Gy kernels, then calculating the magnitude

$$G = \sqrt{G_x^2 + G_y^2}.$$

Processing the image in tiles ensures that the data a thread is working on (a single tile) is small enough to fit well within the CPU caches, which reduces memory bandwidth issues and improves performance, especially on large images.

```
In [17]: omp_df = pd.read_csv("openmp_times.csv")
```

```
In [18]: omp_df.head()
```

Out[18]:

	image_size	threads	run1_time	run2_time	run3_time
0	256	1	0.002602	0.002662	0.002512
1	256	2	0.002633	0.002648	0.002686
2	256	4	0.002697	0.002705	0.002729
3	256	8	0.002934	0.002855	0.002830
4	256	16	0.003115	0.003054	0.003121

In [19]:

```

import pandas as pd
import matplotlib.pyplot as plt
import numpy as np

# 如果未预先加载 OpenMP 数据, 则从报告目录读取
try:
    omp_df
except NameError:
    omp_df = pd.read_csv("openmp_times.csv") # 关键: 确保读取的是 report/openmp_times.csv

# 读取顺序版本数据, 用作“绝对加速比”的基线
seq_df = pd.read_csv("sequential_times.csv") # 关键: 确保读取的是 report/sequential_times.csv
seq_df['average_time'] = seq_df[['run1_time','run2_time','run3_time']].mean()

# 计算 OpenMP 各线程的平均时间与标准差
omp_df['average_time'] = omp_df[['run1_time','run2_time','run3_time']].mean()
omp_df['std_dev'] = omp_df[['run1_time','run2_time','run3_time']].std(axis=1)

# 预先创建加速比例
omp_df['absolute_speedup'] = 0.0
omp_df['relative_speedup'] = 0.0

# 计算绝对/相对加速比
# 绝对加速比: 顺序实现平均时间 / 当前并行平均时间
# 相对加速比: OpenMP 1线程平均时间 / 当前并行平均时间
for size in omp_df['image_size'].unique():
    # 从顺序数据中取出对应 image_size 的平均时间, 作为绝对加速比基线
    seq_time = seq_df.loc[seq_df['image_size'] == size, 'average_time'].iloc[0]
    # 从 OpenMP 数据中取出 1 线程的平均时间, 作为相对加速比基线
    omp1_time = omp_df[(omp_df['image_size'] == size) & (omp_df['threads'] == 1)].mean()

    subset_idx = omp_df[omp_df['image_size'] == size].index
    # 绝对加速比
    omp_df.loc[subset_idx, 'absolute_speedup'] = seq_time / omp_df.loc[subset_idx, 'average_time']
    # 相对加速比
    omp_df.loc[subset_idx, 'relative_speedup'] = omp1_time / omp_df.loc[subset_idx, 'average_time']

# 绘制运行时间 (含标准差误差条)
plt.figure(figsize=(8,5))
for size in sorted(omp_df['image_size'].unique()):
    subset = omp_df[omp_df['image_size'] == size]
    plt.errorbar(subset['threads'], subset['average_time'],
                 yerr=subset['std_dev'],
                 marker='o', label=f'{size}x{size}', capsized=5)

```

```

plt.xlabel('Number of Threads')
plt.ylabel('Runtime (s)')
plt.title('OpenMP Runtime vs Threads (Average ± Std Dev)')
plt.xscale('log', base=2)
plt.xticks([1,2,4,8,16,32])
plt.grid(True, which='both', linestyle='--', alpha=0.6)
plt.legend()
plt.show()

# 绝对加速比 (基线为顺序实现)
plt.figure(figsize=(8,5))
for size in sorted(omp_df['image_size'].unique()):
    subset = omp_df[omp_df['image_size'] == size]
    plt.plot(subset['threads'], subset['absolute_speedup'], marker='o', label=f'{size}x')

plt.xlabel('Number of Threads')
plt.ylabel('Absolute Speedup')
plt.title('OpenMP Absolute Speedup vs Threads (Sequential Baseline)')
plt.xscale('log', base=2)
plt.xticks([1,2,4,8,16,32])
plt.grid(True, which='both', linestyle='--', alpha=0.6)
plt.legend()
plt.show()

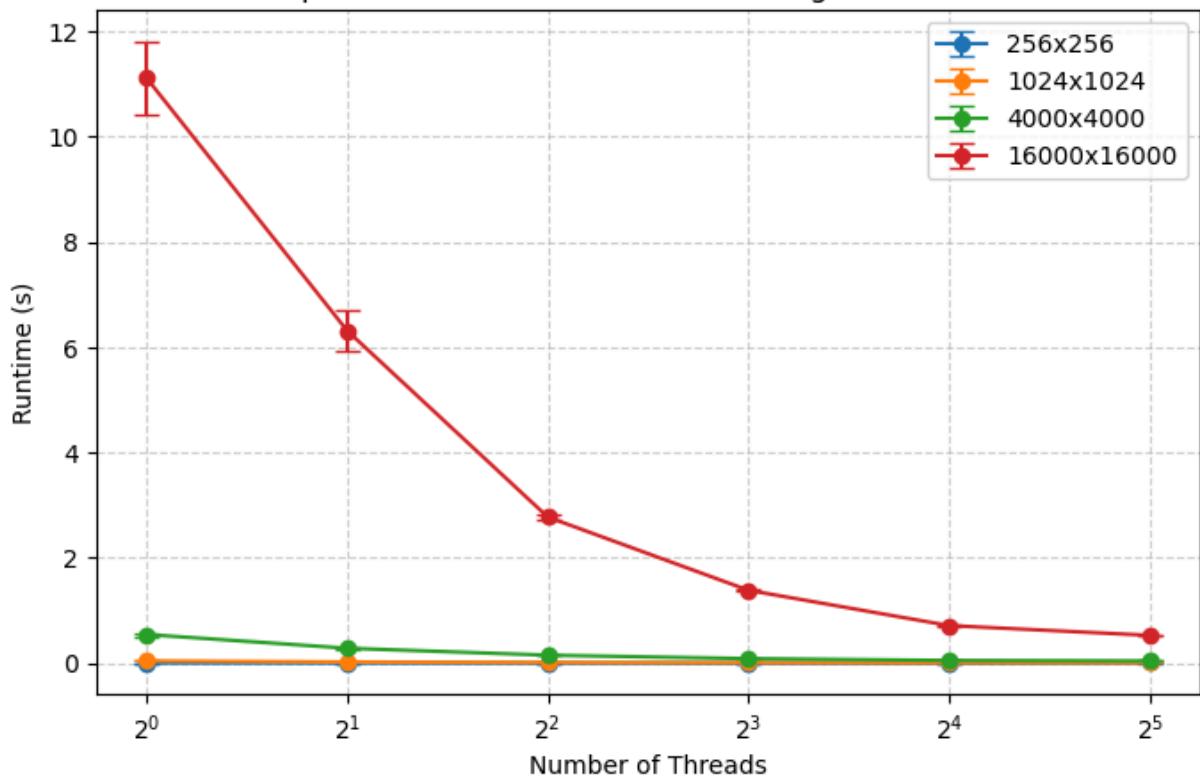
# 相对加速比 (基线为 OpenMP 1 线程)
plt.figure(figsize=(8,5))
for size in sorted(omp_df['image_size'].unique()):
    subset = omp_df[omp_df['image_size'] == size]
    plt.plot(subset['threads'], subset['relative_speedup'], marker='o', label=f'{size}x')

plt.xlabel('Number of Threads')
plt.ylabel('Relative Speedup')
plt.title('OpenMP Relative Speedup vs Threads (OMP-1 Baseline)')
plt.xscale('log', base=2)
plt.xticks([1,2,4,8,16,32])
plt.grid(True, which='both', linestyle='--', alpha=0.6)
plt.legend()
plt.show()

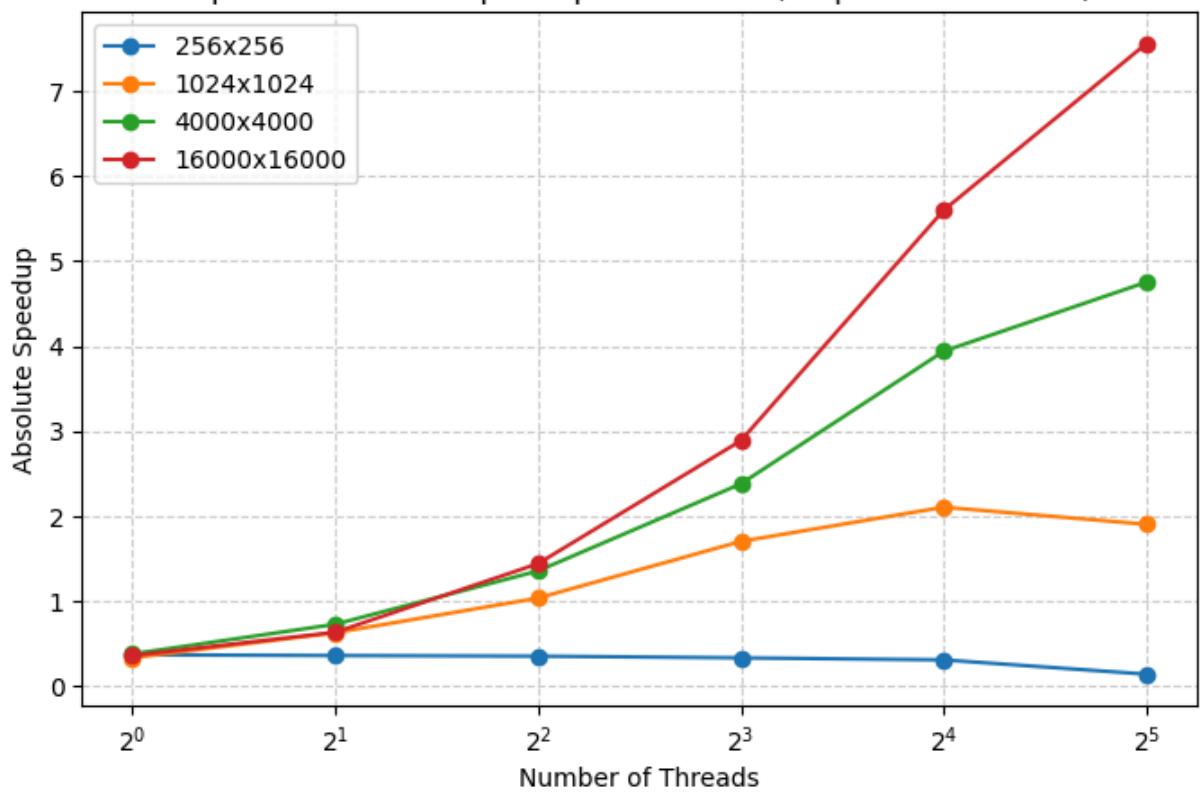
# 打印核对数据
print("OpenMP data with runtime, std_dev, absolute and relative speedups:")
print(omp_df[['image_size','threads','average_time','std_dev','absolute_speedup','relative_speedup']])

```

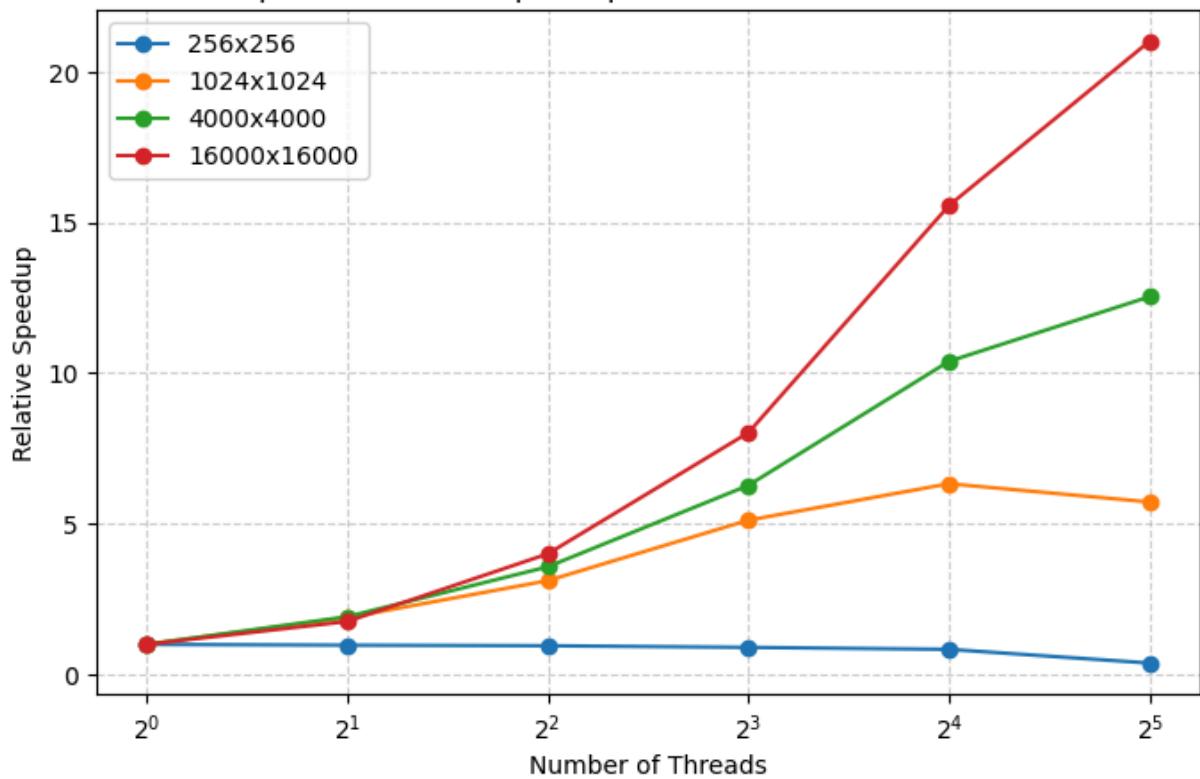
OpenMP Runtime vs Threads (Average \pm Std Dev)



OpenMP Absolute Speedup vs Threads (Sequential Baseline)



OpenMP Relative Speedup vs Threads (OMP-1 Baseline)



OpenMP data with runtime, std_dev, absolute and relative speedups:

	image_size	threads	average_time	std_dev	absolute_speedup	\
0	256	1	0.002592	0.000075	0.368827	
1	256	2	0.002656	0.000027	0.359985	
2	256	4	0.002710	0.000017	0.352724	
3	256	8	0.002873	0.000054	0.332753	
4	256	16	0.003097	0.000037	0.308719	
5	256	32	0.006793	0.000634	0.140726	
6	1024	1	0.045112	0.001055	0.332548	
7	1024	2	0.023913	0.002435	0.627358	
8	1024	4	0.014483	0.000557	1.035811	
9	1024	8	0.008809	0.000231	1.703095	
10	1024	16	0.007126	0.000275	2.105347	
11	1024	32	0.007880	0.000090	1.903807	
12	4000	1	0.545054	0.034005	0.379210	
13	4000	2	0.284085	0.021516	0.727564	
14	4000	4	0.152469	0.007123	1.355623	
15	4000	8	0.086843	0.005820	2.380033	
16	4000	16	0.052449	0.002981	3.940781	
17	4000	32	0.043478	0.001073	4.753935	
18	16000	1	11.111987	0.696742	0.359891	
19	16000	2	6.314521	0.390359	0.633319	
20	16000	4	2.775402	0.044862	1.440911	
21	16000	8	1.384710	0.007167	2.888048	
22	16000	16	0.714140	0.014279	5.599896	
23	16000	32	0.528825	0.008575	7.562247	

	relative_speedup
0	1.000000
1	0.976026
2	0.956340
3	0.902193
4	0.837029
5	0.381551
6	1.000000
7	1.886519
8	3.114776
9	5.121358
10	6.330963
11	5.724915
12	1.000000
13	1.918630
14	3.574859
15	6.276291
16	10.392076
17	12.536413
18	1.000000
19	1.759751
20	4.003739
21	8.024778
22	15.559964
23	21.012585

Part 3: MPI Programming

- Choose a domain decomposition strategy, such as row-wise decomposition, column-wise decomposition, etc., decomposition. Your choice will affect performance, and better-designed decomposition and communication patterns will receive higher marks.
- For each process, you may need to include some approaches to allow seamless computation for the edges.
- [Bonus Point] You can include If a parallelized blurring step and you may need to try to optimize the communications.
- Verify your implementation using small test patterns (5×5 or 10×10) and visually inspect sample images for correctness.

```
In [20]: mpi_df = pd.read_csv("mpi_times.csv")
```

```
In [21]: mpi_df.head()
```

```
Out[21]:   image_size  nodes  processes  run1_time  run2_time  run3_time
0           256      1         1    0.004786    0.004790    0.004787
1           256      1         2    0.004350    0.004399    0.004302
2           256      1         4    0.002177    0.002183    0.002202
3           256      4         8    0.009898    0.010151    0.009965
4           256      4        16    0.009924    0.009968    0.010641
```

```
In [22]: import pandas as pd
import matplotlib.pyplot as plt
import numpy as np

# 如未加载数据则读取
try:
    mpi_df
except NameError:
    mpi_df = pd.read_csv("mpi_times.csv")

# 读取顺序数据用于绝对加速比基线
seq_df = pd.read_csv("sequential_times.csv")
seq_df['average_time'] = seq_df[['run1_time', 'run2_time', 'run3_time']].mean()

# 计算平均时间和标准差
mpi_df['average_time'] = mpi_df[['run1_time', 'run2_time', 'run3_time']].mean()
mpi_df['std_dev'] = mpi_df[['run1_time', 'run2_time', 'run3_time']].std(axis=1)

# 绝对加速比 使用顺序实现平均时间作为基线
abs_baseline = {size: t for size, t in zip(seq_df['image_size'], seq_df['average_time'])}
mpi_df['absolute_speedup'] = mpi_df.apply(lambda row: abs_baseline[row['image_size']] / row['average_time'])

# 相对加速比 使用1节点1进程平均时间作为基线
rel_baseline = {}
for img_size in mpi_df['image_size'].unique():
    base_time = mpi_df[(mpi_df['image_size'] == img_size) & (mpi_df['nodes'] == 1) & (mpi_df['processes'] == 1)]['average_time'].mean()
    rel_baseline[img_size] = base_time
    mpi_df['relative_speedup'] = mpi_df['average_time'] / base_time
```

```

    rel_baseline[img_size] = base_time
mpi_df['relative_speedup'] = mpi_df.apply(lambda row: rel_baseline[row['image_size']] / row['average_time'], axis=1)

# 绘制运行时间
plt.figure(figsize=(10,6))
for img_size in sorted(mpi_df['image_size'].unique()):
    df_img = mpi_df[mpi_df['image_size']==img_size]
    plt.errorbar(df_img['processes'], df_img['average_time'], yerr=df_img['std_dev'], marker='o', capsized=5, label=f'{img_size}x{img_size}')
plt.xlabel('Number of Processes')
plt.ylabel('Average Runtime (s)')
plt.title('MPI: Average Runtime vs Number of Processes')
plt.legend(title='Image Size')
plt.grid(True)
plt.show()

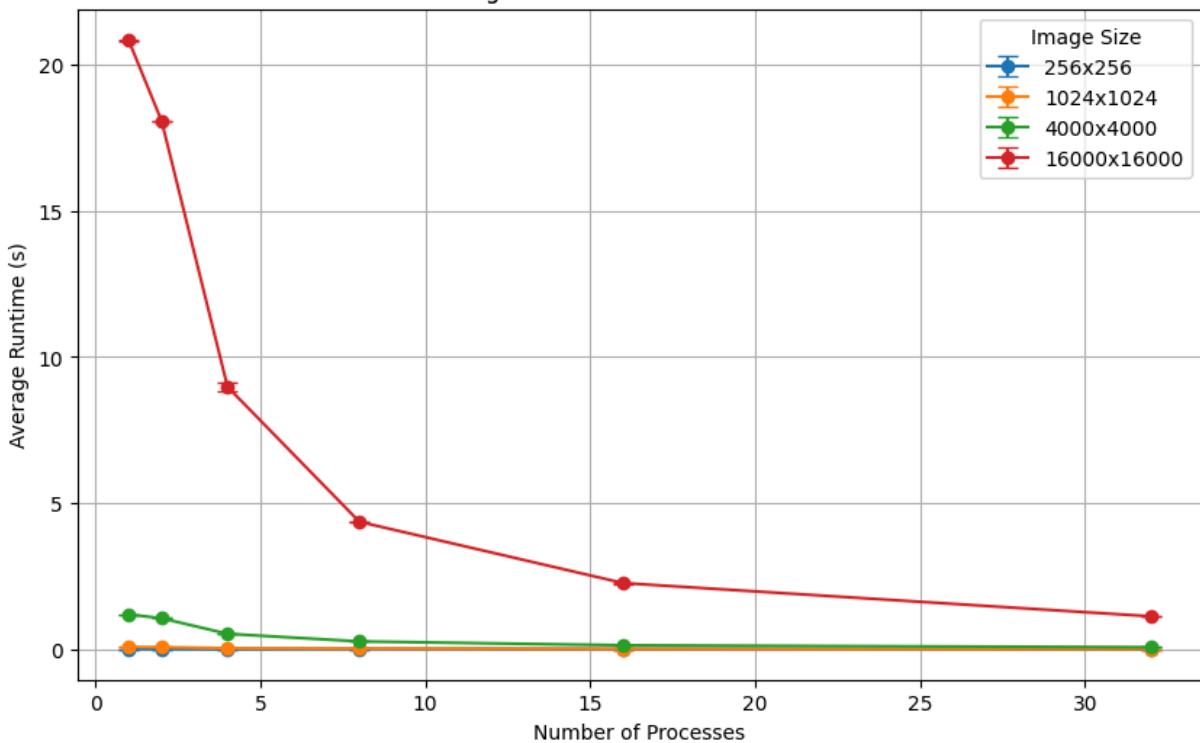
# 绘制绝对加速比
plt.figure(figsize=(10,6))
for img_size in sorted(mpi_df['image_size'].unique()):
    df_img = mpi_df[mpi_df['image_size']==img_size]
    plt.plot(df_img['processes'], df_img['absolute_speedup'], marker='o', label=f'{img_size}x{img_size}')
plt.xlabel('Number of Processes')
plt.ylabel('Absolute Speedup')
plt.title('MPI: Absolute Speedup vs Number of Processes')
plt.legend(title='Image Size')
plt.grid(True)
plt.show()

# 绘制相对加速比
plt.figure(figsize=(10,6))
for img_size in sorted(mpi_df['image_size'].unique()):
    df_img = mpi_df[mpi_df['image_size']==img_size]
    plt.plot(df_img['processes'], df_img['relative_speedup'], marker='o', label=f'{img_size}x{img_size}')
plt.xlabel('Number of Processes')
plt.ylabel('Relative Speedup')
plt.title('MPI: Relative Speedup vs Number of Processes')
plt.legend(title='Image Size')
plt.grid(True)
plt.show()

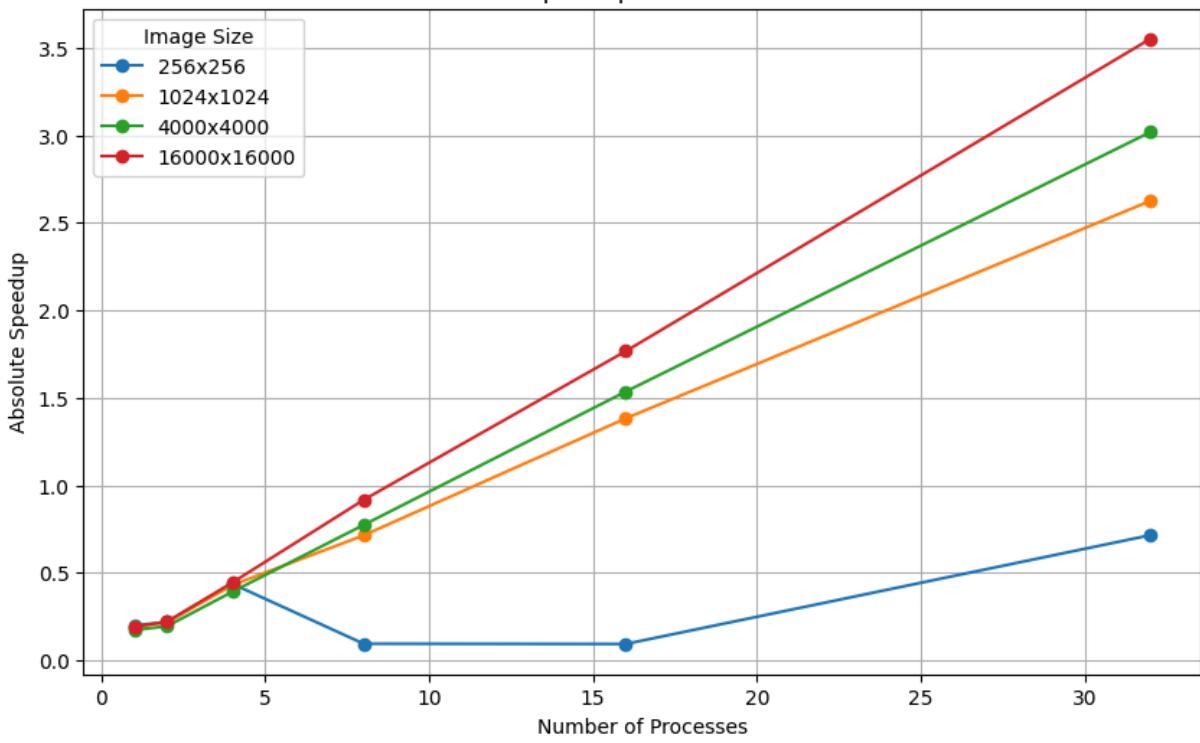
# 打印数据
print(mpi_df[['image_size', 'nodes', 'processes', 'average_time', 'std_dev', 'absolute_speedup', 'relative_speedup']])

```

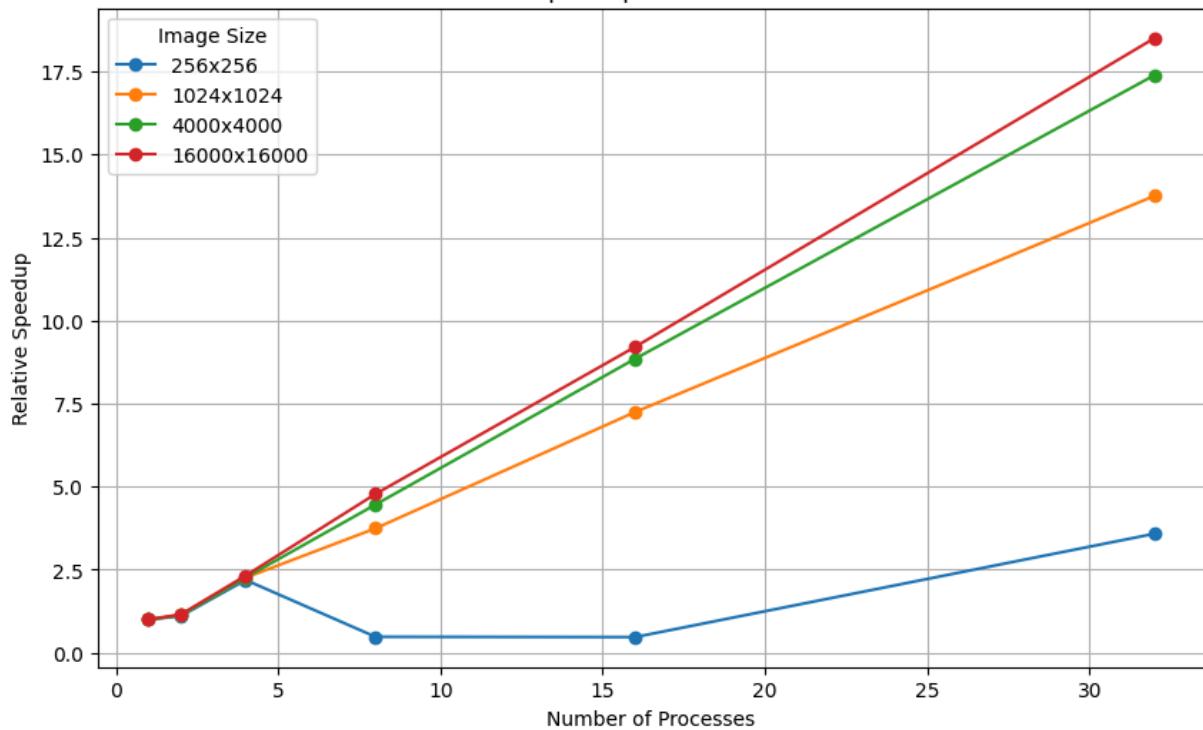
MPI: Average Runtime vs Number of Processes



MPI: Absolute Speedup vs Number of Processes



MPI: Relative Speedup vs Number of Processes



	image_size	nodes	processes	average_time	std_dev	absolute_speedup
0	256	1	1	0.004788	0.000002	0.199680
1	256	1	2	0.004350	0.000049	0.219753
2	256	1	4	0.002187	0.000013	0.437062
3	256	4	8	0.010005	0.000131	0.095555
4	256	4	16	0.010178	0.000402	0.093931
5	256	4	32	0.001337	0.000314	0.715212
6	1024	1	1	0.078634	0.000749	0.190783
7	1024	1	2	0.069275	0.000083	0.216558
8	1024	1	4	0.034820	0.000068	0.430844
9	1024	4	8	0.021006	0.000763	0.714166
10	1024	4	16	0.010849	0.000123	1.382758
11	1024	4	32	0.005716	0.000160	2.624410
12	4000	1	1	1.191254	0.011325	0.173506
13	4000	1	2	1.058956	0.000431	0.195183
14	4000	1	4	0.526464	0.000443	0.392600
15	4000	4	8	0.267107	0.005281	0.773811
16	4000	4	16	0.134598	0.002201	1.535610
17	4000	4	32	0.068503	0.001170	3.017225
18	16000	1	1	20.845706	0.024824	0.191843
19	16000	1	2	18.084436	0.006362	0.221135
20	16000	1	4	8.979863	0.127615	0.445342
21	16000	4	8	4.361434	0.000555	0.916925
22	16000	4	16	2.263662	0.033053	1.766654
23	16000	4	32	1.126529	0.017059	3.549939
	relative_speedup					
0		1.000000				
1		1.100529				
2		2.188814				
3		0.478543				
4		0.470409				
5		3.581796				
6		1.000000				
7		1.135105				
8		2.258300				
9		3.743347				
10		7.247819				
11		13.756021				
12		1.000000				
13		1.124932				
14		2.262745				
15		4.459844				
16		8.850458				
17		17.389723				
18		1.000000				
19		1.152688				
20		2.321383				
21		4.779553				
22		9.208841				
23		18.504372				

In []: