

The livestream will begin shortly...

softwareunderground.org presents



# TRANSFORM 2021

Virtual Conference on the Digital Subsurface, 16–23 April

supported by





# TRANSFORM 2021

**Matt Hall  
Dieter Werthmuller  
& Transform 2021 organizers**

**Thank You!**



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**Materials:** <http://bit.ly/transform-2021-slides>

**Slack:** *swu.ng/slack > #t21-tue-inversion-for-geologists*



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# Inversion for geologists

Seogi Kang, Doug Oldenburg, Lindsey Heagy,  
Dominique Fournier, Joe Capriotti & the SimPEG team



# Collaborators

Doug



Lindsey



Dom



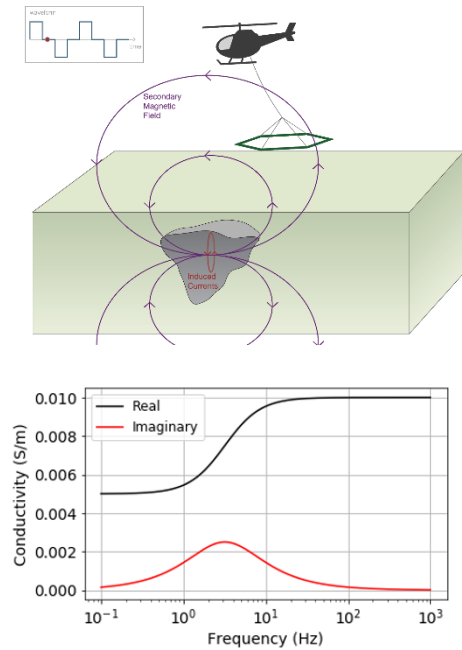
Joe





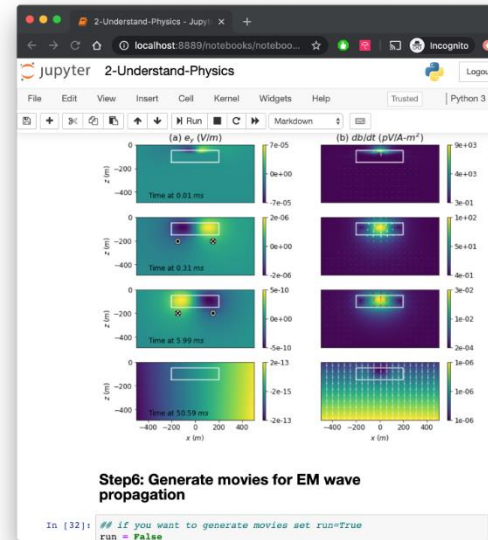
# hello (a bit about me)

## Computational EM geophysics

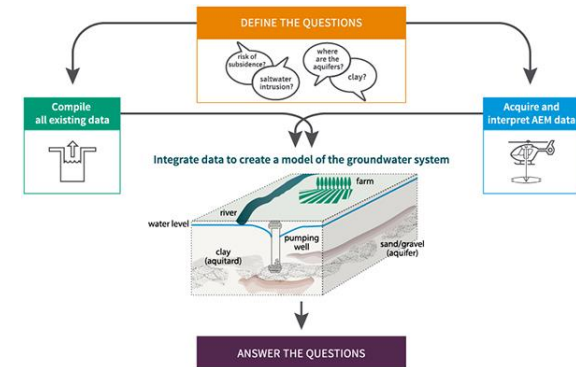


THE UNIVERSITY  
OF BRITISH COLUMBIA

## Open-source software



## Groundwater science & management





# Challenging geoscience problems that we faced ...



minerals



contaminants



water



geothermal



geotechnical



slope stability



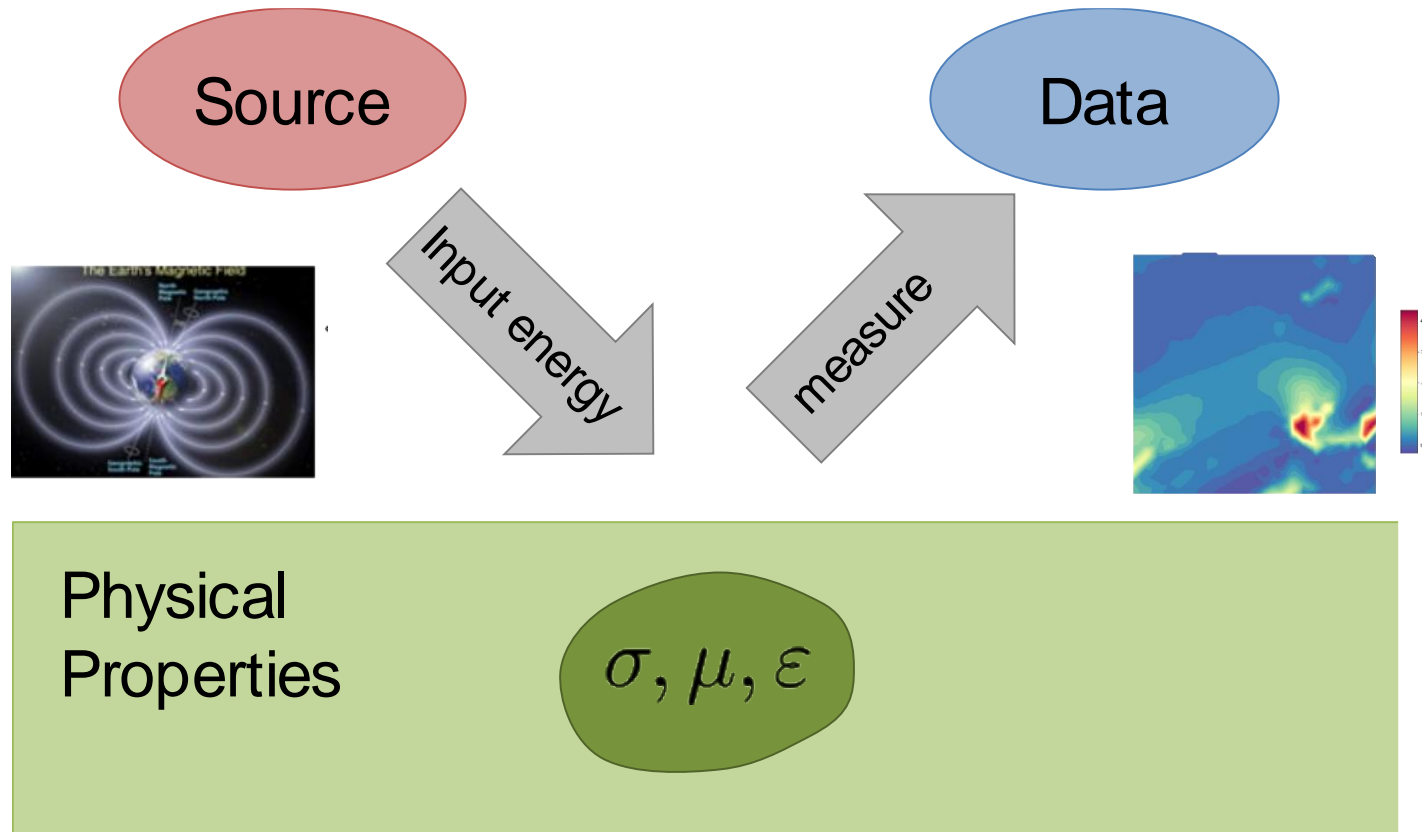
hydrocarbons



unexploded ordnance

# Generic geophysical experiment?

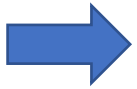
All require ways to see into the earth without direct sampling



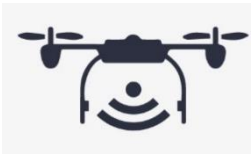


# Increasing data volume and complexity

Airborne sensors



airborne geophysics



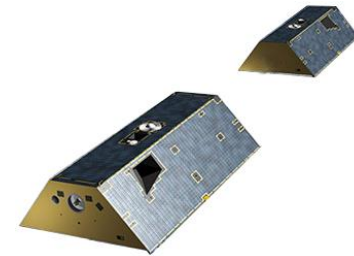
drone geophysics



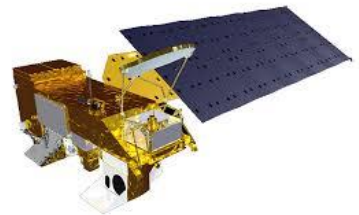
Satellite sensors



Sentinel-2



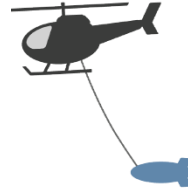
GRACE



MODIS

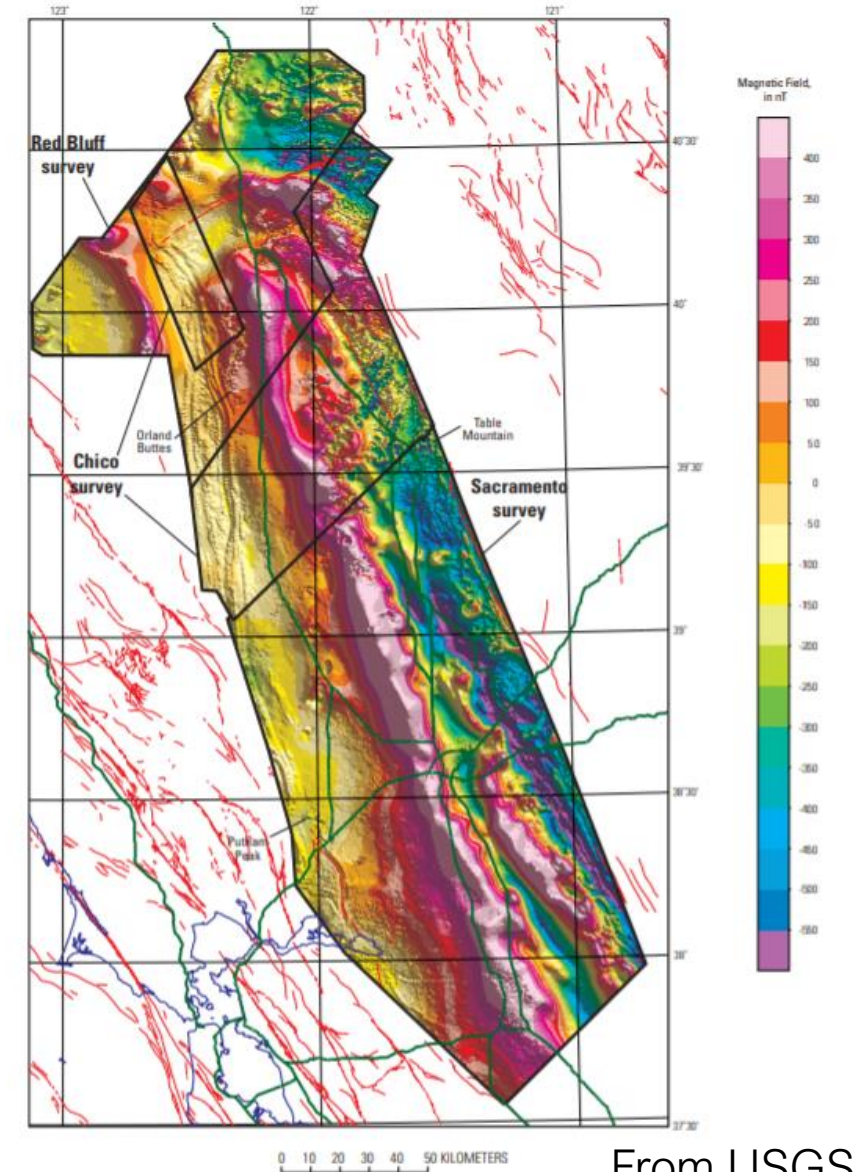
Data are publicly available, but extracting useful information from these data are challenging

# Airborne geophysics



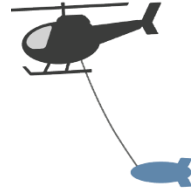
- Potential fields  
Magnetism  
Gravity
- Electromagnetics
- Radar

Increasing  
Resolution



Hundreds of km

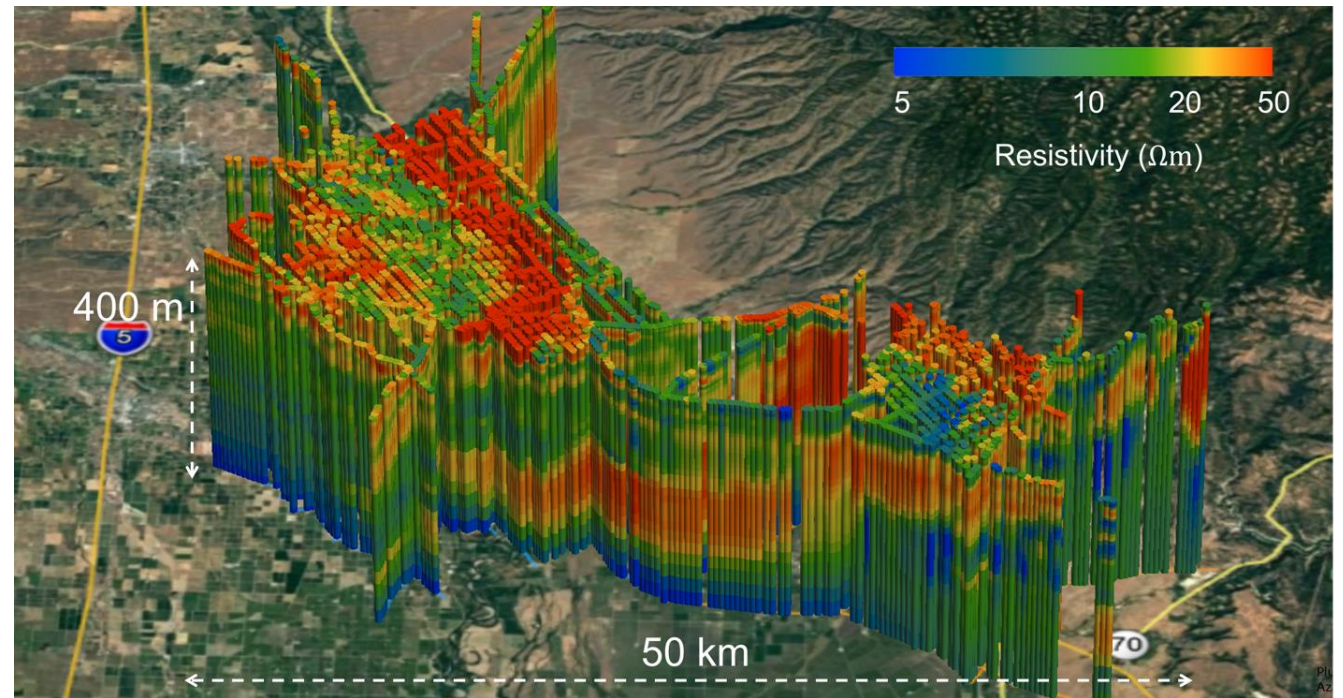
# Airborne geophysics



- Potential fields  
Magnetism  
Gravity
- Electromagnetics
- Radar



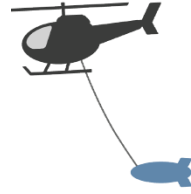
Increasing  
Resolution



Kang et al. (2021)



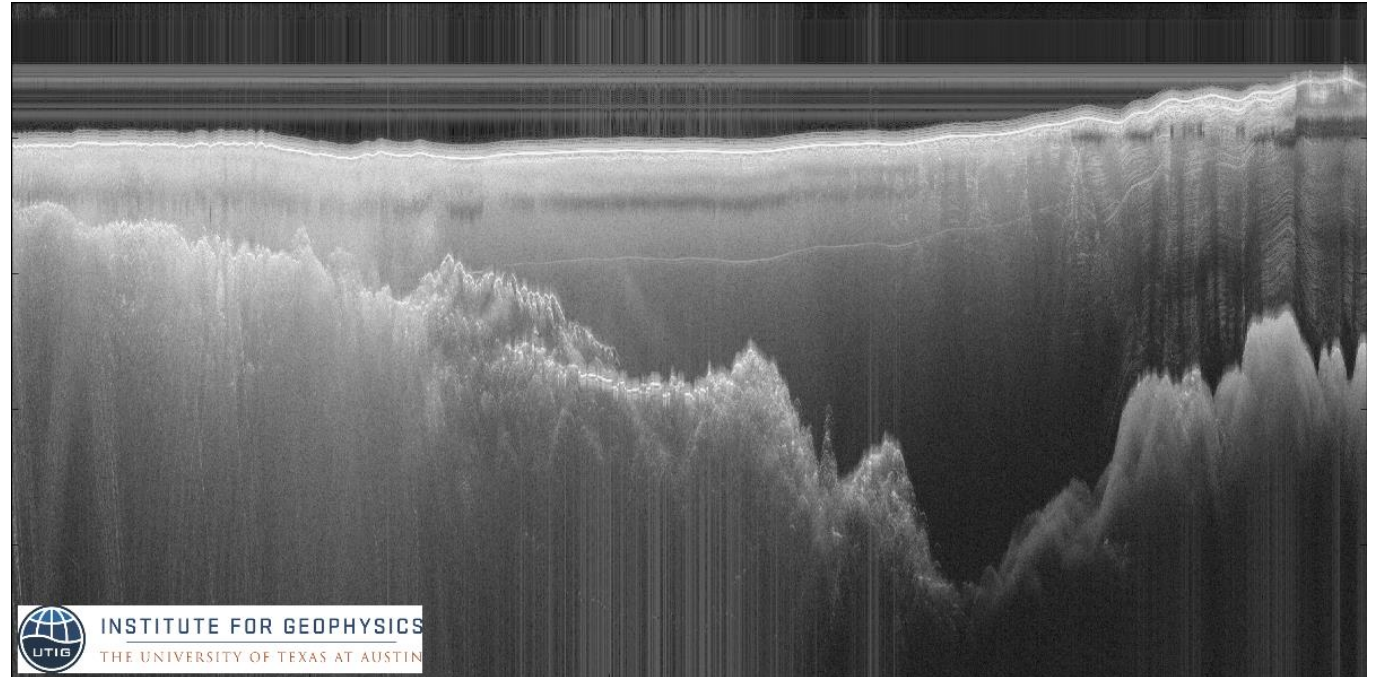
# Airborne geophysics



- Potential fields  
Magnetism  
Gravity
- Electromagnetics
- Radar



Increasing  
Resolution

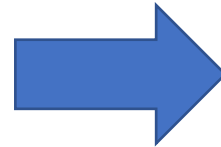
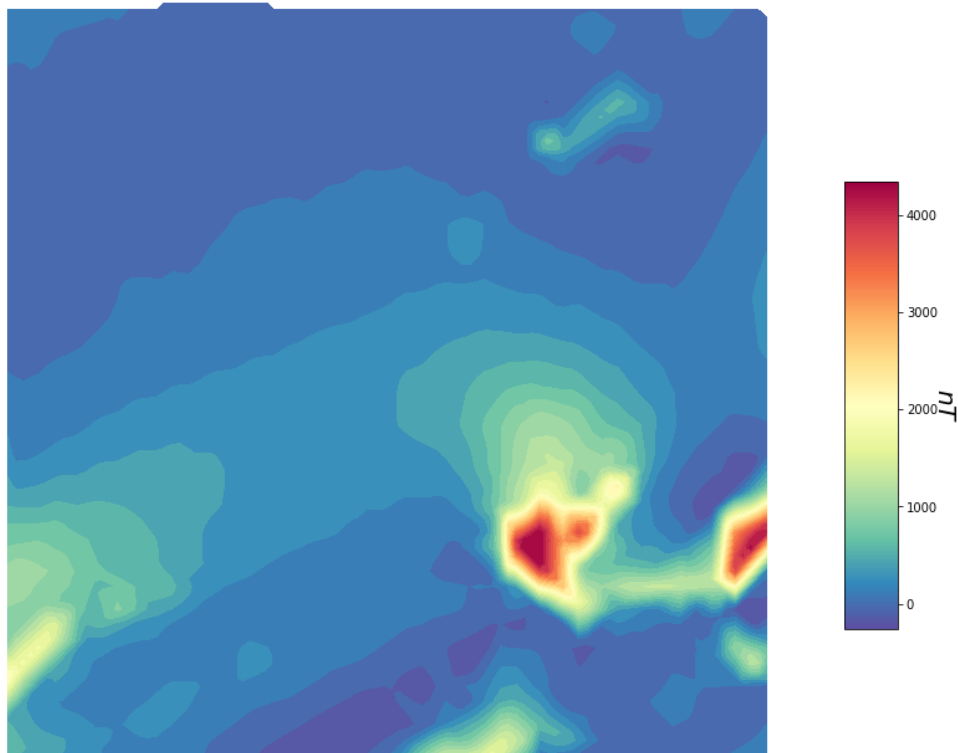


Lindzey (2015)

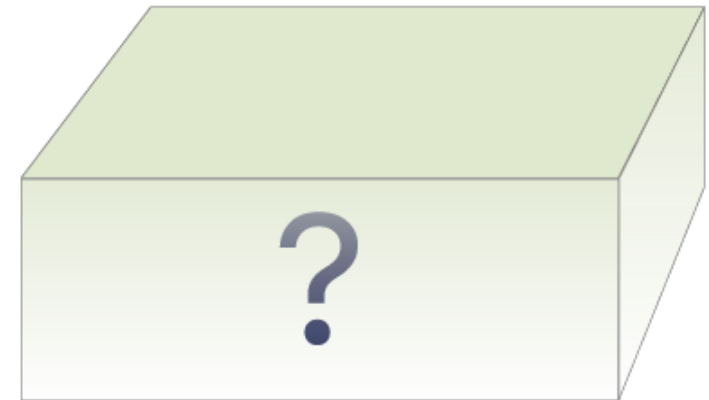
# An overarching question today is ...

How do we find a subsurface model from the observed data in a data-driven way?

Observed data

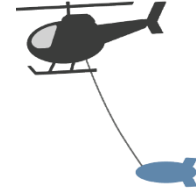


A subsurface model



# Outline

- Backgrounds: Magnetics
- Inversion Framework
- 1D Linear Inverse problem
- 3D Magnetic Inversion
- Including Geologic Information
- Summary





# Open-source packages that I am going to use today...



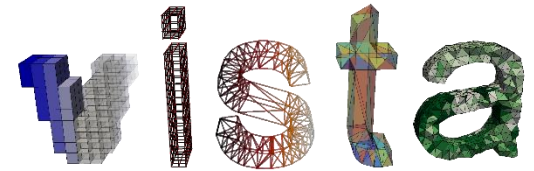
simpeg

Numerical engine for geophysical  
simulation & inversion



GemPy

Geologic modelling

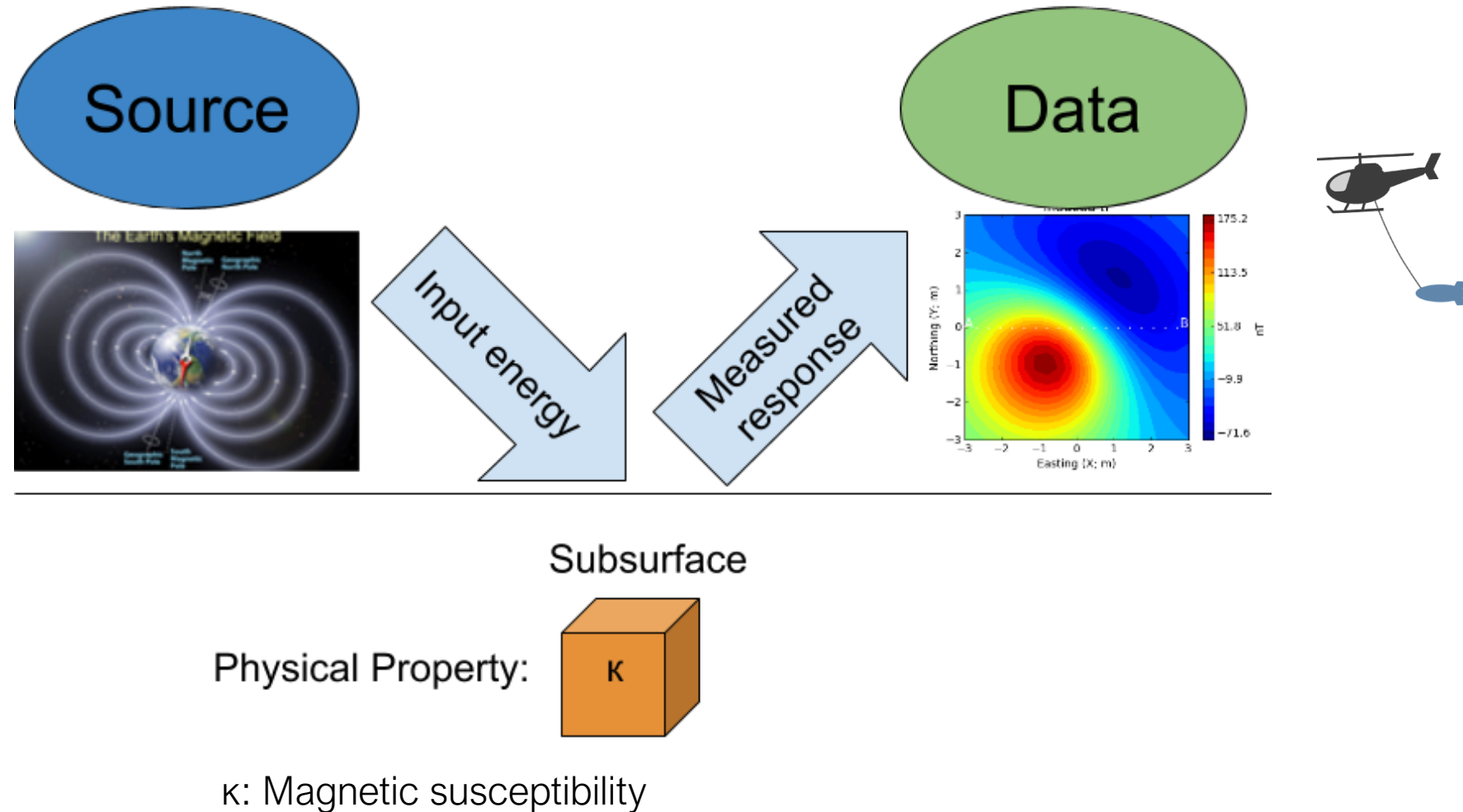


3D visualization

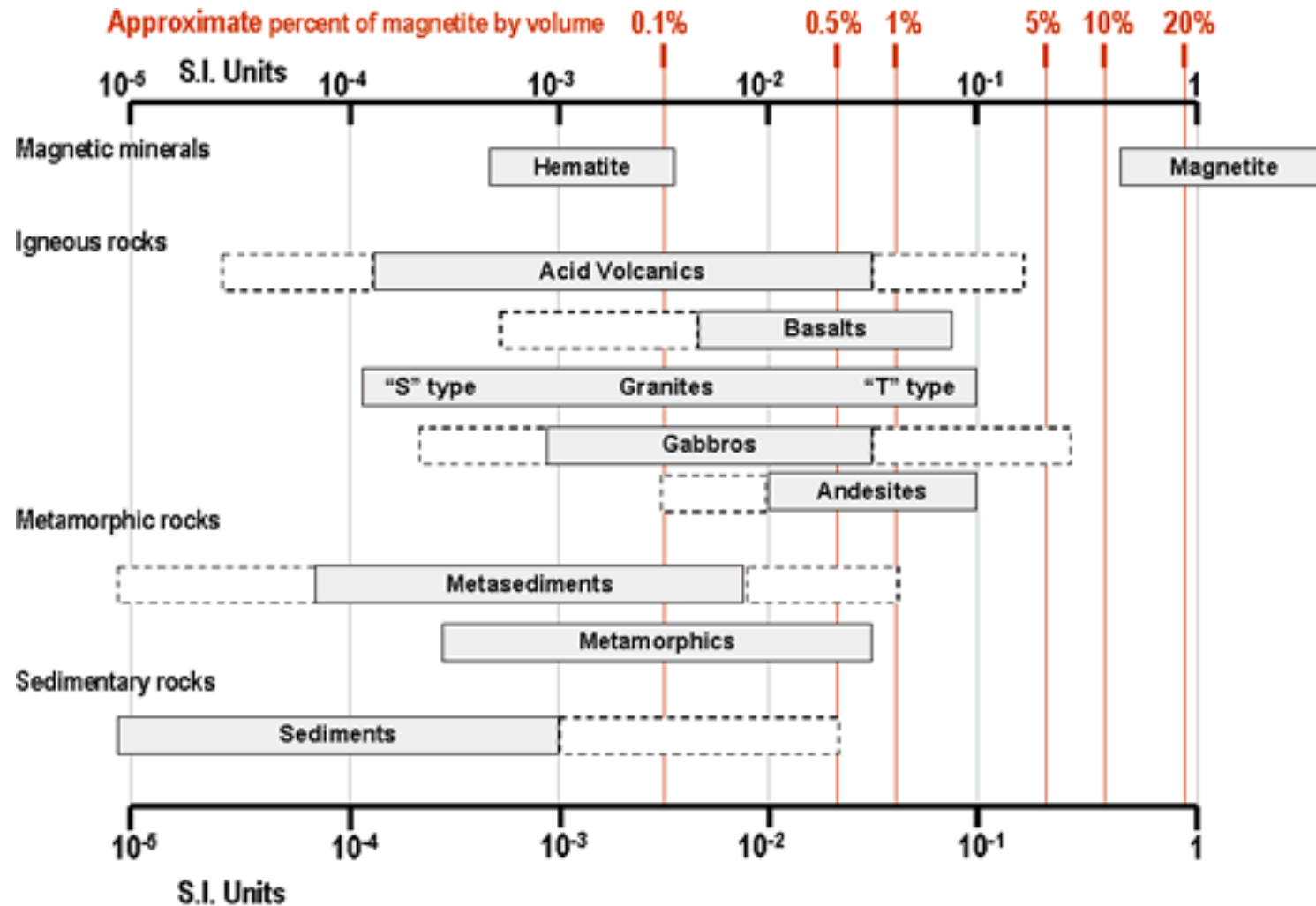
# My intention of this lecture

“*Not* for introducing how geophysical software packages work, *But* for providing fundamental concepts of the inversion”

# Survey: Magnetics



# Magnetic susceptibility



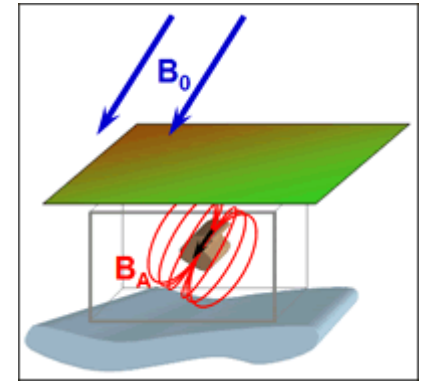
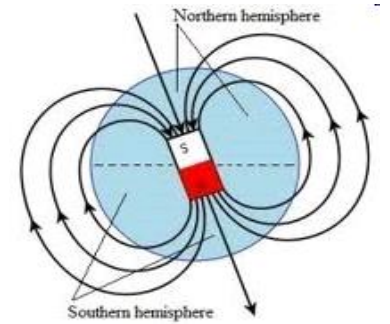
# Magnetic surveying

- Earth's magnetic field  $\vec{B}_0$  is the source:
- Materials become magnetized

Magnetic Susceptibility  $\leftarrow \vec{M} = \kappa \vec{H}_0$  (magnetization)

$$\vec{H}_0 = \vec{B}_0 / \mu_0$$

- Create anomalous magnetic field



# Magnetic surveying

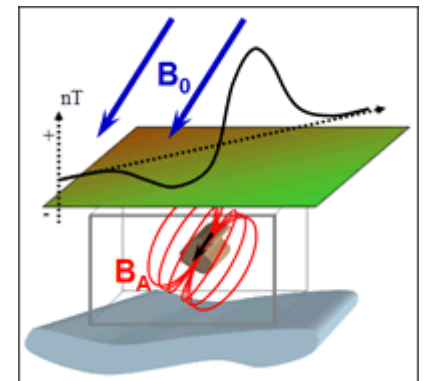
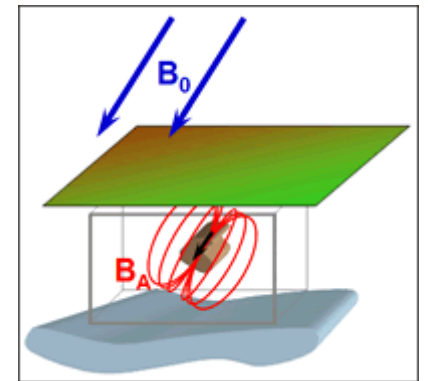
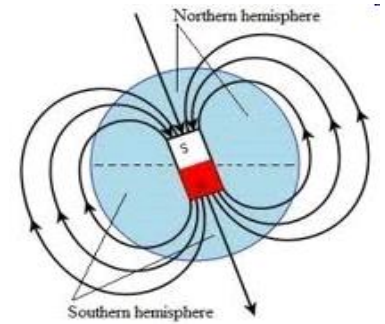
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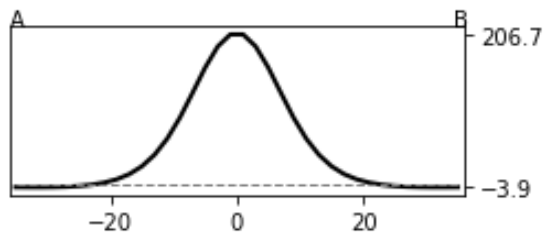
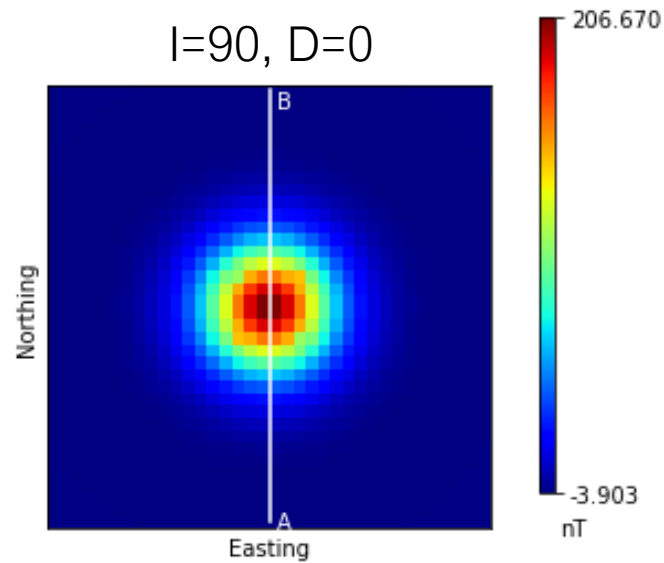
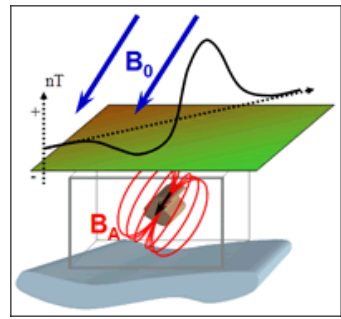
- Create anomalous magnetic field
- Measure total magnetic field:  $|\vec{B}| = |\vec{B}_0 + \vec{B}_A|$

- Total field anomaly:  $\Delta \vec{B} = |\vec{B}_0 + \vec{B}_A| - |\vec{B}_0|$   
 $\Delta \vec{B} \simeq \vec{B}_A \cdot \hat{B}_0$  where  $\hat{B}_0 = \frac{\vec{B}_0}{|\vec{B}_0|}$



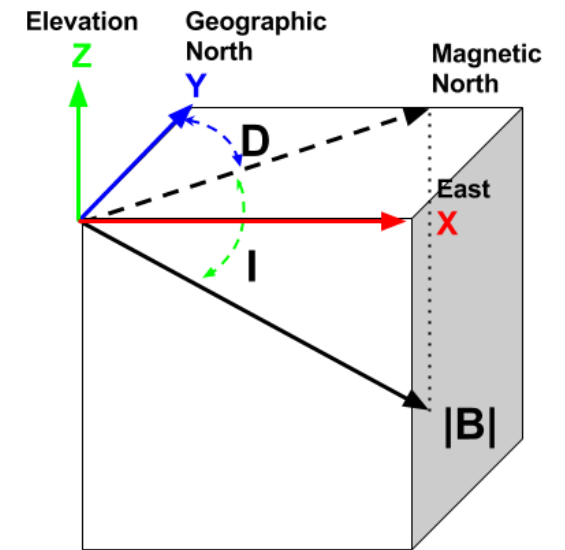
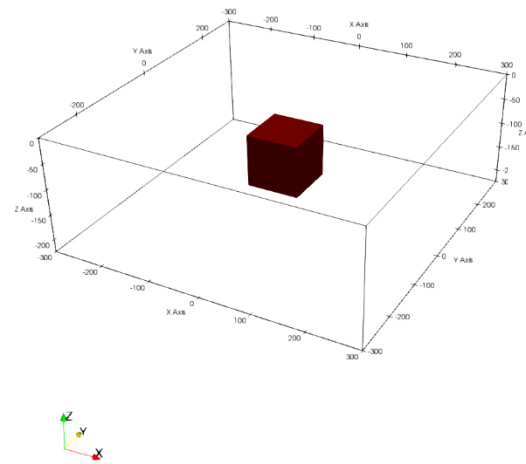


# Magnetic data changes depending upon where you are

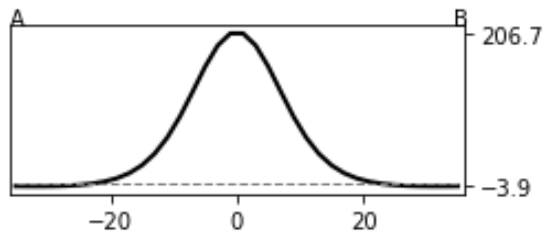
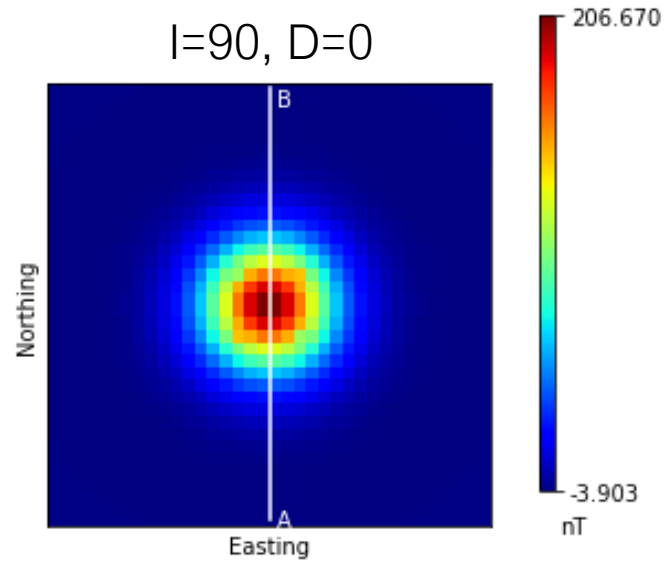
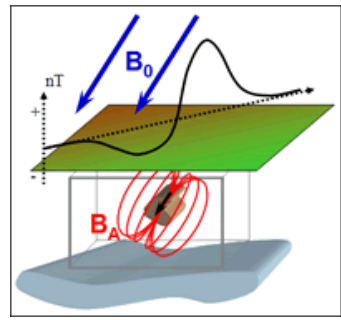


Magnetic pole

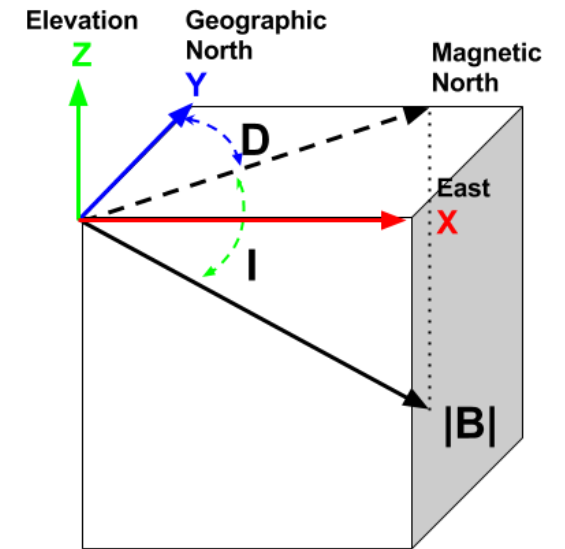
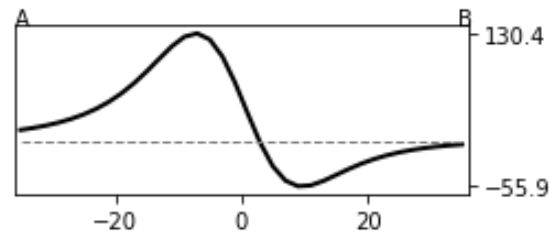
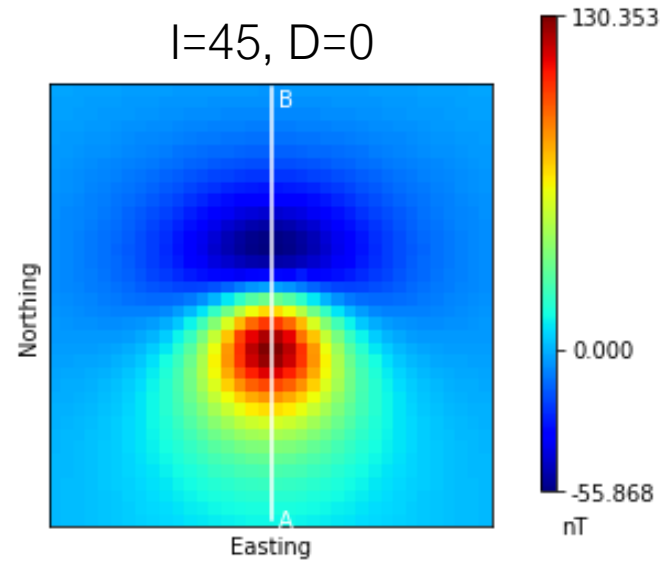
A prism in a homogeneous subsurface



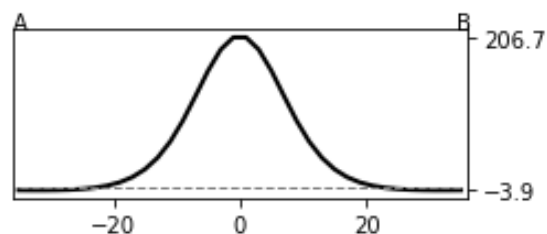
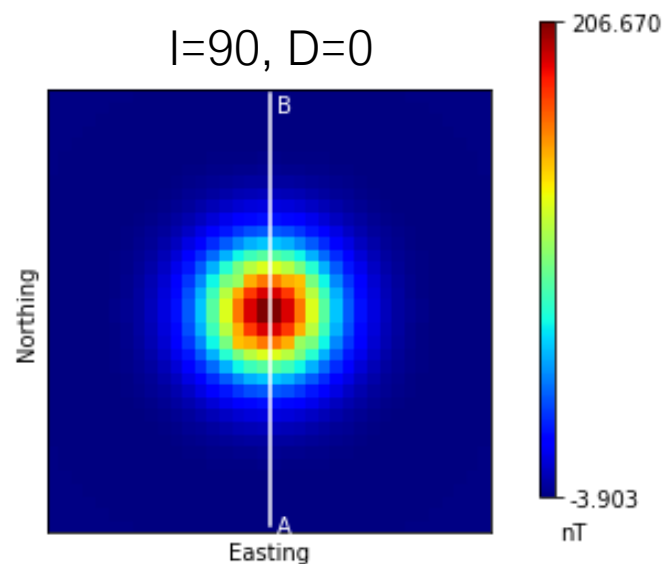
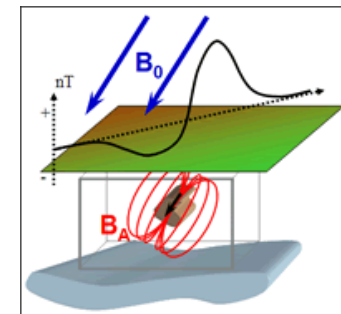
# Magnetic data changes depending upon where you are



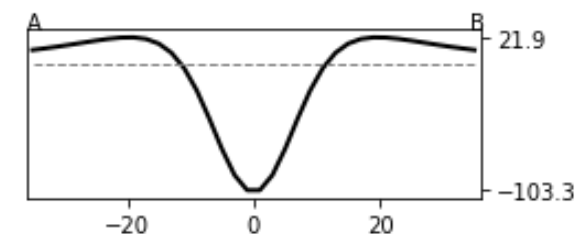
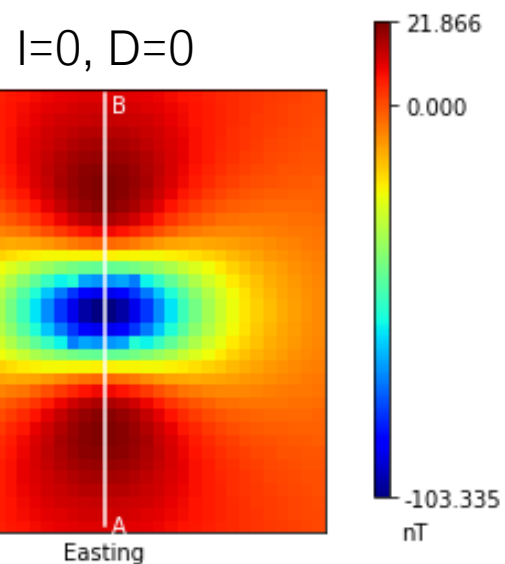
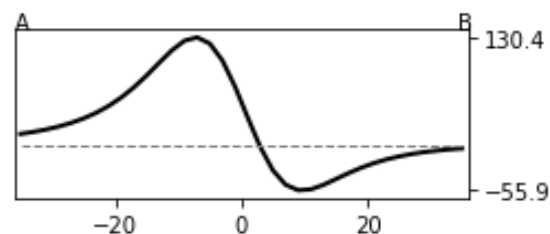
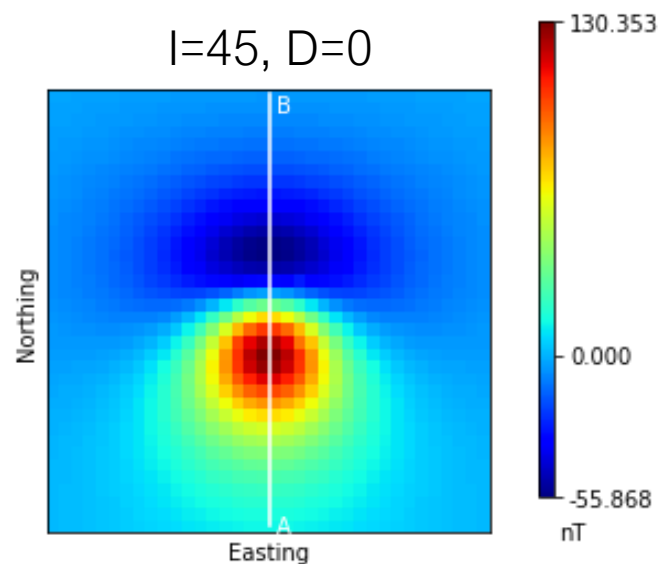
Magnetic pole



# Magnetic data changes depending upon where you are

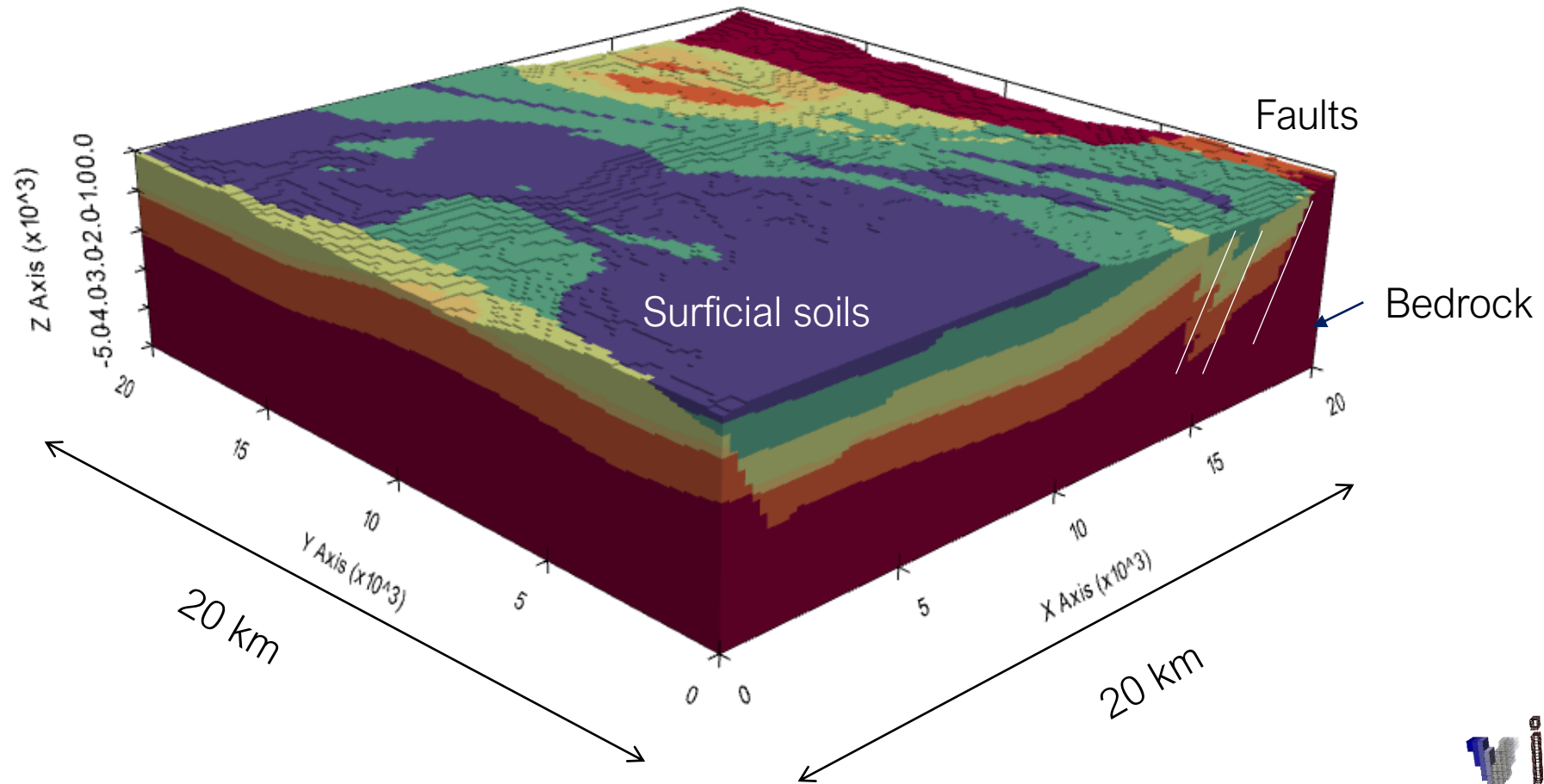


North pole

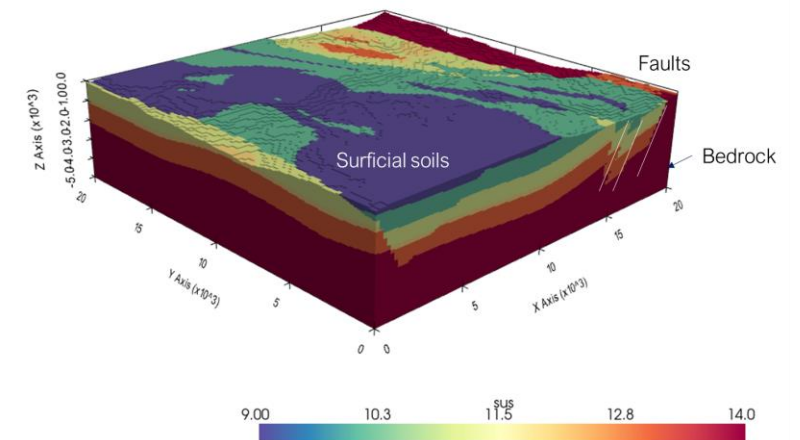
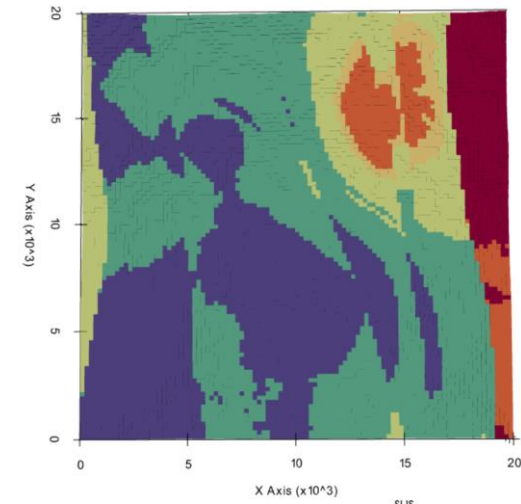
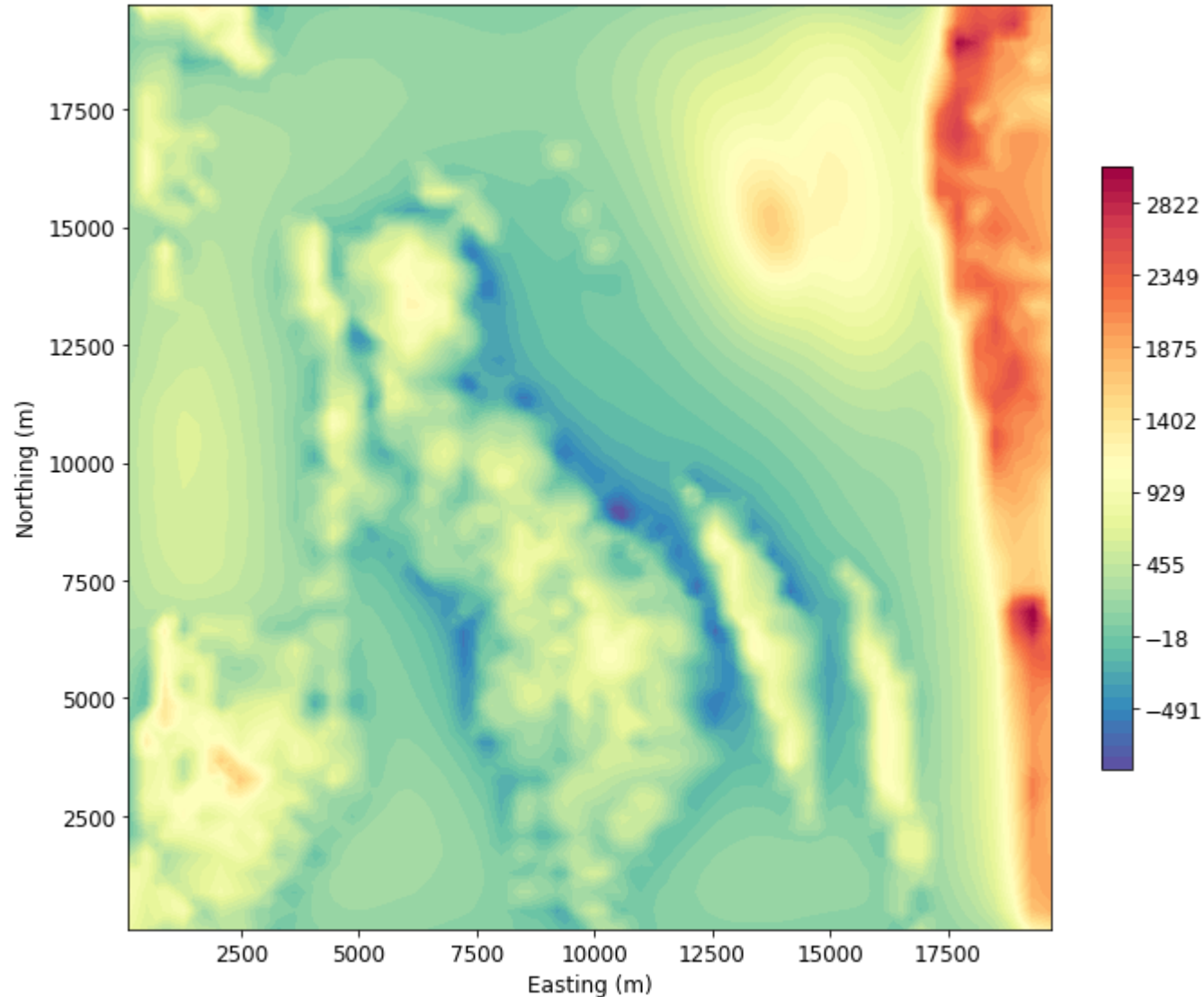


Equator

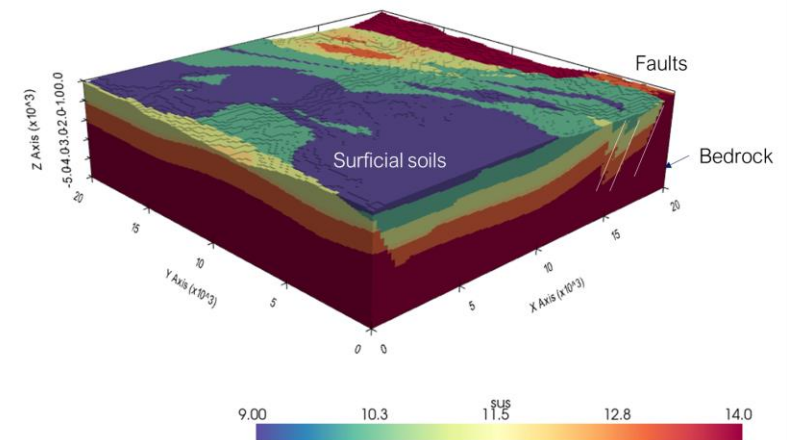
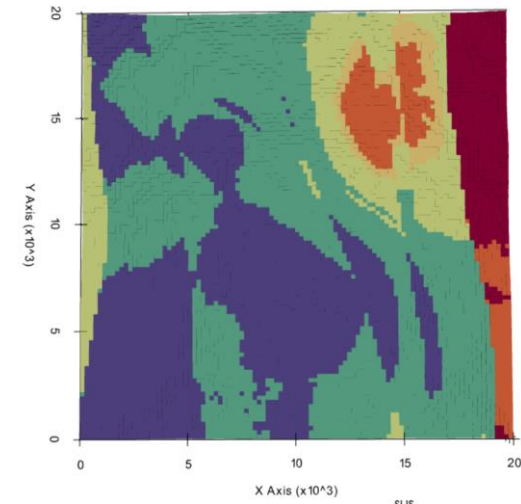
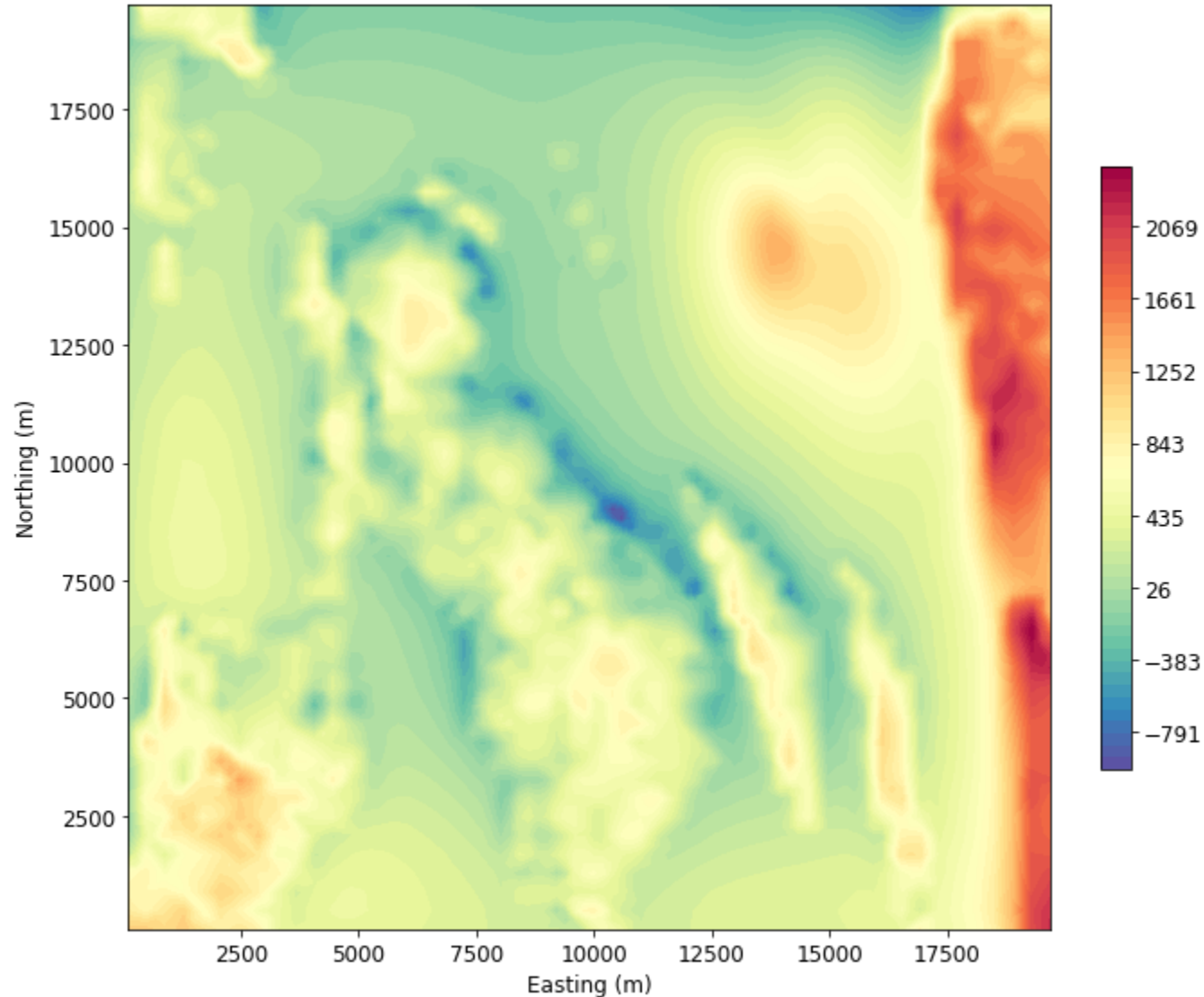
# Subsurface structure is complex



# Measured magnetic data at $I=90$ , $D=0$ (Magnetic pole)

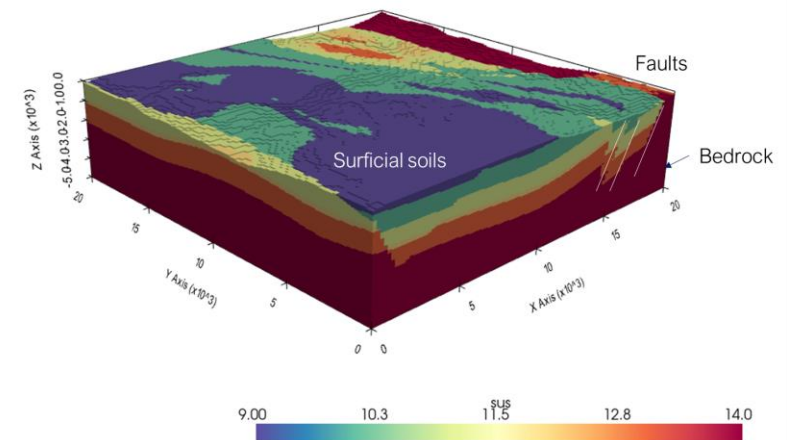
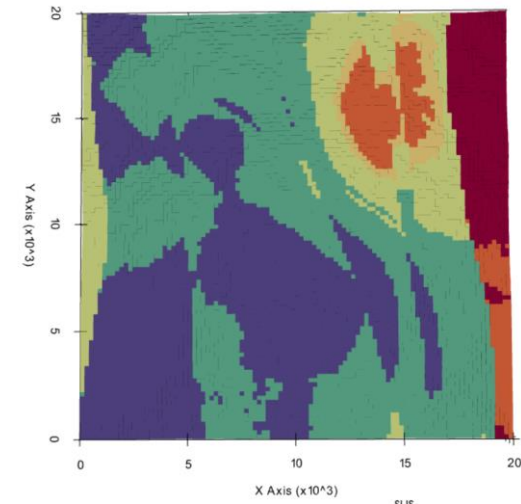
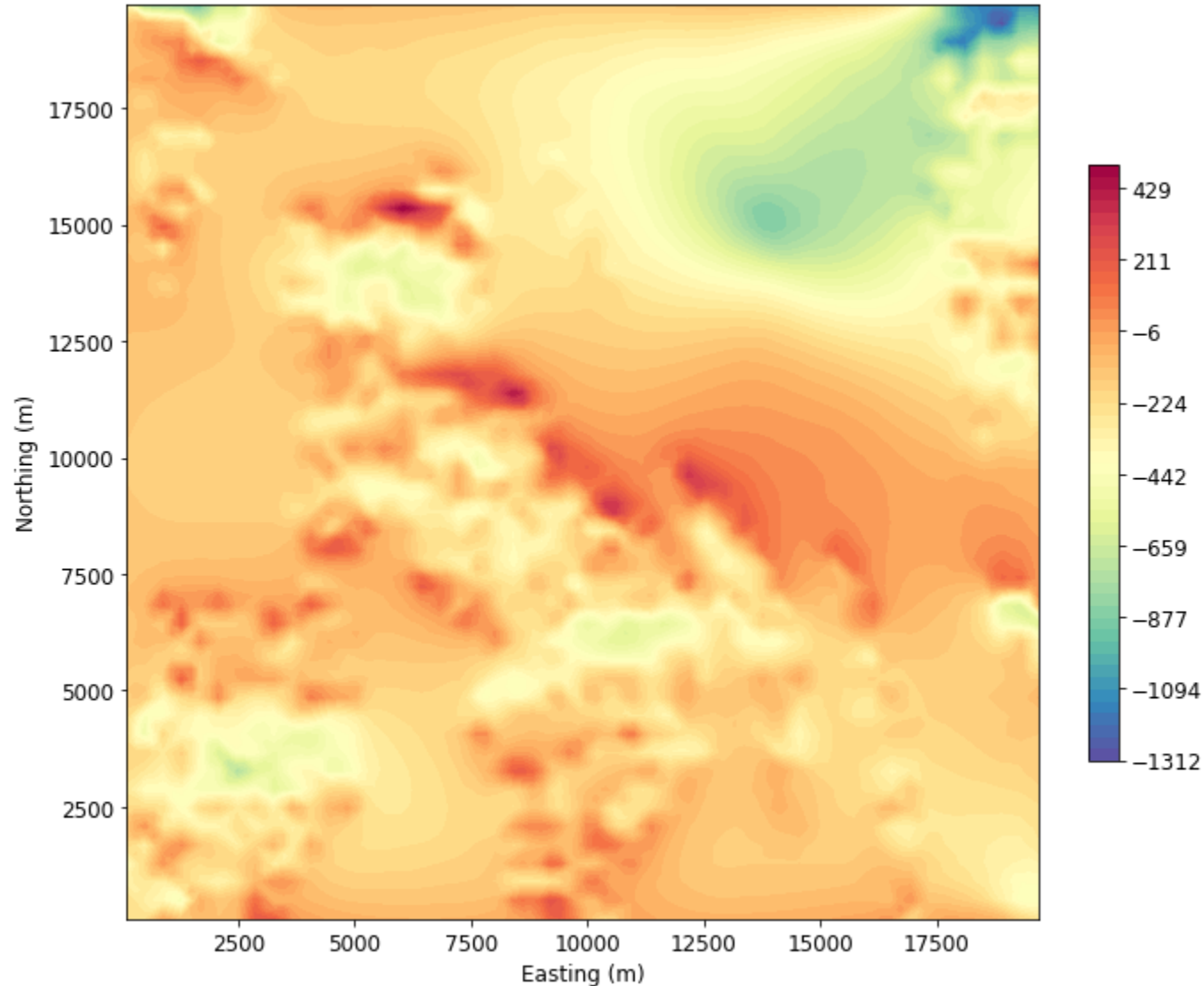


# Measured magnetic data at I=66, D=-6 (California)

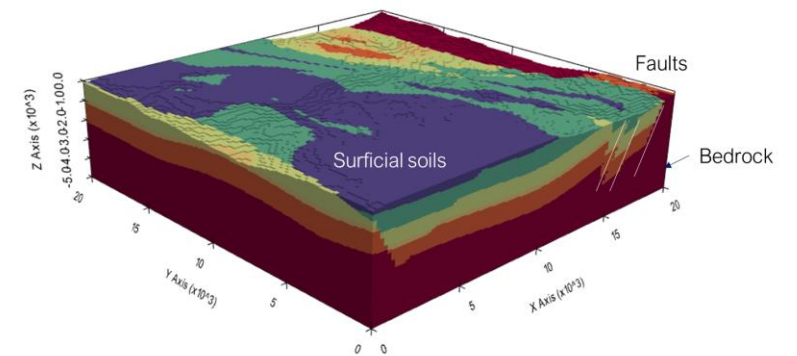
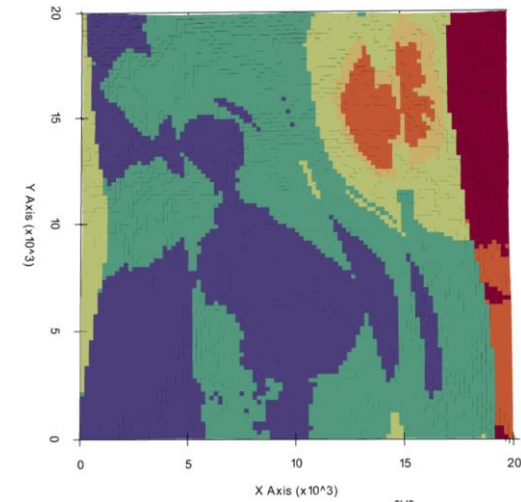
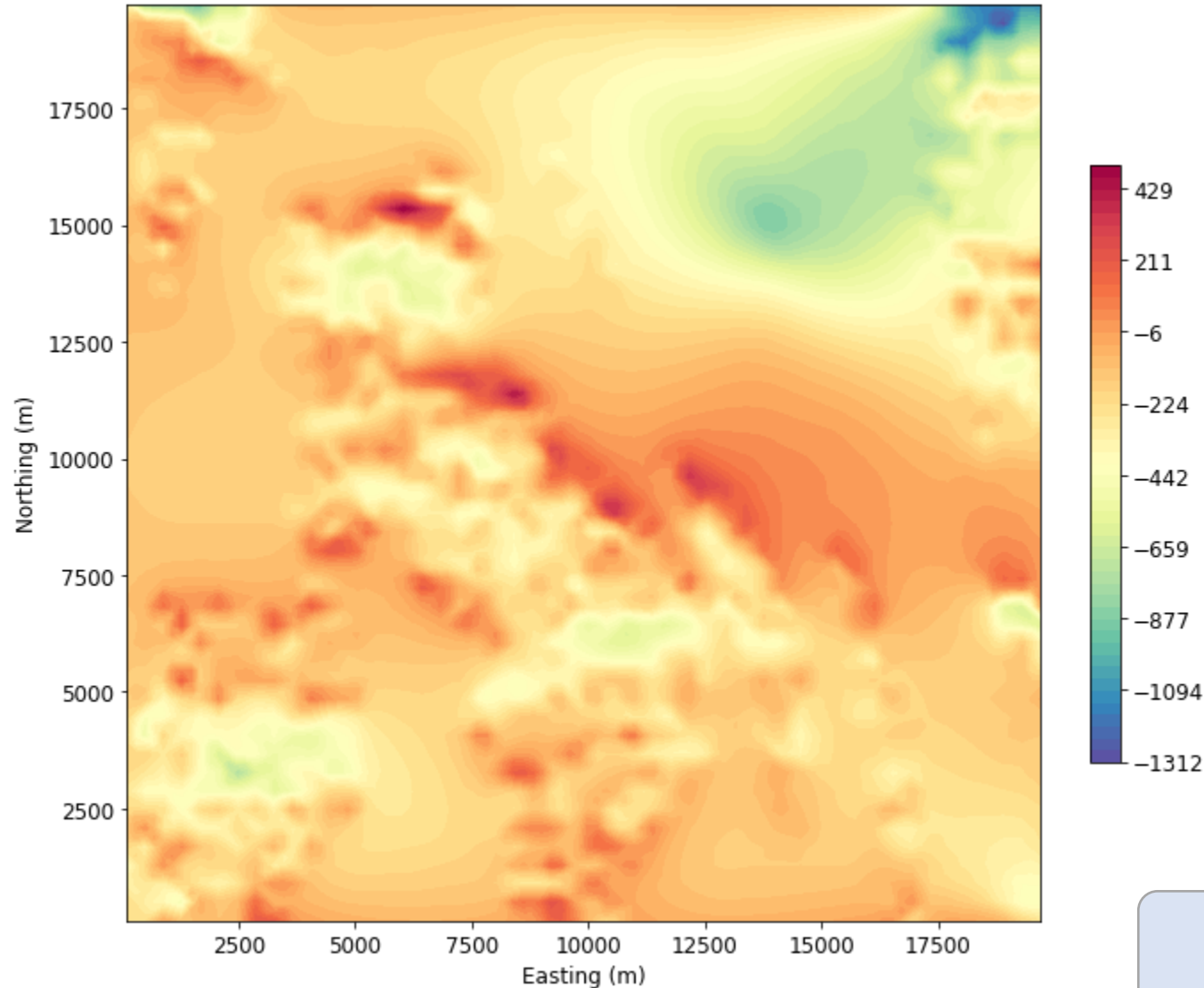




# Measured magnetic data at $I=0$ , $D=0$ (Equator)



# Measured magnetic data at $I=0$ , $D=0$ (Equator)



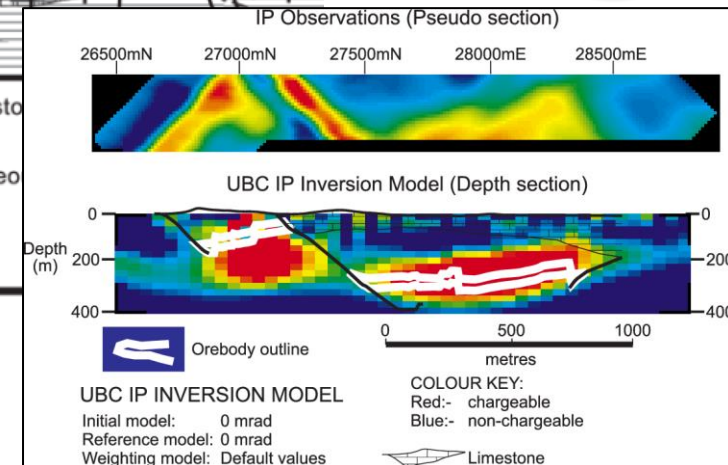
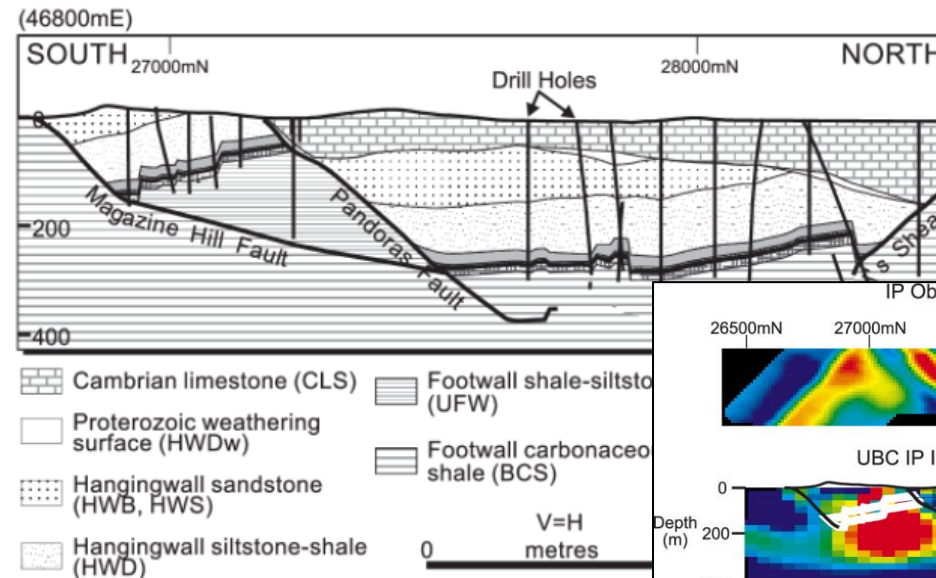
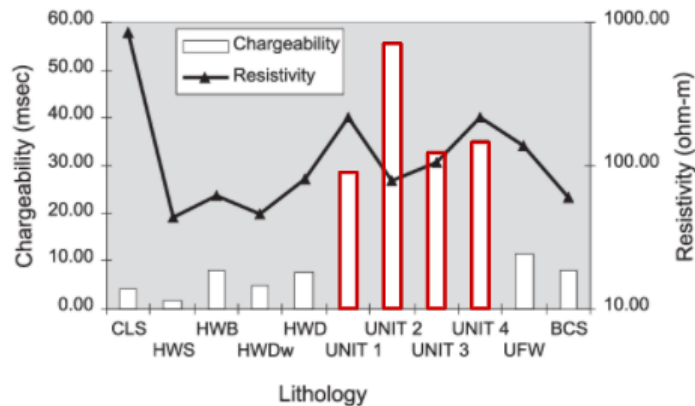
Measured data are large & complex

motivating field example

# Transform 2020: Lindsey Heagy (DC/IP methods)

## Century Deposit: geology + physical properties

- Resistivity: structure, input to IP
- Chargeability: Associated with mineralization



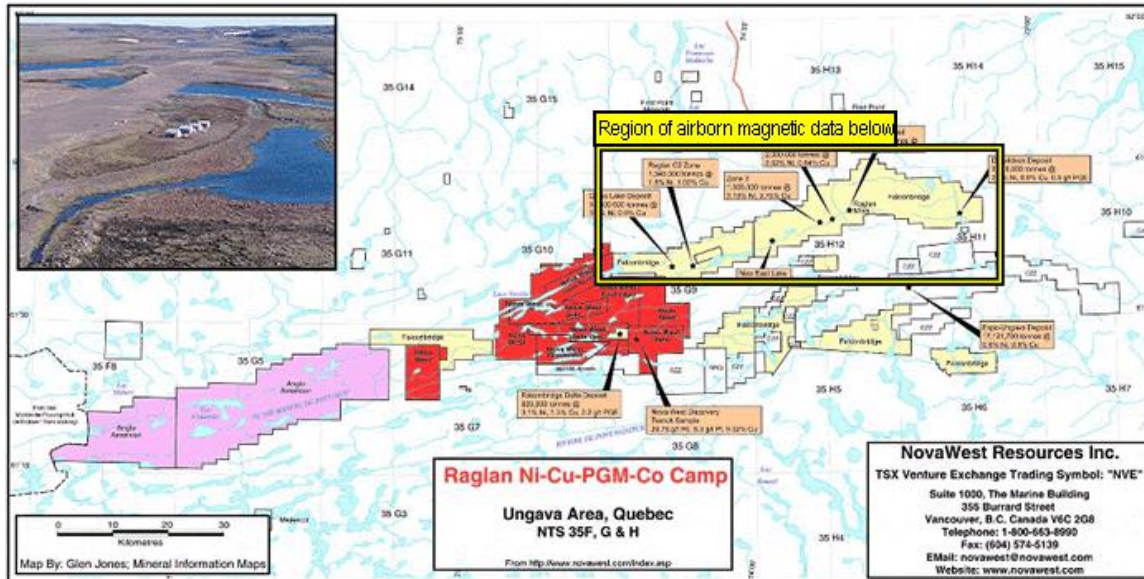
Reproduce the historic geophysical inversion results which made a high impact to the mining community

ground-based geophysics

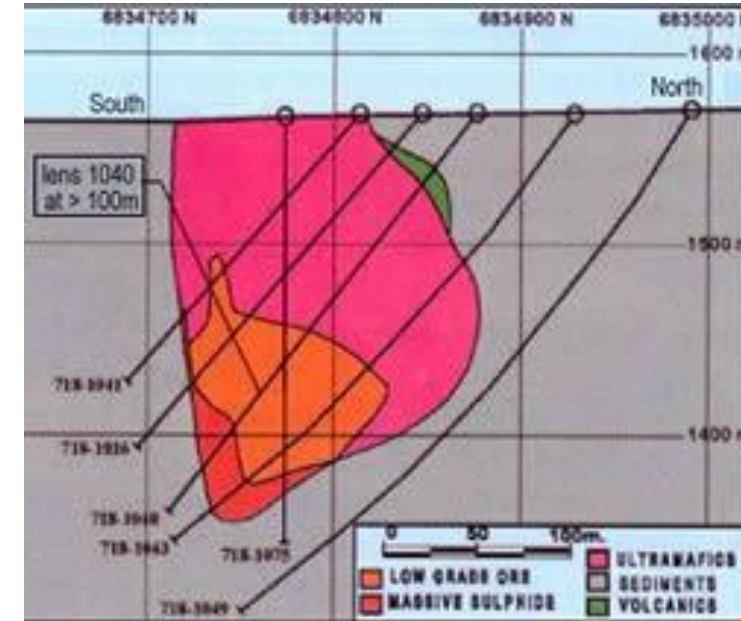


# Raglan Deposit: geology + physical properties

Location map (Northern Quebec, Canada)



Geologic section



## Physical properties

**Grey rocks** are host sediments.

**Green rocks** are volcanics.

**Pink rocks** are ultramafics (susceptibility 0.03 - 0.07 S.I.).

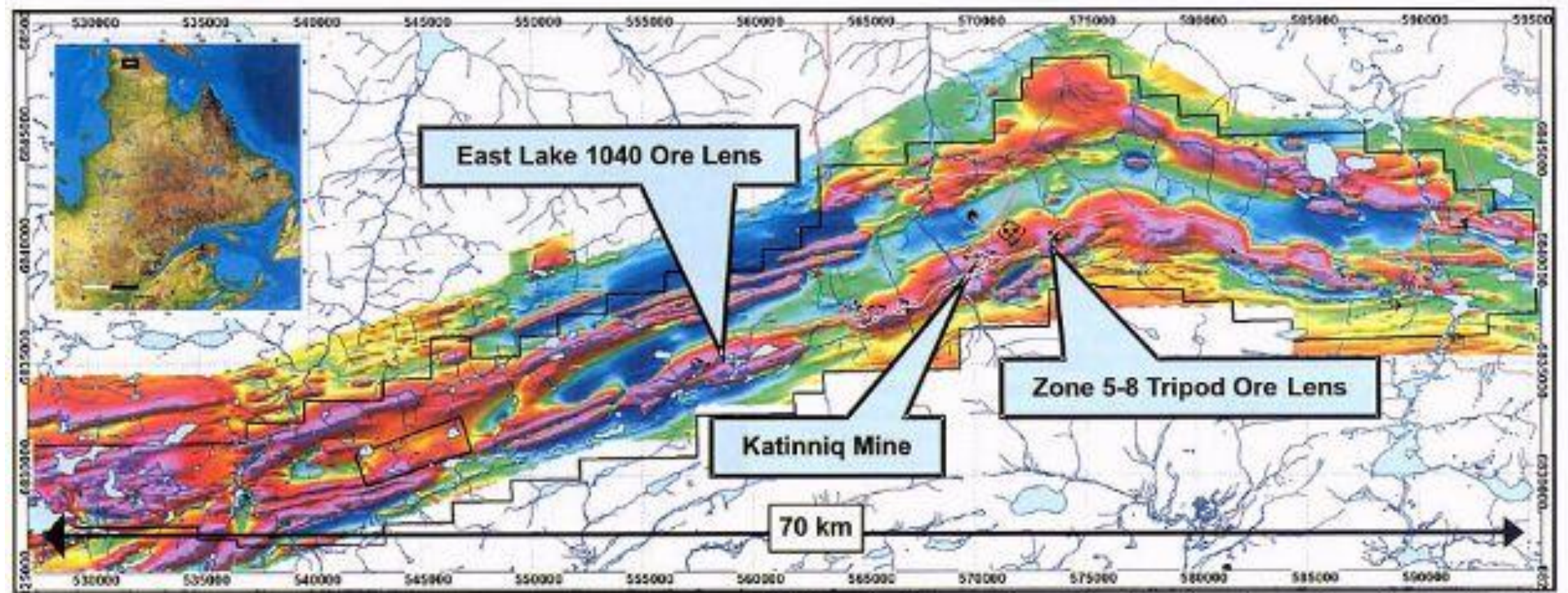
**Orange rocks** are low grade massive ore (susceptibility 0.03 - 0.07 S.I.).

**Red rocks** are the primary massive sulphide ore (susceptibility 0.03 - 0.07 S.I.).

Seek for zones having a high susceptibility ( $\sim 0.04$  SI)



# Raglan Deposit: airborne magnetic data



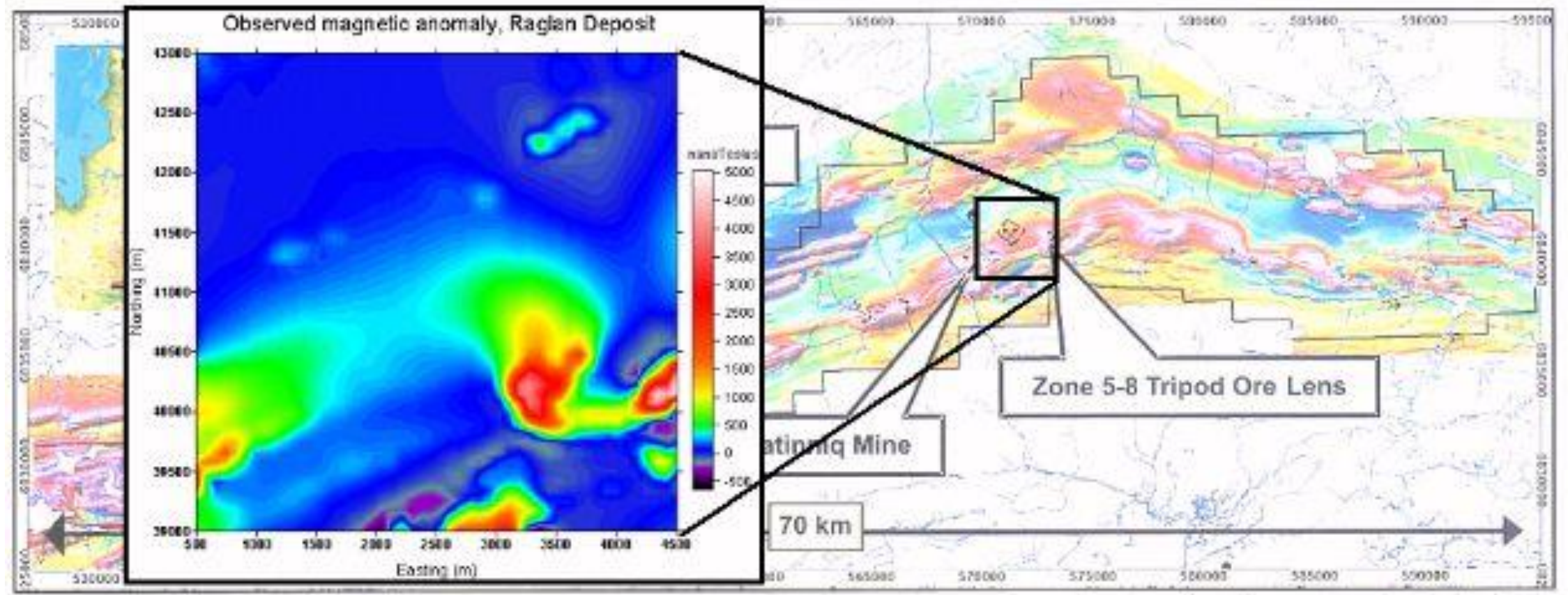
Low magnetic field intensity



High magnetic field intensity

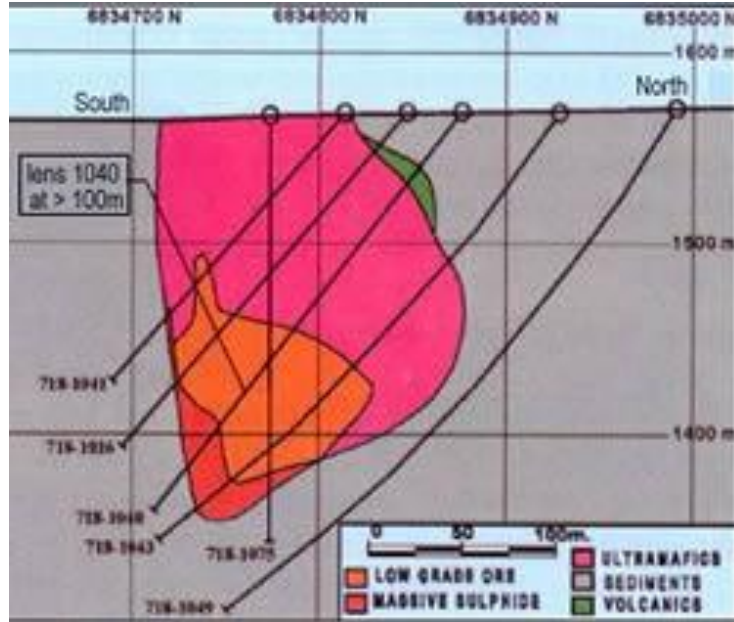


# Raglan Deposit: airborne magnetic data

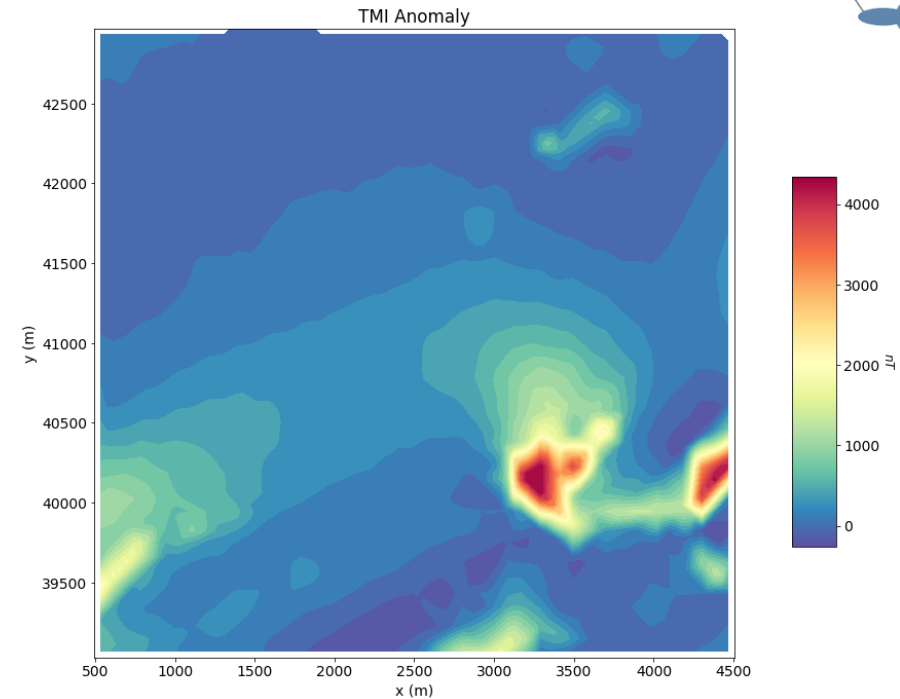


# Initial conceptual model

Geologic section

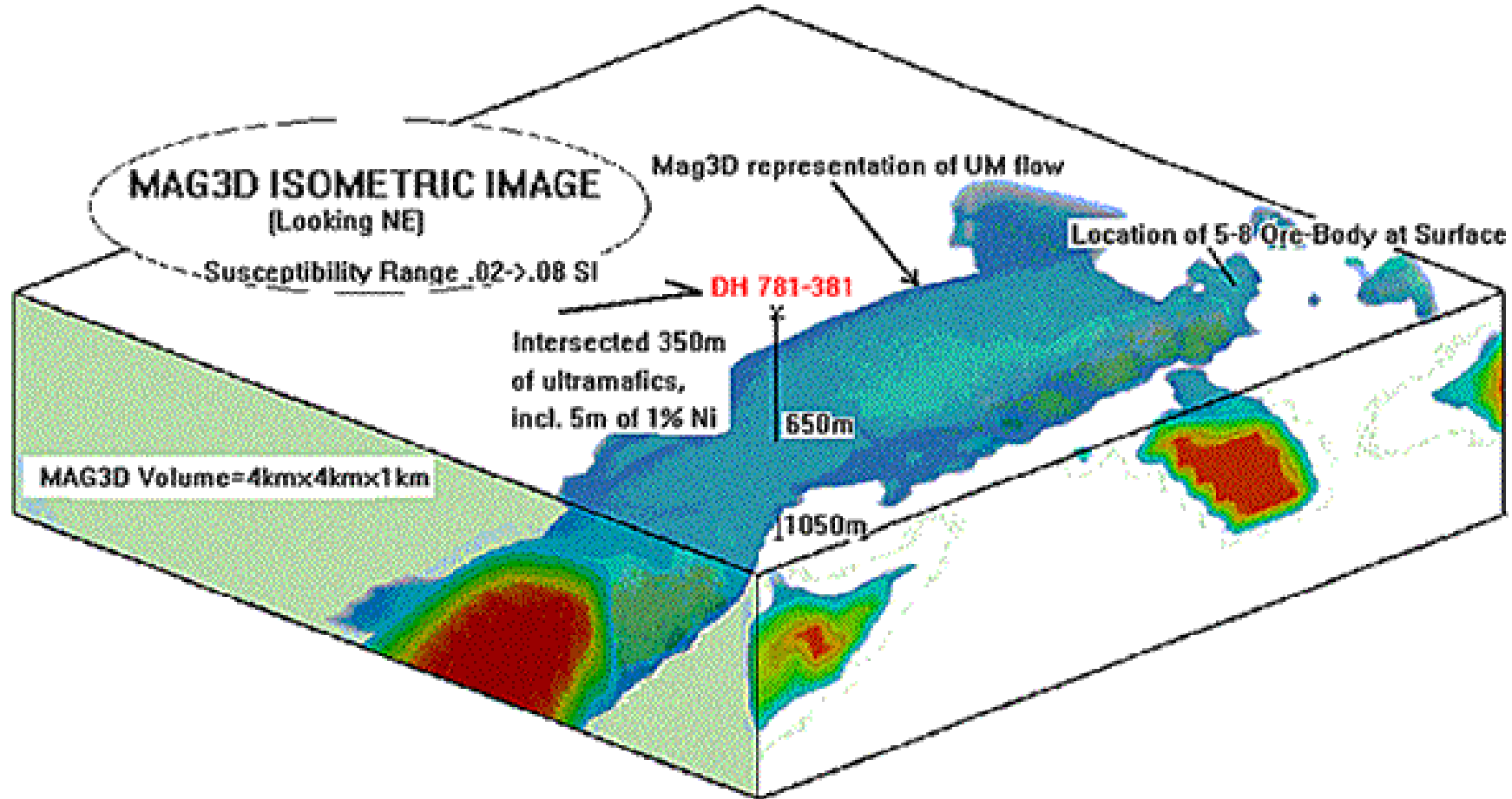


Magnetic data



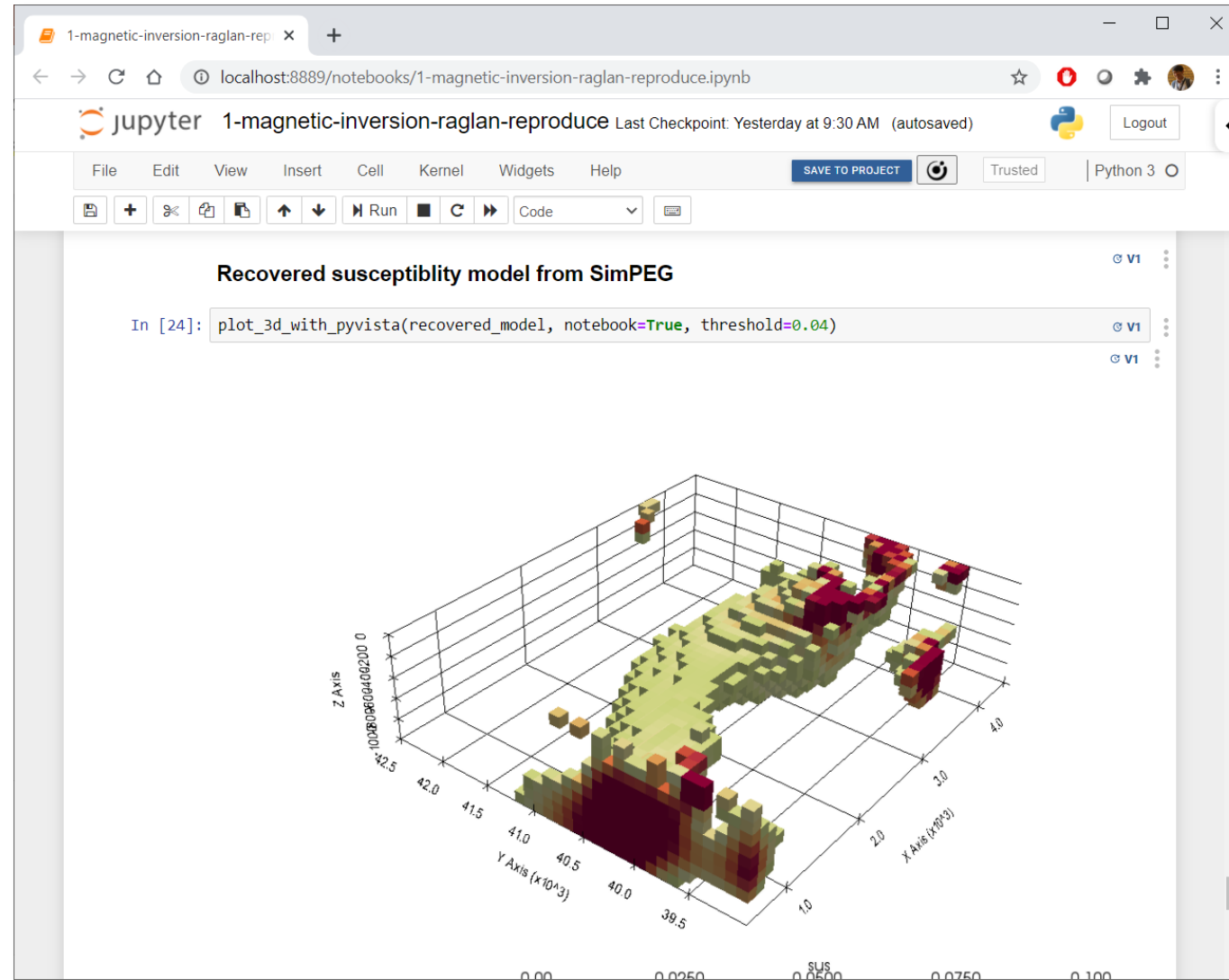
Initial conceptual model: two ultramafic pipes  
Can make impact on drilling location and mineral reserve

# Recovered susceptibility model from a 3D inversion



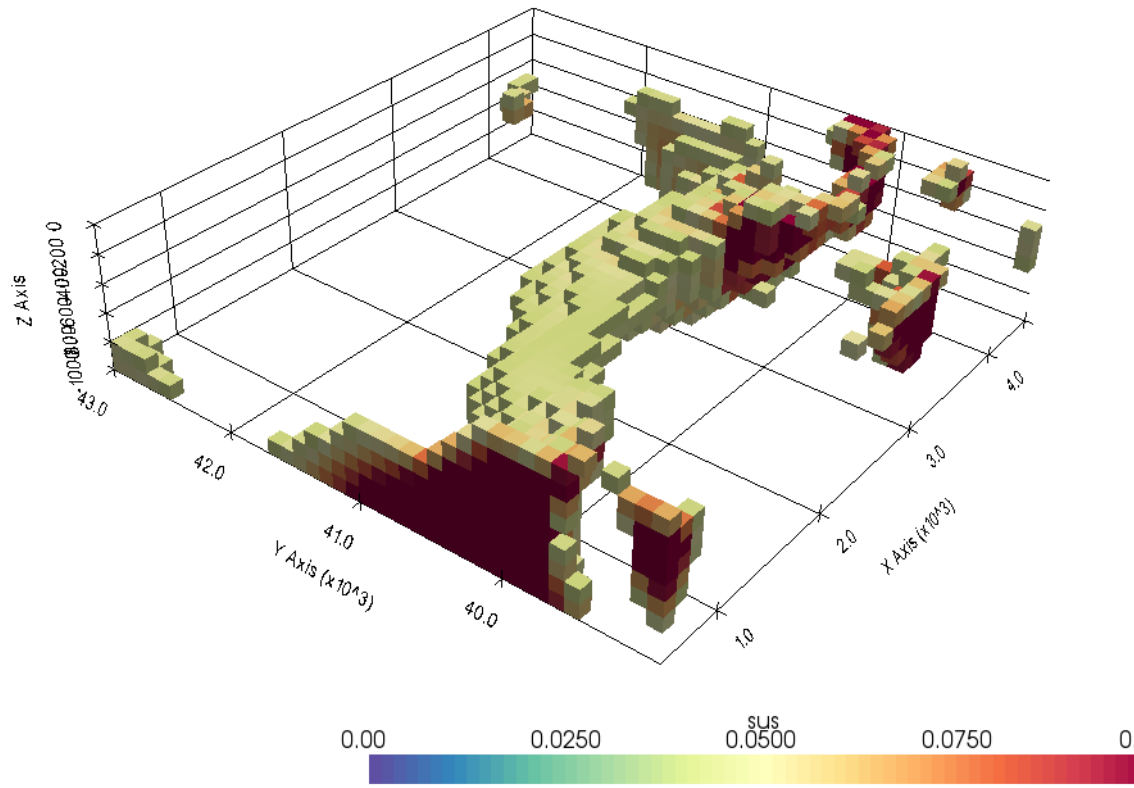
Changed the conceptual model: the two pipes are “connected”

# Can we reproduce this result?

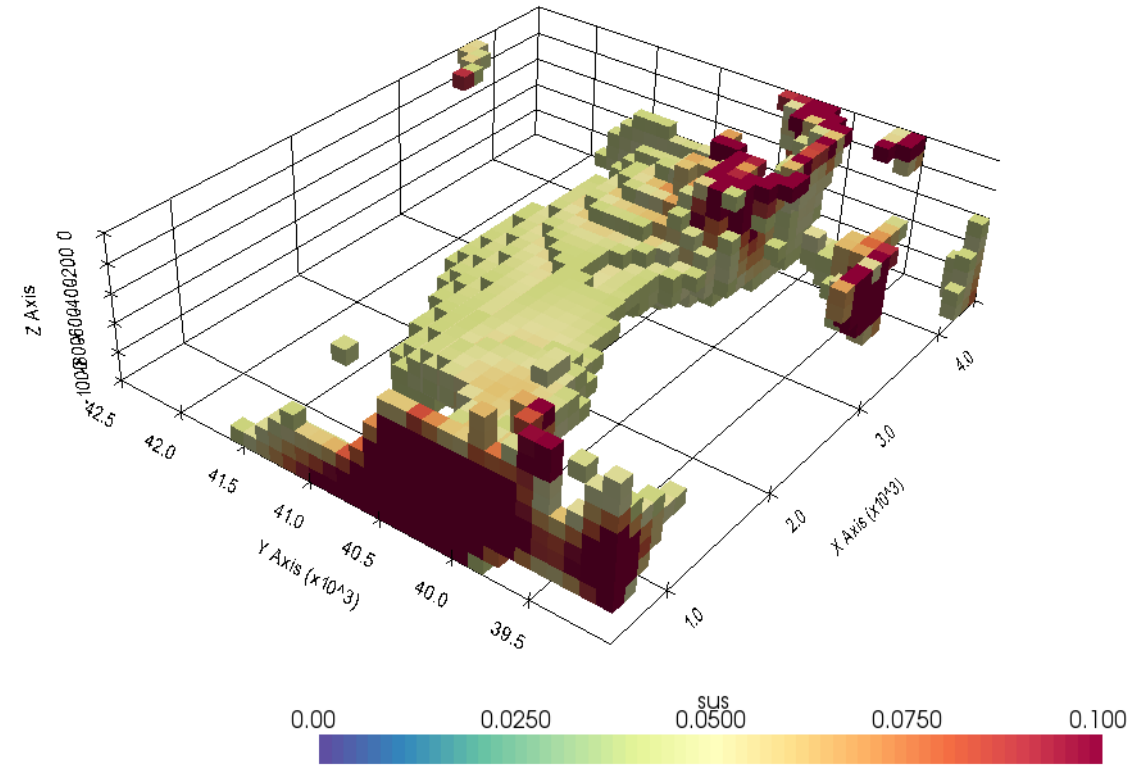


# Comparison

Model from 20 years ago (MAG3D)

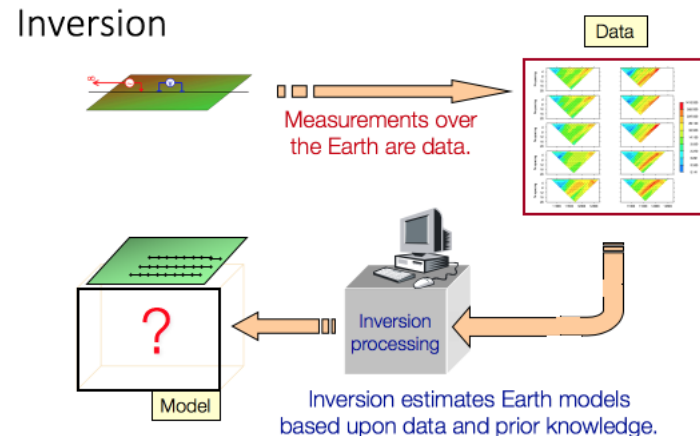
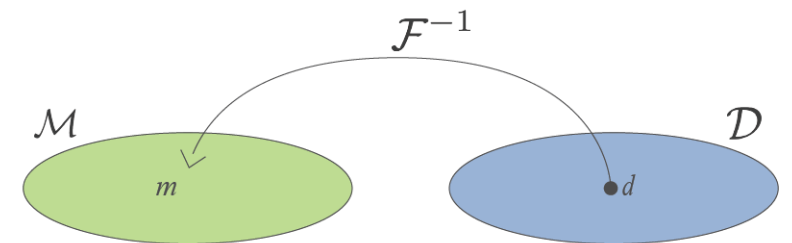
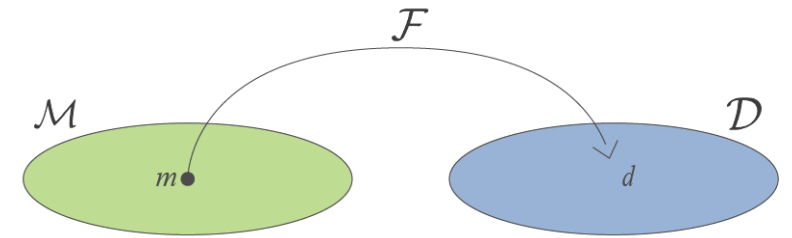


The recovered model (SimPEG)



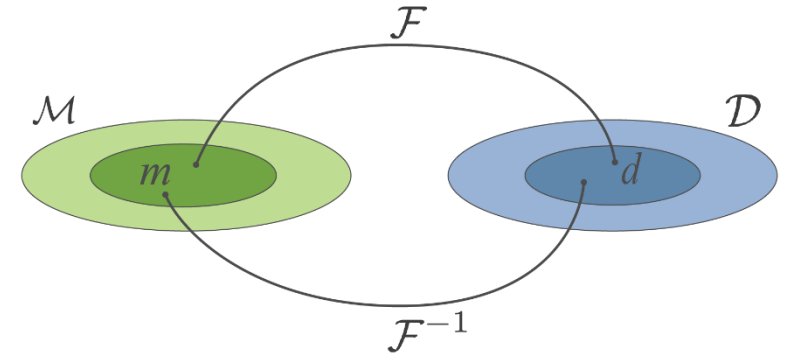
# Our statement of the inverse problem

- Given observations:  $d_j^{obs}$ ,  $j = 1, \dots, N$ 
  - Uncertainties:  $\epsilon_j$
  - Ability for forward modelling:  $\mathcal{F}[m] = d$
- Find the earth model that gave rise to the data.





# Inverse problem



- Non-unique
- Ill-conditioned



The Inverse Problem is ill-posed

Any inversion approach must address these issues

# Framework for the inverse problem

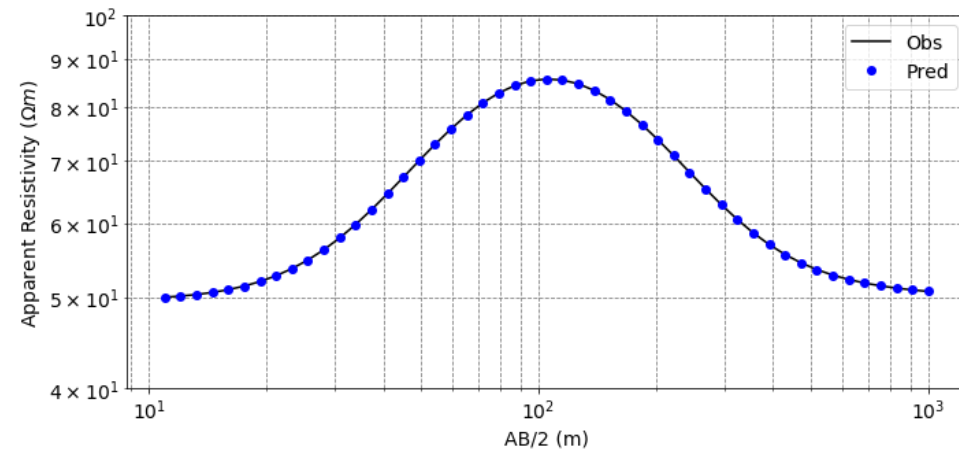
$$\text{minimize } \phi(m) = \phi_d(m) + \beta \phi_m(m)$$

$\phi_d$ : data misfit

$\phi_m$ : model norm

$\beta$ : trade-off parameter

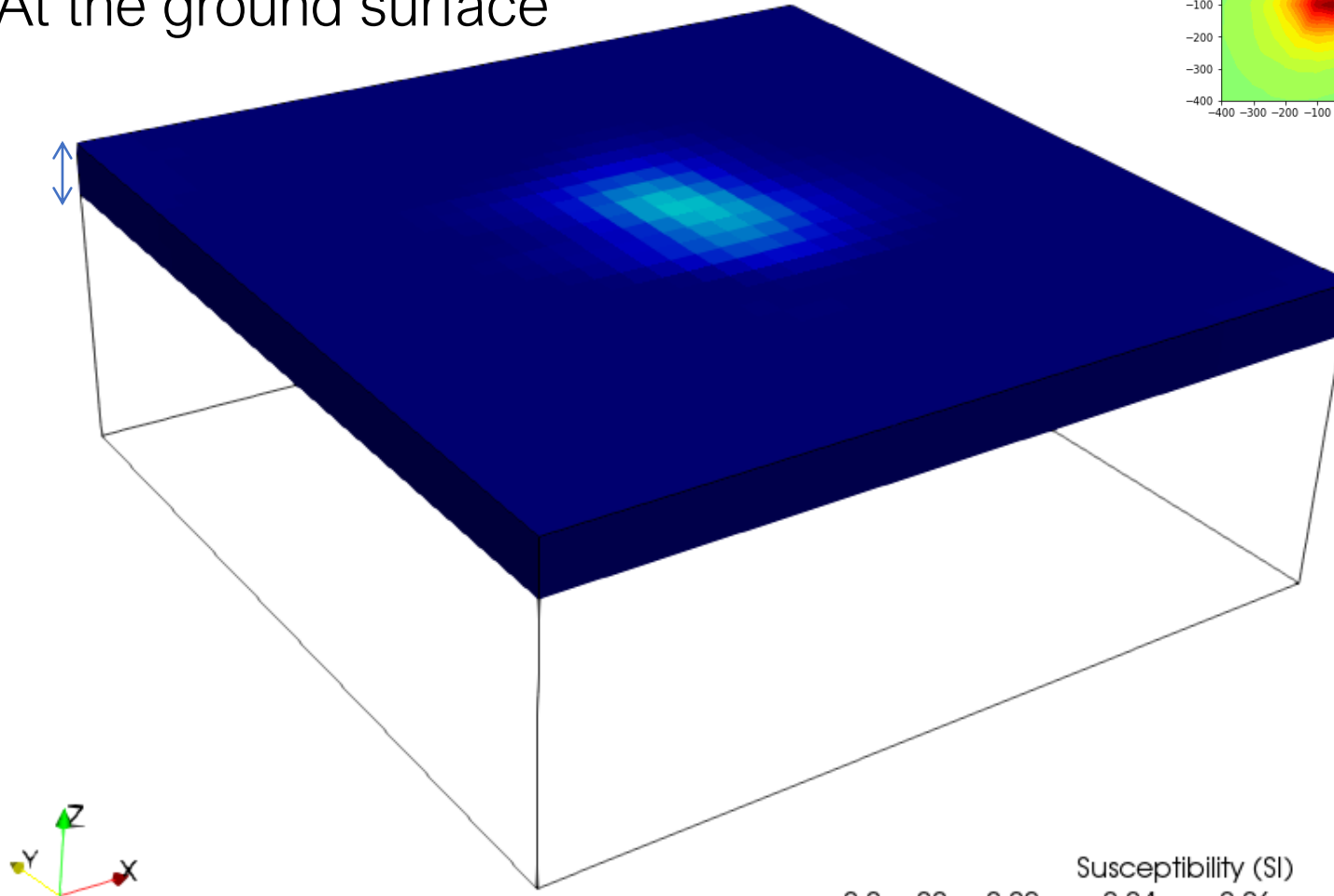
Find a model fitting the data



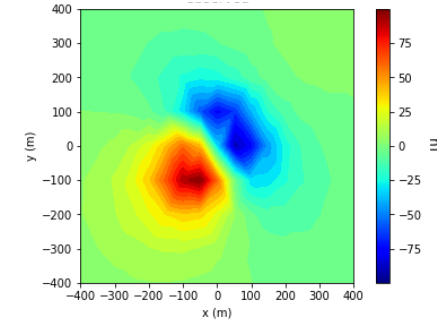
# Example of extreme non-uniqueness

At the ground surface

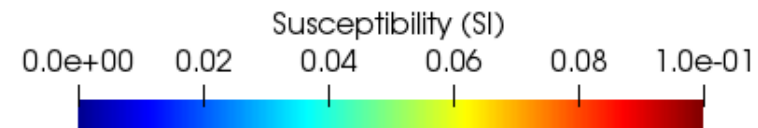
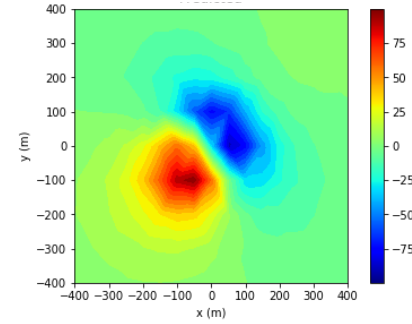
100 m



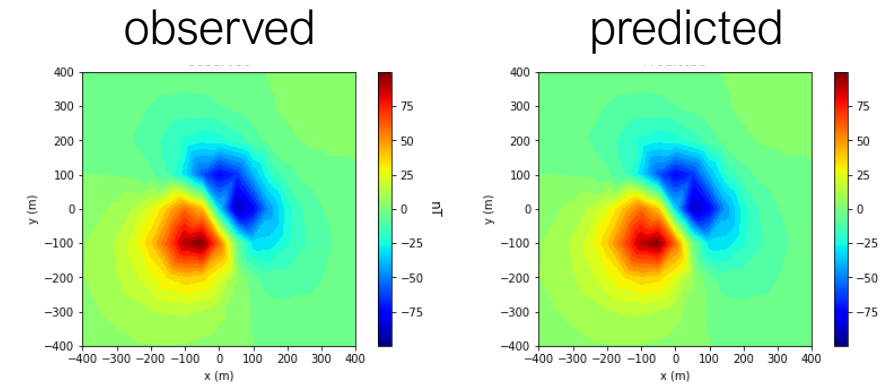
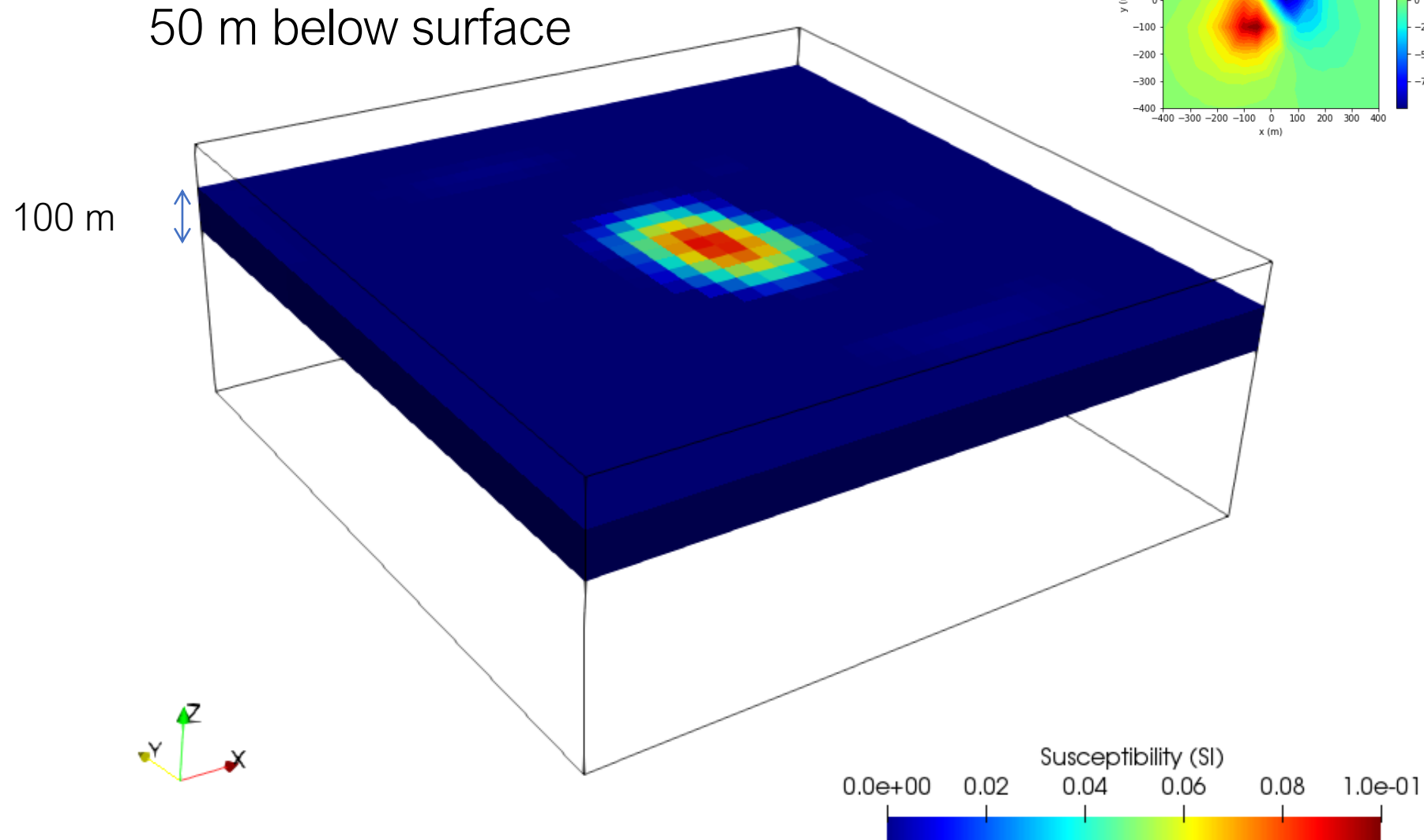
observed



predicted



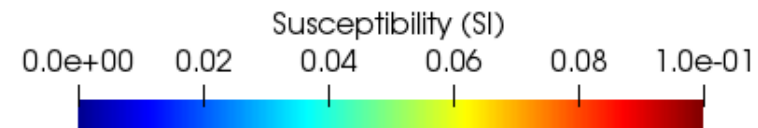
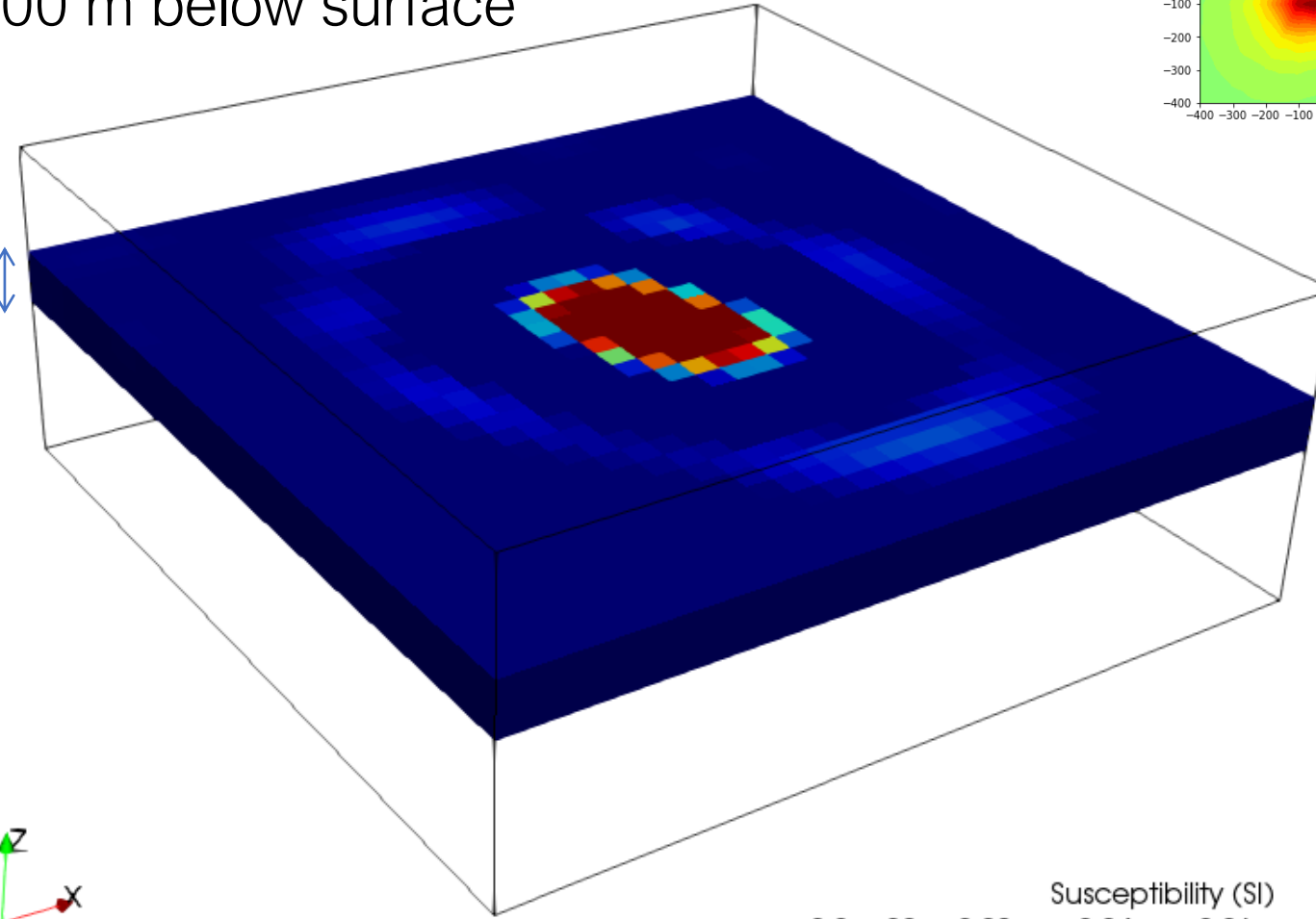
# Example of extreme non-uniqueness



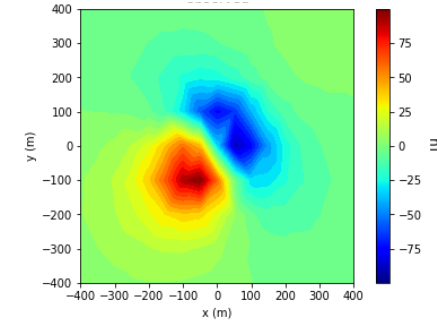
# Example of extreme non-uniqueness

100 m below surface

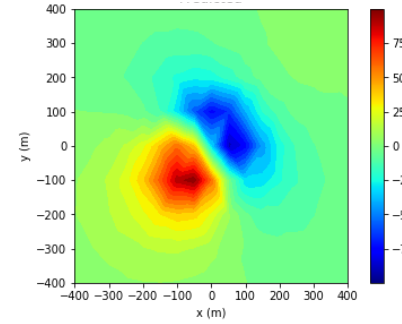
100 m



observed



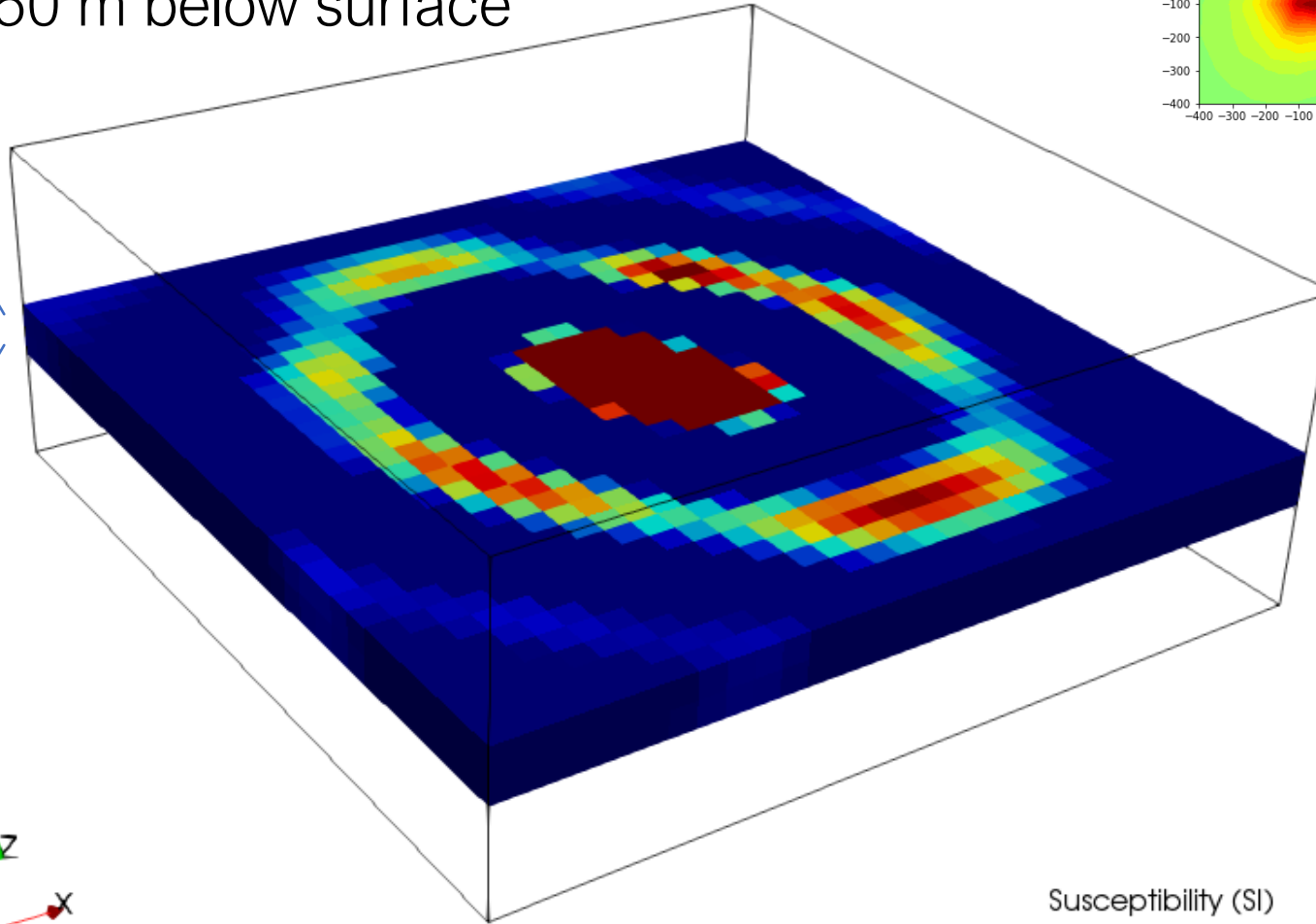
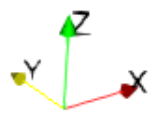
predicted



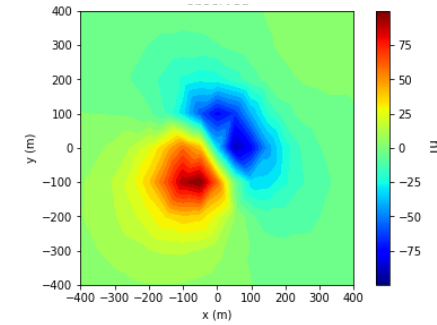
# Example of extreme non-uniqueness

150 m below surface

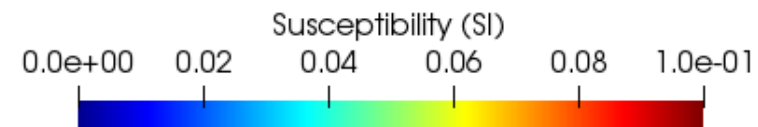
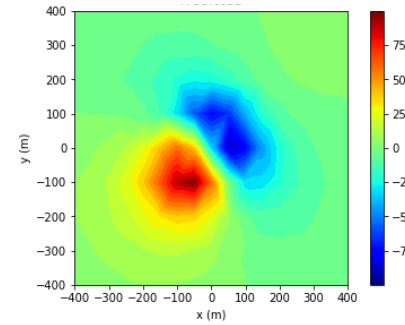
100 m



observed



predicted



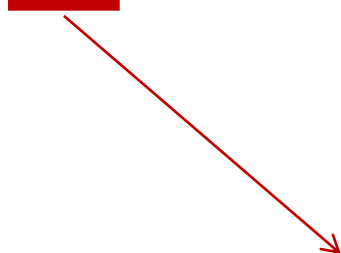
# Framework for the inverse problem

minimize  $\phi(m) = \phi_d(m) + \beta \phi_m(m)$

$\phi_d$ : data misfit  
 $\phi_m$ : model norm  
 $\beta$ : trade-off parameter



Find a model fitting the data



Find a model favoring prior knowledge

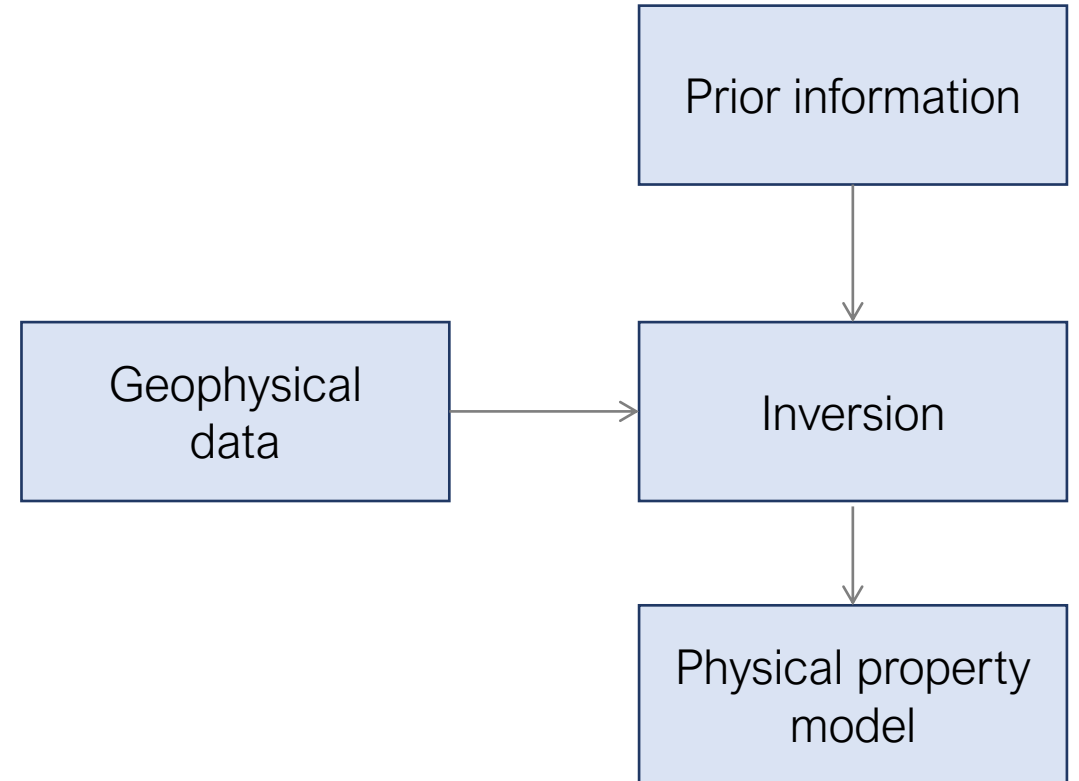
- drillers' logs
- geophysical logs (e.g., resistivity)
- spatial patterns
- other geophysical data (e.g., seismic)
- ....



# Constraining the inversion

What information is available?

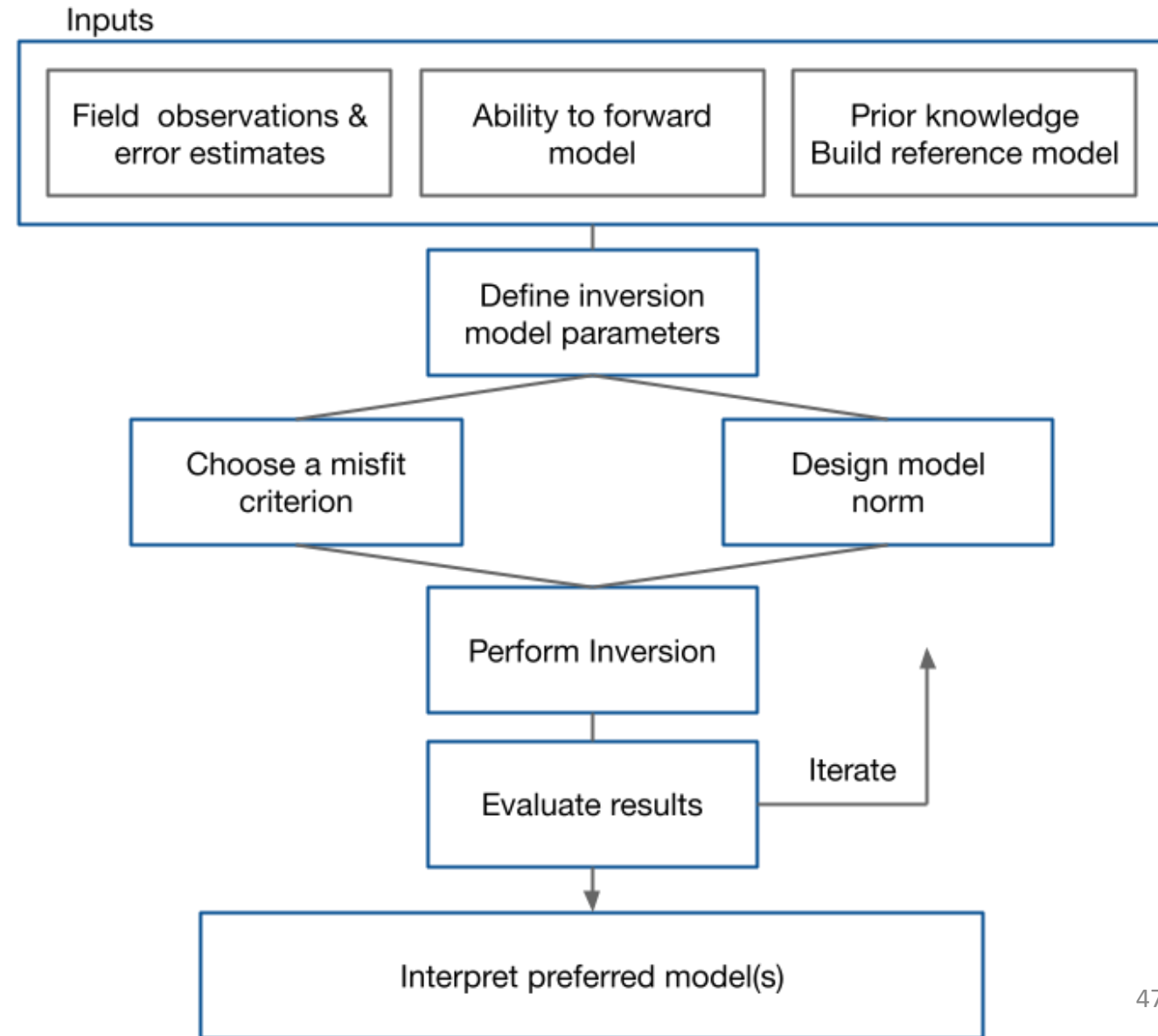
- Geologic structure
- Geologic constraints
- Reference model
- Bounds
- Multiple data sets
- Physical property measurements



How do we achieve our goal?

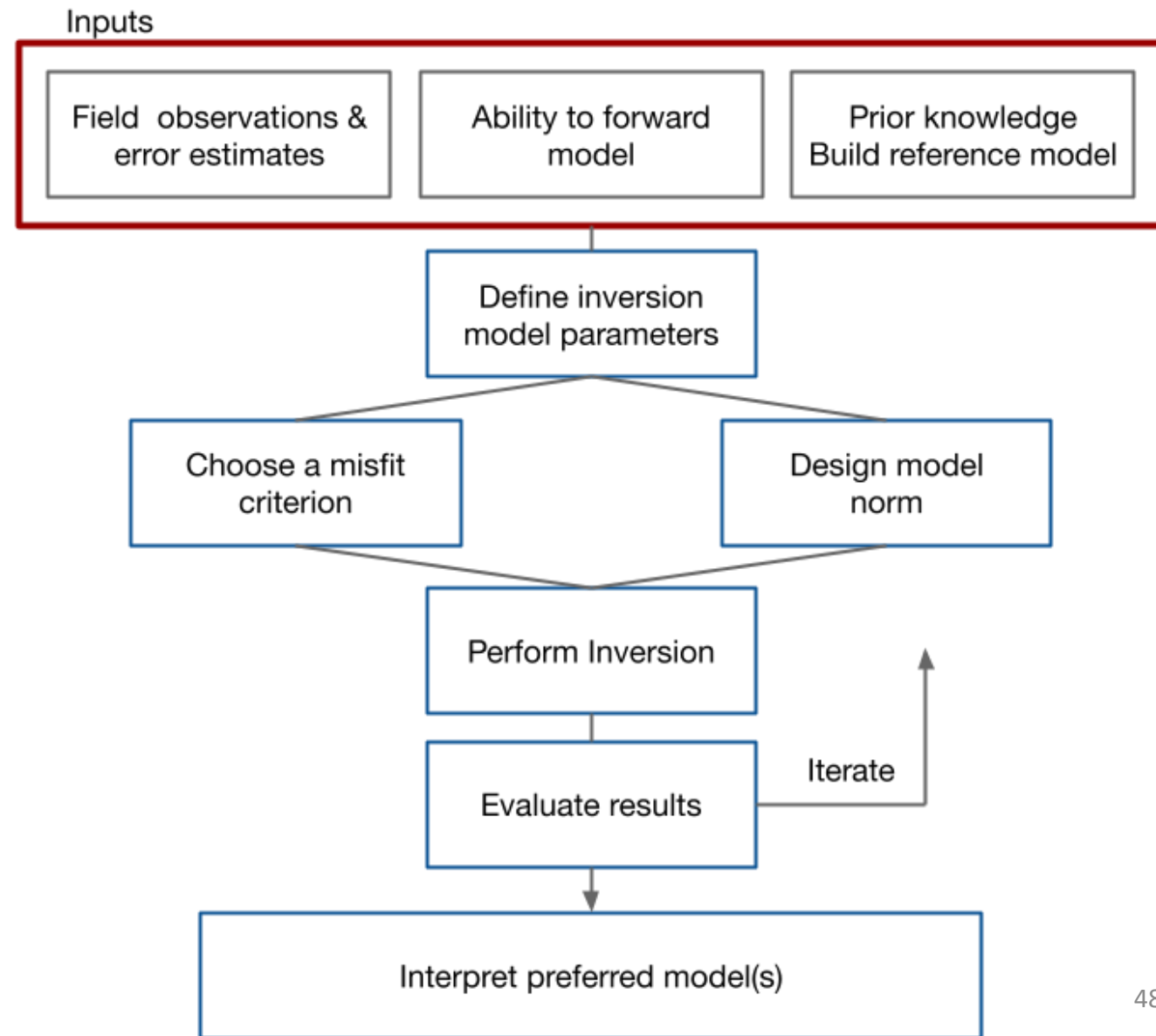
# Flow chart for the inverse problem

- Many components to achieving a quality result
- Success is in the details
- Evaluate each step in the box critically before going on



# Starting up

- Survey and observations
- What processing has been done?
- Normalization of data
- Ability for forward model
- Assemble geologic, petrophysical information
- Build a reference model
- What is the question you want answered from the inversion?



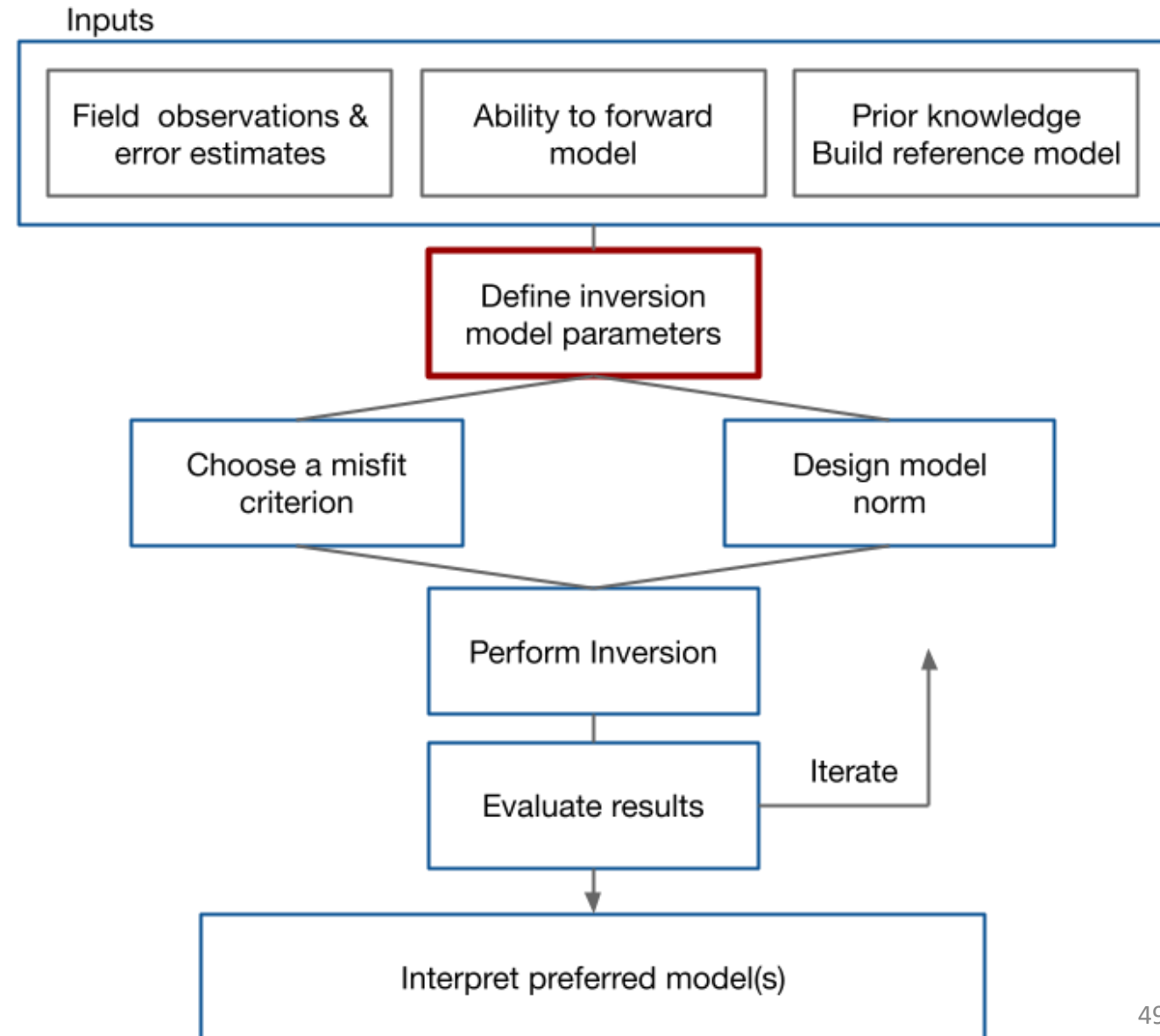
# Inversion model parameters

- In the forward problem

$$d = \mathcal{F}[m]$$

$m$  is our sought function  
(susceptibility, density, ....)

- Inverse problem: we have options  
(e.g., subsurface, parametric ....)



# Inversion as an optimization problem

- Find a single “best” solution by solving optimization

$$\text{minimize} \quad \phi = \phi_d + \beta \phi_m$$

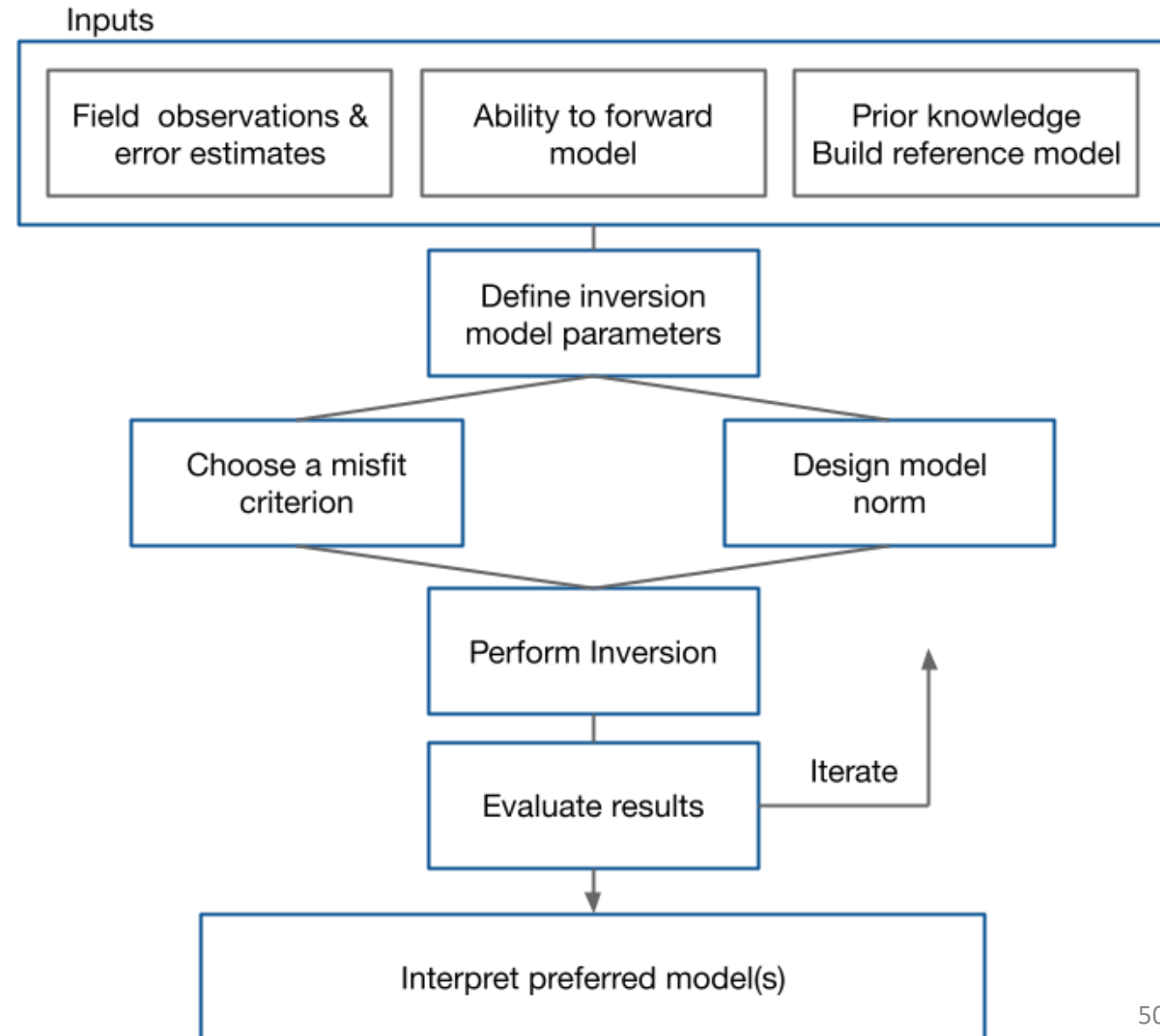
$$\text{subject to} \quad m_L \leq m \leq m_U$$

$\phi_d$  : data misfit

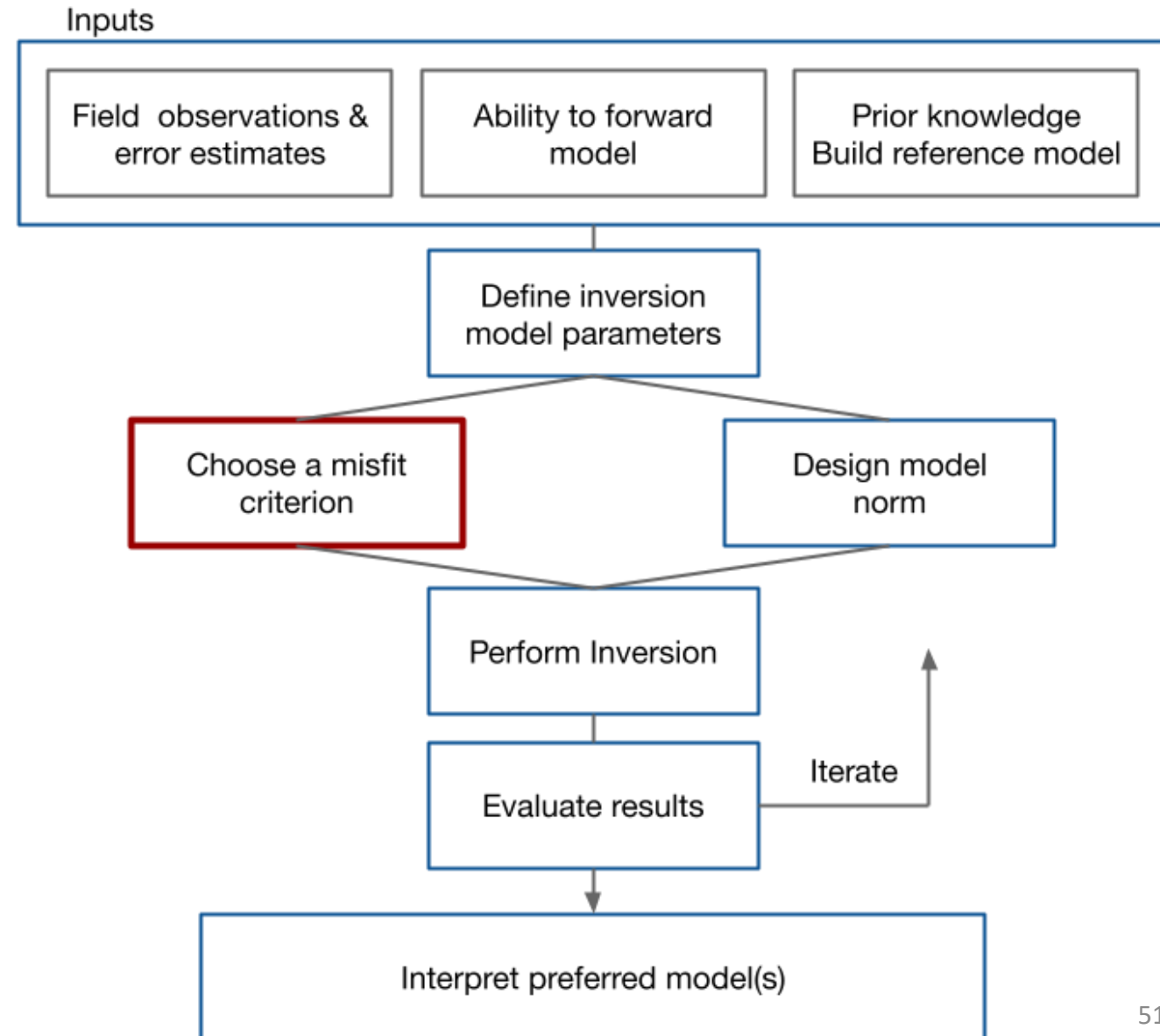
$\phi_m$  : model norm

$\beta$  : trade-off parameter

$m_L, m_U$  : lower and upper bounds



# Flow chart for the Inverse problem



# Dealing with uncertainties

Observed datum

$$d_j^{obs} = F_j(m) + n_j$$

Noise  $n_j$  includes

- Modelling errors
  - dimensionality errors (1D v. 3D)
  - incomplete physics
  - discretization errors
- Noise on data
  - instrument / sensor noise
  - survey parameter errors
  - wind ...

True statistics of “noise” is complicated.  
In practice, assume errors are Gaussian

$$\mathcal{N}(0, \epsilon_j)$$



# Dealing with uncertainties

Consider random variable,  $x_j \in \mathcal{N}(0, 1)$

Define  $\chi_N^2 = \sum_{j=1}^N x_j^2$  Chi-squared statistic with N degrees of freedom

$$\left\{ \begin{array}{l} \text{Expected value: } E(\chi_N^2) = N \\ \text{Variance: } \text{Var}(\chi_N^2) = 2N \\ \text{Standard deviation: } \text{std}(\chi_N^2) = \sqrt{2N} \end{array} \right.$$

# Misfit function

Crucial steps for any misfit: (1) Specify the metric used  
(2) Determine target misfit

We use  $L_2$  norm (least squares statistic)

Define data misfit:  $\phi_d = \sum_{j=1}^N \left( \frac{F_j(m) - d^{obs}}{\epsilon_j} \right)^2$

Define  $\mathbf{W}_d = \mathbf{diag}(1/\epsilon_1, \dots, 1/\epsilon_N)$

$$\phi_d = \|\mathbf{W}_d(F[\mathbf{m}] - \mathbf{d}^{obs})\|_2^2$$

$$E[\phi_d] \simeq N$$

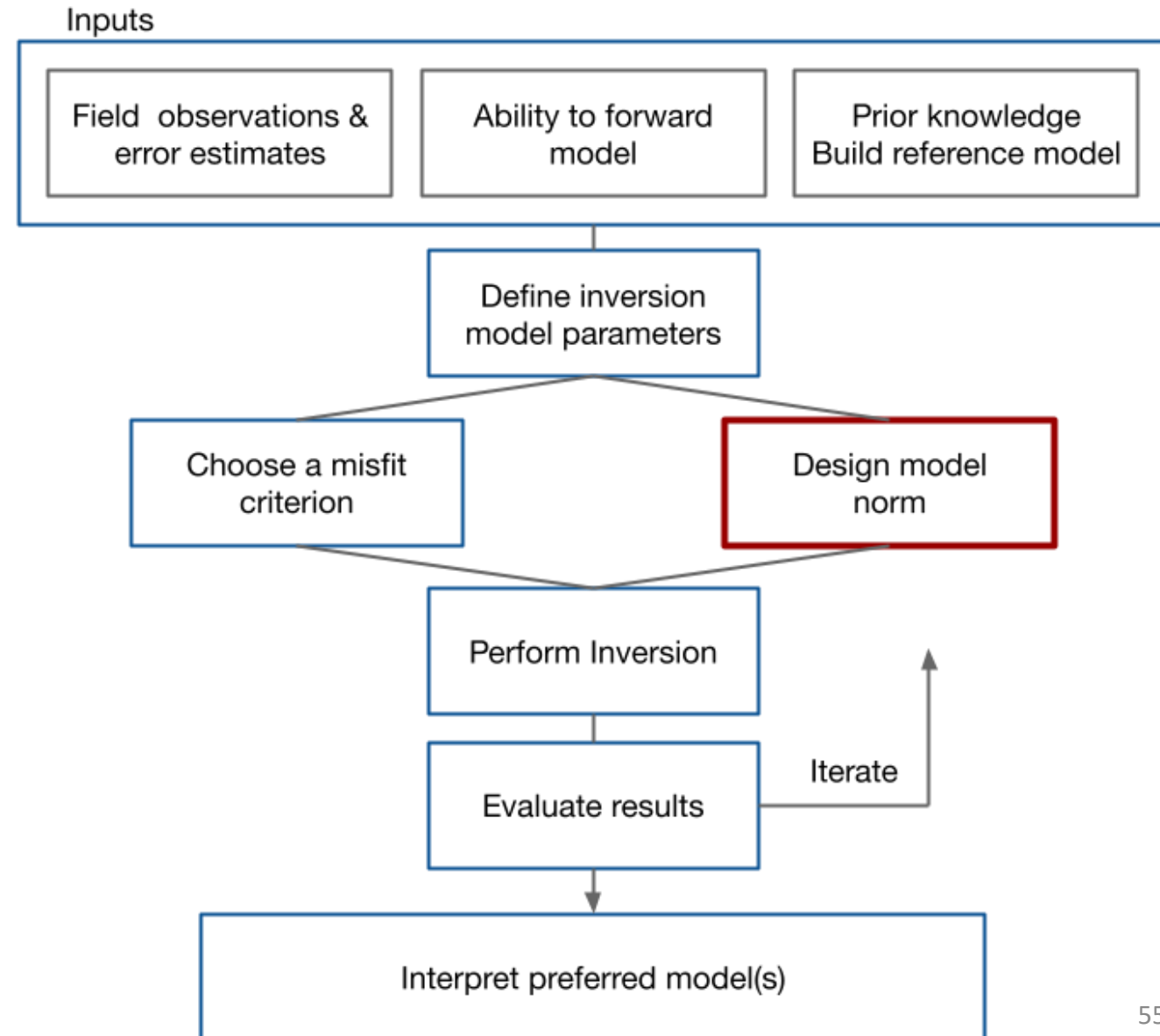
$\phi_d$  is now a  $\chi_N^2$  variable

Reality: we do not know uncertainties

Try:

$$\epsilon_j = \%|d_j^{obs}| + \text{floor}$$

# Flow chart for the Inverse problem



# Model norms

First define our model norms as functions and then discretize

---

Smallest model:

$$\phi_m = \int (m - m_{ref})^2 dx$$

---

Flattest model:

$$\phi_m = \int \left( \frac{dm}{dx} \right)^2 dx$$

---

Combination:

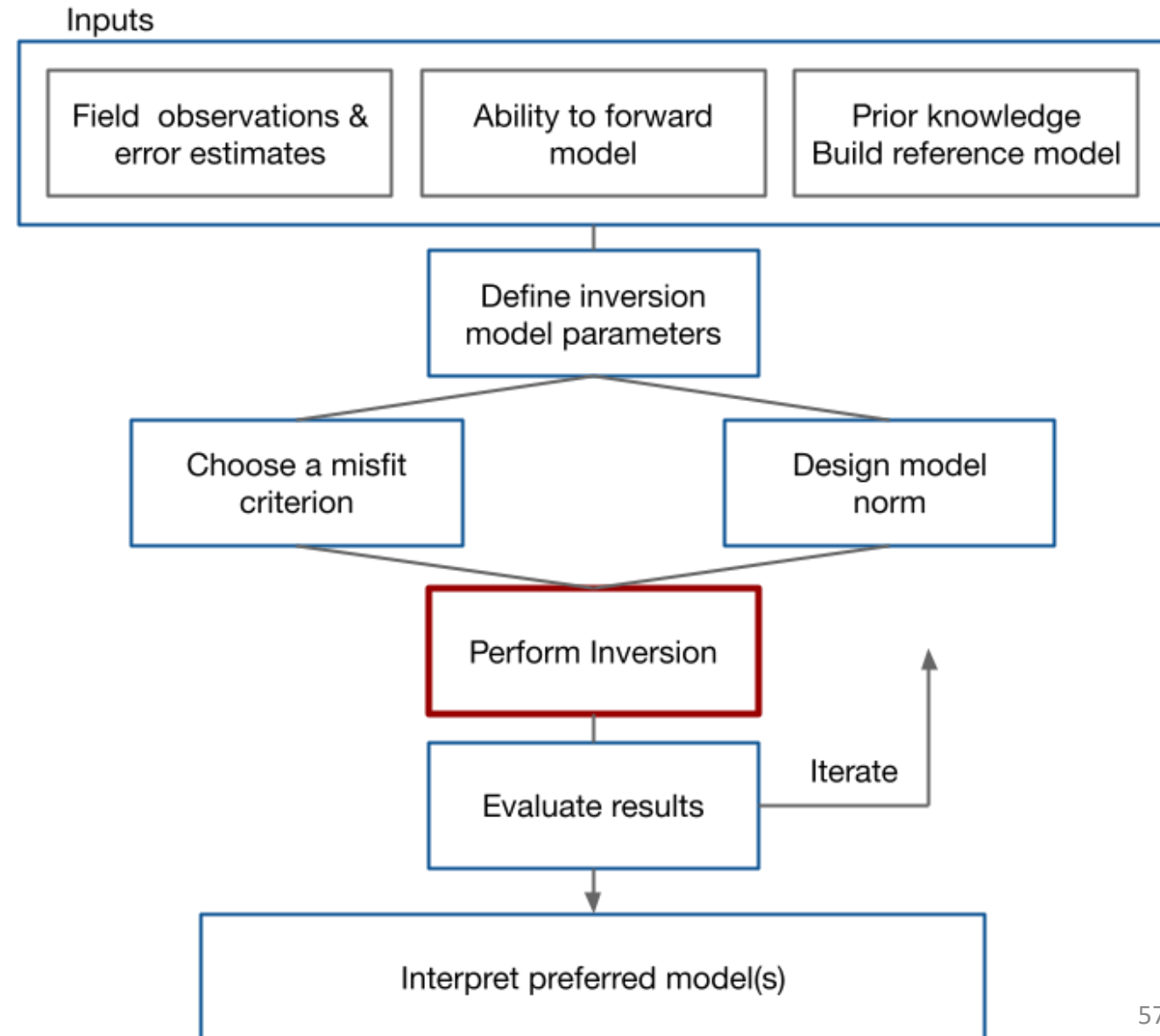
$$\phi_m = \alpha_s \int (m - m_{ref})^2 dx + \alpha_x \int \left( \frac{dm}{dx} \right)^2 dx$$

---

Discretize:

$$\phi_m = \alpha_s \|\mathbf{W}_s(\mathbf{m} - \mathbf{m}_{ref})\|_2^2 + \alpha_x \|\mathbf{W}_x(\mathbf{m})\|_2^2$$

# Flow chart for the Inverse problem

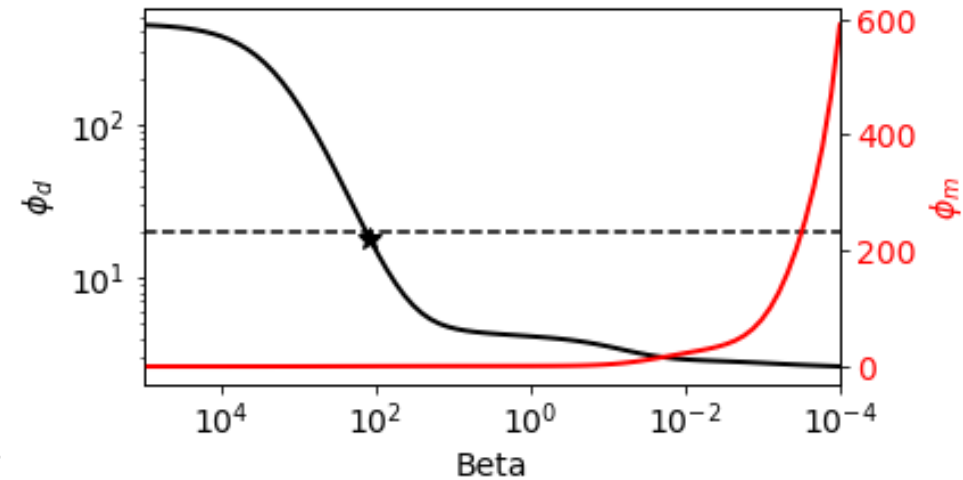




# Role of beta

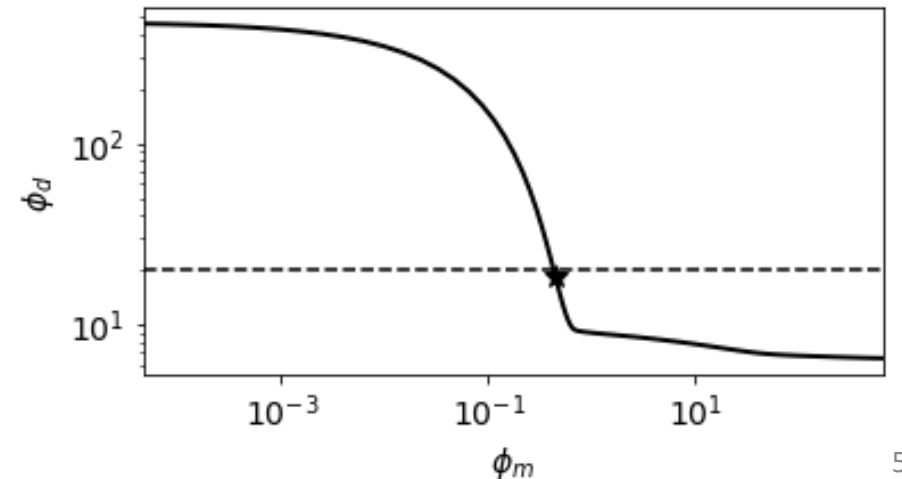
$$\phi(m) = \phi_d(m) + \beta\phi_m(m)$$

$$\begin{aligned}\beta \rightarrow 0 & : \quad \phi \sim \phi_d \\ \beta \rightarrow \infty & : \quad \phi \sim \phi_m\end{aligned}$$



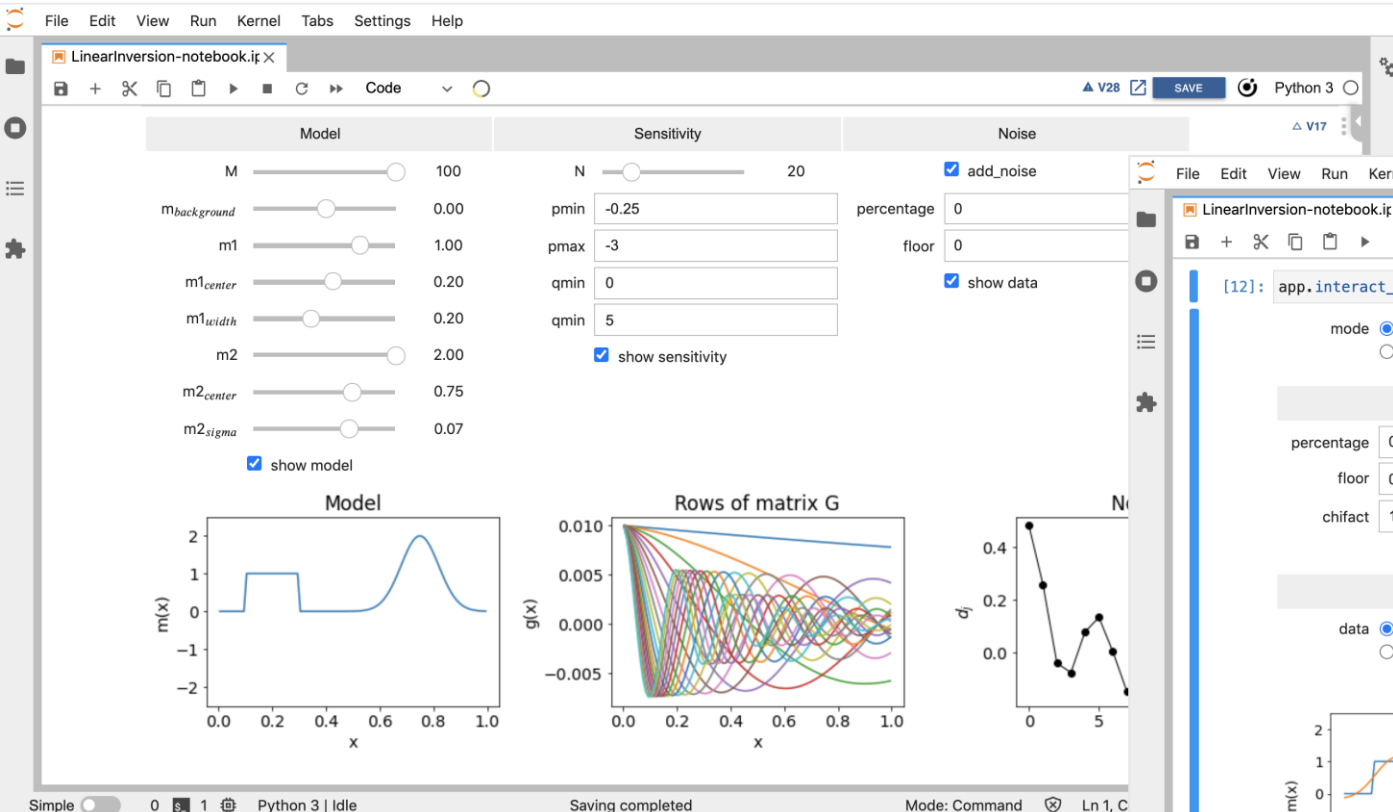
## Tikhonov Curve

- Desired misfit  $\phi_d^* \simeq N$
- Choose  $\beta$  such that  $\phi_d(m) = \phi_d^*$

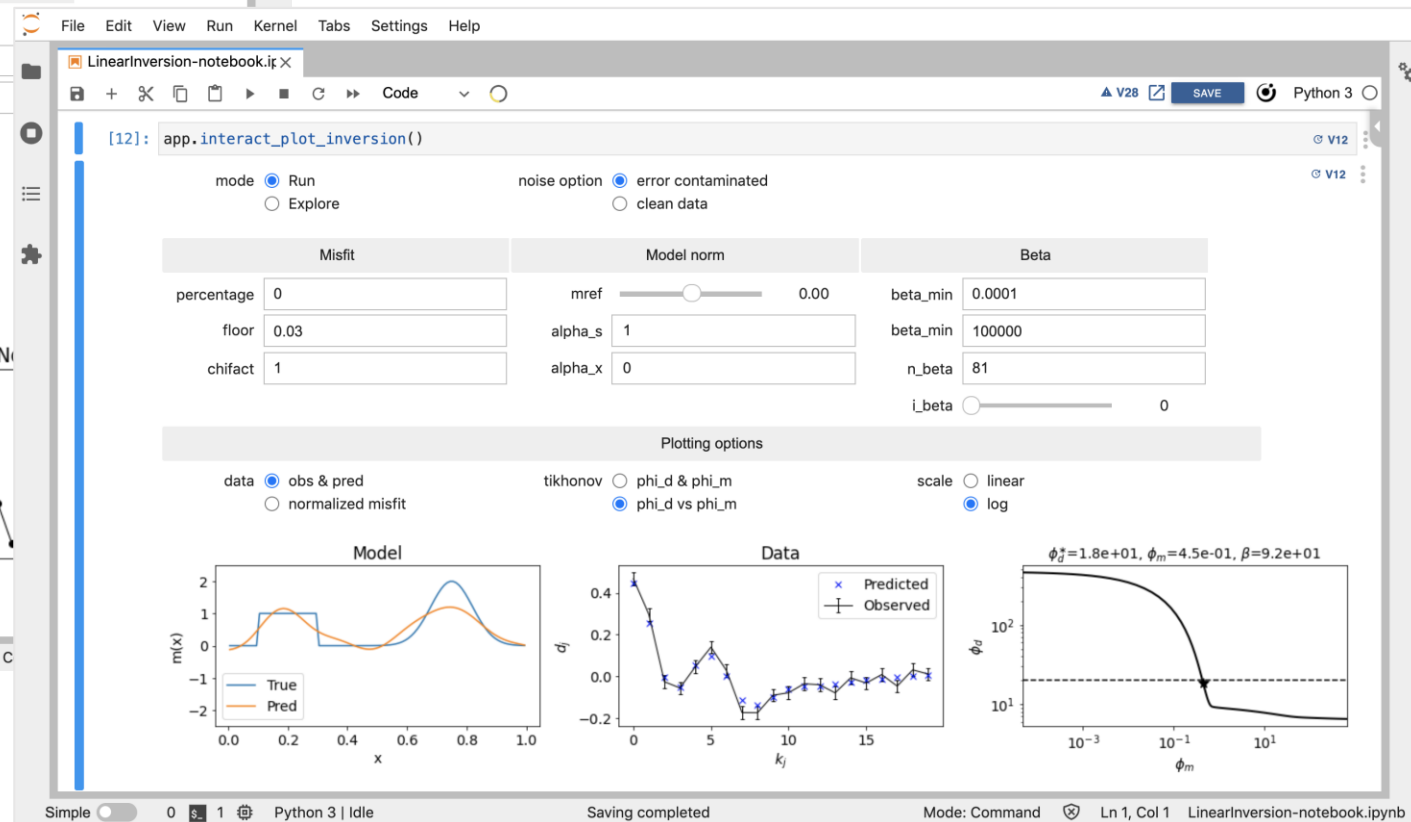


# Demo: Linear Inversion App

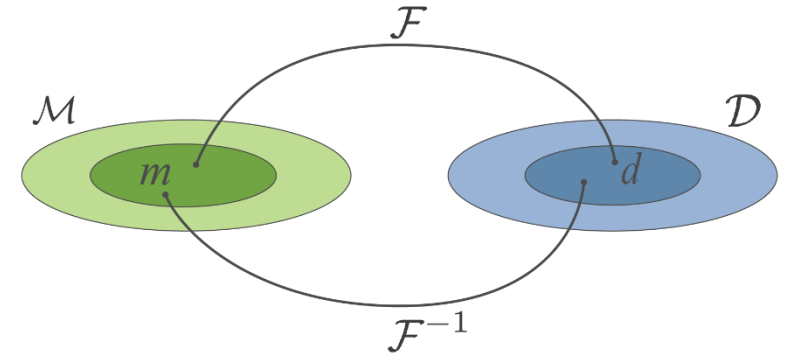
## Develop survey



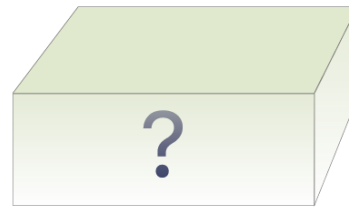
## Run inversion



# Inverse problem



- Non-unique
- Ill-conditioned



The Inverse Problem is ill-posed

Any inversion approach must address these issues