

COMP 478/6771 (FALL 2020)
Digital Image Processing

Digital Image Enhancement in Spatial Domain (cont.)

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Tutors:

Materials provided by Dr. T. D. Bui

Median filter

- `function [J] = median_filter(I, window_size)`
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- `m = size(I,1);`
- `n = size(I,2);`
- `hN = (window_size - 1) / 2;`
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- `K = zeros(m + window_size - 1 , n + window_size - 1);`
- `J = zeros(m, n);`
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- `K(1 + hN : m + hN, 1 + hN : n + hN) = I;`
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- `for i= 1 : m`
- `for j = 1 : n`
- `wind = K(i : i + window_size - 1 , j : j + window_size - 1);`
- `wind_vector = reshape(wind, window_size * window_size, 1);`
- `wind_sorted = sort(wind_vector);`
- `median_w = wind_sorted((end + 1) / 2);`
- `J(i,j) = median_w;`
- `end`
- `end`
-
- `J = uint8(J);`

Test median filter

- We can add noise with imnoise function
- `J = imnoise(I, 'salt & pepper', 0.02);`
- `K = median_filter(J, window_size);`
- `imshow(J), figure, imshow(K)`
- You can compare your result with medfilt2() function.

Edge function

- `BW = edge(I,'sobel')`
- `BW = edge(I,'prewitt')`
- `BW = edge(I,'roberts')`
- `BW = edge(I,'log')`

Edge detection

- Create filter with this command
- `h = fspecial(type)`

Value	Description
average	Averaging filter
disk	Circular averaging filter (pillbox)
gaussian	Gaussian lowpass filter
laplacian	Approximates the two-dimensional Laplacian operator
log	Laplacian of Gaussian filter
motion	Approximates the linear motion of a camera
prewitt	Prewitt horizontal edge-emphasizing filter
sobel	Sobel horizontal edge-emphasizing filter
unsharp	Unsharp, contrast enhancement filter

Apply filter H

- `J = imfilter(A, H)`
- `J = conv2(A,H,'same')`

Exercise

- Write a function to Apply Sobel, Prewitt and Laplacian filter to the sample image.



- Reference : <http://www.mathworks.com>