

STA 365: Applied Bayesian Statistics

Boris Babic
Assistant Professor, University of Toronto

Week 4A: Poisson Models



Combining Information: Posterior Precision

Boris Babic

Normal Models

Poisson Models

- The (conditional) posterior parameters τ_1^2 and μ_1 combine the prior parameters τ_0^2 and μ_0 with terms from the data.

- We already saw that

$$\frac{1}{\tau_1^2} = \frac{1}{\tau_0^2} + \frac{n}{\sigma^2}$$

- Now, let

- $\tilde{\sigma}^2 = 1/\sigma^2$. This is sampling precision – how “close” the x_i ’s are to μ , as opposed to how dispersed they are.
- $\tilde{\tau}_0^2 = 1/\tau_0^2$. This is prior precision. How sharp my prior beliefs are.
- $\tilde{\tau}_1^2 = 1/\tau_1^2$. This is posterior precision. How sharp my posterior beliefs are.
- It is convenient to think about precision as the quantity of information on an additive scale. For the normal model, we can now express posterior precision as:

$$\tilde{\tau}_1^2 = \tilde{\tau}_0^2 + n\tilde{\sigma}^2$$

- And so in that sense: posterior information = prior information + data information

Combining Information: Posterior Mean

Boris Babic

Normal Models

Poisson Models

- We can now write the posterior mean in terms of prior and posterior precision as follows:

$$\mu_1 = \frac{\tilde{\tau}_0^2}{\tilde{\tau}_0^2 + n\tilde{\sigma}^2} \mu_0 + \frac{n\tilde{\sigma}^2}{\tilde{\tau}_0^2 + n\tilde{\sigma}^2} \bar{x}$$

- The posterior mean is a weighted average of the prior mean and the sample mean, as it was in the beta binomial model.
- The weight on the sample mean is n/σ^2 , the sampling precision of the sample mean.
- The weight on the prior mean is $1/\tau_0^2$, the prior precision.
- Example: If the prior mean were based on k_0 prior observations from the same (or a similar) population as X_1, \dots, X_n (i.e., $k_0 = \alpha + \beta$ in the binomial model), then we might want to set $\tau_0^2 = \sigma_0^2/k_0$, the variance of the mean of the prior observations. In this case, the formula for the posterior mean reduces to:

$$\mu_1 = \frac{k_0}{k_0 + n} \mu_0 + \frac{n}{k_0 + n} \bar{x}$$

- Suppose we want to predict \tilde{Y} from the population after observing $Y_1 = y = 1, \dots, Y_n = y_n$.
- Note that $\tilde{Y} \sim N(\mu, \sigma^2) \leftrightarrow \tilde{Y} = \mu + \tilde{\epsilon}, \quad \tilde{\epsilon} \sim N(0, \sigma^2)$
- Saying that \tilde{Y} is normal with mean μ is the same as saying \tilde{Y} is equal to μ plus some mean-zero normally distributed noise.
- Using this, we can compute posterior mean and variance of \tilde{Y} :

$$\begin{aligned} E[\tilde{Y}|y, \sigma^2] &= E[\mu + \tilde{\epsilon}|y, \sigma^2] \\ &= E[\mu|y, \sigma^2] + E[\tilde{\epsilon}|y, \sigma^2] \\ &= \mu_1 + 0 = \mu_1 \end{aligned}$$

$$\begin{aligned} \text{Var}(\tilde{Y}|y, \sigma^2) &= \text{Var}(\mu + \tilde{\epsilon}|y, \sigma^2) \\ &= \text{Var}(\mu|y, \sigma^2) + \text{Var}(\tilde{\epsilon}|y, \sigma^2) \\ &= \tau_1^2 + \sigma^2 \end{aligned}$$

- Recall that the sum of iid normal RVs is also normal.
- Hence, since both μ and $\tilde{\epsilon}$, conditional on y and σ^2 , are normal, so is $\tilde{Y} = \mu + \tilde{\epsilon}$.
- The predictive distribution is therefore

$$\tilde{Y}|\sigma^2, y \sim N(\mu_1, \tau_1^2 + \sigma^2)$$

- Our uncertainty about a new sample \tilde{Y} is therefore a function of our uncertainty about the center of the population as well as how variable the population is. As $n \rightarrow \infty$ we become more confident about where μ is. But certainty about μ does not reduce the sampling variability, and so our uncertainty about \tilde{Y} never goes below σ^2 .

- Grogan and Wirth (1981) provide data on the wing length in millimeters of nine members of a species of midge. From these nine measurements we wish to make inferences on the population mean μ . Studies from other populations suggest that wing lengths are typically around 1.9 mm, and so we set $\mu_0 = 1.9$.
- Suppose we set $\tau_0 = 0.95$.
- The mean of the observations is $\bar{y} = 1.804$ and $s^2 = 0.017$.
- Find μ_1 and τ_1^2 and $\pi(\mu|y, s^2)$
- Find a 95% credible interval for μ based on $\pi(\mu|y, s^2)$.
- This example assumes that $s^2 = \sigma^2$. To get a more accurate representation of uncertainty we will need to develop a model where σ^2 is also unknown.

Unknown Variance, Known Mean

Boris Babic

Normal Models

Poisson Models

- Let $y_i \stackrel{\text{iid}}{\sim} N(\mu, \sigma^2)$ where μ is unknown, σ^2 known.
- The likelihood function is

$$\pi(y|\sigma^2) = (2\pi\sigma^2)^{n/2} \exp \left[- (2\sigma^2)^{-1} \sum_{i=1}^n (y_i - \mu)^2 \right]$$

- For a natural conjugate prior, we seek a prior that has the same functional form:

$$\pi(\sigma^2) \propto (\sigma^2)^{-(\alpha+1)} \exp \left[- \frac{\beta}{\sigma^2} \right]$$

- This is the kernel of an inverse gamma distribution. If $y \sim G^{-1}(\alpha, \beta)$ then

$$f(y|\alpha, \beta) = \frac{\beta^\alpha}{\Gamma(\alpha)} (1/y)^{\alpha+1} \exp(-\beta/y)$$

- Thus the natural conjugate prior in this case is $\sigma^2 \sim G^{-1}(\alpha, \beta)$
- The normalizing constant is $\frac{\beta^\alpha}{\Gamma(\alpha)}$

- The posterior distribution is given by

$$\begin{aligned}\pi(\sigma^2|y, \mu) &\propto (\sigma^2)^{-(\alpha+1)} \exp\left[-\frac{\beta}{\sigma^2}\right] (2\pi\sigma^2)^{n/2} \exp\left[-(2\sigma^2)^{-1} \sum_{i=1}^n (y_i - \mu)^2\right] \\ &\propto (\sigma^2)^{-(n/2+\alpha+1)} \exp\left[-\frac{v/2 + \beta}{\sigma^2}\right]\end{aligned}$$

where $v = \frac{1}{n} \sum (y_i - \mu)^2$

- Hence $\sigma^2|y \sim G^{-1}(n/2 + \alpha, v/2 + \beta)$

An Improper Prior

Boris Babic

Normal Models

Poisson Models

- For a $G^{-1}(\alpha, \beta)$ prior, as $\alpha \downarrow 0$ and $\beta \downarrow 0$ an improper prior results, as it did in the case of a $\text{Beta}(\alpha, \beta)$ prior. In this case,

$$\lim_{\alpha \rightarrow 0, \beta \rightarrow 0} \pi(\sigma^2 | \alpha, \beta) = \sigma^{-2}$$

- The posterior distribution is then

$$\sigma^2 | y \sim G^{-1}(n/2, v/2)$$

- This distribution is proper

- Remember we said in Bayesian approaches we often like to work directly with the precision σ^{-2} , as opposed to the variance.
- The likelihood can be written as

$$\pi(y|\sigma^{-2}) \propto (\sigma^{-2})^{n/2} \exp \left[-\frac{1}{2} \sigma^{-2} \sum (y_i - \mu)^2 \right]$$

- Using the fact that if $y \sim G^{-1}(\alpha, \beta)$ then $y^{-1} \sim G(\alpha, \beta)$ it follows that the natural conjugate prior for σ^{-2} is

$$\sigma^{-2} \sim G(\alpha, \beta)$$

- Therefore,

$$\pi(\sigma^{-2}|y) \propto (\sigma^{-2})^{\alpha+n/2-1} \exp[-(\beta + v/2)\sigma^{-2}]$$

- Hence

$$\sigma^{-2}|y \sim G(\alpha + n/2, \beta + v/2)$$

- As $\alpha \downarrow 0, \beta \downarrow 0$, an improper prior results

$$\pi(\sigma^{-2}) = \sigma^2$$

- Poisson distribution models the probability of events occurring in a fixed interval, provided they occur at a constant rate and independently of the time since the last occurrence.
- This distribution is frequently used in operations management and supply chain logistics.
- For example: A distribution center receives 180 orders per hour; 24 hours a day. The orders are independent in the sense that receiving one does not change the probability of when the next one will arrive.
- Our sample space is $\{0, 1, 2, \dots\}$.
- Notice that this can be used to model any situation where the measurements are non-negative whole numbers, provided the rate of occurrence is constant and the probability of one occurrence is independent of the previous.
- A random variable X has a Poisson distribution with mean θ if

$$\Pr(X = k|\theta) = \frac{\theta^k}{k!} \exp(-\theta) \text{ for } k \in \{0, 1, 2, \dots\}$$

- The mean and variance of X are both θ .
- Hence the Poisson family of distributions has a mean-variance relationship in the sense that if one Poisson distribution has a larger mean than another, it will have a larger variance as well.

- Suppose we have n iid Poisson observations $y = (y_1, \dots, y_n)$ with mean θ , then the likelihood is given by

$$\begin{aligned}\pi(y|\theta) &= \prod_i \pi(y_i|\theta) \\ &= \prod_i \frac{1}{y_i!} \theta^{y_i} \exp(-\theta) \\ &\propto \theta^{\sum y_i} \exp[-n\theta] \\ &\propto \exp[a(y)\theta + b(y) \log(\theta)]\end{aligned}$$

where $a(y) = -n$, and $b(y) = \sum y_i$, (using that $e^{k \log(p)} = p^k$).

- Note also that $\sum Y_i$ is a sufficient statistic for θ and $\sum Y_i \sim \text{Poisson}(n\theta)$.

- We know that our posterior has the following form

$$\pi(\theta|y) \propto \pi(\theta) \times \theta^{\sum y_i} \exp(-n\theta)$$

- This means that whatever our conjugate class of densities is, it will have to include terms like $\theta^{c_1} \exp(-c_2\theta)$ for numbers c_1, c_2 .
- The simplest class of such densities includes only these terms, and their corresponding probability distributions are known as the family of gamma distributions.
- Hence, $\theta \sim G(\alpha, \beta)$ if

$$\pi(\theta) = \frac{\beta^\alpha}{\Gamma(\alpha)} \theta^{\alpha-1} \exp[-\beta\theta] \quad \text{for } \theta, \alpha, \beta > 0$$

- The mean is given by $E[\theta] = \alpha/\beta$, and the variance is $\text{Var}(\theta) = \alpha/\beta^2$
- This is a gamma distribution with $\alpha > 0$ shape and $\beta > 0$ rate. Be careful because sometimes the gamma distribution is parameterized in terms of shape and a scale parameter.

- Let $y_i|\theta \sim \text{Poisson}(\theta)$ and $\theta|\alpha, \beta \sim G(\alpha, \beta)$.
- Then the posterior distribution is given by:

$$\begin{aligned}\pi(\theta|y) &\propto \pi(\theta)\pi(y|\theta) \\ &\propto (\theta^{\alpha-1} \exp[-\beta\theta]) \times (\theta^{\sum y_i} \exp[-n\theta]) \\ &\propto \theta^{\alpha+\sum y_i-1} \exp[-(\beta+n)\theta]\end{aligned}$$

- This is recognizable as a gamma distribution with parameters $\alpha + \sum y_i, \beta + n$.
- Hence, if $\theta \sim G(\alpha, \beta)$ and $Y_1, \dots, Y_n \stackrel{\text{iid}}{\sim} \text{Poisson}(\theta)$ then

$$\theta|Y_1, \dots, Y_n \sim G(\alpha + \sum Y_i, \beta + n)$$

- Estimation and prediction proceed in a manner similar to that in the binomial model.
- The posterior mean of θ is a convex combination of the prior mean and the sample mean:

$$E[\theta|y] = \frac{\alpha + \sum y_i}{\beta + n} = \frac{\beta}{\beta + n} \frac{\alpha}{\beta} + \frac{n}{\beta + n} \frac{\sum y_i}{n}$$

- β is interpreted as the number of prior observations,
- α is interpreted as the sum of counts from β prior observations.
- For large n the information from the data dominates the prior information:

$$n \gg \beta \rightarrow E[\theta|y] \approx \bar{y}, \text{Var}(\theta|y) \approx \bar{y}/n$$

Posterior Inference Summary

Boris Babic

Normal Models

Poisson Models

$$E(\theta) = \alpha\beta^{-1}$$

$$E(\theta \mid y) = (\alpha + n\bar{y})(\beta + n)^{-1}$$

$$\text{Var}(\theta) = \alpha\beta^{-2}$$

$$\text{Var}(\theta \mid y) = (\alpha + n\bar{y})(\beta + n)^{-2}$$

$$\text{Mode}(\theta) = (\alpha - 1)\beta^{-1}$$

$$\text{Mode}(\theta \mid y) = (\alpha - n\bar{y} - 1)(\beta + n)^{-1}$$

- Predictions about additional data can be obtained as before with the posterior predictive distribution, which is given by

$$\begin{aligned}\pi(\tilde{y}|y) &= \int_0^\infty \pi(\tilde{y}|\theta, y) \pi(\theta|y) d\theta \\ &= \int \pi(\tilde{y}|\theta) \pi(\theta|y) d\theta \\ &= \int \tilde{y} \sim \text{Poisson}(\theta) \times \theta \sim G(\alpha + n\bar{y}, \beta + n) d\theta \\ &= \frac{(\beta + n)^{\alpha + \sum y_i}}{\Gamma(\tilde{y} + 1) \Gamma(\alpha + \sum y_i)} \int_0^\infty \theta^{\alpha + \sum y_i + \tilde{y} - 1} \exp[-(\beta + n + 1)\theta] d\theta\end{aligned}$$

- This looks daunting but we can simplify it.
- Using what you know about the Gamma density, see if you can simplify it.

$$1 = \int_0^{\infty} \frac{b^a}{\Gamma(a)} \theta^{a-1} e^{-b\theta} d\theta \quad \text{for any values } a, b > 0 .$$

This means that

$$\int_0^{\infty} \theta^{a-1} e^{-b\theta} d\theta = \frac{\Gamma(a)}{b^a} \quad \text{for any values } a, b > 0 .$$

Now substitute in $a + \sum y_i + \tilde{y}$ instead of a and $b + n + 1$ instead of b to get

$$\int_0^{\infty} \theta^{a+\sum y_i+\tilde{y}-1} e^{-(b+n+1)\theta} d\theta = \frac{\Gamma(a+\sum y_i+\tilde{y})}{(b+n+1)^{a+\sum y_i+\tilde{y}}} .$$

After simplifying some of the algebra, this gives

$$p(\tilde{y}|y_1, \dots, y_n) = \frac{\Gamma(a+\sum y_i+\tilde{y})}{\Gamma(\tilde{y}+1)\Gamma(a+\sum y_i)} \left(\frac{b+n}{b+n+1} \right)^{a+\sum y_i} \left(\frac{1}{b+n+1} \right)^{\tilde{y}}$$

- This is a negative binomial distribution with parameters $(\alpha + \sum y_i, \beta + n)$, and the posterior mean and variance are given by:

$$\begin{aligned}E[\tilde{Y}|y_1, \dots, y_n] &= \frac{a + \sum y_i}{b + n} = E[\theta|y_1, \dots, y_n]; \\ \text{Var}[\tilde{Y}|y_1, \dots, y_n] &= \frac{a + \sum y_i}{b + n} \frac{b + n + 1}{b + n} = \text{Var}[\theta|y_1, \dots, y_n] \times (b + n + 1) \\ &= E[\theta|y_1, \dots, y_n] \times \frac{b + n + 1}{b + n}.\end{aligned}$$