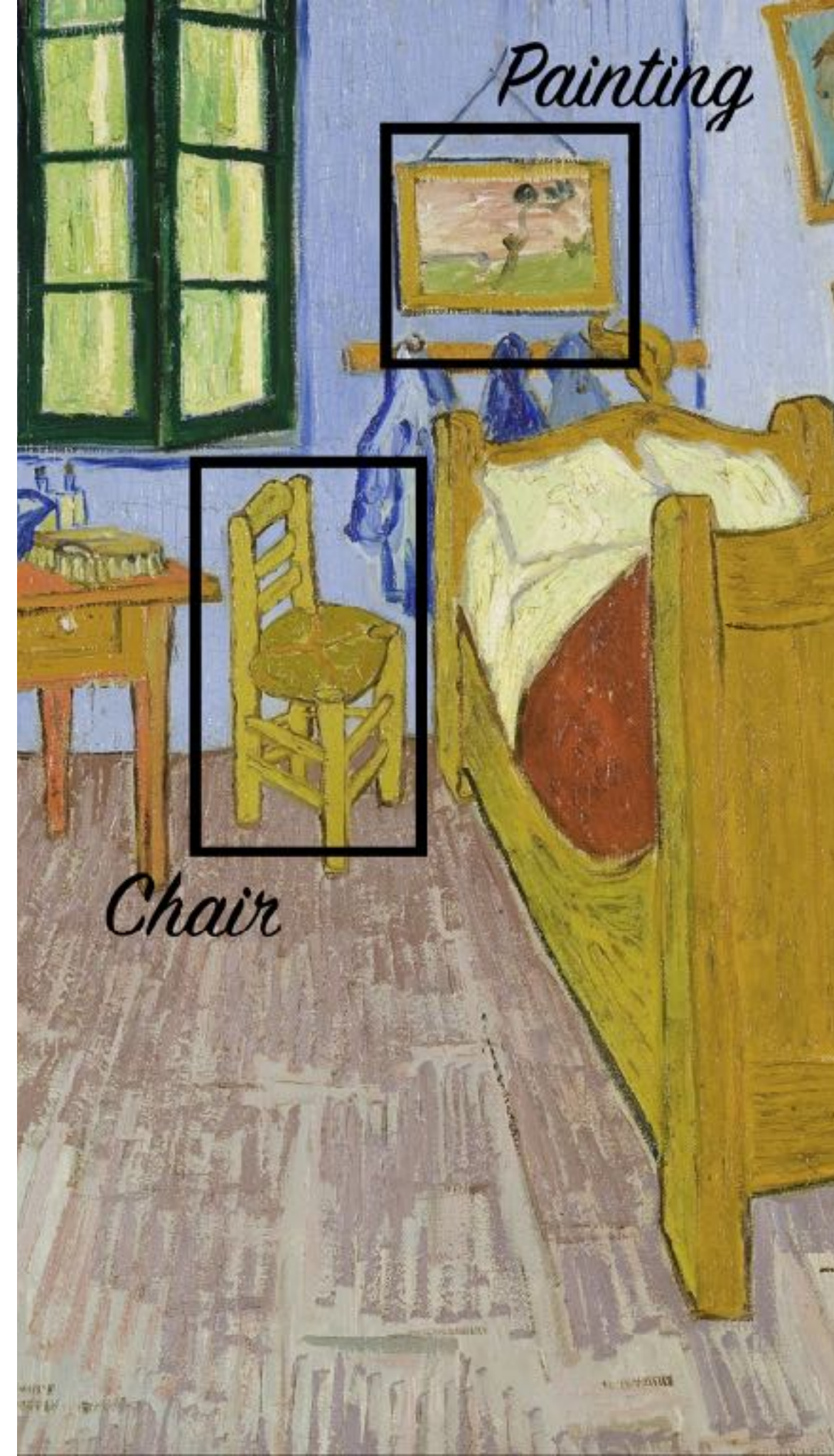


OBJECT DETECTION IN TENSORFLOW

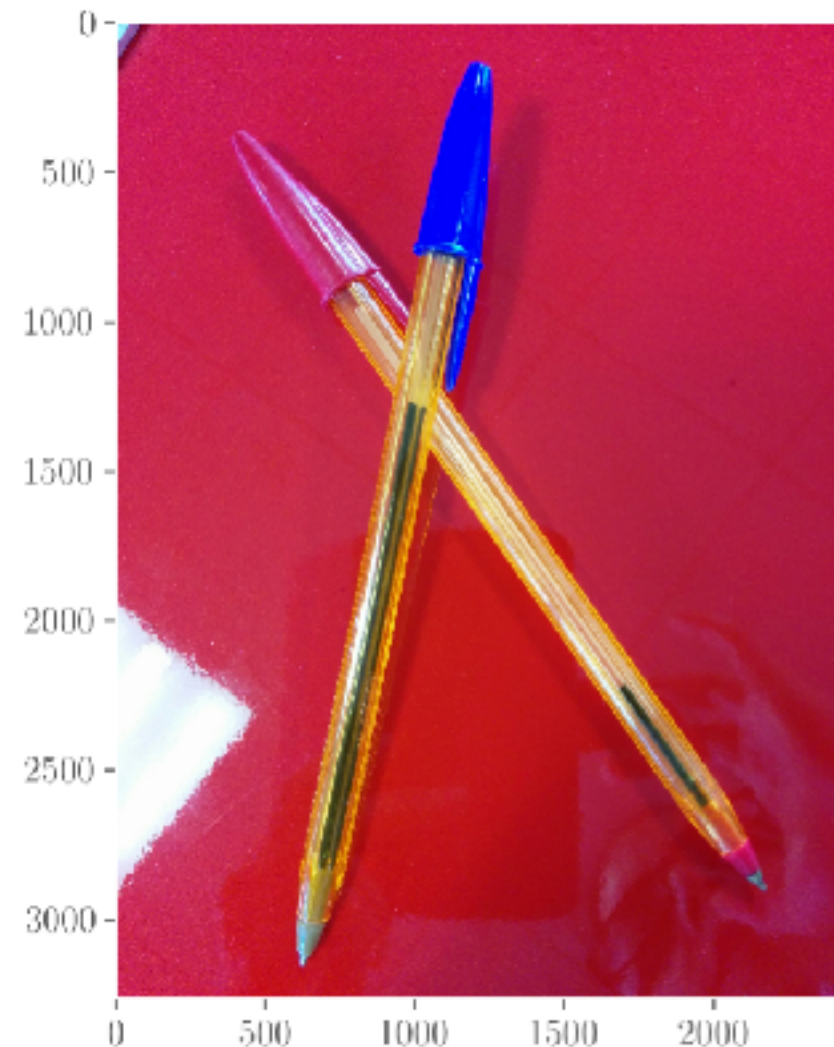
Martina Pugliese
2 May 2019
PyData Edinburgh

SO WHAT IS OBJECT DETECTION?

The little intro



This is an image to **us**:



This is the same image to a **machine**:

```
array( [[[151, 240, 254],  
        [147, 236, 250],  
        [151, 240, 254],  
        ...,  
        [202, 11, 89],  
        [210, 19, 96],  
        [206, 16, 90]],  
        ...,  
        [[206, 40, 112],  
        [234, 69, 138],  
        [240, 77, 144],  
        ...,  
        [136, 8, 67],  
        [146, 18, 75],  
        [152, 25, 80]]], dtype=uint8)
```

*Object detection is the task of detecting the pens there and where they are - drawing **bounding boxes** around them*

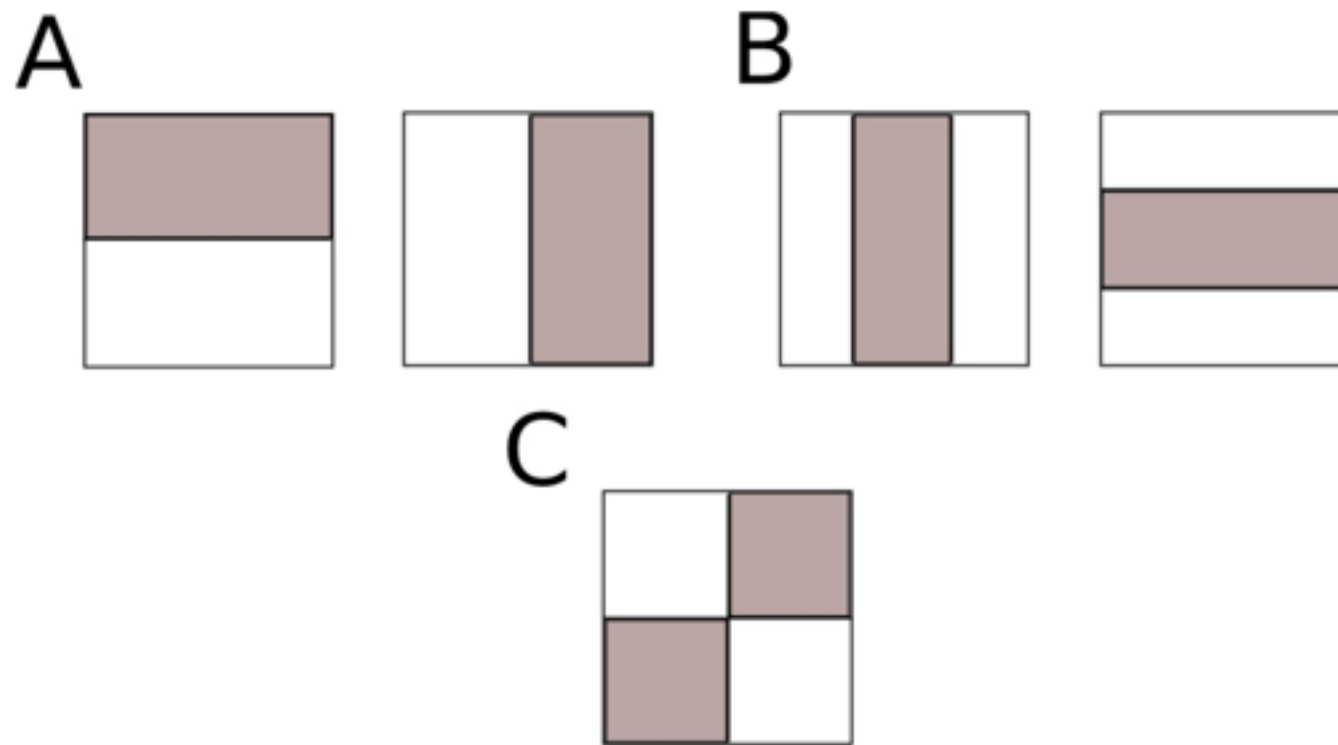
Note that it is a very different problem than a classification (cat or dog)!

METHODS: NON NN-BASED

.....
*You can do many things
without deep learning*



HAAR CASCADES



- Rectangles are moved over the image, compute sum of intensities
- Comparison to trained images (object/lack of object)
- Train a weak classifier for each feature
- Use AdaBoost to weigh all those
- Put these strong classifiers in a cascade

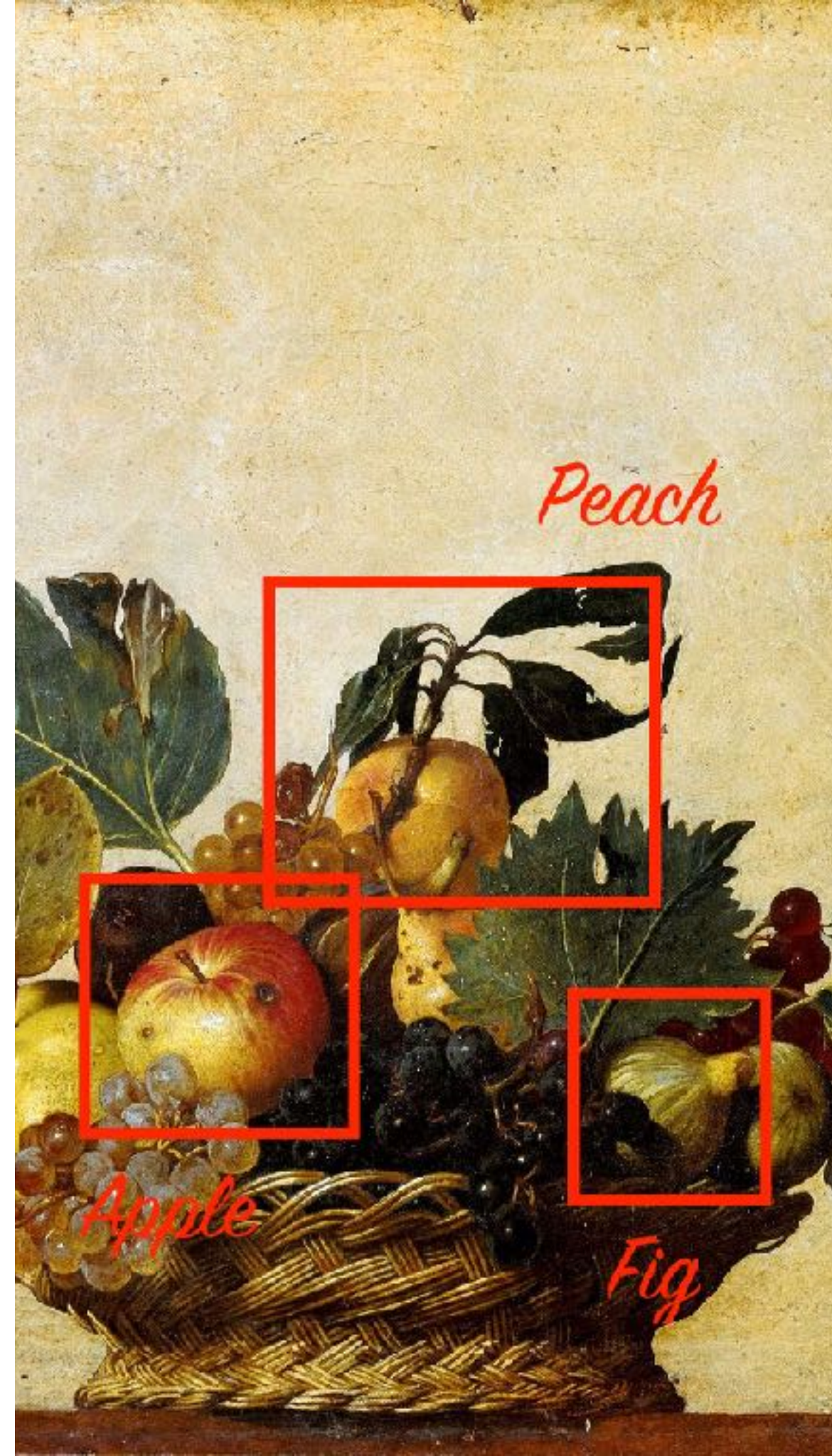
OpenCV comes with pre-trained models for faces, cat faces, plates

You can train it on your own objects

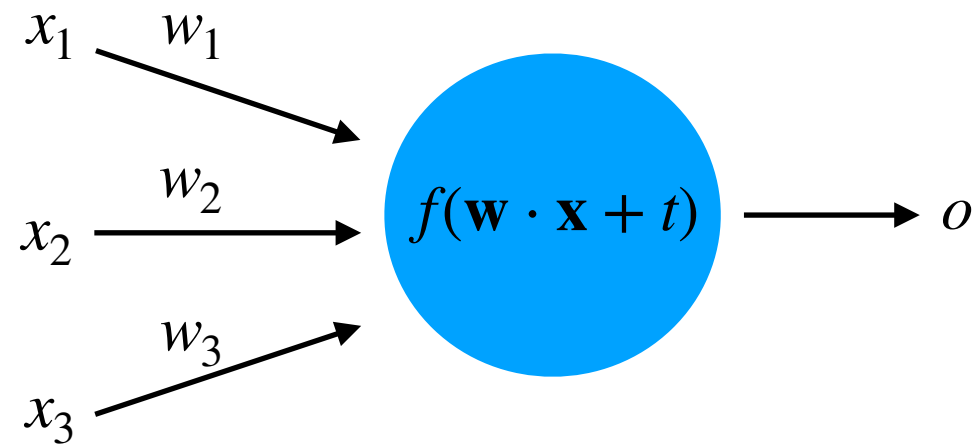
Note there are other methodologies as well

METHODS: DEEP LEARNING ONES

When you really need them



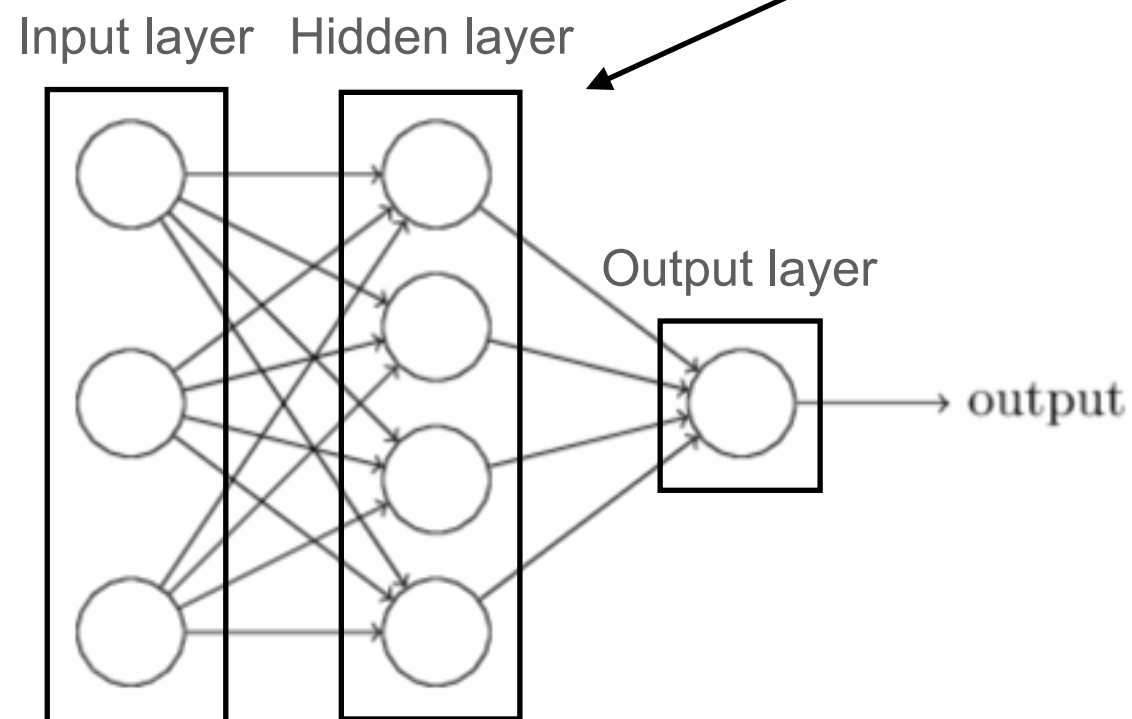
ARTIFICIAL NEURAL NETWORKS (ANNs)



An artificial neuron

- input data and **weights**
- firing **threshold**
- **activation** function

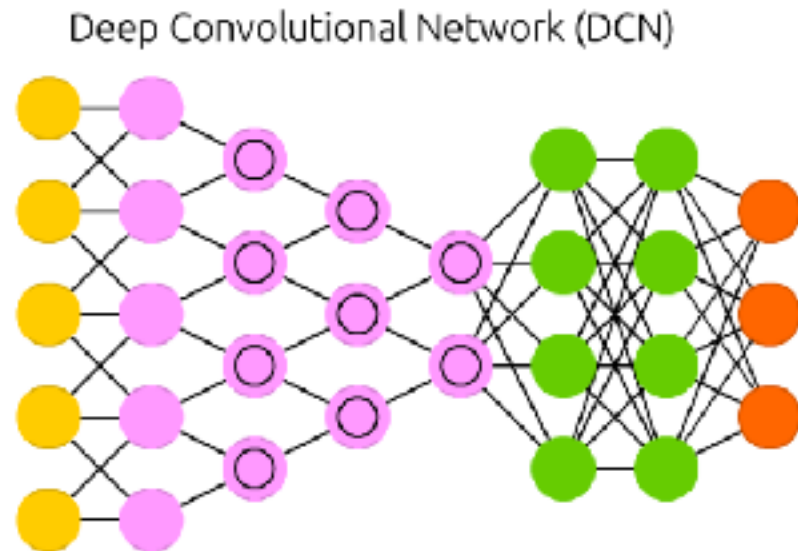
deep means there's several!



An ANN. Img from [1]

- **Weights** are initialised to values - the goal is to adjust them
- Learning: minimise a **loss** function - job of the **optimizer**
- **Backpropagation** improves the weights iteratively -
 - modified by the derivatives of the loss
 - propagated backwards in the net

ANNs & VISION



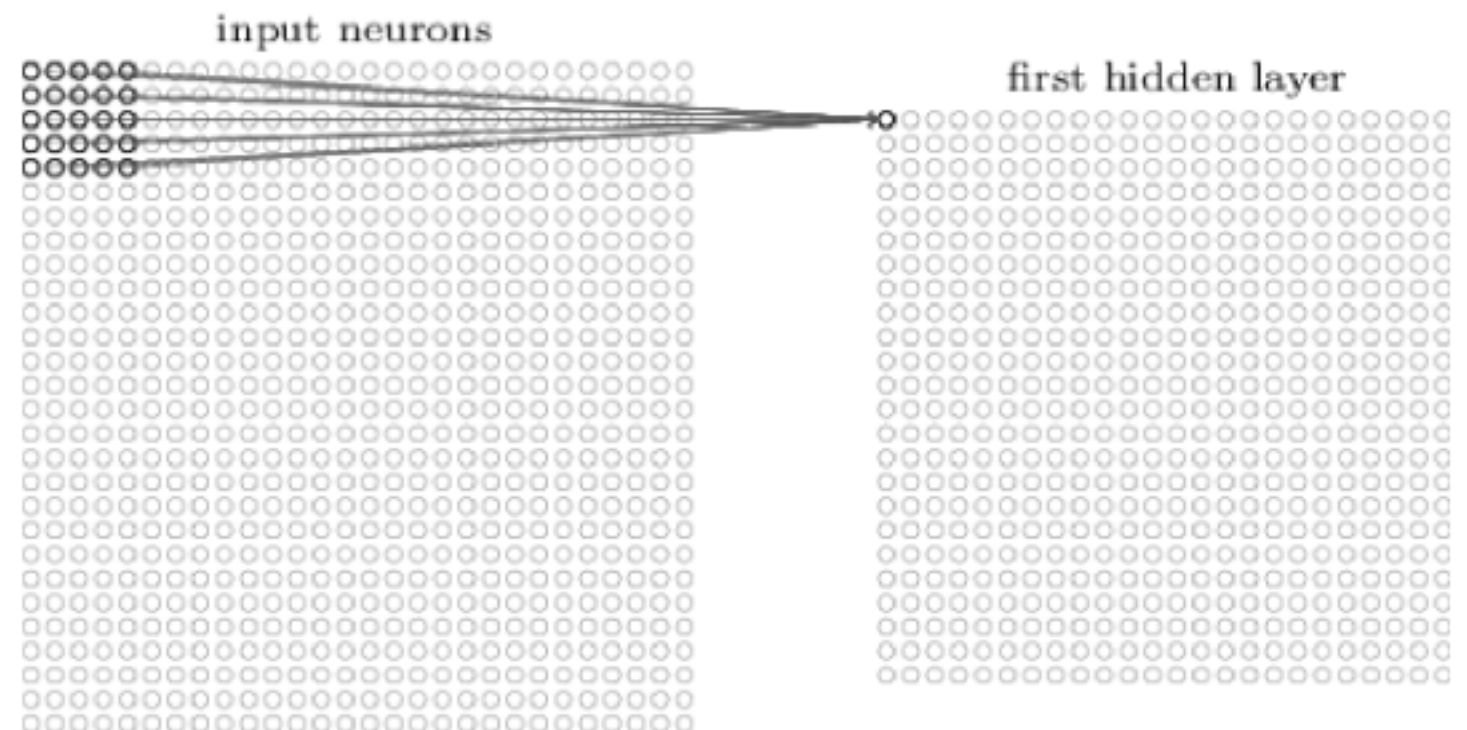
A deep CNN. Image from [4] - the conv layers are highlighted

The biology

CNNs loosely resemble the functioning of the **visual cortex**, which processed images in batches of pixels (region)

CNN:

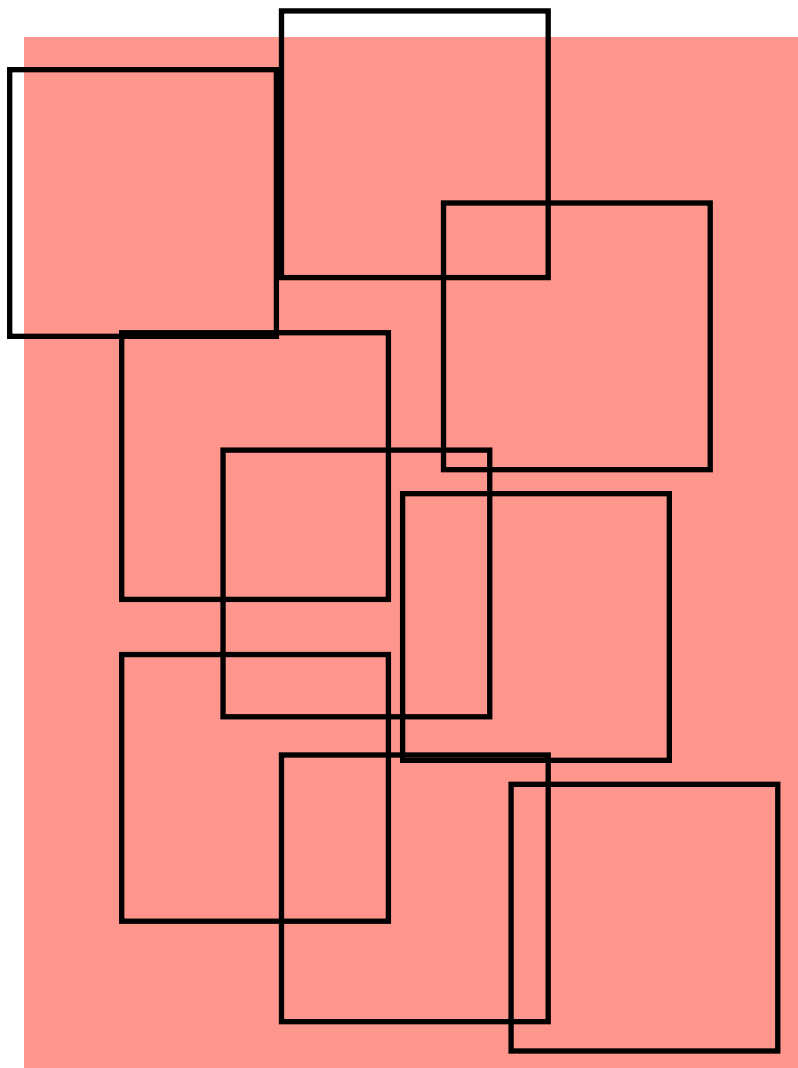
- Some layers are not fully connected
- Output is generated via **convolution** operations
 - every neuron talks to a region of neurons in the layer before
 - a kernel of weights is used to build combinations
 - the combination will pick up when there is agreement
 - the kernel shifts every time
 - a feature map is the output: it encodes shapes
 - shapes are learned hierarchically alongside layers



Convolution, image from [1]

HOW WOULD YOU USE ANNs TO DETECT OBJECTS?

*You could think of applying **a classifier per image region***



- it'd be naive and expensive
- you'd need to consider several regions
- objects overlap
- requires one CNN per region
- objects may have different aspect ratios in different regions

Better methods

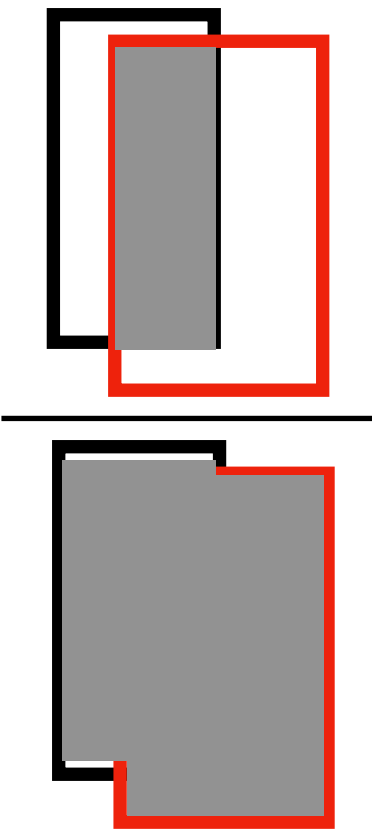
- YOLO
- R-CNN
- SSD

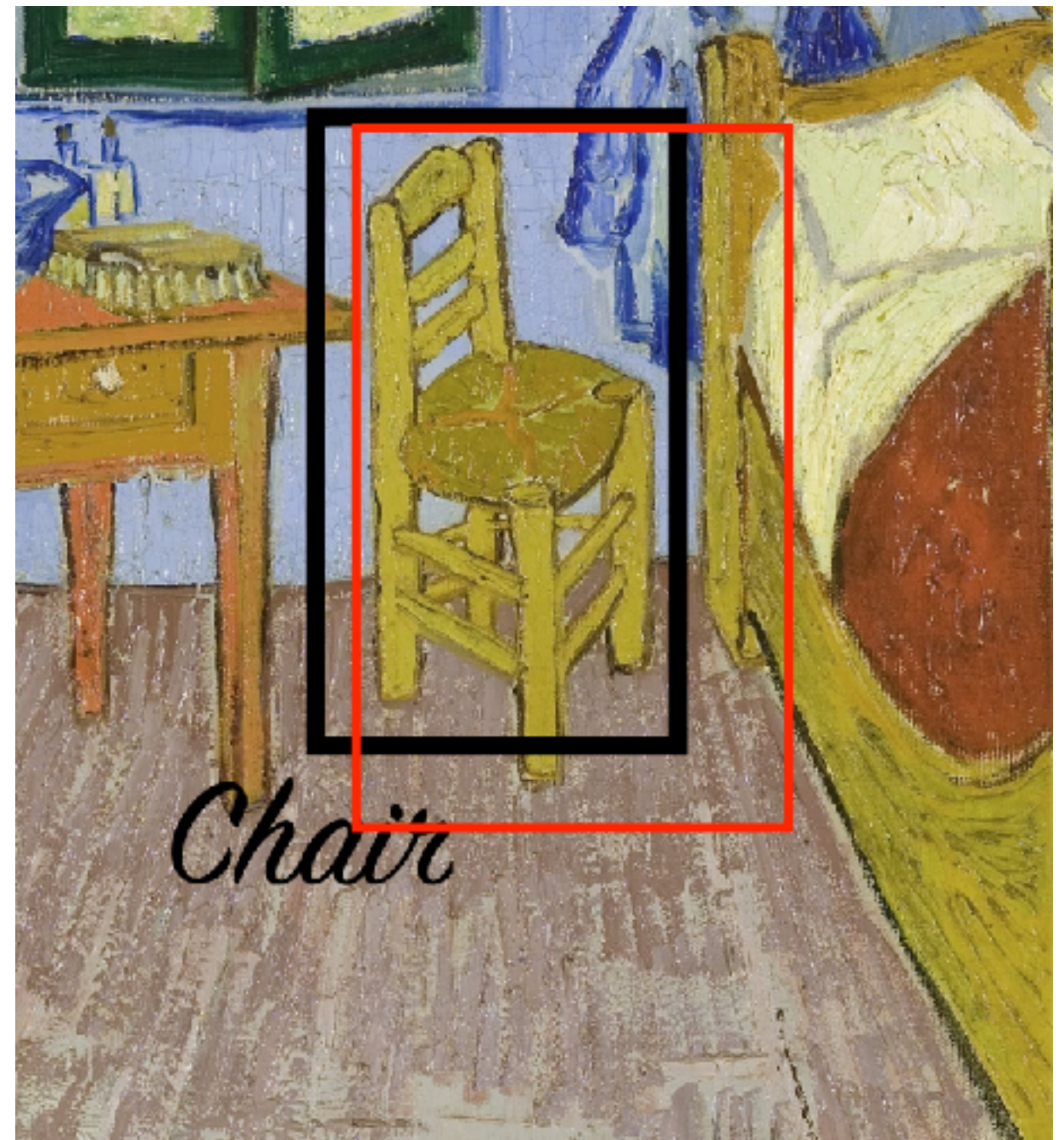
WHEN IS AN OBJECT DETECTED: THE IoU – INTERSECTION OVER UNION

Main metric to assess if the network got an object box right

the box as manually created (training set)

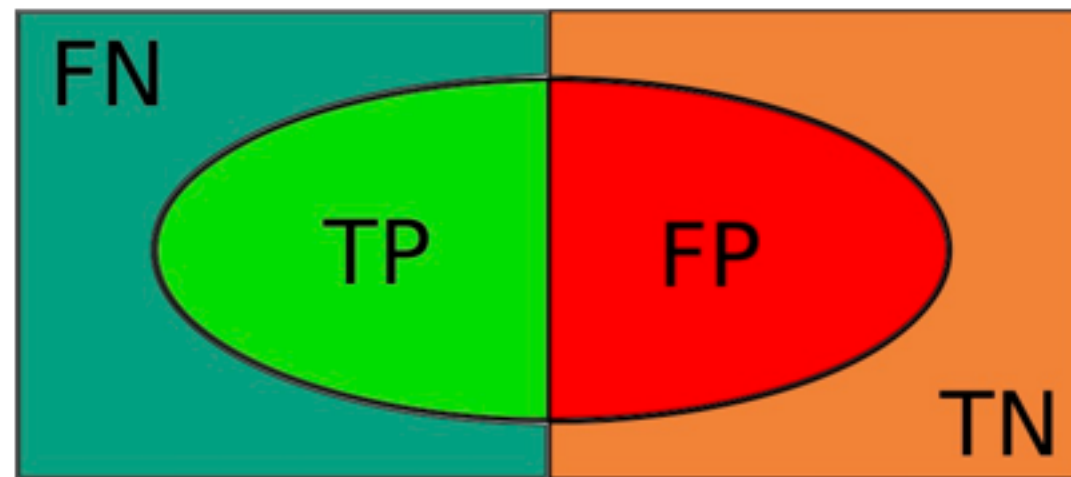
the box as the network found it

$$\text{IoU} = \frac{\text{Intersection}}{\text{Union}}$$




usually a IoU of at least 0.5 is considered a detection

ASSESSING A MODEL'S QUALITY – CLASSIFICATION METRICS



positives

negatives

positive is your class of interest -
binary classification

TP: true positives

FN: false negatives

FP: false positives

FN: false negatives

the fraction of true positives for the class over the total of points belonging to the class, meaning how many of them were detected.

$$p = \frac{TP}{TP + FP}$$

precision - aka fraction of points that are correct for the class
(true positive rate), relevancy

[**specificity** is the true negative rate]

$$r = \frac{TP}{TP + FN}$$

recall - aka fraction of points detected in class, completeness

EVALUATING AN OBJECT DETECTOR: THE mAP

mean average precision

$$\text{mAP} = \frac{1}{|C|} \sum_c \frac{TP_c}{TP_c + FP_c}$$

Average of the precisions
for all classes

You'd normally measure the mAP at different values of IoU

and for different boxes sizes

YOU ONLY LOOK ONCE – THE YOLO NETWORK

The year is 2016

- One of the fastest networks for object detection
 - It passes over the image just **once**
 - It performs a **regression** - predicting the location of the bounding boxes and the class probabilities - for each cell of a grid over the image
-
- **darknet** is a framework to use YOLO - it comes shipped with pre-trained weights
 - it has been ported into TensorFlow as **darkflow**
 - it has APIs in **OpenCV**

OTHER “COMPETITOR” NETWORKS

R-CNN

- R is for “region” - works off of a region segmentation
- searches for candidate regions via convolutions (selective search)
- passes them to an SVM classifier for the object
- because of the region selection is quite slow

Fast R-CNN

- Convolution is done once per image
- Still uses selective search
- Still quite slow

Faster R-CNN

- Drops the selective search in favour of a network approach

SSD

- Single-shot multi box detector - one pass overall (localisation/classification)
- Competes with YOLO in speed
- Multibox is the method for extracting candidate bounding boxes

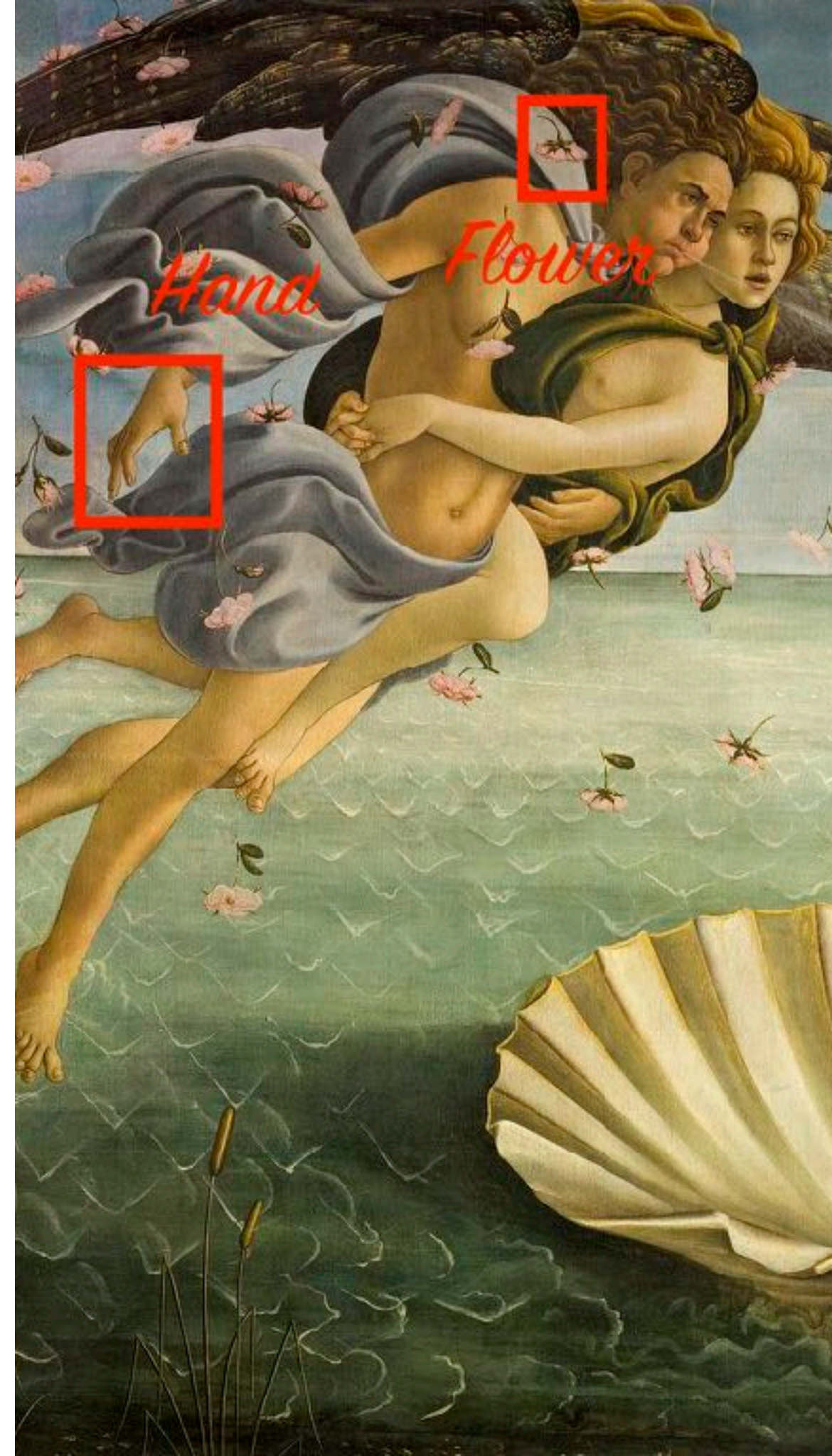
THE SUPER BRIEF TENSORFLOW JOURNEY

*Why am I here?
What do I want?*



OBJECT DETECTION IN TENSORFLOW

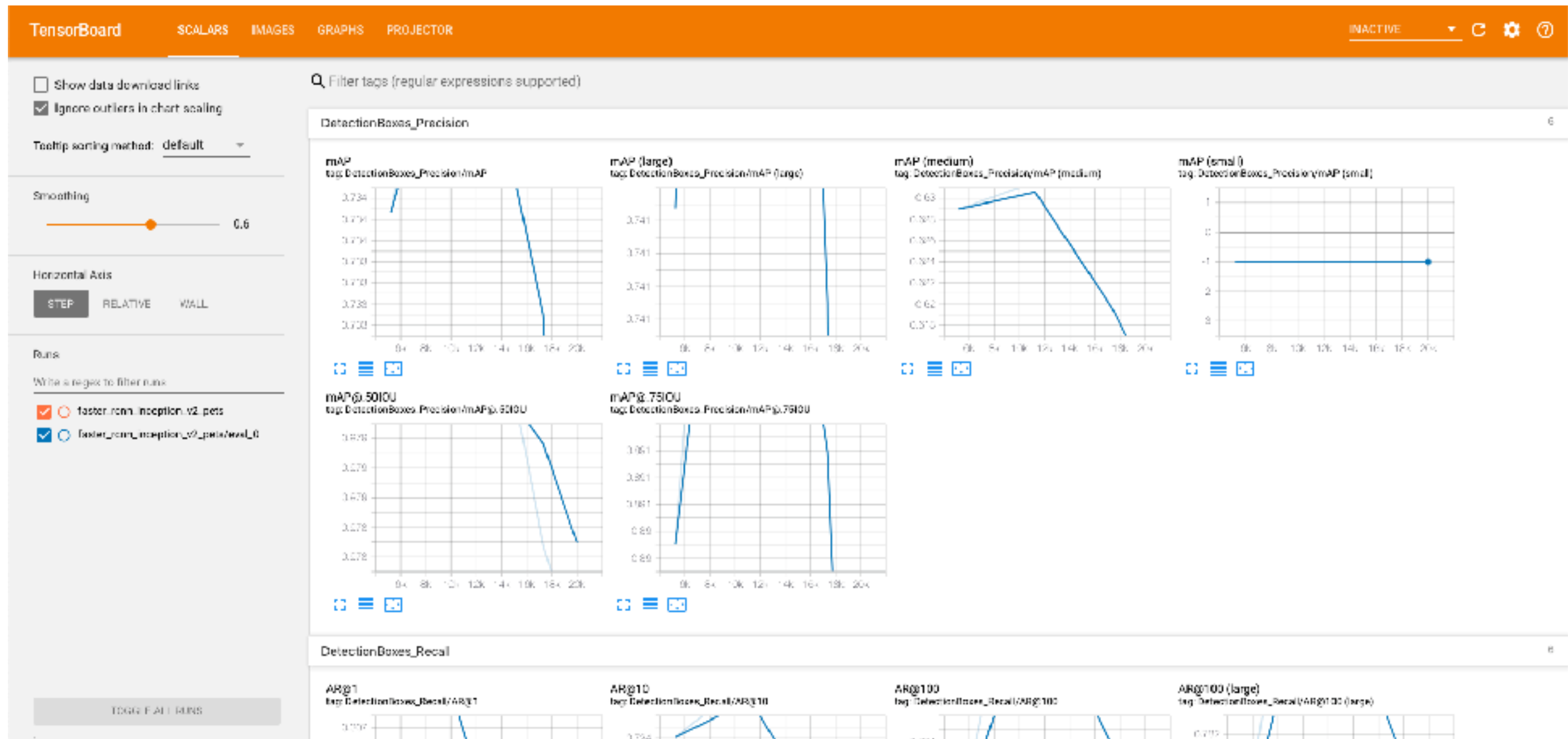
*Why am I here?
What do I want?*



USING TENSORFLOW FOR OBJECT DETECTION

1. Prepare the images and annotate them
2. Configure the job
3. Download the checkpoints for transfer learning
4. Use TensorBoard

Tensorboard – The performance metrics



TensorBoard – The detected objects on the test set

TensorBoardSCALARSIMAGESGRAPHSPROJECTOR

INACTIVE

☐ Show actual image size

Filter tags (regular expressions supported)

Brightness adjustment

RESET

Contrast adjustment

RESET

Runs

Write a regex to filter runs

☒ faster-rcnn_inception_v2_pets

☒ faster-rcnn_inception_v2_pets/eval_0

TOGGLE ALL RUNS

Detections_Left_Groundtruth_Right

Detections_Left_Groundtruth_Right/0/0
faster-rcnn_inception_v2_pets/eval_0
step 20,000
Tue Apr 16 2019 19:38:58 GMT+0100 (British Summer Time)



Detections_Left_Groundtruth_Right/1/0
faster-rcnn_inception_v2_pets/eval_0
step 20,000
Tue Apr 16 2019 19:38:58 GMT+0100 (British Summer Time)



Detections_Left_Groundtruth_Right/2/0
faster-rcnn_inception_v2_pets/eval_0
step 20,000
Tue Apr 16 2019 19:38:58 GMT+0100 (British Summer Time)



Detections_Left_Groundtruth_Right/3/0
faster-rcnn_inception_v2_pets/eval_0
step 20,000
Tue Apr 16 2019 19:38:58 GMT+0100 (British Summer Time)



Detections_Left_Groundtruth_Right/4/0
faster-rcnn_inception_v2_pets/eval_0
step 20,000
Tue Apr 16 2019 19:38:58 GMT+0100 (British Summer Time)



Detections_Left_Groundtruth_Right/5/0
faster-rcnn_inception_v2_pets/eval_0
step 20,000
Tue Apr 16 2019 19:38:58 GMT+0100 (British Summer Time)



Detections_Left_Groundtruth_Right/6/0
faster-rcnn_inception_v2_pets/eval_0
step 20,000
Tue Apr 16 2019 19:38:58 GMT+0100 (British Summer Time)



Detections_Left_Groundtruth_Right/7/0
faster-rcnn_inception_v2_pets/eval_0
step 20,000
Tue Apr 16 2019 19:38:58 GMT+0100 (British Summer Time)



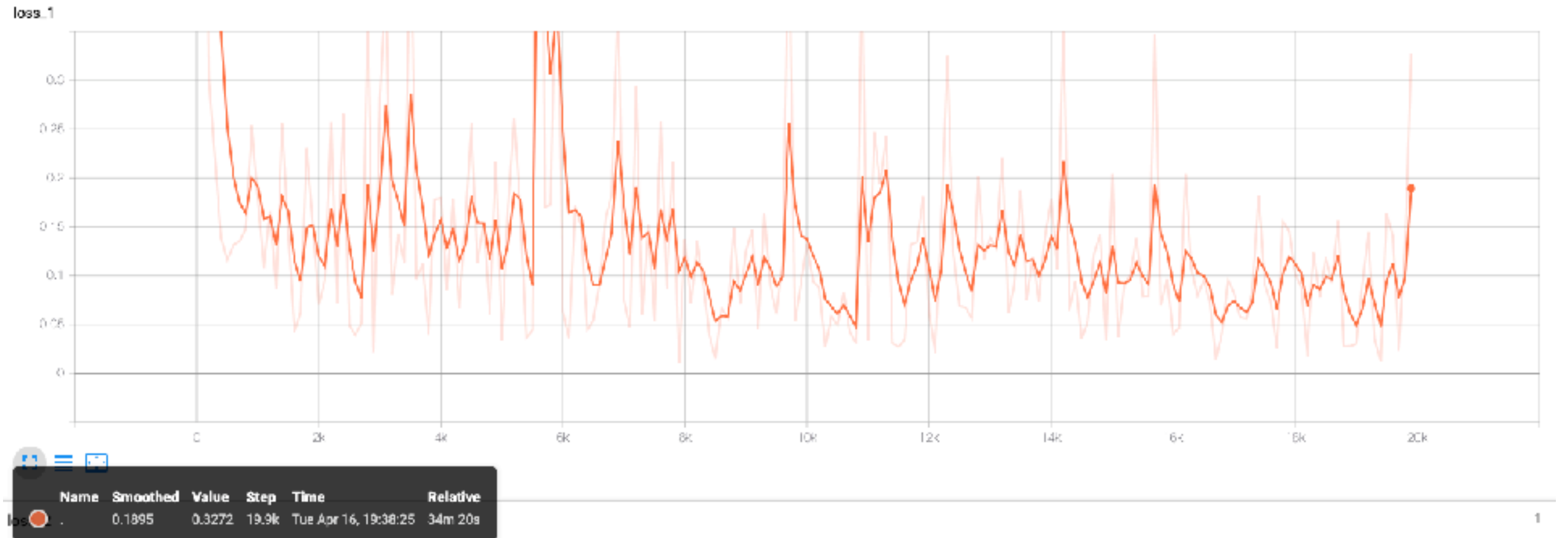
Detections_Left_Groundtruth_Right/8/0
faster-rcnn_inception_v2_pets/eval_0
step 20,000
Tue Apr 16 2019 19:38:58 GMT+0100 (British Summer Time)



Detections_Left_Groundtruth_Right/9/0
faster-rcnn_inception_v2_pets/eval_0
step 20,000
Tue Apr 16 2019 19:38:58 GMT+0100 (British Summer Time)



Tensorboard – The Loss



SOME REFERENCES

Haar Cascades

1. The original Haar Cascades [paper](#)

ANNs & Deep Learning

1. M Nielsen, [Neural networks and deep learning](#), Determination Press, 2015
2. F Chollet, Deep Learning with Python, Manning, 2017
3. [Convolutional Neural Networks for visual recognition](#), a Stanford CS class
4. [The neural network zoo](#), an article + illustration by F Van Veen at the Asimov Institute

YOLO

1. YOLO original papers: [YOLOv1 paper](#), [YOLOv2 paper](#) and [YOLOv3 paper](#)
2. A high-level [blog](#) post about the YOLO paper, introducing its concepts
3. YOLO's [website](#) where to download pre-trained weights

Other networks for object detection

1. A [blog](#) on various object detection algorithms
2. The R-CNN original [paper](#)
3. Faster R-CNN original [paper](#)
4. A Kharpathy on trying R-CNN back in the day, [here](#)
5. The SSD original [paper](#)

In TensorFlow

1. The TensorFlow models [repo](#)
2. The [labellmg](#) tool to annotate
3. A [blog](#) on how to use TensorFlow models for object detection - training a racoon detector

Church



THANKS!



Gondola