

The Plane Space Project



Director of Rocket Science: Tim Squires

Director of Space Operations: Nick Porthouse





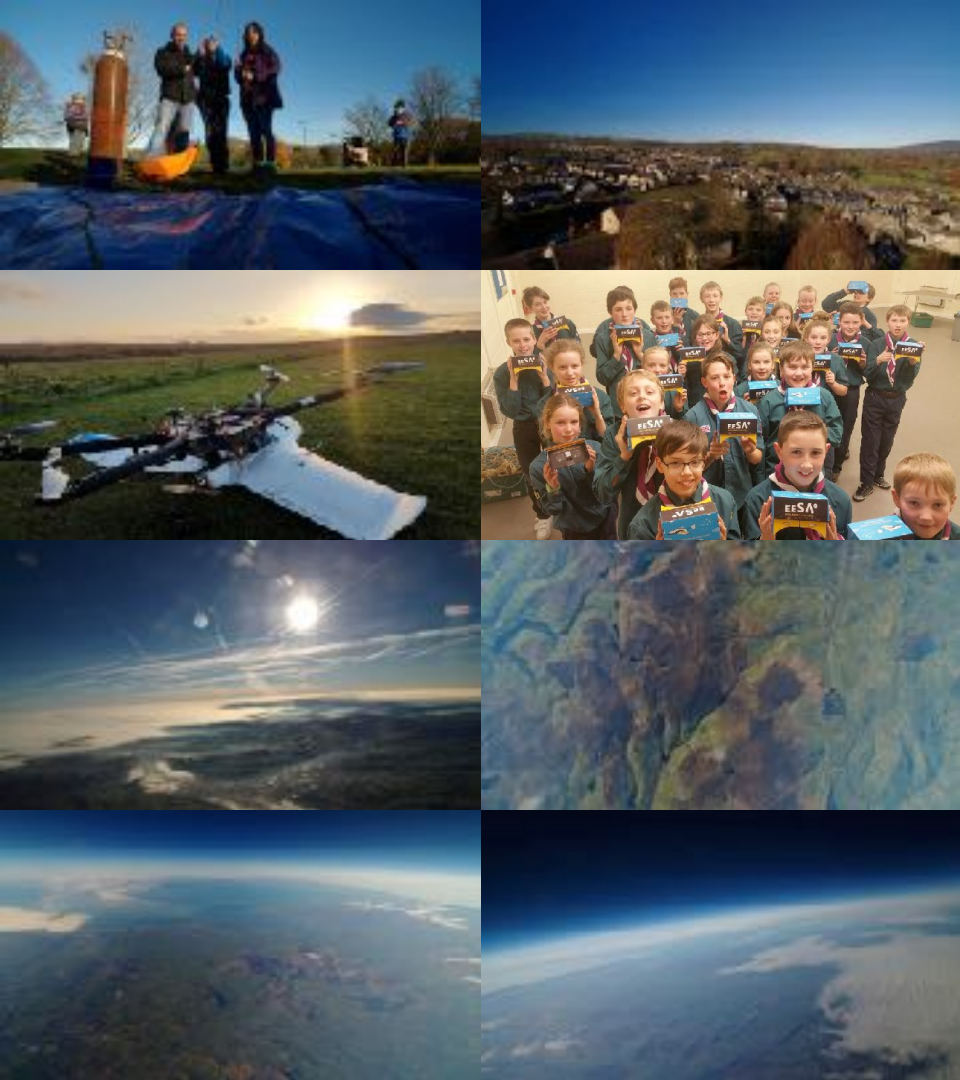
FFSA®

EQUAL EXPERTS COLLEAGUES
TIM SQUIRES & NICK PORTHOUSE

AND TWENTY-FIVE SCOUTS

Why?

- Scouts Project to Break a World Record
- STEM
- Encourage *More* Girls into Engineering
- Because we can
- Because it's fun!

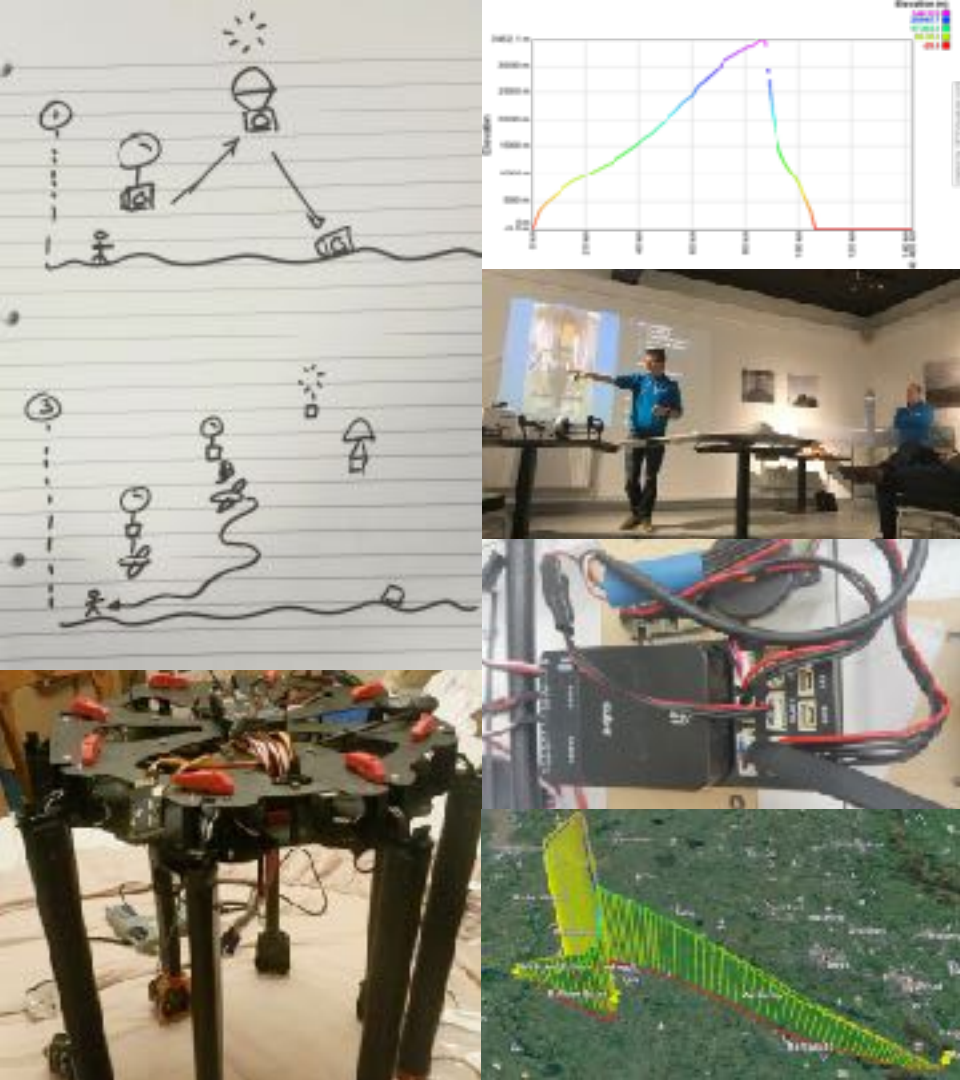






What's this got to do with PyData?

- High Level Mapping Surveys
 - 4 hours of 100 MPixel Images
 - Accurate GPS
 - Camera Attitude
- Python Flight Script
 - We need your help





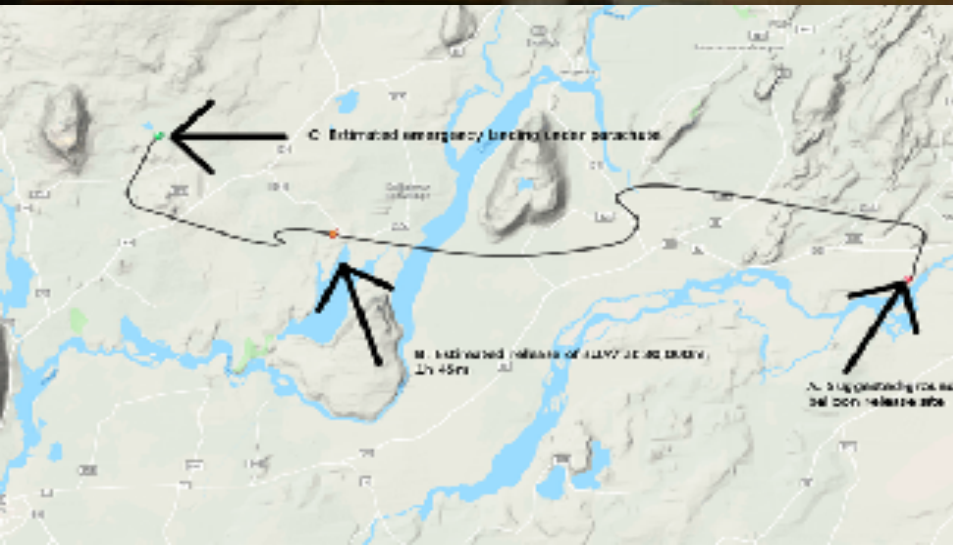
- Initial Balloon Launch
- **Scaled Prototype Test**
- **Flights**
- Release Mechanism Tests
- Safety Case
- Emergency Procedures
- Record Attempt



- Initial Balloon Launch
- Scaled Prototype Test Flights
- **Release Mechanism Tests**
- Safety Case
- Emergency Procedures
- Record Attempt



- Initial Balloon Launch
- Scaled Prototype Test Flights
- Release Mechanism Tests
- **Safety Case**
- Emergency Procedures
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- Initial Balloon Launch
- Scaled Prototype Test Flights
- Release Mechanism Tests
- Safety Case
- **Emergency Procedures**
- Record Attempt



- Initial Balloon Launch
- Scaled Prototype Test Flights
- Release Mechanism Tests
- Auto Return
- Emergency Procedures
- **Record Attempt**



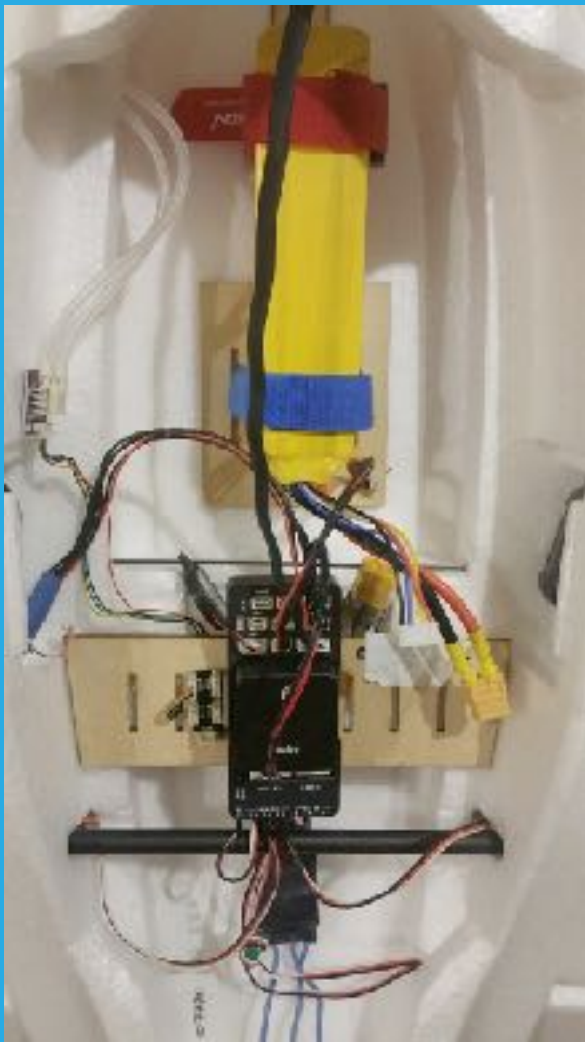
Iceland

- Best launch option
- Two launch sites
- Many landing sites
- 800km driven in a day and a half



The Plane





- **Flight Computer**
 - Pixhawk 2
 - Triple IMU + Compass
 - Dual Power Source
 - WiFi
 - Edison
- **GPS 1 - Here+**
 - Flight Mode
- **ADS-B Ping 1090**
 - Sense & Avoid
 - Radar
- **2 LiPo batteries**
- **Airspeed Sensor**

The Camera Payload

- GoPro HERO5 Session
- Samsung Gear 360
- Another GoPro
in the cube above the plane



On Board Script - Help Wanted!

```
# Moves servo 9 (aux 1) to release payload
def release_payload(self):
    self.log("!!!!!!RELEASING PAYLOAD!!!!!!")
    start_new_thread(self.set_servo, (self.release_servo_number, self))
    self.released = True
    if not self.flight_mission_started:
        self.flight_mission_started = True
        start_new_thread(self.start_flight_mission, ())

# Moves servo 9 (aux 1) to closed to hold payload
def lock_payload(self):
    self.log("!!!!!!LOCKING PAYLOAD!!!!!!")
    start_new_thread(self.set_servo, (self.release_servo_number, self))
    self.released = False
```



<https://github.com/EqualExperts/eesa>

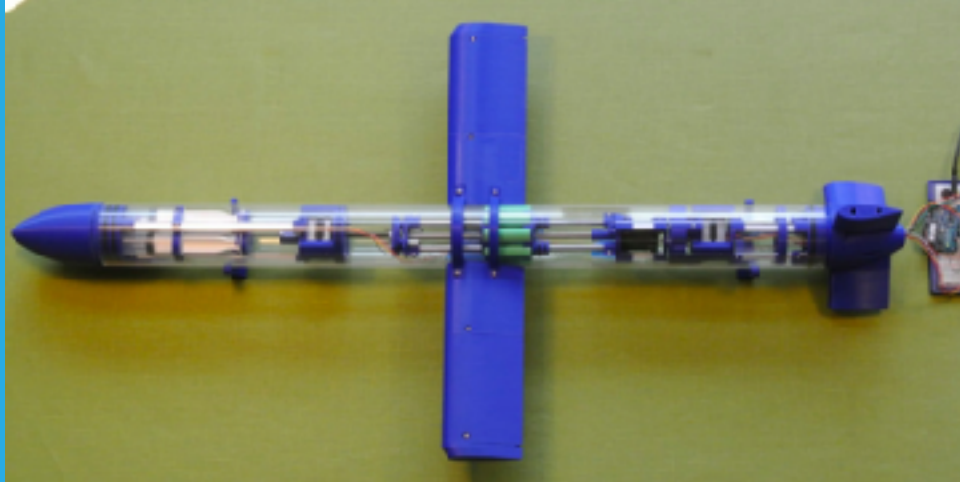
<http://www.equalexperts.com/eesa>





Other Projects?





- UAV Medical Challenge
- The Lake Victoria Challenge
- Auto Speedboat Races
- Underwater Exploration
- Fixed-wing swarms
- Anything else **You** can think off!



Equal Experts

Addingham Scout Group

Questions?