

Equitable Public Transit Network Extreme Weather Event Resilience

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**Career Advising &
Professional Development**

Graduate Student
Professional Development

Agenda

Peter:

- Public Transit (PT) equity
- Problem contextualization
- Problem formalization

Riccardo:

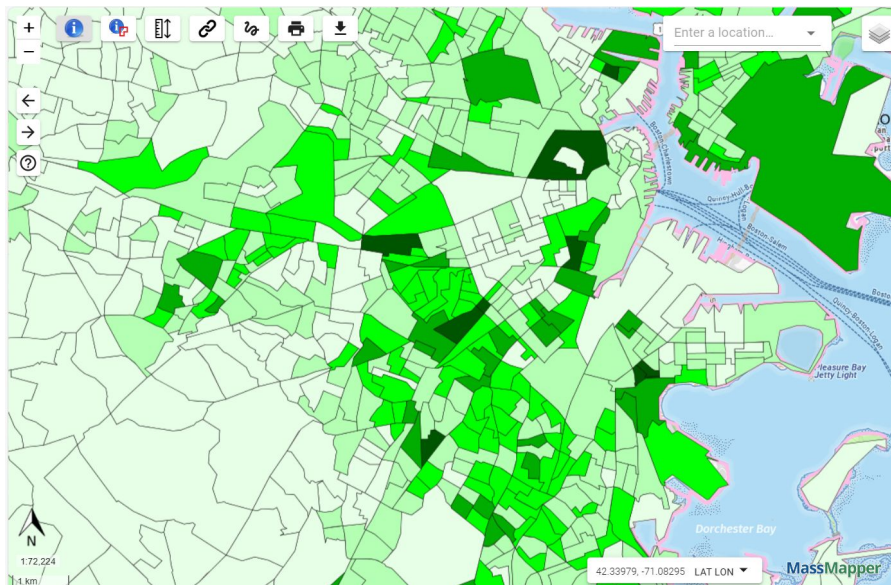
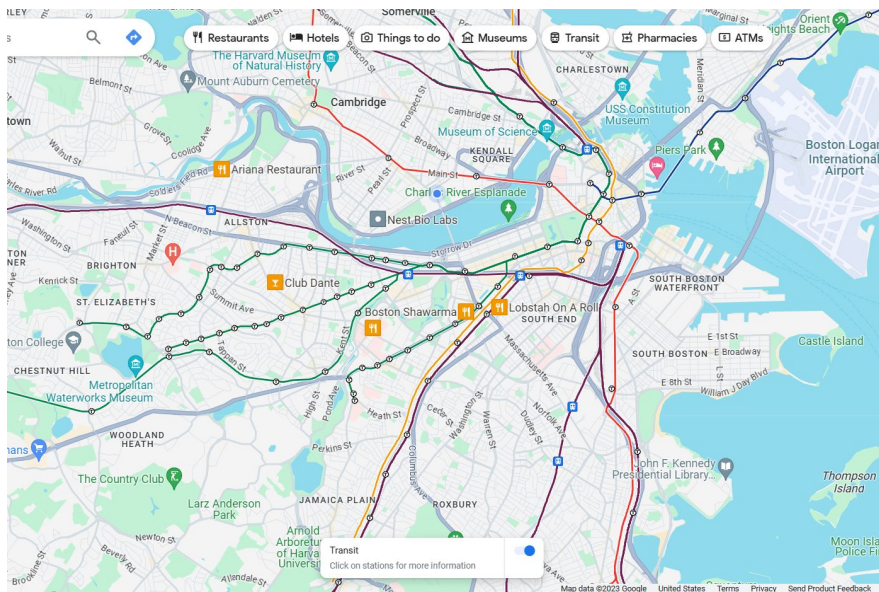
- Formalization validation
- MILP Approach / Experiments
- Conclusion & future work

Public Transit (PT) Equity

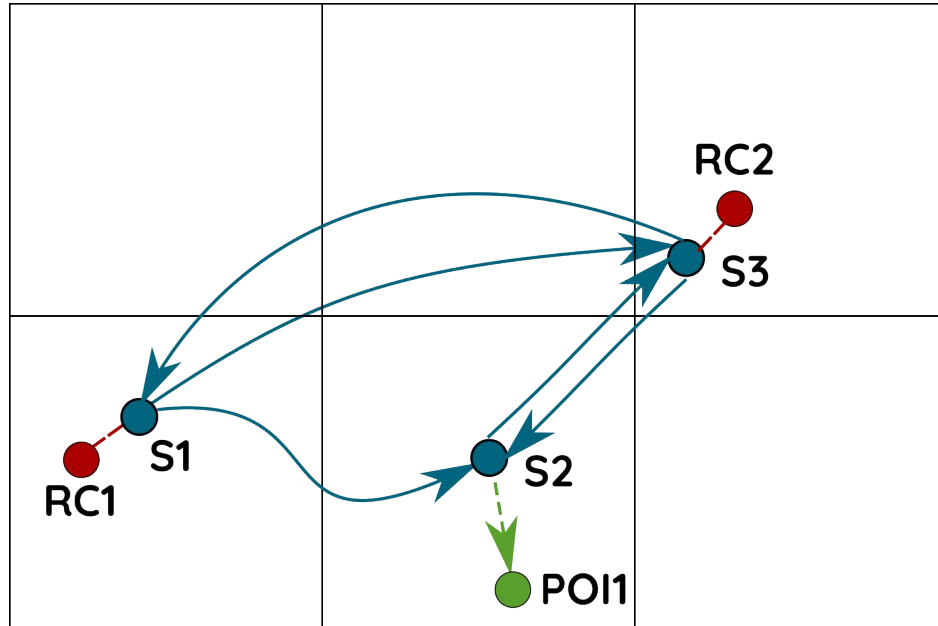
PT Equity

- Map of Boston
- Map of Boston with neighborhoods
- Neighborhood centroids and colored in with census data
- MBTA network on top
- [LINK](#)

PT Equity



Abstraction



PT Equity

- PT is the backbone of socio-economic functioning
- Who are the most **transit critical individuals**?
 - Low income
 - Car-less individuals and households
 - Minorities/Migrants
- Why do we care?
 - Fairness / Equality / **Equity**
 - As a planner but also as a society
 - Economic benefit for all

PT Design

- Design/Planning (Equitable) PTNs
 - Design from scratch
 - “Designing Equitable Transit Networks” [1]
 - Expansion/Reduction
- Operations
 - Paper “Defending transportation networks” [2]
 - Disruptions
 - Extreme weather events (EWE)
 - Increasing in frequency and magnitude
 - Difficult to model (outliers!)
 - Impact on transit critical population

Examples

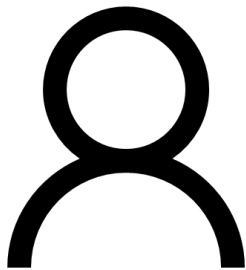
- Pictures of EWE affecting public transit
- Because EWE affect PTNs
- And because individuals from disadvantaged backgrounds are the most vulnerable (transit critical)
- We need to find equitable ways to plan for these disruptions, ensuring access for those that require it the most

Plan for Disruptions Equitably

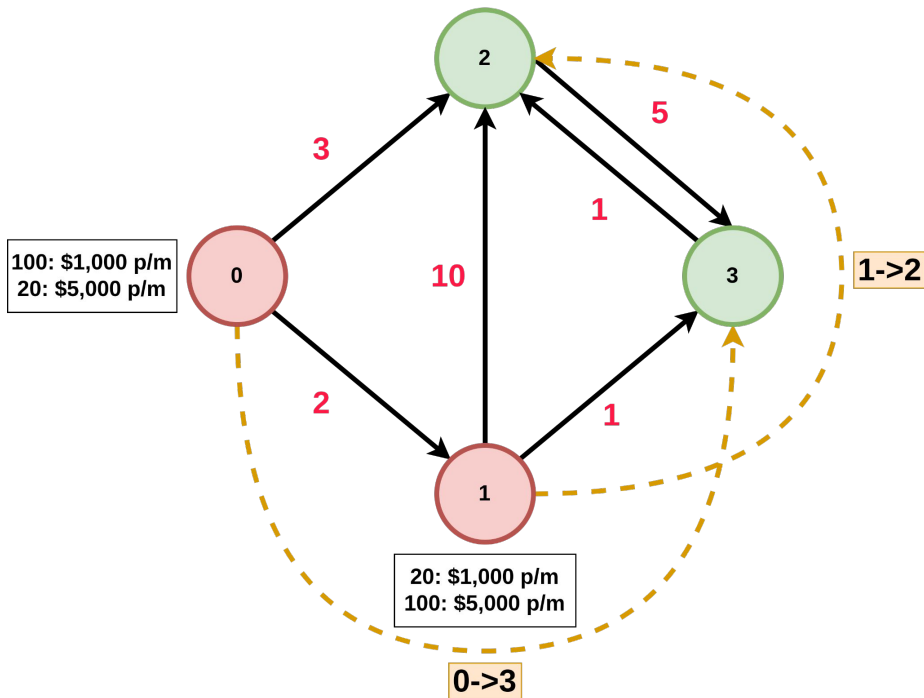
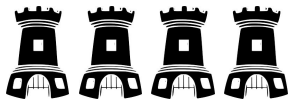


Problem Contextualization & Formulation

The Struggle



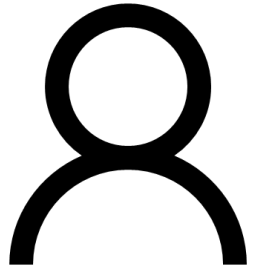
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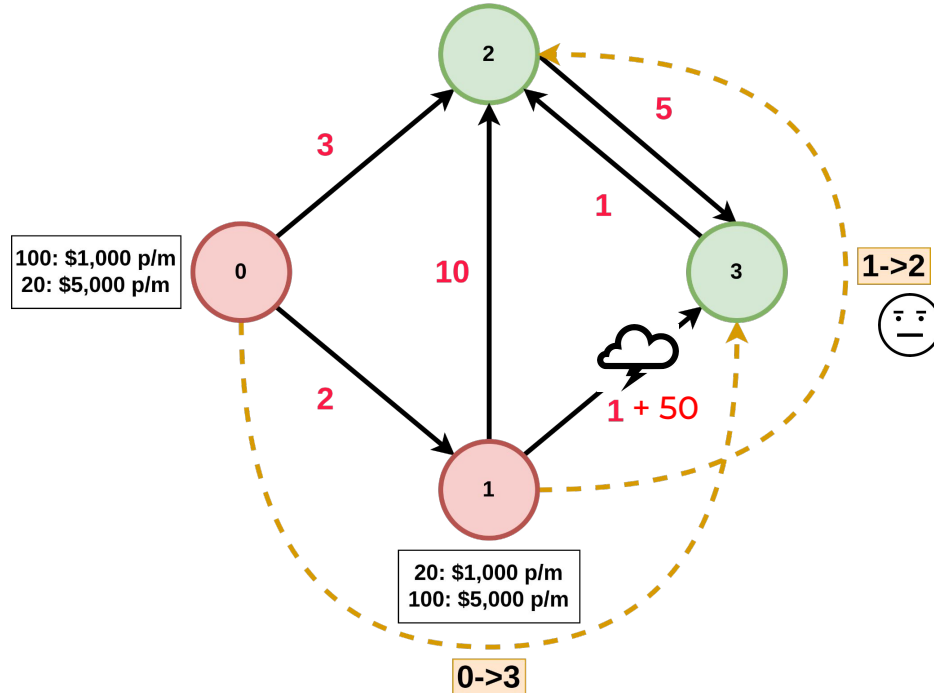
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Disruption

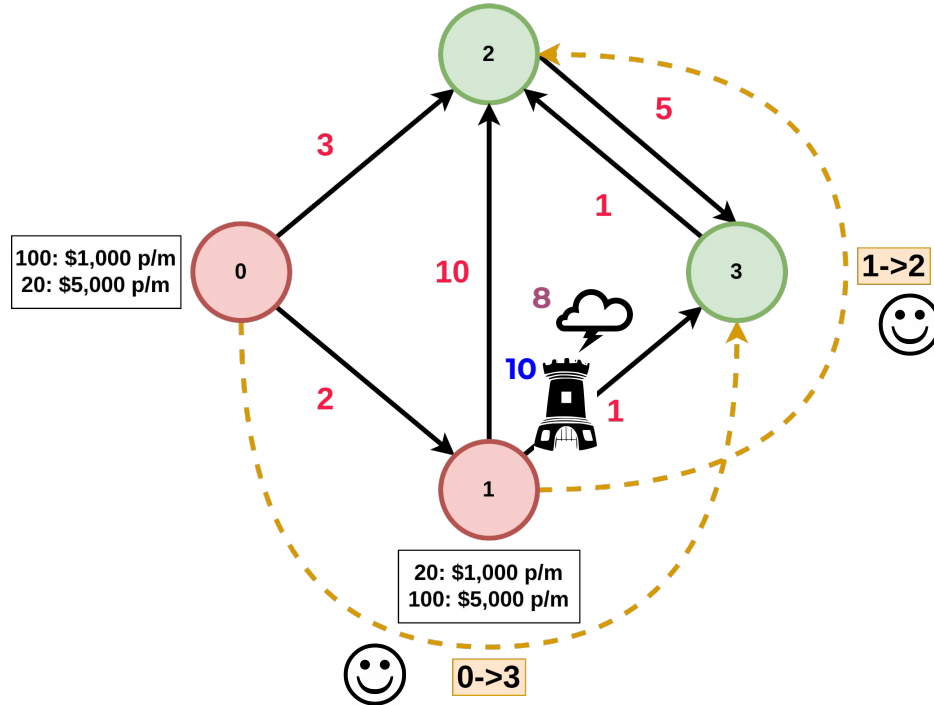
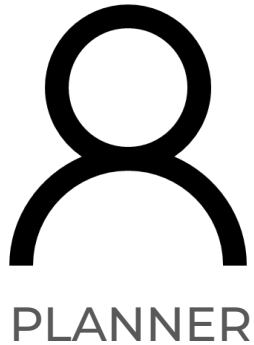


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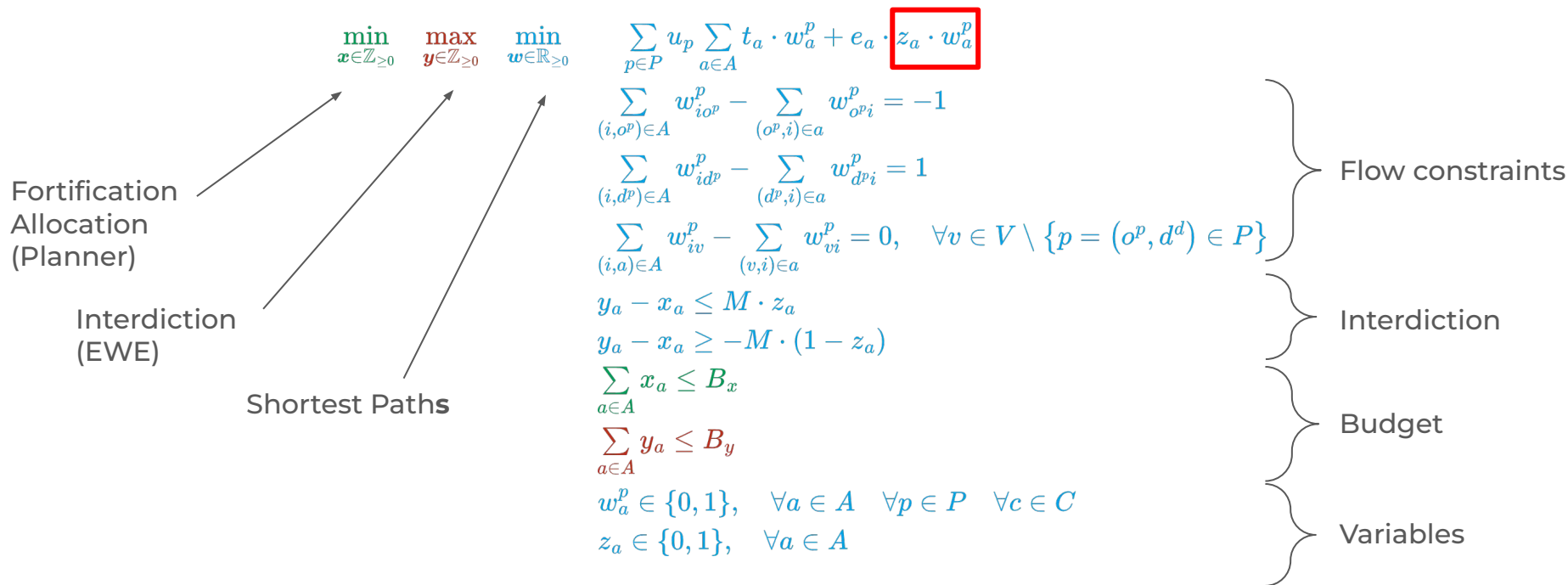


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Fortifying Against Disruption



Problem Formalization



Linearization: McCormick envelopes

$$\min_{x \in \mathbb{Z}_{\geq 0}} \quad \max_{y \in \mathbb{Z}_{\geq 0}} \quad \min_{w \in \mathbb{R}_{\geq 0}}$$

$$\sum_{p \in P} u_p \sum_{a \in A} t_a \cdot w_a^p + e_a \cdot q_a^p$$

$$\sum_{(i, o^p) \in A} w_{io^p}^p - \sum_{(o^p, i) \in a} w_{o^p i}^p = -1$$

$$\sum_{(i, d^p) \in A} w_{id^p}^p - \sum_{(d^p, i) \in a} w_{d^p i}^p = 1$$

$$\sum_{(i, a) \in A} w_{iv}^p - \sum_{(v, i) \in a} w_{vi}^p = 0, \quad \forall v \in V \setminus \{p = (o^p, d^d) \in P\}$$

$$y_a - x_a \leq M \cdot z_a$$

$$y_a - x_a \geq -M \cdot (1 - z_a)$$

$$\sum_{a \in A} x_a \leq B_x$$

$$\sum_{a \in A} y_a \leq B_y$$

$$w_a^p \in \{0, 1\}, \quad \forall a \in A \quad \forall p \in P \quad \forall c \in C$$

$$z_a \in \{0, 1\}, \quad \forall a \in A$$

Flow constraints

Interdiction

Budget

Variables

$$\begin{aligned} q_a^p &\leq z_a \\ q_a^p &\leq w_a^p \\ q_a^p &\geq z_a + w_a^p - 1 \\ q_a^p &\in \{0, 1\}, \quad \forall a \in A \quad \forall p \in P \end{aligned}$$

McCormick envelope constraints

Problem Formalization

$$\min_{x \in \mathbb{Z}_{\geq 0}} \quad \max_{y \in \mathbb{Z}_{\geq 0}} \quad \min_{w \in \mathbb{R}_{\geq 0}}$$

$$\sum_{p \in P} u_p \sum_{a \in A} t_a \cdot w_a^p + e_a \cdot q_a^p$$

$$\sum_{(i, o^p) \in A} w_{io^p}^p - \sum_{(o^p, i) \in a} w_{o^p i}^p = -1$$

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Flow constraints

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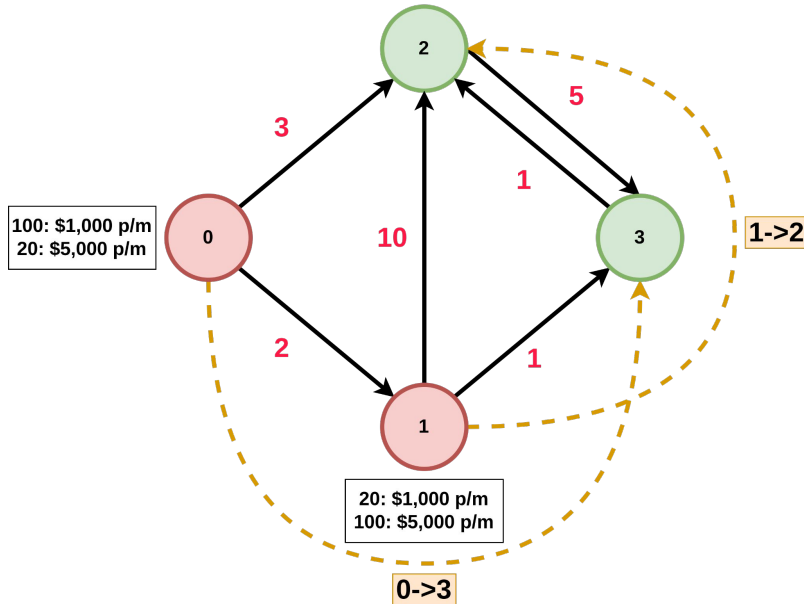
Group and neighborhood median household income

Number of inhabitants of that group in the neighborhood

$$u_p = \sum_{g \in G} \left(\frac{1}{s_g^o} \right) b_g^o \quad \forall p = (o, d) \in P$$

Priority weighting

Formulation Evaluation



TT (0, 3)	8.0	3.0	3.0	8.0	3.0	3.0
TT (1, 2)	2.0	2.0	2.0	10.0	2.0	10.0
OBJ	0.0912	0.0392	0.0392	0.1232	0.0392	0.0712
	(0, 1)	(0, 2)	(1, 2)	(1, 3)	(2, 3)	(3, 2)

Interdictions

Tri/Bilevel MILP

Approach

$$\min_{\mathbf{x} \in \mathbb{Z}_{\geq 0}} \max_{\mathbf{y} \in \mathbb{Z}_{\geq 0}} \min_{\mathbf{w} \in \mathbb{R}_{\geq 0}} \sum_{p \in P} u_p \sum_{a \in A} t_a \cdot w_a^p + e_a \cdot q_a^p$$

Shortest Path Interdiction

$$\min_{w \in \mathbb{R}_{\geq 0}}$$

$$\sum_{a \in A} (t_a + e_a \cdot z_a) w_a^p$$

subject to

$$\sum_{(i, o^p) \in A} w_{io^p}^p - \sum_{(o^p, i) \in A} w_{o^p i}^p = -1$$

$$\sum_{(i, d^p) \in A} w_{id^p}^p - \sum_{(d^p, i) \in A} w_{d^p i}^p = 1$$

$$\sum_{(i, a) \in A} w_{iv}^p - \sum_{(v, i) \in A} w_{vi}^p = 0, \quad \forall v \in V \setminus \{p = (o^p, d^d) \in P\}$$

Shortest Path Interdiction **[3]**

$$\begin{aligned} & \max_{x \in X} \min_w \sum_{a \in A} (t_a + e_a \cdot x_a) w_a \\ \text{s.t. } & \sum_{a \in FS(i)} w_a - \sum_{a \in RS(i)} w_a = \begin{cases} 1 & \text{for } i = o \\ 0 & \forall i \in N \setminus \{o, d\} \\ -1 & \text{for } i = d \end{cases} \\ & w_a \geq 0 \quad \forall a \in A, \end{aligned}$$

Shortest **Multi** Path Interdiction

$$\begin{aligned} & \max_{x \in X} \min_w \sum_{a \in A} (t_a + e_a \cdot x_a) w_a \\ \text{s.t. } & \sum_{a \in FS(i)} w_a - \sum_{a \in RS(i)} w_a = \begin{cases} 1 & \text{for } i = o \\ 0 & \forall i \in N \setminus \{o, d\} \\ -1 & \text{for } i = d \end{cases} \\ & w_a \geq 0 \quad \forall a \in A, \end{aligned}$$



$$\begin{aligned} & \max_{x \in X} \min_w \sum_{p \in P} \sum_{a \in A} (t_a + e_a \cdot x_a) w_a^p \\ \text{s.t. } & \sum_{a \in FS(i)} w_a^p - \sum_{a \in RS(i)} w_a^p = \begin{cases} 1 & \text{for } i = o \\ 0 & \forall i \in N \setminus \{o^p, d^p\} \\ -1 & \text{for } i = d \end{cases} \quad \forall p \in P \\ & w_a^p \geq 0 \quad \forall a \in A, \end{aligned}$$

Shortest **Weighted Multi** Path Interdiction

$$\begin{aligned} & \max_{\mathbf{x} \in X} \min_w \sum_{p \in P} \sum_{a \in A} (t_a + e_a \cdot x_a) w_a^p \\ \text{s.t. } & \sum_{a \in FS(i)} w_a^p - \sum_{a \in RS(i)} w_a^p = \begin{cases} 1 & \text{for } i = o \\ 0 & \forall i \in N \setminus \{o^p, d^p\} \\ -1 & \text{for } i = d \end{cases} \quad \forall p \in P \\ & w_a^p \geq 0 \quad \forall a \in A, \end{aligned}$$



$$\begin{aligned} & \max_{\mathbf{x} \in X} \min_w \sum_{p \in P} \textcolor{red}{u}_p \sum_{a \in A} (t_a + e_a \cdot x_a) w_a^p \\ \text{s.t. } & \sum_{a \in FS(i)} w_a^p - \sum_{a \in RS(i)} w_a^p = \begin{cases} 1 & \text{for } i = o \\ 0 & \forall i \in N \setminus \{o^p, d^p\} \\ -1 & \text{for } i = d \end{cases} \quad \forall p \in P \\ & w_a^p \geq 0 \quad \forall a \in A, \end{aligned}$$

Shortest Weighted Multi Path Interdiction **Dual**

$$\begin{aligned}
 & \max_{\mathbf{x} \in X} \min_{\mathbf{y}} \sum_{p \in P} u_p \sum_{a \in A} (c_a + x_a d_a) y_a^p \\
 \text{s.t. } & \sum_{a \in FS(i)} y_a^p - \sum_{a \in RS(i)} y_a^p = \begin{cases} 1 & \text{for } i = s \\ 0 & \forall i \in N \setminus \{s^p, t^p\} \\ -1 & \text{for } i = t \end{cases} \quad \forall p \in P \\
 & y_a^p \geq 0 \quad \forall a \in A \quad \forall p \in P,
 \end{aligned}$$



$$\begin{aligned}
 & \max_{\mathbf{x}, \pi} \sum_{p \in P} \pi_t^p - \pi_s^p \\
 \text{s.t. } & u_p \left(\pi_j^p - \pi_i^p \right) - d_a x_a \leq c_a \quad \forall a = (i, j) \in A \quad \forall p \in P \\
 & \pi_s^p = 0 \\
 & \mathbf{x} \in X
 \end{aligned}$$

Bilevel Optimization

$$\min_{\mathbf{x} \in \mathbb{Z}_{\geq 0}} \quad \max_{\mathbf{y} \in \mathbb{Z}_{\geq 0}, \boldsymbol{\pi} \in \mathbb{R}}$$

subject to

$$\sum_{p,a} \pi_d^p - \pi_o^p \quad \text{where } p = (o, d)$$

$$\sum_{a \in A} y_a - B_y \leq 0$$

$$\sum_{a \in A} x_a - B_x \leq 0$$

$$u_p \cdot (\pi_j^p - \pi_i^p) - e_a z_a - t_a \leq 0 \quad \forall a = (i, j) \in A, \forall p \in P$$

$$x_a - y_a - M \cdot z_a + \epsilon \leq 0 \quad \forall a = (i, j) \in A$$

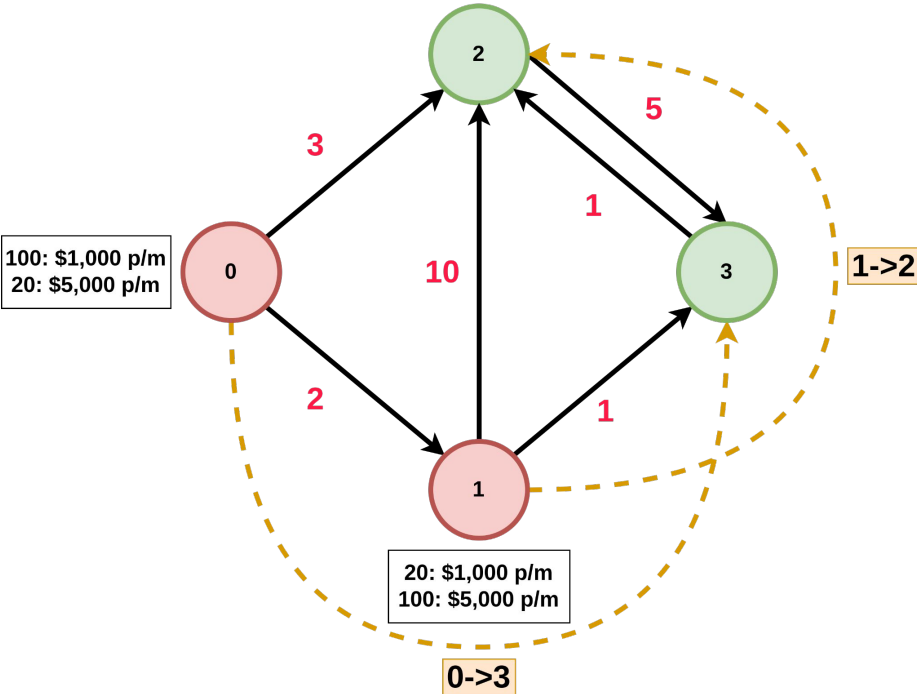
$$-M(1 - z_a) - x_a + y_a \leq 0 \quad \forall a = (i, j) \in A$$

$$z_a \in \{0, 1\} \quad \forall a \in A$$

$$e_a, t_a \in \mathbb{R}_{\geq 0} \quad \forall a \in A$$

$$\pi_o^p = 0 \quad \forall p = (o, d) \in P$$

Results with Fixed Fortifications



Interdiction Budget = 1

Shortest path (dual formulation | multi-path):

For OD pair (0, 3)

[0, 1, 2, 3] travel time: 18.0

For OD pair (1, 2)

[1, 2] travel time: 10.0

Interdicted: [(1,3)]

Interdiction Budget = 2

Shortest path (dual formulation | multi-path):

For OD pair (0, 3)

[0, 2, 3] travel time: 8.0

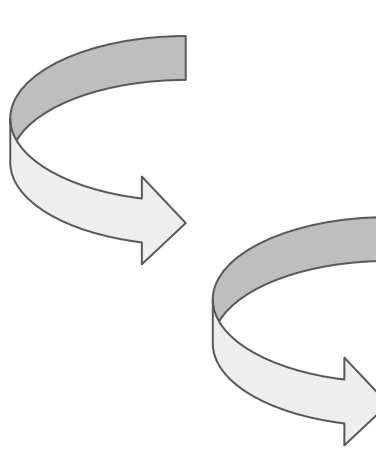
For OD pair (1, 2)

[1, 3, 2] travel time: 2.0

Interdicted: [(0,1), (1,2)]

What Next?

If you like it you should put an Expectation on it



$$\begin{array}{l}
 \min_{\mathbf{x} \in \mathbb{Z}_{\geq 0}} \max_{\mathbf{y} \in \mathbb{Z}_{\geq 0}} \min_{\mathbf{w} \in \mathbb{R}_{\geq 0}} \sum_{p \in P} u_p \sum_{a \in A} t_a \cdot w_a^p + e_a \cdot q_a^p \\
 \min_{\mathbf{x} \in \mathbb{Z}_{\geq 0}} \mathbb{E}_{\xi} \left[\min_{\mathbf{w} \in \mathbb{R}_{\geq 0}} \sum_{p \in P} u_p \sum_{a \in A} t_a \cdot w_a^p + e_a \cdot q_a^p \right] \\
 \min_{\mathbf{x} \in \mathbb{Z}_{\geq 0}, \mathbf{w} \in \mathbb{R}_{\geq 0}} \sum_{s \in S} \alpha(s) \sum_{p \in P} u_p \sum_{a \in A} t_a \cdot w_a^p + e_a \cdot q_a^p
 \end{array}$$

...

$$\begin{array}{l}
 y_a^{\omega} - x_a \leq M \cdot z_a \\
 y_a^{\omega} - x_a \geq -M \cdot (1 - z_a)
 \end{array}$$

...



Conclusion

- Formalizing real-world problems is hard
- Taking the dual is hard
- Stochastic approach is conceptually more appropriate
 - Particularly given real data
- But results suggest that equitable planning for EWE is
 - Quantifiable
 - Optimizable
- Novel weighted-multipath shortest path optimization
- Open questions
 - Quality of solutions?
 - Can we do better?

References

1. Pavia, Sophie, J. Mori, Aryaman Sharma, Philip Pugliese, Abhishek Dubey, Samitha Samaranayake, and Ayan Mukhopadhyay. **"Designing Equitable Transit Networks."** arXiv preprint arXiv:2212.12007 (2022).
2. Lou, Yingyan, and Lihui Zhang. **"Defending transportation networks against random and targeted attacks."** Transportation research record 2234, no. 1 (2011): 31-40.
3. Israeli, Eitan, and R. Kevin Wood. **"Shortest-path network interdiction."** Networks: An International Journal 40, no. 2 (2002): 97-111.