Distributed Systems Master of Science in Engineering in Computer Science

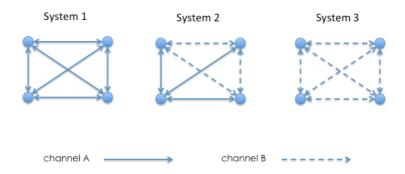
AA 2019/2020

Lecture 6 – Exercises October 15th, 2019

Ex 1: Let channel A and channel B be two different types of point-to-point channels satisfying the following properties:

- channel A: if a correct process p_i sends a message m to a correct process p_j at time t, then m is delivered by p_i by time $t+\delta$.
- channel B: if a correct process p_i sends a message m to a correct process p_j at time t, then m is delivered by p_i with probability $p_{cons}(p_{cons} < 1)$.

Let us consider the following systems composed by 4 processes p_1 , p_2 , p_3 and p_4 connected trough channels A and channels B.



Assuming that each process p_i is aware of the type of channel connecting it to any other process, answer to the following questions:

- 1. is it possible to design an algorithm implementing a perfect failure detector in system 2 if only processes having an outgoing channel of type B can fail by crash?
- 2. is it possible to design an algorithm implementing a perfect failure detector in system 2 if any process can fail by crash?
- 3. is it possible to design an algorithm implementing a perfect failure detector in system 3?

For each point, if an algorithm exists write its pseudo-code, otherwise show the impossibility.

Ex 2: Consider a distributed system composed by n processes $\{p_1, p_2, ..., p_n\}$ that communicate by exchanging messages on top of a line topology, where p_1 and p_n are respectively the first and the last process of the network.

Initially, each process knows only its left neighbour and its right neighbour (if they exist) and stores the respective identifiers in two local variables LEFT and RIGHT.

Processes may fail by crashing, but they are equipped with a perfect oracle that notifies at each process the new neighbour (when one of the two fails) through the following primitives:

- Left_neighbour(p_x): process p_x is the new left neighbour of p_i
- Right_neighbour(p_x): process p_x is the new right neighbour of p_i

Both the events may return a NULL value in case p_i becomes the first or the last process of the line.

Each process can communicate only with its neighbours.

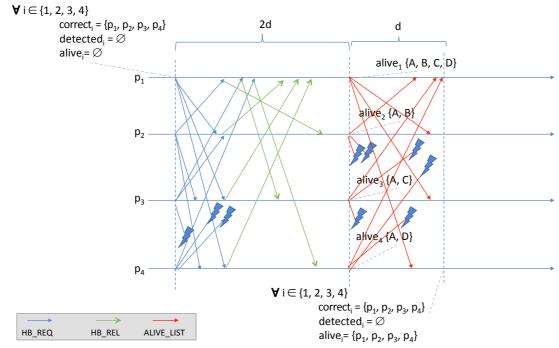
Write the pseudo-code of an algorithm implementing a Leader Election primitive assuming that channels connecting two neighbour processes are perfect.

Solutions

Exercise 1.1

```
Init
correct_i = \{p1, p2, p3, p4\}
alive_i = \emptyset
detected_i = \emptyset
for each p_i \in correct_i do:
         trigger send (HB REQ, i) to pi
start Timer1(2\delta)
upon event deliver (HB REQ, j) from p<sub>i</sub>
         trigger send (HB REL, i) to p<sub>i</sub>
upon event deliver (HB_REL, j) from p<sub>i</sub>
         alive<sub>i</sub> = alive<sub>i</sub> \cup \{p_i\}
when timer 1 = 0
         for each p_i \in correct_i do
                   trigger send (ALIVE LIST, alive, i) to p<sub>i</sub>
         start Timer2(\delta)
upon event deliver (ALIVE LIST, alive<sub>i</sub>, j) from p<sub>i</sub>
         alive_i = alive_i \cup alive_i
when timer2 = 0 do
         for each p_i \in correct_i do
                   if p_i \notin alive_i AND p_i \notin detected_i
                             detected_i = detected_i \cup \{p_i\}
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 \begin{aligned} & \textbf{trigger} \; crash \; (p_j) \\ alive_i &= \varnothing \\ & \textbf{for each} \; p_j \in correct_i \; \textbf{do} : \\ & \textbf{trigger} \; send \; (HB\_REQ, \, i) \; to \; p_j \\ start\_Timer1(2\delta) \end{aligned}
```



 $Figure \ 1-Example \ of \ the \ Algorithm \ execution \ with \ no \ failures \ and \ having \ p_1 \ connected \ with \ just \ channel \ A \ links$

Exercise 1.2

No, you cannot as once the process having all channel A fails (i.e., p_1 in the example) you may lose accuracy

Exercise 1.3

No, because channels B are like fair loss and you cannot implement P on fair loss links.

Exercise 2

Uses

 $\begin{aligned} & Oracle \ O_i \\ & Perfect \ point \ to \ point \ link \end{aligned}$

Init

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\begin{array}{ll} leader_i = \bot \\ left_i = get\_left() \\ right_i = get\_right() \end{array} \\ \begin{array}{ll} \%initialize \ left \ with \ my \ current \ left \ neighbour \\ \%initialize \ left \ with \ my \ current \ right \ neighbor \end{array}
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 \begin{tabular}{l} \textbf{when } left_i = null \begin{tabular}{l} \textbf{do} \\ leader_i = p_i \\ \textbf{trigger} \ leader(p_i) \\ \textbf{trigger} \ send \ (NEW\_LEADER, \ leader_i) \ to \ right_i \\ \end{tabular}  \begin{tabular}{l} \textbf{upon event } deliver \ (NEW\_LEADER, \ l) \ from \ left_i \\ leader_i \neq l \\ leader_i = l \\ \textbf{trigger} \ leader(l) \\ \textbf{trigger} \ send \ (NEW\_LEADER, \ leader_i) \ to \ right_i \\ \end{tabular}  \begin{tabular}{l} \textbf{upon event } \ left\_neighbour(p_j) \\ left_i = p_j \\ \end{tabular}  \begin{tabular}{l} \textbf{upon event } \ right\_neighbour(p_j) \\ right_i = p_j \\ \end{tabular}  \begin{tabular}{l} \textbf{upon event } \ right\_neighbour(p_j) \\ right_i = p_j \\ \end{tabular}  \begin{tabular}{l} \textbf{upon event } \ right\_neighbour(p_j) \\ right_i = p_j \\ \end{tabular}  \begin{tabular}{l} \textbf{upon event } \ right\_neighbour(p_j) \\ right_i = p_j \\ \end{tabular}  \begin{tabular}{l} \textbf{upon event } \ right\_neighbour(p_j) \\ right_i = p_j \\ \end{tabular}  \begin{tabular}{l} \textbf{upon event } \ right\_neighbour(p_j) \\ right_i = p_j \\ \end{tabular}  \begin{tabular}{l} \textbf{upon event } \ right\_neighbour(p_j) \\ \end{tabular}  \begin{tabular}{l} \textbf{upon event } \ right\_neighbour
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