

# Symmetric Ciphers II

Computer and Network Security

Emilio Coppa

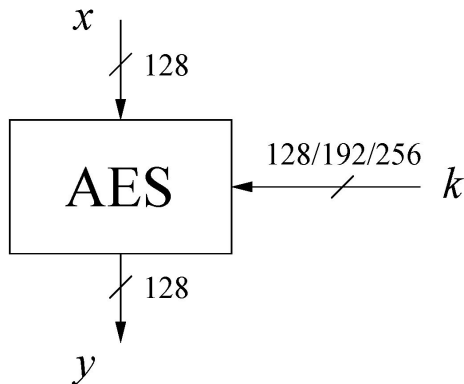
# Advanced Encryption Standard (AES)

- AES is the most widely used symmetric cipher today
- The algorithm for AES was chosen by the US *National Institute of Standards and Technology* (NIST) in a multi-year selection process.
- The requirements for all AES candidate submissions were:
  - Block cipher with **128-bit block size**
  - **Three supported key lengths:** 128, 192 and 256 bit
  - Security relative to other submitted algorithms
  - **Efficiency** in software and hardware

# Chronology of the AES Selection

- Open call for a new block cipher announced by NIST in January, 1997
- 15 candidates algorithms accepted in August, 1998
- 5 finalists announced in August, 1999:
  - *Mars* – IBM Corporation
  - *RC6* – RSA Laboratories
  - *Rijndael* – J. Daemen & V. Rijmen
  - *Serpent* – Eli Biham et al.
  - *Twofish* – B. Schneier et al.
- In October 2000, *Rijndael* was chosen as the AES
- AES was formally approved as a US federal standard in November 2001.  
NSA allows to use AES with 192/256 bit key.

# AES: overview

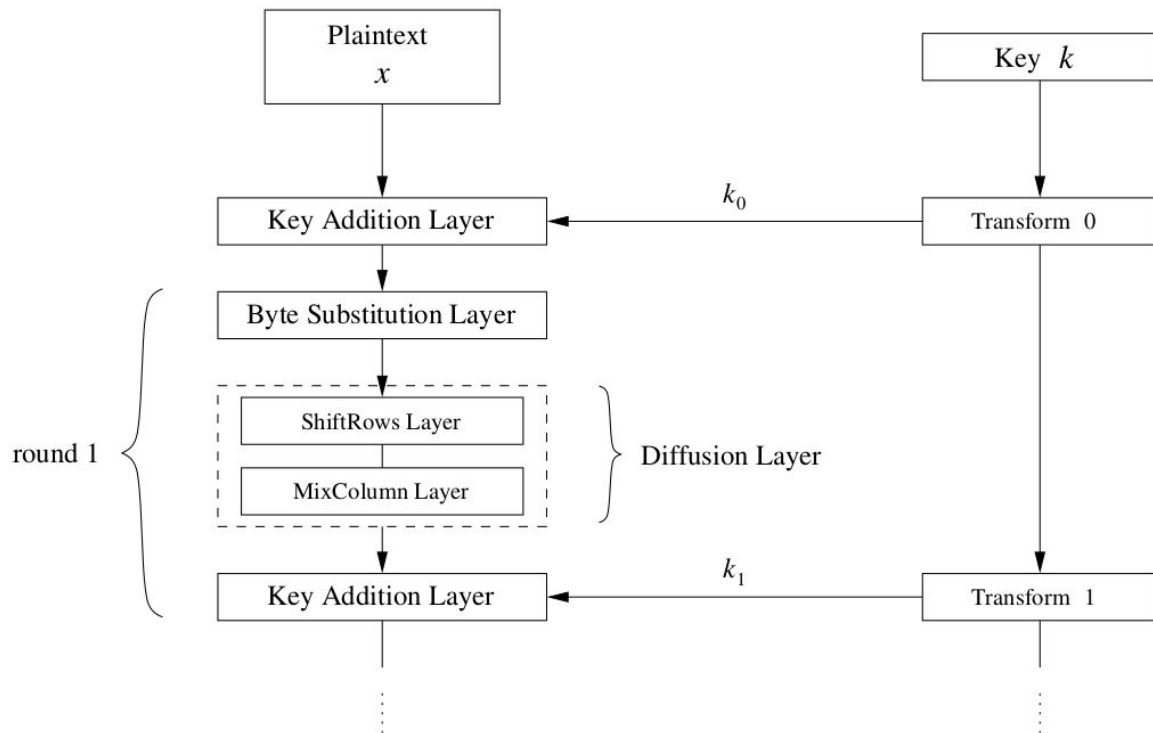


The number of rounds depends on the chosen key length:

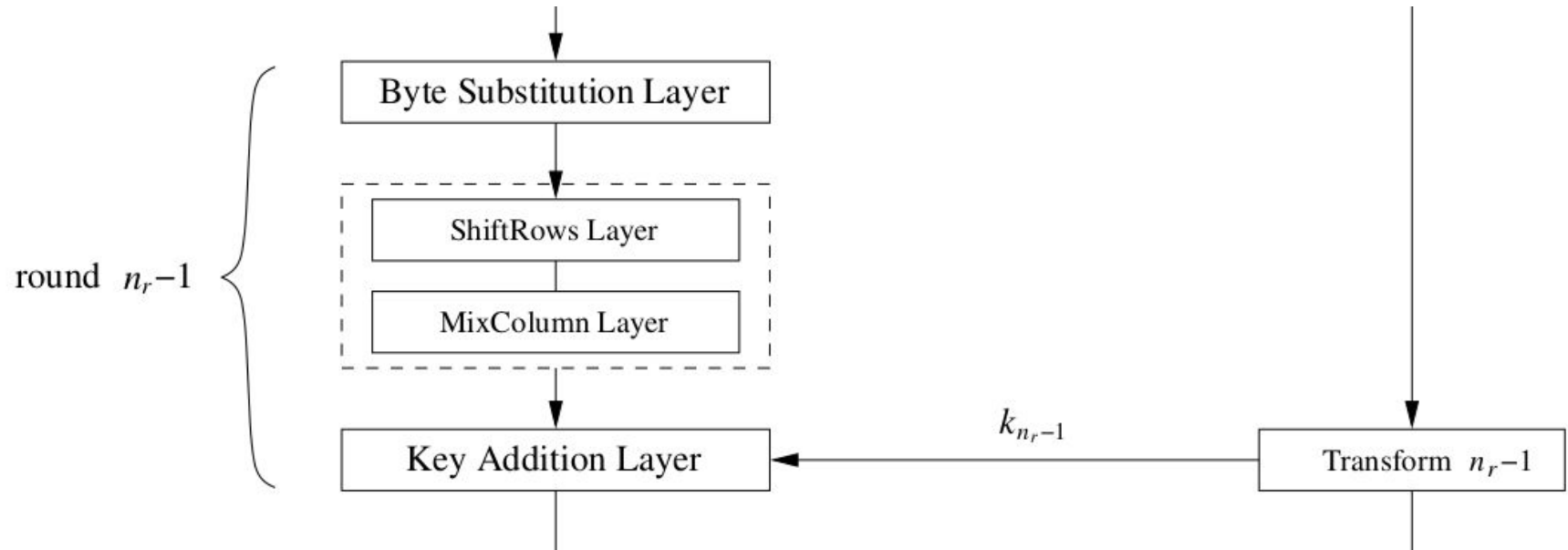
| Key length (bits) | Number of rounds |
|-------------------|------------------|
| 128               | 10               |
| 192               | 12               |
| 256               | 14               |

# AES: Overview

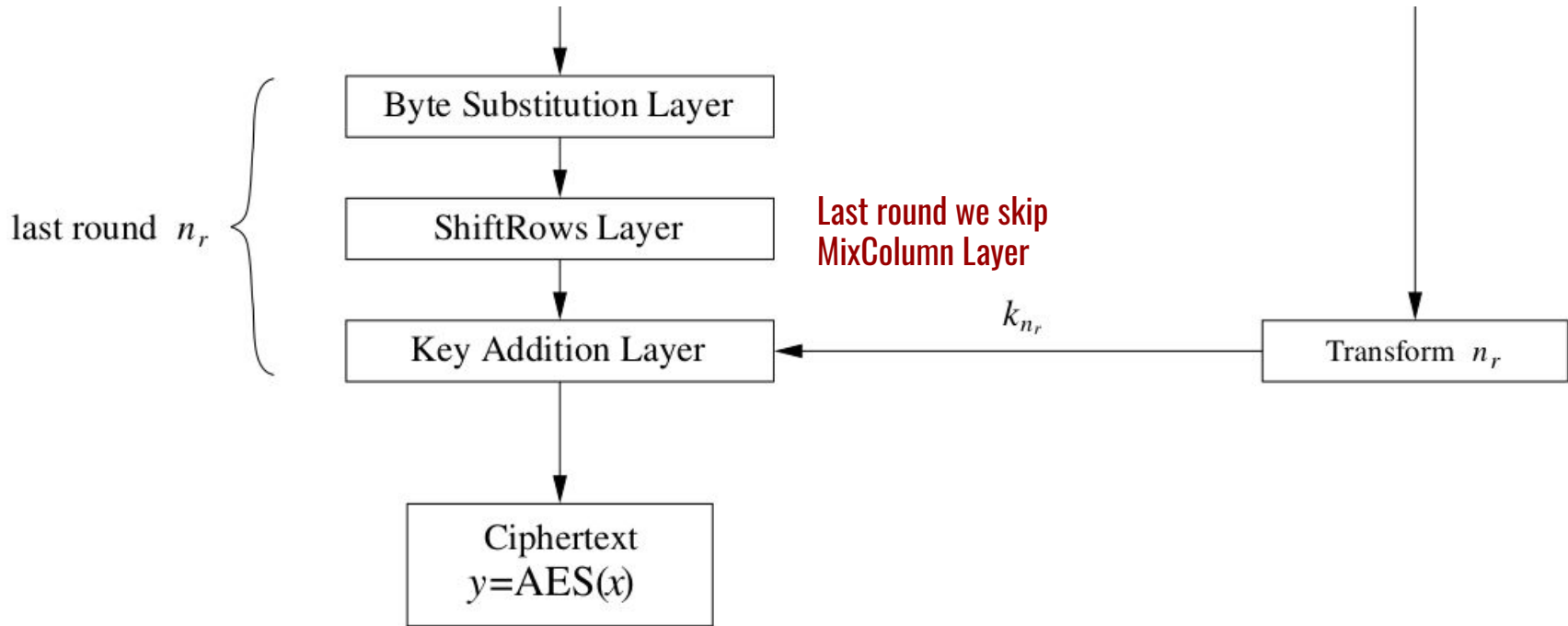
Each round consists of different “layers”



# AES: Overview (2)



# AES: Overview (3)



# AES: Layers

Each round consists of four main layers:

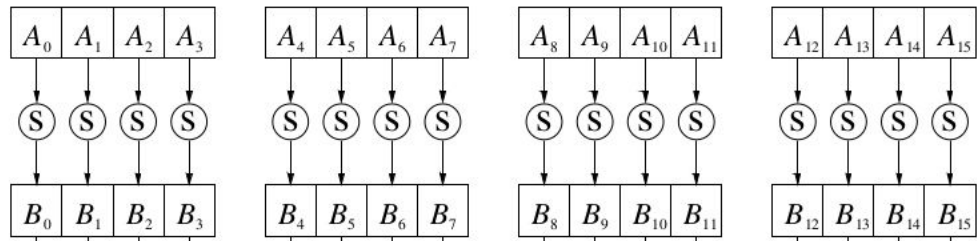
- |                 |   |               |
|-----------------|---|---------------|
| 1. ByteSub      | → | CONFUSION     |
| 2. ShiftRow     | } | →             |
| 3. MixColumn    |   |               |
| 4. Key Addition | → | KEY WHITENING |

**Last round does not have MixColumn layer.**



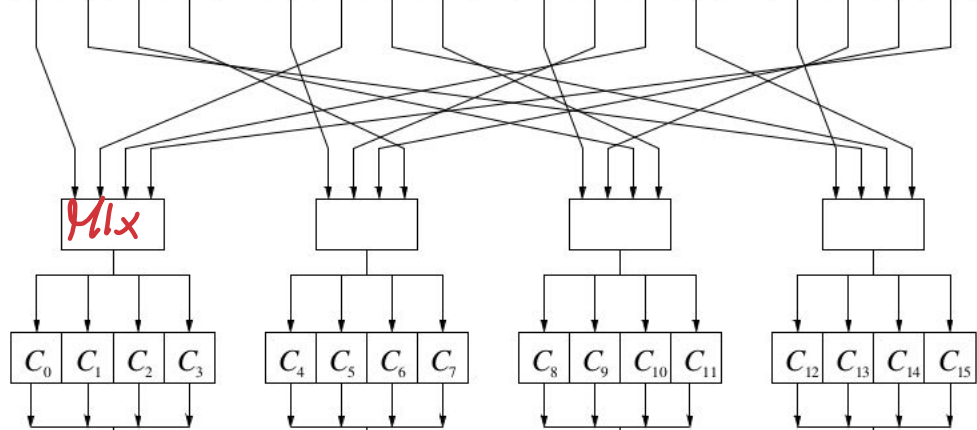
# AES: Layers (2)

16 block  
of 8 bits  
Byte Substitution



ShiftRows

MixColumn



Key Addition



*generated by  
an algorithm.*

# Internal Structure of AES

- AES is a **byte-oriented** cipher. It is not based on Feistel network (as DES), but on a substitution-permutation network
- The state A (i.e., the 128-bit data path) can be arranged in a 4x4 matrix:

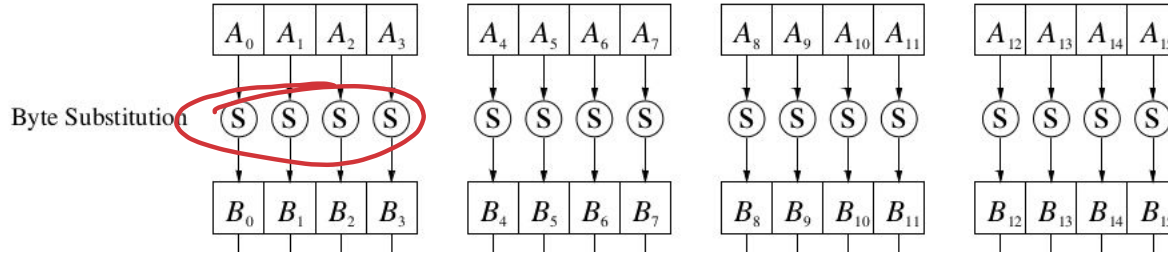
|       |       |          |          |
|-------|-------|----------|----------|
| $A_0$ | $A_4$ | $A_8$    | $A_{12}$ |
| $A_1$ | $A_5$ | $A_9$    | $A_{13}$ |
| $A_2$ | $A_6$ | $A_{10}$ | $A_{14}$ |
| $A_3$ | $A_7$ | $A_{11}$ | $A_{15}$ |

with  $A_0, \dots, A_{15}$  denoting the 16-byte input of AES

# Byte Substitution Layer

1st Step

Independent by every byte.



**Confusion:** if you flip one bit in  $A_i$ , it will affect on average 3 or 4 bits in  $B_i$

- The Byte Substitution layer consists of 16 **S-Boxes** with the following properties:
- The S-Boxes are
  - **identical**
  - the only **nonlinear** elements of AES, i.e.,  $\text{ByteSub}(A_i) + \text{ByteSub}(A_j) \neq \text{ByteSub}(A_i + A_j)$
  - **bijective**, i.e., there exists a one-to-one mapping of input and output bytes  $\Rightarrow$  S-Box can be uniquely reversed
- In sw implementations, the **S-Box** is usually realized as a **lookup table**

# Byte Substitution Layer (2)

$$S(A_i) = B_i$$

|     | y  |    |    |    |    |    |    |    |    |    |    |    |    |    |    |    |
|-----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|
|     | 0  | 1  | 2  | 3  | 4  | 5  | 6  | 7  | 8  | 9  | A  | B  | C  | D  | E  | F  |
| 0   | 63 | 7C | 77 | 7B | F2 | 6B | 6F | C5 | 30 | 01 | 67 | 2B | FE | D7 | AB | 76 |
| 1   | CA | 82 | C9 | 7D | FA | 59 | 47 | F0 | AD | D4 | A2 | AF | 9C | A4 | 72 | C0 |
| 2   | B7 | FD | 93 | 26 | 36 | 3F | F7 | CC | 34 | A5 | E5 | F1 | 71 | D8 | 31 | 15 |
| 3   | 04 | C7 | 23 | C3 | 18 | 96 | 05 | 9A | 07 | 12 | 80 | E2 | EB | 27 | B2 | 75 |
| 4   | 09 | 83 | 2C | 1A | 1B | 6E | 5A | A0 | 52 | 3B | D6 | B3 | 29 | E3 | 2F | 84 |
| 5   | 53 | D1 | 00 | ED | 20 | FC | B1 | 5B | 6A | CB | BE | 39 | 4A | 4C | 58 | CF |
| 6   | D0 | EF | AA | FB | 43 | 4D | 33 | 85 | 45 | F9 | 02 | 7F | 50 | 3C | 9F | A8 |
| 7   | 51 | A3 | 40 | 8F | 92 | 9D | 38 | F5 | BC | B6 | DA | 21 | 10 | FF | F3 | D2 |
| x 8 | CD | 0C | 13 | EC | 5F | 97 | 44 | 17 | C4 | A7 | 7E | 3D | 64 | 5D | 19 | 73 |
| 9   | 60 | 81 | 4F | DC | 22 | 2A | 90 | 88 | 46 | EE | B8 | 14 | DE | 5E | 0B | DB |
| A   | E0 | 32 | 3A | 0A | 49 | 06 | 24 | 5C | C2 | D3 | AC | 62 | 91 | 95 | E4 | 79 |
| B   | E7 | C8 | 37 | 6D | 8D | D5 | 4E | A9 | 6C | 56 | F4 | EA | 65 | 7A | AE | 08 |
| C   | BA | 78 | 25 | 2E | 1C | A6 | B4 | C6 | E8 | DD | 74 | 1F | 4B | BD | 8B | 8A |
| D   | 70 | 3E | B5 | 66 | 48 | 03 | F6 | 0E | 61 | 35 | 57 | B9 | 86 | C1 | 1D | 9E |
| E   | E1 | F8 | 98 | 11 | 69 | D9 | 8E | 94 | 9B | 1E | 87 | E9 | CE | 55 | 28 | DF |
| F   | 8C | A1 | 89 | 0D | BF | E6 | 42 | 68 | 41 | 99 | 2D | 0F | B0 | 54 | BB | 16 |

E.g., Using AES S-Box:

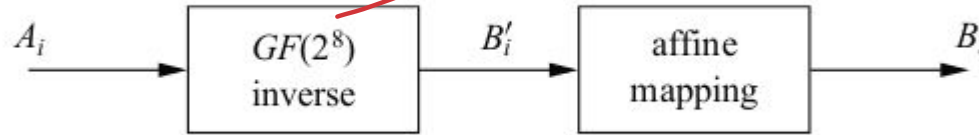
$$S(0xC2) = 0x25$$

# Byte Substitution Layer (3)

**Q.** How the S-Box has been built?

**A.** The S-Box is designed to perform **two operations**:

Multiplication  
inverse of  
galois field



Each  $A_i$  (8 bit) is seen as an element in  $GF(2^8)$ :

$$A_i = 1100\ 0010 \Rightarrow A_i(x) = x^7 + x^6 + x$$

The first step computes the inverse (which provides the non linearity in AES):

$$B'_i(x) = A(x)^{-1}$$

$$P(x) = x^8 + x^4 + x^3 + x + 1$$

such that:  $B'_i(x) \cdot A(x)^{-1} \equiv 1 \pmod{P(x)}$

**AES irreducible polynomial**

# Byte Substitution Layer (4)

E.g.,  $A_i = 1100\ 0010 \Rightarrow A_i(x) = x^7 + x^6 + x$

$$B'_i(x) = A(x)^{-1} = x^5 + x^3 + x^2 + x + 1 \quad \text{(computed with EEA)}$$

The second step computed in the S-Box is an affine mapping (this is done to destroy some algebraic properties that could be exploited by an attacker):

$$\begin{matrix} B_i(x) \\ \begin{pmatrix} b_0 \\ b_1 \\ b_2 \\ b_3 \\ b_4 \\ b_5 \\ b_6 \\ b_7 \end{pmatrix} \end{matrix} \equiv \begin{pmatrix} 1 & 0 & 0 & 0 & 1 & 1 & 1 & 1 \\ 1 & 1 & 0 & 0 & 0 & 1 & 1 & 1 \\ 1 & 1 & 1 & 0 & 0 & 0 & 1 & 1 \\ 1 & 1 & 1 & 1 & 0 & 0 & 0 & 1 \\ 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 1 & 1 \end{pmatrix} \begin{matrix} B'_i(x) \\ \begin{pmatrix} b'_0 \\ b'_1 \\ b'_2 \\ b'_3 \\ b'_4 \\ b'_5 \\ b'_6 \\ b'_7 \end{pmatrix} \end{matrix} + \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \\ 0 \\ 1 \\ 1 \\ 0 \end{pmatrix} \pmod{2}.$$

# Byte Substitution Layer (5)

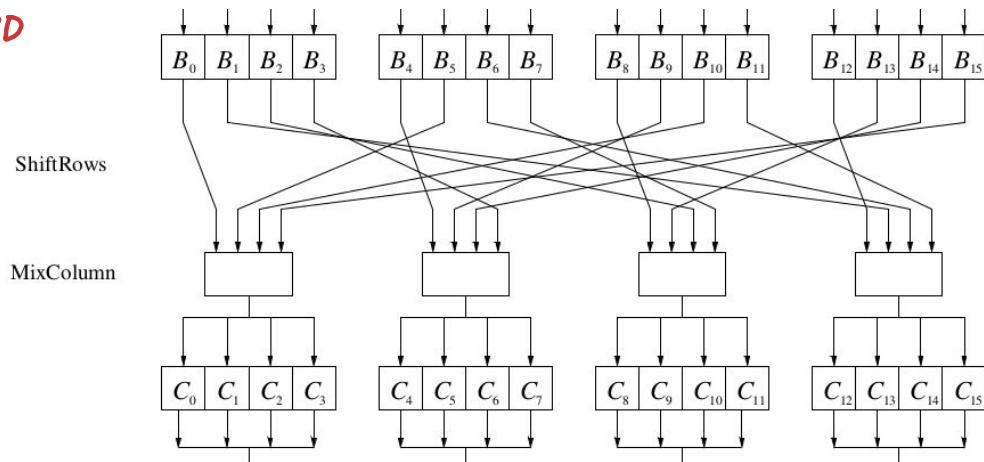
Hence, the S-Box is a precomputation of the output for all the possibly  $A(x)$

|     | $y$ |    |    |    |    |    |    |    |    |    |    |    |    |    |    |    |
|-----|-----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|
|     | 0   | 1  | 2  | 3  | 4  | 5  | 6  | 7  | 8  | 9  | A  | B  | C  | D  | E  | F  |
| 0   | 63  | 7C | 77 | 7B | F2 | 6B | 6F | C5 | 30 | 01 | 67 | 2B | FE | D7 | AB | 76 |
| 1   | CA  | 82 | C9 | 7D | FA | 59 | 47 | F0 | AD | D4 | A2 | AF | 9C | A4 | 72 | C0 |
| 2   | B7  | FD | 93 | 26 | 36 | 3F | F7 | CC | 34 | A5 | E5 | F1 | 71 | D8 | 31 | 15 |
| 3   | 04  | C7 | 23 | C3 | 18 | 96 | 05 | 9A | 07 | 12 | 80 | E2 | EB | 27 | B2 | 75 |
| 4   | 09  | 83 | 2C | 1A | 1B | 6E | 5A | A0 | 52 | 3B | D6 | B3 | 29 | E3 | 2F | 84 |
| 5   | 53  | D1 | 00 | ED | 20 | FC | B1 | 5B | 6A | CB | BE | 39 | 4A | 4C | 58 | CF |
| 6   | D0  | EF | AA | FB | 43 | 4D | 33 | 85 | 45 | F9 | 02 | 7F | 50 | 3C | 9F | A8 |
| 7   | 51  | A3 | 40 | 8F | 92 | 9D | 38 | F5 | BC | B6 | DA | 21 | 10 | FF | F3 | D2 |
| x 8 | CD  | 0C | 13 | EC | 5F | 97 | 44 | 17 | C4 | A7 | 7E | 3D | 64 | 5D | 19 | 73 |
| 9   | 60  | 81 | 4F | DC | 22 | 2A | 90 | 88 | 46 | EE | B8 | 14 | DE | 5E | 0B | DB |
| A   | E0  | 32 | 3A | 0A | 49 | 06 | 24 | 5C | C2 | D3 | AC | 62 | 91 | 95 | E4 | 79 |
| B   | E7  | C8 | 37 | 6D | 8D | D5 | 4E | A9 | 6C | 56 | F4 | EA | 65 | 7A | AE | 08 |
| C   | BA  | 78 | 25 | 2E | 1C | A6 | B4 | C6 | E8 | DD | 74 | 1F | 4B | BD | 8B | 8A |
| D   | 70  | 3E | B5 | 66 | 48 | 03 | F6 | 0E | 61 | 35 | 57 | B9 | 86 | C1 | 1D | 9E |
| E   | E1  | F8 | 98 | 11 | 69 | D9 | 8E | 94 | 9B | 1E | 87 | E9 | CE | 55 | 28 | DF |
| F   | 8C  | A1 | 89 | 0D | BF | E6 | 42 | 68 | 41 | 99 | 2D | 0F | B0 | 54 | BB | 16 |

C code that can  
precompute this  
table.

# Diffusion Layer *2<sup>ND</sup>*

**Diffusion:** given a byte with some bit flips, it will spread the effect on 32 bits from the state.



- provides diffusion over all input state bits
- consists of two sublayers:
  - **ShiftRows Sublayer:** Permutation of the data on a byte level
  - **MixColumn Sublayer:** Matrix operation which combines ("mixes") blocks of four bytes
- performs a linear operation on state matrices A, B, i.e.,
$$\text{DIFF}(A) + \text{DIFF}(B) = \text{DIFF}(A + B)$$



# ShiftRows Sublayer

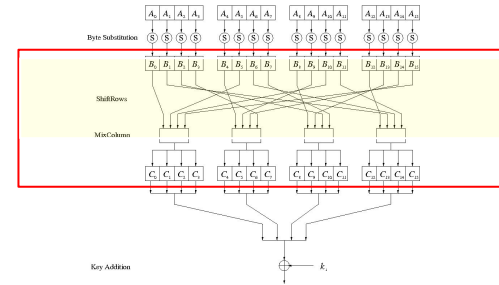
Rows of the state matrix are shifted cyclically:

Input matrix

|       |       |          |          |
|-------|-------|----------|----------|
| $B_0$ | $B_4$ | $B_8$    | $B_{12}$ |
| $B_1$ | $B_5$ | $B_9$    | $B_{13}$ |
| $B_2$ | $B_6$ | $B_{10}$ | $B_{14}$ |
| $B_3$ | $B_7$ | $B_{11}$ | $B_{15}$ |

Output matrix

|          |          |          |          |
|----------|----------|----------|----------|
| $B_0$    | $B_4$    | $B_8$    | $B_{12}$ |
| $B_5$    | $B_9$    | $B_{13}$ | $B_1$    |
| $B_{10}$ | $B_{14}$ | $B_2$    | $B_6$    |
| $B_{15}$ | $B_3$    | $B_7$    | $B_{11}$ |



no shift

← one position left shift

← two positions left shift

← three positions left shift

# MixColumn Sublayer

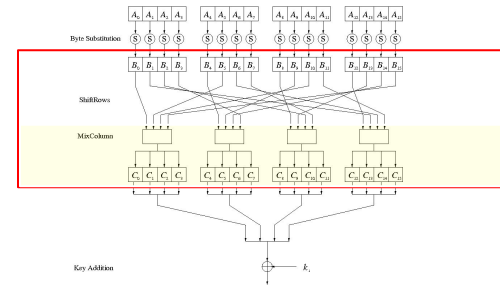
- Linear transformation which mixes each column of the state matrix
- Each 4-byte column is considered as a vector and multiplied by a fixed 4x4 matrix, e.g., the leftmost mix column box is:

$$\begin{pmatrix} C_0 \\ C_1 \\ C_2 \\ C_3 \end{pmatrix} = \begin{pmatrix} 02 & 03 & 01 & 01 \\ 01 & 02 & 03 & 01 \\ 01 & 01 & 02 & 03 \\ 03 & 01 & 01 & 02 \end{pmatrix} \cdot \begin{pmatrix} B_0 \\ B_5 \\ B_{10} \\ B_{15} \end{pmatrix}$$

- where 01, 02 and 03 are given in hexadecimal notation
- each row of the matrix is a shift of the previous row
- All arithmetic is done in the Galois field  $GF(2^8)$ : e.g.,

$$C_0 = \overset{x}{02} \cdot \overset{x+1}{B_0} + \overset{1}{03} \cdot B_5 + \overset{1}{01} \cdot B_{10} + \overset{1}{01} \cdot B_{15}$$

*byte byte*



# MixColumn Sublayer (2)

$$\text{E.g., } C_0 = 02 \cdot B_0 + 03 \cdot B_5 + 01 \cdot B_{10} + 01 \cdot B_{15}$$

$$C_0 = x \cdot B_0 + (x + 1) \cdot B_5 + 1 \cdot B_{10} + 1 \cdot B_{15}$$

Addition and multiplication are done as seen in  $\text{GF}(2^8)$

$$\text{E.g., } B = (25, \dots, 25)$$

$$02 \cdot 25 = x \cdot (x^5 + x^2 + 1)$$

$$= x^6 + x^3 + x,$$

$$03 \cdot 25 = (x + 1) \cdot (x^5 + x^2 + 1)$$

$$= (x^6 + x^3 + x) + (x^5 + x^2 + 1)$$

$$= x^6 + x^5 + x^3 + x^2 + x + 1.$$

No modular reduction with  $P(x)$  is needed since the result has a degree smaller than 8.

# MixColumn Sublayer (3)

Then the addition is, e.g.,:

$$\begin{array}{rcll} 01 \cdot 25 & = & x^5 + & x^2 + 1 \\ 01 \cdot 25 & = & x^5 + & x^2 + 1 \\ 02 \cdot 25 & = & x^6 + & x^3 + x \\ 03 \cdot 25 & = & x^6 + x^5 + x^3 + x^2 + x + 1 \\ \hline C_i & = & x^5 + & x^2 + 1, \end{array}$$

# MixColumn Sublayer (4)

Another way of defining the MixColumn Sublayer is treat each column as four-term polynomial:

$$b(x) = b_3 x^3 + b_2 x^2 + b_1 x + b_0$$

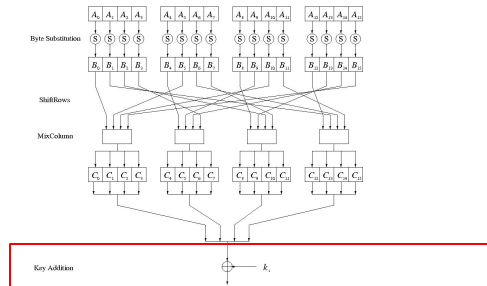
where each coefficient  $b_i$  is in  $\text{GF}(2^8)$  [this is different from coefficient in  $\text{GF}(2)$ !] and multiply it by:

$$a(x) = 3x^3 + x^2 + x + 2 \text{ modulo } x^4 + 1$$

This is the definition given by the standard and since it is a multiplication with a fixed polynomial can be written as a matrix multiplication (previous slide).

# Key Addition Layer

- Inputs:
  - 16-byte state matrix  $C$
  - 16-byte subkey  $k_i$
- Output:  $C \oplus k_i$
- The subkeys are generated in the key schedule



# Key Schedule

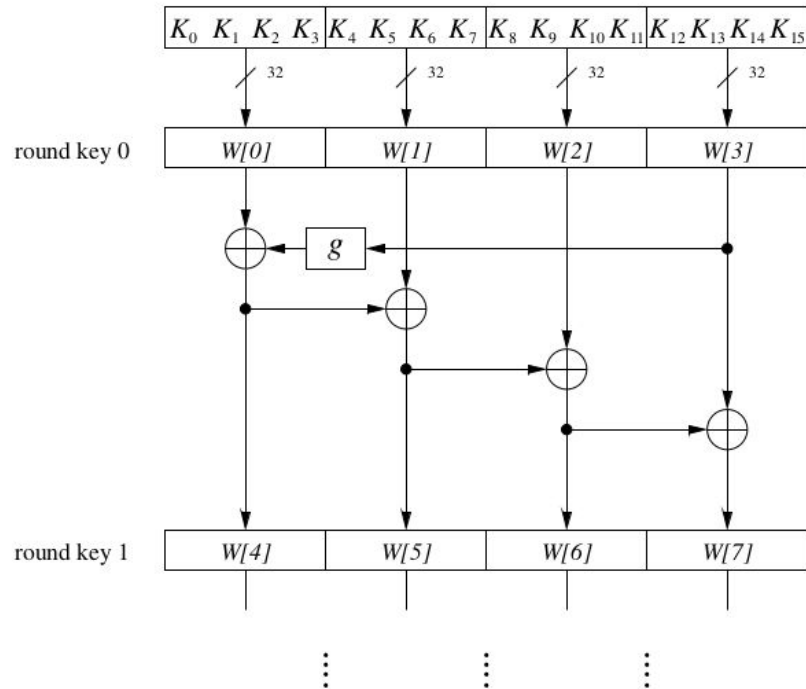
- Subkeys are derived recursively from the original 128/192/256-bit input key
- Each round has 1 subkey, plus 1 subkey at the beginning of AES

| Key length (bits) | Number of subkeys |
|-------------------|-------------------|
| 128               | 11                |
| 192               | 13                |
| 256               | 15                |

- Key whitening: Subkey is used both at the input and output of AES  
 $\Rightarrow \# \text{ subkeys} = \# \text{ rounds} + 1$
- There are different key schedules for the different key sizes

# Key Schedule

## Example: Key schedule for 128-bit key AES

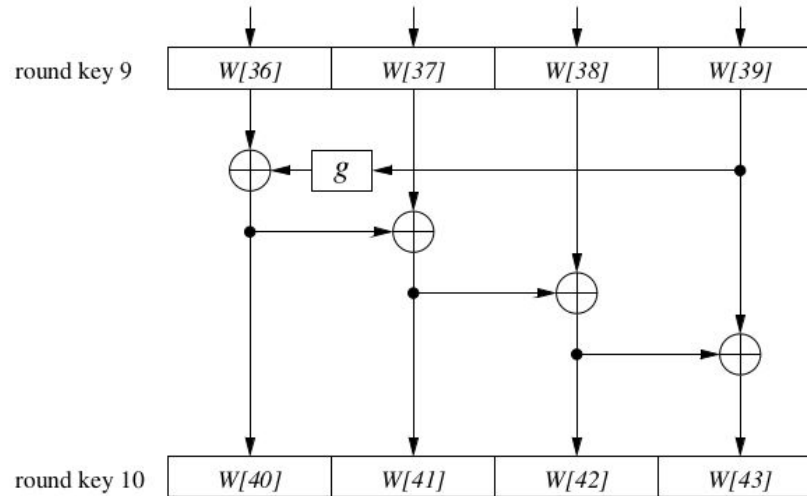


- **Word-oriented: 1 word = 32 bits**
- **11 subkeys are stored in  $W[0] \dots W[3]$ ,  $W[4] \dots W[7]$ , ...,  $W[40] \dots W[43]$**
- **First subkey  $W[0] \dots W[3]$  is the original AES key**



# Key Schedule (2)

Example: Key schedule for 128-bit key AES



# Key Schedule (3)

- Function  $g$  rotates its four input bytes and performs a bitwise S-Box substitution  $\Rightarrow$  nonlinearity
- The round coefficient  $RC$  is only added to the leftmost byte and varies from round to round:

$$RC[1] = x^0 = (00000001)_2$$

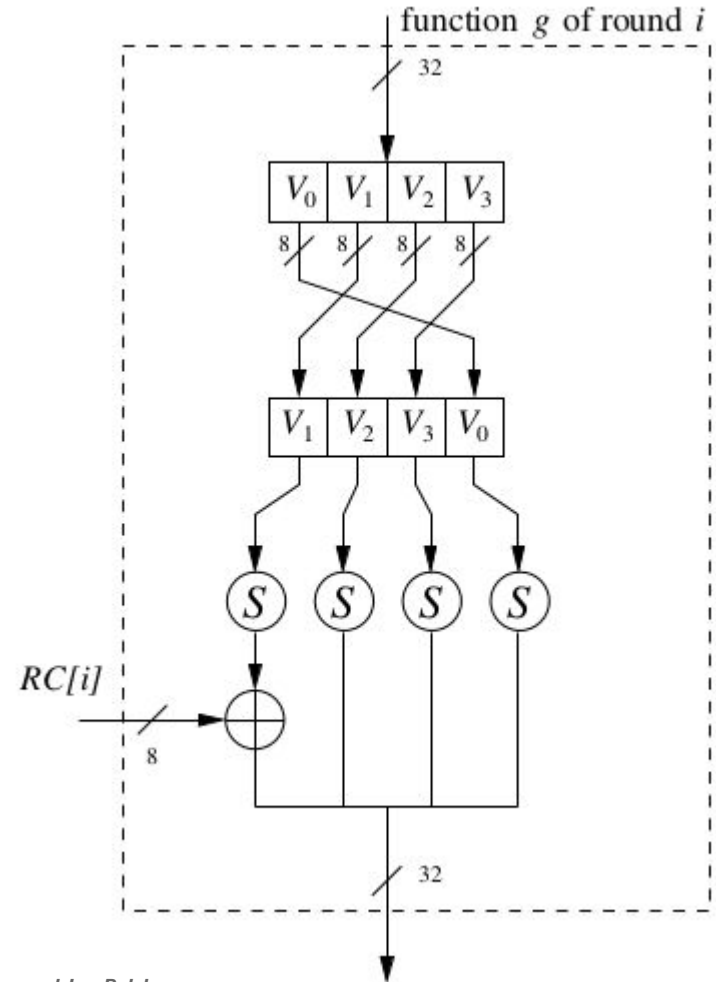
$$RC[2] = x^1 = (00000010)_2$$

$$RC[3] = x^2 = (00000100)_2$$

...

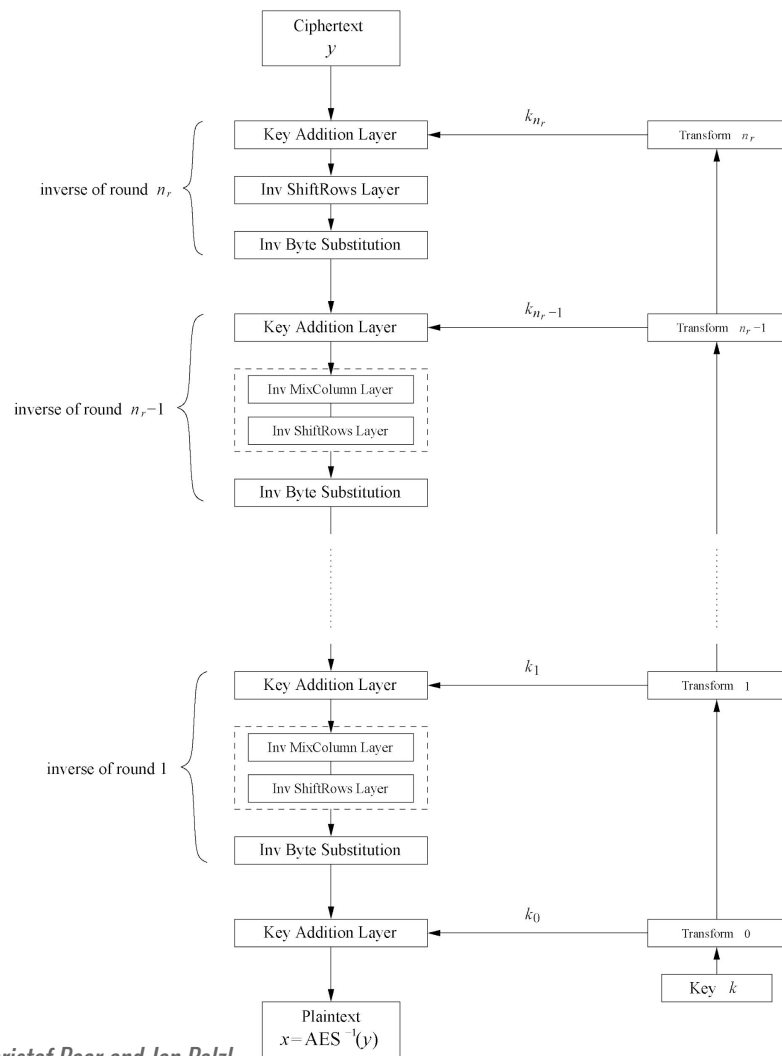
$$RC[10] = x^9 = (00110110)_2$$

- $x^i$  represents an element in a Galois field (again, cf. Chapter 4.3 of Understanding Cryptography)



# Decryption

- AES is not based on a Feistel network  
⇒ All layers must be inverted for decryption:
- MixColumn layer → **Inv MixColumn layer**
- ShiftRows layer → **Inv ShiftRows layer**
- Byte Substitution layer → **Inv Byte Substitution layer**
- Key Addition layer is its own inverse



# Credits

These slides are based on material from:

- Slides of Prof. D'Amore from CNS 2019-2020
- Christof Paar and Jan Pelzl. Understanding Cryptography: A Textbook for Students and Practitioners. Springer. <http://www.crypto-textbook.com/>
- Wikipedia (english version)