

Sapienza University of Rome

Master in Artificial Intelligence and Robotics  
Master in Engineering in Computer Science

## Machine Learning

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## 9. Kernel Methods

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# Summary

- Kernel functions
- Kernelized linear models
- Kernelized SVM - classification
- Kernelized SVM - regression

## References

C. Bishop. Pattern Recognition and Machine Learning. Chap. 6, Sect. 7.1

# Kernels

So far:

Objects represented as fixed-length feature-vectors  $\mathbf{x} \in \mathbb{R}^M$  or  $\phi(\mathbf{x})$ .

Issue:

what about objects with variable length or infinite dimensions?

Examples:

- strings
- trees
- image features
- time-series
- ...

# Kernels

Approach:

use a similarity measure  $k(\mathbf{x}, \mathbf{x}') \geq 0$  between the instances  $\mathbf{x}, \mathbf{x}'$ .  
 $k(\mathbf{x}, \mathbf{x}')$  is called a kernel function.

Note: If we have  $\phi(\mathbf{x})$  a possible choice is  $k(\mathbf{x}, \mathbf{x}') = \phi(\mathbf{x})^T \phi(\mathbf{x}')$ .

# Kernels

## Definition

*Kernel function*: a real-valued function  $k(\mathbf{x}, \mathbf{x}') \in \mathbb{R}$ , for  $\mathbf{x}, \mathbf{x}' \in \mathcal{X}$ , where  $\mathcal{X}$  is some abstract space.

Typically  $k$  is:

- symmetric:  $k(\mathbf{x}, \mathbf{x}') = k(\mathbf{x}', \mathbf{x})$
- non-negative:  $k(\mathbf{x}, \mathbf{x}') \geq 0$ .

Note: Not strictly required!

# Input normalization

Input data in the dataset  $D$  must be normalized in order for the kernel to be a *similarity measure*.

Several types of normalizations:

- min-max  $\bar{x} = \frac{x - \min}{\max - \min}$   
 $\min, \max$ : minimum and maximum input values in  $D$
- normalization (standardization)  $\bar{x} = \frac{x - \mu}{\sigma}$   
 $\mu$  mean and  $\sigma$  standard deviation of input values in  $D$
- unit vector  $\bar{x} = \frac{x}{\|x\|}$

In the following, we assume the use of normalized input data.

## Kernel families

### Linear

$$k(\mathbf{x}, \mathbf{x}') = \mathbf{x}^T \mathbf{x}'$$

### Polynomial

$$k(\mathbf{x}, \mathbf{x}') = (\beta \mathbf{x}^T \mathbf{x}' + \gamma)^d, \quad d \in \{2, 3, \dots\}$$

### Radial Basis Function (RBF)

$$k(\mathbf{x}, \mathbf{x}') = \exp(-\beta |\mathbf{x} - \mathbf{x}'|^2)$$

### Sigmoid

$$k(\mathbf{x}, \mathbf{x}') = \tanh(\beta \mathbf{x}^T \mathbf{x}' + \gamma)$$

## Kernelized linear models

Consider a linear model  $y(\mathbf{x}; \mathbf{w}) = \mathbf{w}^T \mathbf{x}$  with dataset  $D = \{(\mathbf{x}_n, t_n)_{n=1}^N\}$

Minimize  $J(\mathbf{w}) = (\mathbf{t} - \mathbf{X}\mathbf{w})^T (\mathbf{t} - \mathbf{X}\mathbf{w}) + \lambda \|\mathbf{w}\|^2$

*N input instances*  $\mathbf{X} = \begin{bmatrix} \mathbf{x}_1^T \\ \vdots \\ \mathbf{x}_N^T \end{bmatrix}$  design matrix,  $\mathbf{t} = \begin{bmatrix} t_1 \\ \vdots \\ t_N \end{bmatrix}$  output vector

Optimal solution

$$\hat{\mathbf{w}} = (\mathbf{X}^T \mathbf{X} + \lambda I_N)^{-1} \mathbf{X}^T \mathbf{t} = \mathbf{X}^T (\mathbf{X} \mathbf{X}^T + \lambda I_N)^{-1} \mathbf{t},$$

with  $I_N$  the  $N \times N$  identity matrix.

## Kernelized linear models

Let  $\alpha = (\mathbf{X} \mathbf{X}^T + \lambda I_N)^{-1} \mathbf{t}$ ,

then  $\hat{\mathbf{w}} = \mathbf{X}^T \alpha = \sum_{n=1}^N \alpha_n \mathbf{x}_n$ .

Hence we have  $y(\mathbf{x}; \hat{\mathbf{w}}) = \hat{\mathbf{w}}^T \mathbf{x} = \sum_{n=1}^N \alpha_n \mathbf{x}_n^T \mathbf{x}$ .

If we consider a linear kernel  $k(\mathbf{x}, \mathbf{x}') = \mathbf{x}^T \mathbf{x}'$ , we can rewrite the model as

*Linear combination of input instances*

$$y(\mathbf{x}; \hat{\mathbf{w}}) = \sum_{n=1}^N \alpha_n k(\mathbf{x}_n, \mathbf{x})$$

with

$\alpha = (K + \lambda I_N)^{-1} \mathbf{t}$ , and  $K = \mathbf{X} \mathbf{X}^T$  Gram matrix

*Input data for itself.*

## Kernelized linear models

Linear model with linear kernel  $k(\mathbf{x}, \mathbf{x}') = \mathbf{x}^T \mathbf{x}'$

$$y(\mathbf{x}; \boldsymbol{\alpha}) = \sum_{n=1}^N \alpha_n \mathbf{x}_n^T \mathbf{x}$$

Solution

$$\boldsymbol{\alpha} = (K + \lambda I_N)^{-1} \mathbf{t}$$

Gram matrix

$$K = \begin{bmatrix} \mathbf{x}_1^T \mathbf{x}_1 & \cdots & \mathbf{x}_1^T \mathbf{x}_N \\ \vdots & \ddots & \vdots \\ \mathbf{x}_N^T \mathbf{x}_1 & \cdots & \mathbf{x}_N^T \mathbf{x}_N \end{bmatrix}$$

## Kernelized linear models

Linear model with any kernel  $k$

$$y(\mathbf{x}; \boldsymbol{\alpha}) = \sum_{n=1}^N \alpha_n k(\mathbf{x}_n, \mathbf{x})$$

Solution

$$\boldsymbol{\alpha} = (K + \lambda I_N)^{-1} \mathbf{t}$$

Gram matrix

$$K = \begin{bmatrix} k(\mathbf{x}_1, \mathbf{x}_1) & \cdots & k(\mathbf{x}_1, \mathbf{x}_N) \\ \vdots & \ddots & \vdots \\ k(\mathbf{x}_N, \mathbf{x}_1) & \cdots & k(\mathbf{x}_N, \mathbf{x}_N) \end{bmatrix}$$

# Kernel trick

## Kernel trick or kernel substitution

If input vector  $\mathbf{x}$  appears in an algorithm only in the form of an inner product  $\mathbf{x}^T \mathbf{x}'$ , replace the inner product with some kernel  $k(\mathbf{x}, \mathbf{x}')$ .

- Can be applied to any  $\mathbf{x}$  (even infinite size)
- No need to know  $\phi(\mathbf{x})$
- Directly extend many well-known algorithms

*function that maps  
input space in  
feature space (for  
action instance).*

## Kernelized SVM - classification

In SVM, solution has the form:

$$\hat{\mathbf{w}} = \sum_{n=1}^N \alpha_n \mathbf{x}_n$$

Linear model (with linear kernel)

$$y(\mathbf{x}; \alpha) = \text{sign} \left( w_0 + \sum_{n=1}^N \alpha_n \mathbf{x}_n^T \mathbf{x} \right)$$

Kernel trick

$$y(\mathbf{x}; \alpha) = \text{sign} \left( w_0 + \sum_{n=1}^N \alpha_n k(\mathbf{x}_n, \mathbf{x}) \right)$$

Note:  $w_0$  also estimated from  $\alpha$

## Kernelized SVM - classification

Lagrangian problem for kernelized SVM classification

$$\tilde{L}(\mathbf{a}) = \sum_{n=1}^N a_n - \frac{1}{2} \sum_{n=1}^N \sum_{m=1}^N a_n a_m t_n t_m k(\mathbf{x}_n, \mathbf{x}_m)$$

**Solution**

$$a_n = \dots$$

$$w_0 = \frac{1}{|SV|} \sum_{\mathbf{x}_i \in SV} \left( t_i - \sum_{\mathbf{x}_j \in S} a_j t_j k(\mathbf{x}_i, \mathbf{x}_j) \right)$$

## Kernelized linear regression

Linear model for regression  $y = \mathbf{w}^T \mathbf{x}$  and data set  $D = \{(\mathbf{x}_n, t_n)_{n=1}^N\}$

Minimize the regularized loss function

$$J(\mathbf{w}) = \sum_{n=1}^N E(y_n, t_n) + \lambda \|\mathbf{w}\|^2,$$

where  $y_n = \mathbf{w}^T \mathbf{x}_n$ .



## Kernelized linear regression

Consider  $E(y_n, t_n) = (y_n - t_n)^2$ : i.e., regularized linear regression.

### Solution

$$\hat{\mathbf{w}} = (\mathbf{X}^T \mathbf{X} + \lambda I_N)^{-1} \mathbf{X}^T \mathbf{t} = \mathbf{X}^T \boldsymbol{\alpha}$$

$$\boldsymbol{\alpha} = (\mathbf{X} \mathbf{X}^T + \lambda I_N)^{-1} \mathbf{t}$$

Predictions are made using:

$$y(\mathbf{x}; \hat{\mathbf{w}}) = \sum_{n=1}^N \alpha_n \mathbf{x}_n^T \mathbf{x}.$$

## Kernelized linear regression

Apply the kernel trick:

$$y(\mathbf{x}; \hat{\mathbf{w}}) = \sum_{n=1}^N \alpha_n k(\mathbf{x}_n, \mathbf{x})$$

$$\boldsymbol{\alpha} = (\mathbf{K} + \lambda I_N)^{-1} \mathbf{t}$$

Issue: computation of  $\mathbf{K}$  requires  $|D|^2$  operations and  $\mathbf{K}$  is not sparse.

# Kernelized SVM - regression

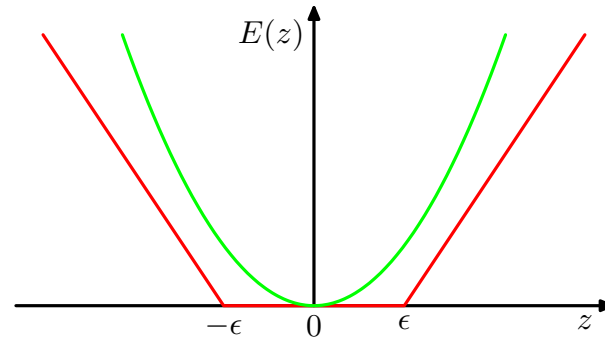
Consider

$$J(\mathbf{w}) = C \sum_{n=1}^N E_{\epsilon}(y_n, t_n) + \frac{1}{2} \|\mathbf{w}\|^2,$$

with  $C$  inverse of  $\lambda$  and an  $\epsilon$ -insensitive error function:

$$E_{\epsilon}(y, t) = \begin{cases} 0 & \text{if } |y - t| < \epsilon \\ |y - t| - \epsilon & \text{otherwise} \end{cases}.$$

*Make minimal noise.*



Not differentiable  $\rightarrow$  difficult to solve.

# Kernelized SVM - regression

Introduce *slack variables*  $\xi_n^+, \xi_n^- \geq 0$ :

$$\begin{aligned} t_n &\leq y_n + \epsilon + \xi_n^+ \\ t_n &\geq y_n - \epsilon - \xi_n^- \end{aligned}$$

*outside the tube.*

Points inside the  $\epsilon$ -tube  $y_n - \epsilon \leq t_n \leq y_n + \epsilon \Rightarrow \xi_n = 0$

$$\xi_n^+ > 0 \Rightarrow t_n > y_n + \epsilon$$

$$\xi_n^- > 0 \Rightarrow t_n < y_n - \epsilon$$

with  $y_n = y(\mathbf{x}_n; \mathbf{w})$

*We are looking for the function that minimizes the error.*

# Kernelized SVM - regression

Loss function can be rewritten as:

$$J(\mathbf{w}) = C \sum_{n=1}^N (\xi_n^+ + \xi_n^-) + \frac{1}{2} \|\mathbf{w}\|^2,$$

*minimize*

subject to the constraints:

$$\begin{aligned} t_n &\leq y(\mathbf{x}_n; \mathbf{w}) + \epsilon + \xi_n^+ \\ t_n &\geq y(\mathbf{x}_n; \mathbf{w}) - \epsilon - \xi_n^- \\ \xi_n^+ &\geq 0 \\ \xi_n^- &\geq 0 \end{aligned}$$

This is a standard quadratic program (QP), can be "easily" solved.

# Kernelized SVM - regression

Lagrangian problem

$$\tilde{L}(\mathbf{a}, \mathbf{a}') = \dots \sum_{n=1}^N \sum_{m=1}^N a_n a_m \dots k(\mathbf{x}_n, \mathbf{x}_m) \dots$$

*maximize*      *Lagrangian multipliers*

from which we compute  $\hat{a}_n, \hat{a}'_m$  (sparse values, most of them are zero) and

$$\hat{w}_0 = t_n - \epsilon - \sum_{m=1}^N (\hat{a}_m - \hat{a}'_m) k(\mathbf{x}_n, \mathbf{x}_m)$$

for some data point  $n$  such that  $0 < a_n < C$

**Prediction**

$$y(\mathbf{x}) = \sum_{n=1}^N (\hat{a}_n - \hat{a}'_n) k(\mathbf{x}, \mathbf{x}_n) + \hat{w}_0$$

*only on the points outside the tube.*

# Kernelized SVM - regression

From Karush-Kuhn-Tucker (KKT) condition (see Bishop Sect. 7.1.4)

Support vectors contribute to predictions

$$\hat{a}_n > 0 \Rightarrow \epsilon + \xi_n + y_n - t_n = 0$$

data point lies on or above upper boundary of the  $\epsilon$ -tube

Points inside the tube have  $a, a' = 0$ ,  
outside the tube have  $a$  or  $a' \neq 0$

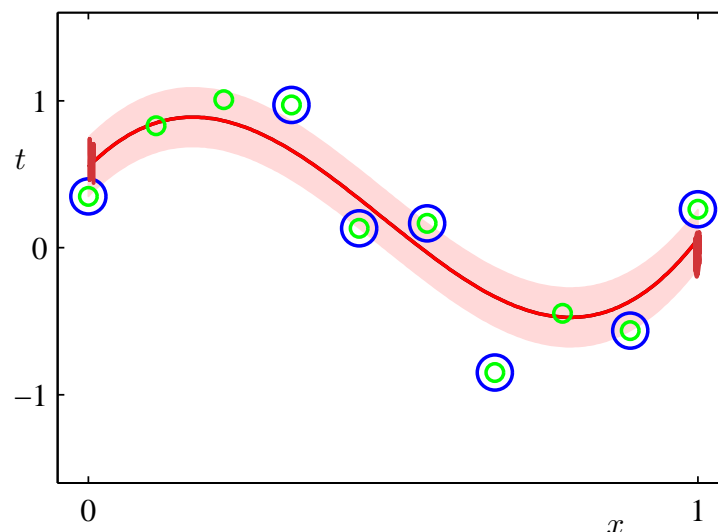
$$\hat{a}'_n > 0 \Rightarrow \epsilon + \xi_n - y_n + t_n = 0$$

data point lies on or below lower boundary of the  $\epsilon$ -tube

All other data points inside the  $\epsilon$ -tube have  $\hat{a}_n = 0$  and  $\hat{a}'_n = 0$  and thus  
do not contribute to prediction.

# Kernelized SVM - regression

Example: support vectors and  $\epsilon$  insensitive tube



# Summary

- Kernel methods overcome difficulties in defining non-linear models
- Kernelized SVM is one of the most effective ML method for classification and regression
- Still requires model selection and hyper-parameters tuning