

# LTL Model Checking

TS  $\gamma$   
 state & trans  
 forms a graph

$\models$

LTL

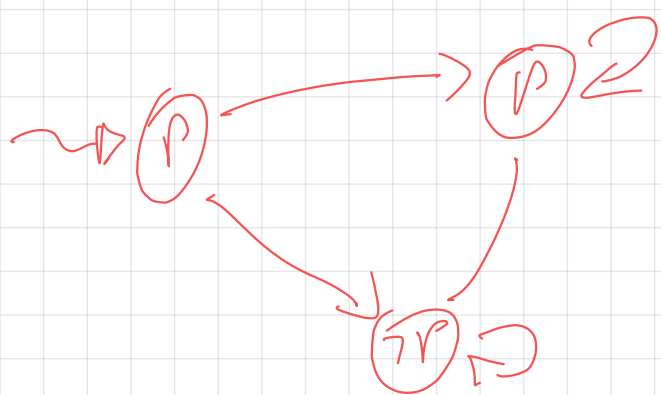
$\phi$

interpreted over  
 infinite traces

$\gamma$

$\Rightarrow$

$\{t \mid t \text{ is an infinite trace of } \gamma\}$



$\left\{ \begin{array}{l} p p p p p \dots \\ \dots p p \dots p \neg p \neg p \neg p \dots \end{array} \right.$   
 and trace

$$L(\gamma) = \{t \mid t \text{ is a state trace of } \gamma\}$$

$$L(\phi) = \{t \mid t \models \phi\}$$

$$\gamma \models \phi$$

it means that:

$$L(\gamma) \subseteq L(\phi)$$

$\forall t \text{ of } \gamma \text{ it is the case that } t \models \phi$

Show that  $L(\gamma)$  and  $L(\phi)$  are  
regular languages (NFA / DFA / DFA)

$$\gamma \rightsquigarrow A_\gamma$$

$$\phi \rightsquigarrow A_\phi$$

$$L(\gamma) = L(A_\gamma)$$

$$L(\phi) = L(A_\phi)$$

$$L(A_\gamma) \subseteq L(A_\phi)$$

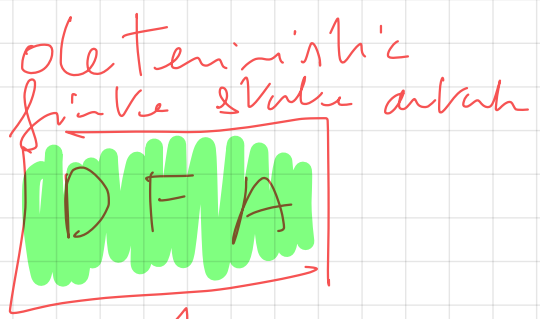
suppose regular  
...

$$\forall t \in L(A_\gamma) \Rightarrow t \in L(A_\phi)$$

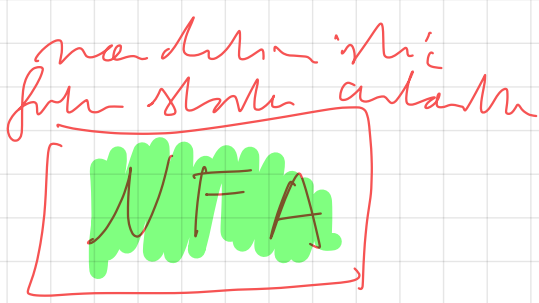
$$\neg \exists t \in L(A_\gamma) \wedge t \notin L(A_\phi) \quad \neg (\neg A \vee B) \quad A \Rightarrow B$$

$$\neg \exists t \in L(A_\gamma \times \overline{A_\phi})$$

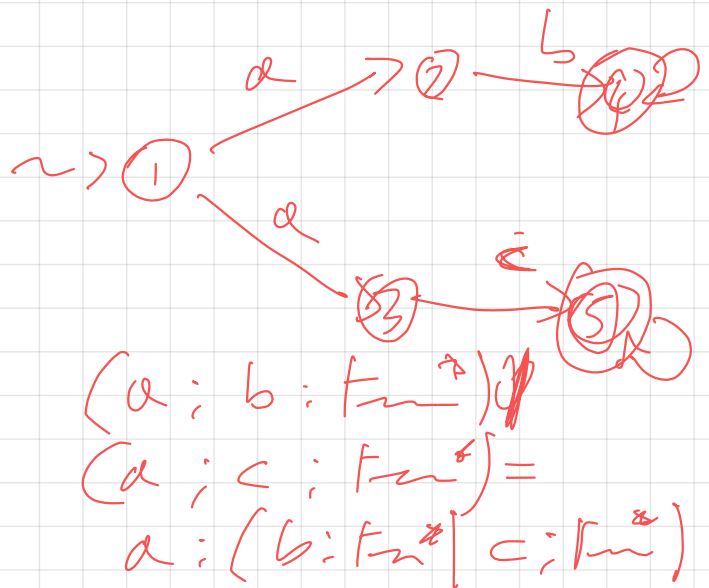
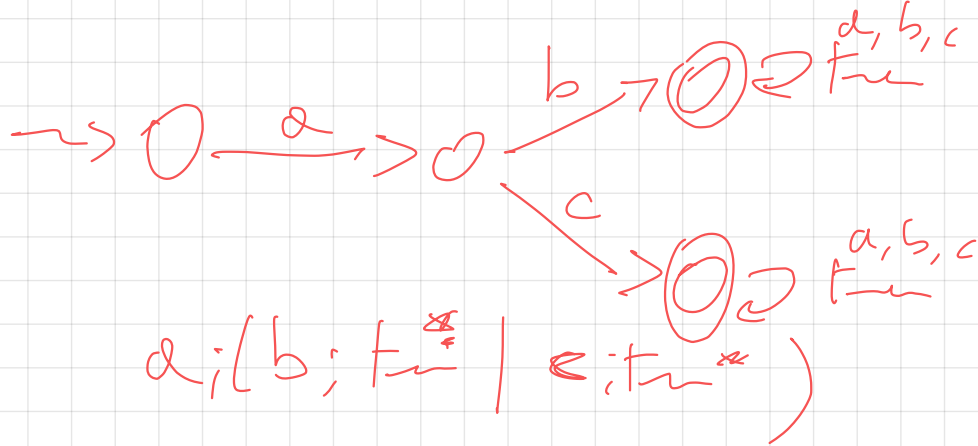
$\uparrow$  complement of  $A_\phi$   
 $\uparrow$  not



implementable machines



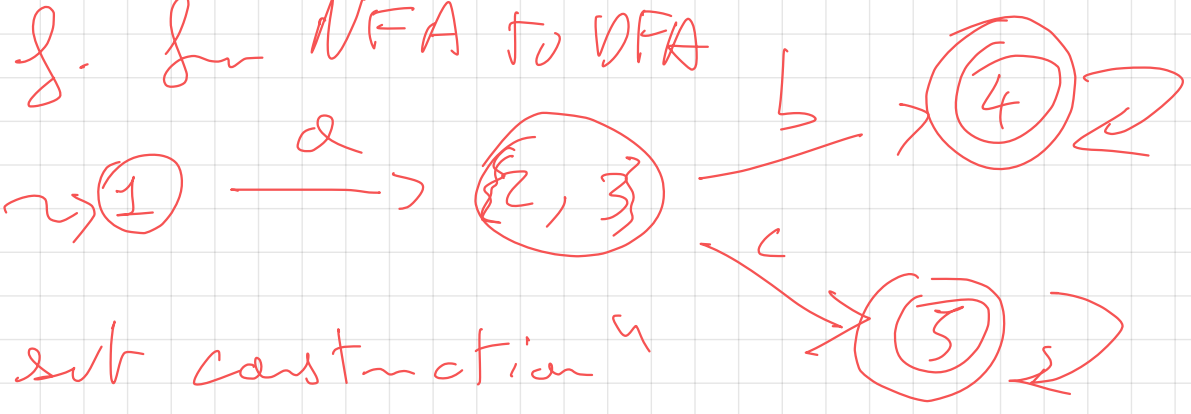
NOT implementable!



Th:  $\forall$  NFA  $\exists$  DFA st

$$L(NFA) = L(DFA)!$$

transf. for NFA to DFA



exp

"subset construction"

but good  
(free comp. part of NFA)  
in practice

DFA  $A_{d1}$

DFA  $A_{d2}$

$\Rightarrow A_{d1} \wedge A_{d1}$  poly

$A_{d1} \vee A_{d2}$  poly

$\neg A_{d1}$  complete poly

closed  
under  
boolean  
operation

NFA  $A_{n1}$

$A_{n1} \wedge A_{n2}$  poly

NFA

$A_{n2}$

$\Rightarrow$

$A_{n1} \vee A_{n2}$  poly

~~$A_{n1}$~~  no complete poly

closed  
under  
boolean  
operation

exp

$$A_{n1} \rightsquigarrow A_{d1} \rightsquigarrow \overline{A_{d1}}$$
$$L(A_{n1}) = \sum_{\text{all paths}} L(\overline{A_{d1}})$$

all paths

Th: NFA  $\rightsquigarrow$  DFA very important

NFA can be checked for  
emptiness / non-emptiness

check iff  $L(A_n) \neq \emptyset$  <sup>non-emptiness</sup>  
 $= \emptyset$  <sup>emptiness</sup>  $\leq [PCL]$   
NLOGSPACE

requires reachability on graph (the graph of the NFA)

checks for reachability  $[n \in \mathbb{Z} \cdot \text{Find } v \leftrightarrow z]$

$$L(\gamma) \subseteq L(\phi)$$

$$L(A_\gamma) \subseteq L(A_\phi) \quad \forall t. t \in L(A_\gamma) \Rightarrow t \in L(A_\phi)$$

$$L(A_\gamma) \cap \overline{L(A_\phi)} = \emptyset$$

$$\nexists t. t \in L(A_\gamma) \wedge t \notin L(A_\phi)$$

$$L(A_\gamma \wedge \overline{A_\phi}) = \emptyset$$

$\uparrow$  poly       $\left( \begin{array}{l} \text{exp} \\ \& \text{poly} \end{array} \right)$

But unfortunately we cannot use  
reg for lang / Automata!

Because our traces are infinite

But we can use  $\omega$ -regular languages

• Reg Lang  $L$ :  $L \subseteq \Sigma^*$

•  $\omega$ -reg Lang  $L$ :  $L \subseteq \Sigma^\omega$  ← is the first in finiteness!

• Reg Lang  $L$ :  $L = L(A)$  ← DFA/NFA

•  $\omega$ -reg Lang  $L$ :  $L = L(A)$  Non-deterministic Büchi automaton  
UBA

$\downarrow$  alphabet    $\downarrow$  finite set of states    $\downarrow$  initial state    $\downarrow$  transition rule/fun.

$$A = (\Sigma, S, S_0, \tau, F)$$

-  $\Sigma$  alphabet (is prop. independent for CTL)

-  $S$  finite set of states

-  $S_0$  finite set of initial stn  $S_0 \subseteq S$

-  $F$  finite set of ~~final~~ <sup>accepting</sup> states  $F \subseteq S$

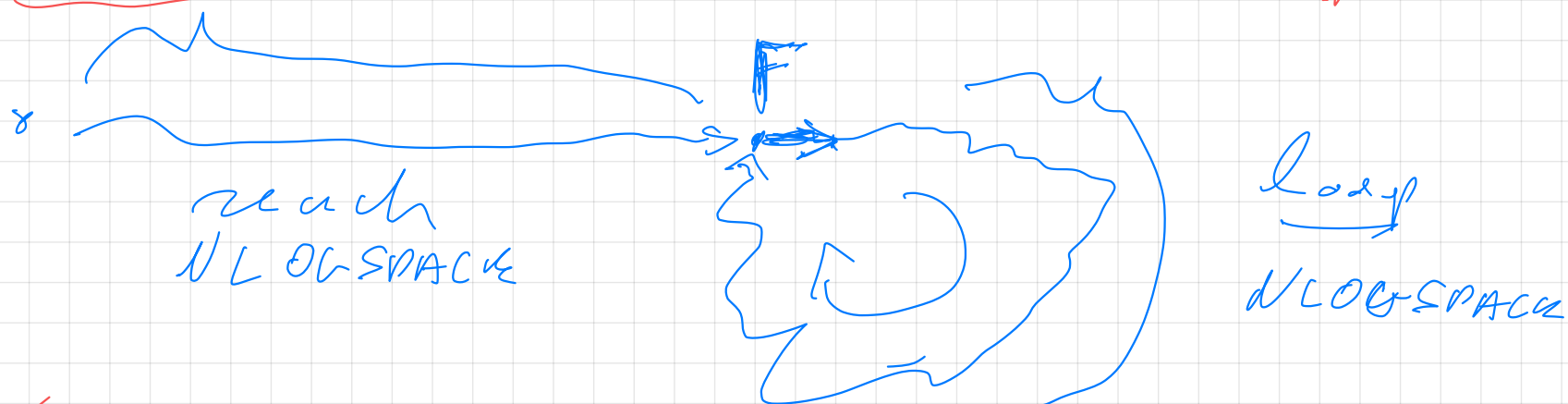
-  $\tau: S \times A \rightarrow \mathbb{Z}^S$  or  $S \times A \times S$   
↑  
return many states

Accepting config:

•  $t$  reaches  $s_f \in F$  as NFA

• and  
•  $t$  loops over  $s_f$ .

"go to  $F$  infinitely often"



~~Th NBA  $\sim$  DBA~~

it can be shown that DBA are less expressive than NBA.

NBA are closed for  $\wedge$ ,  $\vee$  but not for  $\neg$

Th: NBA  $\xrightarrow{\text{exp}}$  DBA

extremely bad alg.  $\uparrow$  parity

in practice too difficult to scale

safer construction: very difficult

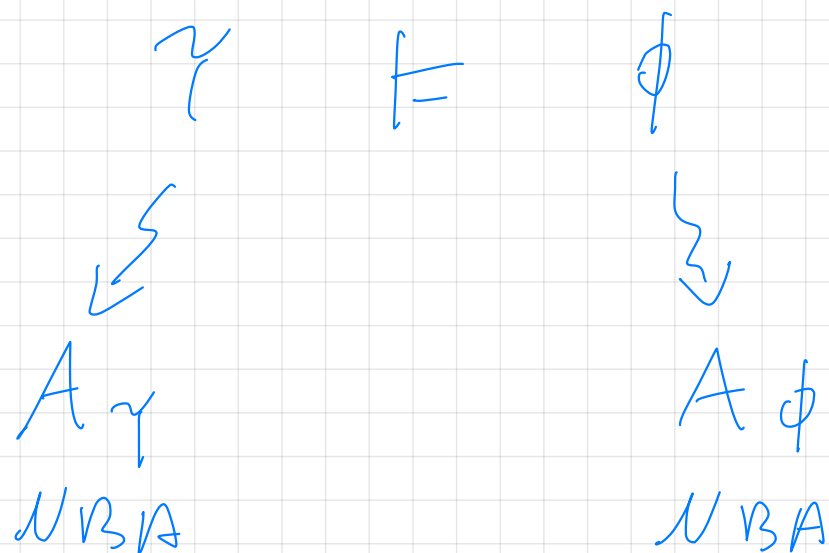
Checking for emptiness of Buchi Automata is easy

"fair reachability"  
"find  $F$  the end loop to it" NLOGSPACE easy!

$$\exists X \wedge Y. ((F \wedge \neg X) \vee \neg Y)$$

m-calc formula to check for "fair reachability"





$$\mathcal{L}(A\gamma) \leq \mathcal{L}(A\phi)$$

$$\mathcal{L}(A\gamma \wedge \boxed{A\phi}) \stackrel{\text{check}}{=} \emptyset$$

★ this is too different to implement in a scalable way

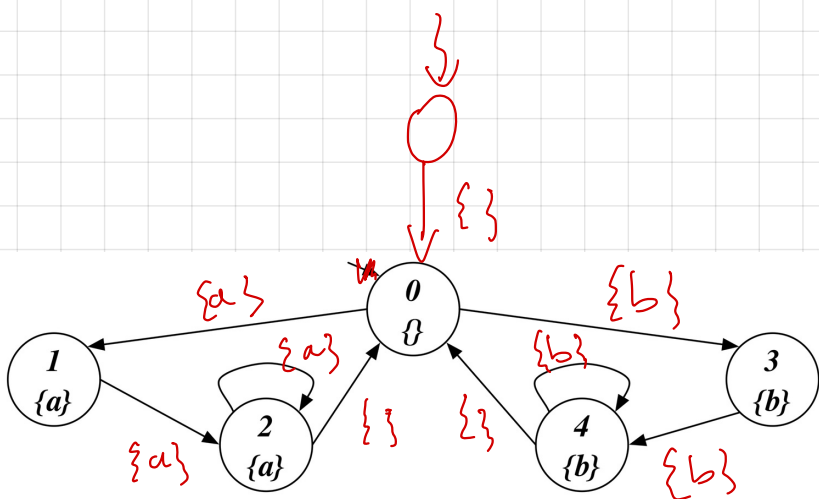
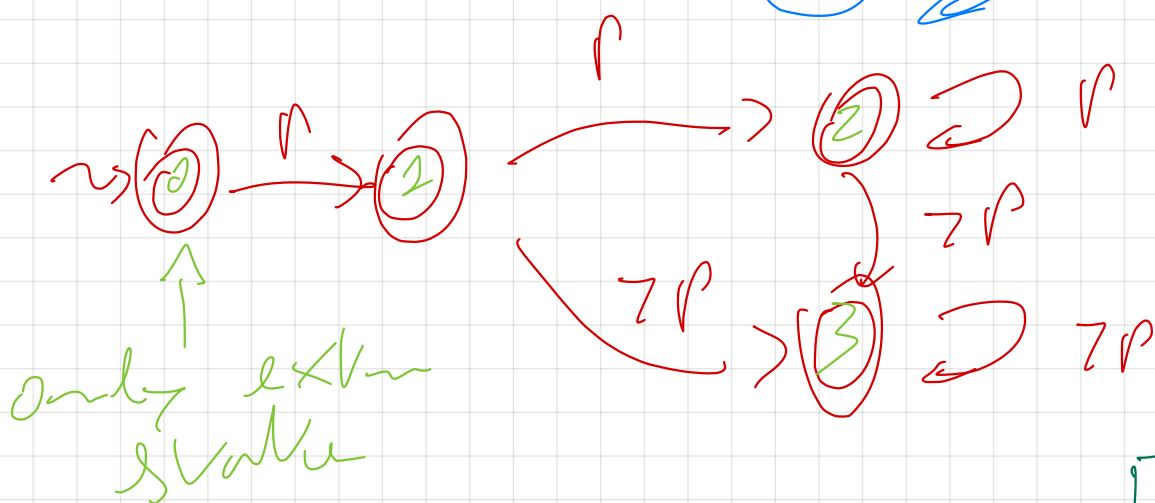
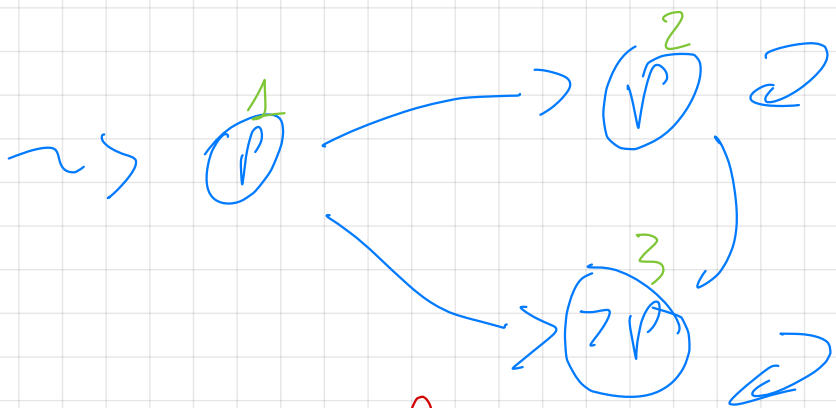
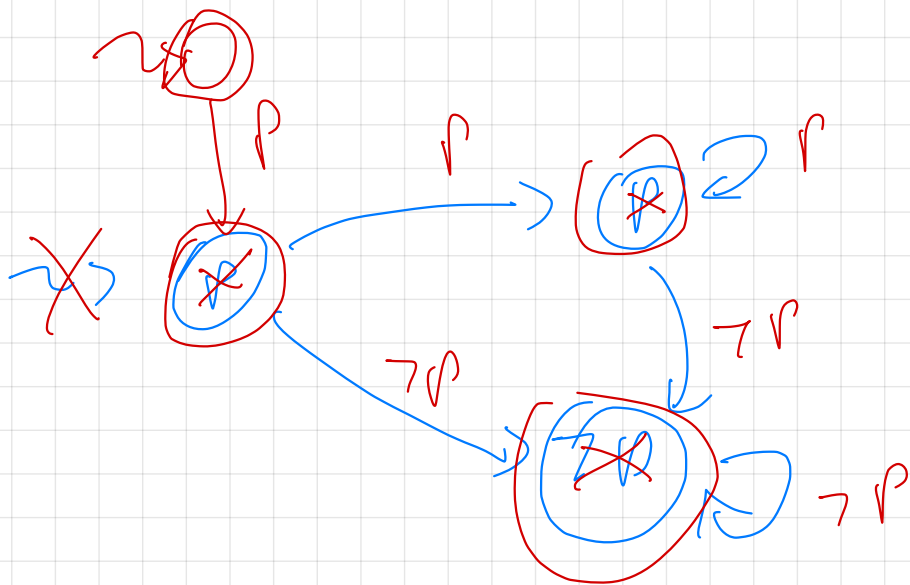
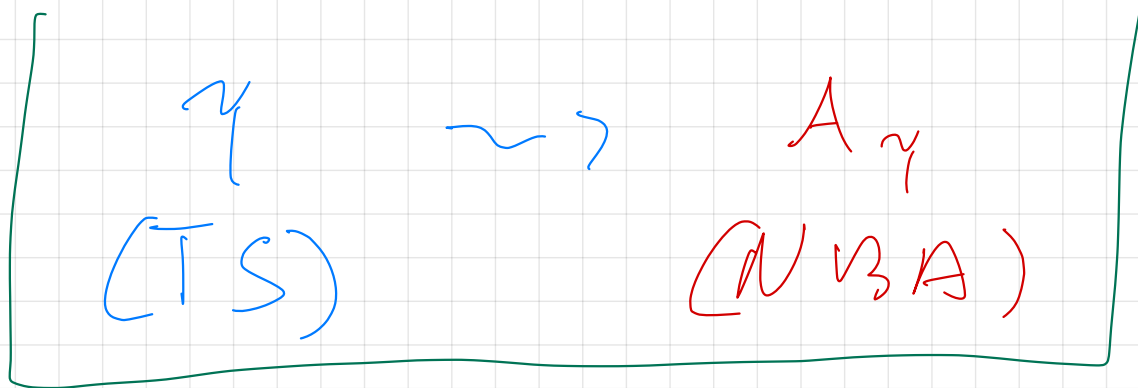
$$\begin{array}{ccc} A\phi & \rightsquigarrow & \overline{A\phi} \\ \uparrow & & \text{too difficult} \\ \phi & \rightsquigarrow & \neg\phi \\ & \uparrow & \text{cannot!} \end{array}$$

$$A\neg\phi = \overline{A\phi}$$

$$\mathcal{L}(\boxed{A\gamma} \wedge \boxed{A\neg\phi}) \stackrel{\text{check}}{=} \emptyset$$

↑ not    ↑ not



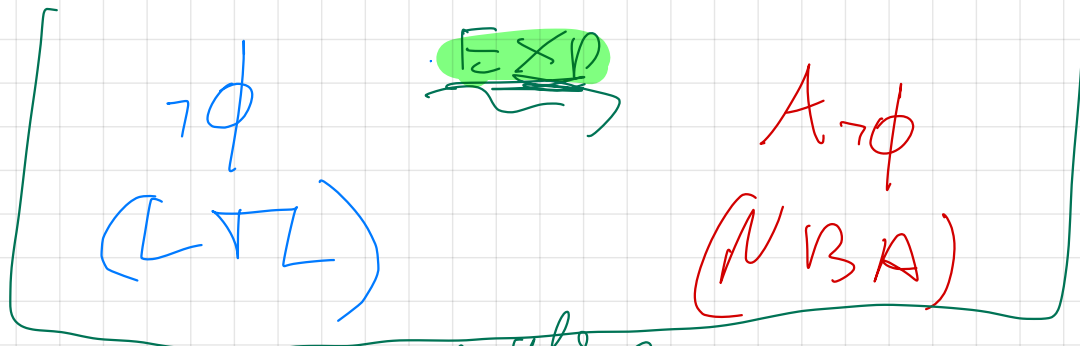


To get  $A_\gamma$  for  $\gamma$

- add extra dummy initial state
- put labelling on state to incoming transition
- Consider as ~~fixed~~ accepting all states.

Th:  $|A_\gamma| \approx |\gamma|$



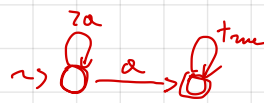


There are nice (online) tools to get the NBA from an LTL formula

• SPOT

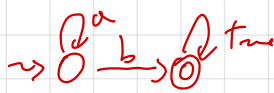
• LTL2BA

$\Diamond a$



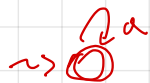
$\neg a \neg a \dots \neg a \ a \ \text{true} \dots$

$a \ U \ b$

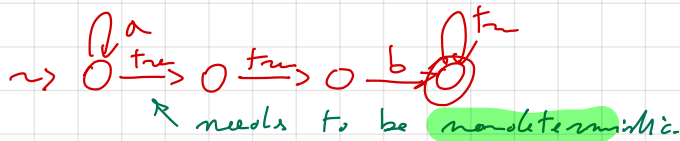


$a \ a \dots a \ \neg a \ \text{true} \dots$

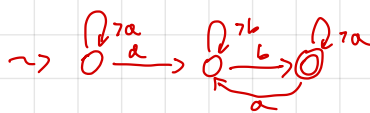
$\Box a$



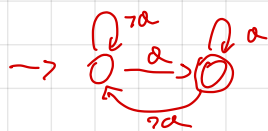
$| a \ U \ o \ o \ b$



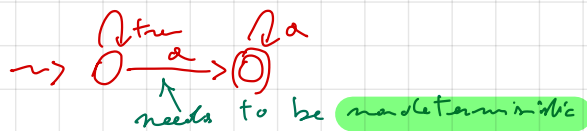
$\Box(a \supset \Box b)$



$\Box \Diamond a$



$| \Diamond \Box a$



Some simpl  
automata

$$\gamma \rightsquigarrow A_\gamma$$

$$\neg\phi \rightsquigarrow A_{\neg\phi}$$

Product

$$A_\gamma \wedge A_{\neg\phi}$$

$$\underline{A_\gamma} \times A_{\neg\phi}$$

every state  
is accepting!

$$A_\gamma = (\Sigma, S_\gamma, S_{0\gamma}, t_{2\gamma}, F_\gamma)$$

$$A_{\neg\phi} = (\Sigma, S_{\neg\phi}, S_{0\neg\phi}, t_{2\neg\phi}, F_{\neg\phi})$$

$$A_\gamma \times A_{\neg\phi} = (\Sigma, S, S_0, t_2, F)$$

•  $\Sigma$  is the alphabet of both  $A_\gamma$  and  $A_{\neg\phi}$

•  $S = S_\gamma \times S_{\neg\phi}$   $(s_\gamma, s_{\neg\phi}) \in S \Rightarrow s_\gamma \in S_\gamma \text{ and } s_{\neg\phi} \in S_{\neg\phi}$

•  $S_0 = S_{0\gamma} \times S_{0\neg\phi}$  both automata start from initial state

•  $F = \underline{S_\gamma} \times F_{\neg\phi}$   
 $\uparrow$   
 $S_\gamma!$   $\nwarrow$  check only  $A_{\neg\phi}$  f.i.l.

•  $t_2: S \times \Sigma \rightarrow 2^S$

$$t_2((s_\gamma, s_{\neg\phi}), a) = \{(s'_\gamma, s'_{\neg\phi}) \mid s'_\gamma \in t_{2\gamma}(s_\gamma, a) \wedge s'_{\neg\phi} \in t_{2\neg\phi}(s_{\neg\phi}, a)\}$$

Intuitively:

run the two automata simultaneously

NBA is not empty iff

(one of its) child state belongs to  
the extension of the following  
u-calc formula:

fair reachability

$$\varphi: \exists X. u \forall Y. (F \wedge \langle \text{next} \rangle X \vee \langle \text{next} \rangle Y)$$

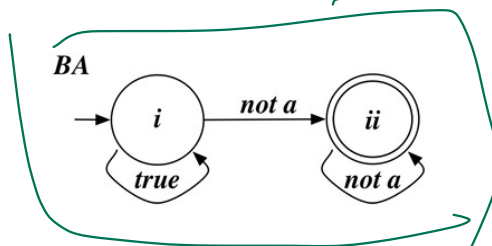
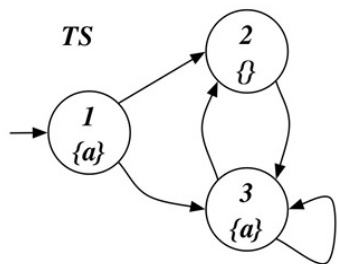
So  $\cap \llbracket \varphi \rrbracket \neq \emptyset$

u-calc

Observe: when evaluating  $\forall \varphi$  over NBA  
you may find states without successor!

(This never happens when we evaluate u-calc  
over TS, since TS need to execute forever to  
generate infinite traces - "time never ends")

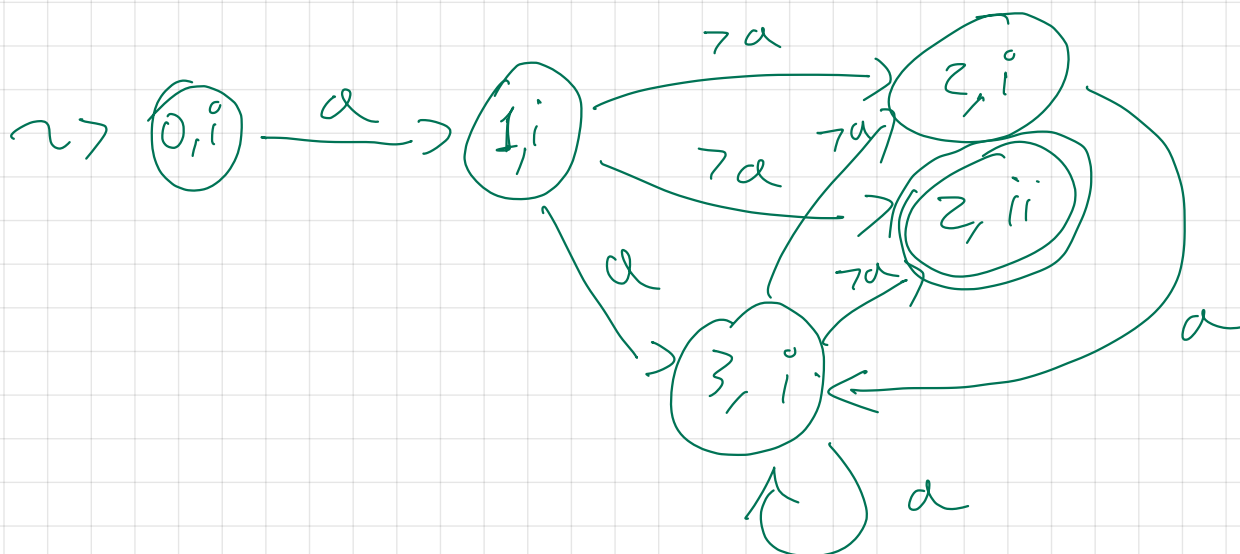
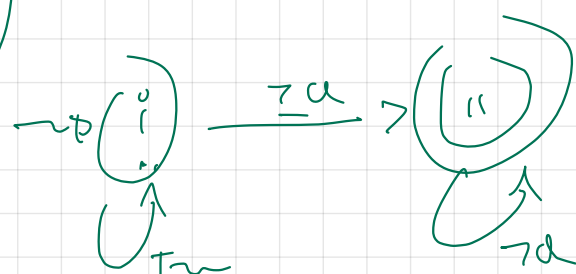
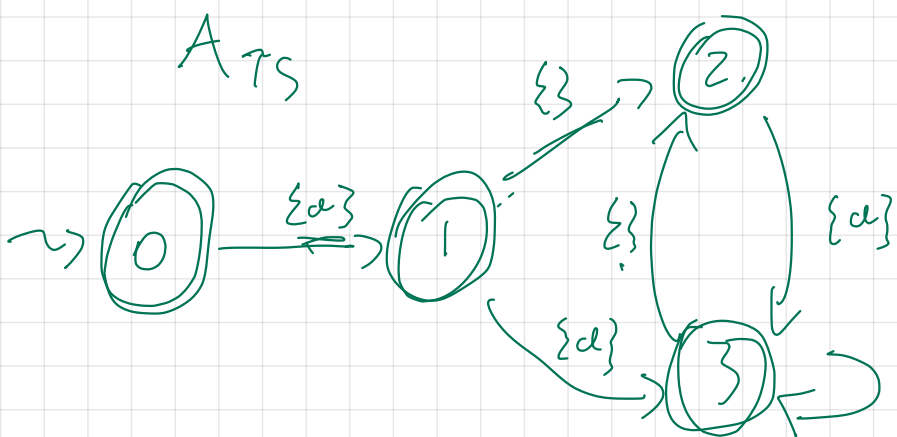
**Exercise 5.** Consider the transition system  $TS$  below. Model check the LTL formula  $\Box \Diamond a$ , by considering that the Büchi automaton  $BA$  for  $\neg \Box \Diamond a$  (i.e.,  $\Diamond \Box \neg a$ ) is the one below:



July 1st, 2021

$TS \models \Box \Diamond a$

$$\mathcal{L}(A_{TS} \cap A_{\neg \Box \Diamond a}) = \emptyset$$



$$\llbracket \forall X. \mu Y. ((F \wedge \langle \text{next} \rangle X) \vee \langle \text{next} \rangle Y) \rrbracket = \emptyset$$

$$\llbracket X_0 \rrbracket = \text{everything}$$

$$\llbracket X_1 \rrbracket = \llbracket \mu Y. ((F \wedge \langle \text{next} \rangle X_0) \vee \langle \text{next} \rangle Y) \rrbracket = \emptyset$$

$$\begin{aligned} \llbracket Y_0 \rrbracket &= \emptyset \\ \llbracket Y_1 \rrbracket &= \llbracket (F \wedge \langle \text{next} \rangle X_0) \vee \langle \text{next} \rangle Y_0 \rrbracket = \\ &= \llbracket F \rrbracket \wedge \text{Pre}_R(-, \llbracket X_0 \rrbracket) \vee \text{Pre}_R(-, \llbracket Y_0 \rrbracket) = \emptyset \end{aligned}$$

$$\llbracket X_2 \rrbracket = \llbracket \mu Y. ((F \wedge \langle \text{next} \rangle X_1) \vee \langle \text{next} \rangle Y) \rrbracket = \emptyset$$

$$\llbracket Y_0 \rrbracket = \emptyset$$

$$\llbracket Y_1 \rrbracket = \llbracket (F \wedge \langle \text{next} \rangle X_1) \vee \langle \text{next} \rangle Y_0 \rrbracket =$$

$$\llbracket F \rrbracket \wedge \text{Pre}_R(-, \llbracket X_1 \rrbracket) \vee \text{Pre}_R(-, \llbracket Y_0 \rrbracket) = \emptyset$$

$$(0, i) \in \llbracket \psi \rrbracket = \emptyset \quad \underline{\text{NO}} \quad \Rightarrow TS \models \Box \Diamond a$$