

Data Structures & Algorithms (F28DA)

Design Techniques – Backtracking, Divide & Conquer

Kathrin Stark

Heriot-Watt University, 2024

Today You'll

- Learn how **backtracking** helps in improving brute force algorithm by pruning the search space
- Learn about the general pattern of **backtracking** algorithms
- Be reminded of the general pattern of Divide-and-Conquer Algorithms
- Learn three ways on how to reason about the asymptomatic runtime of Divide-and-Conquer algorithms



Backtracking

Brute Force

Brute Force Algorithm = A straightforward and exhaustive problem-solving technique that

1. Enumerates all possible solutions
2. Checks whether one of these is actually a solution without leveraging optimisation or heuristic strategies.

Correctness? – Trivial as all solutions are considered

Efficiency? – Often quite inefficient

Runtime:

- **Number of possible solutions:** $g(n)$
- **Time to check a solution:** $f(n)$
- **Total time:** $g(n) * f(n)$

Problem: Possibly a huge problem space

Idea: Can we **prune** the problem space by looking at **partial solutions** already?

Example: Subset Sum Problem

Subset Sum Problem:

Input: A set S of n positive integers, an integer k

Output: True if there is a subset s of integers in S that sum to k

Example. Let $S = \{3, 34, 4, 5\}$. $k = 9$.

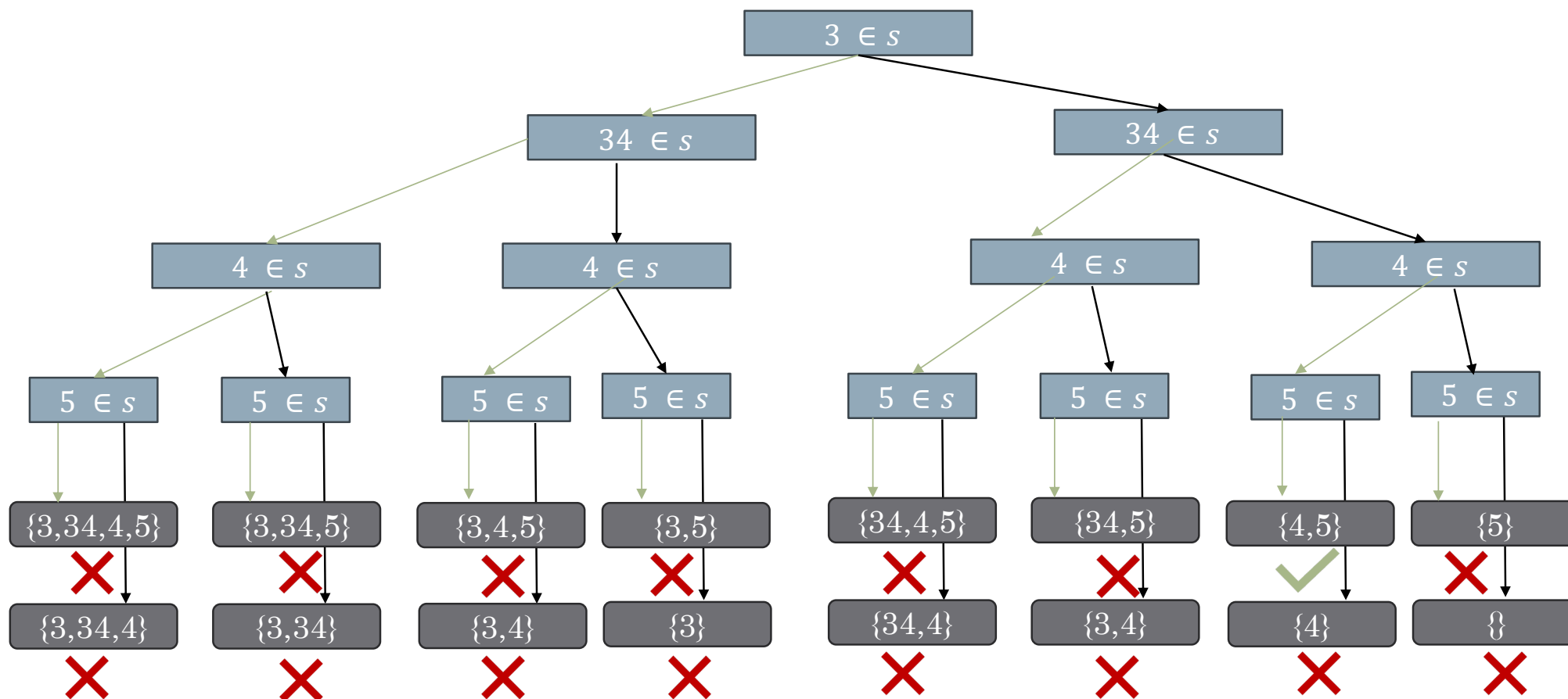
Example: Subset Sum Problem

The Complete Search Tree

Let $S = \{3, 34, 4, 5\}$. $k = 9$.

Brute Force:

1. Enumerates all possible solutions
2. Checks whether one of these is actually a solution



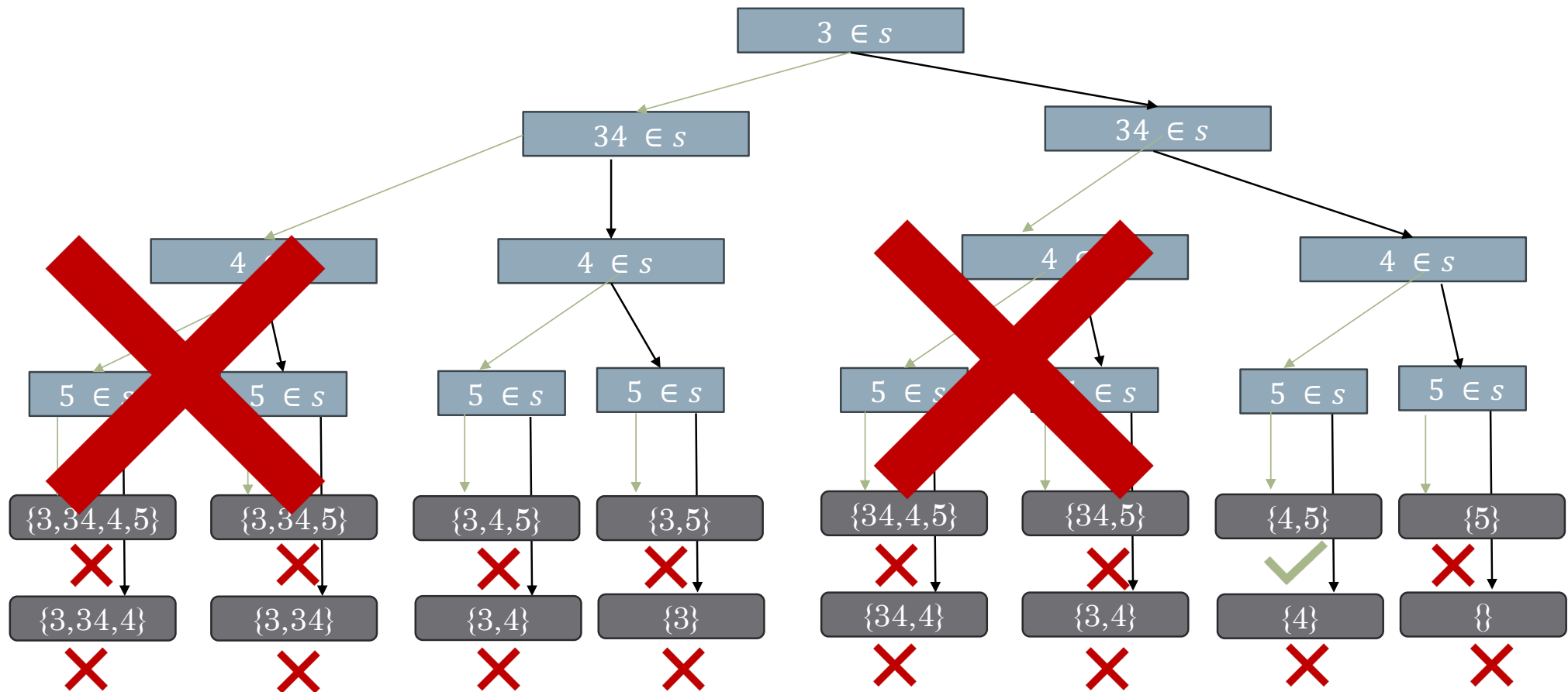
Example: Subset Sum Problem

The Pruned Search Tree

Let $S = \{3, 34, 4, 5\}$. $k = 9$.

Observation:

We can prune parts of the search tree whenever the sum on the way to our set is already $> k$.



General Observation

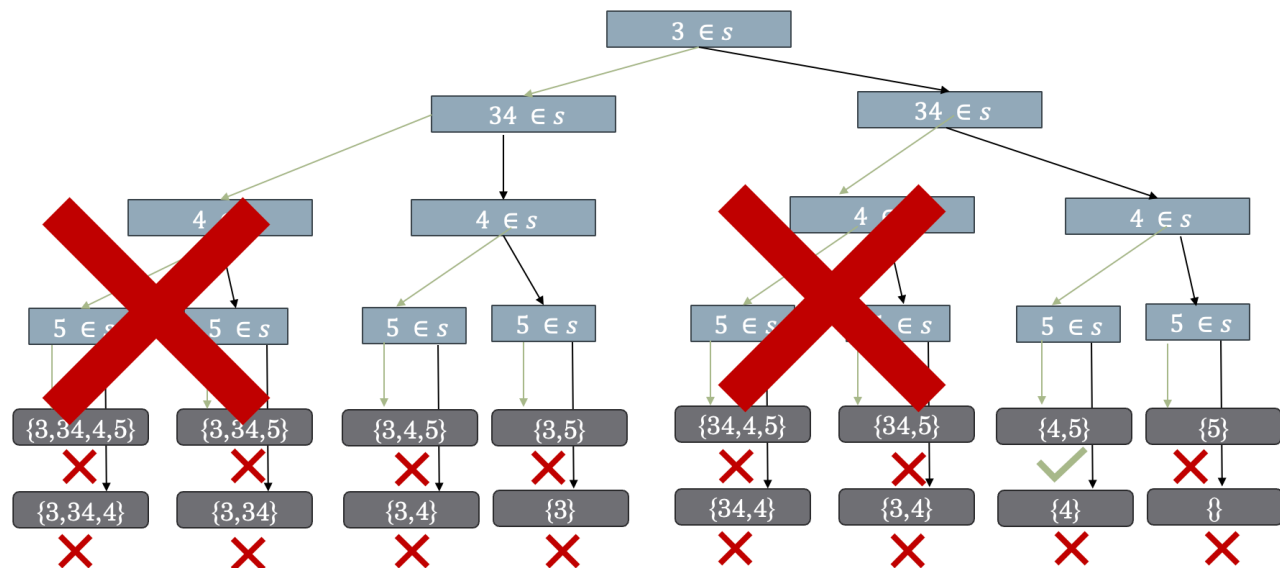
... we can put this in a **general template**.

What we need:

- A way to build up solutions incrementally.
- A way to reject partial solutions.

Example: Subset Sum Problem The Pruned Search Tree

Let $S = \{3, 34, 4, 5\}$. $k = 9$.



Observation:

We can prune parts of the search tree whenever the sum on the way to our set is already $> k$.

Backtracking

Backtracking Algorithm = An exhaustive problem-solving technique that traverses through possible search paths to locate solutions or dead ends.

1. Start with a subproblem configuration.
2. Choose the most promising extending subproblem configuration.
3. If the configuration should get to a dead end, get back to the last decision point.
If a solution is found, stop.

Correctness? – Yes, if all viable paths are considered

General Backtracking Template

Algorithm Backtrack(x):

Input: A problem instance x for a hard problem

Output: A solution for x or “no solution” if none exists

$F \leftarrow \{(x, \emptyset)\}$. $\{F \text{ is the “frontier” set of subproblem configurations}\}$

while $F \neq \emptyset$ **do**

 select from F the most “promising” configuration (x, y)

 expand (x, y) by making a small set of additional choices

 let $(x_1, y_1), (x_2, y_2), \dots, (x_k, y_k)$ be the set of new configurations.

for each new configuration (x_i, y_i) **do**

 perform a simple consistency check on (x_i, y_i)

if the check returns “solution found” **then**

return the solution derived from (x_i, y_i)

if the check returns “dead end” **then**

 discard the configuration (x_i, y_i) $\{\text{Backtrack}\}$

else

$F \leftarrow F \cup \{(x_i, y_i)\}$ $\{(x_i, y_i) \text{ starts a promising search path}\}$

return “no solution”

Source: Algorithm Design by Goodrich & Tamassia, p. 627

Example: Subset Sum Problem

Pseudocode

Algorithm findSubset(S , k)

Input: A set S of n positive integers, an integer k

Output: True if there is a subset s of integers in S that sum to k

`\\ we found a solution`

`if (k == 0) then`

`return True`

`\\ there are no more candidates`

`if (S.isEmpty()) then`

`return False`

`s <- S.get() // next candidate integer`

`if (s > k) then`

`\\ we're overshooting k - so don't include s`

`return findSubset (S\{s}, k)`

`else`

`\\ look both in the case that s is included and not`

`\\ || is short-circuiting`

`findSubset (S\{s}, k - s) || findSubset (S\{s}, k)`

Initial subconfiguration:

The full set S , k .

Extending subconfiguration:

Removing an element s from S ,
 k or $k - s$

Dead end: If no more elements
are in S / k gets negative

Solution: k is 0

Example: Subset Sum Problem

Pseudocode

```
Algorithm findSubset(S, k)
Input: A set S of n positive integers, an integer k
Output: True if there is a subset s of integers in S that sum to k
\\ we found a solution
if (k == 0) then
    return True
\\ there are no more candidates
if (S.isEmpty()) then
    return False

s <- S.get() // next candidate integer

if (s > k) then
    \\ we're overshooting k - so don't include s
    return findSubset (S\{s}, k)
else
    \\ look both in the case that s is included and not
    \\ || is short-circuiting
    findSubset (S\{s}, k - s) || findSubset (S\{s}, k)
```

What's the complexity?

Where Backtracking Is Used

Efficiency: Not necessarily a better asymptotic complexity but can reduce runtime drastically in practice (e.g., SAT solving).

The **heuristic chosen** is important.

Examples:

- **Subset Sum Problem**
- **N-Queens problem:** Given an $N \times N$ chessboard, place N queens such that no two queens threaten each other.
- Solving a partially completed **Sudoku**
- **Knight's Tour:** Find a sequence of moves for a knight on a chessboard such that the knight visits every square exactly once
- (Later): Find a **Hamiltonian circle** in a graph; find a **graph coloring**
- **SAT** solvers



Divide and Conquer

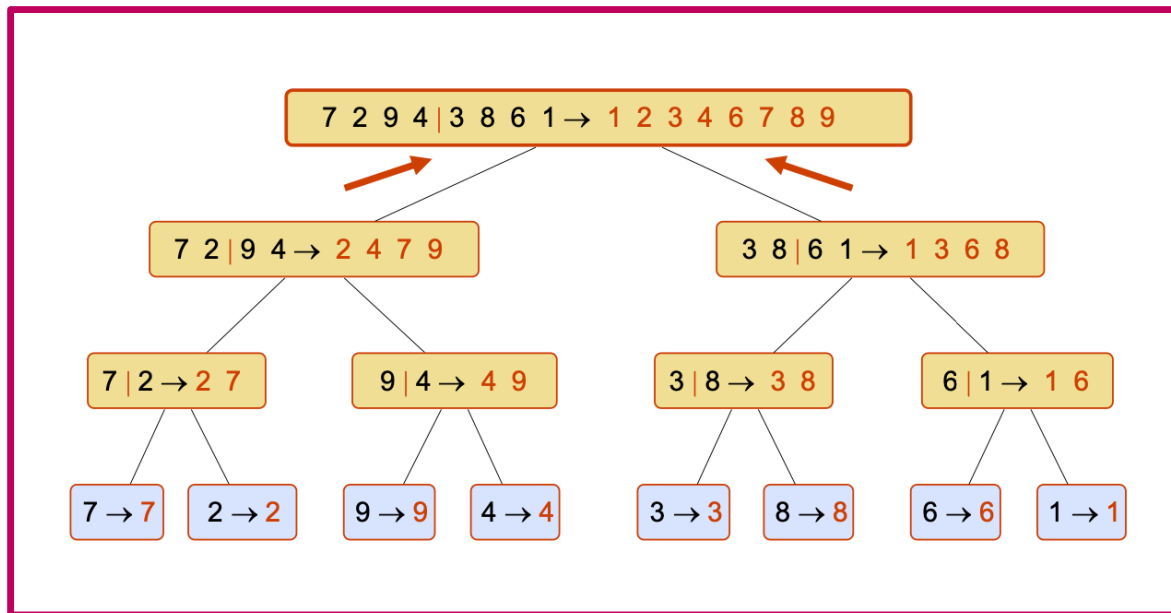
Divide and Conquer Pattern

General Idea

The **Divide-and-Conquer** strategy solves a problem by

1. Breaking it into **subproblems** (= smaller instances of the original problem)
2. Recursively solving the **subproblems** (base case: the problem is small enough to be solved directly)
3. Combining the solutions to get a solution to the original problem.

Reminder: Merge Sort



Idea: Split the list into two and sort every list independently.
Combine the two sorted list with a procedure merge.

Source: F28GS

Breaking it into subproblems
= breaking it into smaller lists

Solving the subproblems
= running the sorting algorithm
on the smaller lists

Combining the solutions
= running the merge algorithm

Divide and Conquer Pattern

Runtime

The **Divide-and-Conquer** strategy solves a problem by

1. Breaking it into **subproblems** (= smaller instances of the original problem)
2. Recursively solving the **subproblems** (base case: the problem is small enough to be solved directly)
3. Combining the solutions to get a solution to the original problem.

We often use a **recurrence** to express the running time of a divide and conquer algorithm.

- Time b in the case that n is small, say $n \leq k$
- Divide the problem into a subproblems, each $1/b$ the size of the original
- Time to divide a size- n problem: $D(n)$
- Time to combine solutions: $C(n)$

$$T(n) = \begin{cases} b, & n \leq k \\ a T\left(\frac{n}{b}\right) + D(n) + C(n), & n > k \end{cases}$$

Runtime Analysis Merge

Algorithm merge(S_1, S_2, S):

Input: Sequences S_1 and S_2 sorted in nondecreasing order, and an empty sequence S

Output: Sequence S containing the elements from S_1 and S_2 sorted in nondecreasing order, with sequences S_1 and S_2 becoming empty

```
while (not ( $S_1$ .isEmpty() or  $S_2$ .isEmpty)) do
  if  $S_1$ .first().element()  $\leq$   $S_2$ .first().element() then
    { move the first element of  $S_1$  at the end of  $S$  }
     $S$ .insertLast( $S_1$ .remove( $S_1$ .first()))
  else
    { move the first element of  $S_2$  at the end of  $S$  }
     $S$ .insertLast( $S_2$ .remove( $S_2$ .first()))
{ move the remaining elements of  $S_1$  to  $S$  }
while (not  $S_1$ .isEmpty()) do
   $S$ .insertLast( $S_1$ .remove( $S_1$ .first()))
{ move the remaining elements of  $S_2$  to  $S$  }
while (not  $S_2$ .isEmpty()) do
   $S$ .insertLast( $S_2$ .remove( $S_2$ .first()))
```

Runtime:

Source: Algorithm Design by Goodrich & Tamassia

Runtime Analysis Merge Sort

Algorithm mergesort (S)

Input: Sequence S

Output: Sequence S in sorted order

if S.size() < 2 then

 return S

// Split S into two equally long sequences (± 1)

(S1, S2) <- split S

S1 <- mergesort (S1)

S2 <- mergesort (S2)

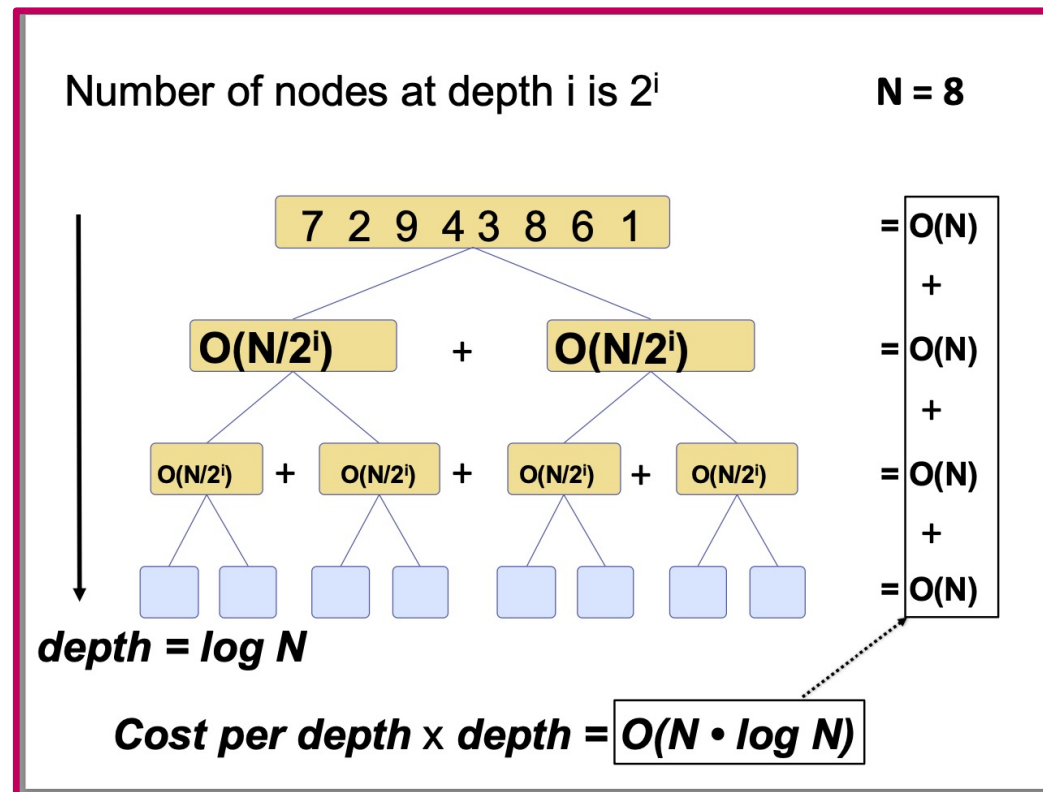
S <- emptySequence

return merge (S1, S2, S)

Recurrence equations for runtime $T(n)$:

$$T(n) = \begin{cases} b, & n < 2 \\ 2 T\left(\frac{n}{2}\right) + c n, & n \geq 2 \end{cases}$$

Possibility 1: Argue on the Recursion Tree



Problem:

Works here but is not as easy when the recursion pattern gets more complicated.

Possibility 2:

Guess a solution and prove it correct

- Guess an expression for the solution. The expression can contain constants that will be determined later.
- Use induction to find the constants and show that the solution works.

Let us apply this method to MERGE-SORT.

The recurrence of MERGE-SORT implies that there exist two constants $c, d > 0$ such that

$$T(n) \leq \begin{cases} c & \text{if } n = 1 \\ 2T(n/2) + dn & \text{if } n > 1 \end{cases}$$

Guess. There is some constant $a > 0$ such that $T(n) \leq an \lg n$ for all $n > 2$ that are powers of 2.

Source: <https://www.cs.ox.ac.uk/files/12487/divide-and-conquer.pdf>

Possibility 2:

Guess a solution and prove it correct

Test. For $n = 2^k$, by induction on k .

Base case: $k = 1$

$$T(2) = 2c + 2d \leq a 2 \lg 2 \quad \text{if } a \geq c + d$$

Inductive step: assume $T(n) \leq an \lg n$ for $n = 2^k$.

Then, for $n' = 2^{k+1}$ we have:

$$\begin{aligned} T(n') &\leq 2a \frac{n'}{2} \lg \left(\frac{n'}{2} \right) + d n' \\ &= a n' \lg n' - a n' \lg 2 + d n' \\ &\leq a n' \lg n' \quad \text{if } a \geq d \end{aligned}$$

In summary: choosing $a \geq c + d$ ensures $T(n) \leq an \lg n$,
and thus $T(n) = O(n \log n)$.

A similar argument can be used to show that $T(n) = \Omega(n \log n)$.

Hence, $T(n) = \Theta(n \log n)$.

Source: <https://www.cs.ox.ac.uk/files/12487/divide-and-conquer.pdf>

Possibility 3: The Master Theorem

A “Recipe” for Recurrence Equations in Divide & Conquer

Let

$$T(n) = \begin{cases} c & \text{if } n < d \\ aT(n/b) + f(n) & \text{if } n \geq d, \end{cases}$$

for $d \geq 1, a > 0, c > 0$ and $b > 1$ and $f(n)$ be a function that is positive for $n \geq d$.

Theorem 5.6 [The Master Theorem]: *Let $f(n)$ and $T(n)$ be defined as above.*

1. *If there is a small constant $\epsilon > 0$, such that $f(n)$ is $O(n^{\log_b a - \epsilon})$, then $T(n)$ is $\Theta(n^{\log_b a})$.*
2. *If there is a constant $k \geq 0$, such that $f(n)$ is $\Theta(n^{\log_b a} \log^k n)$, then $T(n)$ is $\Theta(n^{\log_b a} \log^{k+1} n)$.*
3. *If there are small constants $\epsilon > 0$ and $\delta < 1$, such that $f(n)$ is $\Omega(n^{\log_b a + \epsilon})$ and $af(n/b) \leq \delta f(n)$, for $n \geq d$, then $T(n)$ is $\Theta(f(n))$.*

Source: Algorithm Design Goodrich & Tamassia, p. 268

Example Master Theorem

Merge Sort

$$T(n) = \begin{cases} b, & n < 2 \\ 2 T\left(\frac{n}{2}\right) + b, & n \geq 2 \end{cases}$$

- What's a and b? What's $\log_b a$?
- Of what complexity is $f(n)$?
- Does any of the cases apply?

Let

$$T(n) = \begin{cases} c & \text{if } n < d \\ aT(n/b) + f(n) & \text{if } n \geq d, \end{cases}$$

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Example Master Theorem

Algorithm findMax (a, l, u)

Input: Array a of size u - l + 1 = n >= 1

Output: Max. element in a between l and u - 1

if l+1 = u then

return a[l]

mid = $\left\lfloor \frac{l+u}{2} \right\rfloor$

return max (findMax (a, l, mid),

findMax (a, mid, u))

$$T(n) = \begin{cases} c, & n < 2 \\ 2 T\left(\frac{n}{2}\right) + d, & n \geq 2 \end{cases}$$

- What's a and b? What's $\log_b a$?
- Of what complexity is f(n)?
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for $d \geq 1, a > 0, c > 0$ and $b > 1$ and f(n) be a function that is positive for $n \geq d$.

Theorem 5.6 [The Master Theorem]: Let f(n) and T(n) be defined as above.

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3. If there are small constants $\epsilon > 0$ and $\delta < 1$, such that f(n) is $\Omega(n^{\log_b a + \epsilon})$ and $af(n/b) \leq \delta f(n)$, for $n \geq d$, then T(n) is $\Theta(f(n))$.

You Learned

- How **backtracking** helps in improving brute force algorithm by pruning the search space
- The general pattern of **backtracking** algorithms
- About the general pattern of Divide-and-Conquer Algorithms
- Three ways on how to reason about the asymptomatic runtime of Divide-and-Conquer algorithms

Reading

- Chapter 1.4 of Algorithms by Sedgewick & Wayne
- Chapter 5.2 of Algorithm Design Goodrich & Tamassia
- Chapter 13.5 of Algorithm Design Goodrich & Tamassia

Optional Reading

- [Geogebra.org](https://www.geogebra.org) - allows you to plot graphs
- Big-O Complexity Sheet (<https://www.bigocheatsheet.com>) – Overview of complexity for most standard algorithms
- [Base.cs podcast](#) on O-notation