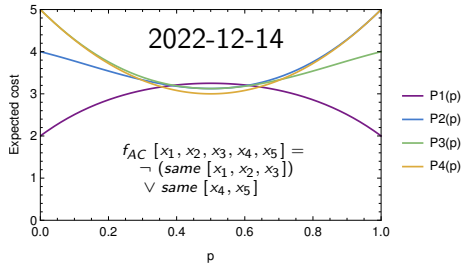


Level-p-complexity of Boolean Functions

Using thinning, memoization, and polynomials

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¹Joint work with Julia Jansson, PhD student, Mathematical sciences, Chalmers

Some key results (teaser)

We want to find a decision tree with minimal cost for a boolean function.

We specify the problem as "generate all, select a smallest".

For an example 5-bit function f_{AC} there are already **54192** different decision trees.

$$t_5 = \text{size}(\text{genAlg } 5 \ f_{AC} :: \text{Set } \text{DecTree})$$



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For a 9-bit function we can estimate the number of trees as

$$t_9 = 9 * t_8^2; \quad t_8 = 8 * t_7^2; \quad t_7 = 7 * t_6^2; \quad t_6 = 6 * t_5^2$$

This estimate gives us $1.29 * 10^{89}$ decision trees!

Clearly, a naive implementation will take far too long to terminate.



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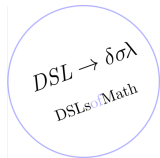
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By using **thinning**, **memoization**, and exact comparisons of **polynomials** we get down to a **singleton set** for iterated majority:

$$\begin{aligned} ps9 &= \text{genAlgThinMemoPoly } 9 \ \text{maj2} :: \text{Set } (\text{Poly } \text{Rational}) \\ -- \text{ps9} &= \text{fromList } [P \ [4, 4, 6, 9, -61, 23, 67, -64, 16]] \end{aligned}$$



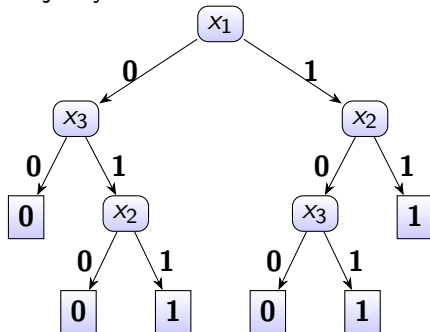
Some key types and definitions

- A Boolean function $f : BoolFun\ n$ takes a tuple of n bits to one bit.
- A tuple $t : Tuple\ n$ is just a vector of n bits (**type** $Bit = Bool$; **0** = False; **1** = True).
- A decision tree describes a way to evaluate a $BoolFun$:

Haskell version:

```
type Index = ℕ
data DecTree where
  Res :: Bool → DecTree
  Pick :: Index → DecTree → DecTree → DecTree
ex1 :: DecTree
ex1 = Pick 1 (Pick 3 (Res 0)
                  (Pick 2 (Res 0) (Res 1)))
          (Pick 2 (Pick 3 (Res 0) (Res 1))
                  (Res 1))
```

A decision tree (ex1) for the 3-bit majority function:



Some key types and definitions

A decision tree describes a way to evaluate a *BoolFun*

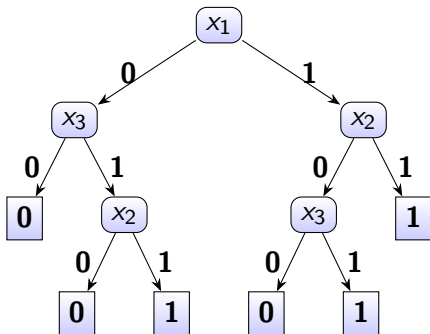
Haskell version:

```
type Index =  $\mathbb{N}$   
data DecTree where  
  Res :: Bool  $\rightarrow$  DecTree  
  Pick :: Index  $\rightarrow$  DecTree  $\rightarrow$  DecTree  $\rightarrow$  DecTree
```

Agda version:

```
data DecTree : (n :  $\mathbb{N}$ )  $\rightarrow$  (f : BoolFun n)  $\rightarrow$  Set where  
  Res : (b : Bool)  $\rightarrow$  DecTree n (const b)  
  Pick : { f : BoolFun (suc n) }  $\rightarrow$  (i : Fin (suc n))  $\rightarrow$  DecTree n (setBit i 0 f)  $\rightarrow$   
                                           DecTree n (setBit i 1 f)  $\rightarrow$   
                                           DecTree (suc n) f  
  
setBit : Fin (suc n)  $\rightarrow$  Bit  $\rightarrow$  BoolFun (suc n)  $\rightarrow$  BoolFun n
```

Decision trees, cost and complexity

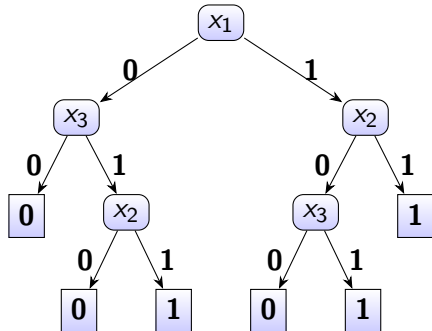


The decision tree *ex1* for the 3-bit majority function *maj*:

- Note that the left subtree is for the function $f_0 = \text{setBit } 1 \ 0 \text{ } maj = (\wedge)$
- and the right subtree for the function $f_1 = \text{setBit } 1 \ 1 \text{ } maj = (\vee)$

²We assume n independent bits, all with probability p to be 1. The polynomials are defined over any *Ring*.

Decision trees, cost and complexity



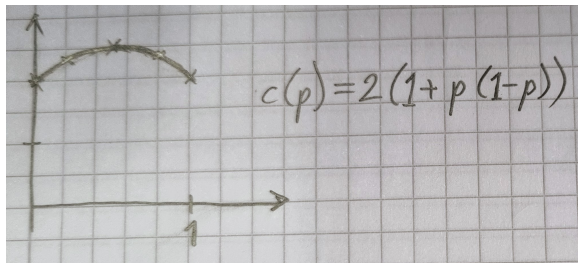
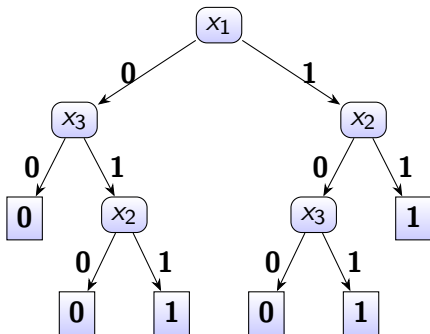
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- The *cost* of a *DecTree* is a function from *Tuple* n to \mathbb{N} :
 $cost : \{n : \mathbb{N}\} \rightarrow \{f : BoolFun\ n\} \rightarrow DecTree\ n\ f \rightarrow Tuple\ n \rightarrow \mathbb{N}$

²We assume n independent bits, all with probability p to be **1**. The polynomials are defined over any *Ring*.

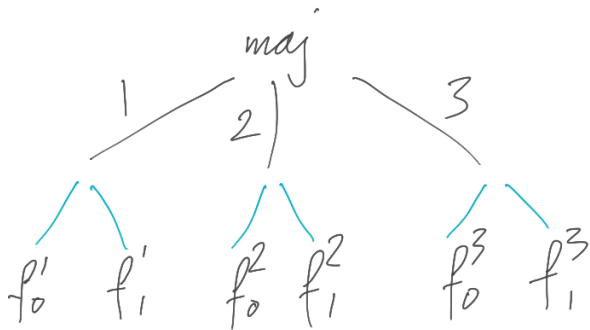
Decision trees, cost and complexity



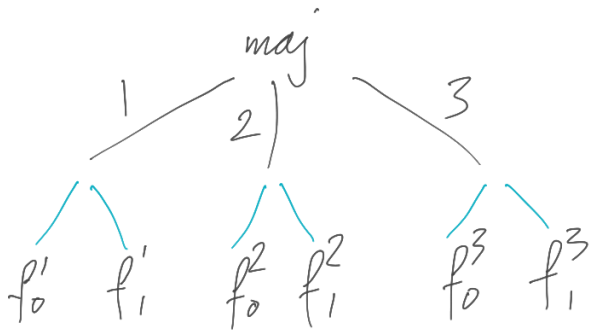
$\text{expCost ex1} = P[2, 2, -2]$

- Finally, the *expected cost*², is a polynomial in the probability p that a bit is **1**:
 $\text{expCost} : \{n : \mathbb{N}\} \rightarrow \{f : \text{BoolFun } n\} \rightarrow \text{DecTree } n \ f \rightarrow \text{Poly } n$

²We assume n independent bits, all with probability p to be **1**. The polynomials are defined over any *Ring*.



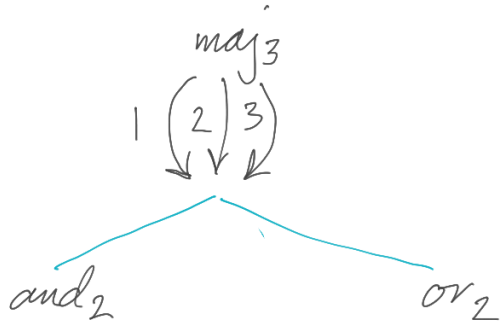
$$f_b^i = \text{set } B \text{ if } i \text{ is } \text{maj}$$



$$f_b^i = \text{set Bit } i \text{ b maj}$$

$$f_0^i = \wedge$$

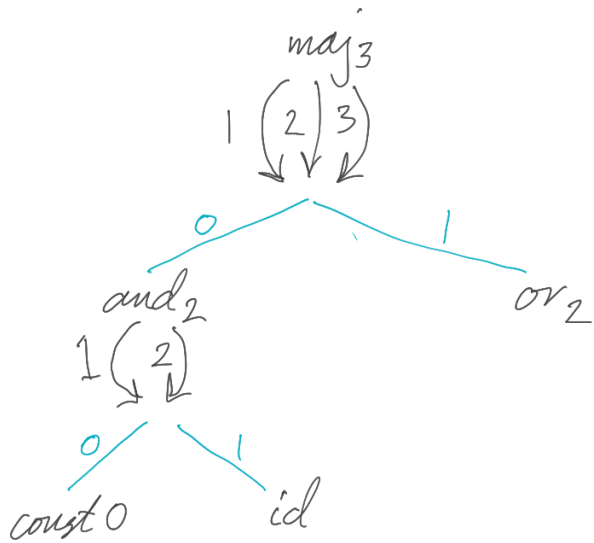
$$f_1^i = \vee$$



$$f_b^i = \text{setBit } i \text{ } b \text{ } \text{maj}$$

$$f_0^i = \wedge = \text{and}_2$$

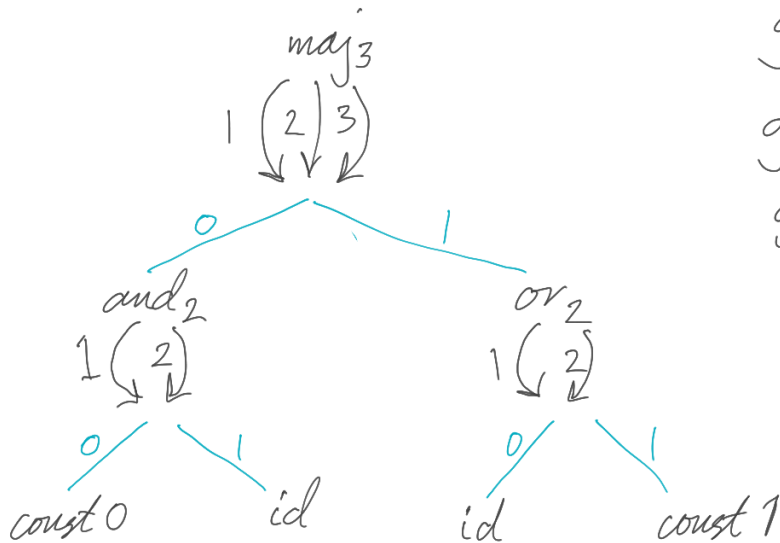
$$f_1^i = \vee = \text{or}_2$$



$$g_b^i = \text{set } B \text{ if } i \text{ is } b \text{ and } 2$$

$$g_0^i = \text{const } 0$$

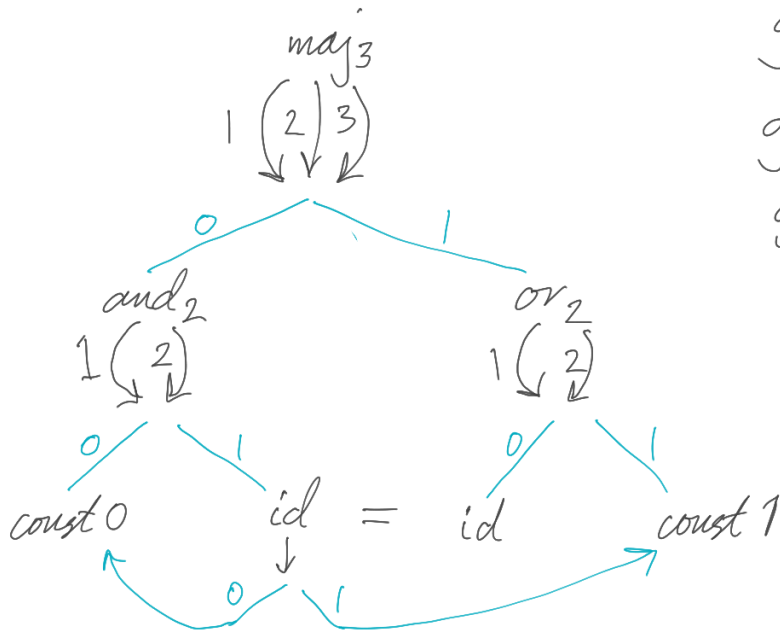
$$g_1^i = \text{id}_B$$



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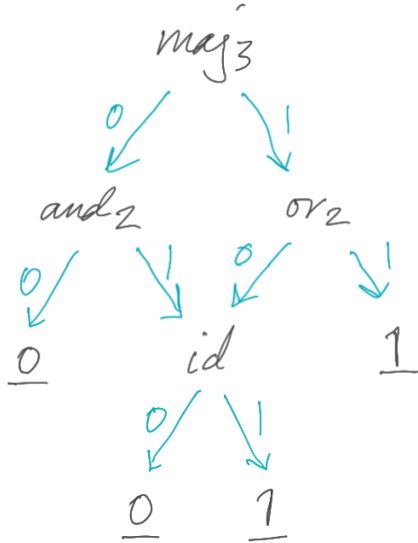
$$g_1^i = \text{const } 1$$

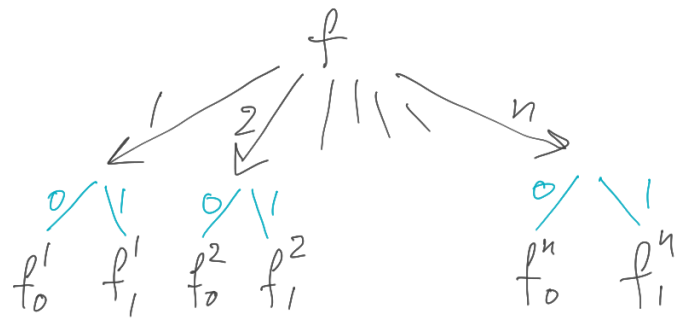


$$g_b^i = \text{set Bit } i \text{ or } 2$$

$$g_0^i = \text{id}_B$$

$$g_1^i = \text{const } 1$$





n -bit

$(n-1)$ -bit

$(n-2)$ -bit

\vdots

0-bit

0 1

A class of Boolean functions

We abstract from the actual type for Boolean functions to a type class:

```
class BoFun bf where  
  isConst :: bf → Maybe Bool  
  setBit   :: Index → Bool → bf → bf
```

We only use one instance: Binary Decision Diagrams (BDDs) which allows good sharing and fast operations.

A class of decision tree algebras

Similarly, for decision trees, we use a class of tree algebras:

```
class TreeAlg a where  
  res :: Bool → a  
  pic :: Index → a → a → a
```

```
ex1 :: TreeAlg a ⇒ a  
ex1 = pic 1 (pic 3 (res 0) (pic 2 (res 0) (res 1)))  
      (pic 2 (pic 3 (res 0) (res 1)) (res 1))
```

```
instance      TreeAlg DecTree    where res = Res;    pic = Pick;  
instance      TreeAlg CostFun    where res = resC;    pic = pickC  
instance Ring a ⇒ TreeAlg (ExpCost a) where res = resPoly; pic = pickPoly
```

A class of decision tree algebras

Similarly, for decision trees, we use a class of tree algebras:

class *TreeAlg* *a* **where**

res :: *Bool* → *a*

pic :: *Index* → *a* → *a* → *a*

ex1 :: *TreeAlg* *a* ⇒ *a*

ex1 = *pic* 1 (*pic* 3 (*res* 0) (*pic* 2 (*res* 0) (*res* 1)))
 (*pic* 2 (*pic* 3 (*res* 0) (*res* 1)) (*res* 1))

instance *TreeAlg* *DecTree* **where** *res* = *Res*; *pic* = *Pick*;

data *DecTree* **where**

Res :: *Bool* → *DecTree*

Pick :: *Index* → *DecTree* → *DecTree* → *DecTree*

A class of decision tree algebras

Similarly, for decision trees, we use a class of tree algebras:

class *TreeAlg* *a* **where**

res :: *Bool* \rightarrow *a*

pic :: *Index* \rightarrow *a* \rightarrow *a* \rightarrow *a*

ex1 :: *TreeAlg* *a* \Rightarrow *a*

ex1 = *pic* 1 (*pic* 3 (*res* 0) (*pic* 2 (*res* 0) (*res* 1)))
 (*pic* 2 (*pic* 3 (*res* 0) (*res* 1)) (*res* 1))

instance *TreeAlg* *CostFun* **where** *res* = *resC*; *pic* = *pickC*

type *CostFun* = *Tuple* \rightarrow *Int*

resC *b* = *const* 0

pickC *i* *c*₀ *c*₁ = $\lambda t \rightarrow 1 +$ **if** *index* *t* *i* **then** *c*₁ *t* **else** *c*₀ *t*

A class of decision tree algebras

Similarly, for decision trees, we use a class of tree algebras:

class *TreeAlg* *a* **where**

res :: *Bool* → *a*

pic :: *Index* → *a* → *a* → *a*

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ex1 = *pic* 1 (*pic* 3 (*res* 0) (*pic* 2 (*res* 0) (*res* 1)))
 (*pic* 2 (*pic* 3 (*res* 0) (*res* 1)) (*res* 1))

instance *Ring* *a* ⇒ *TreeAlg* (*ExpCost* *a*) **where** *res* = *resPoly*; *pic* = *pickPoly*

type *ExpCost* *a* = *Poly* *a*

resPoly _*b* = *zero*

pickPoly _ *p*₀ *p*₁ = *one* + (*one* − *xP*) * *p*₀ + *xP* * *p*₁

Problem formulation: compute the *complexity*

- generate all DecTrees for a given function

$$\text{genAlg} :: (\text{BoFun } bf, \text{TreeAlg } ta) \Rightarrow bf \rightarrow \text{Set } ta$$

- find a small(est) set of dominating trees

$$\text{minWith} :: \text{Preorder } b \Rightarrow (a \rightarrow b) \rightarrow \text{Set } a \rightarrow \text{Set } a$$

- then just keep their costs

$$\begin{aligned} \text{complexity} &:: (\text{BoFun } bf, \text{Ring } a) \Rightarrow bf \rightarrow \text{Set } (\text{Poly } a) \\ \text{complexity} &= \text{mapS } \text{expCost} \circ \text{minWith } \text{expCost} \circ \text{genAlg} \end{aligned}$$

- We can push the map on the other side of *minWith*

complexity = *mapS expCost* \circ *minWith expCost* \circ *genAlg*

-- is equal to

complexity = *minWith id* \circ *mapS expCost* \circ *genAlg*

- Note that this makes the computation more efficient, because several trees map to the same polynomial

Calculation step, cont.

- Next, we push the *expCost* computation into the tree generation, to get another gain in efficiency.

complexity = *minWith id* \circ *mapS expCost* \circ *genAlg*

-- is equal to

complexity = *minWith id* \circ *genPoly*

- Still generating too many polynomials - we can push some of *minWith* into the *genPoly* computation. This is the thinning step.

complexity = *minWith id* \circ *thin* \circ *genPoly*

-- is equal to (the proof is work in progress)

complexity = *minWith id* \circ *genPolyThin*

Unfolding boolean functions

```
genAlg :: (BoFun bf, TreeAlg ta) => bf -> Set ta
genAlg n f = case isConst f of
  Just b   -> singleton (res b)
  Nothing -> crossSigma (\i (t0, t1) -> pic i t0 t1) [1..n] $ \i ->
    cross (genAlg (n - 1) (setBit i 0 f))
          (genAlg (n - 1) (setBit i 1 f))

crossSigma :: (a -> b -> c) -> Set a -> (a -> Set b) -> Set c
-- crossSigma op xs f = { op x y | x ← xs, y ← f x }

cross :: Set a -> Set b -> Set (a, b)
cross xs ys = crossSigma (,) xs (\_ -> ys)
-- cross xs ys = { op x y | x ← xs, y ← ys }
```

- At this point recall the structure of the computation: We have an “unfold”, co-algebra structure when we consume a boolean function and produce all dectrees.
- *isConst* maps an *BoFun* into either a *const b* case or the *setBit* case which for each $i : Fin\ n$ has two subfunctions *setBit i F f* and *setBit i T f*.
- This can cause an enormous number of function calls, which indicates the need to do memoization (dynamic programming) when building up the “call graph”.

- Memoization reminder: naively computing $\text{fib}(n+2) = \text{fib}(n+1) + \text{fib } n$ leads to exponential growth in the number of function calls.
- But if we fill in a table indexed by n with already computed results we get a the result in linear time.

Memoization in our case

- Similarly, here we “just” need to tabulate the result of the calls to complexity so as to avoid recomputation.
- The challenge is that the input is now a boolean function which is not as nicely structured as a natural number index.
- Fortunately, thanks to Hinze and others we have generic Tries only a hackage library away.
- Finally, putting these components together we can compute the level-p-complexity of (small) boolean functions in reasonable time.

Motivating example: 2-level iterated majority *maj2*:

```
ps9 = genAlgThinMemoPoly 9 maj2 :: Set (Poly Rational)  
-- ps9 = fromList [P [4, 4, 6, 9, -61, 23, 67, -64, 16]]
```

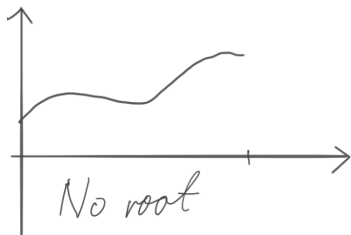
Comparing polynomials

- Now, one of the challenges was actually the implementation of the comparison of polynomials. This is an interesting story in itself but perhaps not the main topic for today.
- Remember that the “complexity” we compute for each decision tree is actually a polynomial in the probability for a bit to be **1**.
- And the mathematical definition of the level- p -complexity includes a “min” over all dec.trees, which in general results in a piecewise polynomial function.
- Ideally we should have a partition of the unit interval, labelled with polynomials, but we choose to represent such piecewise polynomial function simply as a set of polynomials.

Comparing polynomials, cont.

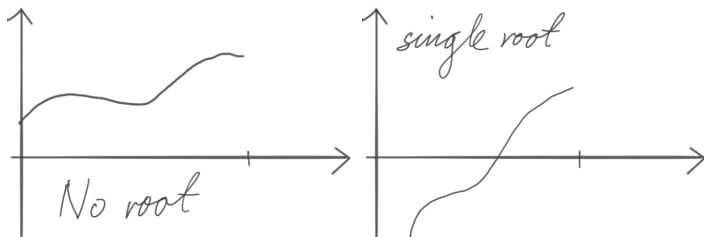
- For thinning we need a preorder on our polynomials, specified as $p \leq q = \text{forall } x. \text{ eval } p \ x \leq \text{eval } q \ x$.
- This can be simplified to $\text{eval } (q - p) \ x \geq 0$ where $q - p$ is also a polynomial.
- We started with some ad-hoc special cases, but the sets did not shrink enough.
- Then we went to the wonderful world of polynomial algebra and root-counting.

Root-counting



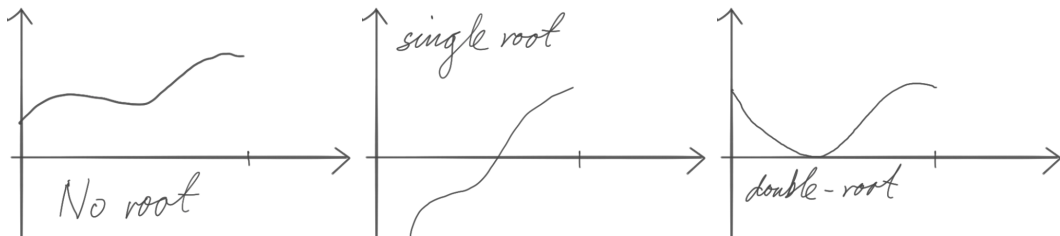
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Root-counting



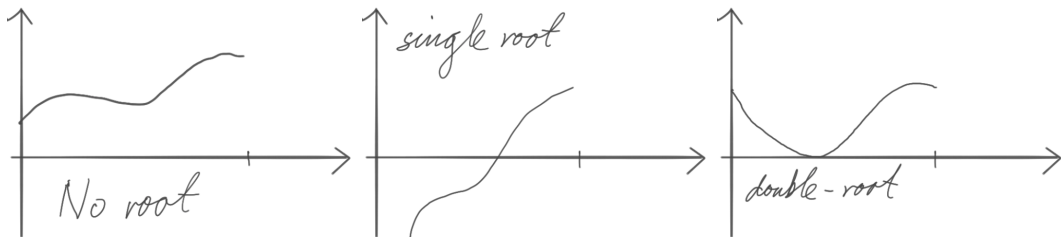
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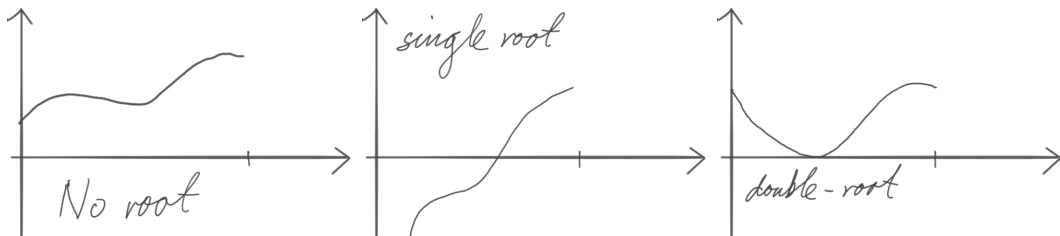
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- Thus, we “only” need to count roots with exact multiplicities in the unit interval.
- Note that we do not need to actually compute the roots, only count them.
- We use Yun’s algorithm for square-free factorisation and Descartes rule of signs in combination with interval-halving.

Conclusions

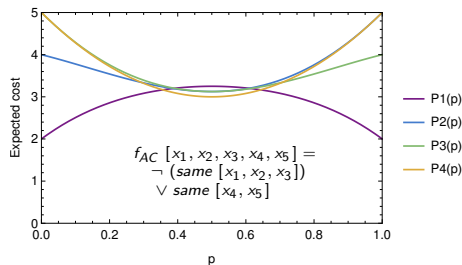
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```

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```

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ps5 = genAlgThinMemoPoly 5 fAC :: Set (Poly Rational)
```

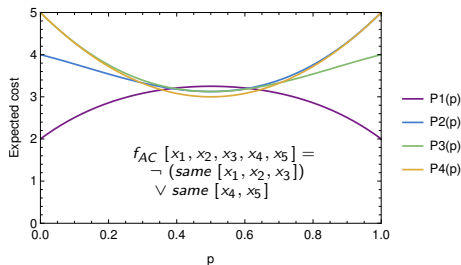
```
check5 = ps5 == fromList [P [2, 6, -10, 8, -4], P [4, -2, -3, 8, -2],  
                           P [5, -8, 9, 0, -2], P [5, -8, 8]]
```



Conclusions

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```
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                          P [5, -8, 9, 0, -2], P [5, -8, 8]]
```



Future work:

- Clean up the calculations / proofs
- More efficient memoization
- Three-level iterated majority (27 bits)