## CareerROBO

**Human-Centered Interaction in Robotics** 

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## Requirements

- numpy
- pybullet
- qibullet
- pydub

- gtts
- opency-python
- RASA













### Architecture

#### Hardware:

- Microphone and speaker for audio input/output
- Camera system for facial recognition

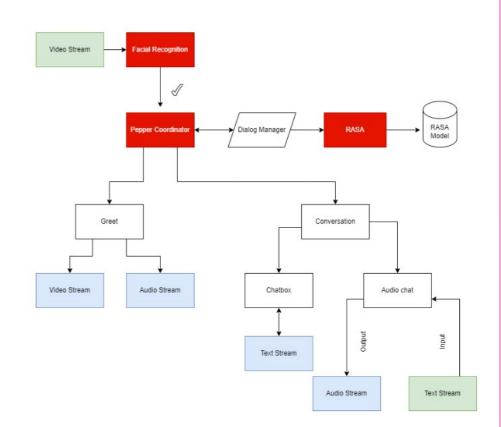
#### Core Components:

- Facial recognition system processes video input
- Rasa chatbot handles conversations (Core for dialog, NLU for language processing)
- API middleware connects Pepper to Rasa

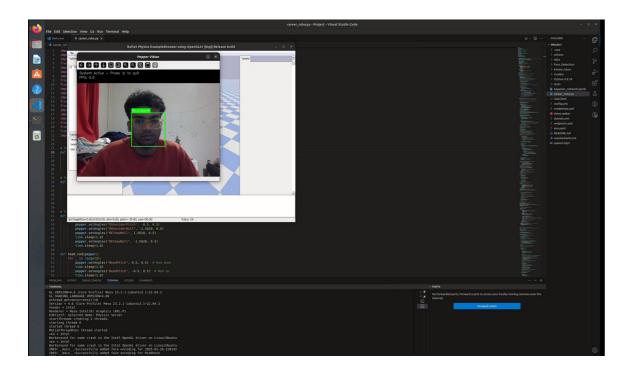
Interaction Flow: Student face detection → Recognition → Personalized greeting → Conversation

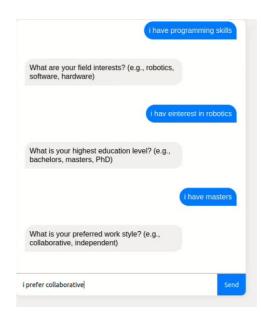






# Demo









# Technical Challenges

### **Environment Setup Challenges:**

- Python dependency conflicts in Ubuntu
- Package compatibility issues
- Environment variable management

### Solutions Implemented:

- Virtual environment isolation
- Manual package version resolution
- Comprehensive documentation of setup steps





### **Ethical Considerations**

### Privacy Protection:

- Secure handling of face detection data
- No permanent storage of user information

#### Bias Mitigation:

- Regular review of career recommendation algorithms
- Diverse career options database

#### **User Trust:**

- Transparent recommendation process
- Clear communication of system capabilities
- Respectful handling of user preferences and choices





# Thank You