

Fall 2019



California State University, Northridge

Department of Electrical and Computer Engineering

ECE 526L

Experiment # 3
Hierarchical Modeling

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I hereby attest that this lab report is entirely my own work. I have not copied either code or text from anyone, nor have I allowed or will I allow anyone to copy my work.

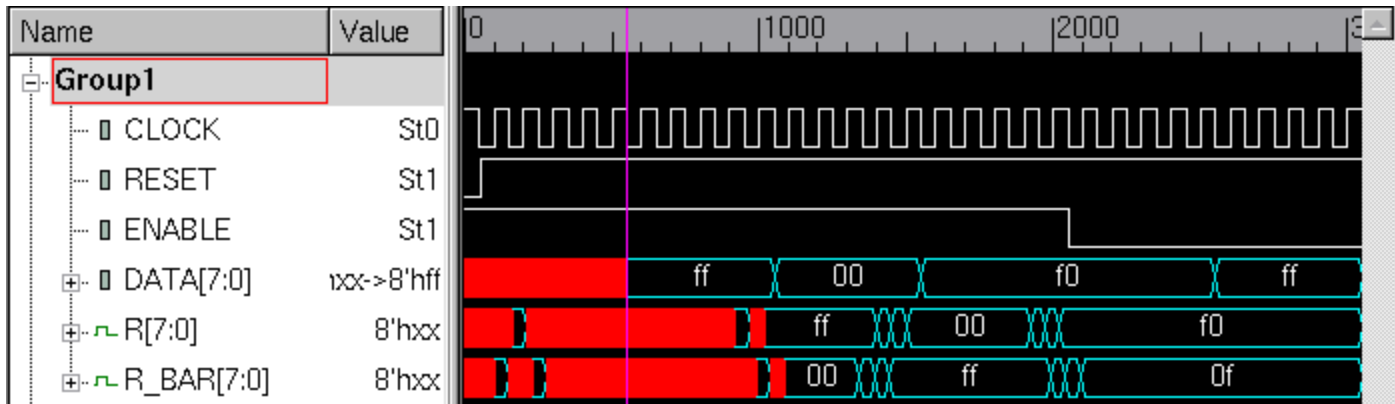
Name (printed) _____

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Date _____

Analysis

Figure 1. TB_REGISTER.v waveform



Looking closely at figure 1, the DATA input is closely followed by the R output. The input tested was FF, 00, then F0.

After F0, the ENABLE input was dropped to 0 and the DATA input was given FF; However, the R output did not follow the DATA input as expected.

Looking closer at figure 2, the RESET is set initially 0. The R output eventually gets a correct value of 00. These results show that the design is logically correct.

Figure 2. Zoom on RESET

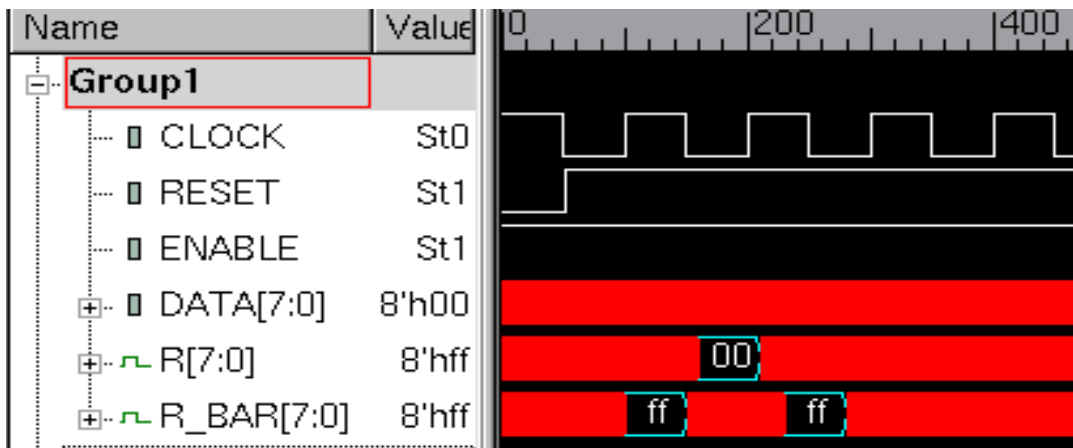
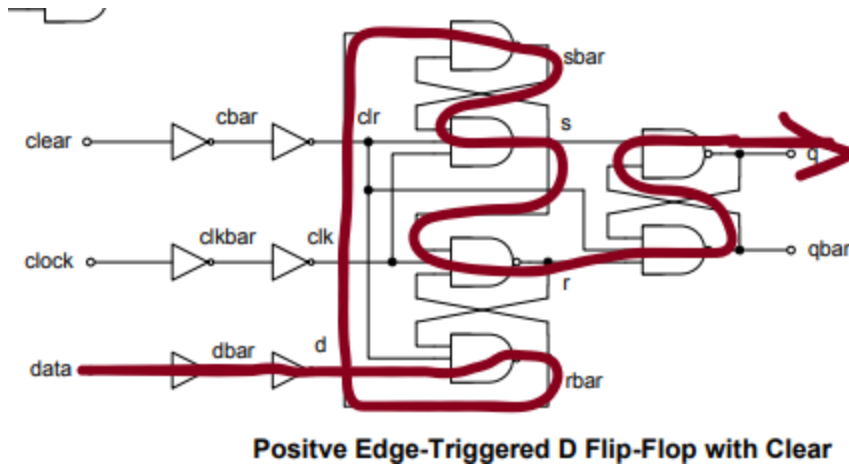


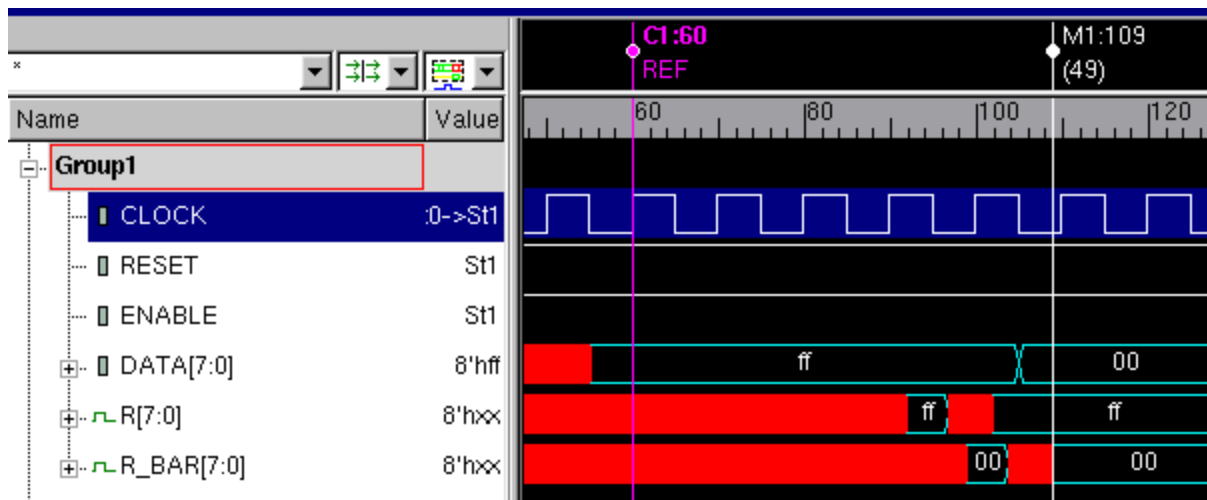
Figure 3. Longest path in DFF



To calculate the operating frequency of the circuit, the longest path of the circuit was found. The longest path includes that data input of the multiplexer to the multiplexers data output to the DFF, and all the way to the DFF's output. By summing the delays of each gate and fanout, the period is calculated to be 35.7 ns.

$$F = \frac{1}{T} = \frac{1}{35.7 \text{ ns}} = 28.01 \text{ MHz}$$

Figure 4. Time delay at first input

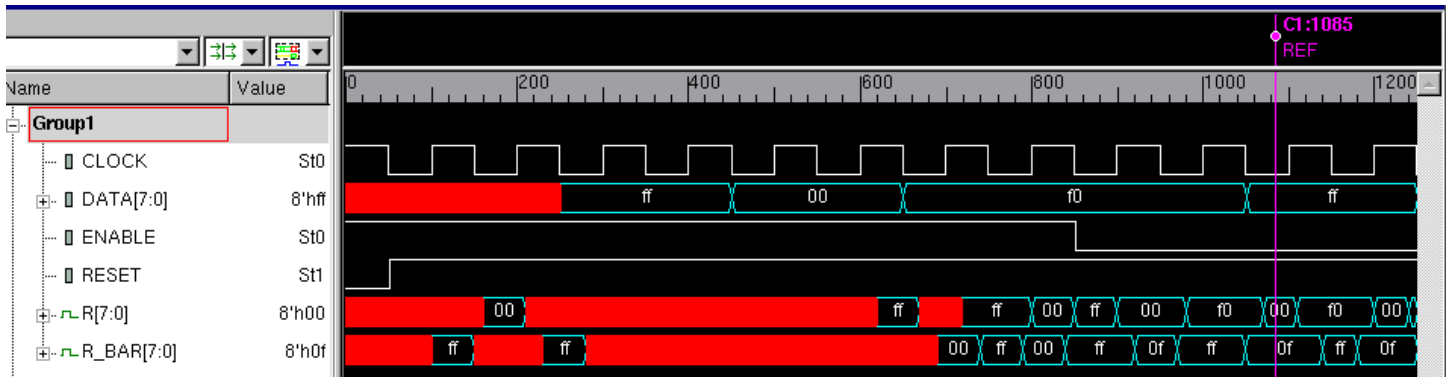


Looking closer at figure 4, the maximum time delay is seen. The DATA=FF input is followed by R = FF and R_BAR = 00 at 109 ns. The max time delay simulated by the circuit is 49 ns. The max operating frequency of the circuit is calculated as follows.

$$F = \frac{1}{T} = \frac{1}{49 \text{ ns}} = 20.408 \text{ MHz}$$

The simulated operating frequency is lower than our calculated because the simulation accounts for the feedback and stabilization of the output.

Figure 5. Input delay of 20 ns



Looking closer at figure 5, the max operating frequency was exceeded by setting the delay between inputs by only 20 ns. Looking at the results of the waveform, the FF input is able to propagate; However, after inputting the DATA = 00 and DATA = F0, the output never stabilizes and begins oscillating between F0 and 00.

```

/*=====
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=====
TB_REGISTER.v
GOALS
- stimulate parallel registers (DATA[7:0] ==> R[7:0])
- stimulate a clock ( #5 CLK = ~ CLK)
- stimulate a reset (RST = 0)
- stimulate enable vs disable
- account for time delay of output and calculate frequency
=====*/
`timescale 1 ns / 100 ps;
`define ALL_ONE DATA = 8'b11111111;
`define ALL_ZERO DATA = 8'b00000000;
`define LSB_HALF_ZERO DATA = 8'b11110000;

module TB_REGISTER ();
    parameter SIZE = 8,
           DELAY = 50;
    reg CLOCK, RESET, ENABLE;
    reg [SIZE - 1: 0] DATA;
    wire [SIZE - 1: 0] R,R_BAR;
    //REGISTER(R,R_BAR,DATA,ENA,CLK,RST)
    REGISTER UUT (R,R_BAR,DATA,ENABLE,CLOCK,RESET);
    //CLOCK INPUT
    always begin
        #5 CLOCK = ~CLOCK;
    end
    initial begin
        $vcdpluson;
        RESET = 0; ENABLE = 1;CLOCK = 1;
        #5.1 RESET = 1;
        #DELAY `ALL_ONE
        #DELAY `ALL_ZERO
        #DELAY `LSB_HALF_ZERO
        #DELAY ENABLE = 0;
        #DELAY `ALL_ONE
        #DELAY $finish;
    end
end
endmodule

```

```

/*=====
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=====
SR_LATCH.sv
Q = ~(S0 & R0 & Q_NOT);
Q_NOT = ~(R1 & R0 & Q);
=====*/

`timescale 1ns / 100ps
`ifndef SINGLE
    `include "DELAYS.v"
`endif

module SR_LATCH(Q, Q_NOT, S0, S1, R0,R1);
    parameter NAND1_DELAY = 3.0;
    output wire Q,Q_NOT;
    input S0,S1,R0,R1;
    nand #3.0 (Q_NOT,Q,R1,R0);
    nand #NAND1_DELAY (Q,S0,S1,Q_NOT);
endmodule

```

```

/*=====
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=====
DFF.v
3 instances of SR_LATCH
connections
CLEAR ==>> R0 of L0      CLOCK ==>> R1 of L0
CLEAR ==>> R0 of L1      CLOCK ==>> S1 of L1
CLEAR ==>> R0 of L2      DATA ==>> R1 of L1
L0 ==>> S0 of L2      L1 ==>> R1 of L2
L0 ==>> S0 of L1      L1_NOT => S0 of L0
=====*/

`timescale 1 ns / 100 ps
`ifndef SINGLE
    `include "DELAYS.v"
`endif
module DFF(Q,QBAR,CLOCK,DATA,CLEAR);
    output Q,QBAR;
    input CLOCK,DATA,CLEAR;

    wire `PRIMARY Q, QBAR;
    wire `FANOUT1 CBAR, CLR;
    wire `FANOUT1 CLKBAR, CLK;
    wire `FANOUT1 DBAR, D;
    wire `FANOUT3 S, SBAR, R, RBAR;

    //Buffers
    not `SINGLE (CBAR,CLEAR);
    not `SINGLE (CLR,CBAR);
    not `SINGLE (CLKBAR,CLOCK);
    not `SINGLE (CLK,CLKBAR);
    not `SINGLE (DBAR,DATA);
    not `SINGLE (D, DBAR);

    //SR_LATCH(Q, Q_NOT, S2, S1, R2,R1)
    SR_LATCH #(2.0) L0(S,SBAR,CLR,CLK,RBAR,1'b1);    // Overwrite first
parameter
    SR_LATCH L1(R,RBAR,S,CLK,CLR,D);
    SR_LATCH #(2.0) L2(Q,QBAR,S,1'b1,CLR,R);        // 1'b1 logic high
endmodule

```

```

//=====
// Ridge Tejuco - CSUN
//=====
// LAB 1
// MUX2_1.v
// September 5, 2019
//=====
`timescale 1 ns / 100 ps
`ifndef SINGLE
    `include "DELAYS.v"
`endif
module MUX2_1(OUT, A, B, SEL);
    //Port declarations
    output OUT;
    input A, B, SEL;

    //Internal variable declarations
    wire `FANOUT1 A1,B1,SEL_N;
    wire `SINGLE OUT;

    //The netlist=====
    not `SINGLE (SEL_N, SEL);

    and `DOUBLE (A1, A, SEL);        //A1 = A and SEL and ENA;

    and `DOUBLE (B1,B,SEL_N);        //B1 = B and SEL_N and ENA;

    or `DOUBLE (OUT,A1,B1);          //OUT = A1 or B1;
endmodule
//=====

```



```

/*=====
CSUN - Experiment 3
Ridge Tejuco
SEPT 19, 2019
=====
REGISTER.v
INPUTS: DATA[0],ENA,CLK,RST
RST => CLEAR of DFF
CLK => CLOCK of DFF
ENA => SEL of MUX
DATA[i - 1] => B of MUX
R[i] => A of MUX
instances of MUX2_1.v and DFF.v
=====*/
`timescale 1 ns / 100 ps;
module REGISTER(R,R_BAR,DATA,ENA,CLK,RST);
    parameter SIZE = 8;
    genvar index;
    input ENA,CLK,RST;
    input wire [SIZE - 1:0] DATA;
    output wire [SIZE - 1:0] R,R_BAR;
    wire [SIZE - 1:0] MUX2_1OUT;

    generate
    for(index = 0; index < SIZE; index=index+1) begin : MUX_LIST
        MUX2_1 MUX0(MUX2_1OUT[index],DATA[index],R[index],ENA);
    end
    for(index = 0; index < SIZE; index=index+1) begin : DFF_LIST
        DFF DFF0(R[index],R_BAR[index],CLK,MUX2_1OUT[index],RST);
    end
    endgenerate
endmodule

```