Machine Learning Project - Cousera Week 4

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1. Overview

2. Data Exploratory Analysis

2.1 Data Loading

The tarining dan test dataset is provided by the data provider and we going to download both dataset form the url (https://d396qusza40orc.cloudfront.net/predmachlearn/).

```
# set the URL for the download
url_train_data <- "https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv"
url_test_test <- "https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv"

file_training_set = file.path("dataset","pml-training.csv")

file_testing_set = file.path("dataset","pml-testing.csv")

# download the datasets
if (!file.exists(file_training_set) || !file.exists(file_testing_set)){
    if(!dir.exists(file.path("dataset"))){
        dir.create("dataset")
    }

    download.file(url_train_data, file_training_set, method="curl")
    download.file(url_test_test, file_testing_set, method="curl")
}

train.dataset.raw <- read.csv(file_training_set, na.strings = c("NA", ""))
test.dataset.raw <- read.csv(file_testing_set, na.strings = c("NA", ""))</pre>
```

2.2 Exploring and Cleansing

The downloaded dataset have the same variable which is 160 and difference numbers of observation data. The training dataset have 19622 observations data and the test dataset 20 have observations data. It is normal practices to have training dataset is larger than the test dataset.

There are (160) variable (predictors) but we only need a few which will contribute to the accuracy of our prediction model later on. Referring to *Appendix A - Dataset Structure for Raw Dataset*, we found out there are a lot of variable contain only NA, #DIV/0! which is need to be remove from the dataset. There are 7 variables is used for data identification such as X, user_name, raw_timestamp_part_1, raw_timestamp_part_2, cvtd_timestamp, new_window and num_window and need to be remove as well.

```
##Remove NA column & column 1-7 as identifier column
train.dataset.clean <- train.dataset.raw[, colSums(is.na(train.dataset.raw)) == 0]
train.dataset.clean <- train.dataset.clean[, -c(1:7)]

test.dataset.clean <- test.dataset.raw[, colSums(is.na(test.dataset.raw)) == 0]
test.dataset.clean <- test.dataset.clean[, -c(1:7)]</pre>
```

Now, we only have 53 variable for both datasets and store it in the new data frame known as train.dataset.clean & test.dataset.clean. Detail dataset structure please refer to $Appendix\ B$ - $List\ of\ Variable\ for\ Clean\ Dataset$

Exploring the classes data it shows that the *classe* A have more records compare to other classes. Based on the Appendix C - Histrogram and the table below classe A have more 1000 records compared to other classes.

```
table(train.dataset.clean$classe)
##
## A B C D E
```

3. Building Prediction Model

5580 3797 3422 3216 3607

The clean training dataset (train.dataset.clean) is split into two (2) partition:

- 1. Training Set (trainset) 70%
- 2. Cross Validation Set (crossvalidationset) 30%

The Training set mention above will be fit into Random Forest Algorithm to create a prediction model which will be used to make a prediction. The prediction model information can be referred on Appendix D - Prediction Model Summary The other sub-training set ($Cross \ Validation$) will be used to evaluate the prediction model accuracy.

3.1 Data Partioning

```
inTrain <- createDataPartition(y=train.dataset.clean$classe, p=0.7, list = FALSE)
trainset <- train.dataset.clean[inTrain,]
crossvalidationset <- train.dataset.clean[-inTrain,]</pre>
```

3.2 Random Forest

```
set.seed(1235)

model.fit <- randomForest(classe ~ ., data=trainset, method="class", importance=TRUE, proximity=TRUE, n
rf.predict <- predict(model.fit, crossvalidationset)
confusion.matrix <- confusionMatrix(rf.predict, crossvalidationset$classe)</pre>
```

The cross validation check shows that the accuracy is 99%. The detail can be referred at Appendix E - Confusion Matrix Output.

4. Applying Model to Test Data

Fit the clean test dataset into the prediction model and print the output.

```
final.predict <- predict(model.fit, test.dataset.clean)
final.predict</pre>
```

```
## 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 ## B A B A A E D B A A B C B A E E A B B B ## Levels: A B C D E
```

Refereces

Ugulino, W.; Cardador, D.; Vega, K.; Velloso, E.; Milidiu, R.; Fuks, H. Wearable Computing: Accelerometers' Data Classification of Body Postures and Movements. Proceedings of 21st Brazilian Symposium on Artificial Intelligence. Advances in Artificial Intelligence - SBIA 2012. In: Lecture Notes in Computer Science. , pp. 52-61. Curitiba, PR: Springer Berlin / Heidelberg, 2012. ISBN 978-3-642-34458-9. DOI: 10.1007/978-3-642-34459-6_6.

Appendixies

Appendix A - Dataset Structure for Raw Dataset

```
str(train.dataset.raw)
                 19622 obs. of 160 variables:
## 'data.frame':
                          : int 1 2 3 4 5 6 7 8 9 10 ...
## $ X
                          : Factor w/ 6 levels "adelmo", "carlitos", ...: 2 2 2 2 2 2 2 2 2 ...
## $ user name
## $ raw_timestamp_part_1
                          : int 1323084231 1323084231 1323084231 1323084232 1323084232 1323084232
## $ raw_timestamp_part_2
                          : int 788290 808298 820366 120339 196328 304277 368296 440390 484323 484
                          : Factor w/ 20 levels "02/12/2011 13:32",...: 9 9 9 9 9 9 9 9 9 9 ...
## $ cvtd_timestamp
## $ new_window
                          : Factor w/ 2 levels "no", "yes": 1 1 1 1 1 1 1 1 1 1 ...
## $ num_window
                               11 11 11 12 12 12 12 12 12 12 ...
## $ roll_belt
                          : num 1.41 1.41 1.42 1.48 1.48 1.45 1.42 1.42 1.43 1.45 ...
                          : num 8.07 8.07 8.07 8.05 8.07 8.06 8.09 8.13 8.16 8.17 ...
## $ pitch belt
## $ yaw_belt
                          : num -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 ...
                          : int 3 3 3 3 3 3 3 3 3 3 ...
## $ total_accel_belt
## $ kurtosis_roll_belt
                          : Factor w/ 396 levels "-0.016850", "-0.021024",..: NA NA NA NA NA NA NA NA NA
                          : Factor w/ 316 levels "-0.021887", "-0.060755", ...: NA NA NA NA NA NA NA NA NA
## $ kurtosis picth belt
## $ kurtosis_yaw_belt
                          : Factor w/ 1 level "#DIV/O!": NA ...
## $ skewness_roll_belt
                          : Factor w/ 394 levels "-0.003095", "-0.010002", ...: NA NA NA NA NA NA NA NA NA
                          ## $ skewness_roll_belt.1
## $ skewness_yaw_belt
                          : Factor w/ 1 level "#DIV/O!": NA ...
## $ max_roll_belt
                          : num NA NA NA NA NA NA NA NA NA ...
## $ max_picth_belt
                          : int NA NA NA NA NA NA NA NA NA ...
                          ## $ max_yaw_belt
## $ min_roll_belt
                          : num NA NA NA NA NA NA NA NA NA ...
## $ min_pitch_belt
                          : int NA NA NA NA NA NA NA NA NA ...
## $ min_yaw_belt
                          ## $ amplitude_roll_belt
                          : num NA NA NA NA NA NA NA NA NA ...
                          : int NA NA NA NA NA NA NA NA NA ...
## $ amplitude_pitch_belt
## $ amplitude_yaw_belt
                          ## $ var_total_accel_belt
                          : num NA NA NA NA NA NA NA NA NA ...
## $ avg_roll_belt
                          : num NA NA NA NA NA NA NA NA NA ...
## $ stddev_roll_belt
                          : num NA NA NA NA NA NA NA NA NA ...
## $ var_roll_belt
                          : num NA NA NA NA NA NA NA NA NA ...
## $ avg_pitch_belt
                          : num NA NA NA NA NA NA NA NA NA ...
## $ stddev_pitch_belt
                          : num NA NA NA NA NA NA NA NA NA ...
## $ var_pitch_belt
                          : num NA NA NA NA NA NA NA NA NA ...
## $ avg_yaw_belt
                          : num NA NA NA NA NA NA NA NA NA ...
## $ stddev_yaw_belt
                               NA NA NA NA NA NA NA NA NA ...
                          : num
## $ var_yaw_belt
                               NA NA NA NA NA NA NA NA NA ...
                          : num
## $ gyros_belt_x
                          ## $ gyros_belt_y
                          : num 0 0 0 0 0.02 0 0 0 0 0 ...
## $ gyros_belt_z
                               -0.02 -0.02 -0.02 -0.03 -0.02 -0.02 -0.02 -0.02 -0.02 0 ...
                          : num
## $ accel_belt_x
                               -21 -22 -20 -22 -21 -21 -22 -22 -20 -21 ...
                          : int
## $ accel_belt_y
                          : int 4453243424 ...
## $ accel_belt_z
                               22 22 23 21 24 21 21 21 24 22 ...
                          : int
## $ magnet_belt_x
                          : int -3 -7 -2 -6 -6 0 -4 -2 1 -3 ...
```

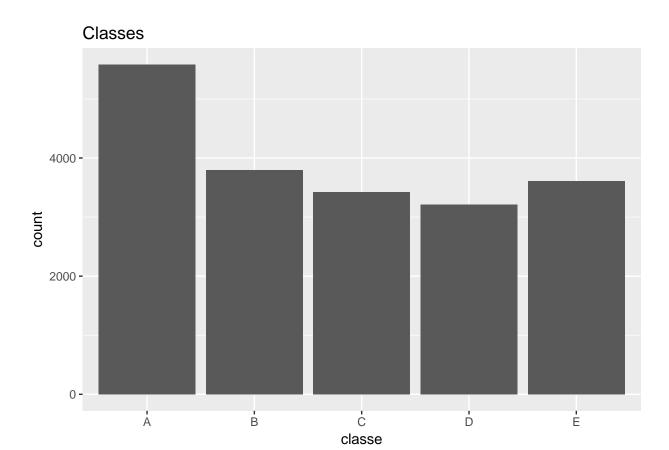
```
$ magnet belt v
                           : int
                                 599 608 600 604 600 603 599 603 602 609 ...
## $ magnet_belt_z
                                 -313 -311 -305 -310 -302 -312 -311 -313 -312 -308 ...
                           : int
                                 ## $ roll arm
                           : num
## $ pitch_arm
                                 22.5 22.5 22.5 22.1 22.1 22 21.9 21.8 21.7 21.6 ...
                           : num
##
   $ yaw arm
                           : num
                                 ## $ total accel arm
                                 34 34 34 34 34 34 34 34 34 ...
                           : int
                                 NA NA NA NA NA NA NA NA NA ...
  $ var accel arm
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
##
   $ avg_roll_arm
                           : num
##
   $ stddev_roll_arm
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ var_roll_arm
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
   $ avg_pitch_arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
##
                                 NA NA NA NA NA NA NA NA NA ...
   $ stddev_pitch_arm
                           : num
   $ var_pitch_arm
##
                                 NA NA NA NA NA NA NA NA NA . . .
                           : num
## $ avg_yaw_arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
## $ stddev_yaw_arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
##
   $ var_yaw_arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
## $ gyros_arm_x
                                 : num
##
                                 0 -0.02 -0.02 -0.03 -0.03 -0.03 -0.03 -0.02 -0.03 -0.03 ...
  $ gyros_arm_y
                           : num
                                 -0.02 -0.02 -0.02 0.02 0 0 0 0 -0.02 -0.02 ...
## $ gyros_arm_z
                           : num
## $ accel_arm_x
                           : int
                                 ## $ accel_arm_y
                           : int
                                 109 110 110 111 111 111 111 111 109 110 ...
## $ accel_arm_z
                                 -123 -125 -126 -123 -123 -122 -125 -124 -122 -124 ...
                           : int
## $ magnet_arm_x
                                 -368 -369 -368 -372 -374 -369 -373 -372 -369 -376 ...
                           : int
                                 337 337 344 344 337 342 336 338 341 334 ...
##
   $ magnet arm y
                           : int
## $ magnet_arm_z
                           : int 516 513 513 512 506 513 509 510 518 516 ...
                           : Factor w/ 329 levels "-0.02438","-0.04190",..: NA NA NA NA NA NA NA NA NA NA
## $ kurtosis_roll_arm
##
                           : Factor w/ 327 levels "-0.00484","-0.01311",..: NA NA NA NA NA NA NA NA NA
   $ kurtosis_picth_arm
                           : Factor w/ 394 levels "-0.01548","-0.01749",..: NA NA NA NA NA NA NA NA NA
## $ kurtosis_yaw_arm
                           : Factor w/ 330 levels "-0.00051", "-0.00696", ...: NA NA NA NA NA NA NA NA NA
## $ skewness_roll_arm
                           : Factor w/ 327 levels "-0.00184","-0.01185",..: NA NA NA NA NA NA NA NA NA
## $ skewness_pitch_arm
                           : Factor w/ 394 levels "-0.00311", "-0.00562", ...: NA NA NA NA NA NA NA NA NA
##
   $ skewness_yaw_arm
   $ max_roll_arm
##
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ max_picth_arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ max_yaw_arm
                           : int
##
   $ min roll arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
## $ min_pitch_arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ min yaw arm
                           : int
                                 NA NA NA NA NA NA NA NA NA ...
## $ amplitude_roll_arm
                           : num NA NA NA NA NA NA NA NA NA ...
##
   $ amplitude_pitch_arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
## $ amplitude_yaw_arm
                           : int NA NA NA NA NA NA NA NA NA ...
## $ roll dumbbell
                           : num
                                13.1 13.1 12.9 13.4 13.4 ...
## $ pitch dumbbell
                                 -70.5 -70.6 -70.3 -70.4 -70.4 ...
                           : num
                           : num -84.9 -84.7 -85.1 -84.9 -84.9 ...
##
   $ yaw dumbbell
## $ kurtosis_roll_dumbbell : Factor w/ 397 levels "-0.0035","-0.0073",..: NA NA NA NA NA NA NA NA NA NA
## $ kurtosis_picth_dumbbell : Factor w/ 400 levels "-0.0163","-0.0233",..: NA NA
##
                           : Factor w/ 1 level "#DIV/O!": NA ...
   $ kurtosis_yaw_dumbbell
                          : Factor w/ 400 levels "-0.0082", "-0.0096", ...: NA NA NA NA NA NA NA NA
##
   $ skewness_roll_dumbbell
##
  $ skewness_pitch_dumbbell : Factor w/ 401 levels "-0.0053","-0.0084",..: NA NA NA NA NA NA NA NA NA NA
## $ skewness_yaw_dumbbell
                           : Factor w/ 1 level "#DIV/O!": NA ...
## $ max_roll_dumbbell
                           : num NA NA NA NA NA NA NA NA NA ...
## $ max_picth_dumbbell
                           : num NA NA NA NA NA NA NA NA NA ...
                           ## $ max_yaw_dumbbell
## $ min_roll_dumbbell
                           : num NA NA NA NA NA NA NA NA NA ...
## $ min pitch dumbbell
                           : num NA NA NA NA NA NA NA NA NA ...
```

Appendix B - List of Variable for Clean Dataset

```
names(train.dataset.clean)
   [1] "roll_belt"
                                "pitch_belt"
                                                        "yaw_belt"
  [4] "total_accel_belt"
                                "gyros_belt_x"
                                                        "gyros_belt_y"
## [7] "gyros_belt_z"
                                "accel belt x"
                                                        "accel belt y"
## [10] "accel_belt_z"
                                "magnet_belt_x"
                                                        "magnet_belt_y"
                                                        "pitch_arm"
## [13] "magnet_belt_z"
                                "roll_arm"
## [16] "yaw_arm"
                                                        "gyros_arm_x"
                                "total_accel_arm"
## [19] "gyros_arm_y"
                                "gyros_arm_z"
                                                        "accel_arm_x"
## [22] "accel_arm_y"
                                "accel_arm_z"
                                                        "magnet_arm_x"
## [25] "magnet_arm_y"
                                "magnet_arm_z"
                                                        "roll_dumbbell"
                                "yaw_dumbbell"
## [28] "pitch_dumbbell"
                                                        "total_accel_dumbbell"
## [31] "gyros_dumbbell_x"
                                "gyros_dumbbell_y"
                                                        "gyros_dumbbell_z"
## [34] "accel_dumbbell_x"
                                "accel_dumbbell_y"
                                                        "accel_dumbbell_z"
## [37] "magnet_dumbbell_x"
                                                        "magnet_dumbbell_z"
                                "magnet_dumbbell_y"
## [40] "roll_forearm"
                                "pitch_forearm"
                                                        "yaw_forearm"
## [43] "total_accel_forearm"
                                "gyros_forearm_x"
                                                        "gyros_forearm_y"
## [46] "gyros_forearm_z"
                                "accel_forearm_x"
                                                        "accel_forearm_y"
## [49] "accel_forearm_z"
                                "magnet_forearm_x"
                                                        "magnet_forearm_y"
## [52] "magnet_forearm_z"
                                "classe"
```

Appendix C - Histogram

```
ggplot(data = train.dataset.clean, aes(x=classe)) +
    geom_histogram(stat = "count") +
    scale_x_discrete(name = "classe") +
    scale_y_continuous(name = "count") +
    ggtitle("Classes")
```



Appendix D - Prediction Model Summary

```
model.fit
##
## Call:
## randomForest(formula = classe ~ ., data = trainset, method = "class", importance = TRUE, proxis
                 Type of random forest: classification
##
                       Number of trees: 30
##
## No. of variables tried at each split: 7
##
          OOB estimate of error rate: 1.26%
## Confusion matrix:
                     D E class.error
       Α
            В
## A 3892
            9
                 4
                      1
                           0 0.003584229
      19 2608 25
## B
                     2
                          4 0.018811136
                    14
## C
       2
           34 2344
                           2 0.021702838
## D
       2
           2
                31 2212
                           5 0.017761989
                    13 2508 0.006732673
## E
```

Appendix E - Confusion Matrix Output

```
confusion.matrix
```

Confusion Matrix and Statistics

```
##
##
            Reference
## Prediction
                Α
                          С
                               D
                                    Ε
##
           A 1673
                     9
                                    0
                          0
                                0
                                     2
##
           В
                 1 1126
                          12
                                0
##
           С
                 0
                     3 1014
                               20
                                     0
##
           D
                 0
                     1
                          0
                             941
##
           Ε
                     0
                           0
                                3 1080
                 0
##
## Overall Statistics
##
##
                  Accuracy: 0.9913
##
                    95% CI: (0.9886, 0.9935)
##
       No Information Rate: 0.2845
##
       P-Value [Acc > NIR] : < 2.2e-16
##
##
                     Kappa: 0.989
  Mcnemar's Test P-Value : NA
##
##
## Statistics by Class:
##
##
                        Class: A Class: B Class: C Class: D Class: E
## Sensitivity
                                  0.9886
                                           0.9883
                                                     0.9761
                                                              0.9982
                         0.9994
## Specificity
                         0.9979
                                  0.9968
                                           0.9953
                                                     0.9998
                                                              0.9994
## Pos Pred Value
                         0.9946 0.9869
                                           0.9778
                                                    0.9989
                                                              0.9972
## Neg Pred Value
                         0.9998 0.9973
                                           0.9975
                                                    0.9953
                                                              0.9996
## Prevalence
                         0.2845
                                 0.1935
                                           0.1743
                                                    0.1638
                                                              0.1839
## Detection Rate
                         0.2843
                                 0.1913
                                           0.1723
                                                    0.1599
                                                              0.1835
## Detection Prevalence
                         0.2858 0.1939
                                           0.1762
                                                     0.1601
                                                              0.1840
## Balanced Accuracy
                         0.9986
                                  0.9927
                                           0.9918
                                                     0.9880
                                                              0.9988
```