CSE 440: Artificial Intelligence, North South University

Quiz-1, Fall 2022

06/11/2022

Full Marks: 20

Time: 25 mins

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For Questions 1-3, consider an intelligent carom-playing robot (a robot, NOT just a software). For this robot and its task environment, answer the following questions and justify your answers

Is this a fully observable or partially observable environment? Justify your answer.

For each step of throwing coin, the churchians require force of throwing, angle of throwing, friction in between caron coins and with caron board. The only uncertainty is when a sudden wind (from an open window etc) blows, coursing more than there average cur resistance. To autrome is uncertain, partially observable 2. Is this a state or dynamic environment? Justify your answer. The environment is static. Because all of the other cains

are stationary, except the throwing coins and coins that are pushed by throwing coin.

3. Is this an episodic or sequential environment? Justify your answer

The environment is expiradic. The consequence of throwing coin impacts from one step to another. The outcome of the previous step affects next step, and

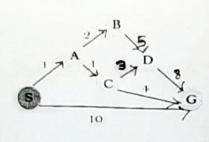
Question 4: Give an example of a goal-based agents.

A goal-based agent can be a simple AI map that uses the arrest appropriate search approaches to find Question 5: Is A* search optimal? If so, under what condition? Yes, A* is optimal. At is optimal of only if the heuristic cost, h(n), is less

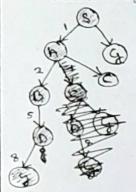
than actual cost.

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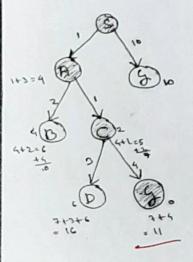
For Questions 6 and 7: Suppose that you need to find a path between 'S' and 'G' in the given graph. The number attached to each edge in the graph represents the actual cost of traversing the edge. The heuristic cost from each node to G is given in the table.

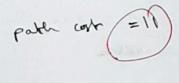


State	h(n)
s	5
Α .	3
В	4
C	2
D	6
G	0



7. Simulate A* Search for this task. Clearly show your work including the resulting tree, the order of visiting the nodes. Finally calculate the total path cost.





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