

# **Linear Algebra and Applications**

## **Homework #09**

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1(a) Linear independence of  $\sin t$ ,  $\cos t$  &  $1$ :

we check if there exists constants

$c_1, c_2, c_3$  (all non-zero) such that:

$$c_1 \sin t + c_2 \cos t + c_3 \cdot 1 = 0 \quad \text{for all } t$$

Now

$$1 = \sin t + \cos t$$

So,

$$c_1 \sin t + c_2 \cos t + c_3 (\sin t + \cos t) = 1$$

$$\Rightarrow (c_1 + c_3) \sin t + (c_2 + c_3) \cos t = 1$$

For this to hold for all  $t$ :

$$c_1 + c_3 = 0 \quad \& \quad c_2 + c_3 = 0$$

if  $c_3 = 1$ ,

$$c_1 = -1, \quad c_2 = -1$$

So, a non-trivial solution exists

$$-\sin t - \cos t + 1 = 0$$

Not linearly independent

1(b)

Let, for  $a, b, c$  the linear combination is,

$$a \sin t + b \cos t + c \sin t = 0 \quad (\text{for all } t)$$

for  $t=0$ :

$$0 + b + 0 = 0$$

$$b = 0$$

for  $t = \pi/2$ :

$$a + 0 + c = 0$$

$$a + c = 0$$

for  $t = \pi/6$ :

$$\frac{a}{4} + b \frac{3}{4} + \frac{c}{2} = 0$$

$$\Rightarrow -\frac{c}{4} + \frac{c}{2} = 0$$

$$\Rightarrow \frac{c}{4} = 0$$

$$\begin{bmatrix} b = 0 \\ a = -c \end{bmatrix}$$

$c = 0$

$$\Rightarrow a + c = 0, \quad a = 0$$

So, only solution exists when

$$\boxed{a = b = c = 0}$$

linearly independent

## Problem 2

The given  $(n+2) \times (n+2)$  matrix is a block diagonal matrix, with

① a  $2 \times 2$  block matrix at first.  $\begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$

② a  $n \times n$  diagonal matrix later.

The determinant of a block diagonal matrix is the product of the determinants of its diagonal blocks.

So,

$$\det(A) = \det \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix} \cdot \det \begin{bmatrix} 1 & \dots & 0 \\ & 2 & \\ & & \ddots & \\ 0 & & & n \end{bmatrix}$$

$$= (1-4) \cdot (1 \cdot 2 \cdot 3 \cdot \dots \cdot n)$$

$$\boxed{\det(A) = (-3) n!}$$

Problem 3:-

we can write,

$$\frac{d}{dt}V = AV \quad \text{--- (i)} \quad \left| \begin{array}{l} \text{where, } A = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} \\ \dot{V}(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \end{array} \right.$$

eigenvalue of A:

$$\det(A - \lambda I) = 0$$

$$\Rightarrow \lambda^2 - \sqrt{2}\lambda + 1 = 0$$

$$\lambda_{1,2} = \frac{\sqrt{2} \pm i\sqrt{2}}{2} = \cos \frac{\pi}{4} \pm i \sin \frac{\pi}{4} = e^{\pm i \frac{\pi}{4}}$$

we can write:

$$A = C^{-1} \Lambda C$$

$$AV = C^{-1} \Lambda C V$$

where,

$$C = [c_1, c_2]$$

$c_1, c_2$  are the eigenvectors

$$\Lambda = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$$

Now, from (1),

$$\frac{d}{dt} v = \Lambda v$$

$$\Rightarrow C^{-1} \frac{d}{dt}(v) = C^{-1} \Lambda v$$

$$= C^{-1} \Lambda C C^{-1} v \quad \left| \quad C C^{-1} = I \right.$$

$$= (C^{-1} \Lambda C) C^{-1} v$$

$$= \Lambda C^{-1} v \quad \left| \quad \begin{array}{l} \Lambda = C^{-1} \Lambda C \\ \Lambda = C^{-1} \Lambda C \end{array} \right.$$

$$\underline{\text{So,}} \quad \frac{d}{dt}(C^{-1} v) = \Lambda (C^{-1} v)$$

$$\text{Let, } C^{-1} v = u$$

$$\text{then } \frac{d}{dt}(u) = \Lambda u$$

$$\text{Now, } \Lambda = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} = \begin{bmatrix} e^{\frac{i\pi}{4}} & 0 \\ 0 & e^{-\frac{i\pi}{4}} \end{bmatrix}$$



$$\underline{\text{So,}} \quad \frac{d}{dt}(V) = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} V$$

$$V = \begin{bmatrix} a e^{\lambda_1 t} \\ b e^{\lambda_2 t} \end{bmatrix}$$

$$= \begin{bmatrix} e^{\lambda_1 t} & 0 \\ 0 & e^{\lambda_2 t} \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

$$\& \quad C^{-1} V = U$$

$$V = C U \quad \dots \textcircled{2}$$

Now, for eigenvectors:

$$\underline{\lambda_1} : (A - \lambda_1 I) C_1 = 0$$

$$\Rightarrow \frac{1}{\sqrt{2}} \begin{bmatrix} 1 - (1+i) & -1 \\ 1 & 1 - (1+i) \end{bmatrix} \begin{bmatrix} C_{11} \\ C_{12} \end{bmatrix} = 0$$

$$\Rightarrow \frac{1}{2} \begin{bmatrix} -i & -1 \\ 1 & -i \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \Rightarrow$$

$$c_1 = \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

$\lambda_2$ :

$$(A - \lambda_2 I) c_2 \Rightarrow$$

$$\Rightarrow \frac{1}{\sqrt{2}} \begin{bmatrix} 1 - (1-i) & -1 \\ 1 & 1 - (1-i) \end{bmatrix} \begin{bmatrix} c_{21} \\ c_{22} \end{bmatrix} \Rightarrow$$

$$c_2 = \begin{bmatrix} 1 \\ i \end{bmatrix}$$

$$\text{So, } C = \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix} \text{ \& } C^{-1} = \frac{1}{2i} \begin{bmatrix} i & -1 \\ i & 1 \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} 1 & i \\ 1 & -i \end{bmatrix}$$



from (2) →

$$\dot{V} = C V$$

$$= \begin{bmatrix} 1 & i \\ -i & i \end{bmatrix} \begin{bmatrix} a e^{\lambda_1 t} \\ b e^{\lambda_2 t} \end{bmatrix} \quad \dots (3)$$

Now,

$$V[0] = C V[0]$$

$$\Rightarrow V[0] = C^{-1} V[0]$$

$$= \frac{1}{2} \begin{bmatrix} 1 & i \\ 1 & -i \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

So,

$$V = \begin{bmatrix} e^{\lambda_1 t} & 0 \\ 0 & e^{\lambda_2 t} \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

$$V[0] = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 1/2 \\ 1/2 \end{bmatrix}$$

So,  $a = \frac{1}{2}, \quad b = \frac{1}{2}$

From (3)  
Now,

$$V = e^U$$

$$= \frac{1}{2} \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix} \begin{bmatrix} e^{\lambda_1 t} \\ e^{\lambda_2 t} \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} e^{\lambda_1 t} + e^{\lambda_2 t} \\ -ie^{\lambda_1 t} + ie^{\lambda_2 t} \end{bmatrix}$$

Now,

$$\begin{aligned} e^{\lambda_1 t} &= e^{(\alpha + i\alpha)t} = e^{\alpha t} \cdot e^{i\alpha t} \\ e^{\lambda_2 t} &= e^{(\alpha - i\alpha)t} = e^{\alpha t} \cdot e^{-i\alpha t} \end{aligned} \quad \left| \quad \alpha = \frac{1}{\sqrt{2}} \right.$$

$$e^{\lambda_1 t} = e^{\alpha t} (\cos(\alpha t) + i \sin(\alpha t))$$

$$e^{\lambda_2 t} = e^{\alpha t} (\cos(\alpha t) - i \sin(\alpha t))$$

So,  $e^{\lambda_1 t} + e^{\lambda_2 t} = 2e^{\alpha t} \cdot \cos \alpha t$

$$e^{\lambda_1 t} - e^{\lambda_2 t} = 2ie^{\alpha t} \cdot \sin \alpha t$$

$$\text{So, } V = \frac{1}{2} \begin{bmatrix} 2e^{\alpha t} \cdot \cos \alpha t \\ -i \cdot 2i \cdot e^{\alpha t} \cdot \sin \alpha t \end{bmatrix}$$

$$= e^{\alpha t} \begin{bmatrix} \cos \alpha t \\ \sin \alpha t \end{bmatrix}$$

$$\alpha = \frac{1}{\sqrt{2}}$$

$$V(t) = e^{\frac{t}{\sqrt{2}}} \begin{bmatrix} \cos \frac{t}{\sqrt{2}} \\ \sin \frac{t}{\sqrt{2}} \end{bmatrix}$$

Problem 4:-

Given  $A = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$

Eigenvalues of A:-

$$\det(A - \lambda I) = 0$$

$$\Rightarrow \lambda^2 - \sqrt{2}\lambda + 1 = 0$$

$$\lambda_{1,2} = \frac{1}{\sqrt{2}} \pm \frac{i}{\sqrt{2}}$$

$$= \cos \frac{\pi}{4} \pm i \sin \frac{\pi}{4}$$

$$= e^{\pm i \frac{\pi}{4}}$$

eigenvectors:-

Let  $\underline{c}_1, \underline{c}_2$  eigenvectors of A

for,  $\lambda = \frac{1}{\sqrt{2}} + \frac{i}{\sqrt{2}}$ ,

$$\frac{1}{\sqrt{2}} \begin{bmatrix} -i & -1 \\ 1 & -i \end{bmatrix} \underline{c}_1 = 0$$

$$\underline{c}_1 = \begin{bmatrix} 1 \\ -i \end{bmatrix}$$



$$\text{for } \lambda_2 = \frac{1}{\sqrt{2}} - \frac{i}{\sqrt{2}}, \quad \frac{1}{\sqrt{2}} \begin{bmatrix} i & -1 \\ 1 & i \end{bmatrix} \zeta_2 = 0$$

$$\zeta_2 = \begin{bmatrix} 1 \\ i \end{bmatrix}$$

$$C = [\zeta_1 \quad \zeta_2] = \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix}$$

$$C^{-1} = \frac{1}{2i} \begin{bmatrix} i & -1 \\ i & 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & i \\ 1 & -i \end{bmatrix}$$

Now,

$$A = C D C^{-1}$$

$$A^N = C D^N C^{-1}$$

$$D = \begin{bmatrix} e^{i\pi/4} & 0 \\ 0 & e^{-i\pi/4} \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix} \begin{bmatrix} e^{i\pi/4} & 0 \\ 0 & e^{-i\pi/4} \end{bmatrix}^N \begin{bmatrix} 1 & i \\ 1 & -i \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix} \begin{bmatrix} e^{iN\pi/4} & 0 \\ 0 & e^{-iN\pi/4} \end{bmatrix} \begin{bmatrix} 1 & i \\ 1 & -i \end{bmatrix}$$



$$= \frac{1}{2} \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix} \begin{bmatrix} e^{i\left(\frac{N\pi}{4}\right)} & i e^{i\left(\frac{N\pi}{4}\right)} \\ e^{-i\left(\frac{N\pi}{4}\right)} & -i e^{-i\left(\frac{N\pi}{4}\right)} \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} e^{i\frac{N\pi}{4}} + e^{-i\frac{N\pi}{4}} & i\left(e^{i\frac{N\pi}{4}} - e^{-i\frac{N\pi}{4}}\right) \\ -i\left(e^{i\frac{N\pi}{4}} - e^{-i\frac{N\pi}{4}}\right) & e^{i\frac{N\pi}{4}} + e^{-i\frac{N\pi}{4}} \end{bmatrix}$$

$$= \begin{bmatrix} \cos\left(\frac{N\pi}{4}\right) & -\sin\left(\frac{N\pi}{4}\right) \\ \sin\left(\frac{N\pi}{4}\right) & \cos\left(\frac{N\pi}{4}\right) \end{bmatrix}$$

(Ans)

using the identity,

$$\begin{cases} \frac{e^{it} + e^{-it}}{2} = \cos t \\ \frac{e^{it} - e^{-it}}{2i} = \sin t \end{cases}$$

Problem 5:

Given  $A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & -1 \\ 0 & 1 & 1 \end{bmatrix}$

Let,  $a_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ ,  $a_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ ,  $a_3 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$

Using Gram-Schmidt orthogonalization:

$$u_1 = a_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$q_1 = \frac{u_1}{\|u_1\|} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

orthogonalizing  $a_2$ : projection of  $a_2$  on  $q_1$ :

$$\text{proj}_{q_1} a_2 = (a_2 \cdot q_1) q_1$$

$$= \left( \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right) q_1$$

$$= \sqrt{2} \, r_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

Now,

$$u_2 = a_2 - \text{proj}_{r_1} a_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$r_2 = \frac{u_2}{\|u_2\|} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

orthogonalizing  $a_3$ : projection of  $a_3$  on  $r_1$  &  $r_2$ :

$$\text{proj}_{r_1} a_3 = (a_3 \cdot r_1) \cdot r_1$$

$$= \left( \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \cdot \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right) r_1$$

$$= \frac{1}{2} r_1$$

$$\text{proj}_{r_2} a_3 = \left( \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right) r_2$$

$$= r_2$$

$$u_3 = a_3 - \text{proj}_{q_1} a_3 - \text{proj}_{q_2} a_3$$

$$= \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$= \frac{1}{2} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$$

$$\text{So, } q_3 = \frac{u_3}{\|u_3\|} = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$$

$$\text{So, } Q = [q_1 \ q_2 \ q_3] = \begin{bmatrix} \frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ 0 & 1 & 0 \end{bmatrix}$$

For P:

$$P_{ij} = a_j \cdot q_i \quad (\text{for } i \leq j), \text{ otherwise } 0$$

$$P_{11} = a_1 \cdot q_1 = \sqrt{2}$$

$$P_{12} = a_2 \cdot q_1 = \sqrt{2}$$

$$P_{13} = a_3 \cdot q_1 = \frac{1}{\sqrt{2}}$$

$$P_{22} = 1$$

$$P_{23} = 1$$

$$P_{33} = \frac{1}{\sqrt{2}}$$



$$\underline{\text{So}} \quad P = \begin{bmatrix} \sqrt{2} & \sqrt{2} & \frac{1}{\sqrt{2}} \\ 0 & 1 & 1 \\ 0 & 0 & \frac{1}{\sqrt{2}} \end{bmatrix}$$

$$\underline{\text{So}}, A = BP = \begin{bmatrix} \frac{1}{\sqrt{2}} & 0 & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} \sqrt{2} & \sqrt{2} & \frac{1}{\sqrt{2}} \\ 0 & 1 & 1 \\ 0 & 0 & \frac{1}{\sqrt{2}} \end{bmatrix}$$

Problem 6:

(a)

$$A = \begin{bmatrix} 1 & \sqrt{6} \\ \sqrt{6} & 2 \end{bmatrix}$$

Characteristic polynomial:

$$\det(A - \lambda I)$$

$$\Rightarrow \begin{vmatrix} 1-\lambda & \sqrt{6} \\ \sqrt{6} & 2-\lambda \end{vmatrix}$$

$$\Rightarrow (1-\lambda)(2-\lambda) - 6$$

$$\Rightarrow \boxed{\lambda^2 - 3\lambda - 4}$$



(b)

Now,

$$A^2 = \begin{bmatrix} 1 & \sqrt{6} \\ \sqrt{6} & 2 \end{bmatrix} \begin{bmatrix} 1 & \sqrt{6} \\ \sqrt{6} & 2 \end{bmatrix}$$

$$= \begin{bmatrix} 7 & 3\sqrt{6} \\ 3\sqrt{6} & 10 \end{bmatrix}$$

$$A^2 - 3A - 4I = \begin{bmatrix} 7 & 3\sqrt{6} \\ 3\sqrt{6} & 10 \end{bmatrix} - \begin{bmatrix} 3 & 3\sqrt{6} \\ 3\sqrt{6} & 6 \end{bmatrix}$$

$$= \begin{bmatrix} 4 & 0 \\ 0 & 4 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

This result is expected because the characteristic polynomial  $\lambda^2 - 3\lambda - 4$  implies

$A^2 - 3A - 4I = 0$ . This is called Cayley-Hamilton

theorem: every square matrix  $A$  satisfy its own characteristic theorem.