

## Convergence Analysis of Gradient Descent for strongly convex functions $\rightarrow$ Strong Convexity parameter $m$

Assumptions:  $f \in C^2(\mathbb{R}^n)$ ,  $m$ -Strongly Convex  
( $m$ -Smooth)

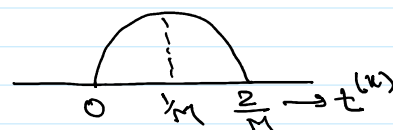
$$\underbrace{mI}_{\text{global bound}} \preceq \nabla^2 f(x) \preceq \underbrace{MI}_{\text{local on the sublevel set}}$$

$$S = \{x: f(x) \leq f(x^{(n)})\}$$

Iteration:  $x^{(k+1)} = x^{(k)} - t^{(k)} \nabla f(x^{(k)})$  for  $t^{(k)}$   
s.t.  $x^{(k+1)} \in \text{dom} f$

Quadratic upper bound  $\forall x \in S$

$$\begin{aligned} f(x^{(k+1)}) &\leq f(x^{(k)}) - t^{(k)} \|\nabla f(x^{(k)})\|_2^2 \\ &\quad + \frac{M t^{(k)^2}}{2} \|\nabla f(x^{(k)})\|_2^2 \\ &= f(x^{(k)}) - \underbrace{\left(-M \frac{t^{(k)^2}}{2} + t^{(k)}\right)}_{\downarrow} \|\nabla f(x^{(k)})\|_2^2 \end{aligned}$$



Exact line Search Analysis

When we do exact line search

$$f(x^{(k+1)}) \leq \min_{t^{(k)}} \left( f(x^{(k)}) - \left( t^{(k)} - m \frac{t^{(k)^2}}{2} \right) \frac{\|\nabla f(x^{(k)})\|_2^2}{2} \right)$$

$t^{(k)} = \frac{1}{m} \star$

$$\textcircled{\star} - f(x^{(k+1)}) \leq f(x^{(k)}) - \frac{1}{2m} \|\nabla f(x^{(k)})\|_2^2$$

Since  $f$  is  $m$ -strongly convex, we know that:

$$f(x^{(k)}) - p^* \leq \frac{1}{2m} \|\nabla f(x^{(k)})\|_2^2$$

Subtract  $p^*$  from both sides of  $\textcircled{\star}$

$$f(x^{(k+1)}) - p^* \leq f(x^{(k)}) - p^* - \frac{1}{2m} \|\nabla f(x^{(k)})\|_2^2$$

$\geq 2m(f(x^{(k)}) - p^*)$

$$f(x^{(k+1)}) - p^* \leq \underbrace{f(x^{(k)}) - p^*}_{\geq \frac{1}{2m} \|\nabla f(x^{(k)})\|_2^2} - \frac{m}{2} \underbrace{(f(x^{(k)}) - p^*)}_{\geq \frac{1}{2m} \|\nabla f(x^{(k)})\|_2^2}$$

$$\Rightarrow f(x^{(k+1)}) - p^* \leq \underbrace{\left(1 - \frac{m}{2}\right)}_{0 \leq C < 1} (f(x^{(k)}) - p^*)$$

If  $\frac{m}{2} = 1 \Rightarrow$  Exact line search gives us the solution in one iteration.

$$f(x^{(k+1)}) - p^* \leq c (f(x^{(k)}) - p^*)$$

Let's recursively apply the above expression from  $k=0$  to  $K$ .

$$f(x^{(K)}) - p^* \leq c^K (f(x^{(0)}) - p^*) \leq \epsilon$$

Fact 1: As  $K \rightarrow \infty$ ,  $f(x^{(K)}) \rightarrow p^*$

Rate of Convergence:

We want  $f(x^{(K)}) - p^* \leq \epsilon$

$$\Leftrightarrow c^K (f(x^{(0)}) - p^*) \leq \epsilon$$

$$\Leftrightarrow c^K \leq \frac{\epsilon}{f(x^{(0)}) - p^*}$$

$$\Leftrightarrow K \ln(c) \leq \ln(\epsilon / (f(x^{(0)}) - p^*))$$

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$$K \leq \frac{\ln(\epsilon / (f(x^{(0)}) - p^*))}{\ln(c)}$$

Ignoring all other constants:  $K = O(\ln(\epsilon))$

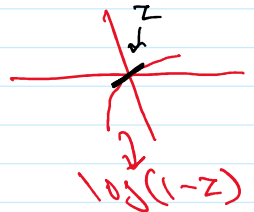
Linear Convergence

Implications: ① As  $\epsilon \downarrow$ ,  $K$  has to increase only logarithmically with  $\epsilon$ .

② As  $f(x^{(0)}) - p^* \uparrow$ ,  $K$  has to increase, but only logarithmically.

③  $K$  is proportional to the Condition number of the problem  $K = M/m \approx$  linearly proportional

$\log(1-z) \approx -z$  when  $z$  is small



Remember:  $c = 1 - \frac{m}{M}$ ; when  $\frac{M}{m}$  is large,  
 $\Rightarrow \frac{m}{M}$  is small

$$\Rightarrow \ln(c) \approx \frac{m}{M}$$

$$\Rightarrow K \leq \left\lceil \ln\left(\frac{6}{f(x^{(0)}) - p^*}\right) \right\rceil \cdot \underbrace{\frac{M}{m}}_{K}$$

Condition number has a fundamental role in determining the performance of gradient descent.

### Analysis of Backtracking line search

There are two key themes for this analysis.

- ① Backtracking line search accepts a step size that is (i)  $t \in [0, \frac{1}{M}]$   
(ii) It is either exactly 1 ✓  
or it is in the interval  $[\frac{\beta}{M}, \frac{1}{M}]$ .

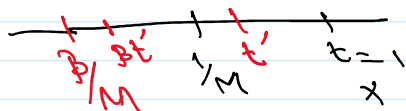
Backtracking evaluation:

Backtracking evaluation:

Accept  $t$  if

$$f(x^{(u+1)}) \leq f(x^{(u)}) - \alpha t \|\nabla f(x^{(u)})\|_2^2$$

for  $\alpha \in (0, 1/2)$



Conclusion:  $f(x^{(u+1)}) \leq f(x^{(u)}) - \min\left\{\alpha, \frac{\alpha\beta}{M}\right\} \|\nabla f(x^{(u)})\|_2^2$

Convergence result:

$$f(x^{(u)}) - p^* \leq C^u (f(x^{(0)}) - p^*)$$

where

$$C = 1 - \min\left\{2m\alpha, 2\alpha\beta \frac{m}{M}\right\}$$

Compare to exact line search:

$$C = 1 - \frac{m}{M}$$

Why should  $\alpha$  be  $\leq 1/2$ ?  $\Rightarrow$  Ensures  $C \in [0, 1)$ .

Exact line search  $C$  is better than backtracking, but both give linear convergence.