

Linear Algebra and Applications

Homework #04

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1(a) Given, $A = \begin{bmatrix} 4 & 1 & 0 \\ 1 & 0 & 2 \\ 0 & 2 & 4 \end{bmatrix}$

Eigenvalues will be the roots of $\det(A - \lambda I) = 0$

Now, $\det(A - \lambda I) = 0$

$$\Rightarrow \det \begin{bmatrix} 4-\lambda & 1 & 0 \\ 1 & -\lambda & 2 \\ 0 & 2 & 4-\lambda \end{bmatrix} = 0$$

$$\Rightarrow (4-\lambda) \det \begin{bmatrix} -\lambda & 2 \\ 2 & 4-\lambda \end{bmatrix} - 1 \det \begin{bmatrix} 1 & 2 \\ 0 & 4-\lambda \end{bmatrix} = 0$$

$$\Rightarrow (4-\lambda)(\lambda^2 - 4\lambda - 4) - 1(4-\lambda) = 0$$

$$\Rightarrow (4-\lambda)(\lambda^2 - 4\lambda - 4) = 0$$

$$\Rightarrow (4-\lambda)(\lambda^2 - 4\lambda - 5) = 0$$

$$\Rightarrow \begin{cases} \lambda_1 = 4 \\ \lambda_2 = 5 \\ \lambda_3 = -1 \end{cases} \text{ eigenvalues}$$

eigenvectors:-

$$A\underline{v} = \lambda \underline{v}$$
$$(A - \lambda I) \underline{v} = \underline{0}$$

for $\lambda = 4$,

$$(A - 4I) \underline{v}_1 = \underline{0}$$

$$\Rightarrow \begin{bmatrix} 0 & 1 & 0 \\ 1 & -4 & 2 \\ 0 & 2 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \underline{0}$$

$$\Rightarrow \begin{cases} x_2 = 0 \\ x_1 - 4x_2 + 2x_3 = 0 \\ 2x_2 = 0 \end{cases} \Rightarrow \begin{cases} x_2 = 0 \\ x_1 = -2x_3 \end{cases}$$

so $\underline{v}_1 =$ scalar multiple of $\begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} \equiv \begin{bmatrix} -2/\sqrt{5} \\ 0 \\ 1/\sqrt{5} \end{bmatrix}$

for $\lambda = 5$

$$(A - 5I) \underline{v}_2 = \underline{0}$$

$$\Rightarrow \begin{bmatrix} -1 & 1 & 0 \\ 1 & -5 & 2 \\ 0 & 2 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \underline{0}$$

$$\Rightarrow \begin{cases} -x_1 + x_2 = 0 \\ x_1 - 5x_2 + 2x_3 = 0 \\ 2x_2 - x_3 = 0 \end{cases} \Rightarrow \begin{cases} x_1 = x_2 \\ -4x_2 + 2x_3 = 0 \\ 2x_2 - x_3 = 0 \end{cases}$$

\Downarrow

$$\begin{cases} x_1 = x_2 \\ x_3 = 2x_2 \end{cases}$$

So $\underline{v}_2 =$ scalar multiple of $\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} \equiv \begin{bmatrix} 1/\sqrt{6} \\ 1/\sqrt{6} \\ 2/\sqrt{6} \end{bmatrix}$

for $\lambda = -1$,

$$(A + I) \underline{v}_3 = 0$$

$$\Rightarrow \begin{bmatrix} 5 & 1 & 0 \\ 1 & 1 & 2 \\ 0 & 2 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

$$\Rightarrow \begin{cases} 5x_1 + x_2 = 0 \\ x_1 + x_2 + 2x_3 = 0 \\ 2x_2 + 5x_3 = 0 \end{cases} \Rightarrow \begin{cases} x_2 = -5x_1 \\ x_3 = -\frac{2}{5}x_2 \\ \quad = +2x_1 \end{cases}$$

So $\underline{v}_3 =$ scalar multiple of $\begin{bmatrix} 1 \\ -5 \\ +2 \end{bmatrix} \equiv \begin{bmatrix} 1/\sqrt{30} \\ -5/\sqrt{30} \\ +2/\sqrt{30} \end{bmatrix}$

eigen values: $\lambda_1 = 4$, $\lambda_2 = 5$, $\lambda_3 = -1$

eigenvector
Corresponding:

$$\underline{u}_1 = \begin{bmatrix} -2/\sqrt{5} \\ 0 \\ 1/\sqrt{5} \end{bmatrix}, \quad \underline{u}_2 = \begin{bmatrix} 1/\sqrt{6} \\ 1/\sqrt{6} \\ 2/\sqrt{6} \end{bmatrix}, \quad \underline{u}_3 = \begin{bmatrix} 1/\sqrt{30} \\ -5/\sqrt{30} \\ -2/\sqrt{30} \end{bmatrix}$$

2(b)

From definition of eigenvectors:

$$\left. \begin{array}{l} A \underline{u}_1 = \lambda_1 \underline{u}_1 \\ A \underline{u}_2 = \lambda_2 \underline{u}_2 \\ A \underline{u}_3 = \lambda_3 \underline{u}_3 \end{array} \right\} \begin{array}{l} A \underline{u}_1 = \lambda_1 \underline{u}_1 \\ A \underline{u}_2 = \lambda_2 \underline{u}_2 \\ A \underline{u}_3 = \lambda_3 \underline{u}_3 \end{array}$$

Written combined,

$$A \begin{bmatrix} \underline{u}_1 & \underline{u}_2 & \underline{u}_3 \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} \begin{bmatrix} \underline{u}_1 & \underline{u}_2 & \underline{u}_3 \end{bmatrix}$$

$$\Rightarrow A C_1 = \Lambda C_1$$

$$\Rightarrow C_1^{-1} A C_1 = \Lambda$$

where, $C_1 = \begin{bmatrix} \underline{u}_1 & \underline{u}_2 & \underline{u}_3 \end{bmatrix} = \begin{bmatrix} -\frac{2}{\sqrt{5}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{30}} \\ 0 & \frac{1}{\sqrt{6}} & -\frac{5}{\sqrt{30}} \\ \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{6}} & \frac{2}{\sqrt{30}} \end{bmatrix}$

Calculating C_1^{-1} explicitly:

$$C_1^{-1} = \frac{1}{\det(C_1)} \text{adj}(C_1)$$

$$\begin{aligned} \det(C_1) &= \left(-\frac{2}{\sqrt{5}}\right) \left(\frac{1}{\sqrt{6}} \cdot \frac{2}{\sqrt{30}} - \left(-\frac{5}{\sqrt{30}}\right) \cdot \frac{2}{\sqrt{6}}\right) \\ &\quad - \frac{1}{\sqrt{6}} \left(0 \cdot \frac{2}{\sqrt{30}} - \left(-\frac{5}{\sqrt{30}}\right) \cdot \frac{1}{\sqrt{5}}\right) \\ &\quad + \frac{1}{\sqrt{30}} \left(0 \cdot \frac{2}{\sqrt{6}} - \frac{1}{\sqrt{6}} \cdot \frac{1}{\sqrt{5}}\right) \\ &= -1 \end{aligned}$$

Each element of cofactor matrix C , is

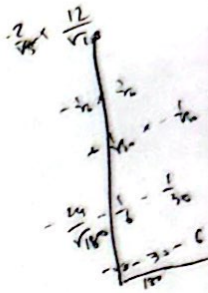
$$C_{ij} = (-1)^{i+j} \det(M_{ij}) \quad \rightarrow \quad \left(C_{11} = +1 \cdot \left(\frac{2}{\sqrt{180}} + \frac{10}{\sqrt{180}} \right) = \frac{12}{\sqrt{180}} \right)$$

M_{ij} is the submatrix obtained by deleting i th row & j th column of C_1

Calculating all, $\text{Cof}(C_1) =$ (similar to C_1)

$$\begin{bmatrix} +\frac{12}{\sqrt{180}} & \frac{5}{\sqrt{150}} & -\frac{1}{\sqrt{30}} \\ 0 & -\frac{5}{\sqrt{150}} & \frac{5}{\sqrt{30}} \\ \frac{6}{\sqrt{180}} & -\frac{10}{\sqrt{150}} & -\frac{2}{\sqrt{30}} \end{bmatrix}$$

$$\text{adj}(C_1) = [\text{Cof}(C_1)]^T$$



So,

$$C_1^{-1} = \frac{1}{\det(C_1)} \text{adj}(C_1)$$

$$= \begin{bmatrix} -\frac{2}{\sqrt{5}} & 0 & \frac{1}{\sqrt{5}} \\ \frac{1}{\sqrt{6}} & +\frac{1}{\sqrt{6}} & +\frac{2}{\sqrt{6}} \\ +\frac{1}{\sqrt{30}} & -\frac{5}{\sqrt{30}} & +\frac{2}{\sqrt{30}} \end{bmatrix}$$

Again, As C_1 is an orthogonal matrix,
(orthonormal)

$$C_1^{-1} = C_1^T$$

A is real & symmetric \rightarrow A has a basis of
orthonormal eigenvectors
 \downarrow

$$C_1^{-1} = C_1^T \leftarrow C_1 \text{ orthonormal matrix}$$

So, we can calculate C_1^{-1} as:

$$C_1^{-1} = C_1^T = \begin{bmatrix} v_1^T \\ v_2^T \\ v_3^T \end{bmatrix} = \begin{bmatrix} -\frac{2}{\sqrt{5}} & 0 & \frac{1}{\sqrt{5}} \\ \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{6}} & -\frac{2}{\sqrt{6}} \\ \frac{1}{\sqrt{30}} & -\frac{5}{\sqrt{30}} & \frac{2}{\sqrt{30}} \end{bmatrix}$$

which is same as before!

1(c) Given, $\frac{d}{dt} u(t) = A_1 u(t)$

$$\Rightarrow C_1^{-1} \frac{d}{dt} u(t) = C_1^{-1} A_1 u(t)$$

$$\Rightarrow \frac{d}{dt} (C_1^{-1} u(t)) = C_1^{-1} A_1 C_1 C_1^{-1} u(t)$$

$$= (C_1^{-1} A_1 C_1) (C_1^{-1} u(t)) \quad [C_1 C_1^{-1} = I]$$

$$\Rightarrow \frac{d}{dt} (v(t)) = \Lambda v(t)$$

where, $v(t) = C_1^{-1} u(t)$

So, differential equation of $v(t)$:

$$\frac{d}{dt} (v(t)) = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} v(t)$$

$$\Rightarrow \begin{bmatrix} v_1'(t) \\ v_2'(t) \\ v_3'(t) \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} \begin{bmatrix} v_1(t) \\ v_2(t) \\ v_3(t) \end{bmatrix}$$

and, $v(0) = C_1^{-1} u(0) = C_1^{-1} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -2\sqrt{5} \\ 1/\sqrt{6} \\ 1/\sqrt{30} \end{bmatrix}$

1(d) from 'C'

$$v_1'(t) = \lambda_1 v_1(t)$$

$$= 4 v_1(t)$$

so $v_1(t) = C_1 e^{4t}$

putting $t=0$, $v_1(0) = C_1 \cdot 1 = C_1$

so $v_1(t) = v_1(0) \cdot e^{4t}$

so $\begin{bmatrix} v_1(t) \\ v_2(t) \\ v_3(t) \end{bmatrix} = v(t) = \begin{bmatrix} e^{4t} & 0 & 0 \\ 0 & e^{5t} & 0 \\ 0 & 0 & e^{-t} \end{bmatrix} \cdot v(0) = \begin{bmatrix} e^{4t} \\ \frac{-2e^{5t}}{\sqrt{5}} \\ e^{-t}/\sqrt{30} \end{bmatrix}$

1(e) Now $v(t) = C_1^{-1} v(t)$

so $v(t) = C_1 v(t)$

$\Rightarrow v(t) = C_1 \begin{bmatrix} e^{4t} & 0 & 0 \\ 0 & e^{5t} & 0 \\ 0 & 0 & e^{-t} \end{bmatrix} v(0)$

$v(t) = C_1 \begin{bmatrix} e^{4t} & 0 & 0 \\ 0 & e^{5t} & 0 \\ 0 & 0 & e^{-t} \end{bmatrix} C_1^{-1} v(0)$

explicitly,

$$v(t) = C_1 v(t)$$

$$= \begin{bmatrix} -\frac{2}{\sqrt{5}} & \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{30}} \\ 0 & \frac{1}{\sqrt{6}} & -\frac{5}{\sqrt{30}} \\ \frac{1}{\sqrt{5}} & \frac{2}{\sqrt{6}} & \frac{2}{\sqrt{30}} \end{bmatrix} \begin{bmatrix} -\frac{2e^{4t}}{\sqrt{5}} \\ \frac{e^{5t}}{\sqrt{6}} \\ \frac{e^{-t}}{\sqrt{30}} \end{bmatrix}$$

Problem 2

2(a)

$$A_2 = \begin{bmatrix} 4 & 1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 4 \end{bmatrix}$$

eigenvalues:

$$\det(A - \lambda I) = 0$$

$$\Rightarrow \det \begin{bmatrix} 4-\lambda & 1 & 0 \\ 1 & -\lambda & -1 \\ 0 & 1 & 4-\lambda \end{bmatrix} = 0$$

$$\Rightarrow (4-\lambda) \det \begin{bmatrix} -\lambda & -1 \\ 1 & 4-\lambda \end{bmatrix} - 1 \cdot \det \begin{bmatrix} 1 & -1 \\ 0 & 4-\lambda \end{bmatrix} = 0$$

$$\Rightarrow (4-\lambda) (\lambda^2 - 4\lambda + 1) - (4-\lambda) = 0$$

$$\Rightarrow (4-\lambda) (\lambda^2 - 4\lambda) = 0$$

$$\Rightarrow \lambda_1 = 4, \lambda_2 = 4, \lambda_3 = 0$$

eigenvectors:

for $\lambda_1 = 4$,

$$A_2 \underline{v}_1 = \lambda_1 \underline{v}_1$$

$$\Rightarrow (A_2 - \lambda_1 I) \underline{v}_1 = 0$$

$$\Rightarrow \begin{bmatrix} 0 & 1 & 0 \\ 1 & -4 & -1 \\ 0 & 1 & 0 \end{bmatrix} \underline{v}_1 = 0$$

$$\Rightarrow \begin{cases} v_2 = 0 \\ v_1 - 4v_2 - v_3 = 0 \\ v_2 = 0 \end{cases} \Rightarrow \begin{cases} v_2 = 0 \\ v_1 = v_3 \end{cases}$$

So, $\underline{v}_1 =$ scalar multiple of $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$

For, $\lambda_2 = 4$, similar analysis for $\lambda_1 = 4$

$$\underline{v}_2 = \underline{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

for, $\lambda_3 = 0$,

$$(A_2 - \lambda_3 I) \underline{v}_3 = 0$$

$$\Rightarrow \begin{bmatrix} 4 & 1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 4 \end{bmatrix} \underline{v}_3 = 0$$

$$\Rightarrow \begin{cases} 4x_1 + x_2 = 0 \\ x_1 - x_3 = 0 \\ x_2 + 4x_3 = 0 \end{cases} \Rightarrow \begin{cases} x_1 = x_3 \\ x_2 = -4x_1 = -4x_3 \end{cases}$$

So, $\underline{v}_3 =$ scalar multiple of $\begin{bmatrix} 1 \\ -4 \\ 1 \end{bmatrix}$

So, we only have two linearly independent

eigenvectors, $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \notin \begin{bmatrix} 1 \\ -4 \\ 1 \end{bmatrix}$, so, A_2 does not

have a full basis of eigenvectors.

(A_2 is 3×3 , so it needs 3 linearly independent eigenvectors to form a basis of eigenvectors)

2(b)

From 2(a)

$$\lambda_3 = 0, \quad \underline{v}_3 = \begin{bmatrix} 1 \\ -4 \\ 1 \end{bmatrix}$$

So, $A_2 \underline{v}_3 = \lambda_3 \underline{v}_3$

$$A_2 \begin{bmatrix} 1 \\ -4 \\ 1 \end{bmatrix} = 0 \cdot \underline{v}_3 = \underline{0} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

So, from definition of nullspace,

$$N(A_2) = \text{span} \left\{ \begin{pmatrix} 1 & -4 & 1 \end{pmatrix}^T \right\}$$

Now, $(A_2 - 4I)^2$:-

$$A_2 - 4I = \begin{bmatrix} 0 & 1 & 0 \\ 1 & -4 & -1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$(A_2 - 4I)^2 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & -4 & -1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & -4 & -1 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & -4 & -1 \\ -4 & 18 & 4 \\ 1 & -4 & -1 \end{bmatrix}$$

for null vector \underline{v} of $(A_2 - 4I)^2$:-

$$(A_2 - 4I)^2 \underline{v} = 0$$

$$\Rightarrow \begin{bmatrix} 1 & -4 & -1 \\ -4 & 18 & 4 \\ 1 & -4 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0$$

$$\Rightarrow \begin{cases} x_1 - 4x_2 - x_3 = 0 \\ -4x_1 + 18x_2 + 4x_3 = 0 \\ x_1 - 4x_2 - x_3 = 0 \end{cases} \quad \text{same}$$

From 1st & 3rd equation, $x_1 = 4x_2 + x_3$

Substituting into 2nd, $-4(4x_2 + x_3) + 18x_2 + 4x_3 = 0$

$$\Rightarrow 0 = 0$$

So, these three equations are linearly dependent.

So, General solution:

$$\underline{x} = \begin{bmatrix} 4x_2 + x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} 4 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

where x_2 & x_3 are scalars.

So, $N((A_2 - 4I)^2) = \text{span} \left\{ (1 \ 0 \ 1)^T, (4 \ 1 \ 0)^T \right\}$

2(c) $\left\{ (1 \ 0 \ 1)^T, (4 \ 1 \ 0)^T \& (1, -4, 1)^T \right\}$ will

form a basis in \mathbb{R}^3 if they are linearly independent of each other.



This will be the case if the matrix form by them is full rank. \longrightarrow Non-singular Matrix \longrightarrow (determinant $\neq 0$)

Now, $M = C_{\text{New}} = \begin{bmatrix} 1 & 4 & 1 \\ 0 & 1 & -4 \\ 1 & 0 & 1 \end{bmatrix}$

$$\det M = 1 \det \begin{bmatrix} 1 & -4 \\ 0 & 1 \end{bmatrix} - 4 \det \begin{bmatrix} 0 & -4 \\ 1 & 1 \end{bmatrix} + 1 \det \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$= 1 - 4(-4) + 1(-1)$$

$$= -16 \neq 0$$

So, Determinant $\neq 0$

↳ Columns are linearly independent

↳ These three vectors form a basis in \mathbb{R}^3 .

Representation of A_2 in M : (A_{new})

$$A_{\text{new}} = M^{-1} A_2 M$$

$$= \begin{bmatrix} 1 & 4 & 1 \\ 0 & 1 & -4 \\ 1 & 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 4 & 1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 4 \end{bmatrix} \begin{bmatrix} 1 & 4 & 1 \\ 0 & 1 & -4 \\ 1 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 4 & 1 \\ 0 & 1 & -4 \\ 1 & 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 4 & 17 & 0 \\ 0 & 4 & 0 \\ 4 & 1 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 4 & 1 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

2(d)

Now,

$$\frac{d}{dt} u(t) = A_2 u(t)$$

$$M^{-1} \frac{d}{dt} u(t) = M^{-1} A_2 u(t)$$

$$\frac{d}{dt} (M^{-1} u(t)) = M^{-1} A_2 M M^{-1} u(t)$$

Let, $v(t) = M^{-1} u(t)$

$$\left\{ \begin{array}{l} M M^{-1} = I \\ M^{-1} A_2 M = A_{\text{New}} \\ M^{-1} u(t) = v(t) \end{array} \right.$$

So, $\frac{d}{dt} v(t) = A_{\text{New}} \cdot v(t)$

$$\frac{d}{dt} v(t) = \begin{bmatrix} 4 & 1 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 0 \end{bmatrix} v(t)$$

$$\begin{bmatrix} v_1'(t) \\ v_2'(t) \\ v_3'(t) \end{bmatrix} = \begin{bmatrix} 4 v_1(t) + v_2(t) \\ 4 v_2(t) \\ 0 \end{bmatrix}$$

So,

$$v_1'(t) = 4 v_1(t) + v_2(t)$$

$$v_2'(t) = 4 v_2(t)$$

And,

$$v(0) = M^{-1} u(0)$$

So, $v_2'(t) = 4 v_2(t)$

$$\therefore v_2(t) = c_2 e^{4t} = v_2(0) e^{4t}$$

and,

$$v_1'(t) = 4v_1(t) + v_2(t)$$

$$= 4v_1(t) + c_2 e^{4t}$$

So, in $v_1(t)$, we will get e^{4t} and $t e^{4t}$ rather than purely $e^{\lambda t}$ (e^{4t}), because A_{new} is not purely diagonal matrix here. A_{new} representation helps us here by decoupling the variable (partially)

Compared to previous problem, A_1 could be fully diagonalized there, so each variable was decoupled from each other there. Now, A_2 is not diagonalizable like A_1 , so we will get term like $e^{\lambda t}$ & $t e^{\lambda t}$ as the variables can't be decoupled fully.