

1.0 Course introduction

Overview for MA930 Data Analysis

Day 1 Basic probability

Day 2 Basic statistics

Day 3 Frequentist statistics

Day 4 Bayesian statistics

Day 5 Basic time-series analysis

Day 6 Spectral methods for time-series analysis

Day 7 Machine-learning approaches to data analysis I

Day 8 Machine-learning approaches to data analysis II

Day 9 Class test and vivas

Day 10 Vivas continued...

Course website

<https://www2.warwick.ac.uk/fac/sci/systemsbiology/staff/richardson/teaching/MA930> (<https://www2.warwick.ac.uk/fac/sci/systemsbiology/staff/richardson/teaching/MA930>)

Day 1 Basic probability

1.1 Probability primer

1.2 Common distributions

1.3 Distributions continued

1.4 Characteristic functions

1.5 Summary and additional questions

1.1 Probability primer

1.1.1 Rules of probability

1.1.2 Continuous and discrete distributions

1.1.3 Cumulative distributions

1.1.4 Exponential distribution example

1.1.1 Rules of probability.

- Probabilities are positive and lie between 0 and 1
$$0 \leq P(A) \leq 1$$
- Probability of all non-overlapping events sums to 1
- Conditionality
$$P(A|B) = P(A \& B) / P(B)$$
$$P(A \& B) = P(A|B)P(B)$$
- Independence
$$P(A|B) = P(A)$$
- Bayes Rule
$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$
- Total probability
$$P(A) = P(A|B)P(B) + P(A|\sim B)P(\sim B)$$

1.1.1 Question: Rules of probability

Consider two events and all their possibilities

Before a test: A work or $\sim A$ play

Result of test: B pass or $\sim B$ fail

	work	play
pass	4/10	2/10
fail	1/10	3/10

- What are $P(\text{work})$, $P(\text{play})$, $P(\text{pass})$ and $P(\text{fail})$?
- What is $P(\text{pass} \mid \text{play})$?
- What is $P(\text{play} \mid \text{play})$?
- Are the effort put in and results independent variables?

1.1.2 Continuous and discrete probability distributions

Often events can be labelled by a

- discrete variable k with a countable number of states
- continuous variable with x

Discrete states have a probability $P(k)$

- With summation rule $1 = \sum_{\{k\}} P(k)$
- Expectation of a function $\langle h(k) \rangle = \sum_{\{k\}} h(k)P(k)$

Continuous states have a probability density $f(x)$ where $f(x)dx$ is prob. X between $x \rightarrow x + dx$

- Integrate to unity $1 = \int dx f(x)$ and units are $1/[x]$
- Expectation of a function $\langle h(x) \rangle = \int dx h(x)f(x)$

Common expectations

- Mean $\mu = \langle x \rangle$
- Variance $\sigma^2 = \langle x^2 \rangle - \langle x \rangle^2$

1.1.3 Cumulative distributions

- The cumulative distribution $F(x)$ is defined as the probability that the variable is less than or equal to x so that

$$F(x) = P(X \leq x)$$

- Maps both probabilities and densities onto the range 0 and 1

$$F(x) = \int_{-\infty}^x f(x)dx$$

- Useful for generating random numbers from any distribution using standard uniform randoms.

$$F = g(X) \quad \text{can be inverted to give} \quad X = g^{-1}(F)$$

- Return to this later

1.1.4 Question: Exponential distribution example

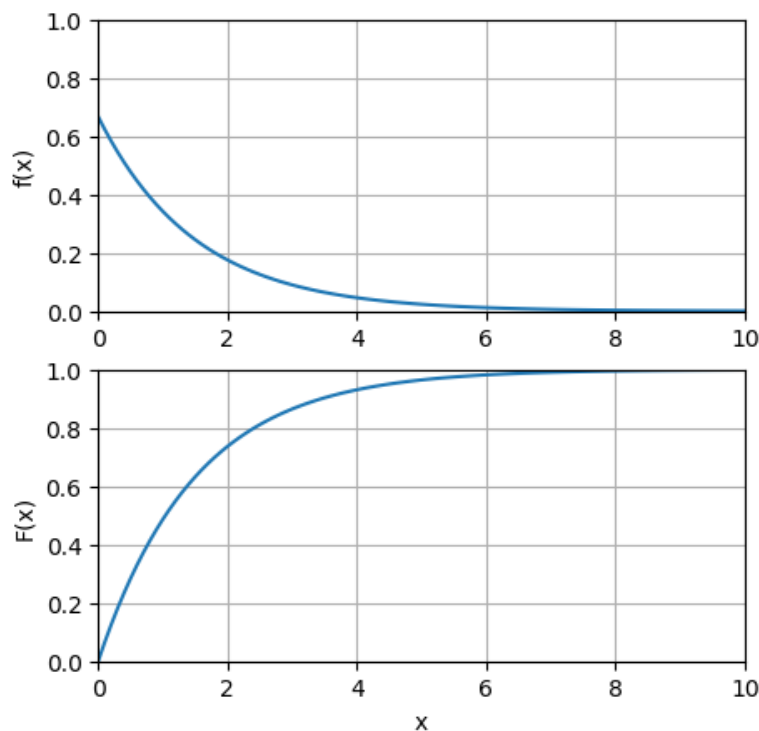
Example: Exponentially distributed random numbers obey

$$f(x) = \theta(x)e^{-x/a}/a$$

- What is the mean?
- What is the variance?
- What is the cumulative distribution?
- Plot the density and cumulative distributions for $a = 1.5$, one above the other, and label axes.

```
In [3]: using PyPlot
a=1.5; x=collect(0:0.1:10)
f=exp.(-x/a)/a
F=1.-exp.(-x/a);

figure(figsize=(5,5));
subplot(2,1,1); plot(x,f); ylabel("f(x)"); grid(); axis([0,10,0,1])
subplot(2,1,2); plot(x,F); xlabel("x"); ylabel("F(x)"); grid(); axis([0,10,0,1]);
```



1.2 Useful distributions

1.2.1 Bernoulli distribution

1.2.2 Binomial distribution

1.2.3 Poisson distribution

1.2.4 Normal distribution

1.2.5 Gamma distribution

1.2.1 Bernoulli distribution

- Discrete distribution where x is a binary random number

$x = 1$ with probability p

$x = 0$ with probability q

- Mean value is $\langle x \rangle = p$
- Variance. Use fact that $x^2 = x$ so that $\langle x^2 \rangle = p$.
Hence $\text{Var}(x) = \langle x^2 \rangle - \langle x \rangle^2 = p(1 - p) = pq$
- **Question:** Generate Bernoulli random numbers using the rand command and check this variance.

1.2.2 Binomial distribution

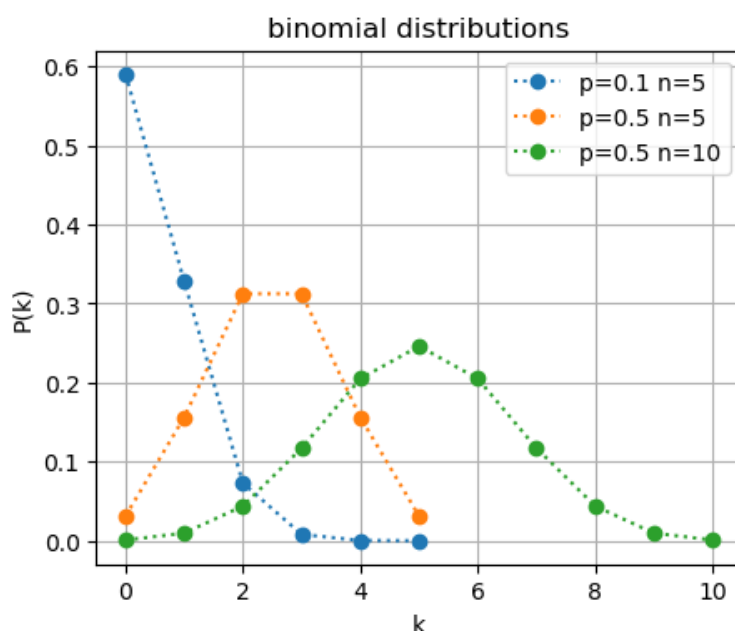
- It's a sum of n Bernoulli random variables $X = \sum_{j=1}^n x_j$
- Discrete distribution with $n + 1$ states.
- Order unimportant so combinatorial factor is required.
- Interpret as prefactor of terms in the expansion of $(p + q)^n$ so need Pascal's Triangle

$$P(X = k) = \binom{n}{k} p^k q^{n-k}$$

- Mean $\langle X \rangle = \sum_{j=1}^n \langle x_j \rangle = np$
- **Question:** What is the variance?

```
In [5]: # Binomial distribution examples
p1=0.1; q1=1-p1; n1=5; k1=collect(0:n1); y1=binomial.(n1,k1).*(p1.^k1).*(q1.^(n1.-k1));
p2=0.5; q2=1-p2; n2=5; k2=collect(0:n2); y2=binomial.(n2,k2).*(p2.^k2).*(q2.^(n2.-k2));
p3=0.5; q3=1-p3; n3=10; k3=collect(0:n3); y3=binomial.(n3,k3).*(p3.^k3).*(q3.^(n3.-k3));
```

```
In [6]: figure(figsize=(5,4)); title("binomial distributions");
plot(k1,y1,":o",label="p=$p1 n=$n1"); plot(k2,y2,":o",label="p=$p2 n=$n2");
plot(k3,y3,":o",label="p=$p3 n=$n3"); xlabel("k"); ylabel("P(k)");
grid(); legend();
```



1.2.3 Poisson distribution

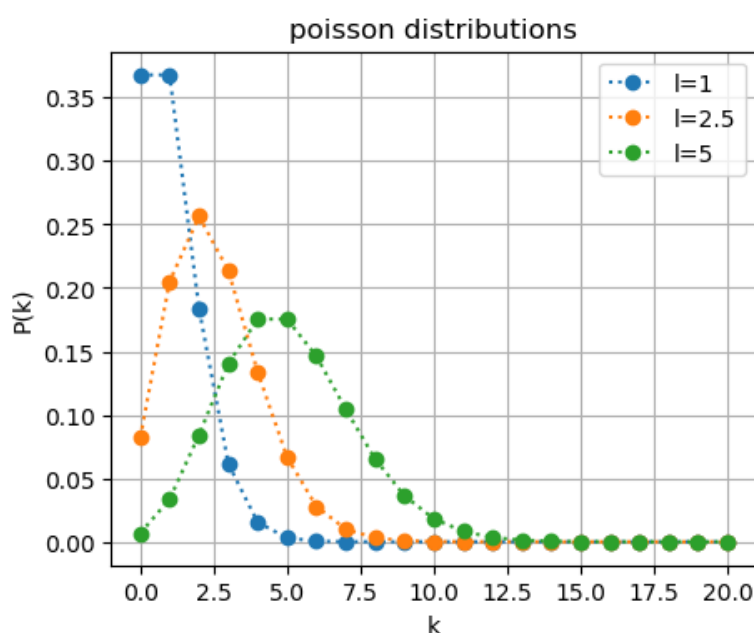
- Discrete distribution with a countable infinity of states
- Determined by parameter λ the typical number of time something happens.

$$P(k) = e^{-\lambda} \frac{\lambda^k}{k!}$$

- Mean number of events is λ
- Variance in number of events is also λ

```
In [9]: # Poisson distribution examples
k=collect(0:20);
lam1=1;      y1=exp(-lam1)*(lam1.^k)./gamma.(k.+1)
lam2=2.5;    y2=exp(-lam2)*(lam2.^k)./gamma.(k.+1)
lam3=5;      y3=exp(-lam3)*(lam3.^k)./gamma.(k.+1);
```

```
In [10]: figure(figsize=(5,4)); title("poisson distributions");
plot(k,y1,"o:",label="l=$\lambda_1$");plot(k,y2,"o:",label="l=$\lambda_2$")
plot(k,y3,"o:",label="l=$\lambda_3$"); xlabel("k"); ylabel("P(k)"); gr
id(); legend();
```



1.2.4 Normal distribution

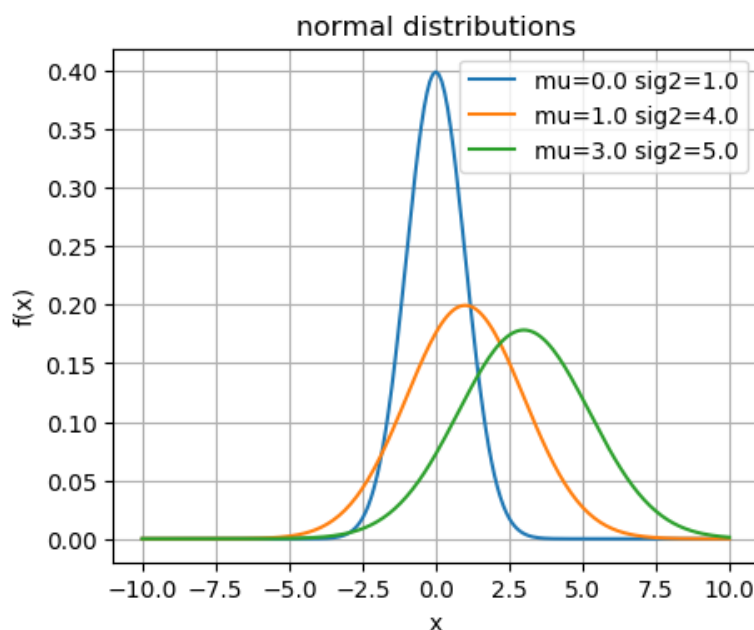
- Continuous distribution ubiquitous due to *Central Limit Theorem*: sums of random numbers tends to a Normal

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(\frac{-(x-\mu)^2}{2\sigma^2}\right)$$

- Specified by the mean μ and variance σ^2 .
- Standard normal: $\mu = 0$ and $\sigma^2 = 1$
- Sum of two normals with μ_1, σ_1 and μ_2 and σ_2^2 is a normal with $\mu = \mu_1 + \mu_2$ and $\sigma^2 = \sigma_1^2 + \sigma_2^2$.


```
In [12]: # Normal distribution examples
x=collect(-10:0.1:10);
mu1=0.0; s1=1.0;      y1=exp(-(x.-mu1).^2/(2*s1^2))/sqrt(2*pi*s
1^2);
mu2=1.0; s2=2.0;      y2=exp(-(x.-mu2).^2/(2*s2^2))/sqrt(2*pi*s
2^2);
mu3=3.0; s3=sqrt(5.0); y3=exp(-(x.-mu3).^2/(2*s3^2))/sqrt(2*pi*s
3^2);
```

```
In [14]: figure(figsize=(5,4)); title("normal distributions");
plot(x,y1,label="mu=$\mu_1$ sig2=$(s1^2)$"); plot(x,y2,label="mu=$\mu_2$
sig2=$(s2^2)$")
plot(x,y3,label="mu=$\mu_3$ sig2=$(round(s3^2;digits=1))"); xlabel("
x"); ylabel("f(x)"); grid(); legend();
```



1.2.6 Gamma distribution

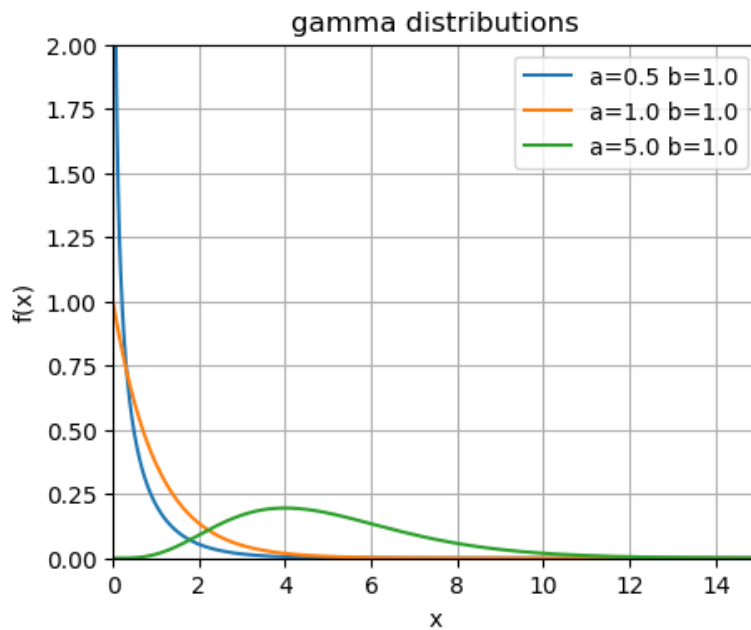
- Continuous distribution parameterised by α and β with

$$f(x) = \theta(x) \frac{1}{\Gamma(\alpha)} \beta^\alpha x^{\alpha-1} e^{-\beta x}$$

- Note the roles of α and β is setting the shape.
- **Question:** What are mean and variance in terms of α and β ?
HINT: use normalisation condition.

```
In [15]: # Gamma distributions
x=collect(0.01:0.01:15.1);
a1=0.5; b1=1.0; y1=(b1^a1)*x.^(a1-1.0).*exp.(-b1*x)/gamma(a1);
a2=1.0; b2=1.0; y2=(b2^a2)*x.^(a2-1.0).*exp.(-b2*x)/gamma(a2);
a3=5.0; b3=1.0; y3=(b3^a3)*x.^(a3-1.0).*exp.(-b3*x)/gamma(a3);
```

```
In [16]: figure(figsize=(5,4)); title("gamma distributions");
plot(x,y1,label="a=$a1 b=$b1"); plot(x,y2,label="a=$a2 b=$b2")
plot(x,y3,label="a=$a3 b=$b3"); xlabel("x"); ylabel("f(x)");
grid(); axis([0,15,0,2]); legend();
```



1.3 Distributions continued

1.3.1 Sums of random numbers

1.3.2 Multidimensional distributions

1.3.3 Marginal and conditional distributions

1.3.4 Transformations of random variables

1.3.1 Sums of random numbers

- Let the two independent random numbers x and y have distributions $f(x)$ and $g(y)$

- Then $z = x + y$ has a distribution $h(z)$ that satisfies

$$h(z) = \int dx \int dy \delta(z - x - y) f(x) g(y)$$

$$h(z) = \int dx f(x) g(z - x)$$

- This is essentially a convolution suggesting a multiplication in Fourier space.

1.3.1 Question: Gamma sum rules

- Gamma distribution $g(x) = \frac{1}{\Gamma(\alpha)} \beta^\alpha x^{\alpha-1} e^{-\beta x}$ for $x > 0$.
- Sum of two Gamma randoms with (α_1, β) and (α_2, β) is a Gamma random with $(\alpha_1 + \alpha_2, \beta)$
- Use the rule $g(x) = \int dx_1 \int dx_2 \delta(x - x_1 - x_2) g(x_1) g(x_2)$ to demonstrate this assertion.

- The Beta function will be of use

$$B(\alpha_1, \alpha_2) = \int_0^1 du u^{\alpha_1-1} (1-u)^{\alpha_2-1} = \frac{\Gamma(\alpha_1)\Gamma(\alpha_2)}{\Gamma(\alpha_1+\alpha_2)}$$

1.3.2 Multi-dimensional distributions

- Discrete case $P(X, Y)$ where X and Y have a countable number of states and the normalisation is

$$1 = \sum_X \sum_Y P(X, Y)$$

- Continuous case $f(x, y)$ where the normalisation is by the double integral

$$1 = \int dx \int dy f(x, y)$$

- Independence $f(x, y) = f(x)f(y)$
- Expectations of joint variables

$$\text{Covariance } \sigma_{xy} = \langle (x - \mu_x)(y - \mu_y) \rangle$$

$$\text{Correlation } \rho_{xy} = \frac{1}{\sigma_x \sigma_y} \sigma_{xy} \text{ which is dimensionless}$$

1.3.3 Marginal and conditional distributions

- Marginal distribution of X first

$$P(X) = \sum_Y P(X, Y) = \sum_Y P(X|Y)P(Y)$$

- Example:

	x_1	x_2	x_3	P_y
y_1	1/16	3/16	5/16	9/16
y_2	2/16	3/16	2/16	7/16
P_x	3/16	6/16	7/16	

- For the continuous case

$$f(x) = \int dy f(x, y) = \int dy f(x|y)f(y)$$

- Note the definition of the conditional density

$$f(x|y) = f(x, y)/f(y)$$

1.3.4 Transformations of random variables

- For the continuous case. Consider a transformation from a variable Y to a new variable $X = g(Y)$.
- Can use the marginal distribution definition where the conditional density is $f_{xy}(x|y) = \delta(x - g(y))$.

$$f_x(x) = \int dy f_{xy}(x|y)f_y(y) = f_y(y) \frac{dy}{dg}$$

- Factor dg/dy from the Dirac delta (integral over dy not dx).
- Note the transformation is $f(x)dx = f(y)dy$.
- But take care when mapping not one-to-one, like $X = Y^2$.

1.3.4 Question: Generating random variables

- We want to generate random variables X with a distribution $f_x(x)$.
- We can easily generate random variables Y uniformly in the range $0 \rightarrow 1$, so $f_y(y) = 1$
- What is the transformation $X = g(Y)$ required?
- What is the link to the cumulative distribution?
- Give the transformation required to generate exponentially distributed random numbers: $f(x) = \theta(x)e^{-x/a}/a$.
- Generate some exponentially distributed random numbers and compare with $f(x)$.
NB: `plt[:hist](x,50,normed=1,color="lightgray")` will plot a histogram of contents of vector x .

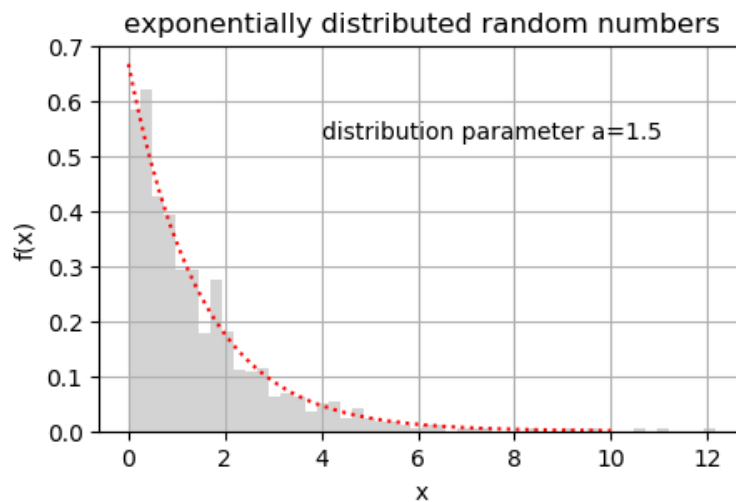
```

In [19]: # choose a=1.5 as before
a=1.5;
n=1000;          # number of random numbers to be generated
y=rand(n)        # generate the uniform random numbers
x=-a*log.(1.-y)  # use the transformation

xx=0:0.01:10
yy=exp.(-xx/a)/a

figure(figsize=(5,3))
plt[:hist](x,50,normed=1,color="lightgray");
plot(xx,yy,"r:"); title("exponentially distributed random numbers
")
xlabel("x"); ylabel("f(x)"); text(4.0,0.53,"distribution paramete
r a=$a");
grid("on")

```



1.4 Characteristic functions

1.4.1 Definition of the characteristic function

1.4.2 Properties of the characteristic function

1.4.3 Characteristic functions for common distributions

1.4.4 Calculations using characteristic functions

1.4.1 Definition of the characteristic function

- Definition of the m th moment $\langle X^m \rangle$
- Moment generating function

$$M(t) = \langle e^{tX} \rangle = \sum_{m=0}^{\infty} \langle X^m \rangle \frac{t^m}{m!}$$

- Characteristic function takes form

$$\phi_X(t) = \langle e^{itX} \rangle = \sum_{m=0}^{\infty} \langle X^m \rangle \frac{(it)^m}{m!}$$

- Closely related to the moment generating function, but always exists.
- Basically a Fourier transform for continuous case.

1.4.2 Properties of the characteristic function

- Characteristic function $\phi_X(t) = \langle e^{itX} \rangle$
- Fundamental convention $\phi_X(0) = 1$
- Sum of two independent random variables $X = X_1 + X_2$

$$\phi_X(t) = \langle e^{it(X_1+X_2)} \rangle = \langle e^{itX_1} \rangle \langle e^{itX_2} \rangle = \phi_{X_1}(t) \phi_{X_2}(t)$$

- Obvious generalisation to sums of multiple random variables
- Useful for later. Consider a sample mean $\bar{X} = \frac{1}{n} \sum_{k=1}^n X_k$ from k independent samples.

$$\phi_{\bar{X}}(t) = \langle e^{it\bar{X}} \rangle^n = [\phi_X(t/n)]^n$$

1.4.3 Characteristic functions of common distributions

- Example for a Bernoulli distribution with probability

$$p = 1 - q$$

$$\phi_X(t) = pe^{it} + q$$

- Summary for other distributions

Distribution	characteristic function $\phi(t)$
Bernoulli	$1 - p + pe^{it}$
Binomial	$(1 - p + pe^{it})^n$
Poisson	$e^{\lambda(e^{it}-1)}$
Normal	$e^{it\mu - \sigma^2 t^2/2}$
Gamma	$(1 - it/\beta)^{-\alpha}$

1.4.4 Calculations using characteristic functions

- Bernoulli has a characteristic function $\phi_x(t) = 1 - p + pe^{it}$
- A binomial random number is a sum of independent Bernoulli randoms $X = \sum_{j=1}^n x_j$
- Characteristic functions of a sum of independent randoms is a product of their individual characteristic functions.
- Hence $\phi_X(t) = \phi_x(t)^n = (1 - p + pe^{it})^n$ as expected.

1.4.4 Question: Calculations using characteristic functions

$X = X_1 + X_2$ then

$$\phi_X(t) = \langle e^{it(X_1+X_2)} \rangle = \langle e^{itX_1} \rangle \langle e^{itX_2} \rangle = \phi_{X_1}(t) \phi_{X_2}(t)$$

- Use this product rule for characteristic functions to derive the summation rules for:

1. Normally-distributed random numbers
2. Gamma-distributed random numbers

1.5 Summary and additional questions

Day 1 Basic probability

- 1.1 Probability primer
 - 1.2 Common distributions
 - 1.3 Distributions continued
 - 1.4 Characteristic functions
 - 1.5 Summary and additional questions
-

Additional questions

Q1.5.1 Derivation of characteristic functions

Q1.5.2 Gamma-distributed random-number generator

Q1.5.3 Using the Distributions.jl package

1.5.1 Question: Derivation of characteristic functions

- In section 1.4.3 a list of characteristic functions was given for the distributions of section 1.2. Derive these from the Bernoulli, Binomial and Poisson distributions.

1.5.2 Question: Gamma-distributed random-number generator.

- For exponentially-distributed random numbers it was possible to invert the cumulative distribution and use this to generate appropriately distributed randoms from uniformly distributed ones.
- In general it is not possible to analytically invert the cumulative distribution function.
- **Task**
- Develop a numerical method that generates gamma-distributed random numbers with shape factors $\alpha > 1$ and β .
- Check that a histogram of random numbers agrees with the original distribution.
- How well does your code work for $0 < \alpha \leq 1$?
- How might it be adapted?

1.5.3 Question: Using the Distributions.jl package

- The Distributions (<https://juliastats.github.io/Distributions.jl/latest/starting.html>) package provides a number of convenient functions for statistics.
- Install this in your version of Julia using
`Pkg.add("Distributions.jl")`
- Browse the "getting started" documentation and use the package to generate some random numbers, plot the original distributions and their cumulative distributions. Here are some examples...
- Generates a named (here Normal) distribution. What are μ and σ ?
`x1=-10.0:0.05:10.0;`
`y1=pdf(Normal(1.0,2.0),x1);`
- Generates a named cumulative distribution (here gamma). What are α and β ? What is θ in this context?
`x2=0.01:0.01:5`
`y2=cdf(Gamma(0.5,1.0),x2);`
- Generates random numbers from a named distribution (here gamma). What are α and β ?
`z=rand(Gamma(0.5, 3.0), 100)`
- You can compare these with your own cumulative distribution function of the previous question.

In []: