

1.answer-

a. If $M_2(x, y) = 1$, it implies that there exists a path of length 2 from vertex x to vertex y in the graph G . Or we can say that there exists a directed edge from x to some intermediate vertex z , and then another directed edge from z to y .

If $M_2(x, y) = 0$, it implies that there is no path of length 2 from vertex x to vertex y in this graph G . There are no intermediate vertices that can connect x and y directly.

b. If M_4 is the product of M_2 with itself, the entries of M_4 signify the existence of paths of length 4 between vertices in the graph G . $M_4(x, y) = 1$ indicates that there exists a path of length 4 from vertex x to vertex y , whereas $M_4(x, y) = 0$ implies that no such path exists. Similarly, the entries of $M_5 = (M_4)(M)$ represent the existence of paths of length 5 in this graph G . $M_5(x, y) = 1$ indicates the presence of a path of length 5 from vertex x to vertex y , and $M_5(x, y) = 0$ signifies the absence of such a path. In general, the matrix M_p represents the existence of paths of length p between vertices in the graph G . The entry $M_r(x, y) = 1$ indicates the presence of a path of length r from vertex x to vertex y , and $M_r(x, y) = 0$ implies there is no such path.

c. If $M_2(x, y) = z$, it implies that the shortest path length from vertex x to vertex y is z in the weighted graph G . The min operation in the definition of M_2 considers all possible intermediate vertices z' and calculates the sum of the weights of the edges from x to z' and from z' to y . $M_2(x, y)$ gives the minimum of all such sums, representing the shortest path length. Therefore, if $M_2(x, y) = z$, it can be concluded that there exists a path from vertex x to vertex y of length z , and this path is the shortest among all paths from x to y in the graph G .

2 .answer-

1. Create a priority queue PQ to store flights with their associated arrival times.

- Initialize all flights with infinite arrival times, except for flights departing from airport a at or after time t . Set their respective arrival times as the departure time plus the minimum connecting time at the destination airport.

- Each flight in the priority queue PQ will be represented as a tuple (flight, arrival time).

2. While PQ is not empty, do the following things:
 - a. Extract the flight f with the minimum arrival time from PQ .
 - b. If the destination airport of f is b , stop the algorithm. The earliest arrival time at b has been found.
 - c. For each flight g in \mathcal{F} with the same origin airport as f , do the following:
 - Calculate the minimum connecting time from the arrival time of f to the departure time of g . This can be done by subtracting the arrival time of f from the departure time of g .
 - If the departure time of g is at or after the minimum connecting time and the arrival time of g is greater than the sum of the arrival time of f and the minimum connecting time at the destination airport of f , update the arrival time of g to the sum of the arrival time of f and the minimum connecting time. Add the flight g with its updated arrival time to PQ .

When updating the arrival time of g , we can remove the old entry from the priority queue PQ and insert the updated entry with the new arrival time.

3. If the algorithm reaches this point, there is no valid sequence of flights from a to b within the given constraints. Return an appropriate error message.

Once the algorithm terminates, the earliest arrival time at b will be the arrival time associated with the flight that reached b .

The key idea behind this algorithm is to use the priority queue PQ to keep track of the flights in a sorted manner based on their arrival times. By always extracting the flight with the minimum arrival time, we ensure that we explore the flights in an optimal order.

The overall time complexity of the algorithm will be $O(m \log m)$, where m is the no. of flights. This is because each flight is inserted and extracted from the priority queue at most once, and each operation takes $O(\log m)$ time. So, multiply no. of flights with $\log m$.

The number of airports n does not affect the time complexity of the algorithm.

3.answer-

To find the maximum bandwidth of a path between two switching centers a and b in a telephone network represented by a graph G , we can use a modified version of Dijkstra's algorithm. Here's the algorithm:

1. Create a priority queue PQ to store vertices with their associated bandwidth values. Initialize all vertices with infinite bandwidth, except for vertex a , which is initialized with bandwidth 0.
2. While PQ is not empty, do the following:
 - a. Extract the vertex u with the minimum bandwidth value from PQ .
 - b. If u is b , stop the algorithm. The maximum bandwidth from a to b has been found.
 - c. For each neighbour v of u , calculate the minimum bandwidth between u and v by taking the minimum of the bandwidth value of u and the bandwidth of the edge (u, v) . Let this minimum bandwidth be new_bw .
 - If new_bw is greater than the current bandwidth value of v , update the bandwidth value of v to new_bw and add v to PQ .
3. If the algorithm reaches this point, there is no path from a to b . Return an appropriate error message.

Once the algorithm terminates, the maximum bandwidth of a path between a and b will be the bandwidth value associated with vertex b . A modified Dijkstra's algorithm ensures that at each step, we update the bandwidth value of a vertex with the minimum bandwidth possible for the path leading to it. By doing this, we effectively find the maximum bandwidth path from a to b .

This algorithm assumes that the bandwidth values on the edges represent the capacity of the communication lines. If the bandwidth values represent some other metric, the algorithm may need to be adjusted accordingly.

4.answer-

we can use the Floyd- Warshall algorithm. Here's an algorithm that computes the transitive reduction:

1. Initialize a matrix R of size $n \times n$, where n is the number of vertices in the graph. Set all elements of R to 0 initially.

2. For each edge (u, v) in the graph, set $R[u][v]$ to 1.
3. For each vertex k from 1 to n , do the following things:
 - a. For each pair of vertices u and v , if u is not equal to k and v is not equal to k , check if $R[u][k]$ and $R[k][v]$ are both 1.
 - b. If both $R[u][k]$ and $R[k][v]$ are 1, then there is a path from u to v through k . In this case, set $R[u][v]$ to 0.
4. Return the resulting matrix R as the transitive reduction of the graph.

The time complexity of this algorithm is $O(n^3)$, where n is the number of vertices in the graph. The algorithm iterates through all possible vertex pairs and checks if there is a transitive edge through each intermediate vertex. The Floyd-Warshall algorithm efficiently computes the transitive closure of a graph, which can be used to derive the transitive reduction