Yuguang Li

$$E(x) = \int_0^1 \int_0^1 \max(x_1, x_2) P(x_1, x_2) dx_1 dx_2$$

$$= \int_0^1 \int_0^{x_1} x_2 dx_1 dx_1 + \int_0^1 \int_{x_2}^{x_2} x_1 dx_1 dx_2$$

$$= \int_0^1 \frac{1}{2} x_2^2 dx_2 + \int_0^1 \frac{1}{2} x_1^2 dx_1$$

=
$$\int_0^1 \int_0^1 \left(\max(x_1, x_2) \right)^2 - \frac{2}{3} \left(\max(x_1, x_2) \right) + \frac{1}{9} \right) dx_1 dx_2$$

$$=\int_{0}^{1} 2 \cdot \frac{1}{3} \times i^{3} dx, -\frac{1}{9}$$

$$=\frac{1}{5}-\frac{1}{9}=\frac{1}{12}$$

3.
$$Cov(x_1, x_2) = \int_0^1 \int_0^1 (\max(x_1, x_2) - x_1)(\max(x_1, x_2) - x_2) dx_1 dx_2$$

$$=\int_0^1\int_0^1\left(\max(x_1,x_2)\right)^2-(x_1+x_2)\max(x_1,x_2)+x_1x_2\,dx_1dx_2$$

$$= \frac{1}{6} - \left(\int_{0}^{1} \int_{0}^{x_{1}} (x_{1} + x_{2}) \cdot x_{2} + x_{1} \cdot x_{2} dx_{1} dx_{1} + \int_{0}^{1} \int_{0}^{x_{2}} (x_{1} + x_{2}) dx_{2} dx_{1} \right)$$

$$= \frac{1}{6} - \int_{0}^{1} \frac{8}{3} \times x^{3} dx,$$

2. 1.
$$P(x|a) = \frac{a^{kx}}{x!} e^{-ax}$$

$$P(G|a) = \frac{a^{2Gi}}{TGi!} e^{-ax}$$

$$P(G|a) = \frac{a^{2Gi}}{TGi!} e^{-ax}$$

$$P(G|a) = \frac{a^{2Gi}}{TGi!} e^{-ax}$$

$$= \Sigma G_i \ln R - \ln G_i - \ln R$$

$$= \Sigma (G_i \ln R - \ln G_i) - \ln R$$

$$\frac{2}{r} \frac{d\ln(P(q/n))}{dn} = \frac{\Sigma G_i}{n} - n = 0 \qquad R = \frac{n}{\Sigma G_i}$$

$$\frac{3}{7} = \frac{4+1+\cdots+8}{7} = \frac{25}{7} = 8$$

$$0 (n^{2}d + d^{3})$$

$$2. \hat{\mathcal{A}}_{i} = \chi_{i}\hat{w} = \chi_{i}(x^{T}x)^{T} \times TY$$

$$= h_{i}Y$$

3.
$$SSE_z = (Y - Z_i)^T (Y - Z_i)$$

= $\frac{2}{5} \frac{7}{5} (Y_1 - Z_1)^2 + \frac{2}{5} (Y_1 - Z_1)^2$

$$= \frac{n}{2} \frac{\hat{y}}{z} (y_1 - y_1)^2 + \frac{n}{z} (y_1 - \hat{y}_1 - \hat{y}_1)^2$$

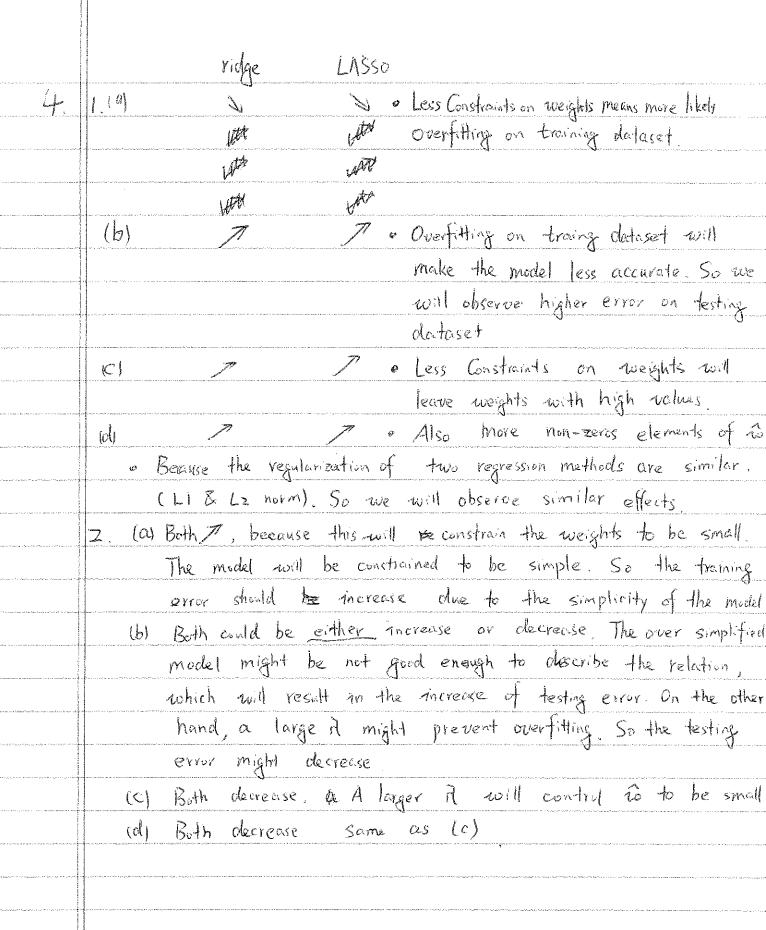
$$= \sum_{i=1}^{N} (y_i - \hat{y}_i^{(-i)})^2 = Loo(V)$$

$$4 \quad \hat{\mathcal{G}}_{i}^{(-i)} = \chi_{i} \hat{\omega}^{(-i)} = \chi_{i} \cdot (\chi^{T} \chi)^{-1} \times Z$$

$$= h_{i} \cdot Z$$

$$5. \hat{y_i} - \hat{y_i}^{(-i)} = \hat{y_i} - h_i Z$$

$$= \underbrace{\sum_{i} h_{i} y_{i}}_{i} - \underbrace{h_{ii} \hat{y}_{i}}_{i} - \underbrace{\sum_{j \neq i} h_{ij} y_{j}}_{j \neq i}$$



5. 5.1 1.
$$L(f) = E_{X,Y} ((Y - f(X))^2)$$

$$= E_{X,Y} ((Y - E(Y|X) + E(Y|X) - f(X))^2)$$

$$= E_{X,Y} ((Y - E(Y|X) + E(Y|X) - f(X))^2)$$

$$= E_{X,Y} ((Y^2 - ZE(Y|X)Y + E(Y|X)^2) + E_{X,Y} (ZE(Y|X)Y + ZE(Y|X)f(X) + ZE(Y|X)f(X)f(X) + ZE(Y|X)f(X)f(X)f(X) + ZE(Y|X)f(X)f(X)f(X) + ZE(Y|X)f(X)f(X)f(X)f(X) + ZE(Y|X)f(X)f(X)f(X)f(X) + ZE(Y|X)f(X)f(X)f(X) + ZE(Y|X)f(X)f(X)f(X)f$$

2. $L(f) = Ex(E(Y|X) - f(X))^2) + Ex, Y((Y-E(Y|X))^2)$ In order to minimize L(f) we can have $L(f_{Boyes}) = E(Y|X)$ while we can't do anything to the second term

$$E_{t}L(\hat{f}) = E_{t}E_{xY}(Y - E(Y|X)^{2}) + E_{t}E_{x}((E(Y|X) - \hat{f}(x))^{2})$$

$$= \frac{1}{4}E_{xY}(Y - E(Y|X)^{2}) + E_{t}E_{x}((E(Y|X)^{2} + \bar{f}(x)^{2} - 2E(Y|X)^{2})$$

$$+ (\mathbb{Z}\hat{f}(x)^{2} + 2 \bar{f}(x)\hat{f}(x) + \bar{f}(x)^{2}) + 2(\bar{f}(x)\hat{f}(x) + E(Y|X)\bar{f}(x)$$

$$- \bar{f}(x)^{2} - 4E(Y|X)\hat{f}(x))$$

$$= E_{x,Y}(Y - E(Y|X))^{2}) + E_{x}((E(Y|X) - \bar{f}(x))^{2})$$

+ Ez Ex ((字(x) - 平(x))) +2Ez Ex ((平(x) - E(Y|x))(字(x) - 平(x)))

Because fix) - Fix) and fix) - E(Y|x) are two independent vandom variable.

$$E_{\tau}E_{x}((\bar{f}_{(x)}-E(Y|x))(\hat{f}_{(x)}-\bar{f}_{(x)}))=0.$$

$$S_{o}E_{\tau}L(\hat{f})=E_{x,Y}(LY-E(Y|x))^{2})+E_{x}((E(Y|x)-\bar{f}_{(x)})^{2})$$

$$+E_{\tau}E_{x}((\hat{f}_{(x)}-\bar{f}_{(x)})^{2})$$

Z.
$$E_{x,Y}((Y - E(Y|x))^2)$$
 noise $E_{x}((E(Y|x) - \overline{f(x)})^2)$ Domance $E_{z}E_{x}((\widehat{f(x)} - \overline{f(x)})^2)$ bias

- 3. No f* is the best estimator of Fix) it might be biosed
- 4. With a large sample size N
- · fix) is the theoretical Y value 1 at point X
 - * E(Y/x) is the observed mean of Y given X
 - e fix) is the estimated Y value using our model at point X. Our model is biased for most of the case (or is just optimized, but not the real one)

6 W 7 1. threshold 0.5 0/1 loss training: 0.0755 square loss training: 0.0505 2, 0/1 loss test: 0.0764 square loss test: 0.0515 3. Because the relation between features & labels might not be linear. Plus there are so many points lying around 0.5, which does not represent probability. 4. $\hat{y}_i = w^T x_i + Bayes optimal predictor.$ hard predictor $\hat{y}_i = \begin{cases} 0 & w^T x_i \neq 0.5 \\ 1 & w^T x_i > 0.5 \end{cases}$ Y:= WTX1 + Ei Ei is a Gaussian vandom Vanible with a mean.

7. 7.1 1. Initialize
$$w_{0}^{\circ} = 0$$

While not converged do

 $w_{0}^{\circ t + 1} = \sum_{i=1}^{N} (y_{i} - y_{i}^{\circ t + 1}) / N + w_{0}^{\circ t + 1}$

for $k \in \{1, 2, ..., d\}$ do

Same as Algorithm 1.

end

2. $O(||X||_{0})$

3. $O(||X||_{0} + 2)$, $O(||X||_{0})$

2.
$$O(||X||_0)$$

3. $O(||X||_0 + 2)$, $O(N+2)$
4. $O(z_i)$
5. $\hat{\mathcal{J}}_i^{(t+1)} = \chi_i w^{(t)} + w_0^{(t+1)}$
 $= \hat{\mathcal{J}}_i^{(t)} - w_0^{(t)} + w_0^{(t+1)}$
Complexity $O(N)$ or $O(z_i)$

6.
$$C_{k}^{(t+1)} = 2 \sum_{i=1}^{N} X_{ik} (\mathcal{J}_{k} - \widehat{\mathcal{J}}_{i} + T_{ij} k^{(t)} X_{ik})$$

$$Q_{k}^{(t+1)} = 2 \sum_{i=1}^{N} X_{ik}^{ik}$$

$$W_{k}^{(t+1)} = \int (C_{k}^{(i+1)} + A) / Q_{k}^{(t+1)} C_{k} e^{-iR}$$

$$C_{k} e^{-iR} A$$

$$(C_{k}^{(t+1)} - A) / Q_{k}^{(t+1)} C_{k} = +R$$

Complexity O(N)

7 Programming Question 2: Lasso

7.3 Try out your work on synthetic data

Question 1

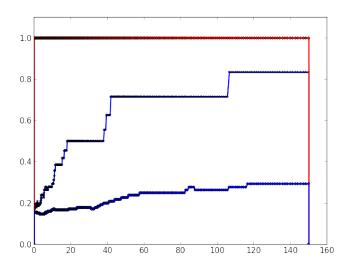


Figure 1: Recall(red) and precision(blue) plots of σ 1(star) and 10(circle) values against λ .

A large λ helps to more accurately discover non-zeros, because more false positive are discovered. As the λ goes lower, the precision goes down. But recalls are always 100%.

Question 2

Plots are found above with circle markers.

When I changed σ from 1.0 to 10.0, the precision become lower, because more false positive are discovered. This is caused by the noise introduced by the larger σ . But the recalls stay at 100%. In this case, I'd like to start with a larger λ and decreased from there.

7.4 Become a data scientist at Yelp

Question 1

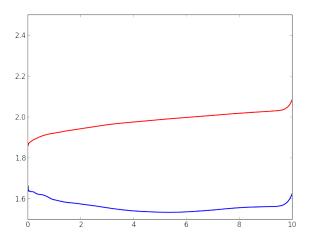


Figure 2: RMSE values against λ from training (red line) and testing (blue line) datasets.

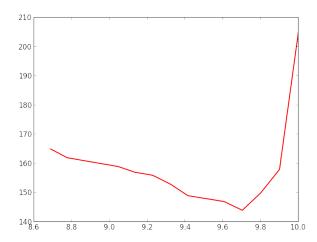


Figure 3: Number of nonzero weights against λ from training (red line) and testing (blue line) datasets.

Question 2

Using the best λ value 4.9983 from the validation performance, I got the RMSE value 1.1829717559 from the testing dataset.

Question 3

```
The best 10 features I discovered are: sqrt(ReviewNumCharacters*UserCoolVotes): [67.64008046] \\ sqrt(UserCoolVotes*BusinessNumStars): [33.55206007] \\ sqrt(ReviewNumCharacters*UserFunnyVotes): [14.92750312] \\ sqrt(UserFunnyVotes*InPhoenix): [61.34628919] \\ BusinessNumReviews*InGlendale: [17.02279332] \\ ReviewInFall*InGlendale: [16.25769229] \\ UserUsefulVotes*InScottsdale: [29.18772702] \\ log(ReviewNumCharacters*UserUsefulVotes): [35.83890522] \\ sq(UserUsefulVotes*IsRestaurant): [42.39206274] \\ sqrt(ReviewNumWords*UserUsefulVotes): [56.53814474]
```

Question 4

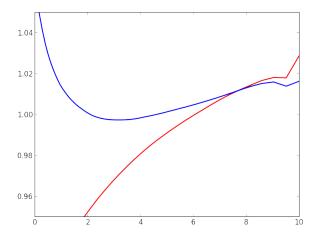


Figure 4: RMSE values against λ from training (red line) and testing (blue line) datasets.

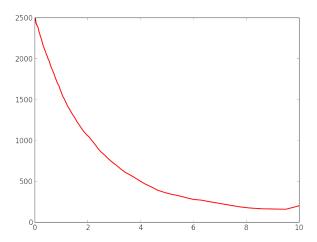


Figure 5: Number of nonzero weights against λ from training (red line) and testing (blue line) datasets.

Using the best λ value 3.0 from the validation performance, I got the RMSE value 0.5608 from the testing dataset.

The best 10 features I discovered are :

 $\begin{array}{l} {\rm great}: [\ 21.10928191] \\ {\rm best}: [\ 18.00001071] \\ {\rm amazing}: [\ 14.74667601] \\ {\rm love}: [\ 11.76668926] \\ {\rm delicious}: [\ 11.09071936] \\ {\rm awesome}: [\ 12.56298077] \end{array}$

perfect : [9.47380946] excellent : [8.90874206] wonderful : [8.44758452] friendly : [8.64004513]