On a four-dimensional oncolytic Virotherapy model (*E*=1)

This Mathematica Notebook is a supplementary material to the paper "On a three-dimensional and two four-dimensional

oncolytic viro-therapy models". It contains some of the calculations and illustrations appearing in the paper.

Ep1)Section 3.5(in paper): 4-Dim.Viro-therapy model when ϵ =1

Ep1-1)Definition of the model and fixed points when $\epsilon=1$

```
In[@]:= SetDirectory[NotebookDirectory[]];
       AppendTo[$Path, Directory];
       Clear["Global`*"];
       Clear["K"];
       (*Some aliases*)
       Format[\betay] = Subscript[\beta, y];
       Format[\betav] = Subscript[\beta, v];
       Format[\beta z] = Subscript[\beta, z];
       Unprotect[Power];
       Power[0, 0] = 1;
       Protect[Power];
       par = \{b, \beta, \lambda, \delta, \beta y, \beta v, \beta z, c, \gamma, K, \epsilon\};
       cp = Join[Thread[Drop[par, {1}] > 0], {b > 1}];
       cKga1 = \{K \rightarrow 1, \gamma \rightarrow 1\};
       cep1 = \{\epsilon \rightarrow 1\};
       R0 = b \beta K / (\beta K + \delta) (* Reproduction number*);
       (*cnb={b→50};
       cE1ri=Join[\{\beta y\rightarrow 1/48, K\rightarrow 2139.258, \beta\rightarrow .0002, \lambda\rightarrow .2062,
             \gamma \rightarrow 1/18, \delta \rightarrow .025, \beta v \rightarrow 2*10^{(-8)}, c \rightarrow 10^{(-3)}, \beta z \rightarrow .027\}, cep1];*)
       \mathsf{CF1} = \left\{ \beta \to \frac{87}{2}, \ \lambda \to 1, \ \gamma \to \frac{1}{128}, \ \delta \to 1 \ / \ 2, \ \beta \mathsf{y} \to 1, \ \beta \mathsf{v} \to 1, \ \mathsf{K} \to 1, \ \beta \mathsf{z} \to 1, \ \mathsf{c} \to 1, \ \epsilon \to 1 \right\};
        (****** Four dim Deterministic epidemic model with Logistic growth ****)
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```
x1 = \lambda x (1 - (x + y) / K) - \beta x v;
y1 = \beta \times V - \beta y y z - \gamma y;
v1 = -\beta x v - \beta v v z + b \gamma y - \delta v;
z1 = z (\beta z y - c z^{\epsilon});
dyn = \{x1, y1, v1, z1\};
dyn3 = \{x1, y1, v1\} /. z \rightarrow 0; (*3dim case used for E* *)
Print[" (y')=", dyn // FullSimplify // MatrixForm]
Print["b0=", b0 = b /. Apart[Solve[R0 == 1, b] [1]] // FullSimplify]]
(***Fixed point when z→0**)
eq = Thread [dyn3 == \{0, 0, 0\}];
sol = Solve[eq, {x, y, v}] // FullSimplify;
Es = \{x, y, v\} /. sol[[3]]; (*Endemic point with z=0*);
Print[" Endemic point with z=0 is E*=", Es // FullSimplify]
jacD = Grad[dyn /. cep1, {x, y, v, z}];
Print["J(x,y,v,z) ="]
jacD // MatrixForm
Print["Det(J(x,y,v,z))="]
Det[jacD] // FullSimplify
Jac3 = Grad[dyn3, {x, y, v}] // FullSimplify;
Jst = Jac3 /. sol[[3]];
Print["Jac(E*) in 3 dim is ", Jst // MatrixForm]
  \begin{pmatrix} \mathbf{x} \\ (\mathbf{y} \\ \mathbf{v} \\ ) = \begin{pmatrix} -\mathbf{v} \times \beta + \mathbf{x} \left( \mathbf{1} - \frac{\mathbf{x} + \mathbf{y}}{\kappa} \right) & \lambda \\ \mathbf{v} \times \beta - \mathbf{y} \left( \mathbf{z} \beta_{\mathbf{y}} + \gamma \right) \\ \mathbf{b} \mathbf{y} \gamma - \mathbf{v} \left( \mathbf{x} \beta + \mathbf{z} \beta_{\mathbf{v}} + \delta \right) \\ \mathbf{z} \left( -\mathbf{c} \mathbf{z}^{\epsilon} + \mathbf{y} \beta_{\mathbf{z}} \right) \end{pmatrix} 
b0=1+\frac{\delta}{K\beta}
  Endemic point with z=0 is E*=  \Big\{ \frac{\delta}{(-1+b)\ \beta} \text{, } \frac{(\ (-1+b)\ K\ \beta-\delta)\ \delta\ \lambda}{(-1+b)\ \beta\ (\ (-1+b)\ K\ \beta\ \gamma+\delta\ \lambda)} \text{, } \frac{\gamma\ (\ (-1+b)\ K\ \beta-\delta)\ \lambda}{\beta\ (\ (-1+b)\ K\ \beta\ \gamma+\delta\ \lambda)} \Big\}
```

$$\left(\begin{array}{ccccc} -v\;\beta - \frac{x\,\lambda}{\kappa} \; + \; \left(1 - \frac{x+y}{\kappa}\right)\;\lambda & -\frac{x\,\lambda}{\kappa} & -x\;\beta & \emptyset \\ & v\;\beta & -z\;\beta_y - \gamma & x\;\beta & -y\;\beta_y \\ & -v\;\beta & b\;\gamma & -x\;\beta - z\;\beta_v - \delta & -v\;\beta_v \\ & \emptyset & z\;\beta_z & \emptyset & -2\;c\;z + y\;\beta_z \end{array} \right)$$

Det(J(x,y,v,z)) =

J(x,y,v,z) =

```
Out[\bullet] = \begin{array}{c} \mathbf{1} \\ \mathbf{K} \end{array}
             \left(2\,c\,z\,\left(K\,v\,\beta\,\left(z\,\beta_{y}+\gamma\right)\,\left(z\,\beta_{v}+\delta\right)\,+\,v\,x\,\beta\,\left(z\,\beta_{v}+\delta\right)\,\lambda\,-\,K\,\left(x\,\beta\,\left(z\,\beta_{y}+\gamma\,-\,b\,\gamma\right)\,+\,\left(z\,\beta_{y}+\gamma\right)\,\left(z\,\beta_{v}+\delta\right)\,\right)\right)
                         \lambda + (2 x + y) (x \beta (z \beta_v + \gamma - b \gamma) + (z \beta_v + \gamma) (z \beta_v + \delta)) \lambda) -
                 \beta_z (Ky\gamma ((-1+b) x\beta - z\beta_v - \delta) \lambda - y (2x+y) \gamma ((-1+b) x\beta - z\beta_v - \delta) \lambda +
                       \mathbf{v} \mathbf{x} \beta (-2 \mathbf{x} \mathbf{z} \beta_{\mathbf{v}} + \mathbf{y} \delta) \lambda + \mathbf{K} \mathbf{v} \beta (\mathbf{y} \gamma (\mathbf{z} \beta_{\mathbf{v}} + \delta) + \mathbf{x} \mathbf{z} \beta_{\mathbf{v}} \lambda))
                                               Jac(E*) in 3 dim is
             (****Fixed points of 4-dim model using P(y)***)
In[ • ]:=
             fy=(c \gamma(b-1)-y \betay \betaz);
             gy=(\beta v \beta z y+c \delta); hy=(\gamma +y \beta z \beta y/c);
             xey=hy gy/(\beta fy); vey=y fy/gy; zey= \betaz y /c;
            ys=y/.sol[3](* y of E*
            Py=\lambda(1-y/K)-\beta y fy/gy-\lambda hy gy/(\beta K fy); yb=c \gamma (b-1)/(\betay \betaz);
             Qy=\lambda fy gy(1- y /K) - \lambda hy gy^2/(\beta K)-y \beta fy^2;
             Qycol=Collect[Together[Qy],y];
             Qycoef=CoefficientList[Qycol,y];
             Print["f(y)=", fy, ",g(y)=", gy, ", h(y)=", hy]
             Print["p(y) =", Py//FullSimplify]
             Print["The polynomial Q(y) is of order ", Length[Qycoef]-1]
             Print["Coefficients of Q(y) are ", Qycoef//FullSimplify]
             Dis=Collect[Discriminant[Qy,y],b];
             Discoef=CoefficientList[Dis,b];Length[Discoef];
             Disn=Dis//.cF1//N;
            bL=50;
             Plot[{0,Disn},{b,0,2 bL},AxesLabel→{"b","Dis"},PlotRange→{{0,bL},{-10,12}}]
             Print["Roots of Dis[b]=0 are: ",solbE=Solve[Disn==0,b]]
          f(y) = -y \beta_y \beta_z + (-1 + b) c \gamma , g(y) = y \beta_v \beta_z + c \delta , h(y) = \frac{y \beta_y \beta_z}{c} + \gamma
          p\left(y\right) = \frac{y \beta \left(y \beta_{y} \beta_{z} - \left(-1 + b\right) c \gamma\right)}{y \beta_{v} \beta_{z} + c \delta} + \lambda - \frac{y \lambda}{K} - \frac{\left(\frac{y \beta_{y} \beta_{z}}{c} + \gamma\right) \left(y \beta_{v} \beta_{z} + c \delta\right) \lambda}{K \beta \left(-v \beta_{w} \beta_{z} + \left(-1 + b\right) c \gamma\right)}
           The polynomial Q(y) is of order 3
          Coefficients of Q(y) are \left\{ \frac{c^2 \, \gamma \, (\, (-1+b) \, \, K \, \beta - \delta) \, \, \delta \, \lambda}{K \, \beta} \right.
```

```
QR=Solve[Qy==0,y,Cubics→False]//ToRadicals(*casus irreducibilis*);
ym= y/.QR[2];
yp= y/.QR[[1]];yi= y/.QR[[3]];
Em1={xey,ym,vey,zey}//.y→ym;
Ep1={xey,yp,vey,zey}//.y→yp;
Eim1={xey,yi,vey,zey}//.y→yi;
Es1=Join[{x,y,v}/.sol[3],{0}];
{Chop[yp],Chop[ym]}//.cF1//N;
jacE1K=jacD/.x\rightarrow K/.y\rightarrow 0/.v\rightarrow 0/.z\rightarrow 0;
Print["J(EK) =", jacE1K//MatrixForm]
(*Jacobians of the fixed points**)
jEs1=jacD/.sol[3]/.z\rightarrow 0;
jEm1=jacD/.x→xey/.v→vey/.z→zey/.y→ym;
jEim1=jacD/.x→xey/.v→vey/.z→zey/.y→yi;
jEp1=jacD/.x→xey/.v→vey/.z→zey/.y→yp;
Print["Eig.val of J(EK) are:", Eigenvalues[jacE1K]//FullSimplify]
jacE1=jacD/.x→xey/.v→vey/.z→zey/.y→y//FullSimplify;
jacE1 //MatrixForm;
Det[jacE1]//FullSimplify;
Print[" Trace of either Ei, E+ or E- is : ", Tr[jacE1]//FullSimplify]
Print["J(E_*) is"]
jEs1//FullSimplify//MatrixForm
bbs=b/.Solve[yb==(y/.sol[3]),b][1](*long expression*);
```

$$\begin{split} & \text{J}\left(\mathsf{EK}\right) = \begin{pmatrix} -\lambda & -\lambda & -\mathsf{K}\,\beta & \emptyset \\ \emptyset & -\gamma & \mathsf{K}\,\beta & \emptyset \\ \emptyset & b\,\gamma & -\mathsf{K}\,\beta - \delta & \emptyset \\ \emptyset & \emptyset & \emptyset & \emptyset & \emptyset \end{pmatrix} \\ & \text{Eig.val of J}\left(\mathsf{EK}\right) & \text{are:} \left\{\emptyset\text{, } \frac{1}{2}\left(-\mathsf{K}\,\beta - \gamma - \delta - \sqrt{-4\,\gamma\,\left(\mathsf{K}\,\left(\beta - \mathsf{b}\,\beta\right) + \delta\right) + \left(\mathsf{K}\,\beta + \gamma + \delta\right)^{\,2}}\right)\text{,} \\ & \frac{1}{2}\left(-\mathsf{K}\,\beta - \gamma - \delta + \sqrt{-4\,\gamma\,\left(\mathsf{K}\,\left(\beta - \mathsf{b}\,\beta\right) + \delta\right) + \left(\mathsf{K}\,\beta + \gamma + \delta\right)^{\,2}}\right)\text{,} \\ & -\lambda\right\} \\ & \text{Trace of either Ei, E+ or E- is: } -y\,\beta_z - \frac{y\,\beta_y\,\beta_z + c\,\gamma}{c} + \frac{y^2\,\beta\,\beta_y\,\beta_z}{y\,\beta_z + c\,\delta} - \\ & \frac{\left(-1 + \mathsf{b}\right)\,c\,y\,\beta\,\gamma}{y\,\beta_v\,\beta_z + c\,\delta} + \frac{\mathsf{b}\,\gamma\,\left(y\,\beta_v\,\beta_z + c\,\delta\right)}{y\,\beta_y\,\beta_z - \left(-1 + \mathsf{b}\right)\,c\,\gamma} + \lambda - \frac{y\,\lambda}{\mathsf{K}} - \frac{2\left(\frac{y\,\beta_y\,\beta_z}{c} + \gamma\right)\,\left(y\,\beta_v\,\beta_z + c\,\delta\right)\,\lambda}{\mathsf{K}\,\beta\,\left(-y\,\beta_y\,\beta_z + \left(-1 + \mathsf{b}\right)\,c\,\gamma\right)} \end{split}$$

 $J(E_{-}*)$ is

Out[•]//MatrixForm=

Form=
$$\begin{pmatrix} \frac{\delta \lambda}{\mathsf{K} \, \beta - \mathsf{b} \, \mathsf{K} \, \beta} & \frac{\delta \lambda}{\mathsf{K} \, \beta - \mathsf{b} \, \mathsf{K} \, \beta} & -\frac{\delta}{-1 + \mathsf{b}} & \mathbf{0} \\ \frac{\gamma \, (\, (-1 + \mathsf{b}) \, \, \mathsf{K} \, \beta - \delta) \, \, \lambda}{(\, -1 + \mathsf{b}) \, \, \mathsf{K} \, \beta \, \gamma + \delta \, \lambda} & -\gamma & \frac{\delta}{-1 + \mathsf{b}} & \frac{\beta_{\mathsf{y}} \, \delta \, \, (\mathsf{K} \, \, (\beta - \mathsf{b} \, \beta) + \delta) \, \, \lambda}{(\, -1 + \mathsf{b}) \, \, \mathsf{K} \, \, (\gamma + \delta) \, \, \lambda} \\ \frac{\gamma \, \, (\mathsf{K} \, \, (\beta - \mathsf{b} \, \beta) + \delta) \, \, \lambda}{(\, -1 + \mathsf{b}) \, \, \mathsf{K} \, \, \beta \, \gamma + \delta \, \lambda)} & \mathsf{b} \, \gamma & \frac{\mathsf{b} \, \delta}{1 - \mathsf{b}} & \frac{\beta_{\mathsf{v}} \, \gamma \, \, (\mathsf{K} \, \, (\beta - \mathsf{b} \, \beta) + \delta) \, \, \lambda}{\beta \, \, \, \, (\, (-1 + \mathsf{b}) \, \, \mathsf{K} \, \, \beta \, \gamma + \delta \, \lambda)} \\ \end{pmatrix} \\ \mathbf{0} & \mathbf{0} & \mathbf{0} & \frac{\beta_{\mathsf{z}} \, \, (\, (-1 + \mathsf{b}) \, \, \mathsf{K} \, \, \beta \, \gamma + \delta \, \lambda)}{(-1 + \mathsf{b}) \, \, \mathsf{K} \, \, \beta \, \gamma + \delta \, \lambda)}$$

<code>In[•]:= (*Canonical form of the dynamical system around Eim***)</code>

Chop[Evaluate[dynCF /. b → 29.90350014 //. cF1]] // MatrixForm

At bH, the canonical form of dyn is
$$\begin{pmatrix} Y1' \\ V1' \end{pmatrix} = Z1'$$

Out[@]//MatrixForm=

Hopf bifurcation point related to bH for Eim:

```
(*it takes few minutes to run*)
In[ • ]:=
        cn=Join[cF1];
        pcm=Collect[Det[\psi IdentityMatrix[4]-(jEim1)],\psi];
        coT=CoefficientList[pcm,ψ];
        Length[coT]
        a1=coT[[2]];a2=coT[[3]];a3=coT[[4]]; a0=coT[[1]]; (*a4=1*)
        H4m=a1*a2*a3-a3^2 a0-a1^2 //.cF1;
        φb4m=Collect[Numerator[Together[H4m]],b];
        cbm=NSolve[(\phi b4m//.cn) == 0, b, WorkingPrecision \rightarrow 10];
        bMm=Max[Table[Re[b/.cbm[i]]],{i,Length[cbm]}]];
        Print["bH=",bHm=N[bMm,50]]
Out[@]= 5
      bH=29.90350014
 In[*]:= Print["Eigenvalues of Eim between b1* and bH"]
      Chop[Eigenvalues[jEim1 //. cF1 /. b \rightarrow 29.5 // N]]
      Print["Eigenvalues of Eim after bH"]
      Chop[Eigenvalues[jEim1 //. cF1 /. b \rightarrow 30 // N]]
      Print["Eigenvalues of Eim at bH"]
      Chop[Eigenvalues[jEim1 //. cF1 /. b \rightarrow bHm // N]]
      Chop[Evaluate[\{a0, a1, a2, a3\} //. cF1 /. b \rightarrow bHm // N]]
      Eigenvalues of Eim between b1∗ and bH
Out_{e} = \{-1.91852, 0.189259, 0.0221014 - 0.0653562 i, 0.0221014 + 0.0653562 i\}
       Eigenvalues of Eim after bH
Out_{e} = \{-2.20448, 0.249073, -0.00308009 - 0.0973103 i, -0.00308009 + 0.0973103 i\}
      Eigenvalues of Eim at bH
Out[\sigma]= {-2.1583, 0.241802, 0. + 0.0934898 \dot{\mathbb{1}}, 0. - 0.0934898 \dot{\mathbb{1}}}
Out[\circ] = \{-0.00456141, 0.0167508, -0.51314, 1.9165\}
       Hopf bifurcation point for E*:
        cn=Join[cF1];
        pc=Collect[Det[\psi IdentityMatrix[3] - (Jst)],\psi];
        coT=CoefficientList[pc, \psi];
        Length[coT]
        a1=coT[3] ;a2=coT[2];a3=coT[1] ;
        H2=a1*a2-a3;//.cF1;
        φb3=Collect[Numerator[Together[H2]],b];
        cb=NSolve[(\phi b3//.cn) == 0, b, WorkingPrecision \rightarrow 10]
        bMH=Max[Table[Re[b/.cb[i]]],{i,Length[cb]}]];
        Print["bH=",bH3=N[bMH,100]]
Out[*]= 4
Out_{a} = \{ \{b \rightarrow -62.24779183\}, \{b \rightarrow 0.0001713909530\}, \{b \rightarrow 0.8865604896\}, \{b \rightarrow 1.154342995\} \} \}
      bH=1.154342995
       Hopf bifurcation point related to b- for Eim:
```

```
(*it takes few minutes to run*)
In[ • ]:=
        cn=Join[cF1];
        pcp=Collect[Det[\psi IdentityMatrix[4] - (jEim1)],\psi];
        coT=CoefficientList[pcp, \psi];
        Length[coT]
        a1=coT[[4]];a2=coT[[3]];a3=coT[[2]]; a4=coT[[1]];
        H4p=a1*a2*a3-a3^2+a1^2 a4//.cF1;
        φb4p=Collect[Numerator[Together[H4p]],b];
        cbp=NSolve[(\phi b4p//.cn) ==0,b,WorkingPrecision \rightarrow 10];
        bMp=Max[Table[Re[b/.cbp[i]]],{i,Length[cbp]}]];
        Print["bH-=",bHp=N[bMp,50]]
```

Out[•]= **5**

bH-=45.29669903

Ep1-2)Trace, Det and third criterion of Routh Hurwitz applied to E*:

Det and Trace of of E* and Analysis of the stability of E* in 4 dim when ϵ =1:

```
Print["Tr[J[E*]]="]
In[ • ]:=
           trEs1=Tr[jacD//.Join[sol[3],{z→0}]]//FullSimplify
           Print["Det[J[E*]]="]
           detEs1=Det[jacD//.Join[sol[3],{z→0}]]//FullSimplify
           pc=Collect[Det[\psi IdentityMatrix[4] - (jEs1)],\psi];
           coT=CoefficientList[pc,\psi]//FullSimplify;
           Length [coT]
           a1=coT[[4]]//FullSimplify;a2=coT[[3]]//FullSimplify;a3=coT[[2]]//FullSimplify; a4=coT[[1]]//FullSimplify
           Print["a<sub>1</sub>=",a1, ", a<sub>2</sub>=",a2, ", a<sub>3</sub>=",a3, ",a<sub>4</sub>=", a4]
           H4=a1*a2*a3-a3^2+a1^2 a4;
           Print["H2(b0)=",H4/.b→b0//FullSimplify]
           Print["Denominator of H2 is ",Denominator[Together[H4]]//FullSimplify]
           φb4=Collect[Numerator[Together[H4]],b];
           cofi=CoefficientList[φb4,b];
           Length[cofi]
            (*Print["value of \phi(b) at crit b is "]
            \phib4/.b\rightarrowb0//FullSimplify; (*so long expression*)*)
         Tr[J[E*]]=
            \text{K } \delta \text{ } (2 \times (-1 + b) \text{ } \beta \text{ } \gamma + b \text{ } \beta \text{ } \delta + \beta_{z} \text{ } \delta) \text{ } \lambda + \delta^{2} \text{ } \lambda^{2} + \text{ } (-1 + b) \text{ } \text{K}^{2} \text{ } \beta \text{ } (\beta \text{ } \gamma \text{ } (\text{ } (-1 + b) \text{ } \gamma + b \text{ } \delta) \text{ } - \beta_{z} \text{ } \delta \text{ } \lambda) 
                                                       (-1 + b) K \beta ((-1 + b) K \beta \gamma + \delta \lambda)
         Det[J[E*]]=
 Out[*] = -\frac{\beta_z \gamma \delta^2 (K (\beta - b \beta) + \delta)^2 \lambda^2}{(-1 + b)^2 K \beta^2 ((-1 + b) K \beta \gamma + \delta \lambda)}
```

Out[]= 5

b2 * = 45.9232

```
a_{1} = \frac{\mathsf{K} \ \delta \ (2 \times (-1 + \mathsf{b}) \ \beta \ \gamma + \mathsf{b} \ \beta \ \delta + \beta_{\mathsf{z}} \ \delta) \ \lambda + \delta^{2} \ \lambda^{2} + (-1 + \mathsf{b}) \ \mathsf{K}^{2} \ \beta \ (\beta \ \gamma \ ((-1 + \mathsf{b}) \ \gamma + \mathsf{b} \ \delta) \ - \beta_{\mathsf{z}} \ \delta \ \lambda)}{\mathsf{b} \ \beta \ \beta \ \beta}
                                                                                                                                                                                                                                                                                                          (-1 + b) K \beta ((-1 + b) K \beta \gamma + \delta \lambda)
                                                          , a_2 = ((\delta \lambda (-((-1+b) K^2 \beta^2 ((-1+b) (\beta + \beta_z) \gamma + b \beta_z \delta)) + (b \beta + \beta_z) \delta^2 \lambda 
                                                                                                                      \mathsf{K} \beta \left(\beta_{\mathsf{z}} \delta \left( \left( -\mathbf{1} + \mathsf{b} \right) \gamma + \mathsf{b} \delta + \lambda - \mathsf{b} \lambda \right) + \left( -\mathbf{1} + \mathsf{b} \right) \beta \gamma \left( \left( -\mathbf{1} + \mathsf{b} \right) \gamma + \delta - \lambda + \mathsf{b} \left( \delta + \lambda \right) \right) \right) \right) / \mathsf{c}
                                                                                 ((-1+b)^2 K \beta^2 ((-1+b) K \beta \gamma + \delta \lambda))), a_3 =
                                                            \left( \, \left( \, \left( \, \left( \, \left( \, -1 + b \right) \, \, \mathsf{K} \, \beta - \delta \right) \, \, \delta \, \, \lambda \, \, \left( \delta^2 \, \left( \, \left( \, -1 + b \right) \,^2 \, \beta \, \gamma - b \, \beta_z \, \, \delta \right) \, \, \lambda^2 + \, \left( \, -1 + b \right) \,^2 \, \mathsf{K}^2 \, \beta^2 \, \gamma \, \, \left( \, \left( \, -1 + b \right) \,^2 \, \beta \, \gamma^2 + \beta_z \, \, \delta \, \lambda \right) \, + \, \lambda^2 \, \, \right) \, \, \lambda^2 + \, \lambda^2 \, \, \lambda^2 + \, \lambda^2 \, \, \lambda^2 + \, \lambda^2 \, \lambda^2 \, \lambda^2 \, \lambda^2 + \, \lambda^2 \, \lambda^2 \, \lambda^2 \, \lambda^2 + \, \lambda^2 \, \lambda^2 \, \lambda^2 \, \lambda^2 + \, \lambda^2 \, \lambda^2 \, \lambda^2 \, \lambda^2 + \, \lambda^2 \, \lambda^2 \, \lambda^2 \, \lambda^2 + \, \lambda^2 \, \lambda^2 \, \lambda^2 \, \lambda^2 \, \lambda^2 \, \lambda^2 + \, \lambda^2 \, \lambda
                                                                                                                         (-1 + b) K \beta \gamma \delta \lambda (2 (-1 + b)^2 \beta \gamma - \beta_z ((-1 + b) \gamma + \delta - \lambda + b (\delta + \lambda))))
                                                                                \left(\,\left(\,\mathbf{-1}+b\right)^{\,3}\,K\,\,\beta^{\,2}\,\,\left(\,\left(\,\mathbf{-1}+b\right)\,\,K\,\,\beta\,\,\gamma\,+\,\delta\,\,\lambda\,\right)^{\,2}\,\right)\,\right) \quad \text{, } \mathbf{a}_{4}=-\,\frac{\,\beta_{z}\,\,\gamma\,\,\delta^{\,2}\,\,\left(\,K\,\,\left(\,\beta\,-\,b\,\,\beta\,\right)\,\,+\,\delta\,\right)^{\,2}\,\,\lambda^{\,2}}{\left(\,\mathbf{-1}+b\right)^{\,2}\,K\,\,\beta^{\,2}\,\,\left(\,\left(\,\mathbf{-1}+b\right)\,\,K\,\,\beta\,\,\gamma\,+\,\delta\,\,\lambda\,\right)}
                                               H2(b0) = 0
                                               Denominator of H2 is (-1+b)^6 K^3 \beta^5 ((-1+b) K \beta \gamma + \delta \lambda)^4
Out[ ]= 11
                                                  Numerical values \epsilon=1:
                                                          cn=Join[cF1]; cnb=\{b\rightarrow 40\};
                                                            cb=NSolve[(\phi b4//.cn) == 0, b, WorkingPrecision \rightarrow 10]
                                                            bM=Max[Table[Re[b/.cb[i]]],{i,Length[cb]}]];
                                                            Print["bH=",bH=N[bM,30]]
                                                            Print["b0=",b0/.cn//N]
                                                          Print["E*",Es1//.cn/.cnb//N]
                                                            Print["E+=",Em1//.cn/.cnb//N]
                                                            Print["Eim=",Eim1//.cn/.cnb//N]
                                                            Print["roots of Dis[b]=0:", bcE1=NSolve[(Dis//.cn)==0,b]]
                                                            bc1=Chop[Evaluate[b/.bcE1[5]]];
                                                            bc2=Chop[Evaluate[b/.bcE1[6]]];
                                                          Print["b1*=", bc1]
                                                            Print[" b2*=", bc2]
 \textit{Out[\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\@align{scale}{0.9ex}\
                                                             \{b \rightarrow 0.060848063 - 10.686990738 \pm \}, \{b \rightarrow 0.060848063 + 10.686990738 \pm \},
                                                             \{b \to 0.8448282668 - 0.9299250641 \pm \}, \{b \to 0.8448282668 + 0.9299250641 \pm 1.92982848 + 0.9299250641 \pm 1.929828 + 0.929250641 \pm 1.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.92884 + 0.928828 + 0.928828 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884
                                                             \{b \to 0.8878046288\}, \{b \to 1.011494253\}, \{b \to 1.022996712\}, \{b \to 1.152364263\}\}
                                                bH=1.152364263
                                                b0=1.01149
                                                E * \{0.000294724, 0.0363426, 0.0221463, 0.\}
                                                E += \left\{0.00262408 + 5.51068 \times 10^{-19} \text{ i, } 0.0462057 + 8.67362 \times 10^{-18} \text{ i,} \right.
                                                                    0.021866 + 3.02367 \times 10^{-18} i, 0.0462057 + 8.67362 \times 10^{-18} i}
                                                Eim=\{0.114678 - 9.26732 \times 10^{-17} \text{ i}, 0.263221 - 2.77556 \times 10^{-17} \text{ i}, 
                                                                    0.0143012 + 8.58446 \times 10^{-18} i, 0.263221 - 2.77556 \times 10^{-17} i
                                                roots of Dis[b]=0:
                                                          \{\{b \rightarrow -126.518\}, \{b \rightarrow -63.\}, \{b \rightarrow -63.\}, \{b \rightarrow -24.5518\}, \{b \rightarrow 29.361\}, \{b \rightarrow 45.9232\}\}
                                                b1 * = 29.361
```

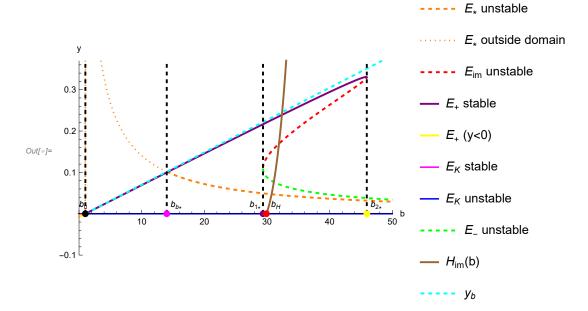
Ep1-3)Bifurcation diagrams:

Numerical solution of the stability (Bifurcation diagram) wrt y:

```
ln[∗]= (*Checks on the stability of the fixed points**)
     Print["Eigenvalues of E* when b=25 and when b=40, respectively "]
     Eigenvalues[jEs1] //. cF1 /. b \rightarrow 25 // N
     Eigenvalues[jEs1] //. cF1 /. b \rightarrow 40 // N
     Print["Eigenvalues of E+ when b=40"]
     Chop [Eigenvalues [jEp1 //. cF1 /. b \rightarrow 40 // N]]
     Print["Eigenvalues of Eim between b1* and bH"]
     Chop[Eigenvalues[jEim1 //. cF1 /. b \rightarrow 29.5 // N]]
     Print["Eigenvalues of E* between b1* and bH"]
     Chop[Eigenvalues[jEs1 //. cF1 /. b \rightarrow 29.5 // N]]
     Print["Eigenvalues of Eim when b=40"]
     Chop[Eigenvalues[jEim1 //. cF1 /. b \rightarrow 40 // N]]
     Print["Eigenvalues of E- between b1* and b2* "]
     Chop[Eigenvalues[jEm1 //. cF1 /. b \rightarrow 35 // N]]
     Print["Eigenvalues of E- between 0 and b1*"]
     Chop[Eigenvalues[jEm1 //. cF1 /. b \rightarrow 20 // N]]
     Eigenvalues of E∗ when b=25 and when b=40, respectively
Out[v] = \{0.0577341, -0.573937, 0.0224059 - 0.0793775 i, 0.0224059 + 0.0793775 i\}
Out[*] = {0.0363426, -0.555066, 0.017069 -0.082122 i, 0.017069 + 0.082122 i}
     Eigenvalues of E+ when b=40
Out == \{-24.7847, -0.377551, -0.150826 - 0.260466 i, -0.150826 + 0.260466 i\}
     Eigenvalues of Eim between b1∗ and bH
Out_{e} = \{-1.91852, 0.189259, 0.0221014 - 0.0653562 i, 0.0221014 + 0.0653562 i\}
     Eigenvalues of E∗ between b1∗ and bH
Out_{0} = \{-0.566329, 0.0202845 + 0.0805187 i, 0.0202845 - 0.0805187 i, 0.0490694\}
     Eigenvalues of Eim when b=40
Out[*] = \{-6.50192, 0.307571, -0.103153 + 0.233849 i, -0.103153 - 0.233849 i\}
     Eigenvalues of E− between b1* and b2*
Out[*] = \{-0.999601, 0.0879326 + 0.166504 i, 0.0879326 - 0.166504 i, -0.0384878\}
     Eigenvalues of E− between 0 and b1*
Out[\sigma]= { -0.840551 - 1.00512 i, 0.242338 + 0.343832 i,
      0.0933864 - 0.157103 i, -0.0937105 - 0.0144354 i}
```

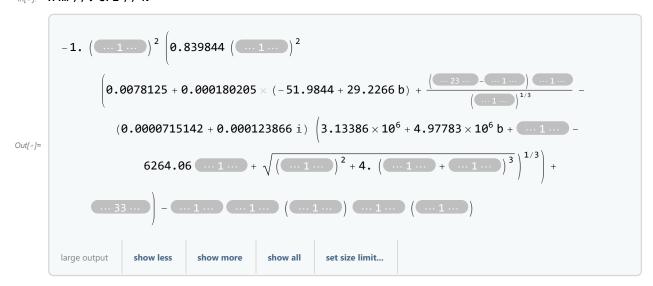
```
cut=cF1;bL=50;max=0.37;
b0n=b0//.cn;
b1=Chop[bbs//.cF1//N];
Print["b0=",b0n//N, " ,b_{b*}=", b1, ", b1*=", bc1, " , b2*=", bc2, " ,bH=",bHm]
lin1=Line[{{ bc1,0},{ bc1,max}}];
li1=Graphics[{Thick,Black,Dashed,lin1}];
lin2=Line[{{ bc2,0},{ bc2,max}}];
li2=Graphics[{Thick,Black,Dashed,lin2}];
lin3=Line[{{ b0n,0},{ b0n,max}}];
li3=Graphics[{Thick,Black,Dashed,lin3}];
lin4=Line[{{ b1,0},{ b1,max}}];
li4=Graphics[{Thick,Black,Dashed,lin4}];
pyb=Plot[{yb}//.cut,{b,0,bL},PlotStyle→{Dashed,Thick,Cyan},
PlotRange \rightarrow { {0,200}, {0,max}}, PlotLegends \rightarrow { "y_b "}];
(*pym1n=Plot[{ym}//.cut,{b,0,bL},PlotStyle→{Green,Thick},PlotRange→All,PlotPoints→200,
PlotLegends→{"E_ unstable"}];*)
pym=Plot[\{ym\}//.cut,\{b,0,bL\},PlotStyle\rightarrow \{Green,Dashed,Thick\},PlotRange\rightarrow All,PlotPoints\rightarrow 180,BlotRange\rightarrow All,PlotPoints\rightarrow 180,BlotRange\rightarrow All,PlotPoints\rightarrow 180,BlotRange\rightarrow All,PlotPoints\rightarrow 180,BlotRange\rightarrow All,PlotRange\rightarrow 180,BlotRange\rightarrow 180
PlotLegends→{"E_ unstable"}];
pyK1=Plot[0,\{b,0,b0n\},PlotStyle\rightarrow\{Magenta\},PlotRange\rightarrow All,PlotLegends\rightarrow\{"E_K stable"\}];
pyK2=Plot[0,\{b,b0n,bL\},PlotStyle\rightarrow\{Blue\},PlotRange\rightarrowAll,PlotLegends\rightarrow\{"E_K unstable"\}];
pyi=Plot[{yi}//.cut,{b,0, bL},PlotStyle→{Red,Dashed,Thick},PlotRange→All,
PlotLegends→{"E<sub>im</sub> unstable"}];
pyp=Plot[\{yp\}//.cut,\{b,b0n,bL\},PlotStyle \rightarrow \{Purple, Thick\},PlotRange \rightarrow All,
PlotLegends→{"E, stable"}];
pypn=Plot[{yp}//.cut,{b,0,b0n},PlotStyle→{Yellow, Thick},PlotRange→All,
PlotLegends \rightarrow {"E, (y<0)"}];
N[{yp}/.cut/.b\rightarrow 40,20] (*check*)
Print["Q(yp) at b0 is "]
Qy/.y→yp/.b→b0//FullSimplify
Show[pyp,pyb,li3,li1,li2,li4];
pys1=Plot[{ys}//.cut,{b,0,b1},PlotStyle→{Orange, Dotted},
PlotRange→{{0,200},{0,max}},
PlotLegends→{"E<sub>*</sub> outside domain"}];
pys2=Plot[{ys}//.cut,{b,b1,bL},PlotStyle→{Orange,Thick,Dashed},
PlotRange→{{0,200},{0,max}},
PlotLegends→{"E<sub>*</sub> unstable"}];
pH4=Plot[{H4m}//.cut,{b,0,bL},PlotStyle→{Brown,Thick},
PlotRange \rightarrow { {0,200}, {0,max}}, PlotLegends \rightarrow {"H_{im}(b)"}];
Print["y*'(b0)=",D[ys,b]/.b\u00f3b0n//.cut//N//FullSimplify]
Chop[ys/.b→b0n//.cut//N] (*Check*);
bifep1=Show[{pys2,pys1,pyi,pyp,pypn,pyK1,pyK2,pym,pH4,pyb,li3,li1,li2,li4},
Epilog\rightarrow{Text["b<sub>0</sub>",Offset[{-2,10},{ b0n//.cut,0}]],{PointSize[Large],
Style[Point[{ b0n//.cut,0}],Black]},
Text["b<sub>1*</sub>",Offset[{-8,10},{ bc1,0}]],{PointSize[Large],
Style[Point[{ bc1,0}],Purple]},
Text["b<sub>2*</sub>",Offset[{10,10},{ bc2,0}]],{PointSize[Large],
Style[Point[{ bc2,0}], Yellow]}, Text["b<sub>b*</sub>", Offset[{10,10}, { b1,0}]], {PointSize[Large],
Style[Point[{ b1,0}],Magenta]},Text["bH",Offset[{10,10},{ bHm,0}]],{PointSize[Large],
Style[Point[{ bHm,0}],Red]},AxesLabel \rightarrow {"b","y"},PlotRange \rightarrow {{-0.2,bL},{-0.1,max}}]
Export["EriB.pdf",bifep1]
```

 $b0{=}1.01149$, $b_{b\star}{=}14.0011$, $b1{\star}{=}29.361$, $b2{\star}{=}45.9232$, $bH{=}29.90350014$ $\textit{Out[\@oldsymbol{out[\@olds$ Q(yp) at b0 is Out[*]= **0** y * ' (b0) = 86.3256



Out[@]= EriB.pdf

In[•]:= H4m //. cF1 // N



(x,b)-Bifurcation diagram:

Determination of the endemic points with respect to x when ϵ =1:

 $ln[\cdot]:=$ Solve[((y1) /. vex /. y \rightarrow yex) == 0, z]

$$\begin{aligned} & \text{Out[*]=} \ \left\{ \left\{ z \rightarrow \frac{-\,c\,\gamma\,-\,\frac{c\,x\,\lambda}{\,\kappa}\,-\,\beta_z\,\,\sqrt{\frac{4\,c\,\beta_y\,\left(x\,\lambda-\frac{x^2\,\lambda}{\,\kappa}\right)}{\beta_z}\,\,+\,\left(-\,\frac{c\,\gamma}{\beta_z}\,-\,\frac{c\,x\,\lambda}{\,\kappa\,\beta_z}\,\right)^2}}{\,2\,c\,\beta_y} \,\right\}, \\ & \left\{ z \rightarrow \frac{-\,c\,\gamma\,-\,\frac{c\,x\,\lambda}{\,\kappa}\,+\,\beta_z\,\,\sqrt{\frac{4\,c\,\beta_y\,\left(x\,\lambda-\frac{x^2\,\lambda}{\,\kappa}\right)}{\beta_z}\,\,+\,\left(-\,\frac{c\,\gamma}{\beta_z}\,-\,\frac{c\,x\,\lambda}{\,\kappa\,\beta_z}\,\right)^2}}{\,2\,c\,\beta_y} \,\right\} \right\} \end{aligned}$$

```
yex=c z/\beta z; (*Frome Solve[(z1/z/.cep1)==0,y]*)
Print["ye(x)=",yex]
Print["ve(x)="]
vex=Solve[(x1/x)==0,v][[1]]
Print["ze(x)="]
zex=Solve[((y1/y)/.vex/.y\rightarrow yex)==0,z][1]]//FullSimplify
(*the first solution of z above doesn't belong to the domain*)
vnn=(v1/v/.vex/.y→yex/.zex );
vnnn=vnn/.cF1
xex=Solve[vnnn==0,x,Cubics→False];
(*or // ComplexExpand[#, TargetFunctions → {Re, Im}] &*)
(*so long time when it's not numeric**)
Print["Number of endemic x"]
Length [xex]
Print["Numerical check"]
xex/.b→40//N
```

$$\begin{aligned} ye\left(x\right) &= \frac{c\;z}{\beta_z} \\ ve\left(x\right) &= \\ \text{Out}[*] &= \left\{v \rightarrow \frac{\left(K - x - y\right)\;\lambda}{K\;\beta}\right\} \\ ze\left(x\right) &= \\ \text{Out}[*] &= \left\{z \rightarrow \frac{-c\;\left(K\;\gamma + x\;\lambda\right)\;+\;\sqrt{c\;\left(4\;K\;\left(K - x\right)\;x\;\beta_y\;\beta_z\;\lambda + c\;\left(K\;\gamma + x\;\lambda\right)\;^2\right)}}{2\;c\;K\;\beta_y}\right\} \end{aligned}$$

$$\begin{aligned} \text{Out} \text{($*]$} &= \left(87 \times \left(\frac{1}{256} \ b \left(-\frac{1}{128} - x + \sqrt{4 \times (1-x) \ x + \left(\frac{1}{128} + x \right)^2} \right) - \\ & \times \left(1 - x + \frac{1}{2} \times \left(\frac{1}{128} + x - \sqrt{4 \times (1-x) \ x + \left(\frac{1}{128} + x \right)^2} \right) \right) - \\ & \frac{1}{87} \times \left(-\frac{1}{128} - x + \sqrt{4 \times (1-x) \ x + \left(\frac{1}{128} + x \right)^2} \right) \times \\ & \left(1 - x + \frac{1}{2} \times \left(\frac{1}{128} + x - \sqrt{4 \times (1-x) \ x + \left(\frac{1}{128} + x \right)^2} \right) \right) + \\ & \frac{1}{87} \times \left(-1 + x + \frac{1}{2} \times \left(-\frac{1}{128} - x + \sqrt{4 \times (1-x) \ x + \left(\frac{1}{128} + x \right)^2} \right) \right) \right) \right) \\ & \left(2 \times \left(1 - x + \frac{1}{2} \times \left(\frac{1}{128} + x - \sqrt{4 \times (1-x) \ x + \left(\frac{1}{128} + x \right)^2} \right) \right) \right) \right) \end{aligned}$$

... Solve: Solutions may not be valid for all values of parameters.

Number of endemic x

Out[•]= 3

Numerical check

```
Out[\sigma]= { { x \to 0.00262408 }, { x \to 0.114678 }, { x \to 0.540959 }
In[@]:= (*Jacobians of the fixed points**)
     jEsx = jacD /. cep1 /. sol[[3]] /. z \rightarrow 0;
     jEmx = jacD /. cep1 /. vex /. y \rightarrow yex /. zex /. xex[[1]];
     jEimx = jacD /. cep1 /. vex /. y \rightarrow yex /. zex /. xex[[2]];
     jEpx = jacD /. cep1 /. vex /. y \rightarrow yex /. zex /. xex[3];
      (*Checks on the stability of the fixed points**)
     Print["Eigenvalues of E* : "]
     Print[" between b0 and b1* "]
     Eigenvalues[jEsx] //. cF1 /. b \rightarrow 15 // N
     Print[" between b1* and b2* "]
     Eigenvalues [jEsx] //. cF1 /. b \rightarrow 40 // N
     Print["Eigenvalues of E+ between b1* and b2*"]
     Chop[Eigenvalues[jEpx //. cF1 /. b \rightarrow 42 // N]]
     Print["Eigenvalues of Eim between b1* and b2*"]
     Chop[Eigenvalues[jEimx //. cF1 /. b \rightarrow 35 // N]]
     Print["Eigenvalues of E- between b0 and b1* "]
     Chop[Eigenvalues[jEmx //. cF1 /. b \rightarrow 15 // N]]
```

Print["Eigenvalues of E- between b1* and b2*"] Chop[Eigenvalues[jEimx //. cF1 /. b \rightarrow 40 // N]]

Chop[Eigenvalues[jEimx //. cF1 /. b \rightarrow 50 // N]]

Print["Eigenvalues of E- after b2*"]

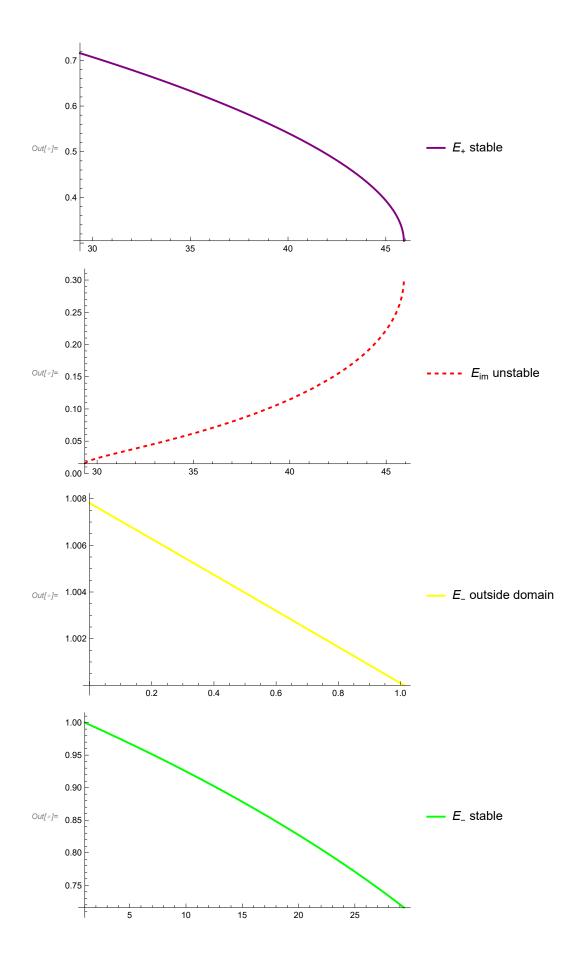
```
Eigenvalues of E_*:
        between b0 and b1*
\textit{Out[e]} = \{0.0950185, -0.606269, 0.0309604 - 0.074022 \, \text{i}, 0.0309604 + 0.074022 \, \text{i}\}
        between b1* and b2*
Out[*] = {0.0363426, -0.555066, 0.017069 -0.082122 i, 0.017069 + 0.082122 i}
       Eigenvalues of E+ between b1∗ and b2∗
Out[\sigma]= {-22.81, -0.157506 + 0.275785 i, -0.157506 - 0.275785 i, -0.301641}
       Eigenvalues of Eim between b1* and b2*
Out[*]= \{-4.10357, 0.346228, -0.0664887 + 0.180685 i, -0.0664887 - 0.180685 i\}
       Eigenvalues of E- between b0 and b1*
Out_{e} = \{-38.9444, -0.864225, -0.053898 + 0.0931984 \, i, -0.053898 - 0.0931984 \, i\}
       Eigenvalues of E- between b1* and b2*
\textit{Out[*]=} \quad \{-6.50192,\ 0.307571,\ -0.103153+0.233849\ \dot{\mathbb{1}},\ -0.103153-0.233849\ \dot{\mathbb{1}}\}
       Eigenvalues of E- after b2*
Out[\circ]= { -14.0734 + 7.77106 \dot{\mathbb{1}}, -0.136004 + 0.346012 \dot{\mathbb{1}},
        -0.181515 - 0.313963 \; \dot{\text{1}} \; , \; -0.00338735 + 0.318699 \; \dot{\text{1}} \; \}
        pc=Collect[Det[\psi IdentityMatrix[4] - (jEimx)],\psi];
In[ • ]:=
        coT=CoefficientList[pc, \psi];
        Length[coT]
        a1=coT[4] ;a2=coT[3];a3=coT[2]; a4=coT[1];
        H4=a1*a2*a3-a3^2+a1^2 a4;
        φb4=Collect[Numerator[Together[H4]],b];
        cn=Join[cF1];
        cb=NSolve[(\phi b4//.cn) ==0,b,WorkingPrecision \rightarrow 10];
        bM=Max[Table[Re[b/.cb[i]]],{i,Length[cb]}]];
        Print["bH=",bH=N[bM,50]]
Out[ • ]= 5
```

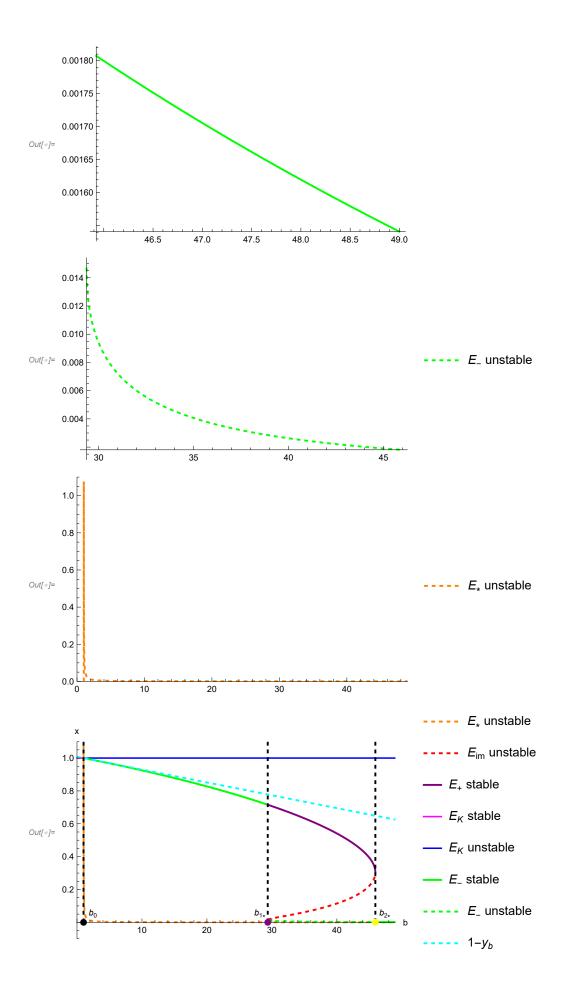
bH=45.29669903

```
cut=cF1;bL=49;max=1.1;
In[ • ]:=
                         b0n=b0//.cn;
                         b1=Chop[b/.Solve[(Es1[1])=(1-yb),b][2]//.cF1//N]
                         Print["bH=",bH, " ,b1*=",bc1, " ,b2*=",bc2]
                         lin1=Line[{{ bc1,0},{ bc1,max}}];
                         li1=Graphics[{Thick,Black,Dashed,lin1}];
                         lin2=Line[{{ bc2,0},{ bc2,max}}];
                         li2=Graphics[{Thick,Black,Dashed,lin2}];
                         lin3=Line[{{ b0n,0},{ b0n,max}}];
                         li3=Graphics[{Thick,Black,Dashed,lin3}];
                         lin4=Line[{{ b1,0},{ b1,max}}];
                         li4=Graphics[{Thick,Black,Dashed,lin4}];
                         pxp=Plot[{x/.xex[3]}}//.cut,{b,0,bL},PlotStyle→{Purple,Thick},PlotRange→All,PlotPoints→180,
                         PlotLegends→{"E, stable"}]
                         pxK1=Plot[K//.cut, \{b,0,b0n\}, PlotStyle \rightarrow \{Magenta\}, PlotRange \rightarrow All, PlotLegends \rightarrow \{"E_K stable"\}];
                         pxK2=Plot[K//.cut, \{b,b0n,bL\}, PlotStyle \rightarrow \{Blue\}, PlotRange \rightarrow All, PlotLegends \rightarrow \{"E_K unstable"\}];
                         pxi=Plot[\{x/.xex[2]\}//.cut,\{b,b0n,\ bL\},PlotStyle\rightarrow \{Red,\ Dashed,Thick\},PlotRange\rightarrow All,\{b,b0n,\ bL\},PlotRange\rightarrow All,\{b,b0
                         PlotLegends \rightarrow \{"E_{im} unstable"\}]
                         pxm0=Plot[\{x/.xex[1]\}//.cut,\{b,0,b0n\},PlotStyle\rightarrow \{Yellow, Thick\},PlotRange\rightarrow All,
                         PlotLegends→{"E<sub>-</sub> outside domain "}]
                         pxm=Plot[{x/.xex[1]}}//.cut,{b,b0n,bc1},PlotStyle→{Green, Thick},PlotRange→All,
                         PlotLegends→{"E<sub>_</sub> stable"}]
                         pxm1=Plot[\{x/.xex[1]\}//.cut,\{b,bc2,bL\},PlotStyle\rightarrow\{Green,\ Thick\},PlotRange\rightarrow All,PlotPoints\rightarrow 40]
                         pxm2=Plot[\{x/.xex[1]\}//.cut,\{b,bc1,bc2\},PlotStyle\rightarrow \{Green,Dashed, Thick\},PlotRange\rightarrow All, FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotRange,FlotF
                         PlotLegends→{"E_ unstable"}]
                         pxs=Plot[{x/.sol[3]}}//.cut,{b,0,bL},PlotStyle→{Orange,Thick,Dashed},
                         PlotRange \rightarrow { {0,bL}, {0,max}},
                         PlotLegends→{"E<sub>*</sub> unstable"}]
                         pxb=Plot[{1-yb}//.cut, {b,0,bL},PlotStyle→{Dashed,Thick,Cyan},
                         PlotRange \rightarrow { {0,bL}, {0,max}}, PlotLegends \rightarrow {"1-y<sub>b</sub>"}];
                         bifep1=Show[{pxs,pxi,pxp,pxK1,pxK2,pxm,pxm1,pxm2,(*pxm0,*)pxb,li3,li1,li2,li4},
                         Epilog \rightarrow \{Text["b_0", Offset[\{10,10\}, \{b0n/.cut,0\}]], \{PointSize[Large], \{b0n/.cut,0\}]\}
                         Style[Point[{ b0n//.cut,0}],Black]},
                         Text["b<sub>1*</sub>",Offset[{-8,10},{ bc1,0}]],{PointSize[Large],
                         Style[Point[{ bc1,0}],Purple]},
                         Text["b<sub>2*</sub>",Offset[{10,10},{ bc2,0}]],{PointSize[Large],
                         Style[Point[{ bc2,0}],Yellow]},Text["b_{b_*}",Offset[{\emptyset,10},{ b1,0}]],{PointSize[Large]},\\
                         Style[Point[{ b1,0}],Magenta]}},AxesLabel→{"b","x"},PlotRange→{{-0.1,bL},{-0.1,max}}]
                         Export["Bif1x.pdf",bifep1]
```

```
Out[\circ]= 128.989
```

bH=1.152364263 ,b1*=29.361 ,b2*=45.9232





```
Out[*]= Bif1x.pdf
In[@]:= (*Some checks*)
      Print["between b0 and b1*; E-="]
      {x /. xex[2], yex[2] /. zex /. xex[2],
           v /. vex /. y \rightarrow yex /. (zex) /. xex[[2]], z /. zex /. xex[[2]] } //. cut /. b \rightarrow 15 // N
      Print["with yb="]
     yb //. cut /. b \rightarrow 15 // N
      Print["between b1* and b2*; E-="]
      {x /. xex[2], yex[2] /. zex /. xex[2],}
           v /. vex /. y \rightarrow yex /. (zex) /. xex[2], z /. zex /. xex[2]} //. cut /. b \rightarrow 35 // N
      Print[" after b2*; E-="]
      \{x /. xex[2], yex[2] /. zex /. xex[2],
           v /. vex /. y \rightarrow yex /. (zex) /. xex[2], z /. zex /. xex[2]} //. cut /. b \rightarrow 47 // N
      Print["between b0 and b1*; E*="]
      sol[3] //. cut /. b \rightarrow 15 // N
      Print[" between b1* and b2*; E*="]
      sol[3] //. cut /. b \rightarrow 35 // N
      Print["After b2*; E*="]
      sol[3] //. cut /. b \rightarrow 47 // N
      between b0 and b1\star; E-=
Out[*]= {0.878336, 0.107541, 0.000324678, 0.107541}
     with yb=
Out[*]= 0.109375
      between b1* and b2*; E_-\!=\!
Out[\circ] = \{0.00405931, 0.0579238, 0.0215636, 0.0579238\}
       after b2∗; E-=
Out[*]= {0.0017057, 0.0367794, 0.0221038, 0.0367794}
      between b0 and b1*; E*=
Out[*]= \{x \to 0.000821018, y \to 0.0950185, v \to 0.0207853\}
       between b1* and b2*; E*=
Out[*]= \{x \to 0.000338066, y \to 0.0414636, v \to 0.0220275\}
     After b2*; E*=
Out[*]= \{x \to 0.000249875, y \to 0.030985, v \to 0.0222705\}
```

```
(*Endemic x using the elimination**)
                                         elx = Eliminate[
                                                                     Thread[({x1/x, y1/y, v1, z1/z} /. cep1/. cKga1) == {0, 0, 0, 0}], {y, v, z}];
                                         Qx = (elx[1] - elx[2]);
                                           Print["Coefficients of Qx by elim polynomial are:"]
                                           cofx = CoefficientList[Qx, x] // FullSimplify;
                                         Length[cofx]
                                           solx = x /. Solve[Qx == 0, x, Cubics \rightarrow False] (*Third order roots*)
                                         solx //. cF1 /. b \rightarrow 40 // N
                                        Coefficients of Qx by elim polynomial are:
Out[ ]= 4
Out 0 = \{ \text{Root} [-b c^2 \beta \beta_v \delta + c^2 \beta_v \delta \lambda + c \beta_v \beta_v \beta_v \delta_z \delta \lambda - c^2 \beta_v \delta^2 \lambda - c^2 \beta_v \delta^2 \lambda \} 
                                                                               c \beta_v^2 \beta_z \delta^2 \lambda + (-b c^2 \beta^2 \beta_v + b^2 c^2 \beta^2 \beta_v + c^2 \beta \beta_v \lambda - b c^2 \beta \beta_v \lambda + c \beta \beta_v \beta_v \beta_z \lambda -
                                                                                                           2 b c \beta \beta_{v} \beta_{v} \beta_{z} \lambda - 2 c^{2} \beta \beta_{v} \delta \lambda + b c^{2} \beta \beta_{v} \delta \lambda - c \beta_{v} \beta_{v} \beta_{z} \delta \lambda - 2 c \beta \beta_{v}^{2} \beta_{z} \delta \lambda +
                                                                                                           c \beta_v^2 \beta_z \delta^2 \lambda + c \beta_v^2 \beta_z \lambda^2 + \beta_v^2 \beta_v \beta_z^2 \lambda^2 + c^2 \beta_v \delta \lambda^2 + c \beta_v \beta_v \beta_z \delta \lambda^2  \pm 1 + c \beta_v \beta_z \delta^2 \lambda + c \beta_v \beta_z \delta \lambda^2 + c \beta_v \beta_z \delta \lambda^2 + c \beta_v \delta \lambda^2 + c \delta_v \delta \delta
                                                                                  (-c^2 \beta^2 \beta_v \lambda + b c^2 \beta^2 \beta_v \lambda - c \beta \beta_v \beta_v \beta_z \lambda + 2 b c \beta \beta_v \beta_v \beta_z \lambda - c \beta^2 \beta_v^2 \beta_z \lambda + 2 c \beta \beta_v^2 \beta_z \delta \lambda +
                                                                                                             c^{2} \beta \beta_{v} \lambda^{2} - b c^{2} \beta \beta_{v} \lambda^{2} - c \beta_{v}^{2} \beta_{z} \lambda^{2} + c \beta \beta_{v} \beta_{v} \beta_{z} \lambda^{2} - 2 \beta_{v}^{2} \beta_{v} \beta_{z}^{2} \lambda^{2} - c \beta_{v} \beta_{v} \beta_{z} \delta \lambda^{2}) \mp 1^{2} + c \beta \beta_{v} \beta_{v} \beta_{z} \delta \lambda^{2} + c \beta \beta_{v} \beta_{v} \beta_{z} \delta \lambda^{2} + c \beta \beta_{v} \beta_{v} \delta_{z} \delta \lambda^{2} + c \beta \beta_{v} \delta_{v} \delta_{z} \delta \lambda^{2} + c \beta \delta_{v} \delta_{v} \delta_{z} \delta \lambda^{2} + c \beta \delta_{v} \delta_{v} \delta_{z} \delta_{v} \delta_{v} \delta_{v} \delta_{z} \delta_{v} \delta_{v}
                                                                                  (c \beta^2 \beta_v^2 \beta_z \lambda - c \beta \beta_v \beta_v \beta_z \lambda^2 + \beta_v^2 \beta_v \beta_z^2 \lambda^2) \pm 1^3 \&, 1],
                                                 Root \left[ -b c^2 \beta \beta_v \delta + c^2 \beta_v \delta \lambda + c \beta_v \beta_v \beta_z \delta \lambda - c^2 \beta_v \delta^2 \lambda - c \beta_v^2 \beta_z \delta^2 \lambda + c \beta_v \delta_v \delta_z \delta \lambda \right]
                                                                                 (-b c^2 \beta^2 \beta_v + b^2 c^2 \beta^2 \beta_v + c^2 \beta \beta_v \lambda - b c^2 \beta \beta_v \lambda + c \beta \beta_v \beta_v \beta_z \lambda -
                                                                                                             2 b c \beta \beta_{v} \beta_{v} \beta_{z} \lambda - 2 c^{2} \beta \beta_{v} \delta \lambda + b c^{2} \beta \beta_{v} \delta \lambda - c \beta_{v} \beta_{v} \beta_{z} \delta \lambda - 2 c \beta \beta_{v}^{2} \beta_{z} \delta \lambda +
                                                                                                           c \beta_v^2 \beta_z \delta^2 \lambda + c \beta_v^2 \beta_z \lambda^2 + \beta_v^2 \beta_v \beta_z^2 \lambda^2 + c^2 \beta_v \delta \lambda^2 + c \beta_v \beta_v \beta_z \delta \lambda^2  \pm 1 +
                                                                                  (-c^2 \beta^2 \beta_v \lambda + b c^2 \beta^2 \beta_v \lambda - c \beta \beta_v \beta_v \beta_z \lambda + 2 b c \beta \beta_v \beta_v \beta_z \lambda - c \beta^2 \beta_v^2 \beta_z \lambda + 2 c \beta \beta_v^2 \beta_z \delta \lambda +
                                                                                                          c^{2} \beta \beta_{v} \lambda^{2} - b c^{2} \beta \beta_{v} \lambda^{2} - c \beta_{v}^{2} \beta_{z} \lambda^{2} + c \beta \beta_{v} \beta_{y} \beta_{z} \lambda^{2} - 2 \beta_{v}^{2} \beta_{y} \beta_{z}^{2} \lambda^{2} - c \beta_{v} \beta_{y} \beta_{z} \delta \lambda^{2})  \sharp \mathbf{1}^{2} + b c^{2} \beta \beta_{v} \lambda^{2} + c \beta \beta_{v} \beta_{z} \lambda^{2} + c \beta_{v} \beta_{z} \lambda^{2} + c
                                                                                  (c \beta^2 \beta_v^2 \beta_z \lambda - c \beta \beta_v \beta_v \beta_z \lambda^2 + \beta_v^2 \beta_v \beta_z^2 \lambda^2) \pm 1^3 \&, 2],
                                                  Root \left[ -b c^2 \beta \beta_v \delta + c^2 \beta_v \delta \lambda + c \beta_v \beta_v \beta_z \delta \lambda - c^2 \beta_v \delta^2 \lambda - c \beta_v^2 \beta_z \delta^2 \lambda + c \beta_v \beta_v \delta \lambda + c \beta_v \delta_v \delta \lambda \right]
                                                                                  (-b c^2 \beta^2 \beta_v + b^2 c^2 \beta^2 \beta_v + c^2 \beta \beta_v \lambda - b c^2 \beta \beta_v \lambda + c \beta \beta_v \beta_v \beta_z \lambda -
                                                                                                           2 b c \beta \beta_v \beta_v \beta_z \lambda - 2 c^2 \beta \beta_v \delta \lambda + b c^2 \beta \beta_v \delta \lambda - c \beta_v \beta_v \beta_z \delta \lambda - 2 c \beta \beta_v^2 \beta_z \delta \lambda +
                                                                                                           c \beta_{y}^{2} \beta_{z} \delta^{2} \lambda + c \beta_{y}^{2} \beta_{z} \lambda^{2} + \beta_{y}^{2} \beta_{y} \beta_{z}^{2} \lambda^{2} + c^{2} \beta_{y} \delta \lambda^{2} + c \beta_{y} \beta_{y} \beta_{z} \delta \lambda^{2})  \sharp 1 +
                                                                                  \left(c \beta^{2} \beta_{v}^{2} \beta_{z} \lambda - c \beta \beta_{v} \beta_{v} \beta_{z} \lambda^{2} + \beta_{v}^{2} \beta_{v} \beta_{z}^{2} \lambda^{2}\right) \sharp \mathbf{1}^{3} \&, 3\right]
Out[*]= \{0.000294987, -19.9296 - 34.5878 i, -19.9296 + 34.5878 i\}
```