On a four-dimensional oncolytic Virotherapy model (*E*=1)

This Mathematica Notebook is a supplementary material to the paper "On a three-dimensional and two four-dimensional

oncolytic viro-therapy models". It contains some of the calculations and illustrations appearing in the paper.

Ep1)Section 3.5(in paper): 4-Dim.Viro-therapy model when $\epsilon=1$

Ep1-1)Definition of the model and fixed points when ϵ =1

```
In[1]:= SetDirectory[NotebookDirectory[]];
                     AppendTo[$Path, Directory];
                     Clear["Global`*"];
                     Clear["K"];
                     (*Some aliases*)
                     Format[\betay] = Subscript[\beta, y];
                     Format[\betav] = Subscript[\beta, v];
                     Format[\beta z] = Subscript[\beta, z];
                    Unprotect[Power];
                     Power[0, 0] = 1;
                     Protect[Power];
                     par = \{b, \beta, \lambda, \delta, \beta y, \beta v, \beta z, c, \gamma, K, \epsilon\};
                     cp = Join[Thread[Drop[par, {1}] > 0], {b > 1}];
                     cKga1 = \{K \rightarrow 1, \gamma \rightarrow 1\};
                     cep1 = \{\epsilon \rightarrow 1\};
                     R0 = b \beta K / (\beta K + \delta) (* Reproduction number*);
                     (*cnb={b→50};
                     cE1ri=Join[\{\beta y\rightarrow 1/48, K\rightarrow 2139.258, \beta\rightarrow .0002, \lambda\rightarrow .2062, \beta\rightarrow .2062
                                     \gamma \rightarrow 1/18, \delta \rightarrow .025, \beta v \rightarrow 2*10^{\circ}(-8), c \rightarrow 10^{\circ}(-3), \beta z \rightarrow .027}, cep1];*)
                    \mathsf{CF1} = \left\{ \beta \to \frac{87}{2}, \ \lambda \to 1, \ \gamma \to \frac{1}{128}, \ \delta \to 1 \ / \ 2, \ \beta \mathsf{y} \to 1, \ \beta \mathsf{v} \to 1, \ \mathsf{K} \to 1, \ \beta \mathsf{z} \to 1, \ \mathsf{c} \to 1, \ \varepsilon \to 1 \right\};
                     (****** Four dim Deterministic epidemic model with Logistic growth ****)
                     x1 = \lambda x (1 - (x + y) / K) - \beta x v;
                    y1 = \beta \times V - \beta y y z - \gamma y;
                    v1 = -\beta x v - \beta v v z + b \gamma y - \delta v;
                     z1 = z (\beta z y - c z^{\epsilon});
                     dyn = \{x1, y1, v1, z1\};
                     dyn3 = \{x1, y1, v1\} /. z \rightarrow 0; (*3dim case used for E* *)
                   Print[" (y')=", dyn // FullSimplify // MatrixForm]
                     Print["b0=", b0 = b /. Apart[Solve[R0 == 1, b] [1]] // FullSimplify]]
                      (***Fixed point when z→0**)
                     eq = Thread[dyn3 == \{0, 0, 0\}];
                     sol = Solve[eq, {x, y, v}] // FullSimplify;
                     Es = \{x, y, v\} /. sol[3]; (*Endemic point with z=0*);
                     Print[" Endemic point with z=0 is E*=", Es // FullSimplify]
                     jacD = Grad[dyn /. cep1, {x, y, v, z}];
                     Print["J(x,y,v,z) ="]
                     jacD // MatrixForm
                     Print["Det(J(x,y,v,z))="]
                     Det[jacD] // FullSimplify
```

Endemic point with z=0 is E*=

$$\Big\{\frac{\delta}{\left(-\mathbf{1}+\mathbf{b}\right)\ \beta}\text{, }\frac{\left(\ \left(-\mathbf{1}+\mathbf{b}\right)\ \mathsf{K}\ \beta-\delta\right)\ \delta\ \lambda}{\left(-\mathbf{1}+\mathbf{b}\right)\ \beta\ \left(\ \left(-\mathbf{1}+\mathbf{b}\right)\ \mathsf{K}\ \beta\gamma+\delta\ \lambda\right)}\text{, }\frac{\gamma\ \left(\ \left(-\mathbf{1}+\mathbf{b}\right)\ \mathsf{K}\ \beta-\delta\right)\ \lambda}{\beta\ \left(\ \left(-\mathbf{1}+\mathbf{b}\right)\ \mathsf{K}\ \beta\gamma+\delta\ \lambda\right)}\Big\}$$

$$J(x,y,v,z) =$$

Out[29]//MatrixForm=

Det(J(x,y,v,z)) =

$$\begin{array}{l} \text{Out} [31] = \begin{array}{l} \displaystyle \frac{1}{K} \\ \\ \displaystyle \left(2\,c\,z\,\left(K\,v\,\beta\,\left(z\,\beta_y + \gamma\right)\right)\,\left(z\,\beta_v + \delta\right) + v\,x\,\beta\,\left(z\,\beta_v + \delta\right)\,\lambda - K\,\left(x\,\beta\,\left(z\,\beta_y + \gamma - b\,\gamma\right) + \left(z\,\beta_y + \gamma\right)\right)\,\left(z\,\beta_v + \delta\right)\right) \\ \\ \displaystyle \lambda + \,\left(2\,x + y\right)\,\left(x\,\beta\,\left(z\,\beta_y + \gamma - b\,\gamma\right) + \left(z\,\beta_y + \gamma\right)\,\left(z\,\beta_v + \delta\right)\right)\lambda\right) - \\ \\ \displaystyle \beta_z\,\left(K\,y\,\gamma\,\left(\left(-1 + b\right)\,x\,\beta - z\,\beta_v - \delta\right)\,\lambda - y\,\left(2\,x + y\right)\,\gamma\,\left(\left(-1 + b\right)\,x\,\beta - z\,\beta_v - \delta\right)\,\lambda + \\ \\ \displaystyle v\,x\,\beta\,\left(-2\,x\,z\,\beta_v + y\,\delta\right)\,\lambda + K\,v\,\beta\,\left(y\,\gamma\,\left(z\,\beta_v + \delta\right) + x\,z\,\beta_v\,\lambda\right)\right)\right) \end{array}$$

```
(****Fixed points of 4-dim model using P(y) ***)
In[32]:=
        fy=(c \gamma(b-1)-y \betay \betaz);
        gy=(\beta v \beta z y+c \delta); hy=(\gamma +y \beta z \beta y/c);
        xey=hy gy/(\beta fy); vey=y fy/gy; zey= \betaz y /c;
        ys=y/.sol[3](* y of E*
        Py=\lambda(1-y/K)-\beta y fy/gy-\lambda hy gy/(\beta K fy); yb=c \gamma (b-1)/(\betay \betaz);
        Qy=\lambda fy gy(1- y /K)- \lambda hy gy^2/(\beta K)-y \beta fy^2;
        Qycol=Collect[Together[Qy],y];
        Qycoef=CoefficientList[Qycol,y];
        Print["f(y) = ", fy, ", g(y) = ", gy, ", h(y) = ", hy]
        Print["p(y) =", Py//FullSimplify]
        Print["The polynomial Q(y) is of order ", Length[Qycoef]-1]
        Print["Coefficients of Q(y) are ", Qycoef//FullSimplify]
        Dis=Collect[Discriminant[Qy,y],b];
        Discoef=CoefficientList[Dis,b];Length[Discoef];
        Disn=Dis//.cF1//N;
        bL=50;
        Plot[{0,Disn},{b,0,2 bL},AxesLabel→{"b","Dis"},PlotRange→{{0,bL},{-10,12}}]
        Print["Roots of Dis[b]=0 are: ",solbE=Solve[Disn==0,b]]
```

$$f\left(y\right)=-y\;\beta_{y}\;\beta_{z}\;+\;\left(-1+b\right)\;c\;\gamma\;\text{ ,g}\left(y\right)=y\;\beta_{v}\;\beta_{z}\;+\;c\;\delta\;\text{ , }\;h\left(y\right)=\frac{y\;\beta_{y}\;\beta_{z}}{c}\;+\;\gamma$$

$$p\left(y\right) = \frac{y\;\beta\;\left(y\;\beta_{y}\;\beta_{z}\;-\;\left(-1+b\right)\;c\;\gamma\right)}{y\;\beta_{v}\;\beta_{z}\;+\;c\;\delta}\;+\;\lambda\;-\;\frac{y\;\lambda}{K}\;-\;\frac{\left(\frac{y\;\beta_{y}\;\beta_{z}}{c}\;+\;\gamma\right)\;\left(y\;\beta_{v}\;\beta_{z}\;+\;c\;\delta\right)\;\lambda}{K\;\beta\;\left(-y\;\beta_{y}\;\beta_{z}\;+\;\left(-1+b\right)\;c\;\gamma\right)}$$

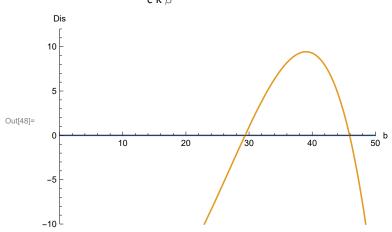
The polynomial Q(y) is of order 3

Coefficients of Q(y) are
$$\left\{ \frac{c^2 \, \gamma \, (\, (-1+b) \, \, K \, \beta - \delta) \, \, \delta \, \lambda}{K \, \beta} \right.$$

$$-\frac{c\;\left(\beta_{z}\;\left(\delta\;\left(2\;\beta_{v}\;\gamma+\beta_{y}\;\delta\right)\;+\;\mathsf{K}\;\beta\;\left(\beta_{v}\;\gamma-\mathsf{b}\;\beta_{v}\;\gamma+\beta_{y}\;\delta\right)\right)\;\lambda\;+\;\left(-\mathsf{1}\;+\;\mathsf{b}\right)\;c\;\beta\;\gamma\;\left(\;\left(-\mathsf{1}\;+\;\mathsf{b}\right)\;\mathsf{K}\;\beta\;\gamma\;+\;\delta\;\lambda\right)\;\right)}{\mathsf{K}\;\beta}\;\mathsf{,}$$

$$\frac{\beta_{z}\,\left(-\beta_{v}\,\beta_{z}\,\left(K\,\beta\,\beta_{y}+\beta_{v}\,\gamma+2\,\beta_{y}\,\delta\right)\,\lambda+c\,\beta\,\left(2\times\left(-1+b\right)\,K\,\beta\,\beta_{y}\,\gamma+\beta_{v}\,\left(\gamma-b\,\gamma\right)\,\lambda+\beta_{y}\,\delta\,\lambda\right)\right)}{K\,\beta}\,\text{,}$$

$$-\frac{\beta_{\boldsymbol{y}}\;\beta_{\boldsymbol{z}}^{2}\;\left(\beta_{\boldsymbol{v}}^{2}\;\beta_{\boldsymbol{z}}\;\lambda+c\;\beta\;\left(\boldsymbol{K}\;\beta\;\beta_{\boldsymbol{y}}-\beta_{\boldsymbol{v}}\;\lambda\right)\right.\right)}{c\;\boldsymbol{K}\;\beta}\;\right\}$$



Roots of Dis[b] = 0 are:

$$\{\,\{b\rightarrow -126.518\}\,\text{, }\{b\rightarrow -63.\}\,\text{, }\{b\rightarrow -63.\}\,\text{, }\{b\rightarrow -24.5518\}\,\text{, }\{b\rightarrow 29.361\}\,\text{, }\{b\rightarrow 45.9232\}\,\}$$

```
QR=Solve[Qy==0,y,Cubics→False]//ToRadicals(*casus irreducibilis*);
In[50]:=
        ym= y/.QR[[2]];
        yp= y/.QR[[1]];yi= y/.QR[[3]];
        Em1={xey,ym,vey,zey}//.y→ym;
        Ep1={xey,yp,vey,zey}//.y→yp;
        Eim1={xey,yi,vey,zey}//.y→yi;
        Es1=Join[{x,y,v}/.sol[3],{0}];
        {Chop[yp],Chop[ym]}//.cF1//N;
        jacE1K=jacD/.x\rightarrow K/.y\rightarrow 0/.v\rightarrow 0/.z\rightarrow 0;
        Print["J(EK) =", jacE1K//MatrixForm]
        (*Jacobians of the fixed points**)
        jEs1=jacD/.sol[3]/.z\rightarrow0;
        jEm1=jacD/.x→xey/.v→vey/.z→zey/.y→ym;
        jEim1=jacD/.x→xey/.v→vey/.z→zey/.y→yi;
        jEp1=jacD/.x→xey/.v→vey/.z→zey/.y→yp;
        Print["Eig.val of J(EK) are:", Eigenvalues[jacE1K]//FullSimplify]
        jacE1=jacD/.x→xey/.v→vey/.z→zey/.y→y//FullSimplify;
        jacE1 //MatrixForm;
        Det[jacE1]//FullSimplify;
        Print[" Trace of either Ei, E+ or E- is : ", Tr[jacE1]//FullSimplify]
        Print["J(E *) is"]
        jEs1//FullSimplify//MatrixForm
        bbs=b/.Solve[yb==(y/.sol[3]),b][1](*long expression*);
```

$$\begin{split} & J\left(\mathsf{EK}\right) = \begin{pmatrix} -\lambda & -\lambda & -\mathsf{K} \, \beta & 0 \\ 0 & -\gamma & \mathsf{K} \, \beta & 0 \\ 0 & 0 & \gamma & \mathsf{K} \, \beta & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \\ & \mathsf{Eig.val} \ \, \text{of} \ \, J\left(\mathsf{EK}\right) \ \, \text{are} \colon \left\{0\,,\, \frac{1}{2} \left(-\mathsf{K} \, \beta - \gamma - \delta - \sqrt{-4 \, \gamma \, \left(\mathsf{K} \, \left(\beta - b \, \beta\right) \, + \delta\right) \, + \left(\mathsf{K} \, \beta + \gamma + \delta\right)^{\, 2}}\,\right)\,, \\ & \frac{1}{2} \left(-\mathsf{K} \, \beta - \gamma - \delta + \sqrt{-4 \, \gamma \, \left(\mathsf{K} \, \left(\beta - b \, \beta\right) \, + \delta\right) \, + \left(\mathsf{K} \, \beta + \gamma + \delta\right)^{\, 2}}\,\right)\,, \\ & \mathsf{Trace} \ \, \text{of} \ \, \text{either} \ \, \mathsf{Ei}\,, \ \, \mathsf{E+} \ \, \text{or} \ \, \mathsf{E-} \ \, \mathsf{is} \, \colon -y \, \beta_z \, - \frac{y \, \beta_y \, \beta_z + c \, \gamma}{c} \, + \frac{y^2 \, \beta \, \beta_y \, \beta_z}{y \, \beta_v \, \beta_z + c \, \delta} \, - \\ & \frac{\left(-1 + b\right) \, c \, y \, \beta \, \gamma}{y \, \beta_v \, \beta_z + c \, \delta} \, + \frac{b \, \gamma \, \left(y \, \beta_v \, \beta_z + c \, \delta\right)}{y \, \beta_y \, \beta_z - \left(-1 + b\right) \, c \, \gamma} \, + \lambda \, - \frac{y \, \lambda}{\mathsf{K}} \, - \frac{2 \, \left(\frac{y \, \beta_y \, \beta_z}{c} \, + \gamma\right) \, \left(y \, \beta_v \, \beta_z + c \, \delta\right) \, \lambda}{\mathsf{K} \, \beta \, \left(-y \, \beta_y \, \beta_z + \left(-1 + b\right) \, c \, \gamma\right)} \, \\ \mathsf{J}\left(\mathsf{E}_- \star\right) \ \, \mathsf{is} \end{split}$$

Out[70]//MatrixForm=

$$\begin{pmatrix} \frac{\delta \lambda}{\mathsf{K} \, \beta \mathsf{-b} \, \mathsf{K} \, \beta} & \frac{\delta \lambda}{\mathsf{K} \, \beta \mathsf{-b} \, \mathsf{K} \, \beta} & -\frac{\delta}{\mathsf{-1} \mathsf{+b}} & \mathbf{0} \\ \frac{\gamma \, ((-1 + \mathsf{b}) \, \mathsf{K} \, \beta \mathsf{-b} \, \lambda) \, \lambda}{(-1 + \mathsf{b}) \, \mathsf{K} \, \beta \, \gamma \mathsf{+} \delta \, \lambda} & -\gamma & \frac{\delta}{\mathsf{-1} \mathsf{+b}} & \frac{\beta_{\mathsf{y}} \, \delta \, \left(\mathsf{K} \, \left(\beta \mathsf{-b} \, \beta\right) + \delta\right) \, \lambda}{(-1 + \mathsf{b}) \, \beta \, \left(\left(-1 + \mathsf{b}\right) \, \mathsf{K} \, \beta \, \gamma + \delta \, \lambda\right)} \\ \frac{\gamma \, \left(\mathsf{K} \, \left(\beta \mathsf{-b} \, \beta\right) + \delta\right) \, \lambda}{(-1 + \mathsf{b}) \, \mathsf{K} \, \beta \, \gamma + \delta \, \lambda} & \mathbf{b} \, \gamma & \frac{\mathsf{b} \, \delta}{\mathsf{1} \mathsf{-b}} & \frac{\beta_{\mathsf{y}} \, \gamma \, \left(\mathsf{K} \, \left(\beta \mathsf{-b} \, \beta\right) + \delta\right) \, \lambda}{\beta \, \left(\left(-1 + \mathsf{b}\right) \, \mathsf{K} \, \beta \, \gamma + \delta \, \lambda\right)} \\ \frac{\delta}{\mathsf{0}} & \mathbf{0} & \mathbf{0} & \frac{\beta_{\mathsf{z}} \, \left(\left(-1 + \mathsf{b}\right) \, \mathsf{K} \, \beta \, \gamma + \delta \, \lambda\right)}{(-1 + \mathsf{b}) \, \beta \, \left(\left(-1 + \mathsf{b}\right) \, \mathsf{K} \, \beta \, \gamma + \delta \, \lambda\right)} \end{pmatrix}$$

Hopf bifurcation point related to b- for E-:

```
(*it takes few minutes to run*)
In[ • ]:=
        cn=Join[cF1];
        pcm=Collect[Det[\psi IdentityMatrix[4] - (jEm1)],\psi];
        coT=CoefficientList[pcm, \psi];
        Length[coT]
        a1=coT[[4]];a2=coT[[3]];a3=coT[[2]]; a4=coT[[1]];
        H4m=a1*a2*a3-a3^2+a1^2 a4//.cF1;
        φb4m=Collect[Numerator[Together[H4m]],b];
        cbm=NSolve[(\phi b4m//.cn) == 0, b, WorkingPrecision \rightarrow 10];
        bMm=Max[Table[Re[b/.cbm[i]]],{i,Length[cbm]}]];
        Print["bH-=",bHm=N[bMm,30]]
```

Out[•]= **5**

bH-=29.19440675

Ep1-2)Trace, Det and third criterion of Routh Hurwitz applied to E*:

Det and Trace of of E* and Analysis of the stability of E* in 4 dim when ϵ =1:

```
Print["Tr[J[E*]]="]
In[72]:=
            trEs1=Tr[jacD//.Join[sol[3],{z→0}]]//FullSimplify
            Print["Det[J[E*]]="]
            detEs1=Det[jacD//.Join[sol[3],{z→0}]]//FullSimplify
            pc=Collect[Det[\psi IdentityMatrix[4] - (jEs1)],\psi];
            coT=CoefficientList[pc,\psi]//FullSimplify;
            Length [coT]
            a1=coT[[4]]//FullSimplify;a2=coT[[3]]//FullSimplify;a3=coT[[2]]//FullSimplify; a4=coT[[1]]//FullSimplify
            Print["a<sub>1</sub>=",a1, ", a<sub>2</sub>=",a2, ", a<sub>3</sub>=",a3, ",a<sub>4</sub>=", a4]
            H4=a1*a2*a3-a3^2+a1^2 a4;
            Print["H2(b0)=",H4/.b→b0//FullSimplify]
            Print["Denominator of H2 is ",Denominator[Together[H4]]//FullSimplify]
            φb4=Collect[Numerator[Together[H4]],b];
            cofi=CoefficientList[φb4,b];
            Length[cofi]
            (*Print["value of \phi(b) at crit b is "]
            φb4/.b→b0//FullSimplify; (*so long expression*)*)
          Tr[J[E*]]=
             \text{K } \delta \text{ } (2 \times (-1 + b) \text{ } \beta \text{ } \gamma + b \text{ } \beta \text{ } \delta + \beta_{z} \text{ } \delta) \text{ } \lambda + \delta^{2} \text{ } \lambda^{2} + (-1 + b) \text{ } \text{K}^{2} \text{ } \beta \text{ } (\beta \text{ } \gamma \text{ } (\text{ } (-1 + b) \text{ } \gamma + b \text{ } \delta) \text{ } - \beta_{z} \text{ } \delta \text{ } \lambda) 
 Out[73]= -
                                                       (-1 + b) K \beta ((-1 + b) K \beta \gamma + \delta \lambda)
         Det[J[E*]]=
         -\frac{\beta_{z} \gamma \delta^{2} (K (\beta - b \beta) + \delta)^{2} \lambda^{2}}{(-1 + b)^{2} K \beta^{2} ((-1 + b) K \beta \gamma + \delta \lambda)}
 Out[78]= 5
```

In[87]:=

b2 * = 45.9232

```
a_{1} = \frac{\mathsf{K} \ \delta \ (2 \times (-1 + \mathsf{b}) \ \beta \ \gamma + \mathsf{b} \ \beta \ \delta + \beta_{\mathsf{z}} \ \delta) \ \lambda + \delta^{2} \ \lambda^{2} + (-1 + \mathsf{b}) \ \mathsf{K}^{2} \ \beta \ (\beta \ \gamma \ ((-1 + \mathsf{b}) \ \gamma + \mathsf{b} \ \delta) \ - \beta_{\mathsf{z}} \ \delta \ \lambda)}{\mathsf{b} \ \beta \ \beta \ \beta}
                                                                                                                                                                                                                                                                       (-1 + b) K \beta ((-1 + b) K \beta \gamma + \delta \lambda)
                                                      , a_2 = ((\delta \lambda (-((-1+b) K^2 \beta^2 ((-1+b) (\beta + \beta_z) \gamma + b \beta_z \delta)) + (b \beta + \beta_z) \delta^2 \lambda 
                                                                                                           \mathsf{K} \beta \left(\beta_{\mathsf{z}} \delta \left( \left( -\mathbf{1} + \mathsf{b} \right) \gamma + \mathsf{b} \delta + \lambda - \mathsf{b} \lambda \right) + \left( -\mathbf{1} + \mathsf{b} \right) \beta \gamma \left( \left( -\mathbf{1} + \mathsf{b} \right) \gamma + \delta - \lambda + \mathsf{b} \left( \delta + \lambda \right) \right) \right) \right) / \mathsf{c}
                                                                          ((-1+b)^2 K \beta^2 ((-1+b) K \beta \gamma + \delta \lambda))), a_3 =
                                                        \left( \, \left( \, \left( \, \left( \, \left( \, -1 + b \right) \, \, \mathsf{K} \, \beta - \delta \right) \, \, \delta \, \, \lambda \, \, \left( \delta^2 \, \left( \, \left( \, -1 + b \right) \,^2 \, \beta \, \gamma - b \, \beta_z \, \, \delta \right) \, \, \lambda^2 + \, \left( \, -1 + b \right) \,^2 \, \mathsf{K}^2 \, \beta^2 \, \gamma \, \, \left( \, \left( \, -1 + b \right) \,^2 \, \beta \, \gamma^2 + \beta_z \, \, \delta \, \lambda \right) \, + \, \lambda^2 \, \, \right) \, \, \lambda^2 + \, \lambda^2 \, \, \lambda^2 + \, \lambda^2 \, \, \lambda^2 + \, \lambda^2 \, \lambda^2 \, \lambda^2 \, \lambda^2 + \, \lambda^2 \, \lambda^2 \, \lambda^2 \, \lambda^2 + \, \lambda^2 \, \lambda^2 \, \lambda^2 \, \lambda^2 \, \lambda^2 \, \lambda^2 + \, \lambda^2 \,
                                                                                                             (-1 + b) K \beta \gamma \delta \lambda (2 (-1 + b)^2 \beta \gamma - \beta_z ((-1 + b) \gamma + \delta - \lambda + b (\delta + \lambda))))
                                                                         \left(\,\left(\,\mathbf{-1}+b\right)^{\,3}\,K\,\,\beta^{\,2}\,\,\left(\,\left(\,\mathbf{-1}+b\right)\,\,K\,\,\beta\,\,\gamma\,+\,\delta\,\,\lambda\,\right)^{\,2}\,\right)\,\right) \quad \text{, } \mathbf{a}_{4}=-\,\frac{\,\beta_{z}\,\,\gamma\,\,\delta^{\,2}\,\,\left(\,K\,\,\left(\,\beta\,-\,b\,\,\beta\,\right)\,\,+\,\delta\,\right)^{\,2}\,\,\lambda^{\,2}}{\left(\,\mathbf{-1}+b\right)^{\,2}\,K\,\,\beta^{\,2}\,\,\left(\,\left(\,\mathbf{-1}+b\right)\,\,K\,\,\beta\,\,\gamma\,+\,\delta\,\,\lambda\,\right)}
                                            H2(b0) = 0
                                            Denominator of H2 is (-1+b)^6 K^3 \beta^5 ((-1+b) K \beta \gamma + \delta \lambda)^4
Out[86]= 11
                                               Numerical values \epsilon=1:
                                                      cn=Join[cF1]; cnb=\{b\rightarrow 40\};
                                                        cb=NSolve[(\phi b4//.cn) == 0, b, WorkingPrecision \rightarrow 10]
                                                        bM=Max[Table[Re[b/.cb[i]]],{i,Length[cb]}]];
                                                        Print["bH=",bH=N[bM,30]]
                                                        Print["b0=",b0/.cn//N]
                                                      Print["E*",Es1//.cn/.cnb//N]
                                                        Print["E+=",Em1//.cn/.cnb//N]
                                                        Print["Eim=",Eim1//.cn/.cnb//N]
                                                        Print["roots of Dis[b]=0:", bcE1=NSolve[(Dis//.cn)==0,b]]
                                                        bc1=Chop[Evaluate[b/.bcE1[5]]];
                                                        bc2=Chop[Evaluate[b/.bcE1[[6]]]];
                                                      Print["b1*=", bc1]
                                                        Print[" b2*=", bc2]
Out[88]= \{\,\{\,b \to -258.7317419\,\}\,\text{, }\{\,b \to -0.01615999598\,\}\,\text{,}
                                                         \{b \rightarrow 0.060848063 - 10.686990738 \pm \}, \{b \rightarrow 0.060848063 + 10.686990738 \pm \},
                                                         \{b \to 0.8448282668 - 0.9299250641 \pm \}, \{b \to 0.8448282668 + 0.9299250641 \pm 1.92982848 + 0.9299250641 \pm 1.929828 + 0.929250641 \pm 1.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.929828 + 0.928828 + 0.929828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.928828 + 0.92884 + 0.928848 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884 + 0.92884
                                                         \{b \to 0.8878046288\}, \{b \to 1.011494253\}, \{b \to 1.022996712\}, \{b \to 1.152364263\}\}
                                              bH=1.152364263
                                              b0=1.01149
                                               E * \{0.000294724, 0.0363426, 0.0221463, 0.\}
                                              E += \left\{0.00262408 + 5.51068 \times 10^{-19} \text{ i, } 0.0462057 + 8.67362 \times 10^{-18} \text{ i,} \right.
                                                               0.021866 + 3.02367 \times 10^{-18} i, 0.0462057 + 8.67362 \times 10^{-18} i}
                                              Eim=\{0.114678 - 9.26732 \times 10^{-17} \text{ i}, 0.263221 - 2.77556 \times 10^{-17} \text{ i}, 
                                                               0.0143012 + 8.58446 \times 10^{-18} i, 0.263221 - 2.77556 \times 10^{-17} i
                                              roots of Dis[b]=0:
                                                      \{\{b \rightarrow -126.518\}, \{b \rightarrow -63.\}, \{b \rightarrow -63.\}, \{b \rightarrow -24.5518\}, \{b \rightarrow 29.361\}, \{b \rightarrow 45.9232\}\}
                                              b1 * = 29.361
```

Ep1-3)Bifurcation diagrams:

Numerical solution of the stability (Bifurcation diagram) wrt y:

```
In[100]:= (*Checks on the stability of the fixed points**)
                  Print["Eigenvalues of E* when b=20 and when b=40, respectively "]
                   Eigenvalues[jEs1] //. cF1 /. b \rightarrow 20 // N
                   Eigenvalues[jEs1] //. cF1 /. b \rightarrow 40 // N
                  Print["Eigenvalues of E+ when b=40"]
                  Chop[Eigenvalues[jEp1 //. cF1 /. b \rightarrow 20 // N]]
                  Print["Eigenvalues of Eim when b=40"]
                  Chop[Eigenvalues[jEim1 //. cF1 /. b \rightarrow 40 // N]]
                  Print["Eigenvalues of E- between b1* and b2* "]
                  Chop[Eigenvalues[jEm1 //. cF1 /. b \rightarrow 35 // N]]
                  Print["Eigenvalues of E- between 0 and b1*"]
                  Chop[Eigenvalues[jEm1 //. cF1 /. b \rightarrow 20 // N]]
                  Eigenvalues of E∗ when b=20 and when b=40, respectively
Out[101] = \{0.0718263, -0.586224, 0.0257451 - 0.0774375 i, 0.0257451 + 0.0774375 i\}
Out[102]= \{0.0363426, -0.555066, 0.017069 - 0.082122 i, 0.017069 + 0.082122 i\}
                   Eigenvalues of E+ when b=40
Out[104]= \{-36.8126, -0.800277, -0.073135 + 0.126319 i, -0.073135 - 0.126319 i\}
                   Eigenvalues of Eim when b=40
Out[106]= \{-6.50192, 0.307571, -0.103153 + 0.233849 i, -0.103153 - 0.233849 i\}
                  Eigenvalues of E− between b1* and b2*
Out[108] = \{-0.999601, 0.0879326 + 0.166504 i, 0.0879326 - 0.166504 i, -0.0384878\}
                   Eigenvalues of E− between 0 and b1*
Out[110]= \{-0.840551 - 1.00512 \,\dot{\mathbb{1}}, \, 0.242338 + 0.343832 \,\dot{\mathbb{1}}, \, 0.242338 + 0.3438332 \,\dot{\mathbb{1}}, \, 0.242338 + 0.343832 \,\dot{\mathbb{1}}, \, 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 + 0.242338 
                     0.0933864 - 0.157103 i, -0.0937105 - 0.0144354 i }
```

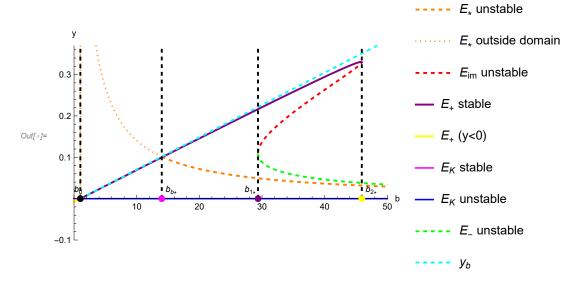
```
cut=cF1;bL=50;max=0.37;
In[ • ]:=
                  b0n=b0//.cn;
                  b1=Chop[bbs//.cF1//N];
                  Print["b0=",b0n//N, " ,b_{b*}=", b1, ", b1*=", bc1, " , b2*=", bc2]
                  lin1=Line[{{ bc1,0},{ bc1,max}}];
                  li1=Graphics[{Thick,Black,Dashed,lin1}];
                  lin2=Line[{{ bc2,0},{ bc2,max}}];
                  li2=Graphics[{Thick,Black,Dashed,lin2}];
                  lin3=Line[{{ b0n,0},{ b0n,max}}];
                  li3=Graphics[{Thick,Black,Dashed,lin3}];
                  lin4=Line[{{ b1,0},{ b1,max}}];
                  li4=Graphics[{Thick,Black,Dashed,lin4}];
                  pyb=Plot[{yb}//.cut,{b,0,bL},PlotStyle→{Dashed,Thick,Cyan},
                  PlotRange \rightarrow { {0,200}, {0,max}}, PlotLegends \rightarrow { "y_b "}];
                   (*pym1n=Plot[{ym}//.cut,{b,0,bL},PlotStyle→{Green,Thick},PlotRange→All,PlotPoints→200,
                  PlotLegends→{"E_ unstable"}];*)
                  pym=Plot[\{ym\}//.cut,\{b,0,bL\},PlotStyle\rightarrow \{Green,Dashed,Thick\},PlotRange\rightarrow All,PlotPoints\rightarrow 180,BlotRange\rightarrow All,PlotPoints\rightarrow 180,BlotRange\rightarrow All,PlotPoints\rightarrow 180,BlotRange\rightarrow All,PlotPoints\rightarrow 180,BlotRange\rightarrow All,PlotRange\rightarrow 180,BlotRange\rightarrow 180
                  PlotLegends→{"E_ unstable"}];
                  pyK1=Plot[0,\{b,0,b0n\},PlotStyle\rightarrow\{Magenta\},PlotRange\rightarrow All,PlotLegends\rightarrow\{"E_K stable"\}];
                  pyK2=Plot[0,\{b,b0n,bL\},PlotStyle\rightarrow\{Blue\},PlotRange\rightarrowAll,PlotLegends\rightarrow\{"E_K unstable"\}];
                  pyi=Plot[{yi}//.cut,{b,0, bL},PlotStyle→{Red,Dashed,Thick},PlotRange→All,
                  PlotLegends→{"E<sub>im</sub> unstable"}];
                  pyp=Plot[\{yp\}//.cut,\{b,b0n,bL\},PlotStyle \rightarrow \{Purple, Thick\},PlotRange \rightarrow All,
                  PlotLegends→{"E, stable"}];
                  pypn=Plot[{yp}//.cut,{b,0,b0n},PlotStyle→{Yellow, Thick},PlotRange→All,
                  PlotLegends \rightarrow {"E, (y<0)"}];
                  N[{yp}/.cut/.b\rightarrow 40,20] (*check*)
                  Print["Q(yp) at b0 is "]
                  Qy/.y→yp/.b→b0//FullSimplify
                  Show[pyp,pyb,li3,li1,li2,li4];
                  pys1=Plot[\{ys\}//.cut,\{b,0,b1\},PlotStyle\rightarrow\{0range,\ Dotted\},
                  PlotRange→{{0,200},{0,max}},
                  PlotLegends→{"E<sub>*</sub> outside domain"}];
                  pys2=Plot[{ys}//.cut,{b,b1,bL},PlotStyle→{Orange,Thick,Dashed},
                  PlotRange→{{0,200},{0,max}},
                  PlotLegends→{"E<sub>*</sub> unstable"}];
                  Print["y*'(b0)=",D[ys,b]/.b→b0n//.cut//N//FullSimplify]
                  Chop[ys/.b→b0n//.cut//N](*Check*);
                  bifep1=Show[{pys2,pys1,pyi,pyp,pypn,pyK1,pyK2,pym,pyb,li3,li1,li2,li4},
                  Epilog→{Text["b<sub>0</sub>",Offset[{-2,10},{ b0n//.cut,0}]],{PointSize[Large],
                  Style[Point[{ b0n//.cut,0}],Black]},
                  Text["b<sub>1*</sub>",Offset[{-8,10},{ bc1,0}]],{PointSize[Large],
                  Style[Point[{ bc1,0}],Purple]},
                  Text["b2*",Offset[{10,10},{ bc2,0}]],{PointSize[Large],
                  Style[Point[{ bc2,0}], Yellow]}, Text["b<sub>b*</sub>", Offset[{10,10}, { b1,0}]], {PointSize[Large],
                  Style[Point[{ b1,0}],Magenta]},AxesLabel \rightarrow {"b","y"},PlotRange \rightarrow {{-0.2,bL},{-0.1,max}}]
                  Export["EriB.pdf",bifep1]
```

```
b0=1.01149 ,b_{b*}=14.0011, b1*=29.361 , b2*=45.9232
Out[\circ]= \{0.29448140956728204616 + <math>0.\times10^{-21} i\}
```

$$Q(yp)$$
 at b0 is

Out[*]= **0**

$$y*'(b0) = 86.3256$$



Out[*]= EriB.pdf

(x,b)-Bifurcation diagram:

Determination of the endemic points with respect to x when ϵ =1:

$$ln[\circ]:=$$
 Solve[((y1) /. vex /. y \rightarrow yex) == 0, z]

$$Out[*] = \left\{ \left\{ \mathbf{Z} \rightarrow \frac{-\mathbf{C} \times \lambda}{\mathbf{K}} - \beta_{\mathbf{Z}} \sqrt{\frac{4 \, \mathbf{C} \, \beta_{\mathbf{y}} \left(\mathbf{x} \, \lambda - \frac{\mathbf{x}^{2} \, \lambda}{\mathbf{K}} \right)}{\beta_{\mathbf{Z}}} + \left(-\frac{\mathbf{C} \, \gamma}{\beta_{\mathbf{z}}} - \frac{\mathbf{C} \, \mathbf{x} \, \lambda}{\mathbf{K} \, \beta_{\mathbf{z}}} \right)^{2}} \right\}.$$

$$= \mathbf{C} \times - \frac{\mathbf{C} \times \lambda}{\mathbf{K}} + \beta_{\mathbf{Z}} \sqrt{\frac{4 \, \mathbf{C} \, \beta_{\mathbf{y}} \left(\mathbf{x} \, \lambda - \frac{\mathbf{x}^{2} \, \lambda}{\mathbf{K}} \right)}{\beta_{\mathbf{Z}}} + \left(-\frac{\mathbf{C} \, \gamma}{\beta_{\mathbf{Z}}} - \frac{\mathbf{C} \, \mathbf{x} \, \lambda}{\mathbf{K} \, \beta_{\mathbf{Z}}} \right)^{2}}$$

$$\left\{z\rightarrow\frac{-\,c\,\gamma-\frac{c\,x\,\lambda}{\kappa}\,+\,\beta_{z}\,\,\sqrt{\frac{4\,c\,\beta_{y}\left(x\,\lambda-\frac{x^{2}\,\lambda}{\kappa}\right)}{\beta_{z}}\,+\,\left(-\,\frac{c\,\gamma}{\beta_{z}}\,-\,\frac{c\,x\,\lambda}{\kappa\,\beta_{z}}\right)^{2}}}{2\,c\,\beta_{y}}\right\}\right\}$$

```
yex=c z/\beta z; (*Frome Solve[(z1/z/.cep1)==0,y]*)
In[372]:=
        Print["ye(x)=",yex]
        Print["ve(x)="]
        vex=Solve[(x1/x)==0,v][[1]
        Print["ze(x)="]
        zex=Solve[((y1/y)/.vex/.y\rightarrow yex)=0,z][1]]//FullSimplify
         (*the first solution of z above doesn't belong to the domain*)
        vnn=(v1/v/.vex/.y→yex/.zex );
        vnnn=vnn/.cF1
        xex=Solve[vnnn=0,x,Cubics→False];
         (*or // ComplexExpand[#, TargetFunctions → {Re, Im}] &*)
         (*so long time when it's not numeric**)
        Print["Number of endemic x"]
        Length [xex]
        Print["Numerical check"]
        xex/.b\rightarrow 40//N
```

$$ye(x) = \frac{c z}{\beta_z}$$

$$ve(x) =$$

Out[375]=
$$\left\{ \mathbf{v} \rightarrow \frac{\left(\mathbf{K} - \mathbf{x} - \mathbf{y} \right) \ \lambda}{\mathbf{K} \ \beta} \right\}$$

$$ze(x) =$$

$$\text{Out[377]=} \left\{ \mathbf{Z} \rightarrow \frac{-\,\mathbf{C}\,\left(\mathbf{K}\,\gamma + \mathbf{x}\,\lambda\right) \,+\, \sqrt{\mathbf{C}\,\left(\mathbf{4}\,\mathbf{K}\,\left(\mathbf{K} - \mathbf{x}\right)\,\mathbf{x}\,\beta_{\mathbf{y}}\,\beta_{\mathbf{z}}\,\lambda + \mathbf{C}\,\left(\mathbf{K}\,\gamma + \mathbf{x}\,\lambda\right)^{\,2}\right)}}{\,2\,\mathbf{C}\,\mathbf{K}\,\beta_{\mathbf{y}}} \right\}$$

$$\text{Out}[379] = \left(87 \times \left(\frac{1}{256} \ b \left(-\frac{1}{128} - x + \sqrt{4 \times (1-x)} \ x + \left(\frac{1}{128} + x \right)^2 \right) - x \left(1 - x + \frac{1}{2} \times \left(\frac{1}{128} + x - \sqrt{4 \times (1-x)} \ x + \left(\frac{1}{128} + x \right)^2 \right) \right) - \frac{1}{87} \times \left(-\frac{1}{128} - x + \sqrt{4 \times (1-x)} \ x + \left(\frac{1}{128} + x \right)^2 \right) \times \left(1 - x + \frac{1}{2} \times \left(\frac{1}{128} + x - \sqrt{4 \times (1-x)} \ x + \left(\frac{1}{128} + x \right)^2 \right) \right) + \frac{1}{87} \times \left(-1 + x + \frac{1}{2} \times \left(-\frac{1}{128} - x + \sqrt{4 \times (1-x)} \ x + \left(\frac{1}{128} + x \right)^2 \right) \right) \right) \right) \right)$$

$$\left(2 \times \left(1 - x + \frac{1}{2} \times \left(\frac{1}{128} + x - \sqrt{4 \times (1-x)} \ x + \left(\frac{1}{128} + x \right)^2 \right) \right) \right) \right)$$

... Solve: Solutions may not be valid for all values of parameters.

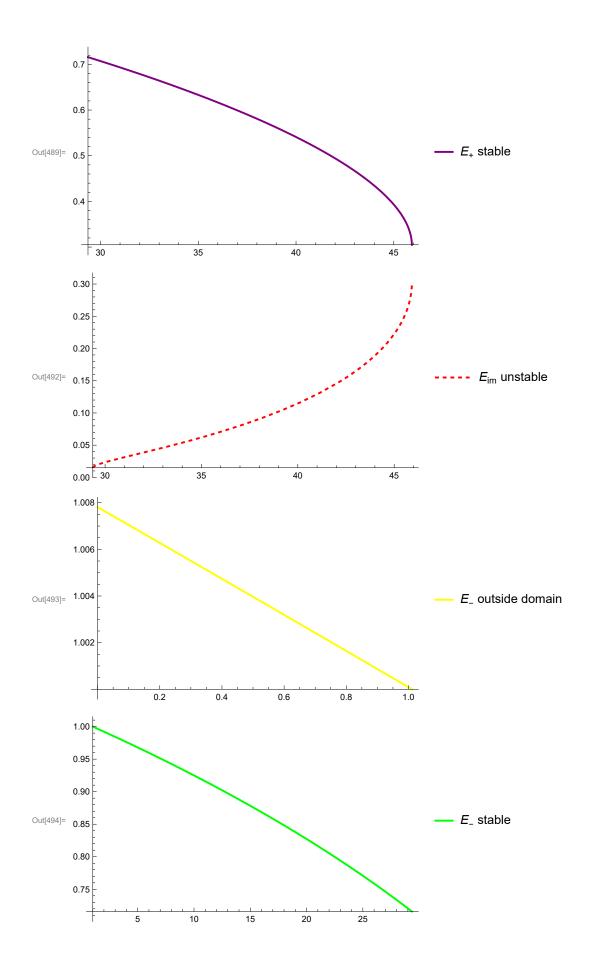
Number of endemic x

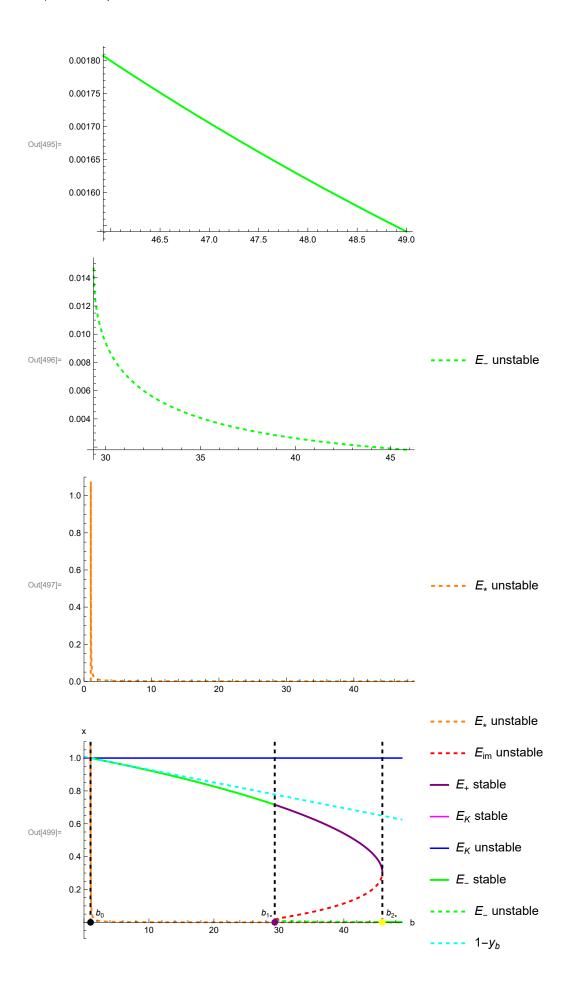
```
Numerical check
Out[384]= \{ \{ x \rightarrow 0.00262408 \}, \{ x \rightarrow 0.114678 \}, \{ x \rightarrow 0.540959 \} \}
In[385]:= (*Jacobians of the fixed points**)
       jEsx = jacD /. cep1 /. sol[[3]] /. z \rightarrow 0;
       jEmx = jacD /. cep1 /. vex /. y \rightarrow yex /. zex /. xex[[1]];
       jEimx = jacD /. cep1 /. vex /. y \rightarrow yex /. zex /. xex[2];
       jEpx = jacD /. cep1 /. vex /. y → yex /. zex /. xex[[3]];
       (*Checks on the stability of the fixed points**)
       Print["Eigenvalues of E* : "]
       Print[" between b0 and b1* "]
       Eigenvalues[jEsx] //. cF1 /. b \rightarrow 15 // N
       Print[" between b1* and b2* "]
       Eigenvalues[jEsx] //. cF1 /. b \rightarrow 40 // N
       Print["Eigenvalues of E+ between b1* and b2*"]
       Chop[Eigenvalues[jEpx //. cF1 /. b \rightarrow 42 // N]]
       Print["Eigenvalues of Eim between b1* and b2*"]
       Chop[Eigenvalues[jEimx //. cF1 /. b \rightarrow 35 // N]]
       Print["Eigenvalues of E- between b0 and b1* "]
       Chop[Eigenvalues[jEmx //. cF1 /. b \rightarrow 15 // N]]
       Print["Eigenvalues of E- between b1* and b2*"]
       Chop[Eigenvalues[jEimx //. cF1 /. b \rightarrow 40 // N]]
       Print["Eigenvalues of E- after b2*"]
       Chop[Eigenvalues[jEimx //. cF1 /. b \rightarrow 50 // N]]
       Eigenvalues of E*:
        between b0 and b1*
Out[391]= \{0.0950185, -0.606269, 0.0309604 - 0.074022 \,\dot{\mathbb{1}}, 0.0309604 + 0.074022 \,\dot{\mathbb{1}}\}
        between b1* and b2*
Out[393] = \{0.0363426, -0.555066, 0.017069 - 0.082122 i, 0.017069 + 0.082122 i\}
       Eigenvalues of E+ between b1* and b2*
\text{Out} \text{[}395\text{]=} \quad \{-22.81, -0.157506 + 0.275785 \, \text{i}, -0.157506 - 0.275785 \, \text{i}, -0.301641\}
       Eigenvalues of Eim between b1* and b2*
Out[397]= \{-4.10357, 0.346228, -0.0664887 + 0.180685 \, i, -0.0664887 - 0.180685 \, i\}
       Eigenvalues of E- between b0 and b1*
Eigenvalues of E- between b1∗ and b2∗
Out[401]= \{-6.50192, 0.307571, -0.103153 + 0.233849 i, -0.103153 - 0.233849 i\}
       Eigenvalues of E- after b2*
Out[403]= \{-14.0734 + 7.77106 \,\dot{\mathbb{1}}, -0.136004 + 0.346012 \,\dot{\mathbb{1}}, 
        -0.181515 - 0.313963 i, -0.00338735 + 0.318699 i
```

```
cut=cF1;bL=49;max=1.1;
In[477]:=
                    b0n=b0//.cn;
                    b1=Chop[b/.Solve[(Es1[1])=(1-yb),b][2]]//.cF1//N]
                    Print["bH=",bH, " ,b1*=",bc1, " ,b2*=",bc2]
                    lin1=Line[{{ bc1,0},{ bc1,max}}];
                    li1=Graphics[{Thick,Black,Dashed,lin1}];
                    lin2=Line[{{ bc2,0},{ bc2,max}}];
                    li2=Graphics[{Thick,Black,Dashed,lin2}];
                    lin3=Line[{{ b0n,0},{ b0n,max}}];
                    li3=Graphics[{Thick,Black,Dashed,lin3}];
                    lin4=Line[{{ b1,0},{ b1,max}}];
                    li4=Graphics[{Thick,Black,Dashed,lin4}];
                    pxp=Plot[{x/.xex[3]}}//.cut,{b,0,bL},PlotStyle→{Purple,Thick},PlotRange→All,PlotPoints→180,
                    PlotLegends→{"E, stable"}]
                    pxK1=Plot[K//.cut, \{b,0,b0n\}, PlotStyle \rightarrow \{Magenta\}, PlotRange \rightarrow All, PlotLegends \rightarrow \{"E_K stable"\}];
                    pxK2=Plot[K//.cut, \{b,b0n,bL\}, PlotStyle \rightarrow \{Blue\}, PlotRange \rightarrow All, PlotLegends \rightarrow \{"E_K unstable"\}];
                    pxi=Plot[\{x/.xex[2]\}//.cut,\{b,b0n,\ bL\},PlotStyle\rightarrow \{Red,\ Dashed,Thick\},PlotRange\rightarrow All,\{b,b0n,\ bL\},PlotRange\rightarrow All,\{b,b0
                    PlotLegends \rightarrow \{"E_{im} unstable"\}]
                    pxm0=Plot[\{x/.xex[1]\}//.cut,\{b,0,b0n\},PlotStyle\rightarrow \{Yellow, Thick\},PlotRange\rightarrow All,
                    PlotLegends→{"E<sub>-</sub> outside domain "}]
                    pxm=Plot[{x/.xex[1]}}//.cut,{b,b0n,bc1},PlotStyle→{Green, Thick},PlotRange→All,
                    PlotLegends→{"E<sub>_</sub> stable"}]
                    pxm1=Plot[\{x/.xex[1]\}//.cut,\{b,bc2,bL\},PlotStyle\rightarrow\{Green,\ Thick\},PlotRange\rightarrow All,PlotPoints\rightarrow 40]
                    PlotLegends→{"E_ unstable"}]
                    pxs=Plot[{x/.sol[3]}}//.cut,{b,0,bL},PlotStyle→{Orange,Thick,Dashed},
                    PlotRange \rightarrow { {0,bL}, {0,max}},
                    PlotLegends→{"E<sub>*</sub> unstable"}]
                    pxb=Plot[{1-yb}//.cut, {b,0,bL},PlotStyle→{Dashed,Thick,Cyan},
                    PlotRange \rightarrow { {0,bL}, {0,max}}, PlotLegends \rightarrow {"1-y<sub>b</sub>"}];
                    bifep1=Show[{pxs,pxi,pxp,pxK1,pxK2,pxm,pxm1,pxm2,(*pxm0,*)pxb,li3,li1,li2,li4},
                    Epilog \rightarrow \{Text["b_0", Offset[\{10,10\}, \{b0n/.cut,0\}]], \{PointSize[Large], \{b0n/.cut,0\}]\}
                    Style[Point[{ b0n//.cut,0}],Black]},
                    Text["b<sub>1*</sub>",Offset[{-8,10},{ bc1,0}]],{PointSize[Large],
                    Style[Point[{ bc1,0}],Purple]},
                    Text["b<sub>2*</sub>",Offset[{10,10},{ bc2,0}]],{PointSize[Large],
                    Style[Point[{ bc2,0}],Yellow]},Text["b_{b_*}",Offset[{\emptyset,10},{ b1,0}]],{PointSize[Large]},\\
                    Style[Point[{ b1,0}],Magenta]}},AxesLabel→{"b","x"},PlotRange→{{-0.1,bL},{-0.1,max}}]
                    Export["Bif1x.pdf",bifep1]
```

```
Out[479]= 128.989
```

bH=1.152364263 ,b1*=29.361 ,b2*=45.9232





```
Out[500]= Bif1x.pdf
  In[@]:= (*Some checks*)
       Print["between b0 and b1*; E-="]
       {x /. xex[2], yex[2] /. zex /. xex[2],
             v /. vex /. y \rightarrow yex /. (zex) /. xex[[2]], z /. zex /. xex[[2]] } //. cut /. b \rightarrow 15 // N
       Print["with yb="]
       yb //. cut /. b \rightarrow 15 // N
       Print["between b1* and b2*; E-="]
       {x /. xex[2], yex[2] /. zex /. xex[2],}
             v /. vex /. y \rightarrow yex /. (zex) /. xex[2], z /. zex /. xex[2]} //. cut /. b \rightarrow 35 // N
       Print[" after b2*; E-="]
       \{x /. xex[2], yex[2] /. zex /. xex[2],
             v /. vex /. y \rightarrow yex /. (zex) /. xex[[2]], z /. zex /. xex[[2]] } //. cut /. b \rightarrow 47 // N
       Print["between b0 and b1*; E*="]
       sol[3] //. cut /. b \rightarrow 15 // N
       Print[" between b1* and b2*; E*="]
       sol[3] //. cut /. b \rightarrow 35 // N
       Print["After b2*; E*="]
       sol[3] //. cut /. b \rightarrow 47 // N
       between b0 and b1\star; E-=
 Out[*]= {0.878336, 0.107541, 0.000324678, 0.107541}
       with yb=
 Out[*]= 0.109375
       between b1* and b2*; E_-\!=\!
 Out[\circ] = \{0.00405931, 0.0579238, 0.0215636, 0.0579238\}
        after b2∗; E-=
 Out[*]= {0.0017057, 0.0367794, 0.0221038, 0.0367794}
       between b0 and b1*; E*=
 \textit{Out[@]=} \ \{x \to \textbf{0.000821018,} \ y \to \textbf{0.0950185,} \ v \to \textbf{0.0207853}\}
        between b1* and b2*; E*=
 Out[*]= \{x \to 0.000338066, y \to 0.0414636, v \to 0.0220275\}
       After b2*; E*=
 Out[*]= \{x \to 0.000249875, y \to 0.030985, v \to 0.0222705\}
```

```
(*Endemic x using the elimination**)
                                         elx = Eliminate[
                                                                     Thread[({x1/x, y1/y, v1, z1/z} /. cep1/. cKga1) == {0, 0, 0, 0}], {y, v, z}];
                                         Qx = (elx[1] - elx[2]);
                                         Print["Coefficients of Qx by elim polynomial are:"]
                                           cofx = CoefficientList[Qx, x] // FullSimplify;
                                         Length[cofx]
                                         solx = x /. Solve[Qx = 0, x, Cubics \rightarrow False] (*Third order roots*)
                                         solx //. cF1 /. b \rightarrow 40 // N
                                         Coefficients of Qx by elim polynomial are:
Out[ ]= 4
Out 0 = \{ \text{Root} [-b c^2 \beta \beta_v \delta + c^2 \beta_v \delta \lambda + c \beta_v \beta_v \beta_v \delta_z \delta \lambda - c^2 \beta_v \delta^2 \lambda - c^2 \beta_v \delta^2 \lambda \} 
                                                                               c \beta_v^2 \beta_z \delta^2 \lambda + (-b c^2 \beta^2 \beta_v + b^2 c^2 \beta^2 \beta_v + c^2 \beta \beta_v \lambda - b c^2 \beta \beta_v \lambda + c \beta \beta_v \beta_v \beta_z \lambda -
                                                                                                           2 b c \beta \beta_{v} \beta_{v} \beta_{z} \lambda - 2 c^{2} \beta \beta_{v} \delta \lambda + b c^{2} \beta \beta_{v} \delta \lambda - c \beta_{v} \beta_{v} \beta_{z} \delta \lambda - 2 c \beta \beta_{v}^{2} \beta_{z} \delta \lambda +
                                                                                                           c \beta_v^2 \beta_z \delta^2 \lambda + c \beta_v^2 \beta_z \lambda^2 + \beta_v^2 \beta_v \beta_z^2 \lambda^2 + c^2 \beta_v \delta \lambda^2 + c \beta_v \beta_v \beta_z \delta \lambda^2  \pm 1 + c \beta_v \beta_z \delta^2 \lambda + c \beta_v \beta_z \delta \lambda^2 + c \beta_v \beta_z \delta \lambda^2 + c \beta_v \delta \lambda^2 + c \delta_v \delta \delta
                                                                                  (-c^2 \beta^2 \beta_v \lambda + b c^2 \beta^2 \beta_v \lambda - c \beta \beta_v \beta_v \beta_z \lambda + 2 b c \beta \beta_v \beta_v \beta_z \lambda - c \beta^2 \beta_v^2 \beta_z \lambda + 2 c \beta \beta_v^2 \beta_z \delta \lambda +
                                                                                                            c^{2} \beta \beta_{v} \lambda^{2} - b c^{2} \beta \beta_{v} \lambda^{2} - c \beta_{v}^{2} \beta_{z} \lambda^{2} + c \beta \beta_{v} \beta_{v} \beta_{z} \lambda^{2} - 2 \beta_{v}^{2} \beta_{v} \beta_{z}^{2} \lambda^{2} - c \beta_{v} \beta_{v} \beta_{z} \delta \lambda^{2}) \mp 1^{2} + c \beta \beta_{v} \beta_{v} \beta_{z} \delta \lambda^{2} + c \beta \beta_{v} \beta_{v} \beta_{z} \delta \lambda^{2} + c \beta \beta_{v} \beta_{v} \delta_{z} \delta \lambda^{2} + c \beta \beta_{v} \delta_{v} \delta_{z} \delta \lambda^{2} + c \beta \delta_{v} \delta_{v} \delta_{z} \delta \lambda^{2} + c \beta \delta_{v} \delta_{v} \delta_{z} \delta_{v} \delta_{v} \delta_{v} \delta_{z} \delta_{v} \delta_{v}
                                                                                  (c \beta^2 \beta_v^2 \beta_z \lambda - c \beta \beta_v \beta_v \beta_z \lambda^2 + \beta_v^2 \beta_v \beta_z^2 \lambda^2) \pm 1^3 \&, 1],
                                                 Root \left[ -b c^2 \beta \beta_v \delta + c^2 \beta_v \delta \lambda + c \beta_v \beta_v \beta_z \delta \lambda - c^2 \beta_v \delta^2 \lambda - c \beta_v^2 \beta_z \delta^2 \lambda + c \beta_v \delta_v \delta_z \delta \lambda \right]
                                                                                 (-b c^2 \beta^2 \beta_v + b^2 c^2 \beta^2 \beta_v + c^2 \beta \beta_v \lambda - b c^2 \beta \beta_v \lambda + c \beta \beta_v \beta_v \beta_z \lambda -
                                                                                                            2 b c \beta \beta_{v} \beta_{v} \beta_{z} \lambda - 2 c^{2} \beta \beta_{v} \delta \lambda + b c^{2} \beta \beta_{v} \delta \lambda - c \beta_{v} \beta_{v} \beta_{z} \delta \lambda - 2 c \beta \beta_{v}^{2} \beta_{z} \delta \lambda +
                                                                                                           c \beta_v^2 \beta_z \delta^2 \lambda + c \beta_v^2 \beta_z \lambda^2 + \beta_v^2 \beta_v \beta_z^2 \lambda^2 + c^2 \beta_v \delta \lambda^2 + c \beta_v \beta_v \beta_z \delta \lambda^2  \pm 1 +
                                                                                  (-c^2 \beta^2 \beta_v \lambda + b c^2 \beta^2 \beta_v \lambda - c \beta \beta_v \beta_v \beta_z \lambda + 2 b c \beta \beta_v \beta_v \beta_z \lambda - c \beta^2 \beta_v^2 \beta_z \lambda + 2 c \beta \beta_v^2 \beta_z \delta \lambda +
                                                                                                          c^{2} \beta \beta_{v} \lambda^{2} - b c^{2} \beta \beta_{v} \lambda^{2} - c \beta_{v}^{2} \beta_{z} \lambda^{2} + c \beta \beta_{v} \beta_{y} \beta_{z} \lambda^{2} - 2 \beta_{v}^{2} \beta_{y} \beta_{z}^{2} \lambda^{2} - c \beta_{v} \beta_{y} \beta_{z} \delta \lambda^{2})  \sharp \mathbf{1}^{2} + b c^{2} \beta \beta_{v} \lambda^{2} + c \beta \beta_{v} \beta_{z} \lambda^{2} + c \beta_{v} \beta_{z} \lambda^{2} + c
                                                                                  (c \beta^2 \beta_v^2 \beta_z \lambda - c \beta \beta_v \beta_v \beta_z \lambda^2 + \beta_v^2 \beta_v \beta_z^2 \lambda^2) \pm 1^3 \&, 2],
                                                  Root \left[ -b c^2 \beta \beta_v \delta + c^2 \beta_v \delta \lambda + c \beta_v \beta_v \beta_z \delta \lambda - c^2 \beta_v \delta^2 \lambda - c \beta_v^2 \beta_z \delta^2 \lambda + c \beta_v \beta_v \delta \lambda + c \beta_v \delta_v \delta \lambda \right]
                                                                                  (-b c^2 \beta^2 \beta_v + b^2 c^2 \beta^2 \beta_v + c^2 \beta \beta_v \lambda - b c^2 \beta \beta_v \lambda + c \beta \beta_v \beta_v \beta_z \lambda -
                                                                                                           2 b c \beta \beta_v \beta_v \beta_z \lambda - 2 c^2 \beta \beta_v \delta \lambda + b c^2 \beta \beta_v \delta \lambda - c \beta_v \beta_v \beta_z \delta \lambda - 2 c \beta \beta_v^2 \beta_z \delta \lambda +
                                                                                                           c \beta_v^2 \beta_z \delta^2 \lambda + c \beta_v^2 \beta_z \lambda^2 + \beta_v^2 \beta_v \beta_z^2 \lambda^2 + c^2 \beta_v \delta \lambda^2 + c \beta_v \beta_v \beta_z \delta \lambda^2 \end{pmatrix} \ddagger 1 +
                                                                                  \left(c \beta^{2} \beta_{v}^{2} \beta_{z} \lambda - c \beta \beta_{v} \beta_{v} \beta_{z} \lambda^{2} + \beta_{v}^{2} \beta_{v} \beta_{z}^{2} \lambda^{2}\right) \sharp \mathbf{1}^{3} \&, 3\right]
Out[*]= \{0.000294987, -19.9296 - 34.5878 i, -19.9296 + 34.5878 i\}
```