

# MATH 20C Notes - Week Two

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## 1 Introduction

Why the yellow chalk?

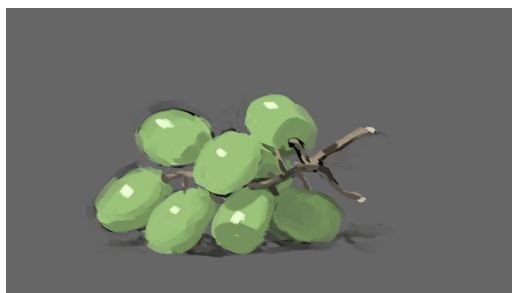
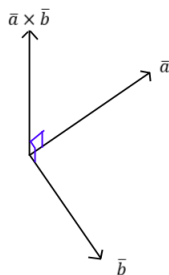


Figure 1: Some grapes

## 2 The Cross Product

While the dot product is used to take two equal-length sequences of numbers and return a single number, we can use **the cross product** in order to multiply and get vectors in 3D.



$$\begin{bmatrix} i & j & k \\ a & b & c \\ d & e & f \end{bmatrix} \begin{array}{l} \leftarrow \text{unit} \\ \leftarrow \vec{v} \\ \leftarrow \vec{w} \end{array}$$

**This method does not work in 2D.**

## Example

$$\begin{aligned} \vec{v} &= (1, 2, 3) \quad \vec{w} = (4, 5, 6) \\ \vec{v} \times \vec{w} &= \begin{bmatrix} i & j & k \\ 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} = (2 \cdot 6 - 3 \cdot 5)\hat{i} - (1 \cdot 6 - 3 \cdot 4)\hat{j} + (1 \cdot 5 - 2 \cdot 4)\hat{k} \\ &= -3\hat{i} + 6\hat{j} - 3\hat{k} \end{aligned}$$

This gives us the direction of the cross product.

## 2.1 Triple Product Formula

We can find the product of three 3-dimensional vectors with the **triple product**

$$\vec{a} = (a_1, a_2, a_3) \quad \vec{b} = (b_1, b_2, b_3) \quad \vec{c} = (c_1, c_2, c_3)$$

$$\text{Triple Product} = (\vec{a} \times \vec{b}) \cdot \vec{c} = \begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix}$$

3x3 Determinants equal zero if and only if the 3 row vectors lie on a single plane.

Because of this,  $\vec{a} \times \vec{b}$  is orthogonal to the plane spanned by  $\vec{a}$  and  $\vec{b}$   
 $\vec{a} \times \vec{b}$  is orthogonal/perpendicular to both  $\vec{a}$  and  $\vec{b}$

## Consequences

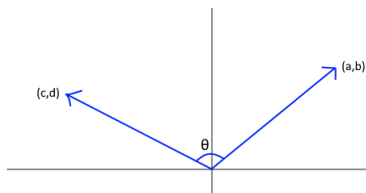
1. If  $\vec{a}$  and  $\vec{b}$  are co-linear (the same line through the origin), then  $\vec{a} \times \vec{b} = (0, 0, 0)$
2. If  $\vec{a}$  and  $\vec{b}$  are unit vectors, then  $\|\vec{a} \times \vec{b}\| = \sin(\theta)$
3. If  $\vec{a}$  and  $\vec{b}$  are perpendicular, then  $\|\vec{a}\| \cdot \|\vec{b}\| = \|\vec{a} \times \vec{b}\|$

## 3 Determinant Signs

### 3.1 2x2 Determinant Signs

If the angle from  $(a, b)$  to  $(c, d)$   $0 \leq \theta \leq \pi$ , then  $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \geq 0$

If the angle from  $(a, b)$  to  $(c, d)$   $-\pi \leq \theta \leq 0$ , then  $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \leq 0$



### 3.2 3x3 Determinant Signs

$$\vec{a} = (a_1, a_2, a_3) \quad \vec{b} = (b_1, b_2, b_3) \quad \vec{c} = (c_1, c_2, c_3)$$

If the vectors  $\vec{a}, \vec{b}, \vec{c}$  satisfy the right hand rule, then  $\begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix} \leq 0$

If the vectors  $\vec{a}, \vec{b}, \vec{c}$  fail the right hand rule (or satisfy the left hand rule),  
then  $\begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix} \geq 0$

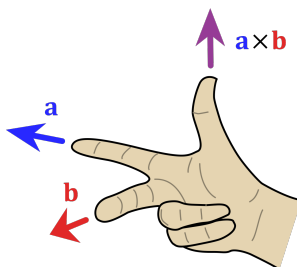


Figure 2: The Right Hand Rule helps us find the direction of the cross product using two vectors

If  $\vec{a} \times \vec{b} \neq (0, 0, 0)$ , then  $\vec{a}, \vec{b}, \vec{a} \times \vec{b}$  satisfy the right hand rule.

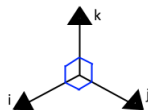


Figure 3:

$$\begin{aligned} ij &= k & jk &= i & ki &= j \\ ji &= -k & kj &= -i & ik &= -j \end{aligned}$$

$$i \times j = \begin{bmatrix} i & j & k \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} = i(0)j(0) + k(1100) = k$$

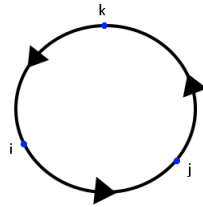


Figure 4:

## 4 Properties of the Cross Product

- $\vec{a} \times \vec{b} = (0, 0, 0)$  if and only if  $\vec{a}$  and  $\vec{b}$  are parallel
- (Skew Symmetry)  $\vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$
- $\vec{a} \times (\vec{b} + \vec{c}) = \vec{a} \times \vec{b} + \vec{a} \times \vec{c}$  and  $(\vec{a} + \vec{b}) \times \vec{c} = \vec{a} \times \vec{c} + \vec{b} \times \vec{c}$
- $(\alpha \vec{a}) \times \vec{b} = \alpha(\vec{a} \times \vec{b})$

### Warning

The cross product is not associative, so

$$(\vec{a} \times \vec{b}) \times \vec{c} \neq \vec{a} \times (\vec{b} \times \vec{c})$$

The cross product also does not interact well with the dot product (except for the triple product formula).

### Exercise

Compute  $(0, 0, 1) \times (1, 1, 0)$  AND  $(1, 0, 0) \times (1, 1, 0)$

$$(0, 0, 1) \times (1, 1, 0) = \begin{bmatrix} i & j & k \\ 0 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} = \hat{i}(0 \cdot 0 - 1 \cdot 1) - \hat{j}(0 \cdot 0 - 1 \cdot 1) + \hat{k}(0 \cdot 1 - 0 \cdot 1) = -\hat{i} + \hat{j}$$

OR

$$(0, 0, 1) = \hat{k} \quad (1, 1, 0) = \hat{i} + \hat{j}$$

$$\hat{k} \times (\hat{i} + \hat{j})$$

$$(1, 0, 0) \times (1, 1, 0) = \begin{bmatrix} i & j & k \\ 1 & 0 & 0 \\ 1 & 1 & 0 \end{bmatrix} = \hat{i}(0 \cdot 0 - 0 \cdot 1) - \hat{j}(1 \cdot 0 - 1 \cdot 0) + \hat{k}(1 \cdot 1 - 1 \cdot 0) = \hat{k}$$

OR

$$\hat{i} \times (\hat{i} + \hat{j})$$

## 5 Equation of Planes

$$\overbrace{Ax + By + Cz}^{(A, B, C) \cdot (x, y, z)} = 0$$

$P$  = solution set = all the vectors perpendicular to  $(A, B, C)$

### Solutions

Call  $(A, B, C)$  the normal vector denoted by  $\bar{n}$

If  $P$  is a plane with normal vector  $\bar{n}$  containing  $P_o = (x_o, y_o, z_o)$

Alternate Equations for Plane  $P$

$$\begin{aligned} &= \bar{n} \cdot (x - x_o, y - y_o, z - z_o) = 0 \\ &= A(x - x_o) + B(y - y_o) + C(z - z_o) = 0 \\ &= Ax + By + Cz + D = 0 \\ &(D = -Ax_o - By_o - Cz_o) \end{aligned}$$

### Example

Find the equation for the plane through  $(1, 1, 0), (1, 0, 1), (0, 1, 1)$

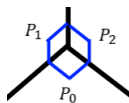


Figure 5: Needs a normal vector, given by  $\vec{a} \times \vec{b}$

**Consider**

$$\vec{a} = P_1 - P_0 = (0, -1, 1)$$

$$\vec{b} = P_2 - P_0 = (-1, 0, 1)$$

$$(0, -1, 1) \times (-1, 0, 1) = (-1, -1, -1) = (A, B, C)$$

$$P_o = (1, 1, 0) \text{ is a point in } P$$

Plane P can be found with

$$(A, B, C) \cdot (x - 1, y - 1, z - 0) = 0$$

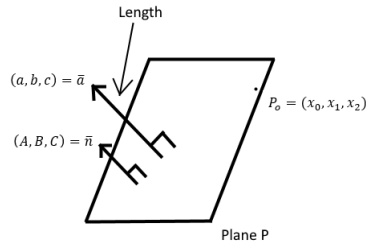
**OR**

$$(-x + 1, -y + 1 - z) = 0$$

$$-x - y - z + 2 = 0 \quad x + y + z = 2$$

## 6 Distance from a Point to a Plane

Find the distance between the point  $\vec{a}$  and the plane  $P$



### Equations

$$\vec{n} \cdot ((x, y, z) - P_o) = 0$$

**OR**

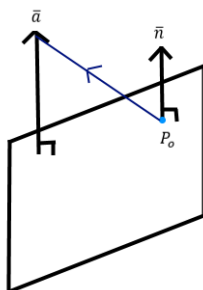
$$\vec{n} \cdot ((x - x_o, y - y_o, z - z_o)) = 0$$

**OR**

$$A(x - x_o) + B(y - y_o) + C(z - z_o) = 0 = Ax + By + Cz + D$$

We can find the line segment from  $\vec{a}$  and the plane  $P$  using the scalar multiple of the normal vector,  $\vec{n}$

The answer should be the length of the projection of  $(\vec{a} - P_o)$  onto  $\vec{n}$



The projection of  $(\vec{a} - P_o)$  onto  $\vec{n}$

$$\begin{aligned}
 & \left\| \frac{(\vec{a} - P_o) \cdot \vec{n}}{\vec{n} \cdot \vec{n}} \cdot \vec{n} \right\| \\
 &= \left\| \frac{((a, b, c) - (x_0, x_1, x_2)) \cdot (A, B, C)}{(A, B, C) \cdot (A, B, C)} \cdot (A, B, C) \right\| \\
 &= \frac{|Aa + Bb + Cc + D|}{A^2 + B^2 + C^2} \|\vec{n}\| \\
 &= \frac{|Aa + Bb + Cc + D|}{\sqrt{A^2 + B^2 + C^2}}
 \end{aligned}$$

D is the collection of constants

$$D = (x_0, x_1, x_2) \cdot (A, B, C)$$

## 7 Multi-variable Functions

We consider functions with domains/co-domains either  $\mathbb{R}$ ,  $\mathbb{R}^2$ ,  $\mathbb{R}^3$

### Case 1

A function with domains  $\mathbb{R}$  and co-domains  $\mathbb{R}$

$$f : \mathbb{R} \rightarrow \mathbb{R}^2$$

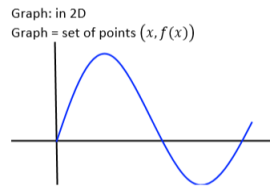


Figure 6: A Regular Real Function

## Case 2

$$\begin{array}{l}
 f : \mathbb{R} \rightarrow \underbrace{\mathbb{R}^2}_{\text{2D Vector}} \\
 \text{OR} \\
 g : \mathbb{R}^2 \rightarrow \underbrace{\mathbb{R}}_{\text{Real Number}}
 \end{array}
 \left\{ \begin{array}{l} \text{For these functions, we can still graph them} \end{array} \right\}$$

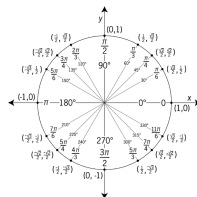
The graph of  $f$  is the set of points  $(x, f(x))$  in  $\underbrace{\mathbb{R}^3}_{\text{3D Vector}}$

## Example 1

$$f(x) = (\cos(x), \sin(x))$$

Question: What is the range of the function?

Answer: The Unit Circle



The graph of  $f(x) = (\cos(x), \sin(y))$  creates a perfect spiral.

$$g : \mathbb{R}^2 \rightarrow \mathbb{R}$$

The graph is a set of points in 3D of the form  $(x, y, g(x, y))$



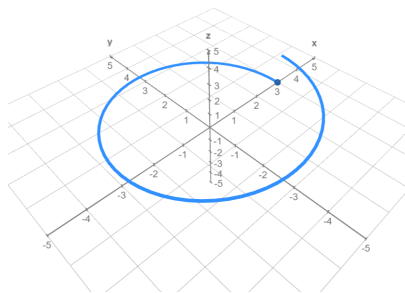


Figure 7:

### Example 2

$$g((x, y)) = (x, y) \cdot (x, y) = x^2 + y^2$$

The range of the function = All non-negative real numbers  $\mathbb{R}$

$$(x, y) = (0, 0)$$

This creates a surface

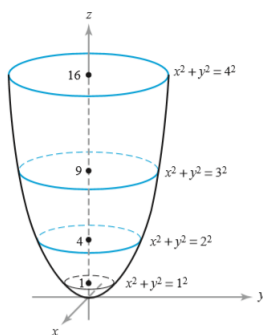


Figure 8:

## 7.1 Hard to Graph Functions

Graphs are useful when the domain and co=domain have dimensions less than three. If  $f : \mathbb{R}^3 \rightarrow \mathbb{R}$  is a function, the level set with level  $c$ , where  $c$  is a real number, is the subject of points in  $\mathbb{R}$  that map to  $c$

### Example

$$f : \mathbb{R}^3 \rightarrow \mathbb{R}$$

$$(x, y, z) \rightarrow x^2 + y^2 + z^2 = f(x, y, z)$$

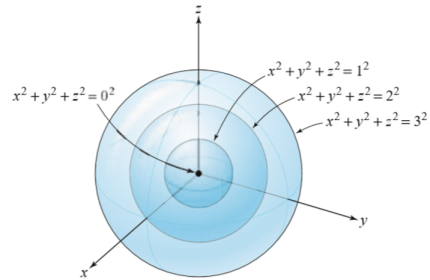


Figure 9: Also known as level surfaces

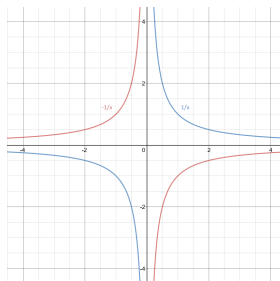
- Level 1
  - A set with length = 1
  - Sphere of radius  $\sqrt{1} = 1$
  - Set of a unit vector
- Level 2
  - A set with length 2
  - Sphere of radius  $\sqrt{2}$

### Exercise

$$g : \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$(x, y) \rightarrow x \cdot y$$

Find the level sets with level -1, 0, 1



- Level Set 0

- $xy = 0$
- $x = 0$  or  $y = 0$
- Level Set 1
  - $xy = 1$
  - $y = \frac{1}{x}$
- Level Set -1
  - $xy = -1$
  - $y = -\frac{1}{x}$

## 7.2 Taking Sections

A section of a graph in 3D is the intersection of the graph with a plane.

**Example**

$$h : \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$(x, y) \rightarrow x^2 - y^2 = h(x, y)$$

$$@ x = 0$$

$$z = h(0, y) = -y^2$$

$$@ y = 0$$

$$z = h(x, 0) = x^2$$

