More general autoregressive processes. [AR(P)]

The p-th order autoregressive process denoted AR(P) is given

$$X_{t} = \rho_{1}X_{t-1} + \rho_{2}X_{t-2} + \cdots + \rho_{\beta}X_{t-\beta} + Z_{t-\beta}$$
Where $9 \ge 23 \times NNN(0, \sigma^{2})$ and Z_{t} is uncorrelated with X_{s} , $4 \le \sqrt{2}$.

· ACF function. The autocorrelation function of a general AR(P)
is a bit complicated. It is best expressed in terms of certain recursive equations.

Note that tor h>0.

$$X_{t-h}X_{t} = \phi_{1}X_{t-h}X_{t-1} + \phi_{2}X_{t-h}X_{t-2} + \cdots + \phi_{p}X_{t-h}X_{t-p} + X_{t-h}Z_{t}$$

Taking expectation on both sides we get. $8z(h) = 9.8z(h-1) + 9.28z(h-2) + \cdots + 9.8z(h-p)$

So we get a recursive equation interms of the autocorrelations as $f_z(h) = 0$, $f_z(h-1) + 0$, $f_z(h-2) + \cdots + 0$, $f_z(h-1) + 0$.

Suppose we define a polynomial of the form,

 $\phi(\mathbf{z}) = 1 - \rho_1 z - \rho_2 z^2 - \rho_3 z^3 - \dots - \rho_{\beta} z^{\beta}$

It can be shown that if $\phi(z) = 0$ has distinct roots $\xi_1, \xi_2, \dots, \xi_{\beta}$,

then the solution of the recursive equations involving for has solution of the form

 $f_{z}(h) = \alpha_{1} \xi_{1}^{-h} + \alpha_{2} \xi_{2}^{-h} + \cdots + \alpha_{5} \xi_{5}^{-h}$

where d,, d2, ..., dp are arbitrary constants.

Now by substituting this solutions in the recursive equations above one can uniquely find $\alpha_1, \dots, \alpha_p$.

"Upshot: The ACF $f_{\mathbf{z}}$ to for an AR(b) process tails off as a mixture of exponentials decay or damped sine waves depending on the roots of q(z) = 0.

PACF of AR(P).

- Recall that by definition a AR (P) process is given by: $X_{t} = P, X_{t-1} + P_{2}X_{t-2} + \cdots + P_{b}X_{t-b} + Z_{t}$
- Note that if we fix x_{t-1} , x_{t-2} , x_{t-p} , the variables x_t and x_{t-p-1} are independent. So by definition $\alpha_{x}(h) = 0$ t h > p.
 - For h >> , we can show that the linear best predictor of X_{h+1} in terms of X_1, \cdots, X_h is given by $\hat{X}_{h+1} = \hat{\phi}_1 X_h + \hat{\phi}_2 X_{h-1} + \cdots + \hat{\phi}_p X_{h-p+1}$.

 So for $h = \hat{p}$, we get $\hat{\phi}_{hh}$ the coefficient of X_1 as $\hat{\phi}_b$.

 So $\alpha_z(\hat{p}) = \hat{\phi}_b$.
 - · For h < p we need to compute dz(h) numerically from the formula above.

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- The process is generated by the relation. $X_t = P_1 X_{t-1} + P_2 X_{t-2} + Z_t,$ $\S Z_{t} \S \vee WN(0, \sigma^2) \text{ and } Z_t \perp L \times_S + S \leq t.$
- In order to find the ACF function, let us write. $\phi_1 = \frac{1}{7} + \frac{1}{72}$ and $\phi_2 = -\frac{1}{7,72}$.

Then it can be shown that.

$$3(h) = \frac{-2\xi_1^2 + \xi_2^2}{(\xi_1 + \xi_2 - 1)(\xi_2 - \xi_1)} \left[(\xi_1^2 - 1)^{-1} \xi_1^{1-h} - (\xi_2^2 - 1)^{-1} \xi_2^{1-h} \right]$$

Note that both &, and &2 may be complex..

· The fx() can be computed directly from the print equations

$$38 \int_{R} f(h) = 3 \theta_1 f_2(h-1) + \theta_2 f_2(h) \cdot h > 1$$

AR(2) (contd.)

Thus we have a pair of equations $f_{2}^{(i)} = q_{1} + p_{2} f_{2}^{(i)}$ $f_{2}^{(i)} = q_{1} f_{2}^{(i)} + p_{2}^{(i)} + p_{3}^{(i)} + p_{4}^{(i)} + p_{$

By solving them we get $f_{2}^{(1)} = \frac{p_1}{1 - p_2}$. $f_{2}^{(2)} = \frac{p_1^2 + p_2 - p_2^2}{1 - p_2}$.

Now fa(h) can be computed recursively from the previous equation.

More generally, consider the equation. $\phi(z) = 1 - \rho_1 z - \rho_2 z^2 = 0$

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The quadratic has two solutions

$$\vec{\beta}_1 = \frac{-\varphi_1 + \sqrt{\varphi_1^2 + 4\varphi_2^2}}{2\varphi_2}$$
 and $\vec{\xi}_2 = -\frac{\varphi_1 - \sqrt{\varphi_1^2 + 4\varphi_2^2}}{2\varphi_2}$

Clearly
$$\vec{\xi}_1, \vec{\xi}_2 = -\frac{1}{p_2}$$
. Thus $\frac{1}{\xi_1} = -\frac{\xi_2 q_2}{2} = \frac{\rho_1 - \sqrt{\rho_1^2 + 4 q_2^2}}{2}$

and
$$\frac{1}{\frac{7}{2}} = -\frac{7}{19} = \frac{9}{1} + \sqrt{9^2 + 49^2}$$

So by the formula mentioned before

$$f_{z}(h) = b_{1} \left\{ \frac{q_{1} + \sqrt{q_{1}^{2} + 4q_{2}}}{2} \right\}^{h} + b_{2} \left\{ \frac{q_{1} - \sqrt{q_{1}^{2} + 4q_{2}}}{2} \right\}^{h}.$$

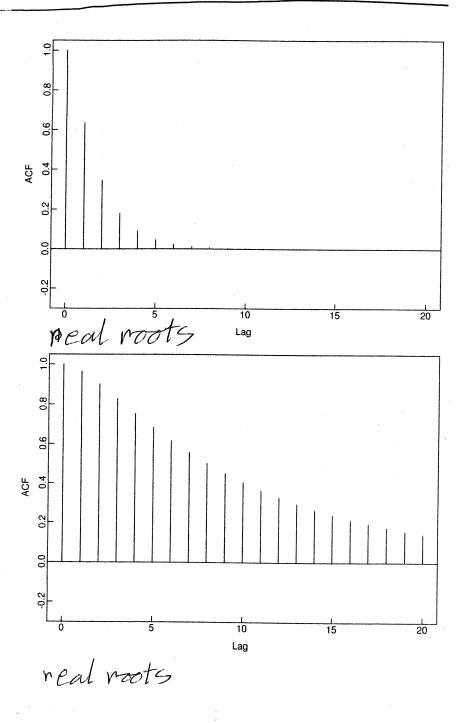
If
$$\varphi_1^2 + 4 \varphi_2 = 0$$

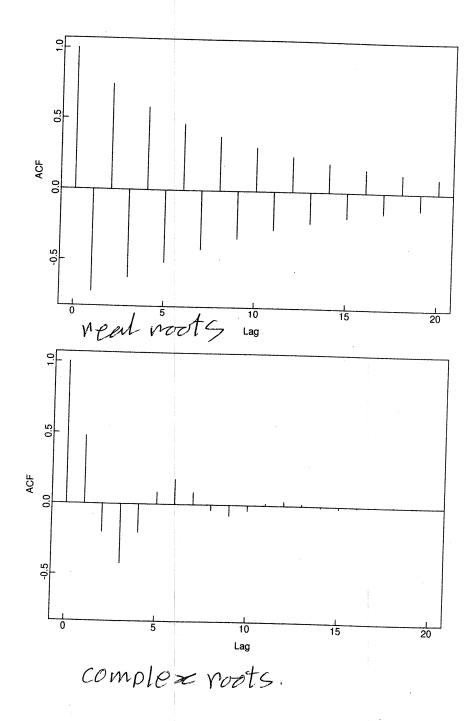
$$\int_{\mathcal{L}} h = (b_1 + b_2) \left[\frac{\varphi_1}{2} \right]^h$$

b, and be are arbitrary constant to be solved from previous two equations.

PACF for AR (2)

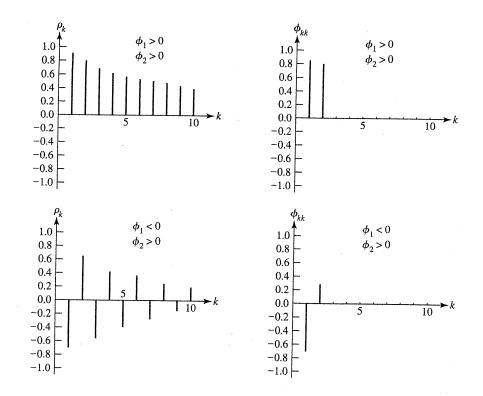
- · PACF for AR(2) is simpler to calculate.





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ACF and PACF for AR (2)



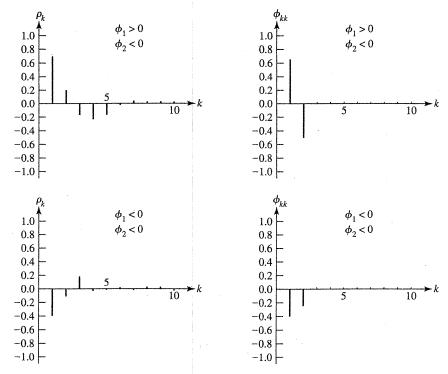


FIGURE 3.7 ACF and PACF of AR(2) process: $(1 - \phi_1 B - \phi_2 B^2) \dot{Z}_t = a_t$.

· A growing average process of order q ie MA(9) process is defined by.

$$X_{t} = Z_{t} + \theta_{1} Z_{t-1} + \theta_{2} Z_{t-2} + \cdots + \theta_{q} Z_{t-q})$$

Where { Zt3 v WN(0,02).

- Var $[X_+] = 8_z(0) = \sigma^2(1 + \frac{2}{f-1}g_p^2)$
 - · For & (h), h > 0, we consider.

$$X_{t} X_{t-h} = Z_{t} X_{t-h} + Q Z_{t-1} X_{t-h} + Q_{q} Z_{t-q} X_{t-h}$$

Now $E\left[Z_{t-i} \times_{t-n}\right] = E\left[Z_{t-i} Z_{t-n} + \theta_i Z_{t-i} Z_{t-n-i} + \theta_q Z_{t-i} Z_{t-n-q}\right]$ $= \begin{cases} \sigma^2 & \text{if } i = h \\ \theta_{i-n} \sigma^2 & \text{if } i \leq h \leq q \end{cases}$

MA(q) contd.

Thus
$$\gamma_{\mathcal{X}}(h) = \begin{cases}
\sigma^{2}(\theta_{h} + \theta_{h+i}\theta_{l} + x + \theta_{q}\theta_{q-h}) & \text{if } h = 1,2,\dots,q. \\
0 & \text{if } h > q.
\end{cases}$$

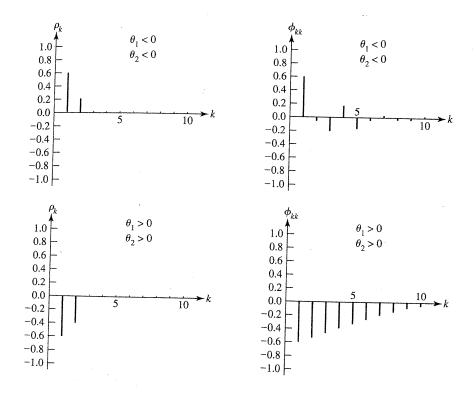
Be viding by
$$8z(0)$$
 we get.

$$Bf_{z}(h) = \begin{cases} \frac{\Theta_{n} + \Theta_{1}\Theta_{n+1} + \cdots + \Theta_{q}\Theta_{q-n}}{1 + \Theta_{1}^{2} + \cdots + \Theta_{n}^{2}}, & h = 1,2,\cdots,q \\ 0 & 0.W. \end{cases}$$

• It can be shown that the PACF of a MA(q) process will tail of exponentially coand/or in damped sign waves depending on the nature of the roots of the polynomial. $\Theta(z) = 1 + \theta_1 z + \theta_2 z^2 + \cdots + \theta_q z^q$

- The process is defined as $X_t = Z_t + \Theta_1 Z_{t-1} + \Theta_2 Z_{t-2}$ Where $3Z_t$ 3 \vee WN(0, σ^2).
 - From the formula the ACF turns out to be. $\int_{\mathcal{Z}} (h) = \begin{cases}
 \frac{\theta_1(1+\theta_2)}{1+\theta_1^2+\theta_2^2} & \text{if } h=1 \\
 \frac{\theta_2}{1+\theta_1^2+\theta_2^2} & \text{if } h=0 \\
 0 & \text{if } h \neq 2
 \end{cases}$
- The PACF can be shown to have the form. $\alpha_{z}(1) = f_{z}(1) = \frac{\theta_{1}(1+\theta_{2})}{1+\theta_{1}^{2}+\theta_{2}^{2}}$ $\alpha_{z}(2) = \frac{f_{z}(2) f_{z}(1)}{1 f_{z}(1)^{2}} \quad \text{etc.}$

ACF and PACF for MA(2).



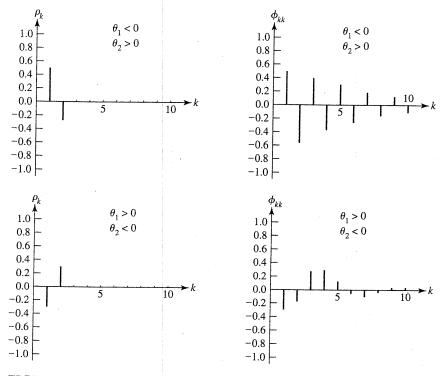


FIGURE 3.12 ACF and PACF of MA(2) processes: $Z_t = (1 - \theta_1 B - \theta_2 B^2) a_t$.

The lag operator.

- · As we have noted so far all stationary models try to predict the present or the future depending on the past.
- Such models with "lage" are more conveniently handled with a lag operator.
 - Suppose we define $B(X_t) =: BX_t := X_{t-1}$
 - B is a function which takes X_t to X_{t-1} . So $B \times_{t+h} = B \times_{t+h-1}$, $B^2 \times_{t} = B(B(X_t)) = B(X_{t-1}) = X_{t-2}$, and so on.
 - Thus as MA(1) model is. $X_{t} = Z_{t} + \theta, Z_{t-1} = (1 + \theta, B) Z_{t}$

Lag operator.

- An ARCI) will be $X_{t} = \varphi_{1} X_{t-1} + Z_{t}$ $\Rightarrow X_{t} \varphi_{1} X_{t-1} = Z_{t}$ $\Rightarrow (1 \varphi_{1} B) X_{t} = Z_{t}$
- MA(2) can be written as. $X_{t} = (1 + \theta_{1}B + \theta_{2}B^{2})Z_{t}.$
- AR(2) should be $(1-q_1B_2-q_2B_2)X_t = Z_t$
- · Polynomial in B.
- So it $\Theta(B) = 1 + \Theta_1 B + \Theta_2 B^2 + \cdots + \Theta_q B^q$, a MA(q) process is simply $X_t = \Theta(B) \neq t$ in AB
- Similarly if $\phi(B) = 1 \theta_1 B \theta_2 B^2 \dots \theta_B B^B$, an AR(P) Process is simply $\phi(B) X_t = Z_t$.

- · Dogs as Polynomials in Lag operators can be handled like polynomial in "z" (recall high school math, power series etc.).
- In particular given a $\phi(B)$ we can find an expression for $\frac{\partial \phi(B)}{\partial \phi(B)}$ another polynomial in B beay $\phi(B)$ such that $\phi(B)$ $\phi(B) = 1$. By poly
 - Now an AR(P) process is given by $\phi_p(B) X_t = Z_t$
 - So $X_t = \frac{1}{\varphi_b(B)} Z_t$.
 - If $\psi(B)$ is such that $\psi(B)$ $\varphi_p(B) = 1$, then $X_t = \psi(B)$ Ξ_t .
 - · Thus it we can find 4(B), we can write X+ as a MA pr.

AR(P) to and MA(0).

- Suppose $\psi(B)$ is a polynomial and lets restrict to AR(2), ii $\varphi(B) = 1 \varphi_1 B \varphi_2 B^2$.
- So we want $(1-q_1B-q_2B^2)(1+4_1B+4_2B^2+\cdots)=1$
- So $1 + 4_1B + 4_2B^2 + 4_3B^3 + \cdots$ • $-4_1B - 4_14_1B^2 - 4_14_2B^3 + \cdots$ $-4_2B^2 - 4_24_2B^3 + \cdots$
- Now equating coefficients of B^{\dagger} with 0 we get. $\psi_1 - \varphi_1 = 0 = 7 \quad \psi_1 = \varphi_1$ $\psi_2 - \varphi_1 \psi_1 - \varphi_2 = 0 = 7 \quad \psi_2 = \psi_1 \varphi_1 + \varphi_2 = \varphi_1^2 + \varphi_2$ and so on.
- In general we can show that for j > 2 $y_j = y_{j-1}, p_1 + y_{j-2} + p_2$

- · Note that 4j may not be zero as in general.
- · So we have a \$(B) which is like a MA(D) process. That is an MA process which depends on infinite lag.
- we need one more thing. To be a meaning ful polyromial the series $\sum_{j=0}^{\infty} Y_j Z_{t-j}$ has to converge.

 - This happens for instance if $\phi_2 = 0$ and $|\psi_1| < 1$.

 In this case we can show that $\psi_j = \phi_1^{\hat{j}}$ and we get an MA(00) process.
- · Similarly it is possible to show that some MA(q) process
- can be represent to a AR (a) process.

 In particular a MA(1) process with 10,1<1 is equivalent to an AR(0).