

Lecture 3

Neural nets and backpropagation

1. NER - Named Entity Recognition

- task of labeling words in text by **word tokens** for ex. name, date etc
- it is done by: taking each word in its fixed **context window** forming word vectors, then running through **classifier** which gives out the probability of its label
- **The classifier:**
 - so if the context window size is 5, then the input would be a 5D-vector \mathbf{x}
 - and it is passed through a neural network
 - x (input) $\in \mathbb{R}^{5d}$ — input vector
 - $h = f(Wx + b)$ — hidden layer (f is activation function)
 - $s = u^T h$ — score
 - $J_t(\theta) = \sigma(s) = \frac{1}{1+e^{-s}}$ — predicted probability (sigmoid) close to 1 if high score
- **Gradients of matrix:**

- **Jacobian Matrix: Generalization of the Gradient**

- Given a function with **m outputs** and **n inputs**

$$\mathbf{f}(x) = [f_1(x_1, x_2, \dots, x_n), \dots, f_m(x_1, x_2, \dots, x_n)]$$

- It's Jacobian is an **$m \times n$ matrix** of partial derivatives

$$\frac{\partial \mathbf{f}}{\partial \mathbf{x}} = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \cdots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \cdots & \frac{\partial f_m}{\partial x_n} \end{bmatrix}$$

$$\left(\frac{\partial \mathbf{f}}{\partial \mathbf{x}} \right)_{ij} = \frac{\partial f_i}{\partial x_j}$$

- 回味多元微积分...
- **Elementwise function:** has some special properties in which $h_i = f(x_i)$ and $\frac{\partial h}{\partial x_i}$ is computed
 - its **Jacobian matrix** is a diagonal matrix
- **simple properties**
 - $\frac{\partial}{\partial x}(Wx + b) = W$
 - $\frac{\partial}{\partial b}(Wx + b) = I$
 - $\frac{\partial}{\partial u}(u^T h) = h^T$ just if you treat a vector as row. so for word vecs, you treat it normally as column vector

2. Neural Nets

- **Working out the gradient of score function:**
 - $s = u^T h$
 - $h = f(z)$
 - $z = Wx + b$
 - so to **update \mathbf{b}** , we compute the partial derivative of s with respect to \mathbf{b}
 - $\frac{\partial s}{\partial b} = \frac{\partial s}{\partial h} \frac{\partial h}{\partial z} \frac{\partial z}{\partial b}$
 - Where $z = Wx + b$, applying chain rule:

- $= u^T \text{diag}(f'(z))I$
- $= u^T \circ f'(z)$ where the \circ is hadamard product, makes it into a $1 \times n$ row vector
- because b must be as the same shape as Wx

- **The method to update W is similar**

- Similarly, the first 2 partial derivatives are **identical**, so we can remove the need of recomputing. **Taking it as δ**

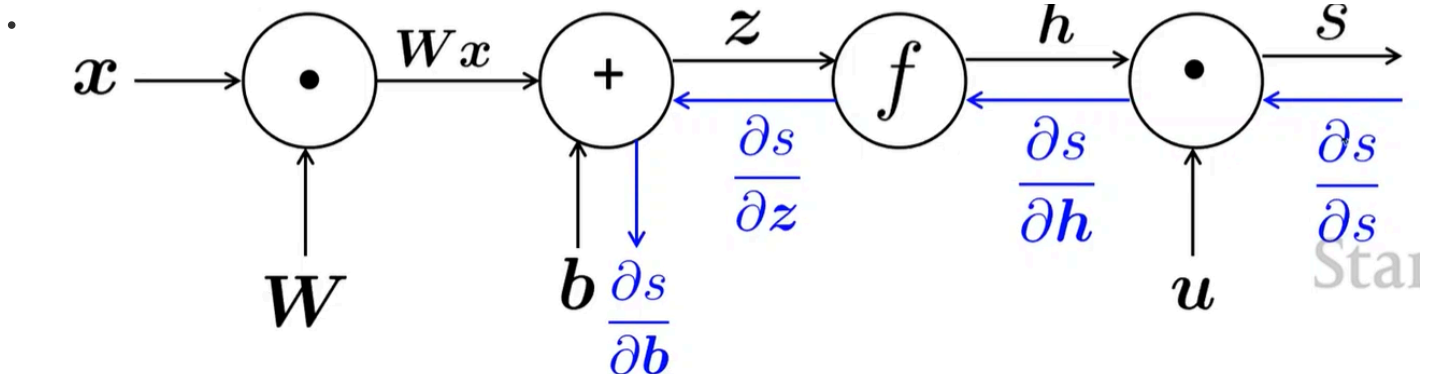
- **Shape Convention:**

- because for derivating in terms of W , $\frac{\partial s}{\partial W}$, the score needs to be a scalar number, so there is $n \times m$ inputs, and 1 output so the **jacobian is a $1 \times nm$ row vector**.
- but in **shape convention** you convert the $1 \times nm$ into the shape of W
- and eventually you use the same $n \times m$ matrix to update the new W
- **Actual and rigorous derivation:**
 - so $\frac{\partial s}{\partial W} = \delta \frac{\partial z}{\partial W}$
 - dimension of δ is $n \times 1$, because W is $n \times m$, x as input, is having $m \times 1$.
 - and $\frac{\partial z}{\partial W} = x$
 - proof of this derivation
 - W_{ij} maps the input x_j to the neuron i
 - so we have $z_i = \sum_{k=1}^m W_{ik}x_k + b_i$
 - so in each derivation, only one term remains
 - so to fit with the dimension $\frac{\partial s}{\partial W} = \delta x^T$ (typo in the lecture??)

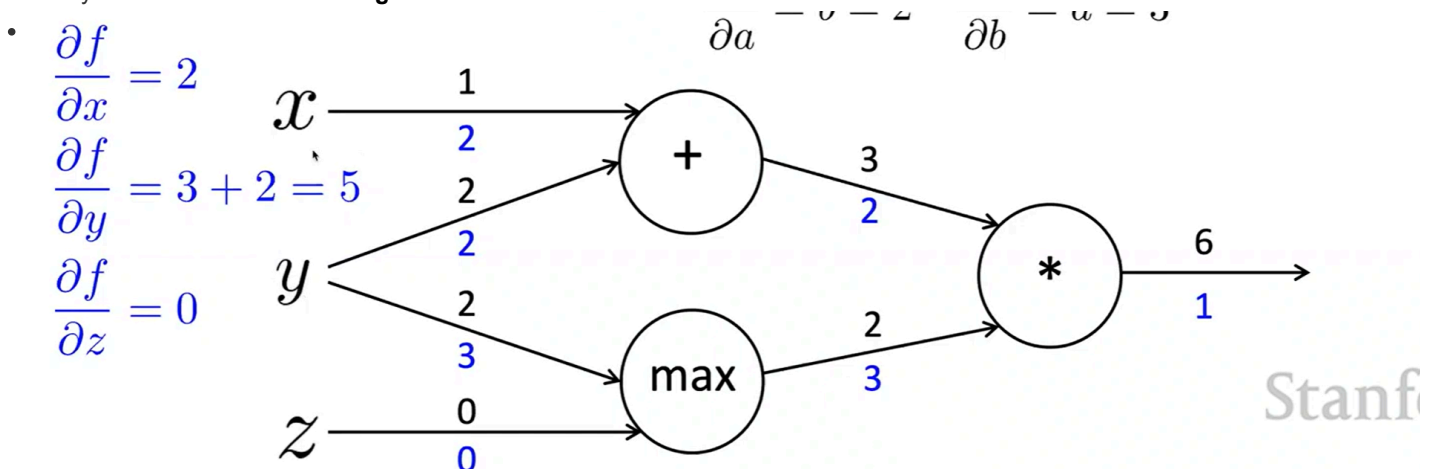
- **Overall, the gradient has to be the same shape as the parameter**

3. Backpropagation

- process of sending back gradients, to update the parameters of the models to learn, to give more accurate outcome and reduce loss.



- **Additionally**, we can make use of the **chain rule**, where with an **upstream gradient**, and calculating the **local gradient** we could easily find out the **downstream gradient**.



- and eventually for here, the gradient on the input represents how much changes you make on the input, that gradient times the change would be the change of final output

• Compute gradient wrt each node using
gradient wrt successors

$\{y_1, y_2, \dots, y_n\} = \text{successors of } x$

$$\frac{\partial z}{\partial x} = \sum_{i=1}^n \frac{\partial z}{\partial y_i} \frac{\partial y_i}{\partial x}$$

- **Intuitions**

- '+' distributes the upstream gradient(the step after) to both summands (no need of local gradient)
- 'max' routes the upstream gradient (chooses one)
- '*' switches the upstream gradient for cases of xy (uses the value of other route, after derivating in terms of one)

- **Automatic Differentiation**: calculating the corresponding gradients before hand.