## HOME AUTOMATION SYSTEM USING 4-PIN ULTRASONIC SENSOR

```
#define echo 11
#define trig 12
long distance, duration;
void setup() {
pinMode(echo,INPUT);
pinMode(trig,OUTPUT);
 pinMode(6,OUTPUT);
pinMode(7,OUTPUT);
Serial.begin(9600);
}
void loop() {
  digitalWrite(trig,LOW);
 delayMicroseconds(2);
 digitalWrite(trig,HIGH);
 delayMicroseconds(10);
 digitalWrite(trig,LOW);
   duration=pulseIn(echo,HIGH);
 distance=(duration/58.2);
 Serial.println(distance);
 if(distance>=22 && distance<40)
  digitalWrite(6, HIGH);
  digitalWrite(7,HIGH);
 }
 else if(distance<15)
  digitalWrite(6,LOW);
  digitalWrite(7,LOW);
 }
```

```
else
{
    digitalWrite(6,LOW);
    digitalWrite(7,LOW);
}
```