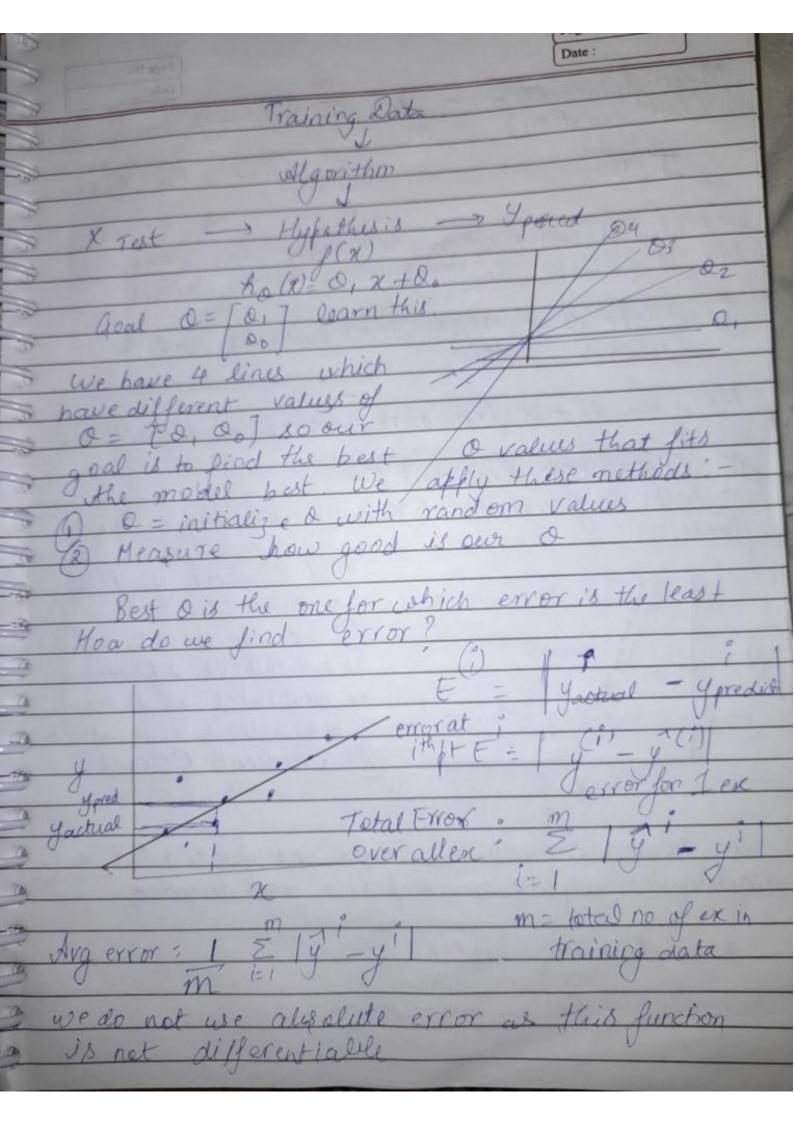
It Linear Regoussion - input and output are continuous Type of supervised learning we supply labelled X and y as training data we observe patterns in training data and try to predict outcome on test data using this. like in this example: X-train y-train
Time yest (hr) (marks) Jesting data Prediction X-test Time spent) equation of line y = mx + cslope intercept prediction main goal-learnbest value of m & c metation 3-y = g1 x + 00
slope intercept



Mean Square Error: - 1 = [g'-y']

(loss function) m = i=1

(pred) = ho (x') we need this loss function to measure how good our sine is lesser the J(u) better the a values. 6 Dubdate a so that I(a) greduces and a lucomes better. Now we do this pracedure using an algorithm # Gradient Descent:
helps to find a local minima in any given

function Find & where y= f(x) (1) we can directly different it but this not differentiable recommended as it doesn't work well on large dataset y=0 (2) Gradient Descent we choose a random value of x and update it till we reach minima depends on step size and direction

onst

onst

gradient

x = N = N 3f(x)

step 3 pc

direction

