

# RISHI SHAH

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## Education

### McMaster University

Apr. 2029

Engineering - Schulich Leader Scholar (1 of 50 in Canada to win \$120K national STEM scholarship)

Hamilton, Ontario

## Experience

### The Centre for Mechatronics and Hybrid Technologies

Oct. 2025 – Present

Machine Learning Researcher

Hamilton, ON

- Built hybrid LSTM model on top of PyBaMM SPMe simulations to predict lithium-ion anode potential, reducing RMSE from ~8 mV to 1.24 mV on held-out charging profiles
- Collaborating with MathWorks engineers on hybrid physics-ML battery modeling workflows

### Western University

Apr. 2024 – Aug. 2025

Machine Learning Researcher

London, ON

- Developed a novel CORNet-S variant, a brain-inspired vision model, achieving 97.82% robustness against adversarial attacks while maintaining clean accuracy and lightweight architecture
- Benchmarked model robustness against ResNet-18 and AlexNet under PGD, CW, and patch attacks across MNIST, CIFAR-100, and ImageNet100 datasets

### Hack49 Global

Jun. 2024 – Jun. 2025

Co-founder

Remote

- Built a global programming community of 950+ students across 40+ countries
- Secured \$19,000+ in sponsorships by leading outreach, partnerships, and logistics

### 3D Forge

May 2024 – Sep. 2024

Founder

London, ON

- Launched 3D printing business for custom Croc accessories, delivering 100+ orders and generating \$3500+ revenue
- Awarded Ontario's Summer Company Grant for student entrepreneurship

### Robarts Research Institute

Nov. 2022 – May 2024

Student Researcher

London, ON

- Developed U-Net segmentation models for DICOM medical images
- Created manual segmentations to support AI training pipelines for surgical imaging
- Built AR visualization apps using Unity and Vuforia for real-time mobile medical applications

## Projects

### Adaptive Learning Robot | C++, Arduino, Python, Cohere LLM

Sept. 2025

- Built a dual-system robot inspired by Kahneman's System 1 / System 2 model that learns new skills instantly from natural language without pre-training or rigid scripts
- Implemented Cohere LLMs with real-time search to convert messy instructions into smooth, executable motions for 2 custom 3-DOF robotic arms

### From Pixels to Precision | Python, MatLab — National Bronze; Divisional Gold; Sanofi BioGenius Award

May 2023

- Partnered with Synaptive Medical Inc. to develop a deep-learning model to track surgical tool movements in minimally invasive surgeries
- Trained on 300 manually segmented surgical images with 95% DICE accuracy
- Analyzed performance across 4 illumination and tool scenarios with sub-0.12s inference speed per image

## Leadership & Extracurricular Activities

### Payload Team Member

Oct. 2025 – Present

McMaster Rocketry Team

Hamilton, ON

- Building PCBs to design and test a self-healing polymer experiment on high-G rocket launches

### DECA Chapter Lead

Sep. 2023 – Apr. 2024

President

London, ON

- Mentored 80+ students, and grew chapter by 55%, raising provincial qualifiers by 52% and international by 50%

## Technical Skills

**Languages:** Python, C++, Java, C#, MATLAB

**Frameworks & Libraries:** PyTorch, Keras, OpenCV, Pandas, NumPy

**Hardware & Tools:** Arduino, Raspberry Pi, ESP32, KiCad, Git/GitHub, VS Code, Unity, Notion

**3D Modeling & Design:** Fusion 360, Blender, SketchUp, OnShape, Ultimaker Cura