# PT-100 Lab Assignment

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**CONTENTS** 

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2 Model

3 Solution

4 Validation

5 Conclusion

Abstract—This document contains a lab report on the modeling of the voltage-temperature characteristics of the PT-100 RTD (Resistance Temperature Detector) using least squares method.

# 1 Training Data

The training data gathered by the PT-100 to train the Arduino is shown in Table 1.

Temperature (°C)	Voltage (V)
66	1.85
27	1.76
2	1.66
23	1.72
56	1.82
34	1.76
33	1.75
31	1.74

TABLE 1: Training data.

The C++ source codes/data.cpp was used along with *platformio* to drive the Arduino.

# 2 Model

For the PT-100, we use the Callendar-Van Dusen equation

$$V(T) = V(0) \left( 1 + AT + BT^2 \right)$$
 (1)

$$\implies c = \mathbf{n}^{\mathsf{T}} \mathbf{x} \tag{2}$$

where

$$c = V(T), \mathbf{n} = V(0) \begin{pmatrix} 1 \\ A \\ B \end{pmatrix}, \mathbf{x} = \begin{pmatrix} 1 \\ T \\ T^2 \end{pmatrix}$$
 (3)

For multiple points, (2) becomes

$$\mathbf{X}^{\mathsf{T}}\mathbf{n} = \mathbf{C} \tag{4}$$

where

$$\mathbf{X} = \begin{pmatrix} 1 & 1 & \dots & 1 \\ T_1 & T_2 & \dots & T_n \\ T_1^2 & T_2^2 & \dots & T_n^2 \end{pmatrix}$$
 (5)

$$\mathbf{C} = \begin{pmatrix} V(T_1) \\ V(T_2) \\ \vdots \\ V(T_n) \end{pmatrix}$$
 (6)

and **n** is the unknown.

# 3 SOLUTION

We approximate **n** by using the least squares method. Using the pseudo-inverse method, the solution to (4) is

$$\mathbf{n} = (\mathbf{X}\mathbf{X}^{\mathsf{T}})^{-1}\mathbf{X}\mathbf{C} \tag{7}$$

The Python code codes/lsq.py solves for **n**. The calculated value of **n** is

$$\mathbf{n} = \begin{pmatrix} 1.6547 \\ 3.199 \times 10^{-3} \\ -3.9599 \times 10^{-6} \end{pmatrix} \tag{8}$$

The approximation is shown in Fig. 1.

#### 4 Validation

The validation dataset is shown in Table 2. The results of the validation are shown in Fig. 2.

### 5 Conclusion

This lab experiment demonstrates how machine learning methods can be used to model the behaviour of an unknown device, and find the right

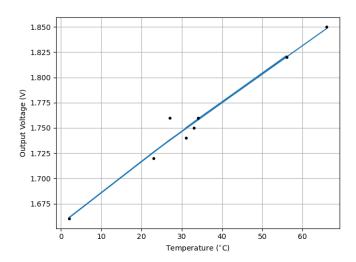


Fig. 1: Training the model.

Temperature (°C)	Voltage (V)
4	1.67
25	1.73
61	1.83
35	1.77

TABLE 2: Validation data.

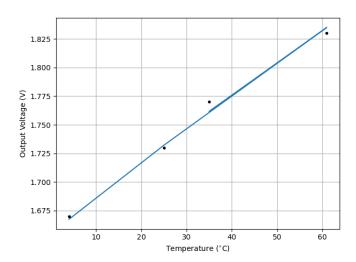


Fig. 2: Validating the model.

parameters that fit the model. It also shows how to use Python libraries and frameworks to collect data and perform optimization.