# **Lab Assignment No.4**

**Aim :** Write C++ program to draw 2-D object and perform following basic transformations, Scaling b) Translation c) Rotation. Apply the concept of operator overloading

#### Code:

```
#include<iostream>
#include<math.h>
#include<graphics.h>
using namespace std;
class matrix
public:
int n,i,j,tx,ty,k,sum,sx,sy;
double a[6][3],b[6][3],mult[6][3],mat3[6][3];
double p,q,r;
double ang=0,angle=0;
public:
void get()
cout<<"\n enter the number of vertices of polygon: ";
cin>>n;
// cout<<"n Entering user matix\n";</pre>
for(i=0;i<n;i++)
{
cout<<"enter x n y co ordinates";</pre>
cin>>b[i][0];
cin>>b[i][1];
b[i][2]=1;
}
//display object matrix
```

```
cout<<"\n original co ordinates are"<<"\n";
for(i=0;i<n;i++)
{
for(j=0;j<3;j++)
{
cout << b[i][j] << "\backslash t";
}cout<<"\n";
}
}
void identitymat()
{
for(i=0;i<n;i++)
{
for(j=0;j<3;j++)
{
if(i==j)
{
a[i][j]=1;
}
else
{
a[i][j]=0;
}
}
}
void trans()
{
```

```
cout<<"enter values of tx and ty";
cin>>tx>>ty;
a[2][0]=tx;
a[2][1]=ty;
cout<<"matrix is"<<"\n";
for(i=0;i<n;i++)
{
for(j=0;j<3;j++)
{
cout << a[i][j] << "\t";
}cout<<"\n";
}
}
void scale()
{
cout<<"\n Enter the values of sx and sy";</pre>
cin>>sx>>sy;
a[0][0]=sx;
a[1][1]=sy;
cout<<"\n Matrix is:"<<"\n";
//To display scaling matrix
for(i=0;i<3;i++)
{
for(j=0;j<3;j++)
{
cout << a[i][j] << "\t";
}cout<<"\n";
}
}
```

```
void rot()
cout<<"Enter the angle";</pre>
cin>>ang;
angle=(ang*3.142)/180;
q=sin(angle);
p=cos(angle);
r=-sin(angle);
a[0][0]=p;
a[0][1]=q;
a[1][0]=r;
a[1][1]=p;
cout<<"tranformation matrix is"<<"\n";
for(i=0;i<3;i++)
{
for(j=0;j<3;j++)
cout << a[i][j] << "\t";
}cout<<"\n";
}
}
void multi()
{
cout<<"\nMultiplying two matrices...";</pre>
for(i=0; i<n; i++)
{
for(j=0; j<3; j++)
{
sum=0;
```

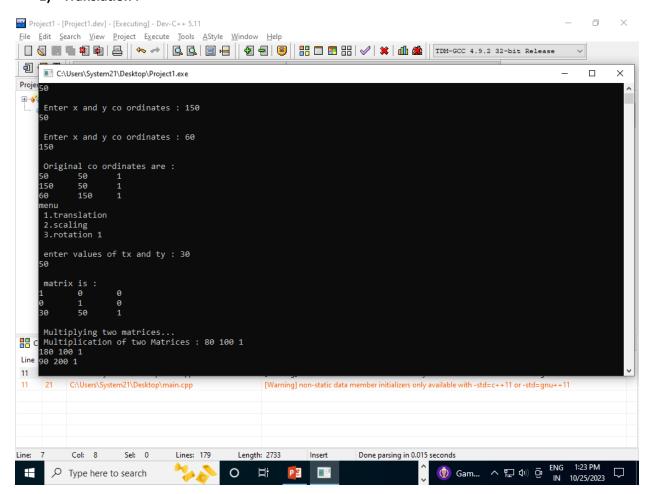
```
for(k=0; k<3; k++)
sum = sum + b[i][k] * a[k][j];
mat3[i][j] = sum;
}
}
}
void display()
{
cout<<"\nMultiplication of two Matrices : \n";</pre>
for(i=0; i<n; i++)
{
for(j=0; j<3; j++)
cout<<mat3[i][j]<<" ";
cout << "\n";
}
int gd=DETECT,gm;
initgraph(&gd,&gm,NULL);
for(int i=0;i<n-1;i++)
line(b[i][0],b[i][1],b[i+1][0],b[i+1][1]);
}
line(b[2][0],b[2][1],b[0][0],b[0][1]);
for(int i=0;i<n-1;i++)
line(mat3[i][0],mat3[i][1],mat3[i+1][0],mat3[i+1][1]);
```

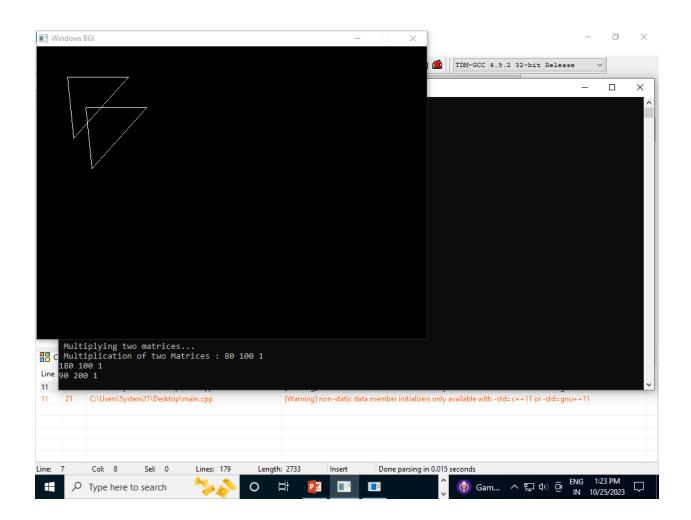
```
}
line(mat3[2][0],mat3[2][1],mat3[0][0],mat3[0][1]);
delay(5000);
closegraph();
}
};
int main()
{
matrix g;
int ch;
char ans;
g.get();
g.identitymat();
do
{
cout << "menu \\ n1.translation \\ n2.scaling \\ n3.rotation";
cin>>ch;
switch(ch)
{
case 1:
g.trans();
g.multi();
g.display();
break;
case 2:
g.scale();
g.multi();
g.display();
break;
```

```
case 3:
g.rot();
g.multi();
g.display();
break;
}cin>>ans;
}while(ans=='Y'&& ans=='y');
return 0;
}
```

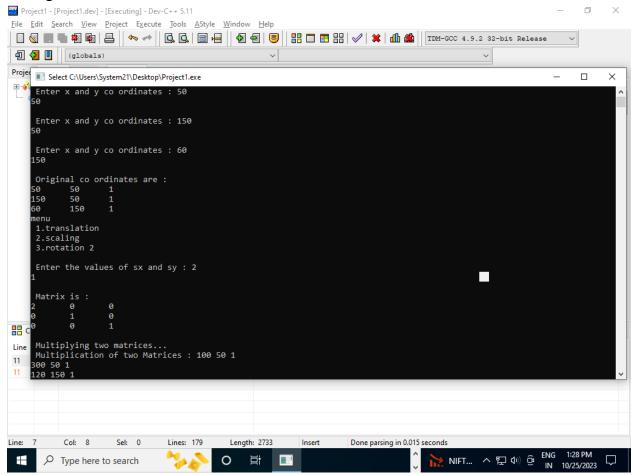
#### Output:

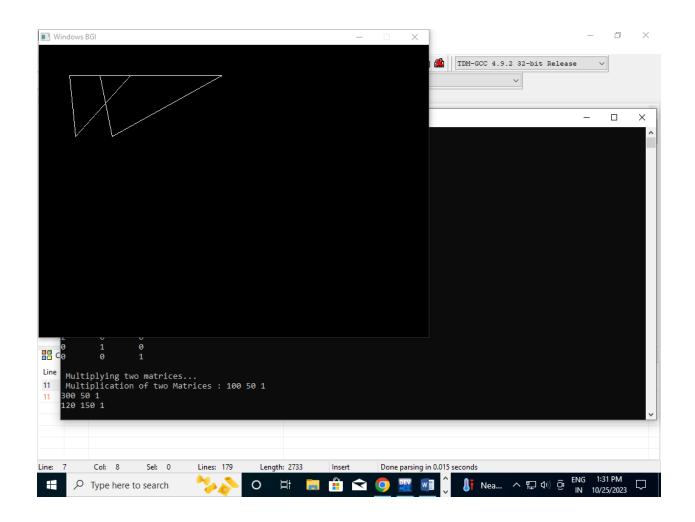
### 1) Translation:





### 2) Scaling





## 3) Rotation

