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EE3025 ASSIGNMENT- 1

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Download all python codes from

https://github.com/Rishithapawar/EE3025/tree/master/Assignment-1/codes

and latex-tikz codes from

https://github.com/Rishithapawar/EE3025/tree/master/Assignment-1

1 Problem

The command

output_signal = signal.lfilter(b,a,
 output_signal)

in Problem 2.3 is executed through following difference equation

$$\sum_{m=0}^{M} a(m) y(n-m) = \sum_{k=0}^{N} b(k) x(n-k)$$
 (1.0.1)

where input signal is x(n) and output signal is y(n) with intial values all 0. Replace **signal.filtfilt** with your own routine and verify

2 Solution

The function **signal.filtfilt(b,a,x)** filters the input using Butter worth filter .This function applies a digital filter twice, once forward and once backward. The combined filter has zero phase shift. Analytically, let v(n) denote the output of the first filtering operation(forward) and let h(n) be the impulse response of the filter. Then:

$$v(n) = (h * x)(n)$$
 (2.0.1)

For the second filtering operation (backward), we "flip" v(n) to obtain v(-n) and apply the filter again:

$$w(n) = (h * flip(v))(n)$$
 (2.0.2)

The final output is then the above result flipped:

$$y = flip(w) = flip(h * flip(v)) = flip(h) * v$$
(2.0.3)

$$y(n) = flip(h * (h * x)) = (flip(h) * (h * x))(n)$$
(2.0.4)

Using the properties of z-transform

$$\mathcal{Z}\{flip(x)\} = X(z^{-k}) \tag{2.0.5}$$

Applying Z-transform to (2.0.4) gives:

$$Y(z) = H(x^{-1}(H(z)X(z))$$
 (2.0.6)

For real filters h, this reduces to

$$Y(exp(jwT)) = |H(exp(jwT))|^2$$
 (2.0.7)

$$X(exp(jwT))$$
 (2.0.8)

Using the properties of z-transform

$$Z\{x(n-k)\} = z^{-k}X(z)$$
 (2.0.9)

$$Z{y(n-m)} = z^{-m}Y(z)$$
 (2.0.10)

where X(z) and Y(z) are the respective z-transforms of x(n) and y(n) respectively.

Converting the difference equation into its z-transform equation

$$Y(z)\sum_{m=0}^{M}a(m)z^{-m} = X(z)\sum_{k=0}^{N}b(k)z^{-k} \qquad (2.0.11)$$

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{k=0}^{N} b(k) z^{-k}}{\sum_{m=0}^{M} a(m) z^{-m}}$$
(2.0.12)

From the coefficients b,a and from (2.0.12) evaluating H(K).

Using built in fft command evaluating X(K) from x(n)

From

$$Y(K) = H(K)X(K)$$
 (2.0.13)

Using built in ifft command evaluating y(n) from Y(K).

Below is the following python code for the above question

codes/ee18btech11033.py

Below is the soundfile constructed from output signal y using own routine filter

codes/Sound_With_ReducedNoise_7.1.wav

3 VERIFICATION

Plotting the time domain output signal evaluated from both own routine filter and signal.filtfilt command and Plotting the frequency domain response evaluated from both own routine and signal.filtfilt.

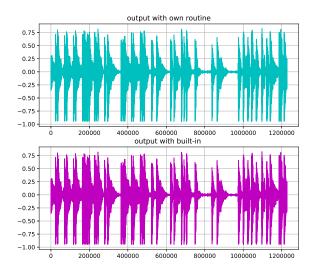


Fig. 0: Time domain response

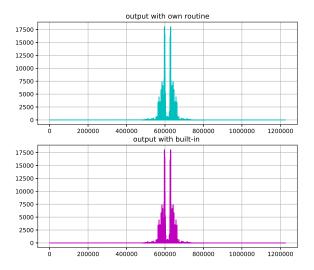


Fig. 0: Frequency domain response