CME 252: Model Fitting

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Linear least squares

Outline

Linear least squares

Non-linear data

Least squares in matrix-vector form

Examples

Linear least squares overview

- Ubiquitous statistical model
- ► Applications everywhere
- ▶ Goal: find linear model f(x) that fits your data
- Useful model for the purpose of studying optimization

Let's start with data

x: independent variable	y: response variable
0.0	0.46
0.11	0.31
0.22	0.38
0.33	0.39
0.44	0.65
0.56	0.4
0.67	0.87
0.78	0.69
0.89	0.87
1.0	0.88

Where might this data come from?

x: independent variable	y: response variable
height	weight
square feet	price of home
device property	failure rate
stock market return	individual asset return

Where did this data come from?

A linear model with random error:

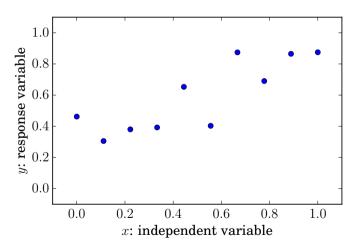
$$y_i = m \cdot x_i + b + \epsilon_i$$

The error is standard normal: $\epsilon_i \sim N(0, \sigma)$

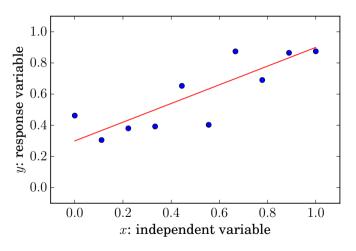
Code to generate in python:

```
np.random.seed(1)
m = 0.6
b = 0.3
sigma = .1
x = np.linspace(0,1,10)
y = m*x + b + sigma*np.random.standard_normal(x.shape)
```

Let's plot the data



Let's draw a line through it



Why do we want to do this?

- We have data. In the previous figures we show 2-dimensional data with points (x_i, y_i)
- Want to better understand data
- Want to use data for useful things, for example to make predictions
- We can do both by building a model

$$y \approx f(x)$$

Model has parameters. We use optimization to compute those parameters.

Linear models in one dimension

The model is:

$$y \approx m \cdot x + b$$

- ightharpoonup x is the independent variable
- ightharpoonup y is the dependent or response variable
- ightharpoonup m is the slope
- ▶ *b* is the *y*-intercept
- ► This is linear regression

Fitting the model to data

- Any given data point is going to result in some model error
- ▶ In optimization and linear algebra, we call this error the *residual*:

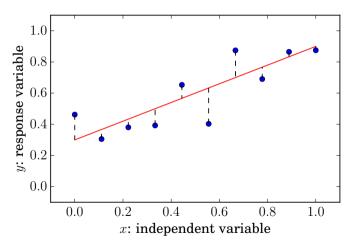
$$r_i = m \cdot x_i + b - y_i$$

▶ To fit the model to data, we set up an optimization problem that chooses parameters m and b to minimize the sum of squared residuals:

minimize
$$\frac{1}{2}\sum_{i=1}^{n}(m\cdot x_i+b-y_i)^2$$

▶ If the errors are distributed according to the normal distribution, then the solution to this optimization problem maximizes the log-likelihood of the model.

Fitting the model to data



Solve in CVXPY

Remember the optimization problem: minimize $\frac{1}{2} \sum_{i=1}^{n} (m \cdot x_i + b - y_i)^2$ We can write this almost directly in python:

```
m = Variable()
b = Variable()
objective = Minimize(sum_squares(m*x + b - y))
prob = Problem(objective)
result = prob.solve()

m.value = 0.56604, b.value = 0.30727
```

Loss functions

sum-of-squares is a loss function describing how unhappy we are with misfit of model

$$y \approx m \cdot x + b$$

- ▶ loss function makes "≈" precise
- sum-of-squares is not the only choice!

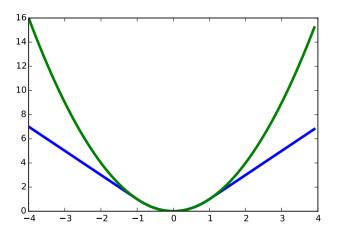
Huber function

- huber function allows us to better handle outliers
- defined as

$$h_M(x) = \begin{cases} x^2 & |x| \le M \\ 2M|x| - M^2 & |x| > M \end{cases}$$

- usual quadratic loss in interval [-M, M]
- ▶ linear loss for |x| > M
- ▶ linear penalty for large errors is much less severe than quadratic
- ▶ large errors are better 'tolerated', have less influence on fit

Huber function



Huber notebook

notebook

Linear least squares

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Non-linear data

Outline

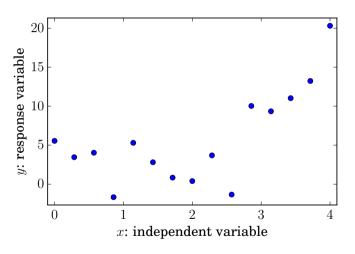
Linear least squares

Non-linear data

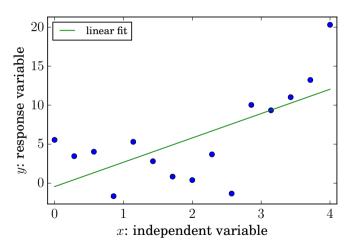
Least squares in matrix-vector form

Examples

What about this data?



Let's fit a linear model



We can fit an exponential model

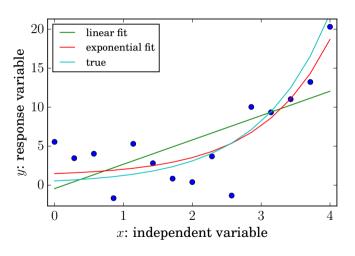
The model:

$$y \approx m \cdot e^x + b$$

Note: this model is still linear in the parameters m and b! We just need to transform the independent variable and then solve using the same technique. In code with CVXPY:

```
m = Variable()
b = Variable()
objective = Minimize(sum_squares(m*np.exp(x) + b - y))
prob = Problem(objective)
result = prob.solve()
```

Result



Least squares in matrix-vector form

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More variables

- ▶ We've been talking about least squares with one independent variable
- ▶ Utility of linear models is increased when we incorporate more variables
- ▶ For this discussion, we need vectors and matrices!

Least squares objective

- ▶ Let's say we have a data set (a_i, y_i)
- lacktriangleright a is now the independent variable and y is the response variable
- ▶ The linear model: $y = m \cdot a + b + r$
- lacktriangle The optimization formulation to find parameters m and b is

minimize
$$\frac{1}{2} \sum_{i=1}^n (m \cdot a_i + b - y_i)^2 = \frac{1}{2} ||m \cdot a + b - y||_2^2 = \frac{1}{2} ||r||_2^2$$

Matrix-vector form for least squares

minimize
$$\frac{1}{2}\sum_{i=1}^{n}(m\cdot a_i+b-y_i)^2$$

ightharpoonup Pack data from the independent variable and a constant into matrix A and model parameters into vector x:

$$A = \begin{pmatrix} a_1 & 1 \\ a_2 & 1 \\ \vdots & \vdots \\ a_n & 1 \end{pmatrix}, \quad x = \begin{bmatrix} m \\ b \end{bmatrix}$$

Linear model for the data is now:

$$y = Ax + r$$

Standard form for least squares

$$\begin{array}{ll} \text{minimize} & \frac{1}{2}||Ax - b||_2^2 \end{array}$$

In the context of model fitting:

- ▶ A is a matrix that contains data from independent variables
- b is the vector holding response data
- x is the vector of model parameters
- lacktriangle The optimization problem above is solved to find x^* , the parameters that minimize the sum of squared residuals
- lacktriangle For each item of data, we have the equation where a_i^T is row i of A

$$a_i^T x - b_i = r_i$$

Notation from statistics

minimize
$$\frac{1}{2}||\mathbf{y}-\mathbf{X}\beta||_2^2$$

The statistics community often uses different notation:

- ▶ X is the matrix of input data
- ▶ y is the vector of response data
- ightharpoonup eta is the vector of model parameters

CVXPY for least squares

```
x = Variable(A.shape[1])
objective = Minimize(sum_squares(A*x - b))
prob = Problem(objective)
prob.solve()
slope = 0.566, intercept = 0.3073
```

Examples

Outline

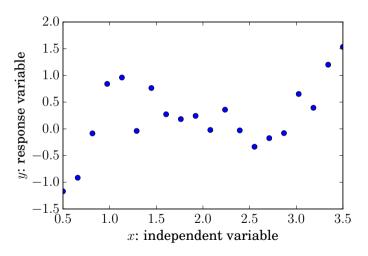
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What about this data?



We can try a polynomial model

- ▶ Have m data points (u_i, y_i)
- ► The model

$$y \approx p(u) = x_1 + x_2 u + x_3 u^2 + \dots + x_n u^{n-1}$$

- u is the independent variable
- ▶ *y* is the response variable
- $ightharpoonup x_i$ are the model parameters and coefficients of the polynomial
- ▶ Model is linear in the parameters! We can use least squares!

Linear model

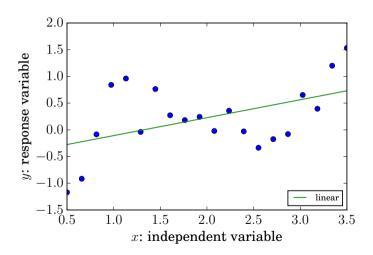
$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ \vdots \\ y_m \end{bmatrix} \approx \begin{bmatrix} 1 & u_1 & u_1^2 & \dots & u_1^{n-1} \\ 1 & u_2 & u_2^2 & \dots & u_2^{n-1} \\ 1 & u_3 & u_3^2 & \dots & u_3^{n-1} \\ 1 & u_4 & u_4^2 & \dots & u_4^{n-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & u_m & u_m^2 & \dots & u_m^{n-1} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix}$$

 $y \approx Ax$

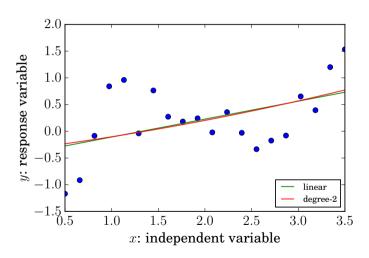
Solve with CVXPY

```
def cvxpy_poly_fit(x,y,degree):
    # construct data matrix
    A = np.vander(x,degree+1)
    b = v
    p_cvx = Variable(degree+1)
    # set up optimization problem
    objective = Minimize(sum_squares(A*p_cvx - b))
    constraints = []
    # solve the problem
    prob = Problem(objective,constraints)
    prob.solve()
    # return the polynomial coefficients
    return np.array(p_cvx.value)
```

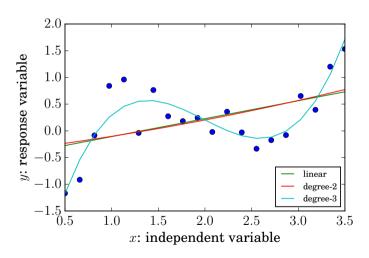
Linear fit



Quadratic fit



Cubic fit



Generating model

