



The Symmetric Perspective

by Lan Stewart - Martin Golubitsky

WESLEEN NGUYEN

Equine REU 2025 | Data-Driven Discovery

## INTRODUCTION TO SYMMETRY

- Why study symmetry? Describes patterns
  - " pattern formation (passive)
  - (active)
- Authors interested w/ its ties to nonlinear dynamics
- Focus on general, then specific cases in book

# CHAPTER 1: Steady - State Bifurcation

Q: What's the mechanism of speciation?

- Darwin's "survival of the fittest" failed on day-to-day level
- Idea 1: Sympatric Speciation: "founder" pop. isolated from main pop.  
→ gene flow between pops. off  $\Rightarrow$  now evolves
- Idea 2: Sympatric Speciation: Biological processes turn off gene flow even when new species remains mixed

• Symmetries enter as organisms are biologically indistinguishable & when broken  $\rightarrow$  bifurcation = speciation event!

• Steady States:  $x(t) = x_0, \forall t$

- If system has sym. group  $\Gamma$ , then eq. is invariant under  $\Sigma \subseteq \Gamma$ ; if  $\Sigma \not\subseteq \Gamma$ , then eq. **Breaks Symmetry**: key for pattern formation

Q1.1: Say there's 3 clumps of identical organisms w/ phenotypes  $(x, y, z) \in \mathbb{R}^3$ ;  $y/$   
 $x = \lambda x + x^2 - x - y$ . Propose a system that models this problem.

**SOLUTION**

$y$ /internal dynamics  $\lambda x + x^2 - x - y$  coupling  $y$

→ Yet suggests clump  $x$  reacts to  $y$  is different from  $x$

→ OK, but from  $x$ 's POV,  $y$  &  $z$  are identical, so instead:  $-y - z$

→ "Identical" means  $y$  has same internal dynamics & similarly coupling & so does  $z$

MATH454

Note this is the normal form of a transcritical bifurcation!

$$\begin{aligned}\dot{x} &= \lambda x - (x+y+z) + x^2 \\ \dot{y} &= \lambda y - (x+y+z) + y^2 \\ \dot{z} &= \lambda z - (x+y+z) + z^2\end{aligned}$$

ANSWER

Observe no matter how  $x, y, z$  are permuted, same eq.  $\rightarrow$  symmetric under  $S_3$   $\oplus$ !

→ Steady State is Trivial if  $\exists$  full symmetry e.g.  $x=y=z=\phi$  above

Linearize:  $J(x, y, z) = \begin{bmatrix} f_x & f_y & f_z \\ g_x & g_y & g_z \\ h_x & h_y & h_z \end{bmatrix} = \begin{bmatrix} \lambda - 1 & -1 & -1 \\ -1 & \lambda - 1 & -1 \\ -1 & -1 & \lambda - 1 \end{bmatrix}$

truncate to 1st order  
e.g. remove  $x^2$



EIGENVECTORS	$\lambda$ VALUES
$v_0 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$	$\lambda = -3$
$v_1 = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$	$\lambda = 1$
$v_2 = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$	$\lambda = 1$

Stable when all  $\lambda$ 's  $< \phi$   
 $\rightarrow \lambda < \phi$ , else it's unstable when  $\lambda > \phi$

What about equilibria w/  $\lambda$ ,  $x \rightarrow \phi$ ?  $\Rightarrow \lambda x + x^2 = \lambda y + y^2 = \lambda z + z^2 = x + y + z$

$$\begin{aligned} & \text{By symmetry, assume } x = y \neq z. \text{ Then: } \lambda x + x^2 = \lambda z + z^2 \rightarrow \lambda(x-z) + (x+z)(x-z) \\ & \quad \downarrow = x - \lambda \quad \downarrow = \phi \Rightarrow x+z = -\lambda \\ & \quad x^2 + x(\lambda-1) - \lambda = \phi \\ & \quad x = y = \frac{-\lambda-1 \pm \sqrt{\lambda^2-6\lambda+1}}{2} \text{ if } \lambda \neq \phi \approx 1-3\lambda-4\lambda^2 \\ & \quad \xleftarrow{\text{Binomial Theorem}} + O(\lambda^3) \end{aligned}$$

$\hookrightarrow$  Observe that when  $\lambda = \phi$ , branches are tangent to  $x+y+z = \phi$  @ origin, so is kernel of linearization @  $\lambda = x = y = z = \phi$ , which is  $S_3$ -invariant

Theorem: Solutions of symmetric ODEs may not be symmetric, but the set of solutions must be, where sym.-breaking soln can bifurcate w/  $\Delta$  of param.

Q1.2: Let  $\dot{x}_i = \lambda x_i - \sum_{j=1}^N x_j + x_i^2 - x_i^3$ ,  $1 \leq i \leq N$

Observe ODE is  $S_N$ -invariant. One way to study is by plotting trials w/  $\lambda$  stepped a tiny amount per run, termed Ramping the Bifurcation Parameter

Finite Groups in Book:  $D_m$ ,  $Z_m$ ,  $S_m$   
Compact Continuous Groups in Book:

Circle Group:  $S^1: \mathbb{T} = \{z \in \mathbb{C} \mid |z|=1\}$

Special Orthogonal Group:  $SO(2)$ , w/ all rotations  $R_\theta = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$

Orthogonal Group:  $O(n)$  is all rotations in  $\mathbb{R}^n$ ,  $n \times n$   $A \in \mathbb{R}^{n \times n}$   $A A^T = I$

More generally,  $SO(n)$  is  $O(n)$  w/  $\det A = 1$

$m$ -Torus:  $\mathbb{T}^m = S^1 \times \dots \times S^1$

$$\det R_\theta = 1$$

$$\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

invertible

Non-Compact Continuous Lie Groups:

all isometries

Euclidean Group in Plane:  $E(2)$ ; all rotations, reflections, translations

Special Euclidean Group:  $SE(2) \subseteq E(2)$ , no reflections (preserves chirality)

Lie Group: Smooth manifold w/ multiplication  $m(g, h) = gh$  are smooth (a.k.a.  $C^\infty$ )

2nd Hausdorff & Countable  
VxEM,  $\exists$  neighborhood  $N \ni x$   
 $\exists$  homeomorphic  $N \cong \mathbb{R}^n$

inversion

$$i(g) = g^{-1}$$

- **Group Action** of Group  $G$  on set  $S$  is a group homomorphism  $S \rightarrow S$ ,  $S \xrightarrow{\sim} V$   
 ↳ If lie group  $\Gamma$  & V.S.  $V$ , we say  $\Gamma$  acts on  $V \longleftrightarrow \exists$  smooth homomorphism  $\rho: \Gamma \rightarrow GL(V)$ ; denote  $\sigma v = \rho(\sigma)(v)$ , where
  - (1)  $(\sigma \delta)v = \sigma(\delta v)$  (associativity)
  - (2)  $1v = v$  (where  $1 \in \Gamma$ )simplified  
 $\rho$  turns  $\sigma$  into a homomorphism  $V \rightarrow V$

- **Propositions:**  $\rho(\Gamma) = \hat{\Gamma} \subset GL(V)$  & if  $\rho$  is injective, then  $\hat{\Gamma} \cong \Gamma$   
 ↳ **Corollary:** If  $\Gamma$  is compact, so is  $\hat{\Gamma}$
- **Ex. 1.3:** Let  $x = (x_1, \dots, x_N)$  w/  $\sigma x = (x_{\sigma^{-1}(1)}, \dots, x_{\sigma^{-1}(N)})$

**Proof of associativity:** Let  $(y_1, \dots, y_N) = \sigma x$ ;  $y_j = x_{\sigma^{-1}(j)}$ . Then:

$$\begin{aligned}\sigma(\sigma x) &= \sigma y = (y_{\sigma^{-1}(1)}, \dots, y_{\sigma^{-1}(N)}) = (x_{\sigma^{-1}\sigma^{-1}(1)}, \dots, x_{\sigma^{-1}\sigma^{-1}(N)}) \\ &= (x_{(\sigma\sigma)^{-1}(1)}, \dots, x_{(\sigma\sigma)^{-1}(N)}) = (\sigma\sigma)x\end{aligned}\quad \square$$

some subgroup

- **Theorem:** Every compact Lie group  $\Gamma$  acting on  $\mathbb{R}^n$  has  $\Gamma \cong M \leq O(n)$
- Say we have parameterized ODEs  $\dot{x} = f(x, \lambda)$ ,  $f: \mathbb{R}^n \times \mathbb{R}^r \rightarrow \mathbb{R}^n$ ,  $f \in C^\infty$ ,  $\lambda \in \mathbb{R}^r$ . Then:  
 ↳  $\tau \in O(n)$  is a **Symmetry** if  $\forall$  solns  $x(t)$ ,  $\tau x(t)$  is also a soln

- **Theorem:**  $\tau$  is a symmetry iff  $f: \mathbb{R}^n \times \mathbb{R}^r \rightarrow \mathbb{R}^n$  is  $\tau$ -Equivariant:  
 $f(\tau x, \alpha) = \tau f(x, \alpha)$ ,  $\forall r \in \Gamma$ ,  $x \in \mathbb{R}^n$

**Proof:** Let  $y(t) = \tau x(t)$ . Then:  $\dot{y}(t) = f(y(t)) = f(\tau x(t)) = \tau f(x(t))$   $\square$

- For  $v \in \mathbb{R}^n$ , the **Isotropy Subgroup** of  $v$  is  $\sum_v = \{\sigma \in \Gamma \mid \sigma v = v\} \leq \Gamma$   
 same in all orientations

all symmetries leaving  $v$  invariant,  
essentially stabilizer,  $Stab(v)$

$$(u, u, v)$$

$$(u, v, u)$$

$$u = \frac{-\lambda + 1 - \sqrt{\lambda^2 - 6\lambda + 1}}{2}$$

$$v = \frac{-\lambda + 1 + \sqrt{\lambda^2 - 6\lambda + 1}}{2}$$

- Ex. 1.4: In Q1.1, recall  $\exists 4$  eq. solns:  $(0, 0, 0)$ ,  $(v, u, u)$   
What are each of its Isotropy Subgroups?

$(0, 0, 0)$ : clearly all of  $S_3$

$(u, u, v)$ : clearly  $(12)$  leaves it invariant, but that's it, so  $\{\text{id}, (12)\}$

$(u, v, u)$ :  $\{\text{id}, (13)\}$ ;  $(v, u, u)$ :  $\{\text{id}, (23)\}$ ; observe  $\begin{pmatrix} (12) \\ (23) \\ (13) \end{pmatrix}$  conjugate in  $S_3$ !

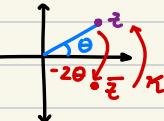
- Ex. 1.5: Let  $\Gamma = O(2)$  act on  $\mathbb{C}$  w/ actions  $\theta z = e^{i\theta}z$  (rotate)  
 $xz = \bar{z}$  (reflect)

• Say  $z = \emptyset$ . Then  $\sum_{\emptyset} = O(2)$  (TRIVIAL)

•  $z \in \mathbb{CP}^1 \setminus \{\emptyset\}$ . Then  $\sum_z = \{\emptyset, \chi\}$  ( $\cong \mathbb{Z}_2$ )

• Say  $z \neq \emptyset$ ,  $z = re^{i\theta}$ . Then  $\sum_z = \{\emptyset, \chi(-2\theta)\}$  ( $\cong \mathbb{Z}_2$ )

conjugate to  $\chi$



- Ex. 1.6: Recall Q1.2; that has numerical soln  $x$  w/ values  $a < 0$ . If  $A = \sum_j |x_j = a\}$ ,  $B = \sum_j |x_j = b\}$ , w/  $N = 100 \rightarrow |A| = 16, |B| = 84$ . What's  $\sum_x$ ?

SOLUTION

$$\sum_x = S_{16} \times S_{84} \leq S_{100} = \Gamma$$

- Say  $x = (x_1, x_2, x_3, x_4, x_5)$  w/  $\overset{x_1, x_2, x_3}{\underset{x_4, x_5}{\text{"equal" e.g.}}} \xrightarrow{\text{choice donut laptop}}$ . Then

$\sum_x = S_3 \times S_2$ . More generally w/  $x \in \mathbb{R}^N$ , partition  $\{1, \dots, N\}$  into disjoint blocks  $B_1, \dots, B_N$  where  $x_i = x_j \Leftrightarrow \exists \alpha \ni i, j \in B_\alpha$ . Let  $b_1 = |B_1|$ . Then

$$\sum_x = \prod_{n=1}^k S_{b_n}$$

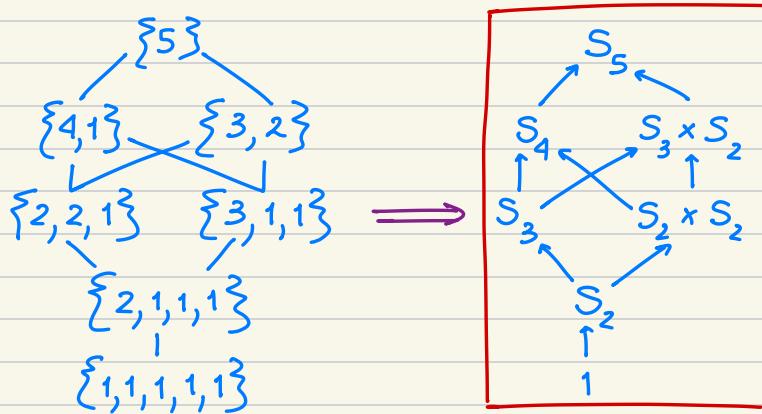
- If  $x \in \mathbb{R}^n$  is an eq. of  $\dot{x} = f(x, \lambda)$  &  $\sigma \in \Gamma$ , then so is  $\sigma x$  as  $f(\sigma x) = \sigma f(x) = \sigma \emptyset = \emptyset$ ; so the group orbit of  $x$  is  $\Gamma x = \{\sigma x \mid \sigma \in \Gamma\}$

→ Proposition:  $x$  &  $\sigma x$  has conj. isotropy subgroups w/  $\sum_{\sigma x} = \sigma \sum_x \sigma^{-1}$

- Let  $H = \{H_i\}$ ,  $K = \{K_j\}$  be 2 conj. classes of isotropy subgroups of  $\Gamma$ . Define Partial Ordering, transitive antisymmetric reflexive relation on some (not ALL!),  $H \preceq K \iff H_i \subset K_j$ . The Isotropy Lattice of  $\Gamma$  in its action on  $\mathbb{R}^n$  is the set of all conj. classes of isotropy subgroups partially ordered by  $\preceq$  (a "lattice")

- P1.7. What's the isotropy lattice of  $S_5$ ?

[SOLUTION] Say  $P_1 = \{S, 3\}$  &  $P_2 = \{4, 2, 1, 1\}$ . Then  $P_2$  is a refinement of  $P_1$ , so  $P_2 \preceq P_1$ . Then we extend the logic to  $\{S\}$ :



- W/  $\Sigma \leq \Gamma$ , the Fixed-Point Subspace of  $\Sigma$  is  $\text{Fix } \Sigma = \{v \in \mathbb{R}^n \mid \sigma v = v, \forall \sigma \in \Sigma\}$

- P1.8. What's  $\text{Fix } S_3$  &  $\text{Fix } \langle (12) \rangle$  from P1.1?

$$\begin{array}{c} \{1, 0, 0\} \\ \{0, 1, 0\} \\ \{0, 0, 1\} \end{array} \quad \begin{array}{c} \{(12)\} \\ \{(13)\} \\ \{(23)\} \end{array}$$

Theorem: Let  $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$  be  $\Gamma$ -equivariant w/  $\Sigma \leq \Gamma$ . Then  $f(\text{Fix } \Sigma) \subseteq \text{Fix } \Sigma$

Proof: Let  $v \in \mathbb{R}^n$  &  $\sigma \in \Sigma$ . Then  $\sigma v = v \Rightarrow \sigma f(v) = f(\sigma v) = f(v) \in \text{Fix } \Sigma$   $\square$

Corollary: Let  $x(t)$  be a soln. trajectory of an equivariant ODE. Then  $\sum_{x(t)} = \sum_{x(0)}$ ,  $\forall t \in \mathbb{R}$ . Namely, isotropy subgroups remain constant along trajectories.

Proof: If  $x(t)$  is flow-invariant, then  $x(t) \in \text{Fix } \Sigma_{x(0)}$ ,  $\forall t \in \mathbb{R}$ . Thus  $\sum_{x(t)} \subseteq \sum_{x(0)}$ . If  $x(0)$  lies on the trajectory through  $x(t)$ , then  $\sum_{x(t)} \subseteq \sum_{x(0)} \Rightarrow \sum_{x(0)} = \sum_{x(t)}$   $\square$

Thus, we find an eq. soln w/ isotopy subgroup  $\Sigma$  by restricting vector field to subspace  $\text{Fix } \Sigma$ . The bigger  $\Sigma$  is  $\rightarrow$  smaller  $\dim \text{Fix } \Sigma$  is. So find solns starting w/ largest isotopy subgroups, then go down the lattice

- $V \subset \mathbb{R}^n$  is a  $\Gamma$ -invariant Subspace if  $\mathcal{D}V = V, \forall \mathcal{D} \in \Gamma$

Ex:  $V = \{\mathbf{0}\}$ ,  $\mathbb{R}^n$ ,  $\text{Fix } \Gamma$

Ex: Let  $SO(2)$  act on  $\mathbb{RP}^2$  by  $\Theta(v, w) = (R_\theta(v), R_\theta(w))$ ,  $\theta \in [0, 2\pi]$ . Fix  $\psi \in SO(2)$  & let  $V_\psi = \{(v, R_\psi(v)) \mid v \in \mathbb{R}^2\}$ . Then  $V_\psi$  is  $SO(2)$ -invariant

Pf:  $\Theta(v, R_\psi(v)) = (R_\theta(v), R_\theta R_\psi(v)) = (R_\theta(v), R_\psi R_\theta(v)) \in V_\psi$

Ex: Let  $S_N$  act on  $\mathbb{R}^n$  by permuting coordinates. Then:

$$V_0 = \mathbb{R}^n(1, \dots, 1)$$

$$V_1 = \{(x_1, \dots, x_N) \mid \sum x_i = 0\}$$

) are  $S_N$ -invariant

- $W \subset \mathbb{R}^n$  is irreducible if the only  $\Gamma$ -invariant subspaces of  $W$  are  $W$  &  $\{\mathbf{0}\}$
- $f(\mathbf{0}) = 0$  by last theorem  
if acts trivially
- So if  $\Gamma$  acts irreducibly on  $\mathbb{R}^n$ , then  $\text{Fix } \Gamma = \{\mathbf{0}\}$  or  $\mathbb{R}^n$ .

- Theorem: Let  $\Gamma \subset O(n)$  be a compact Lie group. Then  $\exists \Gamma$ -irreducible subspaces  $V_1, \dots, V_s \subset \mathbb{R}^n = \bigoplus_{i=1}^s V_i$

Proof:  $\exists \Gamma$ -invariant inner product  $(\cdot, \cdot)$ . If  $\Gamma$  acts irreducibly on  $\mathbb{R}^n$ , done!

Else,  $\exists \Gamma$ -invariant subspace  $W \neq \{\mathbf{0}\}$  or  $\mathbb{R}^n$ . Then  $\exists W^\perp$  is  $\Gamma$ -invariant as  $v \in W^\perp, w \in W, \& \sigma \in \Gamma$  has  $(\sigma v, w) = (v, \sigma^{-1}w) = (v, w) = 0$  for  $w \in W$ . So  $\sigma v \in W^\perp \Rightarrow \mathbb{R}^n = W \oplus W^\perp$ .  
 $\hookrightarrow$  s n  $\in \mathbb{N}$ , the decomposition will terminate.

- P1.8: Let  $S_N$  act on  $\mathbb{R}^N$  by permuting coordinates. Define  $V_0, V_1$  as ①.

Let  $S_N$  act on  $V_1$ . Then the isotropy subgroups of  $S_N$  are the same, yet  $\dim \text{Fix } \Sigma = k-1$  when  $\Sigma$  corresponds to a partition into  $k$  blocks (df  $\eta = \begin{smallmatrix} x_1 & \dots & x_k \\ 0 & \dots & 0 \end{smallmatrix}$ )

- Let  $\Gamma$  act on  $V$  w/ linear map  $A: V \rightarrow V$ . A Commutes w/  $\Gamma$  if  $A\mathcal{D} = \mathcal{D}A, \forall \mathcal{D} \in \Gamma$ , namely  $A$  is  $\Gamma$ -Equivariant

**Proposition:** Let  $A$  be  $\Gamma$ -equivariant. Then:

(1)  $\text{Ker } A$  is a  $\Gamma$ -invariant subspace

$$\text{Pf: } Av = 0 \Rightarrow A(\partial v) = (\partial A)v = 0$$

→ If  $\Gamma$  acts irreducibly, then  $\text{Ker } A = \{0\}$  or  $\mathbb{R}^n$

(2) If  $A$  commutes w/  $\Gamma$  &  $\exists A^{-1}$ , then  $A^{-1}$  also commutes w/  $\Gamma$

$$\text{Pf: } A^{-1}\partial = (\partial^{-1}A)^{-1} = (A\partial^{-1})^{-1} = \partial A^{-1}$$

□

□

**Proposition:** Let  $D$  be the set of commuting linear maps when the group acts on an irreducible subspace. Then  $D$  is a linear subspace & is a skew field. So  $D = \mathbb{R}$ ,  $\mathbb{C}$ , or  $\mathbb{H}$ .

→  $\Gamma$  acts absolutely irreducibly on  $\mathbb{R}^n$  if  $D = \mathbb{R}$

A steady-state bifurcation occurs @ an eq. where the linearized eq. has a zero  $\lambda$  & no  $\lambda$  lies on the imaginary axis

**Theorem:** Say there's a branch of group-invariant equilibria  $y(\lambda)$  to ODE  $\dot{y} = F(y, \lambda)$  &  $\exists$  steady-state bifurcation @  $\lambda = \lambda_0$ , a.k.a.  $A_0 = (dF)_{y(\lambda_0), \lambda_0}$

Then: (1)  $0$  is the only eigenvalue of  $A_0$  on the imaginary axis

(2) The generalized eigenspace corresponding to  $0$  is  $\text{Ker } A_0$

(3)  $\Gamma$  acts absolutely irreducibly on  $\text{Ker } A_0$

We want to find bifurcations

→ One method, Center Manifold Reduction, reduces eq. to  $\dot{x} = g(x, \lambda)$   
where  $g: \text{Ker } A_0 \times \mathbb{R} \rightarrow \text{Ker } A$

linearization  
at the origin

$\det = 0$

→ Another is this: consider ODE system  $\dot{y} = F(y, \alpha)$ ,  $y \in \mathbb{R}^N$ ,  $\alpha \in \mathbb{R}^k$   
 $\text{w/ } F(0, 0) = 0$  &  $(dF)_{0, 0}$  singular. Let  $\tilde{Y} = \text{ker}(dF)_{0, 0} \neq \{0\}$   
 $\text{w/ } \tilde{R} = \text{range}(dF)_{0, 0}$ . Consider  $\tilde{R}^\perp = \text{coke}\tilde{R} = \text{coimage}(dF)_{0, 0}$  w/  
 $\mathbb{R}^N = \tilde{Y} \oplus \tilde{R}^\perp$ . Then  $F(x, w, \alpha) = \emptyset$  ( $x \in \tilde{Y}$ ,  $w \in \tilde{R}^\perp$ ) ...

$\Leftrightarrow$  (1)  $EF(x, w, \alpha) = \emptyset$  w/  $E: \mathbb{R}^N \rightarrow \mathbb{R}$  is the projection onto kernel of  $E$   
 identity map  
lies in  $\mathbb{R}$   
lies in  $\mathbb{R}$   
 (2)  $(I - E)F(x, w, \alpha) = \emptyset$   $x \in E = \mathbb{R}$ . Then:

$$\frac{d}{dw} EF(x, w, \alpha) \Big|_0 = E(dF)_{0,0} \Big|_{\hat{x}} = (dF)_{0,0} \Big|_{\hat{x}} \quad \xrightarrow{\text{Implicit Function Theorem}} \text{nonsingular}$$

$\rightarrow \exists! w: \mathbb{R} \times \mathbb{R}^k \rightarrow \mathbb{R}$  w/  $w(0,0) \Rightarrow EF(x, w(x, \alpha), \alpha) = \emptyset$ .  
 ∵ solving  $F = \emptyset \Leftrightarrow$  solving  $f(x, \alpha) = (I - E)F(x, w(x, \alpha), \alpha) = \emptyset$   
 where  $f: \mathbb{R} \times \mathbb{R}^k \rightarrow \mathbb{R}$ ,  $f(0,0) = 0$ ,  $(df)_{0,0} = 0$

$$= \mathbb{R}^n \xleftarrow{\text{dim of I-space}} \text{original} \xrightarrow{\text{dim } \mathbb{R} = \dim \text{Ker}(dF)_{0,0}}$$

**Theorem:** Solutions to  $F(y, \alpha) = 0$ ,  $y \in \mathbb{R}^N$  are in 1-to-1 correspondence w/  
 Solutions to  $F(x, \alpha) = 0$ ,  $x \in \mathbb{R}^n$  near the origin, termed the  
 Lyapunov-Schmidt Reduction

**Theorem:** Say  $\Gamma \subset O(n)$  is a compact Lie group w/  $F: \mathbb{R}^N \times \mathbb{R}^k \rightarrow \mathbb{R}^N$   
 $\Gamma$ -equivariant. Then  $f: \mathbb{R}^n \times \mathbb{R}^k \rightarrow \mathbb{R}^n$  from  $\mathbb{R}^n = \text{Ker}(dF)_{0,0}$  can be chosen to be  $\Gamma$ -equivariant

**Proof.**  $(dF)_{0,0}$  commutes w/  $\Gamma$  & so  $\mathbb{R}^n$  &  $\mathbb{R}^k$  are both  $\Gamma$ -invariant subspaces.  
 We can choose  $\hat{x}$  &  $\hat{y}$  to be  $\Gamma$ -invariant e.g.  $\hat{x} = x^b$ . Compute:

$$\begin{aligned} EF(x, w_\gamma(x, \alpha), \alpha) &= EF(x, \sigma^{-1}w(\sigma x, \alpha), \alpha) \\ &= E \sigma^{-1} F(\sigma x, w(\sigma x, \alpha), \alpha) \\ &= \sigma^{-1} EF(\sigma x, w(\sigma x, \alpha), \alpha) = 0 \end{aligned}$$

By uniqueness of IFT,  $w_\gamma = w$  or  $\sigma w(\sigma x, \alpha) = w(\sigma x, \alpha)$ . Then by  $\circledast$ , follows that  $f$  is  $\Gamma$ -equivariant.  $\square$

An isotropy subgroup  $\Sigma$  is axial if  $\dim \text{Fix } \Sigma = 1$

Ex. 1.9: What are the axial subgroups of  $S_N$  acting on  $V = \{x \in \mathbb{R}^n \mid \sum_{i=1}^N x_i = 0\}$

**SOLUTION** Up to conjugacy are the form  $[S_p \times S_q]$  w/  $p+q=N$   
 $N$  is partitioned into 2 blocks  $\xrightarrow{1 \leq p \leq N/2}$  fixed-point space has dim 1

**Equivariant Branching Lemma:** Let  $\Gamma \subset O(n)$  be a compact Lie group where  $\Gamma$  acts absolutely irreducibly on  $\mathbb{R}^n$  &  $f: \mathbb{R}^n \times \mathbb{R} \rightarrow \mathbb{R}^n$  be  $\Gamma$ -equivariant. Then  $f(0, \lambda) = 0$  &  $(df)_{0, \lambda} = c(\lambda)I$

Additionally, say  $c(0) = 0$  (<sup>bifurcation condition</sup>),  $c'(0) \neq 0$  ( <sup>$\lambda$  crossing condition</sup>), &  $\Sigma \in \Gamma$  is axial. Then  $\exists!$  branch of solns to  $f(x, \lambda) = 0$  from  $(0, 0)$  where the symmetry of the solns is  $\Sigma$

Proof: As  $c'(0) \neq 0 \Rightarrow \dim \text{Fix } \Sigma = 1$ . Let  $0 \neq v \in \text{Fix } \Sigma$ . Then  $\text{Fix } \Sigma = \mathbb{R}\{v\}$ .  
 $\exists$   $f(tv, \lambda) = h(t, \lambda)v$  w/  $h: \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$  &  $f(0, \lambda) = h(0, \lambda) = 0$ .  
By Taylor's Thm:  $h(t, \lambda) = tk(t, \lambda)$  where  $k(0, 0) = c'(0) \neq 0$   
&  $k_\lambda(0, 0) = c' \neq 0$ . By the IFT,  $\exists! \lambda(t) \geq \lambda(0) = 0$  &  $k(t, \lambda(t)) = 0$ .  
Thus  $f(tv, \lambda(t)) = 0$ . Finally, the solns lie in  $\text{Fix } \Sigma$ , which have symmetries including  $\Sigma$ , so  $\Sigma \leq \Sigma_v$ . As  $\Sigma$  is an isotropy subgroup:  $\Sigma_v = \Sigma$   $\square$

Ex. 1.10: Let  $\Gamma = \mathbb{Z}_2$  w/  $x \mapsto -x$

For  $\Sigma = 1$ , we have  $\text{Fix } \Sigma = \mathbb{R}$ ,  $\dim \text{Fix } \Sigma = 1$ .

By the Equivariant Branching Lemma,  $\exists$  branch of solns w/ trivial symmetry, w/  $f(-x, \lambda) = -f(x, \lambda) \Rightarrow f(0, \lambda) = -f(0, \lambda) \Rightarrow f(0, \lambda) = 0$ . By Taylor's Thm:  $f(x, \lambda) = a(x, \lambda)x$  &  $a(-x, \lambda) = a(x, \lambda) = b(x^2, \lambda)$

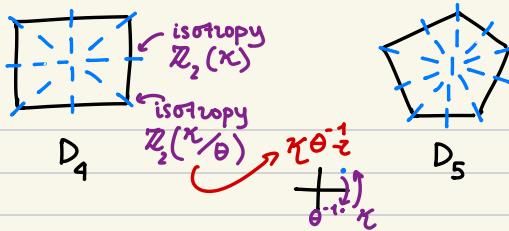
w/  $b_{x^2} \neq 0 \neq b_\lambda$ ,  $f(x, \lambda) \sim (x^2 \pm \lambda)x + \dots$ , the normal form of a Pitchfork Bifurcation

Ex. 1.11: Let  $\Gamma = O(2)$  act on  $\mathbb{R}^2 \cong \mathbb{C}$  by  $\theta z = e^{i\theta}z$ ,  $\theta \in [0, 2\pi)$  &  $\bar{z} = \bar{z}$

For  $\Sigma = \mathbb{Z}_2(\chi) = \{1, \chi\}$ , we have  $\text{Fix } \Sigma = \mathbb{R}$ . Then at an  $O(2)$  steady-state bifurcation,  $\exists$  equilibria w/ reflectational symmetry

Ex. 1.12: Let  $\Gamma = D_m$  act on  $\mathbb{C}$  by  $\theta z = e^{i\theta}z$ ,  $\theta = \frac{2\pi}{m}$ , &  $\bar{z} = \bar{z}$

For  $\Sigma = \mathbb{Z}_2(\chi) = \{1, \chi\}$ , we still have  $\text{Fix } \Sigma = \mathbb{R}$  & solns w/ reflectational symmetry



- Speciation was traditionally thought to be allopatric as discord. effects stem from discont. causes, but by end of 1990s, considered cont. causes: sympatric
  - Could have N animals but rapidly  $\Delta$ , so instead interpreted as **Placeholders for Organism Dynamics (PODs): Coarse-grained phenotypically related clusters**
  - Assumes sympatric speciation occurs in a **Panmictic Population**: All organisms can interbreed, & that environment is uniform, a.k.a.  $\exists$  diversity but each organism experiences the same diversity  $\forall$
  - Consider N PODs. State of POD  $j$  is described by  $x_j$  belongs to a **Phenotypic Space  $\mathbb{R}^r$** , where  $x_j^i$  is a phenotypic character &  $x_j$  is the entire phenotype
    - Ex: N = 100 PODs w/  $x_j \in \mathbb{R}^5$  (e.g., weight, ear angle, head angle, wing span, call rate)