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CHAPTER 1: Manifold & Smooth Maps1.1
Definitions

$f: \underset{\text{open}}{\mathcal{U}} \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$ is **smooth** if \exists partials of all orders

" X " " " " " if such can be locally extended to smooth map on open sets

↳ a.k.a. $\forall x \in X, \exists$ open $\mathcal{U} \subset \mathbb{R}^n$ & smooth $\tilde{f}: \mathcal{U} \rightarrow \mathbb{R}^m \ni \tilde{f}|_{\mathcal{U} \cap X} = f|_{\mathcal{U} \cap X}$ (Local Property)

↳ Say $X \subset \mathbb{R}^n$. X is a **2-Dimensional Manifold** if it's locally diffeomorphic to \mathbb{R}^2 ; a.k.a.

$\forall x \in X, \exists$ neighborhood $x \in V \subset X \ni V \xrightarrow[\text{diffeomorphic}]{} \mathcal{U} \subset \mathbb{R}^2$

• **Diffeomorphism** $\phi: \mathcal{U} \rightarrow V$ is a **Parameterization** of V , & $\phi^{-1}: V \rightarrow \mathcal{U}$ is a **Coordinate System** on V

• \exists k smooth funcs. (x_1, \dots, x_k) on V are **Coordinate Functions** when $\phi^{-1} = (x_1, \dots, x_k)$, so $v \in V \mapsto (x_1(v), \dots, x_k(v)) \in \mathcal{U}$, & $\dim X = k$

each funcs... NOT coordinates

Ex: $S^1 = \{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2 = 1\}$

Case 1: Say (x, y) is in \mathbb{C} . Then $\Phi_1(x) = (x, \sqrt{1-x^2})$ has $W = (-1, 1) \longleftrightarrow \mathbb{C}$

Case 2: " " " " \cup . Then $\Phi_2(x) = (x, -\sqrt{1-x^2})$ " " " " $\longleftrightarrow \mathbb{C}$

Case 3: What's left is $(1, 0)$ & $(-1, 0)$. So have R: $\Phi_3(y) = (\sqrt{1-y^2}, y)$

L: $\Phi_4(y) = (-\sqrt{1-y^2}, y)$

$\hookrightarrow S^1$ is locally diffeomorphic to $\mathbb{R}^1 \iff S^1$ is a **1D Manifold**

Say $X \subset \mathbb{R}^n, Y \subset \mathbb{R}^m$ are manifolds. If $\dim X = k, x \in X, \exists$ open $\mathcal{W} \subset \mathbb{R}^k$ & local parameterization

$\phi: \mathcal{W} \rightarrow X$ around x . Similarly for $\dim Y = l, y \in Y, \exists$ open $\mathcal{U} \subset \mathbb{R}^l$ & " " " " " " $\psi: \mathcal{U} \rightarrow Y$

→ Define $\phi \times \psi: \mathcal{W} \times \mathcal{U} \rightarrow X \times Y, (\phi \times \psi)(w, u) = (\phi(w), \psi(u))$

→ $\mathcal{W} \times \mathcal{U}$ is open & $\phi \times \psi$ is a local parameterization of $X \times Y$ around arbitrary (x, y)

If X & Z are manifolds in \mathbb{R}^n & $Z \subset X$, then Z is a **Submanifold** of X

Lemma: Any open set of X is a submanifold of X

Theorem: If X, Y are manifolds, so $X \times Y$ & $\dim(X \times Y) = \dim X + \dim Y$

1.2

Derivatives & Tangents

Say $f: U \subset \mathbb{R}^n \rightarrow \mathbb{R}^m$ is smooth. For $x, h \in \mathbb{R}^n$, the Derivative of f at x in the direction of h is:

$$Df_x(h) = \lim_{t \rightarrow 0} \frac{f(x+th) - f(x)}{t} \in \mathbb{R}^m, \text{ & more generally: } Jf(x) = \begin{pmatrix} f'_{x_1}(x) & \dots & f'_{x_n}(x) \\ \vdots & & \vdots \\ f'_{x_1}(x) & \dots & f'_{x_n}(x) \end{pmatrix}$$

for $f = (f_1, \dots, f_m)$

→ Lemma: $Df_x: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a linear map.

→ Chain Rule: Such is commutative

$$\mathbb{R}^n \xrightarrow{Df_x} \mathbb{R}^m \xrightarrow{Dg_{f(x)}} \mathbb{R}^l$$

$D(g \circ f)_x$

→ Lemma: If f is linear, then $Df_x = f, \forall x \in U$

Say that $X \subset \mathbb{R}^N$ & $\Phi: U \rightarrow X$ is a local parameterization around x , where $U \subset \mathbb{R}^k$ is open w/ $\Phi(0)=x$

→ Best linear approximation to Φ @ 0 is $u \mapsto \Phi(u) + D\Phi_0(u) = u + D\Phi_0(u)$

→ Tangent Space of X @ x is $T_x(X) := \{D\Phi_0(u) | u \in \mathbb{R}^k\}$, a vector subspace of \mathbb{R}^N
 $\hookrightarrow x \mapsto T_x(X)$ is the closest flat approximation through x on X

→ Tangent Vector to $X \subset \mathbb{R}^N$ @ $x \in X$ is $v \in T_x(X)$

→ Say \exists another parameterization $\Psi: V \rightarrow X$ w/ $\Psi(0)=x, \Phi(0)=\Psi(0)$. Then

$h = \Psi^{-1} \circ \Phi: U \rightarrow V$ is a diffeomorphism $\Rightarrow \Phi = \Psi \circ h \Rightarrow D\Phi_0 = D\Psi_0 \circ Dh_0$,

$\mathcal{L}(D\Phi_0) \subset \mathcal{L}(D\Psi_0)$ & vice versa, $\therefore T_x(X)$ is well-defined

→ Since h is smooth & extends $\Phi: \mathbb{R}^N \rightarrow \mathbb{R}^k$ that extends Φ^{-1} . Then $\Phi^{-1} \circ \Phi$ is identity of U & $\mathbb{R}^k \xrightarrow{D\Phi_0} T_x(X) \xrightarrow{D\Phi_0} \mathbb{R}^k$ is also identity. $\therefore D\Phi_0: \mathbb{R}^k \rightarrow T_x(X)$ is an isomorphism

→ Proposition: $\exists k \in \mathbb{N} \ni T_x(X) \cong \mathbb{R}^k$ & $\dim(T_x(X)) = k$

Say $f: X \rightarrow Y$ is a smooth map between manifolds @ $x \ni f(x) = y$. Then:

$$\begin{array}{ccc}
 X & \xrightarrow{f} & Y \\
 \uparrow \Phi & \searrow \Psi & \\
 U & \longrightarrow & V
 \end{array}
 \quad
 \begin{array}{ccccc}
 & & \xrightarrow{\text{already } D\Phi_0(u)} & & \\
 & T_x(X) & \xrightarrow{Df_x} & T_y(Y) & \xrightarrow{\text{already } D\Psi_0(v)} \\
 & \uparrow D\Phi_0 & & \uparrow D\Psi_0 & \\
 & \text{best linear approx.} & & \text{should linearize} & \\
 & = \text{transform } x \text{ w/} & & \text{transform } y \text{ w/} & \\
 & Dg_x \text{ is valid map} & & Dg_y \text{ is valid map} & \\
 & \uparrow & & \uparrow & \\
 & \mathbb{R}^k & \xrightarrow{Dh_0} & \mathbb{R}^l &
 \end{array}
 \quad
 \begin{array}{c}
 \text{Recall } D\Phi_0, D\Psi_0 \text{ are} \\
 \text{isomorphisms!} \quad \therefore \text{define} \\
 Df_x = D\Psi_0 \circ Dh_0 \circ D\Phi_0^{-1}
 \end{array}$$

$h = \Psi^{-1} \circ f \circ \Phi$
by commutativity

Chain Rule: If $X \xrightarrow{f} Y \xrightarrow{g} Z$ are smooth maps of manifolds, then $D(g \circ f)_x = Dg_{f(x)} \circ Df_x$

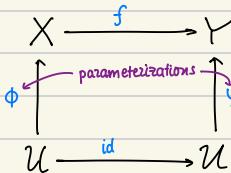
rev. not ∇ , just \exists 2 neighborhoods

\uparrow
neighborhoods

$u \in \mathbb{D} \subset V$

1.3. If X, Y are manifolds in the same dim, then if smooth $f: X \rightarrow Y$ makes $\boxed{\text{is a local Diffeomorphism @ } x}$, then f is a local Diffeomorphism @ x

Inverse Function Theorem (IFT): Say $f: X \rightarrow Y$ is smooth w/ $Df_x @ x$ is an isomorphism. Then f is a local diffeomorphism @ x .
just check $\det Df_x \neq 0$
a.k.a. $T_x X \cong_{\text{lin}} T_{f(x)} Y$



a.k.a. if Df_x is an isomorphism, we can choose local coordinates around $x \in f^{-1}(x) \Rightarrow$

f appears as identity @ $x \Leftrightarrow$ diagram commutes

more generally

$f: X \rightarrow Y$ & $f': X' \rightarrow Y'$ are equivalent if \exists diffeomorphisms $\alpha \in \mathcal{C}^1$ & $\beta \in \mathcal{C}^1$ below commutes:

$$\begin{array}{ccc} X & \xrightarrow{f} & Y \\ \alpha \uparrow & & \uparrow \beta \\ X' & \xrightarrow{f'} & Y' \end{array}$$

" f & f' are same up to diffeomorphism"

If $Df_x: T_x(X) \rightarrow T_{f(x)}(Y)$ is injective, then f is an immersion @ x
↳ Canonical Immersion: Inclusion map $\mathbb{R}^k \hookrightarrow \mathbb{R}^l$ for $k \leq l$ where $(a_1, \dots, a_k) \rightarrow (a_1, \dots, a_k, 0, \dots, 0)$

(e.g. space can twist/bend/etc. but the immersion prevents collapse, squashing, etc.)

(gives criteria to when image is a manifold via embeddings)

Local Immersion Theorem: Say $f: X \rightarrow Y$ is an immersion @ x . Then \exists local coordinates @ $x \in Y$ such that $f(x_1, \dots, x_k) = (x_1, \dots, x_k, 0, \dots, 0)$, a.k.a. f is locally equivalent to the canonical immersion near x .

Proof: Choose any local parameterizations to make such commutative:
As $Dg_0: \mathbb{R}^k \rightarrow \mathbb{R}^l$ is injective, by Δ of basis in \mathbb{R}^l , $\Phi \uparrow$
say it has $1 \times k$ $\begin{pmatrix} I_k \\ 0 \end{pmatrix}$ where I_k is $k \times k$ identity matrix.

$$\begin{array}{ccc} X & \xrightarrow{f} & Y \\ \Phi \uparrow & & \uparrow \Psi \\ U & \xrightarrow{g} & V \end{array}$$

$\Phi(0) = x$
 $\Psi(0) = f(x)$

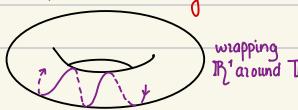
$$\begin{array}{ccc} X & \longrightarrow & Y \\ \Phi \uparrow & & \uparrow \Psi \circ g \\ U & \xrightarrow{\text{canonical}} & V \end{array}$$

Define $G: U \times \mathbb{R}^{l-k} \rightarrow \mathbb{R}^l$, $G(x, z) = g(x) + (0, z)$. Observe G maps open set $\mathbb{R}^l \rightarrow \mathbb{R}^l$ & that $DG_0 = I_k$. $\therefore \text{Inj } T \rightarrow G$ is local diffeomorphism of $\mathbb{R}^l @ 0$. Yet $g = G \circ (\text{canonical immersion})$

$\Psi \circ G$ are local diffeomorphisms @ 0, \therefore so is $\Psi \circ G \circ (\text{canonical immersion})$ such a local parameterization of Y around y . Moreover, if U & V shrink sufficiently, Φ commutes. \square

↳ Corollary: If f is an immersion @ x , then it's an immersion in a neighborhood of x .

Ex: Take $g: \mathbb{R}^1 \rightarrow S^1$ by $g(t) = (\cos 2\pi t, \sin 2\pi t)$, & $G: \mathbb{R}^2 \rightarrow S^1 \times S^1$ by $G(x, y) = (g(x), g(y))$, both local diffeomorphisms. Now define $\mathbb{R}^1 \rightarrow T$ by restricting G to $\{(x, y) \in \mathbb{R}^2 : x^2 + y^2 = 1\}$ as G is a local diffeomorphism, immersion wraps \mathbb{R}^1 around the Torus densely!



wrapping \mathbb{R}^1 around T

$f: X \rightarrow Y$ is Proper if \forall compact $V \subset Y$, $f^{-1}(V)$ is compact in X
 \hookrightarrow A proper, injective immersion is an Embedding

Theorem: An embedding $f: X \rightarrow Y$ maps X diffeomorphically onto a submanifold of Y .

Proof: \exists $\exists (X)$ to be a manifold, WTS if $W \subset X$ is open, $f(W)$ is open in $f(X)$. By WOT, say $f(W)$ isn't open, so $\exists \{y_i\} \subset f(X) \supset \{y_i\} \subset f(W)$, yet $y_i \rightarrow y \in f(W)$. $\nexists \{y_i, y_i\}$ is compact, $f^{-1}(\{y_i, y_i\})$ is compact. Say $y_i \xrightarrow{f^{-1}} x_i, y \xrightarrow{f^{-1}} x \in W$. $\nexists \{x_i, x_i\}$ is compact, $x_i \rightarrow z \in X$ ($\xrightarrow{\text{sequentially compact}}$). $\therefore f(x_i) \rightarrow f(z)$ ($\xrightarrow{\text{smooth, has sequential continuity}}$), & f is injective $\Rightarrow x = z$. Yet W is open, so for large i , $x_i \in W$. Yet $y_i \notin f(W)$, a contradiction. $\therefore f(X)$ is a manifold.

\nexists f is a local diffeomorphism $X \rightarrow f(X)$ & is bijective $\Rightarrow f^{-1}: f(X) \rightarrow X$ is well-defined. Yet f^{-1} is locally smooth, so f is indeed a global diffeomorphism. \square

1.4 Submersions

Buy $f: X \rightarrow Y$. If $Df_x: T_x(X) \rightarrow T_y(Y)$ is surjective, then f is a Submersion @ x ($\xrightarrow{\text{think of projectors}}$)
 \hookrightarrow Canonical Submersion: $\mathbb{R}^k \rightarrow \mathbb{R}^l$, $k \geq l$ where $(a_1, \dots, a_k) \xrightarrow{\quad} (a_1, \dots, a_l)$ ($\xrightarrow{\text{useful to say when preimage @ a point is a submanifold}}$)

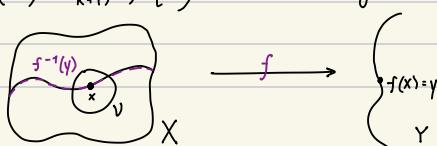
Local Submersion Theorem: Say $f: X \rightarrow Y$ is a submersion @ x . Then \exists local coordinates around $x \in f(x)$
 $\exists (x_1, \dots, x_k) = (x_1, \dots, x_k)$, $k \geq l$, s.t. f is locally equivalent to the canonical submersion near x .

Proof: $X \xrightarrow{f} Y$
 $\Phi \uparrow \quad \uparrow \Psi \quad \Phi(0)=x \quad \Psi(0)=f(x)$
 $U \xrightarrow{g} V$
 $\therefore Dg_0: \mathbb{R}^k \rightarrow \mathbb{R}^l$ is surjective, by linear Δ of coordinates in \mathbb{R}^k ,
such has $l \times k$ matrix (δ_{ij}) . Define $G: U \rightarrow \mathbb{R}^k$, $G(a) = f(g(a))$,
 $a \in U$. Thus $\det Dg_0 = \delta_{ij} \Rightarrow G$ is a local diffeomorphism @ 0

$\therefore \exists G^{-1}$ as a diffeomorphism of some open neighborhood U' of 0 into U . By construction, $g = (\text{canonical submersion}) \circ G$, so $g \circ G^{-1}$ is a canonical submersion. \therefore the L. diagram commutes. \square

Corollary: If f is a submersion @ x , f is a submersion in some neighborhood of x .

Buy $f: X \rightarrow Y$ is a submersion of $x \in f^{-1}(y)$. Select local coordinates around $x \in y \in f(x_1, \dots, x_k)$
 $= (x_1, \dots, x_k)$ w/ $y \rightarrow (0, \dots, 0)$; s.t. near x , $f^{-1}(y)$ is set of pts. $(0, \dots, 0, x_{k+1}, \dots, x_n)$
 \hookrightarrow s.t. let V denote neighborhood of x where (x_1, \dots, x_k) is defined. Then $f^{-1}(y) \cap V$ is set of pts.
where $x_1 = \dots = x_k = 0$, $\therefore x_{k+1}, \dots, x_n$ form a coordinate system on $f^{-1}(y) \cap V$



\exists smooth $f: X \rightarrow Y$ between manifolds, $y \in Y$ is a **Regular Value** for f if $Df_x: T_x(X) \rightarrow T_y(Y)$ is surjective
 $\forall x \in X \ni f(x) = y$. Else y is a **Critical Value**

Preimage Theorem: If y is a regular value of $f: X \rightarrow Y$, then $f^{-1}(y)$ is a submanifold of X with
 $\dim f^{-1}(y) = \dim X - \dim Y$ (a.k.a. if every pt. on level set is non-degen, it's a submanifold)

Say y is regular w/ $f: X \rightarrow Y$ smooth:

→ Case 1: $\dim X > \dim Y$; then f is a submersion $\forall x \in f^{-1}(y)$

→ Case 2: $\dim X = \dim Y$; then f is a local diffeomorphism $\forall x \in f^{-1}(y)$

→ Case 3: $\dim X < \dim Y$; then x is a critical value $\forall x \in f^{-1}(y)$, & x is regular $\forall x \in X/f^{-1}(y)$

By the Preimage Theorem, constructing submanifolds is significantly easier

→ Ex: Consider $f: \mathbb{R}^k \rightarrow \mathbb{R}$, $f(x) = \|x\|^2$

(b)ewse $Df_a = (2a_1, \dots, 2a_k)$ for $a = (a_1, \dots, a_k)$. $\therefore Df_a$ is surjective unless $f(a) = 0$, so $x, \forall x \in \mathbb{R} \setminus \{0\}$, is a regular value of f . $S^{k-1} = f^{-1}(1)$ is a $k-1$ dimensional manifold.

→ Ex: Consider $O(n) = \{A \mid AAT = I\} \subset M_{n \times n} \cong \mathbb{R}^{n^2}$. Show $O(n)$ is a manifold.

Proof. AAT is symmetric & V.S. $S(n)$ of all symmetric $n \times n$ matrices is a submanifold of $M(n) \ni S(n) \cong \mathbb{R}^{\frac{n(n+1)}{2}}$ for $\lambda = \frac{n(n+1)}{2}$ w/ $f: M(n) \rightarrow S(n)$, $f(A) = AAT$ smooth. (b)ewse $O(n) = f^{-1}(I)$, so WTS I is regular.

$$\begin{aligned} Df_A(B) &= \lim_{s \rightarrow 0} \frac{f(A+sB) - f(A)}{s} \\ &= \lim_{s \rightarrow 0} \frac{(A+sB)(A+sB)^T - AA^T}{s} \\ &= \lim_{s \rightarrow 0} \frac{AA^T + sBA^T + sAB^T + s^2BB^T - AA^T}{s} \\ &= \lim_{s \rightarrow 0} BA^T + AB^T + sBB^T \\ &= BA^T + AB^T \end{aligned}$$

Note $T_A M(n) = M(n)$ & $T_{f(A)} S(n) = S(n)$ as subspaces of Euclidean spaces. f is regular $\Leftrightarrow Df_A: M(n) \rightarrow S(n)$ is surjective $\forall A \in O(n) \Leftrightarrow \forall C \in S(n), \exists B \in M(n)$ that solves $Df_A(B) = C$ or $BA^T + AB^T = C$. W/C symmetric $\Rightarrow C = \frac{C}{2} + \frac{C^T}{2}$. $\therefore BA^T = \frac{C}{2}$. Yet as $ATA = I$ $\Rightarrow B = \frac{CA}{2}$. Then:

$$Df_A(B) = \frac{(CA)}{2} A^T + A \left(\frac{CA}{2}\right)^T = \frac{C}{2}(AAT) + \frac{C^T}{2}(AAT) = \frac{C}{2} + \frac{C^T}{2} = C$$

" f is a submersion $\forall A \in f^{-1}(I) \Rightarrow O(n)$ is a submanifold of $M(n)$. Moreover:

$$\dim O(n) = \dim M(n) - \dim S(n) = n^2 - \frac{n(n+1)}{2} = \boxed{\frac{n(n-1)}{2}}$$

□

Lie Group: If manifold & group w/ a smooth b.o.

Q: If g_1, \dots, g_l are smooth, real-valued funcs. on manifold X w/ dimension $n \geq l$. Then is $Z := \{x \in X : g_i(x) = 0 \forall i\}$ a manifold?

Solution: Let $g := (g_1, \dots, g_l) : X \rightarrow \mathbb{R}^l$. If $Z = g^{-1}(0)$, Z is a submanifold if 0 is a regular value of g .
 More precisely: each g_i is smooth $X \rightarrow \mathbb{R}$ w/ $D(g_i)_x : T_x(X) \rightarrow \mathbb{R}$, a linear functional on a D.S.
 Then $D(g_i)_x$ is surjective \Leftrightarrow l functionals $D(g_1)_x, \dots, D(g_l)_x$ are L.S. on $T_x(X)$, o.k.a. the l functions g_1, \dots, g_l are independent @ x .

Proposition: If smooth, real-valued functions g_1, \dots, g_n on X are independent $\forall z \in Z \cap \text{Ker}(g_1, \dots, g_n)$, then Z is a submanifold of X w/ $\dim Z = \dim X - l$

\hookrightarrow Codimension of arbitrary submanifold Z of X is $\text{codim } Z = \dim X - \dim Z$

Proposition: If y is a regular value of smooth $f: X \rightarrow Y$, then $f^{-1}(y)$ can be cut out by independent funcs.

Proof: Choose diffeomorphism h of neighborhood W of y w/ a neighborhood of origin in \mathbb{R}^l where $h(y) = 0$. Set $g = h \circ f$ & check that 0 is a regular value of g . \therefore coordinate funcs. g_1, \dots, g_l works! \square

Proposition: Every submanifold of X is locally cut out by independent functions.

Proof: Let submanifold Z have codimension l w/ $z \in Z$. Then $\exists l$ ind. funcs. g_1, \dots, g_l defined on open neighborhood W of z in $X \ni Z \cap W$ is the common vanishing set of g_i by the converse of the local Immersion theorem. \square

Proposition: Let $f: X \rightarrow Y$ be smooth w/ regular $y \in Y$, $Z := f^{-1}(y)$. Then $\text{Ker}(Df_x) = T_x(Z)$, $\forall x \in Z$

Proof: If f is constant on $Z \Rightarrow Df_x = 0$ on $T_x(Z)$. Yet $Df_x: T_x(X) \rightarrow T_y(Y)$ is surjective, $\therefore \dim(\text{Ker}(Df_x)) = \dim(T_x(X)) - \dim(T_y(Y)) = \dim X - \dim Y = \dim Z$, $\therefore T_x(Z)$ is a subspace of the kernel w/ the same dimension as the complete kernel $\Rightarrow T_x(Z)$ is the kernel! \square

Q: If $f: X \rightarrow Y$ is smooth w/ $Z \subset Y$ a submanifold, what are properties of $f^{-1}(Z)$?

$\text{Recall: } f^{-1}(Z)$ is a manifold $\Leftrightarrow \forall x \in f^{-1}(Z)$ has a neighborhood U in $X \ni f^{-1}(Z) \cap U$ is a manifold

\hookrightarrow If $|Z| = 1$, then a neighborhood of Z is the zero set of independent funcs. g_1, \dots, g_l w/ $l = \text{codim } Z$

- Neg x, then $f^{-1}(Z)$ is zero set of $g_1 \circ f, \dots, g_l \circ f$ $\mathbb{R}^l \rightarrow \mathbb{R}^l \rightarrow W$
- Let $g = (g_1, \dots, g_l)$ be a submersion of y . Then $(g \circ f)^{-1}(0)$ is a submanifold if 0 is regular

◦ If $D(g \circ f)_x = Dg_{f(x)} \circ Df_x$, then $D(g \circ f)_x: T_x(X) \rightarrow \mathbb{R}^l$ is surjective $\Leftrightarrow Dg_{f(x)}$ carries $\text{Im}(Df_x) \rightarrow \mathbb{R}^l$. Yet $Dg_{f(x)}: T_{f(x)}(Y) \rightarrow \mathbb{R}^l$ is surjective w/ $\text{Ker} = T_y(Y)$

◦ $Dg_{f(x)}$ carries a subspace of $T_{f(x)}(Y) \rightarrow \mathbb{R}^l$ if that subspace & $T_{f(x)}(Z)$ span all of $T_{f(x)}(Y)$

$\hookrightarrow g \circ f$ is a submersion @ $x \in f^{-1}(Z) \Leftrightarrow \text{Im}(Df_x) + T_x(Z) = T_{f(x)}(Y)$

partial
converse of
the last prop.

→ Say f is transversal to submanifold $Z \subset Y$ if $f^{-1}(Z) \cap X$ is a submanifold. ("clean" intersections enables to say that preimage of submanifold is indeed a submanifold)

Theorem: If $f: X \rightarrow Y$ is smooth w/ $f^{-1}(Z) \subset Y$ submanifold, then $f^{-1}(Z) \subset X$ is a submanifold. Moreover, $\text{codim } f^{-1}(Z) = \text{codim } Z$

→ Recall $f^{-1}(Z)$ is zero set of l ind. funcs. g_1, \dots, g_l of X , then $\text{codim } f^{-1}(Z) = l = \text{codim } Z$

→ Also recall that if $|Z|=1$, then $T_y(Z)$ is zero subspace of $T_y(Y)$, $\therefore f$ transv if

$$Df_x(T_x(X)) = T_y(Y), \forall x \in f^{-1}(y), \therefore \text{transversality generalizes regularity}$$

Ex: Consider $f: \mathbb{R} \rightarrow \mathbb{R}^2$, $f(t) = (0, t)$, w/ $Z \subset \mathbb{R}^2$ the x -axis. Let $g: \mathbb{R} \rightarrow \mathbb{R}^2$, $g(t) = (t, t^2)$. Then $f \cap Z$, but g isn't transversal to Z .



submanifolds $X \subset Y$ means $x \in i^{-1}(Z) \Rightarrow x \in X \cap Z$ & that $D_i_x: T_x(X) \rightarrow T_x(Y)$ is also an inclusion map, $i \cap Z \Leftrightarrow \forall x \in X \cap Z, T_x(X) + T_x(Z) = T_x(Y)$
 $Z \subset Y$ then say submanifolds X & Z are transversal, denoted $X \pitchfork Z$

Theorem: For submanifolds $X, Z \subset Y$, then $X \pitchfork Z \Rightarrow X \cap Z$ is a submanifold of Y . Moreover: $\text{codim}(X \cap Z) = \text{codim } X + \text{codim } Z$

→ Say X is cut out of Y by $k = \text{codim } X$. Then these $k+l$ funcs. are the independent funcs. for $X \cap Z$
 " " " " " $l = \text{codim } Z$

→ Recall transversality also depends on space Y e.g. 2 intersecting curves is a submanifold $\checkmark \mathbb{R}^2 \times \mathbb{R}^3$

Ex: \mathbb{R}^2

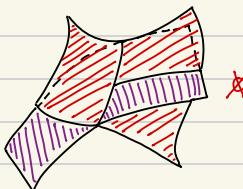
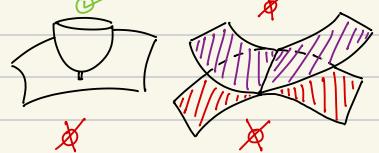


\mathbb{R}^3



Transversal
Non-transversal

Curves & surfaces

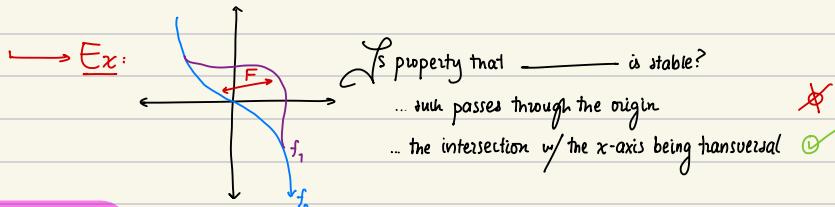


1.6

Homotopy & Stability

Let $\mathcal{L} = [0, 1]$ & $f_0, f_1: X \rightarrow Y$ be smooth. They're Homotopic w/ $f_0 \sim f_1$, if \exists smooth $\tilde{f}: X \times \mathcal{L} \rightarrow Y$ s.t. $\tilde{f}(x, 0) = f_0(x)$, $\tilde{f}(x, 1) = f_1(x)$, where \tilde{f} is the Homotopy between f_0 & f_1 . If $\exists \tilde{f}$, then say they're equivalent as part of the same Homotopy Class.

\hookrightarrow A property is stable if whenever $f_0 \sim f_t$, $t \in \mathcal{L}$ both possesses the property, then $\exists \varepsilon > 0 \ni f_t$, $\forall t \in [0, \varepsilon]$, also has the property



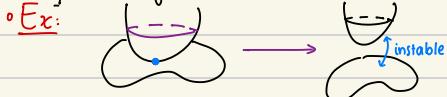
Stability Theorem: The following classes of smooth maps of compact manifold $X \rightarrow$ manifold Y are stable:

- (I) local diffeomorphisms, (II) diffeomorphisms, (III) immersions, (IV) submersions,
- (V) embeddings, (VI) maps transversal to some submanifold $Z \subset Y$

\hookrightarrow recall $X \pitchfork Z$ in Y if $\forall x \in X \cap Z$, $T_x(X) \cdot T_x(Z) = T_x(Y)$. Then for 2 curves in \mathbb{R}^3 , they can't intersect transversally unless they never intersect for algebraically: $1+1 \leq 3$

geometrically: any homotopy $\tilde{f} \rightarrow f$ prevents intersection stability

Explains why other intersections are nontransversal even when "arithmetically - ok": instability



Proof: I, III, IV, VI have same proof as local diffeomorphisms are just immersions when $\dim X = \dim Y$. If $f_0 \sim f_t$, X is compact \Rightarrow any open neighborhood $X \times \mathcal{L} \subset X \times \mathcal{L}$ has $X \times [0, \varepsilon]$ for small ε . WTS each $(x_0, 0)$ has neighborhood $U \subset X \times \mathcal{L} \ni Df_t$ is injective for $(x, t) \in U$ for III. If claim is local, only need to prove for open pieces $\frac{X \cap U}{\mathcal{L}}$. Injectivity of $D(f_t)_{x_0} \Rightarrow$ its $k \times k$ Jacobian $(\frac{\partial (f_t)_i}{\partial x_j}(x_0))$ has a $k \times k$ submatrix w/ nonzero determinant. Yet each $\frac{\partial (f_t)_i}{\partial x_j}(x)$ as a func. on $X \times \mathcal{L}$ is cont. If the determinant is also continuous, $k \times k$ submatrix must be nonsingular: $\forall (x, t)$ in a neighborhood $(x_0, 0)$.

For IV & VI are nearly identical. For V, define $G: X \times \mathcal{L} \rightarrow Y \times \mathcal{L}$, $G(x, t) = (f_t(x), t)$. BWDZ, $\exists t_i \rightarrow 0$ & $x_i \neq y_i \in X \ni G(x_i, t_i) = G(y_i, t_i)$. W/ X compact \Rightarrow sequentially compact \Rightarrow subsequence s.t. $x_i \rightarrow x_0, y_i \rightarrow y_0$. Thus $G(x_0, 0) = \lim G(x_i, t_i) = G(y_i, t_i) = G(y_0, 0) \Rightarrow f_0(x_0) = f_0(y_0)$, so if f is injective, $x_0 = y_0$.

If $DG_{(x_0, 0)} = \begin{pmatrix} D(f_0)_{x_0} & 1 \\ 0 & \dots & 0 & 1 \end{pmatrix}$ w/ $D(f_0)_{x_0}$ is injective, $\exists 2$ ind. rows. $\therefore DG_{(x_0, 0)}$ has $k+1$ ind. rows, making such injective. $\therefore G$ is an immersion around $(x_0, 0)$ & injective on a neighborhood. Yet for large i , (x_i, t_i) & (y_i, t_i) lie inside, a contradiction. Finally, II is left as an exercise. □

$\mathcal{AC}\mathbb{R}^l$ has Measure Zero if $\forall \epsilon > 0, \exists$ countably many rectangles $\{S_i\}_{i \in \mathbb{N}}$ s.t. $\sum_{i \in \mathbb{N}} \text{Vol}(S_i) < \epsilon$

- For manifold $Y \subset \mathbb{C}^n$ also has Measure Zero if \forall local parameterization ψ of Y , then $\psi^{-1}(C)$ has measure zero
- Lemma: If $\mathcal{AC}\mathbb{R}^l$ has measure zero & $g: \mathbb{R}^l \rightarrow \mathbb{R}^l$ is smooth, then $g(A)$ has measure zero

Sard's Theorem: The set of critical values of smooth map between manifolds $X \rightarrow Y$ has measure zero.

- Corollary: The regular values of any " " " " " " are dense in Y .
- countable union of measure zero still has measure zero, so take $C_i = \text{Critical for } C_i$ & have $C = \cup C_i$
- if $f_i: X_i \rightarrow Y$ w/ $i \in \mathbb{N}$ countable are all smooth maps between manifolds, then all $y \in Y$ that's regular to all f_i are dense in Y .

Say $f: X \rightarrow Y$ is smooth. Then $x \in X$ is a Regular Point of f if $Df_x: T_x(X) \rightarrow T_{f(x)}(Y)$ is surjective, else x is a Critical Point of f .

- y is a regular value $\Leftrightarrow \forall x \in f^{-1}(y)$ is a regular point
- " critical value \Leftrightarrow " " " critical point
- Ex: Let $f: X \rightarrow Y$ be the constant map between manifolds. Say $\dim X & Y > 0, f(x) = y_0$.
Observe Df_x is zero map, " critical values (in Y) has measure zero, so that's y_0 .
critical points (in X) do not have measure zero, so that's X

Let $Hf_{ij} = (f_{x_i x_j})$ be the Hessian Matrix. If Hf_x is nonsingular @ critical pt. x , then x is a Non-Degenerate Critical Point of f .

- Let $g: \mathbb{R}^k \rightarrow \mathbb{R}^k, g = (f_{x_1}, \dots, f_{x_k})$. Then $Df_x = 0 \Leftrightarrow g(x) = 0 \wedge Dg_x = Hf_x$
- If x is nondegenerate, then $g(x) = 0$ & g maps a neighborhood of x diffeomorphically onto a neighborhood of x , so g can't be 0 anywhere else in the " "

Morse Lemma: Say $a \in \mathbb{R}^k$ is a nondegenerate critical point of f . Then \exists local coordinate system (x_1, \dots, x_k) around $a \Rightarrow f = f(a) + \sum (Hf_a)_{ij} x_i x_j$ near a (quadratic!).

- Corollary: All nondegenerate critical points of f are isolated.

Say $f: X \rightarrow \mathbb{R}$ has a critical point @ x & that Φ is a local parameterization of the origin $\rightarrow x$. 0 is a critical point for $f \circ \Phi$ as $D(f \circ \Phi)_0 = Df_x \circ D\Phi_0 = 0$. Say x is Non-degenerate for f if 0 is too for $f \circ \Phi$.

- Lemma: Say f on \mathbb{R}^k has a nondegenerate critical point @ 0 & say Ψ is a diffeomorphism w/ $\Psi(0) = 0$. Then $f \circ \Psi$ also has a " " " " .

Proof: Let $f' = f \circ \Phi$. Then $f'_{x_1}(x) = \sum_{\alpha} f_{x_1} [\Psi(x)] (\Psi_{\alpha})_{x_1}(x)$. $\therefore f'_{x_1}(0) = \sum_{\alpha} \sum_{\beta} f_{x_1 x_{\beta}}(0) (\Psi_{\alpha})_{x_1}(0) (\Psi_{\beta})_{x_1}(0)$

 $+ \sum_{\alpha} f_{x_1}(0) (\Psi_{\alpha})_{x_1 x_{\beta}}(0)$. 0 is critical \Rightarrow 2nd sum $\underset{\alpha, \beta}{\oplus} 0$. a.k.a. $Hf' = (D\Psi)^T \Psi^{-1} (D\Psi) = H(D\Psi)$. $\therefore \det(Hf') \neq 0 \Rightarrow \det(Hf) \neq 0$.

Smooth Functions: Funcs. whose critical points are all nondegenerate

Say manifold $X \subset \mathbb{R}^N$ w/ usual coordinate funcs. x_1, \dots, x_N . If f is a func. on X & $\omega = (a_1, \dots, a_N)$, define $f_\omega := f + a_1 x_1 + \dots + a_N x_N$

a.k.a. $f + \text{Thm false}$
has measure zero

* **Theorem:** No matter $f: X \rightarrow \mathbb{R}$, for almost every $\omega \in \mathbb{R}^N$, f_ω is a Morse function on X .

Lemma: Let f be smooth on open $U \subset \mathbb{R}^k$. Then for almost all $\omega \in \mathbb{R}^k$, f_ω is Morse on U .

Proof: Let $g: U \rightarrow \mathbb{R}^k$, $g = (f_{x_1}, \dots, f_{x_k})$. Then $D(f_\omega)_p = ((f_\omega)_{x_1}(p), \dots, (f_\omega)_{x_k}(p)) = g(p) + \omega$. $\therefore p$ is a critical pt. of $f_\omega \Leftrightarrow g(p) = -\omega$. If f_ω & f have the same second partials, then $Df_p = Dg_p$. Say α is a regular value of g . Then $g(p) = -\alpha$ has Dg_p nonsingular. Then every critical point of f_ω is nondegenerate. By Sard's Theorem, $-\alpha$ is a regular value of g for almost all $\omega \in \mathbb{R}^k$. \square

* **Proof:** Say $x \in X$ w/ standard coordinate funcs x_1, \dots, x_N on \mathbb{R}^N . Restricting to some k of x_{i_1}, \dots, x_{i_k} to X is a coordinate system in a neighborhood of x . \therefore we can cover X w/ open U_α for each α , some k of x_1, \dots, x_N form a coordinate system. By the Second Axiom of Countability, \exists countably many U_α (hence U_α w/ coordinate system (x_1, \dots, x_k)). For each $c = (c_{k+1}, \dots, c_N)$, consider $f_{(1, c)} + c_{k+1} x_{k+1} + \dots + c_N x_N$. The lemma means For almost all $b \in \mathbb{R}^k$, $f_{(1, c)} + b_1 x_1 + \dots + b_k x_k$ is a Morse function on U_α . Let $S = \{\omega \in \mathbb{R}^N \mid f_\omega \text{ isn't a Morse func. on } U_\alpha\}$. As each horizontal slice $S \cap (\mathbb{R}^k \times \{\omega\})$ has measure zero in \mathbb{R}^k , S_α has measure zero in \mathbb{R}^N . So by Fubini's Theorem, if func. has a degenerate critical point on $X \Leftrightarrow$ it has one in U_α . $\therefore \{\omega \in \mathbb{R}^N \mid f_\omega \text{ isn't a Morse func. on } X\} = U_S$. As union of measure zero has measure zero, \square

1.8

Embedding Manifolds

Q: k -dim manifold X is locally diffeomorphic to subsets in \mathbb{R}^N , which can be embedded in \mathbb{R}^N , $N \geq k$. So does there exist an $N \geq \text{all } k\text{-dim manifolds lie in?}$ Ex: S^1 is 1D but embeds in \mathbb{R}^2

→ Yes! Suggests \exists "limit" to how complex manifolds can be

Tangent Bundle of manifold X in \mathbb{R}^N is $T(X) = \{(x, v) \in X \times \mathbb{R}^N \mid v \in T_x(X)\}$, a.k.a. all tangent spaces which includes a copy of $X = \{(x, 0)\}$

→ If $f: X \rightarrow Y$ is smooth, \exists global Derivative Map $Df: T(X) \rightarrow T(Y)$, $Df(x, v) = (f(x), Df_x(v))$ if $X \subset \mathbb{R}^N \rightarrow T(X) \subset \mathbb{R}^{2N}$ & $Y \subset \mathbb{R}^M \rightarrow T(Y) \subset \mathbb{R}^{2M}$

→ Lemma: Df is smooth. Proof: f smooth extends to $\exists \overset{\text{open}}{U} \subset \mathbb{R}^N \rightarrow \mathbb{R}^M \Rightarrow Df: T(U) \rightarrow \mathbb{R}^{2M}$ extends Df . Yet $T(U) = U \times \mathbb{R}^N \subset \mathbb{R}^{2N}$, $\therefore Df$ is smooth. $\therefore Df$ can be locally extended to a smooth map. \square

- Main rule says smooth $X \xrightarrow{f} Y \xrightarrow{g} Z \Rightarrow D_g \circ Df : T(X) \rightarrow T(Z)$ equals $D(g \circ f)$
- $\circ f$ diffeomorphism $\Rightarrow Df$ is too $\Rightarrow Df \circ Df^{-1} = D(\text{id}_Y) = \text{id}_{T(Y)}$ & $Df^{-1} \circ Df = D(\text{id}_X) = \text{id}_{T(X)}$
 - \circ a.k.a. diffeomorphic manifolds has diffeomorphic tangent bundles
 - \circ Lemma: $X \xrightarrow{\cong_D} Y \Rightarrow T(X) \xrightarrow{\cong_D} T(Y)$
 - \circ Lemma: If U is open in manifold X , then U is a submanifold.

Proof: Let $x \in U$ w/ neighborhood $U_x \xrightarrow{\cong_D} V_x \subset \mathbb{R}^n$ via diffeomorphism φ_x . Restrict $\varphi_x|_{\text{An}U}$, which is still a diffeomorphism $A \cap U \xrightarrow{\cong_D} \varphi_x(A \cap U)$, $\varphi_x|_{\text{An}U}(x) = 0$, $\forall x \in A \cap U$. Et voilà! \square

Proposition: If X is a manifold w/ $f: X \rightarrow Y$ smooth, then $T(X)$ is a manifold w/ $\dim T(X) = 2\dim X$

Proof: $W \subset X \Rightarrow W$ open $\Rightarrow T(W) \subset T(X) \cap (W \times \mathbb{R}^n) \subset T(X)$. So $W \times \mathbb{R}^n \subset X \times \mathbb{R}^n$ is open in $T(X)$. Say W is image of local parameterization $\Phi: U \subset \mathbb{R}^k \xrightarrow{\text{open}} W$. Then $D\Phi: T(U) \rightarrow T(W)$ is a diffeomorphism. Yet $T(U) = U \times \mathbb{R}^k \subset \mathbb{R}^{2k}$, so $D\Phi$ parameterizes $T(W)$ in $T(X)$. \square

Theorem: Every k -dimensional manifold admits an injective immersion in \mathbb{R}^{2k+1}

Proof: Let $X \subset \mathbb{R}^N$ be k -dimensional $\& N > 2k+1$. I claim if $f: X \rightarrow \mathbb{R}^N$ is an injective immersion, \exists unit $a \in \mathbb{R}^N$ $\& a \rightarrow a^\perp$ is an injective immersion too. PROOF: Define $h: X \times X \times \mathbb{R} \rightarrow \mathbb{R}^N$, $h(x, y, t) = t[f(x) - f(y)] + g: T(X) \rightarrow \mathbb{R}^N$, $g(x, v) = Df_x(v)$. So $N > 2k+1$, Sard's Theorem means $\exists a \in \mathbb{R}^N$ has $0 \neq a \in \text{Im } h$. Let $H = \{b \in \mathbb{R}^N \mid b \perp a^\perp\}$ & project $\mathbb{R}^N \rightarrow H$. Then $\pi \circ f: X \rightarrow H$ is injective (say $\pi \circ f(x) = \pi \circ f(y) \Rightarrow f(x) - f(y) = ta$ for some scalar t . $x \neq y \Rightarrow t \neq 0$ as f is injective, yet $h(x, y, \frac{1}{t}) = a \rightarrow a^\perp$) & an immersion (say $0 \neq v \in T_x(X)$ s.t. $D(\pi \circ f)_x(v) = 0$. π is linear $\Rightarrow D(\pi \circ f)_x = \pi \circ Df_x(v) = 0 \Rightarrow Df_x(v) = ta$ for some scalar t . f is an immersion $\Rightarrow t \neq 0$. Yet $g(x, \frac{1}{t}) = a \rightarrow a^\perp$). \blacksquare

If H is a $N-1$ -dimensional vector subspace, follows $H \cong \mathbb{R}^{N-1}$, $a \rightarrow a^\perp$ is an injective immersion. \square

→ Corollary: Compact manifolds has injective immersions \Leftrightarrow embeddings, \therefore all embed to \mathbb{R}^{2k+1}

Theorem: Let $X \subset \mathbb{R}^N$ be arbitrary. For open covering $\{U_\alpha\}$, Essequence of θ_i smooth func $\{f_i\}$ on X , a Partition of Unity subordinate to $\{U_\alpha\}$, s.t. (I) $0 \leq \theta_i(x) \leq 1$, $\forall x \in X$, $i \in \mathbb{N}$, (II) each $x \in X$ has a neighborhood where all but finitely many funcs. are 0, (III) each θ_i is 0 except on some closed set contained in one U_α , & (IV) $\forall x \in X$, $\sum_i \theta_i(x) = 1$

→ Corollary: On any manifold X , \exists proper $p: X \rightarrow \mathbb{R}$

Proof: Let $\{\cup_i\}$ open cover X w/ compact closure & have $\{\theta_i\}$ be a subordinate partition of unity. Then $p = \sum_{i=1}^n i\theta_i$ is a well-defined smooth func. \Rightarrow if $p(x) \leq j$, then at least 1 of first j funcs. $\theta_1, \dots, \theta_j$ is nonzero @ x . $\therefore p^{-1}[-j, j] \subset \bigcup_{i=1}^j \{x \mid \theta_i(x) \neq 0\}$, a set w/ compact closure. Yet every compact set in \mathbb{R} lies in some interval $[-j, j]$. \square

Whitney's Embedding Theorem: Every k -dimensional manifold embeds in \mathbb{R}^{2k+1} .

Proof: Say $X \rightarrow \mathbb{R}^{2k+1}$ is an injective immersion. Compose w/ any diffeomorphism of \mathbb{R}^{2k+1} into unit ball, say $z \mapsto \frac{z}{1+z^2}$, we get $f: X \rightarrow \mathbb{R}^{2k+1} \ni f(x) < 1, \forall x \in X$. Let $p: X \rightarrow \mathbb{R}$ be proper. Define injective immersion $\tilde{f}: X \rightarrow \mathbb{R}^{2k+2}, \tilde{f}(x) = (f(x), p(x))$. Drop to \mathbb{R}^{2k+2} via $\pi: \mathbb{R}^{2k+2} \xrightarrow{\text{orthogonal projection}} \mathbb{H} \subset \mathbb{R}^{2k+2}$ (linear space to $a \in \mathbb{R}^{2k+2}$)

Recall $\pi \circ \tilde{f}: X \rightarrow \mathbb{H}$ is an $\overset{\text{injective}}{\text{immersion}}$ for almost every $a \in \mathbb{H}^{2k+1}$, to pick a that's neither poles. Then $\pi \circ \tilde{f}$ is proper. I claim given bound c , \exists number $d \ni \{x \in X \mid |\pi \circ \tilde{f}(x)| \leq c\} \subset \{x \in X \mid |p(x)| \leq d\}$. PROOF:

If p is proper, latter is compact subset of X . \therefore claim suggests preimage under $\pi \circ \tilde{f}$ of every closed ball in \mathbb{H} is a compact subset of X . So BUOC, $\exists \{x_i\} \subset X \ni |\pi \circ \tilde{f}(x_i)| < c$ but $p(x_i) \rightarrow \infty$.

Then by definition, $\forall z \in \mathbb{R}^{2k+2}, \pi(z) \in \mathbb{H}$ where $z - \pi(z)$ is a multiple of $a \in \mathbb{H}^{2k+1}$. $\therefore \tilde{f}(x_i) - \pi \circ \tilde{f}(x_i)$ is a multiple of a for each i . $\therefore w_i = \frac{1}{p(x_i)} [\tilde{f}(x_i) - \pi \circ \tilde{f}(x_i)]$. Then $i \rightarrow \infty$ has $\frac{\tilde{f}(x_i)}{p(x_i)} = \left(\frac{f(x_i)}{p(x_i)}, 1 \right) \rightarrow (0, \dots, 0, 1)$ as $|f(x_i)| < 1, \forall i$. $\therefore \frac{\pi \circ \tilde{f}(x_i)}{p(x_i)}$ has norm $\leq \frac{c}{p(x_i)}$ that converges 0. $\therefore w_i \rightarrow (0, \dots, 0, 1)$.

Yet each w_i is a multiple of a , so is the limit. $\therefore a \in \mathbb{N}$ a pole of $S^{2k+1} \rightarrow \mathbb{H}$ thus $\pi \circ \tilde{f}$ embeds X into \mathbb{R}^{2k+1} . \blacksquare thus $\pi \circ \tilde{f}$ \square