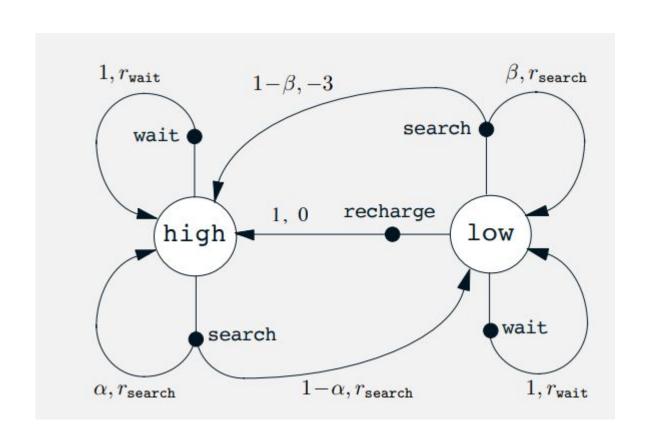
Automatons

- A mobile robot has the job of collecting empty soda cans in an oce environment.
- It has sensors for detecting cans, and an arm and gripper that can pick them up and place them in an onboard bin; it runs on a rechargeable battery.

- Assume that only two charge levels can be distinguished,
 comprising a small state set S = {high, low}
- In each state, the agent can decide whether to:
 - Actively search for a can for a certain period of time,
 - Remain stationary and wait for someone to bring it a can, or
 - Head back to its home base to recharge its battery

 The rewards are zero most of the time, but become positive when the robot secures an empty can, or large and negative if the battery runs all the way down



_	_	s'	-(-/)	l =(/)	$1, r_{\text{wait}}$ $1-\beta, -3$ β, r_{search}
S	a		p(s' s,a)	r(s, a, s')	
high	search	high	α	$r_{\mathtt{search}}$	wait search
high	search	low	$1-\alpha$	rsearch	
low	search	high	$1-\beta$	-3	
low	search	low	β	$r_{\mathtt{search}}$	1, 0 recharge
high	wait	high	1	$r_{\mathtt{wait}}$	high → (low)
high	wait	low	0		
low	wait	high	0	-	
low	wait	low	1	$r_{\mathtt{Wait}}$	
low	recharge	high	1	0	search
low	recharge	low	0	-	
					$\alpha, r_{\mathtt{search}}$ $1-\alpha, r_{\mathtt{search}}$ $1, r_{\mathtt{wait}}$