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Actions shape: (49,)
- ✓ Found trajectory: traj51
Actions shape: (49,)
- ✓ Found trajectory: traj248
Actions shape: (49,)
- ✓ Found trajectory: traj277
Actions shape: (49,)
- ✓ Found trajectory: traj283
Actions shape: (49,)
- ✓ Found trajectory: traj67
Actions shape: (49,)
- ✓ Found trajectory: traj93
Actions shape: (49,)
- ✓ Found trajectory: traj241
Actions shape: (49,)

- ✓ Found trajectory: traj58
Actions shape: (49,)
- ✓ Found trajectory: traj94
Actions shape: (49,)
- ✓ Found trajectory: traj279
Actions shape: (49,)
- ✓ Found trajectory: traj60
Actions shape: (49,)
- ✓ Found trajectory: traj246
Actions shape: (49,)
- ✓ Found trajectory: traj212
Actions shape: (49,)
- ✓ Found trajectory: traj34
Actions shape: (49,)
- ✓ Found trajectory: traj215
Actions shape: (49,)
- ✓ Found trajectory: traj33
Actions shape: (49,)
- ✓ Found trajectory: traj223
Actions shape: (49,)
- ✓ Found trajectory: traj224
Actions shape: (49,)
- ✓ Found trajectory: traj61
Actions shape: (49,)
- ✓ Found trajectory: traj278
Actions shape: (49,)
- ✓ Found trajectory: traj95
Actions shape: (49,)
- ✓ Found trajectory: traj247
Actions shape: (49,)
- ✓ Found trajectory: traj92
Actions shape: (49,)
- ✓ Found trajectory: traj66
Actions shape: (49,)
- ✓ Found trajectory: traj59
Actions shape: (49,)
- ✓ Found trajectory: traj240
Actions shape: (49,)
- ✓ Found trajectory: traj249
Actions shape: (49,)
- ✓ Found trajectory: traj50
Actions shape: (49,)
- ✓ Found trajectory: traj282
Actions shape: (49,)

✓ Found trajectory: traj276
Actions shape: (49,)
✓ Found trajectory: traj57
Actions shape: (49,)
✓ Found trajectory: traj271
Actions shape: (49,)
✓ Found trajectory: traj68
Actions shape: (49,)
✓ Found trajectory: traj285
Actions shape: (49,)
✓ Found trajectory: traj225
Actions shape: (49,)
✓ Found trajectory: traj222
Actions shape: (49,)
✓ Found trajectory: traj214
Actions shape: (49,)
✓ Found trajectory: traj32
Actions shape: (49,)
✓ Found trajectory: traj213
Actions shape: (49,)
✓ Found trajectory: traj35
Actions shape: (49,)
✓ Found trajectory: traj198
Actions shape: (49,)
✓ Found trajectory: traj153
Actions shape: (49,)
✓ Found trajectory: traj154
Actions shape: (49,)
✓ Found trajectory: traj162
Actions shape: (49,)
✓ Found trajectory: traj196
Actions shape: (49,)
✓ Found trajectory: traj191
Actions shape: (49,)
✓ Loaded 500 samples

⌚ Running evaluation...

💡 Sample 1: traj30

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0291, 0.0698, 0.0007, -0.0083, 0.0017, -0.6787, 0.0609]

Predicted: [-0.0083, 0.0177, 0.0380, 0.0420, -0.0611, 0.0999, 0.0000]

Time: 718.3s

MAE: 0.1518, MSE: 0.0887, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0321, 0.0641, -0.0044, 0.0002, 0.0026, -0.6839, 0.9952]

Predicted: [-0.0074, 0.0119, 0.0400, 0.0439, -0.0926, 0.0999, 0.0000]

Time: 2077.3s

MAE: 0.2913, MSE: 0.2316, Task Success: ✗

📸 Sample 2: traj3

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0030, -0.0366, 0.0037, -0.0035, 0.0072, 0.3568, 0.9934]

Predicted: [-0.0029, -0.0050, -0.0153, 0.0158, 0.0133, -0.0017, 0.9961]

Time: 729.9s

MAE: 0.0625, MSE: 0.0186, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0021, -0.0359, -0.0042, -0.0047, 0.0044, 0.3398, 0.9956]

Predicted: [0.0025, 0.0015, -0.0057, 0.0145, 0.0059, 0.0112, 0.0000]

Time: 746.3s

MAE: 0.1984, MSE: 0.1573, Task Success: ✗

📸 Sample 3: traj4

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0059, 0.0033, 0.0010, -0.0062, -0.0001, 0.4447, 1.0000]
 Predicted: [-0.0132, -0.0173, -0.0106, 0.0177, 0.0106, 0.0128, 0.9961]
 Time: 752.3s
 MAE: 0.0728, MSE: 0.0268, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0011, 0.0052, -0.0267, -0.0026, 0.0080, 0.4295, 1.0000]
 Predicted: [-0.0022, -0.0011, -0.0156, 0.0037, 0.0441, -0.0001, 0.9961]
 Time: 759.9s
 MAE: 0.0706, MSE: 0.0266, Task Success:

Sample 4: traj5

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0243, -0.0485, -0.0007, -0.0077, -0.0003, 0.7667, 0.9955]
 Predicted: [0.0023, 0.0018, -0.0008, 0.0145, 0.0086, 0.0112, 0.0000]
 Time: 759.6s
 MAE: 0.2656, MSE: 0.2237, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0284, -0.0369, -0.0021, -0.0025, 0.0000, 0.7629, 0.9945]
 Predicted: [0.0023, 0.0018, -0.0023, 0.0145, -0.0015, -0.0081, 0.0000]
 Time: 750.5s
 MAE: 0.2648, MSE: 0.2266, Task Success:

Sample 5: traj2

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0076, 0.0858, 0.0006, 0.0033, -0.0000, -0.6684, 1.0000]
 Predicted: [0.0034, 0.0122, 0.0218, 0.0037, -0.0537, 0.0128, 0.0000]
 Time: 740.1s
 MAE: 0.2630, MSE: 0.2104, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0142, 0.0841, -0.0027, 0.0081, 0.0029, -0.6480, 1.0000]
 Predicted: [-0.0031, 0.0161, 0.0208, -0.0199, -0.0343, 0.0531, 0.0000]
 Time: 748.6s
 MAE: 0.2670, MSE: 0.2142, Task Success:

Sample 6: traj13

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_4.jpg
 Ground Truth: [0.0243, 0.0290, -0.0028, -0.0030, -0.0083, -0.1676, 0.9938]
 Predicted: [0.0108, -0.0014, -0.0153, -0.0180, 0.0186, 0.0112, 0.9961]
 Time: 737.3s
 MAE: 0.0399, MSE: 0.0049, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_21.jpg
 Ground Truth: [0.0198, 0.0266, -0.0026, -0.0014, 0.0061, -0.1630, 0.9945]
 Predicted: [-0.0045, -0.0075, -0.0148, 0.0114, 0.0428, -0.0259, 0.9961]
 Time: 759.3s
 MAE: 0.0370, MSE: 0.0032, Task Success:

Sample 7: traj14

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0032, -0.0558, -0.0014, 0.0030, 0.0015, 0.6495, 1.0000]

 Predicted: [-0.0036, -0.0211, -0.0236, -0.0512, 0.0193, -0.0629, 0.0000]

 Time: 746.9s

 MAE: 0.2640, MSE: 0.2161, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0169, -0.0490, -0.0041, 0.0063, -0.0045, 0.6170, 0.9950]

 Predicted: [0.0029, -0.0231, -0.0213, -0.0327, 0.0153, -0.0629, 0.0000]

 Time: 746.0s

 MAE: 0.2558, MSE: 0.2079, Task Success: 

Sample 8: traj22

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [-0.0387, -0.0348, 0.0032, -0.0012, 0.0002, -0.2183, 0.0596]

 Predicted: [0.0031, 0.0083, -0.0018, 0.0177, 0.0052, -0.0001, 0.0000]

 Time: 748.8s

 MAE: 0.0560, MSE: 0.0079, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [-0.0334, -0.0257, 0.0037, -0.0054, 0.0027, -0.2083, 0.0633]

 Predicted: [-0.0051, 0.0141, -0.0093, -0.0404, 0.0227, -0.0597, 0.0000]

 Time: 743.9s

📊 MAE: 0.0497, MSE: 0.0043, Task Success: ✗

📸 Sample 9: traj25

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_4.jpg

✓ Ground Truth: [0.0134, 0.0466, 0.0040, -0.0087, -0.0012, 0.7999, 0.0689]

🎯 Predicted: [-0.0080, -0.0338, -0.0145, -0.0206, 0.0193, -0.0307, 0.0000]

⌚ Time: 754.2s

📊 MAE: 0.1503, MSE: 0.1003, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_5.jpg

✓ Ground Truth: [0.0234, 0.0557, 0.0029, -0.0022, 0.0014, 0.7811, 0.0558]

🎯 Predicted: [0.0159, -0.0082, -0.0236, 0.0280, 0.0267, -0.0339, 0.9961]

⌚ Time: 743.4s

📊 MAE: 0.2727, MSE: 0.2221, Task Success: ✗

📸 Sample 10: traj24

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [-0.0041, -0.0255, -0.0027, 0.0002, -0.0044, -0.7090, 1.0000]

🎯 Predicted: [0.0000, 0.0090, -0.0034, 0.0644, -0.0068, -0.0001, 0.9961]

⌚ Time: 750.3s

📊 MAE: 0.1169, MSE: 0.0726, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [0.0001, -0.0147, -0.0077, 0.0037, -0.0022, -0.6958, 1.0000]

🎯 Predicted: [-0.0060, -0.0163, 0.0400, -0.0244, -0.0926, -0.0436, 0.9961]
⌚ Time: 740.1s
📊 MAE: 0.1186, MSE: 0.0624, Task Success: 

📸 Sample 11: traj23

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [-0.0212, 0.0174, 0.0000, -0.0037, -0.0027, -0.4425, 0.9989]

🎯 Predicted: [-0.0033, -0.0017, -0.0057, -0.0014, 0.0039, -0.0097, 0.9961]

⌚ Time: 756.9s

📊 MAE: 0.0696, MSE: 0.0269, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [-0.0214, 0.0196, -0.0041, 0.0009, 0.0060, -0.4308, 1.0000]

🎯 Predicted: [0.0011, -0.0111, -0.0067, 0.0043, -0.0323, -0.0242, 0.9961]

⌚ Time: 766.8s

📊 MAE: 0.0726, MSE: 0.0240, Task Success: 

📸 Sample 12: traj15

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [-0.0163, -0.0294, 0.0012, -0.0030, 0.0026, -0.4423, 0.9934]

🎯 Predicted: [-0.0004, -0.0001, 0.0013, -0.0021, -0.0028, -0.0001, 0.9961]

⌚ Time: 751.1s

📊 MAE: 0.0709, MSE: 0.0281, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg
 Ground Truth: [-0.0100, -0.0322, -0.0096, -0.0032, -0.0051, -0.4234, 0.9953]
 Predicted: [-0.0036, 0.0336, -0.0080, -0.0238, 0.0227, 0.1563, 0.0000]
 Time: 750.6s
 MAE: 0.2425, MSE: 0.1903, Task Success: X

Sample 13: traj12

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0013, -0.0053, -0.0347, -0.0026, -0.0006, 0.0974, 1.0000]
 Predicted: [-0.0069, -0.0079, 0.0044, -0.0219, -0.0504, -0.1000, 0.9961]
 Time: 744.0s
 MAE: 0.0457, MSE: 0.0062, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0108, -0.0034, -0.0221, -0.0065, 0.0049, 0.0774, 0.9996]
 Predicted: [-0.0074, -0.0208, 0.0044, -0.0219, -0.0450, -0.1097, 0.9961]
 Time: 746.4s
 MAE: 0.0454, MSE: 0.0056, Task Success: ✓

Sample 14: traj9

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0181, -0.0346, -0.0046, -0.0038, -0.0064, 0.7927, 1.0000]
 Predicted: [-0.0069, 0.0148, -0.0052, 0.0318, 0.0140, 0.0096, 0.0000]
 Time: 749.1s
 MAE: 0.2734, MSE: 0.2312, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0054, -0.0458, -0.0062, 0.0075, 0.0009, 0.7680, 0.9958]
 Predicted: [-0.0038, 0.0041, -0.0065, 0.0561, -0.0215, -0.0130, 0.0000]
 Time: 744.9s
 MAE: 0.2724, MSE: 0.2296, Task Success: 

Sample 15: traj7

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0194, 0.0260, 0.0015, -0.0058, -0.0044, 0.7748, 0.0763]
 Predicted: [0.0000, -0.0043, -0.0002, 0.0209, -0.0015, -0.0081, 0.0000]
 Time: 735.0s
 MAE: 0.1343, MSE: 0.0887, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0226, 0.0173, 0.0014, -0.0012, -0.0004, 0.7697, 0.0687]
 Predicted: [-0.0062, -0.0069, -0.0044, -0.0257, -0.0162, -0.0017, 0.9961]
 Time: 744.8s
 MAE: 0.2568, MSE: 0.2082, Task Success: 

Sample 16: traj0

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0169, -0.0110, 0.0022, -0.0002, 0.0112, 0.5428, 1.0000]
 Predicted: [-0.0152, -0.0046, -0.0054, 0.0126, -0.0061, 0.0870, 0.9961]
 Time: 752.4s
 MAE: 0.0766, MSE: 0.0299, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0208, -0.0022, -0.0023, 0.0055, 0.0086, 0.5372, 0.9981]
 Predicted: [-0.0051, -0.0169, -0.0036, 0.0126, 0.0052, -0.0178, 0.9961]
 Time: 751.9s
 MAE: 0.0871, MSE: 0.0441, Task Success:

Sample 17: traj1

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0072, -0.0069, 0.0015, -0.0004, -0.0029, 0.7976, 1.0000]
 Predicted: [-0.0007, 0.0167, 0.0013, -0.0372, -0.0088, 0.0515, 0.0000]
 Time: 756.8s
 MAE: 0.2599, MSE: 0.2227, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0165, -0.0003, 0.0060, -0.0054, 0.0053, 0.7756, 1.0000]
 Predicted: [0.0213, 0.0252, -0.0073, 0.0618, 0.0454, 0.0322, 0.0000]
 Time: 743.5s
 MAE: 0.2753, MSE: 0.2230, Task Success:

Sample 18: traj6

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0151, 0.0128, 0.0028, 0.0056, -0.0052, 0.2289, 0.9913]
 Predicted: [0.0031, 0.0329, 0.0057, -0.0097, -0.0416, 0.0692, 0.0000]
 Time: 749.8s

📊 MAE: 0.1777, MSE: 0.1444, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0122, 0.0059, 0.0033, 0.0006, -0.0028, 0.2130, 0.9980]
🎯 Predicted: [-0.0009, 0.0018, -0.0148, 0.0171, 0.0655, 0.0322, 0.0000]
⌚ Time: 745.3s
📊 MAE: 0.1853, MSE: 0.1477, Task Success: ✗

📸 Sample 19: traj8

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0165, -0.0370, -0.0010, -0.0001, 0.0057, -0.4236, 1.0000]
🎯 Predicted: [0.0085, 0.0012, -0.0236, 0.0650, 0.0267, 0.0418, 0.9961]
⌚ Time: 743.2s
📊 MAE: 0.0892, MSE: 0.0319, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0108, -0.0344, -0.0037, -0.0016, -0.0046, -0.4194, 1.0000]
🎯 Predicted: [0.0027, 0.0009, -0.0034, 0.0101, -0.0048, -0.0242, 0.9961]
⌚ Time: 744.6s
📊 MAE: 0.0649, MSE: 0.0225, Task Success: ✓

📸 Sample 20: traj17

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_4.jpg
✓ Ground Truth: [0.0209, -0.0393, 0.0051, 0.0034, -0.0015, -0.6995, 1.0000]

🎯 Predicted: [-0.0033, 0.0187, -0.0002, -0.0321, -0.0162, 0.0499, 0.9961]
⌚ Time: 747.0s
📊 MAE: 0.1273, MSE: 0.0810, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_5.jpg
✓ Ground Truth: [0.0208, -0.0448, 0.0007, 0.0074, -0.0078, -0.6986, 0.9884]
🎯 Predicted: [-0.0033, -0.0156, 0.0086, -0.0225, -0.0356, 0.0354, 0.9961]
⌚ Time: 745.6s
📊 MAE: 0.1229, MSE: 0.0774, Task Success: ✓

📸 Sample 21: traj28

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [0.0000, -0.0323, 0.0042, -0.0015, 0.0080, 0.3114, 1.0000]
🎯 Predicted: [-0.0049, -0.0017, -0.0028, 0.0050, 0.0106, 0.0451, 0.9961]
⌚ Time: 761.8s
📊 MAE: 0.0460, MSE: 0.0103, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0034, -0.0303, -0.0047, 0.0062, -0.0004, 0.2925, 0.9967]
🎯 Predicted: [0.0146, 0.0261, -0.0075, -0.0065, 0.0032, 0.0950, 0.0000]
⌚ Time: 738.9s
📊 MAE: 0.1840, MSE: 0.1480, Task Success: ✗

📸 Sample 22: traj10

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)

 Image 1: im_42.jpg
 Ground Truth: [0.0345, -0.0424, -0.0044, -0.0018, 0.0048, 0.9367, 0.0518]
 Predicted: [0.0000, -0.0082, 0.0042, -0.0282, -0.0390, -0.0452, 0.0000]
 Time: 746.9s
 MAE: 0.1687, MSE: 0.1388, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0184, -0.0279, 0.0024, -0.0018, -0.0002, 0.9139, 0.0575]
 Predicted: [-0.0022, -0.0004, 0.0008, -0.0014, 0.0173, -0.0130, 0.9961]
 Time: 748.9s
 MAE: 0.2761, MSE: 0.2488, Task Success: X

Sample 23: traj26

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0021, -0.0291, 0.0024, 0.0071, 0.0069, -0.9734, 0.9993]
 Predicted: [-0.0058, -0.0046, 0.0055, -0.0397, -0.0162, -0.0210, 0.0000]
 Time: 738.4s
 MAE: 0.2939, MSE: 0.2727, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0018, -0.0231, 0.0037, 0.0017, -0.0037, -0.9650, 0.9939]
 Predicted: [-0.0002, -0.0105, 0.0187, -0.0187, -0.0524, -0.0162, 0.9961]
 Time: 735.3s
 MAE: 0.1499, MSE: 0.1291, Task Success: ✓

Sample 24: traj19

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0170, -0.0371, -0.0083, 0.0035, -0.0063, -0.6241, 0.0547]
 Predicted: [0.0081, 0.0015, -0.0075, -0.0206, 0.0059, 0.0209, 0.0000]
 Time: 736.7s
 MAE: 0.1143, MSE: 0.0603, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0171, -0.0401, 0.0019, 0.0021, -0.0049, -0.6082, 0.0558]
 Predicted: [0.0081, -0.0134, -0.0021, -0.0116, -0.0175, -0.0323, 0.0000]
 Time: 750.8s
 MAE: 0.1020, MSE: 0.0481, Task Success: 

Sample 25: traj21

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0058, 0.0124, 0.0002, -0.0092, 0.0055, -0.1390, 0.9988]
 Predicted: [-0.0154, 0.0141, 0.0039, -0.0161, -0.0135, 0.0241, 0.9961]
 Time: 743.6s
 MAE: 0.0312, MSE: 0.0039, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0013, 0.0134, 0.0012, -0.0005, -0.0120, -0.1349, 0.9912]
 Predicted: [-0.0154, 0.0141, -0.0073, 0.0101, -0.0108, 0.1579, 0.9961]
 Time: 749.2s
 MAE: 0.0479, MSE: 0.0123, Task Success: 

Sample 26: traj20

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_4.jpg
 Ground Truth: [0.0346, 0.0529, -0.0023, -0.0049, -0.0076, 0.7310, 0.0699]
 Predicted: [-0.0116, 0.0381, 0.0112, 0.0056, -0.0249, 0.1563, 0.0000]
 Time: 756.2s
 MAE: 0.1067, MSE: 0.0483, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_5.jpg
 Ground Truth: [0.0420, 0.0557, 0.0045, 0.0021, 0.0035, 0.7388, 0.0592]
 Predicted: [-0.0036, 0.0219, 0.0018, 0.0158, -0.0108, 0.0289, 0.0000]
 Time: 751.0s
 MAE: 0.1256, MSE: 0.0730, Task Success: ✗

Sample 27: traj27

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0082, 0.0435, 0.0002, -0.0021, 0.0044, -0.6192, 0.9991]
 Predicted: [0.0072, 0.0106, -0.0013, 0.0094, -0.0068, 0.0161, 0.0000]
 Time: 745.1s
 MAE: 0.2438, MSE: 0.2005, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0027, 0.0478, -0.0026, 0.0010, 0.0082, -0.6088, 0.9959]
 Predicted: [-0.0080, 0.0018, 0.0380, -0.0295, -0.0852, 0.0209, 0.0000]
 Time: 739.3s
 MAE: 0.2638, MSE: 0.2003, Task Success: ✗

Sample 28: traj18

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0096, 0.0235, -0.0024, -0.0001, -0.0021, -0.9147, 0.0621]
 Predicted: [-0.0047, -0.0004, -0.0021, -0.0033, 0.0166, -0.0178, 0.0000]
 Time: 746.4s
 MAE: 0.1443, MSE: 0.1156, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0093, 0.0172, 0.0048, -0.0059, -0.0032, -0.8765, 0.0594]
 Predicted: [-0.0047, -0.0037, 0.0312, -0.0180, -0.0497, -0.0081, 0.9961]
 Time: 740.6s
 MAE: 0.2736, MSE: 0.2335, Task Success:

Sample 29: traj11

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0033, -0.0178, 0.0018, 0.0039, 0.0018, -0.3363, 0.0662]
 Predicted: [-0.0076, 0.0407, -0.0117, 0.0292, 0.0200, 0.0870, 0.0000]
 Time: 746.0s
 MAE: 0.0880, MSE: 0.0269, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0033, -0.0194, 0.0055, -0.0015, 0.0005, -0.3148, 0.9978]
 Predicted: [0.0000, 0.0018, -0.0057, 0.0120, 0.0200, 0.0032, 0.0000]
 Time: 739.8s
 MAE: 0.1978, MSE: 0.1568, Task Success:

Sample 30: traj16

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0008, 0.0465, 0.0095, 0.0060, -0.0083, -0.6037, 1.0000]

 Predicted: [0.0246, 0.0086, -0.0080, -0.0116, -0.0095, -0.0033, 0.0000]

 Time: 748.7s

 MAE: 0.2426, MSE: 0.1947, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [-0.0097, 0.0469, 0.0043, -0.0005, -0.0055, -0.5842, 1.0000]

 Predicted: [0.0058, -0.0092, 0.0021, -0.0250, -0.0122, -0.0017, 0.9961]

 Time: 754.2s

 MAE: 0.0988, MSE: 0.0491, Task Success: 

Sample 31: traj29

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [-0.0151, -0.0257, -0.0010, -0.0008, 0.0011, -0.9034, 0.0574]

 Predicted: [-0.0031, -0.0053, -0.0039, -0.0295, 0.0059, -0.0194, 0.9961]

 Time: 746.6s

 MAE: 0.2702, MSE: 0.2377, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [-0.0122, -0.0176, -0.0050, 0.0035, -0.0077, -0.9056, 0.0598]

 Predicted: [0.0081, -0.0121, 0.0348, -0.0104, -0.0617, -0.0404, 0.0000]

Time: 748.7s
 MAE: 0.1512, MSE: 0.1082, Task Success: X

Sample 32: traj30

Instruction: pick up the object and place it in the bowl

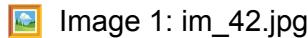
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0085, 0.0546, 0.0053, 0.0036, -0.0013, 0.4814, 0.9949]

⌚ Predicted: [0.0014, 0.0009, -0.0002, 0.0043, 0.0052, -0.0130, 0.0000]

Time: 746.1s

MAE: 0.2237, MSE: 0.1768, Task Success: X

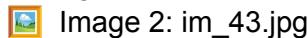
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0129, 0.0547, 0.0002, -0.0001, -0.0043, 0.4672, 0.9960]

⌚ Predicted: [-0.0022, -0.0046, -0.0021, 0.0209, -0.0075, -0.0226, 0.0000]

Time: 738.7s

MAE: 0.2260, MSE: 0.1766, Task Success: X

Sample 33: traj37

Instruction: pick up the object and place it in the bowl

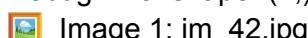
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0251, -0.0647, 0.0052, -0.0026, 0.0034, -0.9744, 0.0522]

⌚ Predicted: [-0.0062, -0.0153, -0.0047, -0.0167, -0.0189, -0.0436, 0.9961]

Time: 747.5s

MAE: 0.2842, MSE: 0.2516, Task Success: X

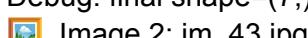
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0322, -0.0604, 0.0016, 0.0017, 0.0021, -0.9572, 0.0540]
🎯 Predicted: [-0.0020, -0.0176, -0.0140, 0.0069, 0.0106, -0.0629, 0.9961]
⌚ Time: 743.4s
📊 MAE: 0.2770, MSE: 0.2415, Task Success: ✗

📸 Sample 34: traj39

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [0.0011, 0.0092, 0.0059, 0.0065, -0.0095, -0.2077, 0.9996]

🎯 Predicted: [-0.0020, 0.0005, -0.0104, -0.0033, 0.0320, -0.0033, 0.9961]

⌚ Time: 742.0s

📊 MAE: 0.0411, MSE: 0.0063, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [-0.0030, 0.0111, -0.0047, 0.0086, 0.0042, -0.1892, 1.0000]

🎯 Predicted: [-0.0109, -0.0082, -0.0086, 0.0248, -0.0115, 0.1692, 0.9961]

⌚ Time: 738.2s

📊 MAE: 0.0607, MSE: 0.0185, Task Success: ✓

📸 Sample 35: traj52

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_4.jpg

✓ Ground Truth: [0.0292, 0.0592, 0.0019, 0.0001, -0.0010, -0.1297, 0.9928]

🎯 Predicted: [0.0049, 0.0187, -0.0013, 0.0082, -0.0041, 0.0289, 0.0000]

⌚ Time: 744.6s

📊 MAE: 0.1758, MSE: 0.1447, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)
Image 2: im_21.jpg
Ground Truth: [0.0170, 0.0586, -0.0021, -0.0034, -0.0033, -0.1174, 0.9977]
Predicted: [-0.0045, -0.0033, 0.0151, 0.0005, -0.0423, 0.0161, 0.0000]
Time: 750.8s
MAE: 0.1821, MSE: 0.1456, Task Success: ✗

📸 Sample 36: traj55

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [0.0238, 0.0752, -0.0051, -0.0001, -0.0073, 0.7085, 0.9911]
Predicted: [0.0027, 0.0138, 0.0120, -0.0110, -0.0115, 0.0289, 0.0000]
Time: 742.6s
MAE: 0.2551, MSE: 0.2070, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [0.0233, 0.0774, 0.0068, -0.0014, -0.0062, 0.6993, 1.0000]
Predicted: [0.0110, 0.0009, 0.0000, 0.0056, -0.0256, 0.0015, 0.0000]
Time: 747.0s
MAE: 0.2600, MSE: 0.2133, Task Success: ✗

📸 Sample 37: traj38

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [0.0111, -0.0530, -0.0033, -0.0044, 0.0009, 0.4800, 0.9966]
Predicted: [-0.0080, 0.0158, 0.0104, 0.0082, 0.0026, 0.0241, 0.0000]
Time: 747.7s
MAE: 0.2241, MSE: 0.1724, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0041, -0.0435, -0.0074, 0.0012, 0.0081, 0.4543, 1.0000]
 Predicted: [-0.0065, -0.0004, 0.0203, -0.0129, -0.0316, 0.0032, 0.0000]
 Time: 747.4s
 MAE: 0.2266, MSE: 0.1726, Task Success:

Sample 38: traj36

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0210, -0.0142, -0.0050, 0.0054, 0.0021, -0.2200, 1.0000]
 Predicted: [-0.0004, 0.0077, -0.0021, -0.0129, 0.0012, 0.0322, 0.9961]
 Time: 744.6s
 MAE: 0.0459, MSE: 0.0093, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0372, -0.0148, 0.0098, 0.0007, 0.0047, -0.2197, 1.0000]
 Predicted: [-0.0040, -0.0024, -0.0109, -0.0257, 0.0106, -0.0678, 0.9961]
 Time: 772.0s
 MAE: 0.0375, MSE: 0.0037, Task Success:

Sample 39: traj31

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0110, 0.0021, 0.0018, 0.0000, 0.0021, -0.8165, 0.9960]
 Predicted: [-0.0056, 0.0116, -0.0036, -0.0474, 0.0012, 0.0580, 0.9961]
 Time: 779.2s
 MAE: 0.1348, MSE: 0.1096, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0144, 0.0060, 0.0100, -0.0036, 0.0033, -0.8041, 0.9986]
 Predicted: [-0.0141, 0.0077, -0.0028, -0.0512, -0.0530, -0.0500, 0.9961]
 Time: 765.3s
 MAE: 0.1251, MSE: 0.0820, Task Success:

Sample 40: traj54

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0137, 0.0228, 0.0050, 0.0041, -0.0042, -0.8320, 0.9951]
 Predicted: [-0.0051, -0.0134, -0.0140, -0.0365, 0.0059, -0.0307, 0.0000]
 Time: 782.6s
 MAE: 0.2745, MSE: 0.2337, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0094, 0.0321, -0.0020, -0.0068, -0.0011, -0.8208, 0.9998]
 Predicted: [-0.0074, -0.0415, -0.0047, -0.0423, -0.0075, -0.0710, 0.0000]
 Time: 772.6s
 MAE: 0.2692, MSE: 0.2241, Task Success:

Sample 41: traj53

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0242, -0.0008, -0.0015, -0.0071, -0.0015, 0.3296, 0.9944]
 Predicted: [0.0116, -0.0134, 0.0016, -0.0231, -0.0926, -0.0597, 0.0000]

⌚ Time: 763.1s
📊 MAE: 0.2203, MSE: 0.1643, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0185, -0.0046, -0.0131, -0.0036, -0.0036, 0.3254, 1.0000]
🎯 Predicted: [0.0014, -0.0124, 0.0008, -0.0206, 0.0126, -0.0162, 0.0000]
⌚ Time: 797.1s
📊 MAE: 0.2023, MSE: 0.1597, Task Success: ✗

📸 Sample 42: traj3
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0046, 0.0117, -0.0179, 0.0017, 0.0052, -0.6941, 1.0000]
🎯 Predicted: [0.0014, 0.0009, -0.0002, 0.0075, -0.0095, 0.0080, 0.0000]
⌚ Time: 783.8s
📊 MAE: 0.2506, MSE: 0.2134, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0044, 0.0078, -0.0130, 0.0005, -0.0008, -0.6692, 1.0000]
🎯 Predicted: [0.0014, -0.0007, 0.0000, 0.0248, -0.0095, -0.0049, 0.0000]
⌚ Time: 749.4s
📊 MAE: 0.2464, MSE: 0.2060, Task Success: ✗

📸 Sample 43: traj4
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg

Ground Truth: [-0.0074, -0.0100, 0.0012, -0.0003, 0.0031, 0.9462, 1.0000]

Predicted: [-0.0007, 0.0167, 0.0218, 0.0177, -0.0517, 0.0257, 0.0000]

Time: 738.4s

MAE: 0.2925, MSE: 0.2645, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0075, 0.0019, -0.0011, -0.0017, -0.0054, 0.9289, 1.0000]

Predicted: [0.0085, -0.0169, 0.0148, -0.0512, -0.0309, -0.0452, 0.0000]

Time: 738.3s

MAE: 0.3000, MSE: 0.2790, Task Success:

Sample 44: traj5

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0081, 0.0226, -0.0014, 0.0022, 0.0038, -0.5799, 1.0000]

Predicted: [-0.0116, -0.0004, -0.0127, 0.0107, 0.0119, 0.0386, 0.9961]

Time: 774.6s

MAE: 0.0967, MSE: 0.0548, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0196, 0.0340, 0.0100, 0.0021, 0.0008, -0.5751, 0.9946]

Predicted: [-0.0078, -0.0046, -0.0236, -0.0110, 0.0180, -0.0194, 0.9961]

Time: 779.0s

MAE: 0.0959, MSE: 0.0446, Task Success:

Sample 45: traj2

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [0.0289, -0.0058, -0.0045, -0.0011, -0.0024, 0.2351, 0.9992]

Predicted: [0.0108, -0.0305, -0.0140, 0.0280, -0.0276, -0.1338, 0.9961]

Time: 761.3s

MAE: 0.0684, MSE: 0.0198, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0146, -0.0085, -0.0086, 0.0082, 0.0003, 0.2223, 1.0000]

Predicted: [-0.0009, -0.0124, -0.0140, -0.0225, -0.0229, -0.0468, 0.9961]

Time: 761.5s

MAE: 0.0502, MSE: 0.0106, Task Success: ✓

📸 Sample 46: traj49

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [0.0203, 0.0468, -0.0029, -0.0038, -0.0002, 0.7138, 0.0695]

Predicted: [0.0014, -0.0338, -0.0057, 0.0011, -0.0088, -0.0516, 0.0000]

Time: 745.5s

MAE: 0.1358, MSE: 0.0854, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0316, 0.0391, -0.0083, -0.0075, -0.0062, 0.7007, 1.0000]

Predicted: [-0.0058, 0.0145, 0.0000, 0.0043, -0.0061, 0.0241, 0.0000]

Time: 739.0s

MAE: 0.2513, MSE: 0.2086, Task Success: ✗

📸 Sample 47: traj40

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0140, -0.0319, 0.0050, -0.0102, 0.0036, -0.2586, 1.0000]
 Predicted: [0.0018, -0.0001, -0.0106, 0.0273, 0.0381, -0.0049, 0.0000]
 Time: 747.7s
 MAE: 0.1979, MSE: 0.1526, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0180, -0.0366, -0.0021, 0.0017, -0.0007, -0.2464, 1.0000]
 Predicted: [-0.0004, -0.0001, -0.0073, 0.0062, 0.0260, -0.0017, 0.0000]
 Time: 736.5s
 MAE: 0.1909, MSE: 0.1518, Task Success:

Sample 48: traj47

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0357, -0.0209, 0.0003, -0.0070, 0.0037, -0.8047, 0.0590]
 Predicted: [-0.0118, -0.0004, 0.0070, -0.0008, -0.0249, 0.0161, 0.0000]
 Time: 739.1s
 MAE: 0.1413, MSE: 0.0972, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0315, -0.0293, -0.0010, 0.0084, 0.0121, -0.7859, 0.9994]
 Predicted: [-0.0071, 0.0041, -0.0067, 0.0005, 0.0253, 0.0064, 0.9961]
 Time: 742.6s
 MAE: 0.1278, MSE: 0.0901, Task Success:

Sample 49: traj13

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0188, 0.0013, -0.0022, -0.0094, -0.0069, 0.8908, 0.0600]
 Predicted: [-0.0172, -0.0127, 0.0109, -0.0174, -0.0718, -0.0533, 0.9961]
 Time: 740.3s
 MAE: 0.2831, MSE: 0.2532, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0224, -0.0055, 0.0051, 0.0020, 0.0087, 0.8724, 0.0519]
 Predicted: [-0.0087, -0.0043, 0.0008, -0.0027, -0.0343, 0.0644, 0.9961]
 Time: 747.8s
 MAE: 0.2598, MSE: 0.2209, Task Success:

Sample 50: traj14

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0260, -0.0073, 0.0052, -0.0017, -0.0023, -0.7051, 1.0000]
 Predicted: [-0.0074, -0.0050, 0.0400, -0.0321, -0.0926, 0.0177, 0.9961]
 Time: 736.0s
 MAE: 0.1290, MSE: 0.0761, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0288, -0.0107, 0.0012, 0.0005, 0.0051, -0.7042, 0.9893]
 Predicted: [-0.0009, -0.0037, 0.0042, -0.0231, -0.0202, -0.0113, 0.9961]
 Time: 738.9s
 MAE: 0.1123, MSE: 0.0689, Task Success:

Sample 51: traj22

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [-0.0229, -0.0601, 0.0096, 0.0005, -0.0033, -0.1245, 0.9986]

 Predicted: [-0.0002, -0.0001, -0.0073, 0.0005, 0.0247, 0.0096, 0.9961]

 Time: 748.6s

 MAE: 0.0378, MSE: 0.0033, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [-0.0259, -0.0496, -0.0015, -0.0039, -0.0098, -0.1315, 0.9934]

 Predicted: [-0.0013, -0.0001, -0.0093, -0.0014, 0.0294, 0.0096, 0.9961]

 Time: 745.1s

 MAE: 0.0382, MSE: 0.0035, Task Success: 

Sample 52: traj25

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [-0.0043, -0.0327, 0.0006, -0.0125, -0.0038, -0.8999, 0.0640]

 Predicted: [0.0130, -0.0221, -0.0031, -0.0027, 0.0086, -0.0758, 0.0000]

 Time: 762.4s

 MAE: 0.1346, MSE: 0.0977, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [-0.0071, -0.0385, -0.0049, 0.0007, 0.0037, -0.8845, 0.0576]

 Predicted: [0.0023, -0.0007, -0.0002, 0.0024, 0.0086, -0.0597, 0.9961]

 Time: 774.7s

 MAE: 0.2602, MSE: 0.2232, Task Success: X

 Sample 53: traj46

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

✓ Ground Truth: [0.0083, -0.0370, -0.0005, 0.0046, -0.0080, 0.6497, 0.0657]

○ Predicted: [-0.0031, -0.0014, -0.0002, -0.0072, 0.0173, -0.0178, 0.9961]

 Time: 747.5s

 MAE: 0.2403, MSE: 0.1876, Task Success: X

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

✓ Ground Truth: [0.0214, -0.0425, -0.0074, 0.0005, -0.0035, 0.6239, 1.0000]

○ Predicted: [-0.0013, -0.0014, -0.0015, -0.0174, -0.0001, -0.0017, 0.9961]

 Time: 754.4s

 MAE: 0.1029, MSE: 0.0563, Task Success: ✓

 Sample 54: traj41

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

✓ Ground Truth: [-0.0021, -0.0110, 0.0021, -0.0046, 0.0096, 0.6986, 1.0000]

○ Predicted: [0.0063, -0.0033, -0.0023, -0.0155, -0.0437, 0.0032, 0.9961]

 Time: 756.9s

 MAE: 0.1120, MSE: 0.0695, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

✓ Ground Truth: [0.0024, -0.0023, 0.0109, 0.0014, 0.0061, 0.6726, 1.0000]

🎯 Predicted: [-0.0051, 0.0035, 0.0011, -0.0531, 0.0207, 0.0177, 0.9961]
⌚ Time: 767.2s
📊 MAE: 0.1073, MSE: 0.0618, Task Success: ✓

📸 Sample 55: traj48

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_4.jpg

✓ Ground Truth: [-0.0040, -0.0001, 0.0023, 0.0131, -0.0009, -0.5900, 1.0000]

🎯 Predicted: [-0.0224, 0.0116, -0.0104, 0.0292, -0.0055, 0.0338, 0.9961]

⌚ Time: 761.3s

📊 MAE: 0.0987, MSE: 0.0557, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_21.jpg

✓ Ground Truth: [-0.0156, -0.0024, -0.0053, -0.0074, 0.0007, -0.5836, 0.9982]

🎯 Predicted: [-0.0163, 0.0145, 0.0187, 0.0790, 0.0006, 0.1385, 0.0000]

⌚ Time: 758.9s

📊 MAE: 0.2641, MSE: 0.2180, Task Success: ✗

📸 Sample 56: traj24

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0042, 0.0086, 0.0001, 0.0089, 0.0018, -0.7992, 0.9930]

🎯 Predicted: [-0.0076, -0.0173, 0.0224, -0.0257, -0.0604, 0.0612, 0.0000]

⌚ Time: 747.8s

📊 MAE: 0.2872, MSE: 0.2475, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg
 Ground Truth: [0.0063, 0.0122, -0.0006, -0.0003, 0.0011, -0.7854, 0.9938]
 Predicted: [-0.0038, 0.0093, 0.0148, -0.0001, 0.0495, -0.0001, 0.0000]
 Time: 750.1s
 MAE: 0.2651, MSE: 0.2296, Task Success: X

Sample 57: traj23

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0119, -0.0070, 0.0025, 0.0005, -0.0030, -0.5207, 1.0000]

 Predicted: [-0.0051, 0.0129, -0.0065, -0.0078, 0.0200, 0.0096, 0.9961]

 Time: 738.1s

 MAE: 0.0873, MSE: 0.0404, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0213, -0.0223, -0.0042, 0.0079, -0.0010, -0.5158, 0.9984]

 Predicted: [0.0130, 0.0264, 0.0198, -0.0333, -0.0195, 0.0499, 0.0000]

 Time: 742.4s

 MAE: 0.2436, MSE: 0.1888, Task Success: X

Sample 58: traj15

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0111, 0.0845, 0.0019, 0.0042, 0.0052, -0.3238, 0.0675]

 Predicted: [0.0179, 0.0093, 0.0400, 0.0082, -0.0926, 0.0209, 0.0000]

 Time: 745.8s

 MAE: 0.0906, MSE: 0.0200, Task Success: X

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0158, 0.0781, -0.0011, -0.0073, 0.0020, -0.3038, 0.0699]
 Predicted: [-0.0013, 0.0018, -0.0010, 0.0120, 0.0052, -0.0017, 0.0000]
 Time: 758.3s
 MAE: 0.0697, MSE: 0.0147, Task Success: X

Sample 59: traj12

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0142, 0.0255, 0.0020, 0.0027, 0.0010, 0.7825, 1.0000]
 Predicted: [-0.0224, 0.0404, -0.0088, 0.0037, -0.0068, 0.0999, 0.0000]
 Time: 749.6s
 MAE: 0.2505, MSE: 0.2097, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0047, 0.0339, -0.0007, 0.0104, -0.0004, 0.7724, 0.9985]
 Predicted: [0.0116, 0.0407, -0.0093, 0.0816, -0.0564, -0.0130, 0.0000]
 Time: 744.3s
 MAE: 0.2762, MSE: 0.2318, Task Success: X

Sample 60: traj56

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0186, 0.0630, -0.0069, -0.0109, -0.0097, 0.9401, 1.0000]
 Predicted: [0.0014, -0.0169, -0.0140, -0.0231, 0.0106, -0.0355, 0.0000]
 Time: 1174.4s
 MAE: 0.3018, MSE: 0.2799, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0228, 0.0665, 0.0043, 0.0125, 0.0020, 0.9358, 0.9971]
 Predicted: [0.0014, 0.0187, -0.0197, 0.0216, 0.0341, 0.0289, 0.0000]
 Time: 759.5s
 MAE: 0.2912, MSE: 0.2602, Task Success: X

Sample 61: traj51

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0413, -0.0276, 0.0049, -0.0010, 0.0000, 0.6809, 0.9952]
 Predicted: [0.0014, -0.0004, 0.0000, -0.0091, -0.0015, -0.0210, 0.0000]
 Time: 767.0s
 MAE: 0.2545, MSE: 0.2122, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0362, -0.0179, 0.0058, 0.0030, 0.0038, 0.6543, 1.0000]
 Predicted: [-0.0067, -0.0011, -0.0023, 0.0069, 0.0233, 0.0418, 0.0000]
 Time: 764.3s
 MAE: 0.2415, MSE: 0.1967, Task Success: X

Sample 62: traj58

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0109, -0.0386, 0.0037, -0.0033, 0.0055, 0.2312, 0.9990]
 Predicted: [-0.0027, -0.0124, -0.0189, -0.0052, -0.0222, -0.0194, 0.0000]
 Time: 807.1s

📊 MAE: 0.1909, MSE: 0.1518, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0072, -0.0473, -0.0045, -0.0002, -0.0036, 0.2154, 0.9916]
🎯 Predicted: [-0.0016, -0.0011, -0.0018, -0.0129, -0.0169, 0.0660, 0.9961]
⌚ Time: 801.9s
📊 MAE: 0.0335, MSE: 0.0035, Task Success: ✓

📸 Sample 63: traj34

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0169, -0.0523, 0.0007, 0.0053, -0.0056, 0.1214, 1.0000]
🎯 Predicted: [-0.0031, -0.0059, 0.0107, -0.0104, -0.0276, 0.0322, 0.9961]
⌚ Time: 786.0s
📊 MAE: 0.0296, MSE: 0.0016, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0178, -0.0437, -0.0056, 0.0039, -0.0032, 0.1077, 0.9944]
🎯 Predicted: [-0.0022, -0.0001, 0.0011, 0.0011, 0.0119, -0.0017, 0.9961]
⌚ Time: 778.3s
📊 MAE: 0.0285, MSE: 0.0021, Task Success: ✓

📸 Sample 64: traj33

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0192, -0.0059, 0.0047, -0.0001, -0.0050, 0.3399, 0.0703]

🎯 Predicted: [0.0038, 0.0022, -0.0093, 0.0120, 0.0341, 0.0032, 0.0000]
⌚ Time: 777.7s
📊 MAE: 0.0708, MSE: 0.0172, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [0.0136, -0.0060, 0.0068, -0.0044, 0.0022, 0.3344, 0.0589]
🎯 Predicted: [-0.0040, 0.0002, -0.0065, 0.0043, 0.0106, -0.0049, 0.0000]
⌚ Time: 774.4s
📊 MAE: 0.0646, MSE: 0.0170, Task Success: ✗

📸 Sample 65: traj50
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [0.0166, -0.0228, -0.0045, 0.0012, -0.0057, 0.7978, 0.9998]
🎯 Predicted: [-0.0040, 0.0012, 0.0003, -0.0065, 0.0287, 0.0048, 0.0000]
⌚ Time: 758.0s
📊 MAE: 0.2692, MSE: 0.2330, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [0.0107, -0.0244, -0.0012, 0.0118, 0.0031, 0.7839, 0.9986]
🎯 Predicted: [-0.0040, 0.0002, -0.0031, -0.0180, 0.0253, -0.0081, 0.0000]
⌚ Time: 762.5s
📊 MAE: 0.2691, MSE: 0.2324, Task Success: ✗

📸 Sample 66: traj57
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)

 Image 1: im_42.jpg
 Ground Truth: [0.0264, -0.0190, 0.0021, -0.0041, -0.0111, -0.9114, 0.9994]
 Predicted: [-0.0022, -0.0124, -0.0127, 0.0273, 0.0126, -0.0017, 0.0000]
 Time: 760.0s
 MAE: 0.2877, MSE: 0.2613, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0304, -0.0256, 0.0051, -0.0050, 0.0005, -0.8957, 0.9934]
 Predicted: [-0.0029, -0.0017, -0.0208, -0.0052, 0.0501, -0.0017, 0.0000]
 Time: 768.1s
 MAE: 0.2886, MSE: 0.2559, Task Success: X

Sample 67: traj32

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0063, -0.0177, -0.0048, 0.0095, 0.0050, 0.4186, 0.9958]
 Predicted: [-0.0074, -0.0338, -0.0047, -0.0212, 0.0227, -0.0855, 0.0000]
 Time: 773.1s
 MAE: 0.2255, MSE: 0.1782, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0138, -0.0165, 0.0127, -0.0032, -0.0015, 0.4093, 0.9924]
 Predicted: [0.0025, -0.0415, 0.0205, -0.0774, -0.0142, -0.0694, 0.0000]
 Time: 767.6s
 MAE: 0.2289, MSE: 0.1743, Task Success: X

Sample 68: traj35

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0183, -0.0492, 0.0096, -0.0032, 0.0070, -0.2891, 0.0623]
🎯 Predicted: [-0.0112, -0.0001, -0.0158, 0.0088, 0.0240, 0.0080, 0.9961]
 Time: 768.7s
 MAE: 0.1916, MSE: 0.1377, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0221, -0.0463, -0.0032, -0.0033, -0.0056, -0.2780, 0.0533]
🎯 Predicted: [-0.0112, 0.0061, 0.0395, 0.0088, -0.0745, 0.0273, 0.0000]
 Time: 784.5s
 MAE: 0.0780, MSE: 0.0151, Task Success: ✗

Sample 69: traj9

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [0.0008, -0.0514, -0.0009, -0.0043, 0.0079, 0.8169, 0.9926]
🎯 Predicted: [0.0043, -0.0053, -0.0075, -0.0084, 0.0126, -0.0162, 0.9961]
 Time: 755.3s
 MAE: 0.1288, MSE: 0.0995, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0126, -0.0368, -0.0027, 0.0004, 0.0006, 0.7859, 0.9936]
🎯 Predicted: [0.0047, -0.0024, -0.0171, 0.0082, 0.0133, 0.0112, 0.9961]
 Time: 775.6s
 MAE: 0.1234, MSE: 0.0860, Task Success: ✓

Sample 70: traj7

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [0.0015, 0.0362, -0.0059, -0.0009, 0.0141, -0.1929, 0.0691]
🎯 Predicted: [0.0087, 0.0086, 0.0120, -0.0110, -0.0115, 0.0209, 0.0000]
 Time: 767.1s
 MAE: 0.0530, MSE: 0.0075, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [0.0046, 0.0425, 0.0033, 0.0058, -0.0051, -0.1994, 0.0536]
🎯 Predicted: [0.0034, -0.0166, 0.0081, -0.0104, -0.0055, -0.0500, 0.0000]
 Time: 752.6s
 MAE: 0.0407, MSE: 0.0041, Task Success: ✗

Sample 71: traj0

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [0.0074, -0.0260, 0.0106, 0.0027, 0.0061, 0.5296, 0.9972]
🎯 Predicted: [-0.0051, -0.0075, -0.0028, 0.0005, 0.0052, -0.0178, 0.9961]
 Time: 747.2s
 MAE: 0.0852, MSE: 0.0429, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [0.0041, -0.0220, -0.0039, -0.0030, -0.0095, 0.5077, 1.0000]
🎯 Predicted: [-0.0076, -0.0169, -0.0099, 0.0126, 0.0320, -0.0629, 0.9961]
 Time: 746.2s
 MAE: 0.0935, MSE: 0.0468, Task Success: ✓

Sample 72: traj1

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0189, 0.0088, 0.0012, -0.0114, -0.0042, 0.7985, 1.0000]
 Predicted: [0.0090, -0.0072, 0.0034, -0.0333, -0.0222, -0.0613, 0.9961]
 Time: 762.7s
 MAE: 0.1331, MSE: 0.1058, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0125, 0.0171, 0.0005, -0.0037, 0.0001, 0.7889, 1.0000]
 Predicted: [0.0072, -0.0007, -0.0135, -0.0512, 0.0086, -0.0871, 0.9961]
 Time: 748.4s
 MAE: 0.1390, MSE: 0.1100, Task Success:

Sample 73: traj6

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0217, -0.0040, 0.0048, -0.0074, -0.0046, -0.1860, 0.0713]
 Predicted: [0.0081, 0.0038, -0.0062, 0.0184, -0.0303, -0.0275, 0.9961]
 Time: 763.1s
 MAE: 0.1691, MSE: 0.1261, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0169, -0.0046, 0.0005, 0.0010, 0.0002, -0.1784, 0.9950]
 Predicted: [0.0025, 0.0077, -0.0104, 0.0184, 0.0213, -0.0178, 0.9961]
 Time: 764.8s
 MAE: 0.0347, MSE: 0.0039, Task Success:

Sample 74: traj8

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_4.jpg

 Ground Truth: [-0.0031, -0.0066, -0.0025, 0.0016, 0.0079, 0.7095, 0.9991]

 Predicted: [0.0058, -0.0101, -0.0138, 0.0114, 0.0079, -0.0404, 0.9961]

 Time: 752.1s

 MAE: 0.1123, MSE: 0.0804, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_21.jpg

 Ground Truth: [0.0072, -0.0013, -0.0130, 0.0093, 0.0008, 0.6844, 0.9972]

 Predicted: [-0.0004, 0.0407, 0.0039, -0.0225, -0.0490, 0.0773, 0.0000]

 Time: 764.0s

 MAE: 0.2503, MSE: 0.1955, Task Success: 

Sample 75: traj17

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_4.jpg

 Ground Truth: [0.0190, 0.0132, -0.0007, -0.0024, 0.0073, 0.0287, 0.9882]

 Predicted: [-0.0074, -0.0040, 0.0068, -0.0046, -0.0256, -0.0178, 0.9961]

 Time: 744.1s

 MAE: 0.0201, MSE: 0.0006, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_5.jpg

 Ground Truth: [0.0110, 0.0101, 0.0022, 0.0050, 0.0055, 0.0266, 1.0000]

 Predicted: [-0.0109, 0.0132, -0.0109, 0.0171, 0.0408, -0.0194, 0.9961]

Time: 743.6s
 MAE: 0.0193, MSE: 0.0006, Task Success: ✓

Sample 76: traj28

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

✓ Ground Truth: [0.0257, -0.0207, -0.0004, -0.0019, 0.0022, 0.9419, 0.0574]

⌚ Predicted: [0.0130, -0.0059, -0.0140, 0.0075, 0.0347, -0.0242, 0.0000]

Time: 741.8s

MAE: 0.1581, MSE: 0.1341, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

✓ Ground Truth: [0.0323, -0.0105, 0.0062, -0.0013, -0.0023, 0.9300, 0.0651]

⌚ Predicted: [-0.0036, -0.0211, -0.0034, -0.0027, -0.0162, -0.0839, 0.0000]

Time: 760.7s

MAE: 0.1643, MSE: 0.1477, Task Success: ✗

Sample 77: traj10

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

✓ Ground Truth: [-0.0136, -0.0283, -0.0071, 0.0014, 0.0022, 0.0950, 0.0667]

⌚ Predicted: [-0.0022, -0.0001, -0.0156, 0.0037, 0.0428, -0.0033, 0.9961]

Time: 742.7s

MAE: 0.1598, MSE: 0.1252, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

✓ Ground Truth: [0.0002, -0.0274, -0.0009, 0.0076, 0.0024, 0.0933, 0.0625]
⌚ Predicted: [-0.0085, 0.0239, -0.0164, -0.0033, 0.0414, 0.0773, 0.9961]
⌚ Time: 735.2s
📊 MAE: 0.1536, MSE: 0.1252, Task Success: ✗

📸 Sample 78: traj26

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [-0.0225, -0.0185, 0.0077, -0.0110, 0.0009, -0.1887, 1.0000]
⌚ Predicted: [0.0025, 0.0028, 0.0221, -0.0027, -0.0517, -0.0371, 0.9961]
⌚ Time: 745.2s
📊 MAE: 0.0396, MSE: 0.0039, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0322, -0.0179, -0.0018, -0.0047, 0.0027, -0.1733, 1.0000]
⌚ Predicted: [-0.0076, 0.0005, -0.0140, 0.0056, 0.0361, -0.0081, 0.9961]
⌚ Time: 736.1s
📊 MAE: 0.0383, MSE: 0.0042, Task Success: ✓

📸 Sample 79: traj19

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0181, 0.0580, 0.0021, 0.0068, 0.0067, 0.4169, 0.9972]
⌚ Predicted: [-0.0130, 0.0057, -0.0182, -0.0014, 0.0253, -0.0001, 0.9961]
⌚ Time: 751.1s
📊 MAE: 0.0784, MSE: 0.0255, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)

Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0111, 0.0534, -0.0045, -0.0059, 0.0014, 0.3987, 1.0000]
 Predicted: [-0.0040, 0.0018, -0.0140, 0.0177, 0.0019, 0.0241, 0.9961]
 Time: 733.6s
 MAE: 0.0684, MSE: 0.0205, Task Success: 

Sample 80: traj21

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0135, 0.0075, 0.0071, -0.0071, -0.0046, -0.3619, 1.0000]
 Predicted: [-0.0266, -0.0173, -0.0184, -0.0806, 0.0119, -0.1322, 0.9961]
 Time: 740.4s
 MAE: 0.0553, MSE: 0.0086, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0122, 0.0045, 0.0070, 0.0046, 0.0029, -0.3488, 0.9973]
 Predicted: [-0.0112, -0.0266, -0.0171, 0.0280, 0.0260, -0.0291, 0.9961]
 Time: 740.2s
 MAE: 0.0606, MSE: 0.0150, Task Success: 

Sample 81: traj44

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0019, 0.0098, -0.0062, 0.0020, 0.0117, -0.7527, 1.0000]
 Predicted: [-0.0159, 0.0151, 0.0024, -0.0155, -0.0115, -0.0033, 0.9961]
 Time: 737.6s
 MAE: 0.1174, MSE: 0.0804, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0052, 0.0061, 0.0030, -0.0063, -0.0072, -0.7464, 0.9982]
 Predicted: [0.0027, -0.0017, -0.0065, -0.0212, -0.0242, -0.0017, 0.9961]
 Time: 740.7s
 MAE: 0.1141, MSE: 0.0793, Task Success:

Sample 82: traj43

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0165, 0.0289, -0.0082, -0.0031, 0.0014, -0.8326, 1.0000]
 Predicted: [-0.0076, -0.0037, -0.0075, -0.0129, 0.0046, -0.0936, 0.9961]
 Time: 745.8s
 MAE: 0.1140, MSE: 0.0782, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0303, 0.0255, -0.0009, -0.0069, -0.0064, -0.8181, 0.9998]
 Predicted: [-0.0069, -0.0001, -0.0106, 0.0126, -0.0195, -0.0597, 0.9961]
 Time: 741.1s
 MAE: 0.1219, MSE: 0.0824, Task Success:

Sample 83: traj20

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0130, 0.0098, -0.0030, 0.0052, 0.0017, 0.7200, 1.0000]
 Predicted: [-0.0022, -0.0001, -0.0052, -0.0040, 0.0066, -0.0033, 0.9961]
 Time: 736.1s
 MAE: 0.1098, MSE: 0.0748, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0081, 0.0154, -0.0070, 0.0020, 0.0063, 0.7152, 1.0000]
 Predicted: [-0.0022, -0.0001, -0.0127, -0.0040, 0.0374, -0.0017, 0.9961]
 Time: 743.0s
 MAE: 0.1128, MSE: 0.0736, Task Success:

Sample 84: traj27

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0036, 0.0347, -0.0028, -0.0018, 0.0040, -0.4906, 1.0000]
 Predicted: [-0.0042, -0.0066, 0.0057, -0.0180, -0.0015, -0.0049, 0.0000]
 Time: 747.6s
 MAE: 0.2236, MSE: 0.1769, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0007, 0.0364, 0.0065, 0.0007, 0.0040, -0.4696, 0.9994]
 Predicted: [-0.0040, 0.0407, -0.0065, 0.0458, 0.0200, 0.1305, 0.0000]
 Time: 734.8s
 MAE: 0.2402, MSE: 0.1945, Task Success:

Sample 85: traj18

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0338, 0.0363, 0.0008, 0.0013, 0.0029, -0.1069, 0.0624]
 Predicted: [0.0081, -0.0406, 0.0400, -0.0308, -0.0926, -0.0903, 0.0000]

⌚ Time: 747.0s
📊 MAE: 0.0498, MSE: 0.0032, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0195, 0.0386, 0.0038, -0.0018, -0.0002, -0.0952, 0.9923]
🎯 Predicted: [0.0000, 0.0015, 0.0000, 0.0050, -0.0021, 0.0112, 0.0000]
⌚ Time: 739.1s
📊 MAE: 0.1668, MSE: 0.1425, Task Success: ✗

📸 Sample 86: traj11
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0217, 0.0338, -0.0033, 0.0013, -0.0032, -0.0902, 1.0000]
🎯 Predicted: [-0.0031, 0.0002, -0.0169, -0.0187, 0.0401, 0.0128, 0.0000]
⌚ Time: 743.6s
📊 MAE: 0.1769, MSE: 0.1450, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0130, 0.0491, -0.0058, -0.0053, -0.0066, -0.0798, 0.9955]
🎯 Predicted: [-0.0029, -0.0001, -0.0156, 0.0050, 0.0434, -0.0033, 0.0000]
⌚ Time: 738.6s
📊 MAE: 0.1725, MSE: 0.1432, Task Success: ✗

📸 Sample 87: traj16
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg

✓ Ground Truth: [0.0350, 0.0499, -0.0075, -0.0025, -0.0041, 0.0836, 0.9917]

✗ Predicted: [0.0072, -0.0024, -0.0023, 0.0369, -0.0416, -0.0033, 0.0000]

⌚ Time: 748.0s

📊 MAE: 0.1773, MSE: 0.1425, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼 Image 2: im_43.jpg

✓ Ground Truth: [0.0336, 0.0423, -0.0007, -0.0042, -0.0064, 0.0845, 0.9956]

✗ Predicted: [0.0130, -0.0040, 0.0234, -0.0397, -0.0316, -0.0178, 0.0000]

⌚ Time: 735.7s

📊 MAE: 0.1785, MSE: 0.1438, Task Success: ✗

🎥 Sample 88: traj29

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼 Image 1: im_42.jpg

✓ Ground Truth: [-0.0239, -0.0238, -0.0101, 0.0015, -0.0048, 0.4317, 0.9986]

✗ Predicted: [-0.0179, -0.0173, -0.0028, -0.0244, 0.0012, -0.0790, 0.0000]

⌚ Time: 748.0s

📊 MAE: 0.2230, MSE: 0.1798, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼 Image 2: im_43.jpg

✓ Ground Truth: [-0.0258, -0.0149, -0.0090, 0.0026, -0.0003, 0.4131, 1.0000]

✗ Predicted: [-0.0262, -0.0121, -0.0031, -0.0436, 0.0213, -0.0113, 0.0000]

⌚ Time: 734.7s

📊 MAE: 0.2145, MSE: 0.1690, Task Success: ✗

🎥 Sample 89: traj42

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0011, -0.0112, -0.0310, 0.0005, 0.0012, -0.4201, 1.0000]

Predicted: [-0.0074, -0.0415, -0.0093, -0.0436, 0.0227, -0.0855, 0.0000]

Time: 747.4s

MAE: 0.2083, MSE: 0.1594, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0014, -0.0060, -0.0312, 0.0020, -0.0039, -0.4211, 0.9962]

Predicted: [0.0099, 0.0061, -0.0164, -0.0110, 0.0039, -0.0371, 0.0000]

Time: 734.5s

MAE: 0.2052, MSE: 0.1629, Task Success: ✗

📸 Sample 90: traj45

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0132, 0.0028, -0.0075, -0.0009, -0.0004, -0.3191, 1.0000]

Predicted: [0.0000, -0.0046, -0.0106, -0.0059, -0.0483, 0.0725, 0.9961]

Time: 760.0s

MAE: 0.0675, MSE: 0.0223, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0097, -0.0008, -0.0035, -0.0061, -0.0018, -0.3112, 1.0000]

Predicted: [0.0029, -0.0007, -0.0086, 0.0145, -0.0222, -0.0371, 0.9961]

Time: 737.5s

MAE: 0.0481, MSE: 0.0109, Task Success: ✓

📸 Sample 91: traj30

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0099, -0.0198, -0.0015, -0.0016, -0.0006, 0.8194, 0.9981]
 Predicted: [0.0014, 0.0005, -0.0002, -0.0014, -0.0081, 0.0048, 0.0000]
 Time: 769.5s
 MAE: 0.2648, MSE: 0.2372, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0158, -0.0174, 0.0064, -0.0004, 0.0027, 0.7942, 0.9934]
 Predicted: [0.0000, -0.0007, -0.0013, -0.0033, 0.0006, 0.0048, 0.9961]
 Time: 758.8s
 MAE: 0.1196, MSE: 0.0891, Task Success: 

Sample 92: traj37

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0222, 0.0411, 0.0012, 0.0036, -0.0051, -0.6084, 0.0634]
 Predicted: [0.0018, -0.0014, 0.0026, -0.0027, -0.0061, -0.0033, 0.0000]
 Time: 767.7s
 MAE: 0.1063, MSE: 0.0532, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0274, 0.0400, 0.0026, -0.0017, -0.0005, -0.6112, 0.0676]
 Predicted: [0.0025, 0.0009, -0.0093, -0.0059, -0.0068, -0.0065, 0.9961]
 Time: 756.8s
 MAE: 0.2321, MSE: 0.1758, Task Success: 

Sample 93: traj39

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0070, -0.0154, -0.0027, 0.0017, -0.0033, 0.6591, 0.0679]
 Predicted: [-0.0096, 0.0209, -0.0028, 0.0082, 0.0200, 0.0757, 0.0000]
 Time: 751.6s
 MAE: 0.1029, MSE: 0.0496, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0117, -0.0161, -0.0075, 0.0094, -0.0011, 0.6395, 1.0000]
 Predicted: [-0.0024, -0.0024, -0.0060, -0.0302, 0.0260, -0.0275, 0.0000]
 Time: 753.8s
 MAE: 0.2512, MSE: 0.2068, Task Success: ✗

Sample 94: traj38

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0051, 0.0194, 0.0086, 0.0033, 0.0008, -0.3087, 0.9937]
 Predicted: [-0.0121, -0.0415, -0.0041, -0.0187, 0.0039, -0.0855, 0.0000]
 Time: 750.8s
 MAE: 0.1889, MSE: 0.1488, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0123, 0.0087, 0.0021, -0.0064, -0.0017, -0.3007, 1.0000]
 Predicted: [-0.0121, -0.0266, -0.0015, 0.0018, 0.0233, -0.0001, 0.0000]
 Time: 781.1s
 MAE: 0.1962, MSE: 0.1560, Task Success: ✗

Sample 95: traj36

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0403, 0.0200, -0.0015, -0.0051, -0.0120, -0.3953, 0.9951]

Predicted: [-0.0009, -0.0114, -0.0036, 0.0114, 0.0073, -0.0242, 0.0000]

Time: 752.5s

MAE: 0.2107, MSE: 0.1616, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0389, 0.0142, -0.0079, -0.0010, 0.0048, -0.3959, 0.9958]

Predicted: [-0.0027, -0.0024, -0.0026, -0.0052, 0.0039, -0.0017, 0.9961]

Time: 787.1s

MAE: 0.0654, MSE: 0.0224, Task Success:

Sample 96: traj31

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0036, 0.0286, -0.0030, -0.0007, 0.0001, -0.9956, 0.9955]

Predicted: [-0.0116, -0.0040, 0.0161, 0.0126, 0.0066, -0.0533, 0.0000]

Time: 758.4s

MAE: 0.2882, MSE: 0.2687, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0032, 0.0290, -0.0104, 0.0057, 0.0027, -1.0000, 0.9975]

Predicted: [-0.0165, -0.0415, 0.0296, -0.0806, -0.0329, -0.0404, 0.0000]

Time: 783.7s

 MAE: 0.3147, MSE: 0.2759, Task Success: X

 Sample 97: traj3

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0087, 0.0614, 0.0072, 0.0003, 0.0006, -0.7127, 1.0000]

 Predicted: [-0.0071, 0.0083, -0.0112, 0.0171, 0.0468, 0.0338, 0.9961]

 Time: 782.0s

 MAE: 0.1287, MSE: 0.0804, Task Success: X

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0044, 0.0531, -0.0090, -0.0061, -0.0028, -0.6795, 0.9951]

 Predicted: [-0.0156, 0.0083, -0.0151, -0.0231, 0.0501, -0.0307, 0.0000]

 Time: 768.9s

 MAE: 0.2549, MSE: 0.2024, Task Success: X

 Sample 98: traj4

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0065, -0.0167, -0.0081, -0.0038, -0.0098, 0.8609, 1.0000]

 Predicted: [-0.0027, -0.0208, 0.0208, -0.0321, -0.0926, -0.0404, 0.0000]

 Time: 791.8s

 MAE: 0.2935, MSE: 0.2601, Task Success: X

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0007, -0.0127, 0.0080, 0.0006, 0.0057, 0.8397, 1.0000]

🎯 Predicted: [0.0000, -0.0351, 0.0400, -0.0308, -0.0926, -0.0113, 0.0000]
⌚ Time: 786.3s
📊 MAE: 0.2908, MSE: 0.2481, Task Success: ✗

📸 Sample 99: traj5

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0383, -0.0249, 0.0087, 0.0038, 0.0064, 0.3135, 0.0699]
🎯 Predicted: [-0.0047, 0.0268, -0.0091, 0.0356, 0.0046, -0.0597, 0.9961]
⌚ Time: 769.3s
📊 MAE: 0.2052, MSE: 0.1432, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0321, -0.0098, -0.0041, -0.0058, 0.0033, 0.2915, 0.0632]
🎯 Predicted: [0.0007, 0.0015, -0.0005, -0.0167, -0.0081, 0.0161, 0.9961]
⌚ Time: 765.0s
📊 MAE: 0.1826, MSE: 0.1354, Task Success: ✗

📸 Sample 100: traj2

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [0.0142, -0.0164, -0.0017, -0.0016, 0.0057, 0.8185, 0.9995]
🎯 Predicted: [0.0000, -0.0234, 0.0400, 0.0299, -0.0926, -0.0952, 0.0000]
⌚ Time: 752.2s
📊 MAE: 0.3008, MSE: 0.2638, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)

 Image 2: im_43.jpg
 Ground Truth: [0.0094, -0.0091, 0.0075, -0.0014, -0.0040, 0.7870, 0.9969]
 Predicted: [-0.0172, 0.0073, -0.0002, 0.0114, -0.0329, 0.0273, 0.9961]
 Time: 745.9s
 MAE: 0.1219, MSE: 0.0827, Task Success: 

Sample 101: traj40

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0047, -0.0002, -0.0355, -0.0133, 0.0005, 0.1299, 0.9995]

 Predicted: [0.0000, 0.0070, -0.0065, -0.0059, -0.0035, 0.0177, 0.0000]

 Time: 751.0s

 MAE: 0.1663, MSE: 0.1447, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0066, -0.0008, -0.0200, -0.0031, -0.0017, 0.1141, 0.9947]

 Predicted: [-0.0147, -0.0075, -0.0088, -0.0333, 0.0361, -0.0404, 0.0000]

 Time: 752.7s

 MAE: 0.1795, MSE: 0.1452, Task Success: 

Sample 102: traj13

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0255, 0.0281, -0.0069, -0.0095, 0.0018, 0.7666, 1.0000]

 Predicted: [0.0110, -0.0056, -0.0104, 0.0145, -0.0175, -0.0871, 0.0000]

 Time: 759.3s

 MAE: 0.2784, MSE: 0.2473, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0196, 0.0140, -0.0063, -0.0069, -0.0002, 0.7660, 0.9975]
 Predicted: [0.0096, -0.0399, 0.0115, -0.0193, -0.0323, 0.0032, 0.0000]
 Time: 733.7s
 MAE: 0.2695, MSE: 0.2259, Task Success: 

Sample 103: traj14

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_4.jpg
 Ground Truth: [-0.0046, 0.0777, -0.0021, 0.0046, -0.0013, -0.9884, 0.9978]
 Predicted: [0.0163, 0.0258, -0.0002, -0.0219, 0.0173, 0.1289, 0.9961]
 Time: 761.9s
 MAE: 0.1770, MSE: 0.1789, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_21.jpg
 Ground Truth: [-0.0004, 0.0793, -0.0018, 0.0066, -0.0086, -0.9729, 0.9974]
 Predicted: [-0.0031, -0.0027, 0.0008, -0.0353, -0.0182, 0.0015, 0.0000]
 Time: 757.9s
 MAE: 0.3015, MSE: 0.2790, Task Success: 

Sample 104: traj22

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0032, 0.0422, -0.0048, 0.0087, -0.0066, 0.7900, 0.9935]
 Predicted: [-0.0004, -0.0001, 0.0013, -0.0021, -0.0028, -0.0001, 0.9961]
 Time: 786.5s
 MAE: 0.1228, MSE: 0.0895, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0115, 0.0349, -0.0056, 0.0111, 0.0051, 0.7794, 0.9953]
 Predicted: [-0.0004, 0.0358, -0.0005, -0.0474, -0.0309, 0.1063, 0.0000]
 Time: 804.4s
 MAE: 0.2543, MSE: 0.2069, Task Success:

Sample 105: traj25

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0094, 0.0140, 0.0013, 0.0103, 0.0020, 0.6655, 1.0000]
 Predicted: [-0.0031, -0.0001, -0.0034, -0.0014, 0.0093, 0.0015, 0.9961]
 Time: 805.1s
 MAE: 0.1017, MSE: 0.0630, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0108, 0.0180, 0.0066, 0.0036, 0.0004, 0.6391, 0.9982]
 Predicted: [0.0014, 0.0064, 0.0380, -0.0244, -0.0899, 0.0144, 0.0000]
 Time: 782.2s
 MAE: 0.2566, MSE: 0.1995, Task Success:

Sample 106: traj41

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0084, -0.0021, 0.0010, -0.0030, -0.0011, -0.2090, 1.0000]
 Predicted: [0.0002, 0.0174, 0.0120, -0.0199, 0.0026, 0.0354, 0.0000]
 Time: 777.7s

📊 MAE: 0.1862, MSE: 0.1515, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0126, -0.0035, -0.0015, 0.0043, 0.0017, -0.2066, 0.9993]
🎯 Predicted: [-0.0143, 0.0138, 0.0400, 0.0222, -0.0926, 0.0418, 0.0000]
⌚ Time: 758.8s
📊 MAE: 0.2065, MSE: 0.1532, Task Success: ✗

📸 Sample 107: traj24
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0057, 0.0004, -0.0356, -0.0000, 0.0010, -0.5747, 0.9915]
🎯 Predicted: [0.0105, 0.0187, -0.0210, -0.0110, -0.0222, 0.0467, 0.0000]
⌚ Time: 740.7s
📊 MAE: 0.2407, MSE: 0.1958, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0005, 0.0028, -0.0306, -0.0004, -0.0014, -0.5764, 0.9985]
🎯 Predicted: [0.0085, 0.0051, -0.0065, 0.0382, -0.0577, -0.0049, 0.0000]
⌚ Time: 743.2s
📊 MAE: 0.2429, MSE: 0.1898, Task Success: ✗

📸 Sample 108: traj23
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_4.jpg
✓ Ground Truth: [0.0401, 0.0154, 0.0087, 0.0063, -0.0019, -0.1788, 0.9924]

🎯 Predicted: [0.0058, 0.0080, -0.0189, 0.0139, -0.0075, 0.0580, 0.9961]
⌚ Time: 766.0s
📊 MAE: 0.0461, MSE: 0.0083, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_20.jpg
✓ Ground Truth: [0.0363, 0.0017, -0.0127, 0.0090, -0.0012, -0.1624, 1.0000]
🎯 Predicted: [0.0000, -0.0040, 0.0005, -0.0104, -0.0015, -0.0033, 0.0000]
⌚ Time: 770.3s
📊 MAE: 0.1763, MSE: 0.1467, Task Success: ✗

📸 Sample 109: traj15
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0404, 0.0031, -0.0062, -0.0007, -0.0078, -0.4171, 0.0709]
🎯 Predicted: [-0.0174, 0.0345, 0.0068, 0.0318, -0.0765, -0.0597, 0.9961]
⌚ Time: 770.6s
📊 MAE: 0.2073, MSE: 0.1416, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0296, -0.0087, 0.0035, -0.0019, 0.0045, -0.4136, 0.9978]
🎯 Predicted: [-0.0051, -0.0075, -0.0028, 0.0005, -0.0081, -0.0097, 0.9961]
⌚ Time: 775.0s
📊 MAE: 0.0647, MSE: 0.0234, Task Success: ✓

📸 Sample 110: traj12
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)

 Image 1: im_42.jpg
 Ground Truth: [-0.0101, -0.0074, 0.0059, 0.0029, -0.0051, -0.8681, 0.0769]
 Predicted: [-0.0165, 0.0054, -0.0031, -0.0314, -0.0926, 0.0531, 0.9961]
 Time: 799.3s
 MAE: 0.2843, MSE: 0.2432, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0133, 0.0032, 0.0058, 0.0009, -0.0006, -0.8585, 0.0620]
 Predicted: [-0.0092, 0.0187, -0.0109, 0.0248, 0.0026, 0.1015, 0.9961]
 Time: 777.7s
 MAE: 0.2796, MSE: 0.2564, Task Success: X

 Sample 111: traj34
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0023, 0.0319, -0.0062, 0.0043, 0.0012, 0.6655, 0.0654]
 Predicted: [0.0018, 0.0116, -0.0065, 0.0624, -0.0055, 0.0177, 0.0000]
 Time: 779.0s
 MAE: 0.1142, MSE: 0.0611, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0000, 0.0295, 0.0090, -0.0113, -0.0021, 0.6583, 0.0603]
 Predicted: [-0.0147, -0.0415, -0.0026, -0.0512, 0.0314, -0.0855, 0.0000]
 Time: 4563.2s
 MAE: 0.1393, MSE: 0.0807, Task Success: X

 Sample 112: traj33
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0032, 0.0277, 0.0042, -0.0007, 0.0049, -0.0732, 1.0000]
 Predicted: [-0.0190, -0.0241, -0.0114, -0.0110, -0.0209, -0.0162, 0.9961]
 Time: 739.9s
 MAE: 0.0267, MSE: 0.0011, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0113, 0.0310, 0.0072, 0.0043, -0.0005, -0.0671, 1.0000]
 Predicted: [-0.0051, 0.0119, -0.0075, 0.0139, -0.0001, 0.0032, 0.9961]
 Time: 753.1s
 MAE: 0.0178, MSE: 0.0008, Task Success: 

Sample 113: traj32

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0188, -0.0242, -0.0015, 0.0002, 0.0009, 0.7327, 1.0000]
 Predicted: [-0.0016, -0.0004, -0.0013, -0.0167, 0.0046, -0.0210, 0.0000]
 Time: 736.5s
 MAE: 0.2598, MSE: 0.2242, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0130, -0.0213, -0.0018, -0.0069, -0.0052, 0.7052, 1.0000]
 Predicted: [-0.0033, 0.0009, 0.0089, -0.0084, -0.0269, 0.0096, 0.0000]
 Time: 728.3s
 MAE: 0.2526, MSE: 0.2122, Task Success: 

Sample 114: traj35

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0002, -0.0106, -0.0162, 0.0090, 0.0003, 0.1612, 0.9982]
 Predicted: [0.0108, 0.0261, 0.0400, -0.0199, -0.0926, 0.0644, 0.9961]
 Time: 737.1s
 MAE: 0.0463, MSE: 0.0033, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0193, -0.0240, -0.0012, 0.0071, -0.0141, 0.1347, 1.0000]
 Predicted: [0.0101, -0.0033, -0.0127, -0.0263, -0.0329, -0.0017, 0.9961]
 Time: 833.4s
 MAE: 0.0334, MSE: 0.0030, Task Success:

Sample 115: traj9

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0039, 0.0356, -0.0001, 0.0014, -0.0005, -0.4233, 1.0000]
 Predicted: [0.0065, -0.0050, 0.0400, 0.0145, -0.0926, -0.0436, 0.9961]
 Time: 743.2s
 MAE: 0.0828, MSE: 0.0223, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0075, 0.0382, 0.0058, -0.0003, -0.0011, -0.4171, 0.9981]
 Predicted: [0.0081, -0.0111, 0.0086, -0.0167, -0.0872, -0.0130, 0.9961]
 Time: 759.1s
 MAE: 0.0802, MSE: 0.0248, Task Success:

📸 Sample 116: traj7

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_4.jpg

✓ Ground Truth: [0.0033, 0.0464, 0.0033, -0.0007, -0.0075, 0.2861, 1.0000]

🎯 Predicted: [-0.0027, -0.0169, 0.0029, 0.0126, -0.0209, -0.0178, 0.9961]

⌚ Time: 764.1s

📊 MAE: 0.0578, MSE: 0.0138, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_5.jpg

✓ Ground Truth: [-0.0054, 0.0395, 0.0040, -0.0014, 0.0039, 0.2689, 0.9985]

🎯 Predicted: [-0.0040, 0.0193, 0.0013, -0.0040, -0.0108, 0.0499, 0.9961]

⌚ Time: 753.4s

📊 MAE: 0.0376, MSE: 0.0069, Task Success: ✓

📸 Sample 117: traj0

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [-0.0074, 0.0469, -0.0069, -0.0012, -0.0063, 0.3752, 1.0000]

🎯 Predicted: [0.0108, 0.0148, -0.0117, 0.0018, 0.0213, 0.0161, 0.0000]

⌚ Time: 759.1s

📊 MAE: 0.2064, MSE: 0.1616, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [-0.0050, 0.0466, 0.0027, -0.0037, -0.0081, 0.3725, 1.0000]

🎯 Predicted: [0.0108, 0.0148, -0.0117, 0.0133, -0.0055, -0.0081, 0.0000]

Time: 799.7s
 MAE: 0.2089, MSE: 0.1638, Task Success: X

Sample 118: traj1

Instruction: pick up the object and place it in the bowl

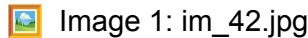
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0045, 0.0030, -0.0146, -0.0058, 0.0052, 0.4587, 0.0714]

⌚ Predicted: [-0.0051, 0.0407, -0.0114, 0.0120, 0.0019, 0.0322, 0.9961]

Time: 790.8s

MAE: 0.2020, MSE: 0.1484, Task Success: X

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0021, 0.0007, -0.0278, 0.0091, -0.0012, 0.4425, 0.0692]

⌚ Predicted: [0.0134, 0.0164, -0.0138, 0.0082, -0.0530, -0.0565, 0.9961]

Time: 798.6s

MAE: 0.2177, MSE: 0.1588, Task Success: X

Sample 119: traj6

Instruction: pick up the object and place it in the bowl

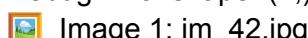
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0075, 0.0455, -0.0109, -0.0068, -0.0033, 0.7839, 0.9983]

⌚ Predicted: [-0.0027, -0.0266, 0.0029, -0.0448, 0.0260, -0.0420, 0.0000]

Time: 778.9s

MAE: 0.2832, MSE: 0.2409, Task Success: X

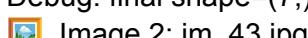
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0015, 0.0485, -0.0013, 0.0038, 0.0005, 0.7683, 1.0000]
🎯 Predicted: [0.0116, -0.0415, 0.0109, -0.0244, 0.0166, -0.0694, 0.0000]
⌚ Time: 782.7s
📊 MAE: 0.2854, MSE: 0.2445, Task Success: ✗

📸 Sample 120: traj8

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0281, -0.0650, -0.0046, -0.0057, 0.0087, -0.9102, 0.0721]
🎯 Predicted: [-0.0087, 0.0054, 0.0380, -0.0231, -0.0704, 0.0144, 0.0000]
⌚ Time: 803.9s
📊 MAE: 0.1751, MSE: 0.1248, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0310, -0.0615, -0.0017, 0.0061, 0.0005, -0.9109, 0.0610]
🎯 Predicted: [-0.0040, 0.0038, -0.0036, 0.0088, 0.0073, 0.0048, 0.0000]
⌚ Time: 789.0s
📊 MAE: 0.1543, MSE: 0.1210, Task Success: ✗

📸 Sample 121: traj17

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [0.0005, 0.0619, -0.0019, 0.0016, -0.0023, 0.7362, 1.0000]
🎯 Predicted: [0.0034, -0.0108, 0.0187, -0.0327, -0.0383, -0.0323, 0.0000]
⌚ Time: 808.6s
📊 MAE: 0.2764, MSE: 0.2284, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)

Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [-0.0027, 0.0545, 0.0107, 0.0014, 0.0039, 0.7231, 0.9984]
Predicted: [0.0038, -0.0105, 0.0177, -0.0327, -0.0383, -0.0404, 0.0000]
Time: 814.5s
MAE: 0.2738, MSE: 0.2267, Task Success: ✗

📸 Sample 122: traj28

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [0.0016, -0.0179, -0.0016, 0.0005, -0.0009, -0.4513, 1.0000]
Predicted: [0.0081, 0.0038, 0.0312, -0.0097, -0.0812, 0.0064, 0.0000]
Time: 787.4s
MAE: 0.2299, MSE: 0.1739, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [-0.0017, -0.0118, -0.0033, 0.0072, 0.0062, -0.4469, 1.0000]
Predicted: [-0.0009, -0.0037, -0.0018, 0.0018, 0.0039, -0.0001, 0.9961]
Time: 823.6s
MAE: 0.0670, MSE: 0.0285, Task Success: ✓

📸 Sample 123: traj10

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [-0.0038, 0.0567, -0.0019, -0.0005, -0.0001, -0.9385, 1.0000]
Predicted: [0.0186, -0.0234, 0.0400, -0.0685, -0.0926, -0.0436, 0.0000]
Time: 791.1s
MAE: 0.3143, MSE: 0.2604, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0078, 0.0663, -0.0051, 0.0042, 0.0047, -0.9140, 0.9927]
 Predicted: [0.0045, -0.0153, 0.0073, -0.0423, -0.0309, -0.0533, 0.0000]
 Time: 806.3s
 MAE: 0.2917, MSE: 0.2481, Task Success: 

Sample 124: traj26

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0109, -0.0551, 0.0045, -0.0077, 0.0008, 0.1297, 1.0000]
 Predicted: [0.0184, -0.0014, -0.0127, 0.0369, -0.0437, -0.0226, 0.9961]
 Time: 802.1s
 MAE: 0.0493, MSE: 0.0045, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0017, -0.0415, -0.0029, -0.0036, 0.0046, 0.1085, 0.9983]
 Predicted: [-0.0009, -0.0007, -0.0008, -0.0027, 0.0046, -0.0097, 0.9961]
 Time: 767.3s
 MAE: 0.0236, MSE: 0.0022, Task Success: 

Sample 125: traj19

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0056, -0.0019, -0.0244, 0.0046, -0.0052, 0.5748, 0.9994]
 Predicted: [0.0219, 0.0080, -0.0166, 0.0465, -0.0463, -0.0597, 0.9961]
 Time: 756.0s
 MAE: 0.1095, MSE: 0.0581, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0008, 0.0018, -0.0155, 0.0024, -0.0003, 0.5572, 0.9984]
 Predicted: [0.0242, -0.0011, -0.0065, 0.0114, -0.0142, -0.2064, 0.9961]
 Time: 766.6s
 MAE: 0.1180, MSE: 0.0834, Task Success:

Sample 126: traj21

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0032, -0.0368, -0.0027, -0.0103, 0.0088, 0.5700, 1.0000]
 Predicted: [0.0047, 0.0018, 0.0042, 0.0120, -0.0296, -0.0017, 0.9961]
 Time: 767.1s
 MAE: 0.0976, MSE: 0.0472, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0000, -0.0394, 0.0022, 0.0027, -0.0007, 0.5539, 0.9986]
 Predicted: [-0.0031, -0.0150, 0.0140, -0.0423, -0.0926, 0.0322, 0.0000]
 Time: 769.8s
 MAE: 0.2424, MSE: 0.1829, Task Success:

Sample 127: traj20

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0235, 0.0527, -0.0023, -0.0013, -0.0115, 0.6326, 0.9923]
 Predicted: [0.0081, 0.0002, 0.0213, -0.0001, -0.0289, -0.0307, 0.0000]

⌚ Time: 775.9s
📊 MAE: 0.2545, MSE: 0.2042, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0185, 0.0566, 0.0014, 0.0003, -0.0092, 0.6266, 0.9977]
🎯 Predicted: [-0.0007, -0.0059, 0.0354, -0.0257, -0.0497, -0.0291, 0.0000]
⌚ Time: 765.1s
📊 MAE: 0.2620, MSE: 0.2047, Task Success: ✗

📸 Sample 128: traj27
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0106, -0.0096, -0.0005, -0.0036, 0.0036, 0.7280, 0.9975]
🎯 Predicted: [0.0034, -0.0241, 0.0377, -0.0052, -0.0926, 0.0241, 0.0000]
⌚ Time: 790.0s
📊 MAE: 0.2656, MSE: 0.2145, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0007, -0.0215, 0.0001, 0.0013, 0.0151, 0.7139, 1.0000]
🎯 Predicted: [0.0034, -0.0250, 0.0257, -0.0308, -0.0905, -0.0404, 0.0000]
⌚ Time: 784.9s
📊 MAE: 0.2750, MSE: 0.2260, Task Success: ✗

📸 Sample 129: traj18
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg

✓ Ground Truth: [-0.0291, 0.0704, 0.0051, -0.0008, -0.0079, -0.0024, 0.0595]

🎯 Predicted: [-0.0018, 0.0061, 0.0031, 0.0318, 0.0126, -0.0130, 0.0000]

⌚ Time: 769.5s

📊 MAE: 0.0310, MSE: 0.0014, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [-0.0241, 0.0680, 0.0061, 0.0067, 0.0027, -0.0002, 0.0583]

🎯 Predicted: [0.0000, -0.0108, 0.0005, -0.0531, 0.0113, -0.0113, 0.0000]

⌚ Time: 745.3s

📊 MAE: 0.0352, MSE: 0.0020, Task Success: ✗

📸 Sample 130: traj11

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [-0.0446, 0.0315, -0.0039, 0.0081, -0.0051, -0.2843, 1.0000]

🎯 Predicted: [0.0139, 0.0226, -0.0189, 0.0126, 0.0113, 0.0096, 0.0000]

⌚ Time: 760.7s

📊 MAE: 0.1996, MSE: 0.1558, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [-0.0415, 0.0358, -0.0077, 0.0067, -0.0023, -0.2704, 1.0000]

🎯 Predicted: [0.0139, 0.0226, -0.0182, 0.0126, -0.0316, 0.0338, 0.0000]

⌚ Time: 759.2s

📊 MAE: 0.2026, MSE: 0.1567, Task Success: ✗

📸 Sample 131: traj16

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_4.jpg

Ground Truth: [0.0215, 0.0431, -0.0092, 0.0073, 0.0047, -0.1053, 0.0652]

Predicted: [-0.0156, -0.0059, -0.0023, -0.0193, 0.0026, 0.0676, 0.0000]

Time: 748.1s

MAE: 0.0514, MSE: 0.0055, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_5.jpg

Ground Truth: [0.0158, 0.0443, 0.0053, 0.0036, -0.0036, -0.0883, 0.0617]

Predicted: [-0.0078, -0.0101, 0.0380, 0.0075, -0.0805, 0.0483, 0.0000]

Time: 765.2s

MAE: 0.0557, MSE: 0.0047, Task Success: ✗

📸 Sample 132: traj29

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [0.0148, 0.0395, 0.0033, 0.0026, -0.0029, -0.1020, 0.0707]

Predicted: [-0.0020, 0.0125, 0.0060, 0.0171, -0.0148, 0.0515, 0.9961]

Time: 745.6s

MAE: 0.1646, MSE: 0.1259, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0218, 0.0221, -0.0040, -0.0076, -0.0057, -0.0911, 0.0678]

Predicted: [0.0000, 0.0067, -0.0062, -0.0365, -0.0035, 0.0467, 0.9961]

Time: 756.5s

MAE: 0.1624, MSE: 0.1260, Task Success: ✗

📸 Sample 133: traj30

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_4.jpg
 Ground Truth: [0.0300, 0.0439, -0.0024, 0.0035, -0.0065, 0.1076, 1.0000]
 Predicted: [-0.0074, 0.0180, 0.0011, 0.0114, -0.0115, 0.0144, 0.9961]
 Time: 746.5s
 MAE: 0.0252, MSE: 0.0016, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_5.jpg
 Ground Truth: [0.0334, 0.0434, 0.0080, -0.0045, 0.0018, 0.0951, 1.0000]
 Predicted: [0.0168, 0.0316, 0.0013, -0.0014, -0.0845, 0.0112, 0.9961]
 Time: 750.5s
 MAE: 0.0303, MSE: 0.0021, Task Success: 

Sample 134: traj37

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_4.jpg
 Ground Truth: [0.0255, 0.0136, 0.0034, -0.0030, 0.0062, 0.9728, 0.9847]
 Predicted: [0.0014, -0.0263, 0.0042, 0.0126, -0.0416, -0.1903, 0.9961]
 Time: 740.3s
 MAE: 0.1861, MSE: 0.1939, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_21.jpg
 Ground Truth: [0.0318, 0.0010, 0.0082, -0.0035, 0.0031, 0.9652, 0.9949]
 Predicted: [-0.0087, -0.0053, 0.0052, -0.0206, 0.0173, -0.0581, 0.0000]
 Time: 750.6s
 MAE: 0.2999, MSE: 0.2913, Task Success: 

Sample 135: traj39

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_4.jpg
 Ground Truth: [0.0308, 0.0771, 0.0059, 0.0036, 0.0028, 0.0656, 0.9934]
 Predicted: [-0.0217, -0.0186, -0.0138, 0.0177, 0.0260, -0.0049, 0.9961]
 Time: 742.5s
 MAE: 0.0398, MSE: 0.0026, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_21.jpg
 Ground Truth: [0.0285, 0.0722, -0.0053, -0.0087, 0.0029, 0.0646, 0.9994]
 Predicted: [-0.0096, -0.0085, 0.0239, -0.0321, -0.0296, 0.0289, 0.0000]
 Time: 744.0s
 MAE: 0.1770, MSE: 0.1444, Task Success: ✗

Sample 136: traj52

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0360, 0.0219, 0.0064, 0.0002, -0.0070, -0.2078, 1.0000]
 Predicted: [0.0038, 0.0022, -0.0028, 0.0120, -0.0048, 0.0064, 0.9961]
 Time: 751.4s
 MAE: 0.0419, MSE: 0.0068, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0311, 0.0233, 0.0050, 0.0010, 0.0021, -0.1960, 1.0000]
 Predicted: [-0.0011, -0.0082, -0.0161, 0.0299, -0.0236, -0.0242, 0.9961]
 Time: 743.5s
 MAE: 0.0450, MSE: 0.0048, Task Success: ✓

📸 Sample 137: traj55

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [-0.0067, -0.0462, 0.0005, 0.0012, -0.0076, 0.0167, 0.9960]

🎯 Predicted: [-0.0011, -0.0033, -0.0028, 0.0075, 0.0039, 0.0402, 0.9961]

⌚ Time: 753.2s

📊 MAE: 0.0133, MSE: 0.0004, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [-0.0132, -0.0407, 0.0014, 0.0030, -0.0083, 0.0066, 0.9969]

🎯 Predicted: [-0.0022, -0.0004, -0.0070, -0.0065, -0.0222, -0.0017, 0.0000]

⌚ Time: 751.4s

📊 MAE: 0.1554, MSE: 0.1423, Task Success: ✗

📸 Sample 138: traj63

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [0.0034, 0.0249, 0.0027, -0.0028, 0.0005, 0.5758, 0.0594]

🎯 Predicted: [-0.0056, -0.0017, 0.0140, -0.0404, -0.0262, -0.0017, 0.0000]

⌚ Time: 738.2s

📊 MAE: 0.1069, MSE: 0.0486, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [0.0060, 0.0330, -0.0029, -0.0031, 0.0063, 0.5573, 0.0638]

🎯 Predicted: [0.0043, -0.0007, 0.0179, 0.0312, -0.0390, -0.0323, 0.0000]

⌚ Time: 743.7s

📊 MAE: 0.1127, MSE: 0.0509, Task Success: ✗

📸 Sample 139: traj64

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [-0.0187, 0.0432, 0.0055, 0.0005, -0.0003, 0.3867, 1.0000]

🎯 Predicted: [-0.0038, 0.0035, 0.0018, -0.0033, -0.0008, -0.0162, 0.9961]

⌚ Time: 750.1s

📊 MAE: 0.0671, MSE: 0.0234, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [-0.0220, 0.0527, 0.0101, 0.0062, 0.0046, 0.3789, 1.0000]

🎯 Predicted: [0.0083, -0.0098, 0.0400, -0.0295, -0.0926, 0.0096, 0.0000]

⌚ Time: 750.6s

📊 MAE: 0.2321, MSE: 0.1647, Task Success: ✗

📸 Sample 140: traj38

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [-0.0190, -0.0122, 0.0101, 0.0082, 0.0018, -0.9899, 0.9955]

🎯 Predicted: [-0.0136, -0.0150, -0.0171, -0.0129, 0.0253, 0.0177, 0.9961]

⌚ Time: 750.3s

📊 MAE: 0.1554, MSE: 0.1453, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [-0.0234, -0.0103, 0.0070, 0.0006, 0.0018, -0.9776, 0.9932]

🎯 Predicted: [-0.0208, -0.0266, 0.0024, 0.0337, -0.0926, -0.1419, 0.9961]
⌚ Time: 756.9s
📊 MAE: 0.1414, MSE: 0.1012, Task Success: ✓

📸 Sample 141: traj36

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0143, 0.0123, -0.0000, 0.0046, 0.0028, -0.8065, 1.0000]

🎯 Predicted: [0.0049, 0.0138, 0.0400, 0.0318, -0.0825, 0.0257, 0.0000]

⌚ Time: 746.7s

📊 MAE: 0.2851, MSE: 0.2432, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [0.0055, 0.0053, -0.0013, 0.0030, 0.0022, -0.7904, 0.9964]

🎯 Predicted: [0.0193, 0.0141, 0.0400, -0.0155, -0.0926, 0.0338, 0.0000]

⌚ Time: 747.0s

📊 MAE: 0.2854, MSE: 0.2405, Task Success: ✗

📸 Sample 142: traj31

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [-0.0186, -0.0109, 0.0038, 0.0054, 0.0009, 0.9343, 1.0000]

🎯 Predicted: [-0.0062, -0.0024, 0.0024, 0.0114, -0.0289, 0.0370, 0.9961]

⌚ Time: 749.4s

📊 MAE: 0.1370, MSE: 0.1152, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg
 Ground Truth: [-0.0236, -0.0151, -0.0015, -0.0058, -0.0029, 0.9203, 1.0000]
 Predicted: [-0.0098, -0.0063, 0.0055, 0.0446, -0.0336, 0.0370, 0.9961]
 Time: 771.9s
 MAE: 0.1425, MSE: 0.1120, Task Success: 

 Sample 143: traj65
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0006, -0.0028, -0.0241, 0.0011, -0.0012, 0.1397, 1.0000]
 Predicted: [-0.0033, -0.0001, -0.0023, 0.0011, 0.0106, -0.0049, 0.9961]
 Time: 756.3s
 MAE: 0.0268, MSE: 0.0031, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0037, 0.0069, -0.0163, 0.0066, -0.0056, 0.1336, 1.0000]
 Predicted: [0.0000, -0.0014, -0.0179, 0.0145, 0.0006, 0.0177, 0.9961]
 Time: 740.6s
 MAE: 0.0211, MSE: 0.0019, Task Success: 

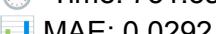
 Sample 144: traj62
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0196, 0.0270, -0.0032, 0.0026, 0.0067, 0.9376, 0.0699]
 Predicted: [-0.0011, 0.0044, -0.0189, 0.0318, -0.0242, -0.0404, 0.0000]
 Time: 755.1s
 MAE: 0.1664, MSE: 0.1377, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0183, 0.0267, 0.0018, 0.0066, 0.0002, 0.9202, 0.0595]
 Predicted: [-0.0011, -0.0024, -0.0008, -0.0001, 0.0046, -0.0162, 0.9961]
 Time: 764.2s
 MAE: 0.2761, MSE: 0.2508, Task Success: 

Sample 145: traj54

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0259, 0.0090, 0.0010, -0.0067, 0.0027, -0.1757, 0.9987]
 Predicted: [-0.0020, -0.0014, -0.0018, 0.0018, 0.0093, -0.0097, 0.0000]
 Time: 752.9s
 MAE: 0.1744, MSE: 0.1466, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0208, 0.0096, 0.0021, 0.0032, 0.0021, -0.1675, 1.0000]
 Predicted: [-0.0183, -0.0415, 0.0052, -0.0423, -0.0081, -0.0549, 0.0000]
 Time: 739.9s
 MAE: 0.1802, MSE: 0.1456, Task Success: 

Sample 146: traj53

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0164, -0.0031, -0.0044, -0.0003, -0.0051, -0.0336, 0.9940]
 Predicted: [-0.0143, 0.0151, 0.0086, -0.0110, -0.0524, 0.0773, 0.9961]
 Time: 751.5s
 MAE: 0.0292, MSE: 0.0022, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0252, -0.0117, -0.0039, 0.0005, -0.0037, -0.0383, 1.0000]
 Predicted: [-0.0016, 0.0028, -0.0078, 0.0062, 0.0287, 0.0193, 0.9961]
 Time: 754.6s
 MAE: 0.0202, MSE: 0.0007, Task Success:

Sample 147: traj3

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0222, 0.0241, -0.0001, -0.0019, 0.0010, -0.5309, 0.9942]
 Predicted: [0.0025, -0.0088, -0.0067, -0.0206, 0.0052, -0.0242, 0.0000]
 Time: 761.5s
 MAE: 0.2269, MSE: 0.1782, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0180, 0.0127, 0.0028, -0.0054, -0.0049, -0.5261, 1.0000]
 Predicted: [-0.0152, -0.0312, -0.0093, -0.0736, -0.0148, -0.0516, 0.0000]
 Time: 789.7s
 MAE: 0.2302, MSE: 0.1760, Task Success:

Sample 148: traj4

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0210, 0.0190, 0.0033, 0.0059, 0.0039, 0.4692, 0.9967]
 Predicted: [0.0014, 0.0193, -0.0215, 0.0318, 0.0073, 0.0950, 0.0000]
 Time: 743.7s

📊 MAE: 0.2068, MSE: 0.1622, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0243, 0.0221, 0.0029, -0.0087, -0.0018, 0.4577, 0.9966]
🎯 Predicted: [0.0134, 0.0057, -0.0130, 0.0305, 0.0300, 0.0580, 0.0000]
⌚ Time: 787.9s
📊 MAE: 0.2196, MSE: 0.1654, Task Success: ✗

📸 Sample 149: traj5

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [-0.0085, -0.0254, 0.0050, 0.0039, -0.0049, -0.1173, 0.9931]
🎯 Predicted: [0.0081, 0.0002, 0.0000, -0.0001, -0.0048, -0.0001, 0.9961]
⌚ Time: 766.7s
📊 MAE: 0.0245, MSE: 0.0021, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0097, -0.0247, 0.0006, 0.0020, 0.0036, -0.1069, 1.0000]
🎯 Predicted: [-0.0047, 0.0044, -0.0065, 0.0114, 0.0093, 0.0241, 0.0000]
⌚ Time: 791.4s
📊 MAE: 0.1710, MSE: 0.1455, Task Success: ✗

📸 Sample 150: traj2

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0036, 0.0465, -0.0004, -0.0057, 0.0068, 0.6653, 0.0688]

🎯 Predicted: [-0.0049, -0.0017, -0.0036, 0.0005, 0.0166, 0.0064, 0.9961]
⌚ Time: 799.5s
📊 MAE: 0.2374, MSE: 0.1852, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [0.0081, 0.0504, 0.0037, -0.0030, -0.0063, 0.6466, 0.0640]
🎯 Predicted: [-0.0071, 0.0407, -0.0067, -0.0104, 0.0253, 0.2030, 0.0000]
⌚ Time: 810.0s
📊 MAE: 0.0831, MSE: 0.0289, Task Success: ✗

📸 Sample 151: traj71
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0248, 0.0721, 0.0033, -0.0040, 0.0025, 0.6961, 0.0695]
🎯 Predicted: [0.0081, -0.0024, 0.0296, -0.0244, -0.0450, -0.0049, 0.0000]
⌚ Time: 828.9s
📊 MAE: 0.1389, MSE: 0.0723, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0257, 0.0820, 0.0014, -0.0017, -0.0033, 0.6851, 0.0652]
🎯 Predicted: [0.0002, -0.0001, 0.0320, 0.0197, -0.0765, -0.0210, 0.9961]
⌚ Time: 855.9s
📊 MAE: 0.2672, MSE: 0.1970, Task Success: ✗

📸 Sample 152: traj49
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)

 Image 1: im_42.jpg
 Ground Truth: [0.0208, 0.0157, 0.0125, -0.0139, -0.0019, -0.4378, 0.9922]
 Predicted: [-0.0013, 0.0015, 0.0018, 0.0075, 0.0066, 0.0112, 0.0000]
 Time: 837.9s
 MAE: 0.2169, MSE: 0.1696, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0101, 0.0147, 0.0116, 0.0030, 0.0034, -0.4062, 0.9932]
 Predicted: [0.0000, -0.0069, 0.0026, 0.0082, -0.0189, -0.0404, 0.0000]
 Time: 847.0s
 MAE: 0.2039, MSE: 0.1602, Task Success: X

 Sample 153: traj76
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0078, -0.0706, 0.0015, -0.0022, 0.0020, -0.8135, 0.9963]
 Predicted: [-0.0007, 0.0018, -0.0044, -0.0008, 0.0233, 0.0161, 0.0000]
 Time: 862.9s
 MAE: 0.2765, MSE: 0.2410, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0030, -0.0806, 0.0039, -0.0017, -0.0011, -0.8067, 1.0000]
 Predicted: [-0.0029, -0.0007, -0.0093, 0.0114, 0.0334, -0.0178, 0.0000]
 Time: 896.1s
 MAE: 0.2765, MSE: 0.2329, Task Success: X

 Sample 154: traj40
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_4.jpg
 Ground Truth: [0.0149, 0.0774, -0.0001, -0.0009, 0.0048, 0.4210, 0.9944]
 Predicted: [0.0157, -0.0250, -0.0062, 0.0165, -0.0812, -0.0597, 0.9961]
 Time: 980.7s
 MAE: 0.0993, MSE: 0.0356, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_5.jpg
 Ground Truth: [0.0184, 0.0811, -0.0033, -0.0129, 0.0015, 0.3973, 0.9998]
 Predicted: [0.0166, -0.0095, -0.0140, 0.0062, 0.0776, -0.1709, 0.9961]
 Time: 971.6s
 MAE: 0.1100, MSE: 0.0482, Task Success:

Sample 155: traj78

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0041, -0.0453, -0.0091, -0.0030, -0.0004, -0.6116, 0.9935]
 Predicted: [-0.0047, 0.0077, -0.0021, 0.0171, 0.0012, 0.0515, 0.9961]
 Time: 1019.2s
 MAE: 0.1069, MSE: 0.0633, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0110, -0.0305, -0.0022, -0.0045, 0.0025, -0.5974, 1.0000]
 Predicted: [-0.0040, -0.0069, -0.0028, -0.0078, 0.0200, -0.0549, 0.9961]
 Time: 1006.5s
 MAE: 0.0855, MSE: 0.0422, Task Success:

Sample 156: traj47

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0056, 0.0175, -0.0031, 0.0072, 0.0047, -0.2458, 0.0765]
🎯 Predicted: [0.0029, -0.0266, -0.0153, 0.0241, 0.0059, -0.0597, 0.9961]
 Time: 1016.1s
 MAE: 0.1698, MSE: 0.1261, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0101, 0.0091, 0.0025, 0.0081, 0.0028, -0.2306, 0.0586]
🎯 Predicted: [0.0029, -0.0276, -0.0067, 0.0312, -0.0416, -0.1484, 0.9961]
 Time: 1433.4s
 MAE: 0.1638, MSE: 0.1271, Task Success: ✗

Sample 157: traj13

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0334, -0.0117, -0.0015, 0.0000, 0.0005, 0.1169, 0.9895]
🎯 Predicted: [-0.0109, 0.0015, -0.0135, -0.0238, -0.0162, 0.0273, 0.9961]
 Time: 993.1s
 MAE: 0.0263, MSE: 0.0014, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0261, -0.0249, 0.0080, 0.0086, 0.0012, 0.1004, 0.9924]
🎯 Predicted: [-0.0067, 0.0154, 0.0013, 0.0816, 0.0481, 0.2030, 0.9961]
 Time: 969.8s
 MAE: 0.0418, MSE: 0.0029, Task Success: ✓

Sample 158: traj14

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [-0.0423, 0.0488, 0.0038, 0.0067, -0.0025, -0.6516, 0.9990]

 Predicted: [-0.0224, -0.0166, 0.0107, -0.0078, -0.0470, 0.0209, 0.0000]

 Time: 979.2s

 MAE: 0.2604, MSE: 0.2082, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [-0.0407, 0.0423, -0.0020, -0.0013, -0.0051, -0.6486, 0.9980]

 Predicted: [-0.0174, -0.0127, 0.0195, -0.0423, -0.0370, -0.0355, 0.0000]

 Time: 968.4s

 MAE: 0.2548, MSE: 0.1969, Task Success: 

Sample 159: traj22

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [-0.0176, 0.0449, 0.0035, 0.0039, -0.0075, 0.0814, 0.9885]

 Predicted: [-0.0096, -0.0208, -0.0187, -0.0008, 0.0548, -0.0017, 0.0000]

 Time: 984.1s

 MAE: 0.1764, MSE: 0.1418, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [-0.0114, 0.0392, 0.0049, 0.0021, -0.0024, 0.0784, 1.0000]

🎯 Predicted: [-0.0031, -0.0292, -0.0013, -0.0238, 0.0006, -0.0017, 0.0000]
⌚ Time: 976.0s
📊 MAE: 0.1703, MSE: 0.1446, Task Success: ✗

📸 Sample 160: traj25

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [0.0223, -0.0309, 0.0022, -0.0052, 0.0061, -0.0343, 0.9948]
🎯 Predicted: [-0.0130, 0.0116, -0.0023, 0.0235, -0.0115, 0.1289, 0.9961]
⌚ Time: 963.4s
📊 MAE: 0.0418, MSE: 0.0044, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [0.0192, -0.0203, -0.0105, 0.0054, -0.0005, -0.0414, 1.0000]
🎯 Predicted: [0.0007, 0.0061, -0.0008, 0.0260, -0.0041, -0.1064, 0.9961]
⌚ Time: 971.7s
📊 MAE: 0.0211, MSE: 0.0008, Task Success: ✓

📸 Sample 161: traj46

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [0.0009, 0.0052, -0.0291, -0.0015, 0.0141, -0.4279, 0.0696]
🎯 Predicted: [-0.0049, 0.0009, -0.0187, 0.0126, 0.0548, 0.0096, 0.9961]
⌚ Time: 977.7s
📊 MAE: 0.2056, MSE: 0.1502, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)

 Image 2: im_43.jpg
 Ground Truth: [-0.0051, 0.0088, -0.0262, 0.0034, 0.0028, -0.4194, 0.0682]
 Predicted: [-0.0074, 0.0005, -0.0184, 0.0126, 0.0555, 0.0096, 0.9961]
 Time: 953.7s
 MAE: 0.2053, MSE: 0.1497, Task Success: X

 Sample 162: traj41

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0110, 0.0463, -0.0024, -0.0017, -0.0035, 0.7356, 0.9963]

 Predicted: [-0.0049, 0.0284, 0.0000, 0.0050, -0.0008, 0.0241, 0.0000]

 Time: 888.5s

 MAE: 0.2505, MSE: 0.2142, Task Success: X

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0125, 0.0493, 0.0111, -0.0007, -0.0053, 0.7254, 0.9966]

 Predicted: [-0.0056, -0.0137, -0.0119, -0.0314, 0.0106, -0.0242, 0.0000]

 Time: 795.5s

 MAE: 0.2710, MSE: 0.2230, Task Success: X

 Sample 163: traj48

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [-0.0230, 0.0224, 0.0072, 0.0004, 0.0021, 0.7063, 1.0000]

 Predicted: [0.0121, 0.0070, 0.0250, 0.0260, -0.0504, 0.0064, 0.0000]

 Time: 788.9s

 MAE: 0.2637, MSE: 0.2136, Task Success: X

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0245, 0.0185, 0.0016, -0.0059, 0.0137, 0.7021, 1.0000]
 Predicted: [0.0161, 0.0129, 0.0120, 0.0177, -0.0771, 0.0193, 0.0000]
 Time: 797.4s
 MAE: 0.2649, MSE: 0.2110, Task Success: X

Sample 164: traj77

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0208, 0.0240, 0.0010, 0.0048, -0.0006, 0.8612, 1.0000]
 Predicted: [0.0175, -0.0066, 0.0400, 0.0439, -0.0926, -0.0807, 0.0000]
 Time: 761.4s
 MAE: 0.3115, MSE: 0.2716, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0124, 0.0148, -0.0063, 0.0035, -0.0077, 0.8474, 1.0000]
 Predicted: [-0.0179, -0.0111, 0.0211, 0.0120, -0.0416, -0.0162, 0.9961]
 Time: 785.4s
 MAE: 0.1384, MSE: 0.1069, Task Success: ✓

Sample 165: traj70

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0110, 0.0405, 0.0055, 0.0029, 0.0067, -0.3828, 0.0671]
 Predicted: [0.0137, 0.0015, 0.0213, 0.0350, -0.0711, 0.0225, 0.0000]
 Time: 759.7s
 MAE: 0.0914, MSE: 0.0254, Task Success: X

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0059, 0.0242, 0.0029, -0.0062, 0.0041, -0.3573, 0.0608]
 Predicted: [0.0112, -0.0276, 0.0164, -0.0238, -0.0450, -0.0130, 0.0000]
 Time: 769.8s
 MAE: 0.0775, MSE: 0.0183, Task Success:

Sample 166: traj24

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0057, -0.0178, -0.0019, -0.0012, -0.0064, -0.6847, 0.9979]
 Predicted: [-0.0004, 0.0005, 0.0013, -0.0021, 0.0012, -0.0033, 0.9961]
 Time: 756.1s
 MAE: 0.1027, MSE: 0.0664, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0129, -0.0230, -0.0004, -0.0015, -0.0035, -0.6890, 0.9889]
 Predicted: [0.0000, 0.0048, -0.0067, 0.0529, 0.0213, -0.0033, 0.9961]
 Time: 797.2s
 MAE: 0.1170, MSE: 0.0678, Task Success:

Sample 167: traj23

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0086, 0.0550, 0.0034, -0.0036, 0.0018, -0.1907, 0.0729]
 Predicted: [0.0009, 0.0015, -0.0002, 0.0107, -0.0001, -0.0081, 0.0000]

⌚ Time: 770.0s
📊 MAE: 0.0483, MSE: 0.0060, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0042, 0.0502, 0.0064, -0.0062, -0.0046, -0.1823, 0.0595]
🎯 Predicted: [0.0085, 0.0093, 0.0102, -0.0219, -0.0189, 0.0193, 0.0000]
⌚ Time: 778.1s
📊 MAE: 0.0498, MSE: 0.0066, Task Success: ✗

📸 Sample 168: traj15
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [-0.0464, -0.0003, -0.0039, -0.0038, 0.0057, -0.2578, 0.9990]
🎯 Predicted: [0.0121, -0.0059, -0.0023, -0.0468, -0.0544, -0.0597, 0.9961]
⌚ Time: 797.6s
📊 MAE: 0.0528, MSE: 0.0069, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0344, 0.0130, 0.0062, 0.0070, -0.0031, -0.2388, 0.9967]
🎯 Predicted: [0.0121, -0.0079, 0.0213, -0.0225, -0.0396, -0.0420, 0.0000]
⌚ Time: 760.7s
📊 MAE: 0.1917, MSE: 0.1482, Task Success: ✗

📸 Sample 169: traj12
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg

Ground Truth: [-0.0168, -0.0156, 0.0059, -0.0135, 0.0015, -0.3387, 0.0644]

Predicted: [-0.0020, 0.0407, -0.0023, -0.0021, 0.0287, 0.0870, 0.0000]

Time: 771.9s

MAE: 0.0869, MSE: 0.0271, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0220, -0.0064, -0.0084, 0.0050, -0.0087, -0.3374, 0.0630]

Predicted: [0.0047, 0.0378, -0.0023, -0.0116, -0.0021, 0.1079, 0.0000]

Time: 782.5s

MAE: 0.0869, MSE: 0.0293, Task Success:

Sample 170: traj56

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0022, -0.0179, 0.0005, 0.0006, 0.0030, -0.6425, 1.0000]

Predicted: [0.0143, 0.0151, -0.0125, 0.0241, 0.0213, -0.0081, 0.0000]

Time: 785.8s

MAE: 0.2484, MSE: 0.2007, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0024, -0.0273, 0.0029, -0.0082, -0.0139, -0.6265, 0.9970]

Predicted: [0.0208, 0.0145, -0.0260, 0.0401, 0.0776, 0.0177, 0.0000]

Time: 1723.0s

MAE: 0.2678, MSE: 0.2032, Task Success:

Sample 171: traj69

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0053, -0.0126, 0.0033, -0.0057, 0.0035, -0.5038, 0.9963]

Predicted: [-0.0183, 0.0239, 0.0143, 0.0222, -0.0115, 0.1079, 0.9961]

Time: 787.3s

MAE: 0.1022, MSE: 0.0538, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0008, -0.0206, -0.0049, -0.0037, 0.0001, -0.4852, 1.0000]

Predicted: [-0.0076, -0.0011, 0.0104, 0.0452, -0.0926, -0.0629, 0.9961]

Time: 769.9s

MAE: 0.0871, MSE: 0.0271, Task Success: ✓

Sample 172: traj51

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0005, -0.0586, 0.0007, 0.0058, -0.0003, 0.4076, 0.0622]

Predicted: [-0.0042, -0.0095, -0.0171, -0.0052, 0.0381, -0.0242, 0.9961]

Time: 757.4s

MAE: 0.2123, MSE: 0.1518, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0026, -0.0552, 0.0050, -0.0009, -0.0082, 0.3769, 0.0569]

Predicted: [-0.0147, 0.0116, -0.0010, 0.0312, 0.0006, -0.0081, 0.9961]

Time: 779.0s

MAE: 0.2071, MSE: 0.1480, Task Success: ✗

Sample 173: traj67

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0006, -0.0311, 0.0017, 0.0002, -0.0080, 0.6580, 0.9966]
 Predicted: [-0.0004, -0.0004, -0.0067, 0.0031, 0.0220, 0.0080, 0.0000]
 Time: 772.2s
 MAE: 0.2457, MSE: 0.2025, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0100, -0.0478, 0.0031, 0.0122, -0.0012, 0.6337, 0.9968]
 Predicted: [-0.0024, 0.0015, -0.0067, 0.0197, 0.0173, -0.0097, 0.0000]
 Time: 778.8s
 MAE: 0.2482, MSE: 0.2015, Task Success: 

Sample 174: traj58

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0021, -0.0271, -0.0026, -0.0099, 0.0109, -0.2113, 0.0677]
 Predicted: [-0.0071, -0.0037, -0.0109, -0.0365, -0.0008, 0.0418, 0.0000]
 Time: 791.7s
 MAE: 0.0572, MSE: 0.0100, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0097, -0.0273, -0.0069, 0.0056, 0.0084, -0.2175, 0.0579]
 Predicted: [-0.0071, 0.0277, -0.0021, 0.0107, 0.0073, 0.2030, 0.0000]
 Time: 791.8s
 MAE: 0.0781, MSE: 0.0262, Task Success: 

Sample 175: traj60

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0192, -0.0392, -0.0029, -0.0057, -0.0044, 0.7785, 0.9987]
 Predicted: [-0.0116, 0.0381, -0.0101, 0.0114, -0.0316, 0.0128, 0.9961]
 Time: 767.5s
 MAE: 0.1292, MSE: 0.0848, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0300, -0.0310, 0.0021, -0.0006, -0.0081, 0.7529, 1.0000]
 Predicted: [-0.0116, -0.0208, -0.0034, -0.0749, 0.0213, -0.0226, 0.9961]
 Time: 787.8s
 MAE: 0.1310, MSE: 0.0869, Task Success:

Sample 176: traj34
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0153, 0.0292, 0.0050, 0.0011, -0.0046, 0.4390, 0.0696]
 Predicted: [-0.0031, 0.0012, 0.0005, 0.0082, 0.0032, 0.0015, 0.9961]
 Time: 761.4s
 MAE: 0.2034, MSE: 0.1501, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0048, 0.0255, 0.0011, 0.0075, -0.0093, 0.4178, 0.0643]
 Predicted: [-0.0024, -0.0001, -0.0096, 0.0037, 0.0334, -0.0001, 0.9961]
 Time: 752.1s
 MAE: 0.2050, MSE: 0.1493, Task Success:

📸 Sample 177: traj33

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [0.0157, 0.0452, -0.0020, -0.0050, 0.0074, -0.8995, 0.0520]

🎯 Predicted: [-0.0004, 0.0018, -0.0073, -0.0052, -0.0242, 0.0515, 0.9961]

⌚ Time: 747.9s

📊 MAE: 0.2845, MSE: 0.2570, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [0.0148, 0.0561, -0.0083, 0.0033, 0.0100, -0.8826, 0.0533]

🎯 Predicted: [0.0043, -0.0033, -0.0034, 0.0120, -0.0336, 0.0580, 0.0000]

⌚ Time: 761.0s

📊 MAE: 0.1602, MSE: 0.1276, Task Success: ✗

📸 Sample 178: traj61

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [-0.0071, 0.0539, 0.0074, -0.0031, 0.0005, 0.5523, 0.9999]

🎯 Predicted: [-0.0051, -0.0050, 0.0070, -0.0135, -0.0356, 0.1240, 0.9961]

⌚ Time: 764.9s

📊 MAE: 0.0771, MSE: 0.0269, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [-0.0110, 0.0584, 0.0134, 0.0054, -0.0010, 0.5309, 0.9937]

🎯 Predicted: [0.0014, -0.0105, 0.0003, 0.0177, 0.0200, -0.0097, 0.9961]

⌚ Time: 757.8s

 MAE: 0.0958, MSE: 0.0426, Task Success: X

 Sample 179: traj66

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0075, -0.0184, 0.0023, -0.0046, 0.0060, -0.0477, 0.0590]

 Predicted: [-0.0040, 0.0151, 0.0013, -0.0321, 0.0026, 0.0451, 0.0000]

 Time: 757.2s

 MAE: 0.0327, MSE: 0.0020, Task Success: X

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0117, -0.0222, -0.0066, 0.0033, -0.0052, -0.0534, 0.0581]

 Predicted: [-0.0145, 0.0407, 0.0029, 0.0312, -0.0048, 0.0499, 0.0000]

 Time: 764.3s

 MAE: 0.0412, MSE: 0.0028, Task Success: X

 Sample 180: traj59

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0027, 0.0512, -0.0001, 0.0075, 0.0080, 0.8356, 1.0000]

 Predicted: [0.0014, -0.0124, -0.0023, 0.0043, 0.0073, -0.0549, 0.0000]

 Time: 758.0s

 MAE: 0.2802, MSE: 0.2567, Task Success: X

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0132, 0.0528, -0.0042, -0.0010, 0.0025, 0.8324, 0.9930]

🎯 Predicted: [0.0081, -0.0004, 0.0174, -0.0397, -0.0329, 0.0032, 0.0000]
⌚ Time: 766.4s
📊 MAE: 0.2823, MSE: 0.2400, Task Success: ✗

📸 Sample 181: traj50

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [-0.0238, 0.0378, -0.0030, -0.0013, -0.0037, 0.2721, 0.9974]

🎯 Predicted: [-0.0036, -0.0037, -0.0067, -0.0091, 0.0314, -0.0226, 0.9961]

⌚ Time: 754.6s

📊 MAE: 0.0578, MSE: 0.0129, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [-0.0229, 0.0349, 0.0043, 0.0122, 0.0023, 0.2568, 0.9977]

🎯 Predicted: [-0.0022, -0.0224, -0.0119, 0.0082, 0.0347, -0.1081, 0.0000]

⌚ Time: 764.8s

📊 MAE: 0.2133, MSE: 0.1619, Task Success: ✗

📸 Sample 182: traj57

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0140, 0.0242, 0.0005, 0.0023, -0.0006, 0.2087, 0.0667]

🎯 Predicted: [0.0072, 0.0077, -0.0153, 0.0082, -0.0162, -0.0952, 0.9961]

⌚ Time: 758.6s

📊 MAE: 0.1848, MSE: 0.1367, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg
 Ground Truth: [0.0199, 0.0146, -0.0012, -0.0107, 0.0013, 0.1919, 1.0000]
 Predicted: [0.0020, 0.0145, -0.0023, 0.0082, -0.0055, 0.0451, 0.9961]
 Time: 755.8s
 MAE: 0.0279, MSE: 0.0032, Task Success: 

Sample 183: traj68

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0093, 0.0277, 0.0050, -0.0038, 0.0003, 0.4756, 1.0000]

 Predicted: [-0.0266, -0.0040, 0.0005, 0.0069, -0.0061, -0.0210, 0.9961]

 Time: 751.0s

 MAE: 0.0842, MSE: 0.0356, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0109, 0.0298, -0.0006, -0.0043, 0.0068, 0.4687, 1.0000]

 Predicted: [-0.0036, -0.0007, -0.0156, -0.0078, 0.0441, 0.0032, 0.9961]

 Time: 734.6s

 MAE: 0.0815, MSE: 0.0314, Task Success: 

Sample 184: traj32

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [-0.0252, -0.0018, 0.0058, 0.0026, -0.0052, -0.9209, 0.9992]

 Predicted: [0.0009, 0.0018, -0.0002, 0.0082, -0.0102, 0.0080, 0.9961]

 Time: 750.7s

 MAE: 0.1398, MSE: 0.1234, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0283, 0.0004, 0.0000, -0.0030, 0.0020, -0.9069, 0.9960]
 Predicted: [0.0000, -0.0040, 0.0005, 0.0145, 0.0052, -0.0017, 0.0000]
 Time: 754.5s
 MAE: 0.2793, MSE: 0.2589, Task Success: X

 Sample 185: traj35

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0115, 0.0509, -0.0060, -0.0005, 0.0022, -0.3621, 1.0000]
 Predicted: [-0.0067, -0.0095, 0.0247, 0.0145, -0.0296, -0.0291, 0.0000]
 Time: 747.9s
 MAE: 0.2127, MSE: 0.1596, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0123, 0.0466, -0.0066, -0.0077, 0.0040, -0.3566, 1.0000]
 Predicted: [0.0081, -0.0037, 0.0400, 0.0011, -0.0926, -0.0017, 0.0000]
 Time: 747.8s
 MAE: 0.2231, MSE: 0.1629, Task Success: X

 Sample 186: traj9

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0269, 0.0201, -0.0036, -0.0030, -0.0007, -0.3030, 0.9962]
 Predicted: [-0.0172, 0.0077, -0.0031, 0.0605, -0.0195, 0.0177, 0.9961]
 Time: 752.5s
 MAE: 0.0657, MSE: 0.0156, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0208, 0.0254, 0.0010, -0.0021, 0.0016, -0.2892, 1.0000]
 Predicted: [-0.0062, -0.0118, -0.0171, -0.0225, -0.0209, -0.0242, 0.9961]
 Time: 747.8s
 MAE: 0.0563, MSE: 0.0105, Task Success:

Sample 187: traj7

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0129, -0.0335, -0.0002, 0.0054, -0.0025, 0.7750, 1.0000]
 Predicted: [0.0014, -0.0069, -0.0008, -0.0014, -0.0021, -0.0033, 0.0000]
 Time: 746.0s
 MAE: 0.2610, MSE: 0.2295, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0174, -0.0379, 0.0037, 0.0016, 0.0022, 0.7557, 1.0000]
 Predicted: [0.0034, 0.0187, -0.0109, 0.0082, -0.0028, 0.0547, 0.9961]
 Time: 749.6s
 MAE: 0.1155, MSE: 0.0708, Task Success:

Sample 188: traj0

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0132, 0.0584, -0.0020, 0.0010, 0.0077, 0.0225, 1.0000]
 Predicted: [-0.0246, 0.0242, -0.0106, 0.0082, -0.0115, 0.0306, 0.9961]
 Time: 746.3s

📊 MAE: 0.0170, MSE: 0.0005, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0051, 0.0603, -0.0042, -0.0040, -0.0011, 0.0335, 0.9983]
🎯 Predicted: [-0.0056, -0.0273, 0.0000, -0.0135, 0.0099, 0.0354, 0.9961]
⌚ Time: 750.4s
📊 MAE: 0.0167, MSE: 0.0011, Task Success: ✗

📸 Sample 189: traj1
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [-0.0159, 0.0446, -0.0034, -0.0015, -0.0024, 0.4225, 0.9958]
🎯 Predicted: [0.0014, -0.0075, -0.0015, -0.0219, 0.0046, -0.0081, 0.0000]
⌚ Time: 749.0s
📊 MAE: 0.2179, MSE: 0.1686, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0207, 0.0585, 0.0000, -0.0052, 0.0005, 0.4198, 0.9992]
🎯 Predicted: [0.0081, -0.0160, 0.0400, 0.0222, -0.0926, -0.0049, 0.0000]
⌚ Time: 740.9s
📊 MAE: 0.2411, MSE: 0.1709, Task Success: ✗

📸 Sample 190: traj6
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [-0.0055, -0.0218, -0.0033, -0.0038, 0.0034, -0.5425, 0.0719]

🎯 Predicted: [0.0000, -0.0066, -0.0054, 0.0126, -0.0095, -0.0049, 0.9961]
⌚ Time: 751.1s
📊 MAE: 0.2163, MSE: 0.1634, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0087, -0.0205, 0.0031, -0.0052, 0.0106, -0.5287, 0.0602]
🎯 Predicted: [-0.0074, 0.0109, -0.0065, -0.0110, 0.0508, 0.0741, 0.9961]
⌚ Time: 754.1s
📊 MAE: 0.2324, MSE: 0.1774, Task Success: ✗

📸 Sample 191: traj8

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0053, -0.0172, -0.0000, -0.0007, -0.0021, -0.6332, 0.0644]
🎯 Predicted: [-0.0004, 0.0018, -0.0067, -0.0097, 0.0213, 0.0112, 0.9961]
⌚ Time: 749.4s
📊 MAE: 0.2341, MSE: 0.1835, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0191, -0.0325, -0.0044, 0.0014, -0.0080, -0.6276, 0.0622]
🎯 Predicted: [-0.0004, 0.0038, -0.0005, 0.0203, 0.0180, 0.0209, 0.0000]
⌚ Time: 755.1s
📊 MAE: 0.1163, MSE: 0.0610, Task Success: ✗

📸 Sample 192: traj17

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)

 Image 1: im_42.jpg
 Ground Truth: [0.0135, -0.0037, 0.0016, 0.0065, 0.0071, -0.9837, 1.0000]
 Predicted: [0.0014, -0.0241, -0.0138, -0.0206, 0.0073, 0.1498, 0.9961]
 Time: 753.4s
 MAE: 0.1732, MSE: 0.1838, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0164, 0.0018, -0.0067, -0.0002, 0.0041, -0.9594, 0.9949]
 Predicted: [-0.0027, -0.0027, -0.0031, 0.0011, -0.0041, 0.0338, 0.9961]
 Time: 745.6s
 MAE: 0.1473, MSE: 0.1410, Task Success: 

 Sample 193: traj28
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_4.jpg
 Ground Truth: [0.0214, 0.0360, -0.0006, -0.0021, 0.0048, -0.1500, 1.0000]
 Predicted: [-0.0089, -0.0124, -0.0158, 0.0248, -0.0195, 0.0322, 0.9961]
 Time: 741.4s
 MAE: 0.0473, MSE: 0.0054, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_21.jpg
 Ground Truth: [0.0174, 0.0343, 0.0014, -0.0004, 0.0015, -0.1381, 1.0000]
 Predicted: [0.0047, -0.0001, 0.0400, -0.0359, -0.0926, -0.0081, 0.0000]
 Time: 765.0s
 MAE: 0.1922, MSE: 0.1471, Task Success: 

 Sample 194: traj10
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0029, -0.0187, -0.0010, -0.0089, -0.0073, -0.8761, 1.0000]
🎯 Predicted: [0.0087, 0.0080, 0.0268, -0.0104, -0.0537, 0.0128, 0.0000]
 Time: 767.2s
 MAE: 0.2861, MSE: 0.2563, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0078, -0.0253, -0.0035, -0.0037, -0.0045, -0.8620, 0.9963]
🎯 Predicted: [0.0087, -0.0121, 0.0213, -0.0397, -0.0242, -0.0339, 0.0000]
 Time: 747.2s
 MAE: 0.2764, MSE: 0.2401, Task Success: ✗

Sample 195: traj26

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0192, -0.0639, 0.0059, 0.0123, -0.0002, -0.5193, 0.9946]
🎯 Predicted: [-0.0087, -0.0273, -0.0028, 0.0031, -0.0416, -0.0629, 0.9961]
 Time: 748.7s
 MAE: 0.0806, MSE: 0.0302, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0253, -0.0636, -0.0011, -0.0004, 0.0004, -0.5070, 1.0000]
🎯 Predicted: [-0.0127, -0.0331, -0.0213, -0.0806, 0.0046, -0.0581, 0.9961]
 Time: 747.6s
 MAE: 0.0858, MSE: 0.0299, Task Success: ✓

Sample 196: traj19

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0439, -0.0455, 0.0039, -0.0036, -0.0114, 0.9258, 0.0595]
🎯 Predicted: [0.0014, -0.0131, 0.0257, 0.0120, -0.0550, -0.0404, 0.9961]
 Time: 755.1s
 MAE: 0.2945, MSE: 0.2595, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0217, -0.0592, -0.0014, -0.0089, 0.0013, 0.9105, 1.0000]
🎯 Predicted: [0.0000, -0.0007, -0.0018, 0.0037, -0.0035, -0.0049, 0.9961]
 Time: 766.4s
 MAE: 0.1453, MSE: 0.1203, Task Success: ✗

Sample 197: traj21

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [0.0040, 0.0114, 0.0045, 0.0042, 0.0094, 0.3592, 0.9937]
🎯 Predicted: [-0.0116, -0.0121, 0.0076, 0.0248, -0.0926, -0.1322, 0.9961]
 Time: 758.5s
 MAE: 0.0940, MSE: 0.0362, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0121, 0.0053, -0.0012, -0.0020, 0.0036, 0.3362, 0.9969]
🎯 Predicted: [-0.0027, 0.0005, -0.0119, 0.0050, 0.0381, 0.0096, 0.9961]
 Time: 756.1s
 MAE: 0.0562, MSE: 0.0154, Task Success: ✓

📸 Sample 198: traj75

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0103, -0.0375, -0.0016, 0.0028, -0.0079, -0.1597, 0.9982]

🎯 Predicted: [-0.0071, -0.0241, -0.0075, -0.0206, 0.0314, 0.0322, 0.0000]

⌚ Time: 746.3s

📊 MAE: 0.1842, MSE: 0.1480, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [0.0034, -0.0424, -0.0013, -0.0083, -0.0019, -0.1461, 0.9938]

🎯 Predicted: [-0.0038, -0.0202, -0.0023, 0.0075, -0.0088, 0.0418, 0.0000]

⌚ Time: 776.4s

📊 MAE: 0.1764, MSE: 0.1462, Task Success: ✗

📸 Sample 199: traj72

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0083, 0.0518, 0.0066, -0.0081, 0.0042, 0.0371, 0.9978]

🎯 Predicted: [0.0251, -0.0406, 0.0013, -0.0806, -0.0926, -0.0694, 0.0000]

⌚ Time: 788.7s

📊 MAE: 0.1983, MSE: 0.1472, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [0.0058, 0.0510, -0.0027, 0.0020, -0.0011, 0.0426, 0.9990]

🎯 Predicted: [-0.0033, -0.0338, -0.0184, -0.0806, -0.0068, -0.0968, 0.0000]

Time: 783.8s
 MAE: 0.1909, MSE: 0.1474, Task Success: X

Sample 200: traj44

Instruction: pick up the object and place it in the bowl

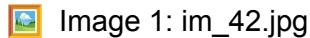
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0074, -0.0247, -0.0029, 0.0003, 0.0003, -0.1539, 0.9997]

⌚ Predicted: [0.0121, -0.0124, 0.0400, 0.0554, -0.0926, -0.0291, 0.0000]

Time: 765.6s

MAE: 0.1925, MSE: 0.1470, Task Success: X

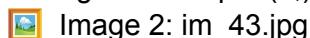
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [0.0042, -0.0362, 0.0020, 0.0017, -0.0048, -0.1373, 1.0000]

⌚ Predicted: [-0.0033, -0.0001, 0.0255, -0.0129, -0.0497, 0.0144, 0.0000]

Time: 782.1s

MAE: 0.1826, MSE: 0.1467, Task Success: X

Sample 201: traj43

Instruction: pick up the object and place it in the bowl

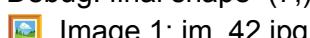
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0180, -0.0195, 0.0026, -0.0012, -0.0043, 0.6375, 1.0000]

⌚ Predicted: [-0.0058, -0.0105, 0.0278, 0.0088, -0.0617, -0.0436, 0.0000]

Time: 776.3s

MAE: 0.2564, MSE: 0.2097, Task Success: X

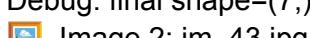
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0246, -0.0147, 0.0031, -0.0006, 0.0049, 0.6222, 1.0000]
⌚ Predicted: [0.0000, -0.0075, 0.0008, 0.0056, 0.0052, -0.0259, 0.0000]
⌚ Time: 779.6s
📊 MAE: 0.2413, MSE: 0.2030, Task Success: ✗

📸 Sample 202: traj20

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0056, 0.0336, 0.0073, -0.0017, 0.0092, -0.9223, 1.0000]
⌚ Predicted: [-0.0040, -0.0017, -0.0023, -0.0001, 0.0173, -0.0049, 0.9961]
⌚ Time: 771.3s
📊 MAE: 0.1397, MSE: 0.1204, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0018, 0.0333, 0.0005, -0.0025, 0.0022, -0.9180, 0.9946]
⌚ Predicted: [0.0108, 0.0086, -0.0067, 0.0082, 0.0086, 0.0032, 0.9961]
⌚ Time: 759.3s
📊 MAE: 0.1406, MSE: 0.1214, Task Success: ✓

📸 Sample 203: traj27

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0044, -0.0158, -0.0053, 0.0045, -0.0041, 0.3848, 1.0000]
⌚ Predicted: [0.0047, 0.0022, -0.0088, 0.0184, 0.0032, 0.0161, 0.9961]
⌚ Time: 792.5s
📊 MAE: 0.0606, MSE: 0.0195, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)

Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [-0.0048, -0.0129, 0.0002, -0.0031, 0.0041, 0.3761, 0.9967]
Predicted: [-0.0257, -0.0046, -0.0021, 0.0050, -0.0416, -0.0758, 0.9961]
Time: 805.9s
MAE: 0.0768, MSE: 0.0296, Task Success: ✓

 Sample 204: traj18

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [0.0011, -0.0015, -0.0348, 0.0001, -0.0019, 0.4420, 0.9963]
Predicted: [-0.0199, -0.0046, -0.0117, -0.0027, 0.0274, -0.0226, 0.9961]
Time: 768.6s
MAE: 0.0778, MSE: 0.0311, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [0.0049, 0.0000, -0.0245, -0.0056, -0.0046, 0.4198, 1.0000]
Predicted: [-0.0264, 0.0090, -0.0028, 0.0484, -0.0343, 0.0209, 0.9961]
Time: 790.6s
MAE: 0.0784, MSE: 0.0235, Task Success: ✓

 Sample 205: traj11

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [-0.0037, -0.0099, -0.0021, -0.0088, 0.0037, 0.0348, 0.0750]
Predicted: [0.0130, -0.0179, 0.0400, -0.0289, -0.0926, -0.0404, 0.0000]
Time: 764.8s
MAE: 0.0476, MSE: 0.0033, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0022, -0.0214, -0.0009, 0.0016, -0.0027, 0.0237, 0.0636]
 Predicted: [0.0130, -0.0095, 0.0400, 0.0011, -0.0926, -0.0049, 0.0000]
 Time: 764.9s
 MAE: 0.0352, MSE: 0.0021, Task Success:

Sample 206: traj16

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0317, -0.0290, -0.0015, -0.0015, -0.0064, -0.7793, 0.9992]
 Predicted: [0.0016, -0.0131, -0.0171, -0.0129, 0.0039, -0.1403, 0.9961]
 Time: 765.2s
 MAE: 0.1041, MSE: 0.0586, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0328, -0.0205, 0.0001, -0.0049, 0.0039, -0.7620, 0.9915]
 Predicted: [0.0027, -0.0134, -0.0127, -0.0410, -0.0926, -0.1484, 0.9961]
 Time: 758.7s
 MAE: 0.1152, MSE: 0.0555, Task Success:

Sample 207: traj29

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0226, 0.0888, -0.0005, -0.0005, -0.0059, -0.5116, 1.0000]
 Predicted: [0.0215, -0.0020, 0.0325, -0.0321, -0.0926, 0.0032, 0.0000]
 Time: 776.8s
 MAE: 0.2573, MSE: 0.1835, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0185, 0.0836, -0.0120, 0.0071, -0.0045, -0.4996, 1.0000]
 Predicted: [0.0087, 0.0022, -0.0034, 0.0139, -0.0035, 0.0193, 0.0000]
 Time: 754.5s
 MAE: 0.2349, MSE: 0.1824, Task Success:

Sample 208: traj42

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0087, -0.0366, 0.0023, 0.0006, 0.0017, 0.4491, 1.0000]
 Predicted: [0.0116, -0.0082, -0.0127, 0.0050, 0.0166, -0.0081, 0.9961]
 Time: 776.6s
 MAE: 0.0778, MSE: 0.0301, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0069, -0.0295, 0.0083, 0.0031, 0.0052, 0.4180, 0.9933]
 Predicted: [-0.0132, -0.0105, -0.0171, -0.0225, 0.0294, 0.0080, 0.9961]
 Time: 773.3s
 MAE: 0.0733, MSE: 0.0243, Task Success:

Sample 209: traj45

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0074, 0.0240, 0.0020, 0.0011, 0.0028, -0.4747, 1.0000]
 Predicted: [0.0014, -0.0017, -0.0078, -0.0014, -0.0497, -0.0307, 0.9961]

⌚ Time: 764.2s
📊 MAE: 0.0782, MSE: 0.0287, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0074, 0.0284, 0.0083, 0.0043, -0.0051, -0.4524, 1.0000]
🎯 Predicted: [0.0025, -0.0121, -0.0179, -0.0397, -0.0162, -0.0694, 0.9961]
⌚ Time: 755.4s
📊 MAE: 0.0741, MSE: 0.0216, Task Success: ✓

📸 Sample 210: traj73
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [-0.0320, 0.0291, 0.0029, 0.0057, 0.0113, -0.4731, 0.0727]
🎯 Predicted: [-0.0027, -0.0001, 0.0021, -0.0014, 0.0140, -0.0210, 0.0000]
⌚ Time: 761.8s
📊 MAE: 0.0848, MSE: 0.0302, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0370, 0.0313, -0.0014, 0.0052, 0.0040, -0.4556, 0.0681]
🎯 Predicted: [-0.0029, -0.0004, -0.0023, 0.0203, -0.0470, 0.0241, 0.0000]
⌚ Time: 772.1s
📊 MAE: 0.0973, MSE: 0.0343, Task Success: ✗

📸 Sample 211: traj74
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg

✓ Ground Truth: [0.0038, 0.0017, -0.0172, 0.0054, 0.0061, 0.9015, 0.0643]
🎯 Predicted: [-0.0127, 0.0381, -0.0138, 0.0088, 0.0032, -0.0065, 0.9961]
⌚ Time: 796.3s
📊 MAE: 0.2718, MSE: 0.2421, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0015, 0.0069, -0.0204, -0.0023, -0.0063, 0.8854, 1.0000]
🎯 Predicted: [-0.0060, 0.0116, -0.0075, 0.0280, 0.0153, -0.0839, 0.9961]
⌚ Time: 773.8s
📊 MAE: 0.1496, MSE: 0.1344, Task Success: ✓

🎥 Sample 212: traj3

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0157, -0.0162, 0.0054, 0.0076, -0.0026, -0.9753, 0.9975]
🎯 Predicted: [-0.0020, -0.0415, -0.0099, 0.0088, 0.0575, -0.0613, 0.0000]
⌚ Time: 772.3s
📊 MAE: 0.2896, MSE: 0.2622, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0163, -0.0153, 0.0023, -0.0005, -0.0046, -0.9628, 1.0000]
🎯 Predicted: [-0.0069, -0.0111, 0.0050, 0.0158, -0.0242, -0.0178, 0.9961]
⌚ Time: 778.6s
📊 MAE: 0.1430, MSE: 0.1277, Task Success: ✓

🎥 Sample 213: traj4

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [0.0027, 0.0800, -0.0041, -0.0049, -0.0037, 0.5888, 0.0610]

Predicted: [0.0094, 0.0077, 0.0278, -0.0199, -0.0798, 0.0257, 0.0000]

Time: 763.5s

MAE: 0.1180, MSE: 0.0476, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0128, 0.0811, -0.0021, 0.0020, 0.0033, 0.5702, 1.0000]

Predicted: [0.0121, -0.0040, 0.0148, -0.0187, -0.0289, 0.0032, 0.0000]

Time: 769.5s

MAE: 0.2461, MSE: 0.1901, Task Success: ✗

📸 Sample 214: traj5

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0307, 0.0071, -0.0027, -0.0057, 0.0060, 0.2439, 0.9950]

Predicted: [-0.0076, -0.0066, -0.0088, -0.0084, 0.0193, -0.0404, 0.9961]

Time: 767.0s

MAE: 0.0492, MSE: 0.0117, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0238, 0.0228, 0.0009, -0.0032, 0.0034, 0.2514, 0.9972]

Predicted: [-0.0165, -0.0124, -0.0208, -0.0231, 0.0394, -0.0226, 0.9961]

Time: 805.9s

MAE: 0.0565, MSE: 0.0112, Task Success: ✓

📸 Sample 215: traj2

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0138, -0.0031, 0.0021, -0.0147, -0.0126, -0.1704, 0.0628]
 Predicted: [-0.0002, 0.0009, 0.0003, 0.0011, -0.0001, -0.0146, 0.9961]
 Time: 1852.4s
 MAE: 0.1624, MSE: 0.1280, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0053, -0.0043, 0.0004, -0.0048, -0.0052, -0.1641, 0.0640]
 Predicted: [-0.0009, -0.0004, -0.0010, -0.0027, -0.0001, -0.0097, 0.9961]
 Time: 772.2s
 MAE: 0.1576, MSE: 0.1275, Task Success: 

 Sample 216: traj9
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0198, -0.0454, 0.0013, -0.0051, -0.0054, -0.4277, 0.0594]
 Predicted: [-0.0031, 0.0125, -0.0132, -0.0008, 0.0039, 0.1482, 0.0000]
 Time: 740.7s
 MAE: 0.1054, MSE: 0.0484, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0332, -0.0495, 0.0070, -0.0026, 0.0023, -0.4093, 0.0579]
 Predicted: [0.0148, -0.0322, 0.0174, -0.0512, -0.0926, -0.0291, 0.0000]
 Time: 735.5s
 MAE: 0.0939, MSE: 0.0231, Task Success: 

 Sample 217: traj7
Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0354, -0.0644, -0.0004, 0.0092, 0.0091, -0.4793, 1.0000]
 Predicted: [-0.0071, 0.0090, 0.0239, -0.0634, -0.0872, 0.0225, 0.0000]
 Time: 4650.8s
 MAE: 0.2567, MSE: 0.1819, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0304, -0.0476, -0.0007, 0.0058, 0.0086, -0.4801, 1.0000]
 Predicted: [0.0130, -0.0111, 0.0335, -0.0199, -0.0926, 0.0032, 0.0000]
 Time: 3317.5s
 MAE: 0.2463, MSE: 0.1784, Task Success: ✗

Sample 218: traj0

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0268, 0.0083, -0.0027, 0.0006, -0.0047, 0.3764, 0.9943]
 Predicted: [0.0119, 0.0015, 0.0247, -0.0104, -0.0316, -0.0162, 0.0000]
 Time: 775.3s
 MAE: 0.2105, MSE: 0.1635, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0207, 0.0074, -0.0057, 0.0016, 0.0013, 0.3659, 0.9935]
 Predicted: [-0.0089, 0.0077, 0.0268, -0.0225, -0.0336, 0.0032, 0.9961]
 Time: 767.6s
 MAE: 0.0695, MSE: 0.0193, Task Success: ✓

📸 Sample 219: traj1

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0038, -0.0156, 0.0015, 0.0018, 0.0009, -0.5246, 0.0608]

🎯 Predicted: [-0.0085, -0.0127, 0.0115, 0.0554, 0.0059, 0.0692, 0.0000]

⌚ Time: 777.9s

📊 MAE: 0.1055, MSE: 0.0514, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [0.0170, -0.0277, -0.0017, 0.0059, 0.0002, -0.5179, 1.0000]

🎯 Predicted: [-0.0022, 0.0407, -0.0080, -0.0333, 0.0026, 0.0999, 0.0000]

⌚ Time: 772.2s

📊 MAE: 0.2505, MSE: 0.1983, Task Success: ✗

📸 Sample 220: traj6

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0041, 0.0587, -0.0016, 0.0041, -0.0062, -0.8251, 0.9958]

🎯 Predicted: [0.0148, 0.0407, -0.0189, -0.0238, 0.0347, 0.0950, 0.0000]

⌚ Time: 759.1s

📊 MAE: 0.2901, MSE: 0.2631, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [0.0032, 0.0685, 0.0030, -0.0001, -0.0062, -0.7895, 0.9965]

🎯 Predicted: [0.0148, 0.0358, -0.0182, 0.0082, 0.0233, 0.0789, 0.0000]

Time: 760.1s
 MAE: 0.2812, MSE: 0.2500, Task Success: X

Sample 221: traj8

Instruction: pick up the object and place it in the bowl

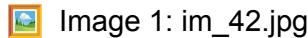
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [0.0138, -0.0322, 0.0022, -0.0010, 0.0029, 0.0756, 1.0000]

⌚ Predicted: [-0.0116, 0.0407, 0.0198, 0.0363, -0.0550, 0.0580, 0.9961]

Time: 763.8s

MAE: 0.0332, MSE: 0.0016, Task Success: X

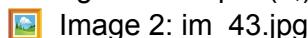
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [0.0159, -0.0396, 0.0029, 0.0032, -0.0107, 0.0677, 1.0000]

⌚ Predicted: [-0.0085, -0.0357, -0.0034, 0.0082, -0.0115, -0.1081, 0.9961]

Time: 762.4s

MAE: 0.0314, MSE: 0.0045, Task Success: ✓

Sample 222: traj0

Instruction: pick up the object and place it in the bowl

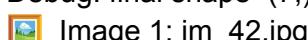
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0005, 0.0276, 0.0000, 0.0067, -0.0189, 0.9969, 1.0000]

⌚ Predicted: [-0.0145, -0.0030, 0.0146, -0.0187, -0.0081, 0.0402, 0.0000]

Time: 775.0s

MAE: 0.2931, MSE: 0.2739, Task Success: X

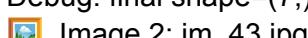
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [0.0001, 0.0278, 0.0000, 0.0100, -0.0323, 0.9865, 1.0000]
⌚ Predicted: [-0.0067, 0.0015, 0.0213, -0.0065, -0.0316, 0.0709, 0.0000]
⌚ Time: 850.0s
📊 MAE: 0.2839, MSE: 0.2628, Task Success: ✗

📸 Sample 223: traj1

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [0.0088, -0.0077, 0.0000, 0.0036, -0.0173, -0.9270, 1.0000]
⌚ Predicted: [0.0034, -0.0040, 0.0177, 0.0139, -0.0524, -0.0065, 0.9961]
⌚ Time: 827.7s
📊 MAE: 0.1424, MSE: 0.1213, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [0.0092, -0.0076, 0.0000, 0.0052, -0.0287, -0.9176, 1.0000]
⌚ Predicted: [-0.0009, -0.0114, 0.0252, 0.0382, -0.0296, -0.0194, 0.9961]
⌚ Time: 757.0s
📊 MAE: 0.1393, MSE: 0.1155, Task Success: ✓

📸 Sample 224: traj30

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0448, -0.0194, -0.0008, 0.0180, -0.0181, -0.6624, 0.9945]
⌚ Predicted: [0.0027, -0.0007, -0.0008, -0.0091, -0.0169, 0.0177, 0.9961]
⌚ Time: 768.9s
📊 MAE: 0.1109, MSE: 0.0666, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)

Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [-0.0320, -0.0149, -0.0032, 0.0125, -0.0409, -0.6499, 0.9914]
Predicted: [0.0067, -0.0040, -0.0093, -0.0155, -0.0028, -0.0146, 0.9961]
Time: 748.7s
MAE: 0.1088, MSE: 0.0582, Task Success: ✓

 Sample 225: traj37

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [-0.0254, -0.0131, 0.0038, 0.0060, -0.0340, -0.5940, 0.9999]
Predicted: [0.0170, 0.0090, -0.0052, 0.0318, -0.0108, 0.0870, 0.9961]
Time: 777.5s
MAE: 0.1153, MSE: 0.0668, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [-0.0223, -0.0096, -0.0028, -0.0029, -0.0562, -0.5918, 1.0000]
Predicted: [0.0170, 0.0090, -0.0052, 0.0292, -0.0329, -0.0130, 0.9961]
Time: 759.6s
MAE: 0.0998, MSE: 0.0484, Task Success: ✓

 Sample 226: traj39

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [0.0463, 0.0389, 0.0093, -0.0058, -0.0347, -0.4919, 1.0000]
Predicted: [-0.0065, 0.0103, 0.0166, 0.0267, -0.0008, 0.0161, 0.0000]
Time: 757.5s
MAE: 0.2376, MSE: 0.1806, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0484, 0.0429, 0.0038, -0.0056, -0.0318, -0.4727, 0.9972]
 Predicted: [0.0204, -0.0134, 0.0242, 0.0043, -0.0343, -0.0678, 0.0000]
 Time: 770.6s
 MAE: 0.2170, MSE: 0.1661, Task Success:

Sample 227: traj52

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0156, 0.0215, -0.0066, 0.0129, -0.0248, 0.9830, 0.9956]
 Predicted: [0.0049, 0.0025, 0.0005, 0.0535, 0.0026, -0.0162, 0.9961]
 Time: 777.7s
 MAE: 0.1578, MSE: 0.1430, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0271, 0.0219, -0.0013, 0.0104, -0.0357, 0.9678, 0.9993]
 Predicted: [0.0005, -0.0017, 0.0005, -0.0116, -0.0015, -0.0033, 0.0000]
 Time: 783.3s
 MAE: 0.2970, MSE: 0.2778, Task Success:

Sample 228: traj55

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0336, -0.0651, 0.0009, 0.0148, -0.0219, 0.1823, 1.0000]
 Predicted: [0.0083, 0.0106, 0.0338, -0.0084, -0.0751, 0.0370, 0.0000]
 Time: 754.0s
 MAE: 0.1937, MSE: 0.1474, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0416, -0.0665, 0.0017, 0.0175, -0.0377, 0.1592, 0.9983]
 Predicted: [-0.0078, 0.0077, 0.0008, 0.0139, 0.0253, 0.0209, 0.0000]
 Time: 765.8s
 MAE: 0.1897, MSE: 0.1468, Task Success:

Sample 229: traj63

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0079, -0.0055, 0.0006, 0.0070, -0.0162, -0.4191, 0.9974]
 Predicted: [0.0043, -0.0037, 0.0089, 0.0011, -0.0236, 0.0064, 0.9961]
 Time: 785.3s
 MAE: 0.0660, MSE: 0.0259, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0004, -0.0089, -0.0063, 0.0037, -0.0326, -0.4169, 0.9944]
 Predicted: [0.0108, -0.0004, -0.0057, 0.0101, -0.0028, -0.0017, 0.9961]
 Time: 771.6s
 MAE: 0.0675, MSE: 0.0248, Task Success:

Sample 230: traj64

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0425, -0.0127, 0.0036, -0.0086, -0.0135, -0.0213, 0.9966]
 Predicted: [-0.0009, -0.0014, 0.0094, -0.0021, -0.0155, -0.0113, 0.0000]

⌚ Time: 752.6s
📊 MAE: 0.1536, MSE: 0.1422, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0362, -0.0250, -0.0127, -0.0053, -0.0265, -0.0368, 1.0000]
🎯 Predicted: [-0.0116, 0.0093, 0.0117, 0.0088, -0.0001, 0.0418, 0.0000]
⌚ Time: 767.9s
📊 MAE: 0.1751, MSE: 0.1444, Task Success: ✗

📸 Sample 231: traj38
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [-0.0178, -0.0160, -0.0014, 0.0080, -0.0216, -0.2720, 0.9992]
🎯 Predicted: [-0.0013, 0.0041, 0.0086, 0.0031, -0.0236, -0.0049, 0.0000]
⌚ Time: 759.7s
📊 MAE: 0.1885, MSE: 0.1529, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0223, -0.0235, -0.0058, 0.0176, -0.0361, -0.2520, 1.0000]
🎯 Predicted: [0.0014, 0.0048, -0.0002, 0.0145, -0.0061, 0.0128, 0.9961]
⌚ Time: 774.0s
📊 MAE: 0.0513, MSE: 0.0104, Task Success: ✓

📸 Sample 232: traj36
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg

Ground Truth: [0.0381, -0.0089, -0.0083, 0.0090, -0.0176, -0.3080, 0.9976]

Predicted: [0.0029, 0.0077, 0.0187, -0.0014, -0.0329, 0.0370, 0.0000]

Time: 754.2s

MAE: 0.2067, MSE: 0.1595, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0316, -0.0079, 0.0039, 0.0108, -0.0440, -0.2987, 0.9931]

Predicted: [0.0043, 0.0022, 0.0187, 0.0177, -0.0430, 0.0096, 0.0000]

Time: 759.5s

MAE: 0.1945, MSE: 0.1546, Task Success:

Sample 233: traj31

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0097, -0.0134, -0.0009, 0.0041, -0.0149, -0.1550, 1.0000]

Predicted: [0.0014, -0.0037, 0.0005, -0.0059, -0.0015, -0.0339, 0.0000]

Time: 746.8s

MAE: 0.1667, MSE: 0.1450, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0064, -0.0056, 0.0001, 0.0101, -0.0350, -0.1697, 1.0000]

Predicted: [0.0000, 0.0051, 0.0231, 0.0241, -0.0309, 0.0306, 0.0000]

Time: 750.1s

MAE: 0.1798, MSE: 0.1487, Task Success:

Sample 234: traj65

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [-0.0254, -0.0038, -0.0063, 0.0002, -0.0225, 0.7434, 1.0000]
Predicted: [-0.0007, 0.0035, -0.0010, -0.0116, -0.0061, 0.0015, 0.9961]
Time: 759.5s
MAE: 0.1159, MSE: 0.0788, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [-0.0207, 0.0047, -0.0044, 0.0026, -0.0407, 0.7269, 1.0000]
Predicted: [-0.0013, 0.0022, 0.0159, 0.0088, -0.0249, 0.0128, 0.9961]
Time: 751.1s
MAE: 0.1118, MSE: 0.0730, Task Success: ✓

📸 Sample 235: traj62

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [0.0008, -0.0022, -0.0046, 0.0009, -0.0122, 0.2337, 0.9986]
Predicted: [0.0002, -0.0001, -0.0073, 0.0171, 0.0253, -0.0178, 0.9961]
Time: 746.3s
MAE: 0.0447, MSE: 0.0093, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [-0.0030, 0.0121, -0.0284, 0.0089, -0.0382, 0.2168, 1.0000]
Predicted: [-0.0013, -0.0004, -0.0057, 0.0005, 0.0207, -0.0001, 0.9961]
Time: 748.9s
MAE: 0.0464, MSE: 0.0073, Task Success: ✓

📸 Sample 236: traj54

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0044, 0.0557, 0.0086, -0.0028, -0.0229, 0.0247, 0.9902]
 Predicted: [-0.0031, 0.0077, 0.0161, -0.0499, -0.0517, 0.0144, 0.0000]
 Time: 757.6s
 MAE: 0.1619, MSE: 0.1409, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0011, 0.0605, 0.0035, -0.0103, -0.0460, 0.0339, 1.0000]
 Predicted: [-0.0065, -0.0004, 0.0146, -0.0008, -0.0336, 0.0112, 0.0000]
 Time: 769.5s
 MAE: 0.1603, MSE: 0.1435, Task Success: 

Sample 237: traj53

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0228, -0.0207, -0.0086, 0.0111, -0.0387, 0.2405, 1.0000]
 Predicted: [0.0014, -0.0186, 0.0187, -0.0321, -0.0463, -0.0549, 0.9961]
 Time: 754.2s
 MAE: 0.0577, MSE: 0.0129, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0149, -0.0058, -0.0069, 0.0135, -0.0545, 0.2313, 1.0000]
 Predicted: [0.0007, 0.0057, -0.0052, 0.0133, -0.0135, 0.0322, 0.9961]
 Time: 751.5s
 MAE: 0.0390, MSE: 0.0060, Task Success: 

Sample 238: traj3

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0137, 0.0283, -0.0033, -0.0040, -0.0305, -0.6301, 1.0000]
 Predicted: [0.0090, -0.0075, -0.0093, -0.0065, 0.0106, -0.0033, 0.9961]
 Time: 761.9s
 MAE: 0.1056, MSE: 0.0566, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0237, 0.0385, -0.0019, -0.0033, -0.0482, -0.6168, 0.9992]
 Predicted: [0.0096, -0.0050, -0.0047, 0.0024, -0.0075, -0.0065, 0.9961]
 Time: 752.9s
 MAE: 0.1056, MSE: 0.0539, Task Success:

Sample 239: traj4

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0027, 0.0396, 0.0023, -0.0110, -0.0157, -0.4791, 0.9955]
 Predicted: [-0.0002, 0.0044, -0.0010, 0.0139, -0.0068, 0.0080, 0.9961]
 Time: 757.9s
 MAE: 0.0804, MSE: 0.0342, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0051, 0.0401, 0.0045, -0.0161, -0.0284, -0.4611, 1.0000]
 Predicted: [0.0002, -0.0001, 0.0000, -0.0027, -0.0021, 0.0048, 0.9961]
 Time: 747.7s
 MAE: 0.0799, MSE: 0.0314, Task Success:

📸 Sample 240: traj5

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [0.0293, -0.0155, 0.0031, 0.0114, -0.0325, 0.2811, 0.9960]

🎯 Predicted: [0.0083, 0.0070, 0.0138, 0.0458, -0.0195, 0.0032, 0.0000]

⌚ Time: 752.3s

📊 MAE: 0.1965, MSE: 0.1531, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [0.0255, -0.0156, 0.0021, 0.0241, -0.0378, 0.2595, 0.9959]

🎯 Predicted: [0.0083, 0.0035, 0.0231, 0.0458, 0.0052, -0.0629, 0.0000]

⌚ Time: 739.8s

📊 MAE: 0.2058, MSE: 0.1570, Task Success: ✗

📸 Sample 241: traj2

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [-0.0072, 0.0076, 0.0017, 0.0038, -0.0314, -0.4471, 0.9976]

🎯 Predicted: [0.0134, 0.0154, -0.0002, 0.0094, -0.0202, 0.0499, 0.0000]

⌚ Time: 751.5s

📊 MAE: 0.2203, MSE: 0.1776, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [-0.0084, 0.0044, 0.0034, -0.0042, -0.0341, -0.4256, 0.9951]

🎯 Predicted: [0.0114, 0.0057, -0.0083, 0.0050, -0.0390, -0.0549, 0.9961]

⌚ Time: 748.7s

 MAE: 0.0598, MSE: 0.0197, Task Success: 

 Sample 242: traj49

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0033, 0.0143, -0.0031, -0.0012, -0.0153, -0.5452, 0.9971]

 Predicted: [-0.0024, -0.0147, 0.0104, -0.0333, -0.0336, -0.0404, 0.9961]

 Time: 760.0s

 MAE: 0.0864, MSE: 0.0368, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0081, 0.0159, -0.0094, -0.0111, -0.0368, -0.5295, 1.0000]

 Predicted: [0.0094, -0.0218, 0.0003, -0.0333, -0.0182, -0.0726, 0.9961]

 Time: 753.8s

 MAE: 0.0786, MSE: 0.0302, Task Success: 

 Sample 243: traj40

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [-0.0046, 0.0297, -0.0054, -0.0156, -0.0243, -0.9960, 0.9859]

 Predicted: [0.0036, 0.0002, 0.0156, 0.0107, -0.0390, 0.0338, 0.9961]

 Time: 759.7s

 MAE: 0.1628, MSE: 0.1518, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0083, 0.0248, 0.0026, -0.0063, -0.0420, -0.9663, 1.0000]

🎯 Predicted: [-0.0065, -0.0050, -0.0158, -0.0110, -0.0148, -0.0436, 0.9961]
⌚ Time: 752.2s
📊 MAE: 0.1459, MSE: 0.1219, Task Success: ✓

📸 Sample 244: traj47

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✅ Ground Truth: [-0.0168, -0.0100, 0.0010, 0.0101, -0.0257, 0.9688, 1.0000]

🎯 Predicted: [0.0130, -0.0066, -0.0096, -0.0193, -0.0008, -0.0162, 0.0000]

⌚ Time: 764.8s

📊 MAE: 0.2976, MSE: 0.2818, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✅ Ground Truth: [-0.0262, -0.0020, 0.0052, 0.0110, -0.0432, 0.9517, 0.9975]

🎯 Predicted: [-0.0051, 0.0116, 0.0122, 0.0101, -0.0497, 0.0435, 0.0000]

⌚ Time: 751.0s

📊 MAE: 0.2792, MSE: 0.2601, Task Success: ✗

📸 Sample 245: traj13

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✅ Ground Truth: [0.0341, -0.0217, 0.0047, 0.0055, -0.0255, -0.4553, 1.0000]

🎯 Predicted: [0.0078, -0.0095, 0.0335, 0.0618, -0.0256, -0.0420, 0.9961]

⌚ Time: 748.9s

📊 MAE: 0.0773, MSE: 0.0251, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg
 Ground Truth: [0.0289, -0.0186, -0.0100, 0.0129, -0.0335, -0.4536, 0.9988]
 Predicted: [-0.0027, 0.0038, -0.0078, 0.0254, -0.0115, -0.0162, 0.9961]
 Time: 759.0s
 MAE: 0.0758, MSE: 0.0276, Task Success: 

 Sample 246: traj14
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0110, 0.0152, -0.0022, -0.0102, -0.0394, -0.5189, 1.0000]
 Predicted: [-0.0074, 0.0018, 0.0203, 0.0152, -0.0162, 0.0225, 0.0000]
 Time: 766.9s
 MAE: 0.2349, MSE: 0.1850, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0118, 0.0176, 0.0040, -0.0196, -0.0556, -0.5156, 0.9935]
 Predicted: [0.0016, -0.0134, 0.0179, 0.0075, -0.0343, -0.0339, 0.0000]
 Time: 743.6s
 MAE: 0.2255, MSE: 0.1745, Task Success: 

 Sample 247: traj22
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0088, 0.0079, -0.0049, 0.0015, -0.0253, 0.6076, 1.0000]
 Predicted: [-0.0042, 0.0054, -0.0015, 0.0018, -0.0148, -0.0017, 0.9961]
 Time: 747.5s
 MAE: 0.0918, MSE: 0.0531, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0156, 0.0061, 0.0054, 0.0052, -0.0377, 0.5945, 1.0000]
 Predicted: [0.0058, 0.0041, -0.0065, 0.0101, -0.0303, -0.0162, 0.9961]
 Time: 750.3s
 MAE: 0.0929, MSE: 0.0533, Task Success: 

Sample 248: traj25

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0215, -0.0618, 0.0034, 0.0076, -0.0216, 0.9302, 0.9873]
 Predicted: [-0.0027, -0.0007, -0.0036, -0.0161, -0.0102, -0.0226, 0.0000]
 Time: 764.2s
 MAE: 0.2954, MSE: 0.2697, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0166, -0.0725, -0.0100, 0.0104, -0.0359, 0.9154, 0.9960]
 Predicted: [-0.0087, 0.0145, 0.0257, -0.0340, -0.0463, 0.0435, 0.9961]
 Time: 770.9s
 MAE: 0.1536, MSE: 0.1103, Task Success: 

Sample 249: traj46

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0067, -0.0376, -0.0031, 0.0111, -0.0209, 0.3737, 1.0000]
 Predicted: [0.0020, 0.0041, -0.0054, 0.0024, -0.0148, 0.0064, 0.9961]
 Time: 739.2s
 MAE: 0.0621, MSE: 0.0195, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0124, -0.0409, 0.0096, 0.0179, -0.0358, 0.3681, 1.0000]
 Predicted: [0.0083, -0.0017, -0.0093, -0.0014, 0.0106, -0.0065, 0.9961]
 Time: 763.5s
 MAE: 0.0724, MSE: 0.0207, Task Success:

Sample 250: traj41

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0152, 0.0267, 0.0085, -0.0026, -0.0241, 0.4828, 1.0000]
 Predicted: [-0.0040, 0.0038, 0.0000, -0.0174, 0.0173, 0.0128, 0.9961]
 Time: 742.0s
 MAE: 0.0830, MSE: 0.0320, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0167, 0.0237, 0.0016, -0.0032, -0.0373, 0.4700, 1.0000]
 Predicted: [-0.0040, 0.0057, 0.0018, -0.0231, -0.0195, 0.0128, 0.9961]
 Time: 767.3s
 MAE: 0.0768, MSE: 0.0301, Task Success:

Sample 251: traj48

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0429, -0.0212, 0.0014, 0.0068, -0.0216, -0.8783, 1.0000]
 Predicted: [0.0029, 0.0090, 0.0338, -0.0091, -0.0423, 0.0547, 0.9961]
 Time: 781.2s

📊 MAE: 0.1537, MSE: 0.1250, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0382, -0.0194, 0.0026, 0.0194, -0.0258, -0.8652, 1.0000]
🎯 Predicted: [0.0065, -0.0014, -0.0018, -0.0072, -0.0256, -0.0130, 0.0000]
⌚ Time: 837.3s
📊 MAE: 0.2761, MSE: 0.2469, Task Success: ✗

📸 Sample 252: traj24
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0139, 0.0597, 0.0017, -0.0056, -0.0210, 0.3092, 1.0000]
🎯 Predicted: [-0.0065, -0.0014, 0.0148, -0.0027, -0.0296, 0.0161, 0.0000]
⌚ Time: 780.5s
📊 MAE: 0.1999, MSE: 0.1558, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0291, 0.0673, 0.0089, 0.0008, -0.0326, 0.3011, 1.0000]
🎯 Predicted: [-0.0016, -0.0092, 0.0018, 0.0075, 0.0079, -0.0146, 0.0000]
⌚ Time: 784.6s
📊 MAE: 0.2110, MSE: 0.1583, Task Success: ✗

📸 Sample 253: traj23
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0340, -0.0422, 0.0063, 0.0111, -0.0321, 0.8428, 0.9989]

🎯 Predicted: [0.0014, -0.0325, -0.0057, -0.0512, 0.0019, -0.0919, 0.0000]

⌚ Time: 786.1s

📊 MAE: 0.2978, MSE: 0.2683, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [0.0445, -0.0327, -0.0033, 0.0137, -0.0348, 0.8409, 0.9996]

🎯 Predicted: [-0.0054, 0.0171, 0.0115, 0.0145, 0.0086, 0.0918, 0.0000]

⌚ Time: 753.1s

📊 MAE: 0.2725, MSE: 0.2239, Task Success: ✗

📸 Sample 254: traj15

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0014, 0.0080, -0.0001, 0.0089, -0.0320, -0.5439, 1.0000]

🎯 Predicted: [-0.0009, -0.0082, 0.0263, 0.0420, -0.0437, 0.0596, 0.9961]

⌚ Time: 783.0s

📊 MAE: 0.0996, MSE: 0.0523, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [0.0134, 0.0138, 0.0046, 0.0191, -0.0352, -0.5368, 0.9938]

🎯 Predicted: [0.0101, -0.0040, -0.0049, 0.0005, -0.0349, -0.0581, 0.9961]

⌚ Time: 761.1s

📊 MAE: 0.0758, MSE: 0.0328, Task Success: ✓

📸 Sample 255: traj12

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg
 Ground Truth: [-0.0197, -0.0123, -0.0095, 0.0001, -0.0447, 0.0105, 1.0000]
 Predicted: [0.0090, 0.0070, -0.0034, 0.0018, -0.0008, 0.0080, 0.0000]
 Time: 769.1s
 MAE: 0.1575, MSE: 0.1433, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0159, -0.0007, 0.0066, 0.0008, -0.0585, 0.0037, 0.9961]
 Predicted: [-0.0002, 0.0018, 0.0000, 0.0069, -0.0015, -0.0033, 0.9961]
 Time: 769.0s
 MAE: 0.0136, MSE: 0.0005, Task Success: 

 Sample 256: traj56
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0148, 0.0289, -0.0009, -0.0045, -0.0261, -0.1100, 0.9896]
 Predicted: [0.0078, 0.0161, 0.0260, -0.0123, -0.0537, 0.0451, 0.9961]
 Time: 763.1s
 MAE: 0.0370, MSE: 0.0038, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0192, 0.0267, 0.0012, -0.0139, -0.0620, -0.1098, 0.9932]
 Predicted: [-0.0011, 0.0070, 0.0252, 0.0216, -0.0711, 0.0418, 0.9961]
 Time: 776.9s
 MAE: 0.0373, MSE: 0.0037, Task Success: 

 Sample 257: traj51
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0033, -0.0195, -0.0026, 0.0038, -0.0517, 0.7023, 0.9968]
 Predicted: [-0.0074, 0.0161, -0.0062, 0.0356, 0.0776, 0.0870, 0.0000]
 Time: 771.5s
 MAE: 0.2595, MSE: 0.1987, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0150, -0.0215, 0.0090, 0.0092, -0.0621, 0.6859, 1.0000]
 Predicted: [-0.0024, 0.0174, -0.0010, 0.0184, -0.0637, 0.0257, 0.0000]
 Time: 758.5s
 MAE: 0.2475, MSE: 0.2054, Task Success: 

Sample 258: traj67

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0106, -0.0108, 0.0022, 0.0243, -0.0295, -0.3237, 0.9978]
 Predicted: [-0.0056, 0.0054, 0.0078, -0.0148, -0.0282, 0.0080, 0.9961]
 Time: 754.1s
 MAE: 0.0572, MSE: 0.0160, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0026, -0.0065, 0.0003, 0.0321, -0.0449, -0.3117, 0.9892]
 Predicted: [-0.0016, 0.0002, 0.0143, -0.0008, -0.0236, 0.0112, 0.9961]
 Time: 777.4s
 MAE: 0.0584, MSE: 0.0152, Task Success: 

Sample 259: traj58

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0040, -0.0346, 0.0078, 0.0075, -0.0244, 0.0456, 1.0000]
 Predicted: [0.0029, 0.0009, -0.0023, 0.0177, -0.0215, 0.0080, 0.9961]
 Time: 780.6s
 MAE: 0.0153, MSE: 0.0004, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0023, -0.0258, 0.0015, 0.0129, -0.0480, 0.0274, 0.9913]
 Predicted: [0.0029, 0.0005, -0.0002, 0.0088, -0.0189, 0.0080, 0.9961]
 Time: 761.1s
 MAE: 0.0130, MSE: 0.0003, Task Success:

Sample 260: traj60

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0368, -0.0217, -0.0078, 0.0035, -0.0304, 0.0231, 1.0000]
 Predicted: [0.0007, 0.0005, -0.0114, 0.0024, 0.0253, -0.0162, 0.9961]
 Time: 786.3s
 MAE: 0.0232, MSE: 0.0009, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0397, -0.0328, 0.0047, 0.0206, -0.0356, 0.0268, 0.9973]
 Predicted: [0.0029, 0.0002, -0.0109, -0.0021, 0.0006, 0.0080, 0.9961]
 Time: 778.0s
 MAE: 0.0235, MSE: 0.0007, Task Success:

📸 Sample 261: traj34

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [0.0181, 0.0542, 0.0011, 0.0012, -0.0206, -0.9295, 0.9929]

⌚ Predicted: [-0.0009, -0.0056, 0.0198, -0.0397, 0.0052, 0.0112, 0.0000]

⌚ Time: 772.2s

📊 MAE: 0.2997, MSE: 0.2682, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [0.0104, 0.0344, 0.0021, -0.0006, -0.0417, -0.8896, 1.0000]

⌚ Predicted: [0.0029, -0.0134, 0.0276, -0.0397, -0.0785, -0.0259, 0.0000]

⌚ Time: 772.2s

📊 MAE: 0.2886, MSE: 0.2503, Task Success: ✗

📸 Sample 262: traj33

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [-0.0106, 0.0052, -0.0088, -0.0052, -0.0353, 0.0416, 1.0000]

⌚ Predicted: [0.0002, 0.0154, 0.0034, -0.0244, 0.0146, -0.1709, 0.0000]

⌚ Time: 772.7s

📊 MAE: 0.1879, MSE: 0.1498, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [-0.0142, 0.0007, 0.0050, -0.0013, -0.0635, 0.0409, 1.0000]

⌚ Predicted: [-0.0009, 0.0161, 0.0034, 0.0043, -0.0068, 0.0902, 0.0000]

Time: 793.0s
 MAE: 0.1631, MSE: 0.1437, Task Success: X

Sample 263: traj61

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [0.0450, -0.0180, 0.0010, 0.0023, -0.0181, 0.9102, 0.9965]

Predicted: [-0.0031, 0.0077, 0.0104, 0.0082, 0.0093, 0.0805, 0.0000]

Time: 767.2s

MAE: 0.2775, MSE: 0.2407, Task Success: X

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0427, -0.0193, -0.0020, 0.0059, -0.0435, 0.8968, 0.9999]

Predicted: [0.0027, 0.0054, 0.0361, 0.0037, -0.0765, 0.0418, 0.0000]

Time: 781.0s

MAE: 0.2847, MSE: 0.2479, Task Success: X

Sample 264: traj66

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [0.0142, -0.0352, -0.0052, 0.0101, -0.0103, 0.6822, 1.0000]

Predicted: [-0.0031, -0.0092, 0.0125, 0.0267, -0.0396, 0.0499, 0.0000]

Time: 783.6s

MAE: 0.2485, MSE: 0.2003, Task Success: X

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

✓ Ground Truth: [0.0127, -0.0286, 0.0033, 0.0088, -0.0402, 0.6590, 0.9902]
⌚ Predicted: [-0.0031, 0.0038, -0.0002, 0.0050, 0.0160, 0.0257, 0.9961]
⌚ Time: 786.1s
📊 MAE: 0.1073, MSE: 0.0579, Task Success: ✓

📸 Sample 265: traj59

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0084, 0.0185, -0.0010, 0.0063, -0.0535, -0.3103, 1.0000]
⌚ Predicted: [-0.0065, 0.0012, 0.0179, 0.0452, -0.0081, 0.0080, 0.0000]
⌚ Time: 777.0s
📊 MAE: 0.2058, MSE: 0.1579, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0086, 0.0255, 0.0037, 0.0191, -0.0712, -0.2978, 0.9989]
⌚ Predicted: [-0.0004, 0.0009, 0.0060, -0.0167, -0.0202, 0.0064, 0.0000]
⌚ Time: 765.3s
📊 MAE: 0.2036, MSE: 0.1564, Task Success: ✗

📸 Sample 266: traj50

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0183, 0.0239, 0.0084, -0.0060, -0.0166, 0.5453, 1.0000]
⌚ Predicted: [-0.0011, 0.0041, 0.0146, 0.0209, -0.0336, 0.0306, 0.9961]
⌚ Time: 771.9s
📊 MAE: 0.0865, MSE: 0.0381, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)

Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [-0.0121, 0.0179, 0.0070, -0.0134, -0.0393, 0.5330, 0.9927]
Predicted: [0.0034, 0.0031, -0.0002, 0.0184, -0.0249, 0.0080, 0.9961]
Time: 746.9s
MAE: 0.0874, MSE: 0.0396, Task Success: ✓

 Sample 267: traj57

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [0.0190, -0.0768, -0.0009, 0.0091, -0.0174, 0.0200, 1.0000]
Predicted: [0.0074, -0.0017, -0.0080, 0.0075, -0.0182, -0.0194, 0.9961]
Time: 760.7s
MAE: 0.0199, MSE: 0.0011, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [0.0224, -0.0682, -0.0033, 0.0115, -0.0394, 0.0133, 0.9990]
Predicted: [0.0054, 0.0015, 0.0016, 0.0222, -0.0215, -0.0017, 0.9961]
Time: 764.8s
MAE: 0.0197, MSE: 0.0008, Task Success: ✗

 Sample 268: traj68

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [0.0113, 0.0083, 0.0051, 0.0023, -0.0279, -0.3453, 0.9996]
Predicted: [-0.0013, 0.0041, 0.0000, 0.0031, -0.0008, 0.0048, 0.9961]
Time: 762.5s
MAE: 0.0576, MSE: 0.0176, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0145, 0.0096, 0.0074, -0.0096, -0.0461, -0.3434, 1.0000]
 Predicted: [-0.0013, 0.0041, 0.0000, -0.0027, -0.0008, 0.0048, 0.9961]
 Time: 760.0s
 MAE: 0.0619, MSE: 0.0177, Task Success:

Sample 269: traj32

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0009, -0.0157, -0.0036, -0.0088, -0.0365, -0.1496, 0.9968]
 Predicted: [0.0065, -0.0179, 0.0231, 0.0152, -0.0611, -0.0436, 0.0000]
 Time: 760.7s
 MAE: 0.1697, MSE: 0.1438, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0017, -0.0145, -0.0022, 0.0011, -0.0493, -0.1517, 0.9947]
 Predicted: [0.0002, 0.0018, -0.0036, 0.0011, -0.0195, -0.0017, 0.9961]
 Time: 767.5s
 MAE: 0.0286, MSE: 0.0034, Task Success:

Sample 270: traj35

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0111, -0.0469, 0.0057, 0.0091, -0.0377, -0.0327, 0.9983]
 Predicted: [0.0085, 0.0054, -0.0002, 0.0024, -0.0423, -0.0017, 0.9961]
 Time: 1681.6s
 MAE: 0.0150, MSE: 0.0005, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0001, -0.0465, -0.0034, 0.0110, -0.0456, -0.0349, 0.9971]
 Predicted: [0.0087, 0.0022, -0.0057, 0.0120, -0.0028, -0.0017, 0.9961]
 Time: 783.5s
 MAE: 0.0197, MSE: 0.0008, Task Success:

Sample 271: traj9

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0411, 0.0014, -0.0030, 0.0056, -0.0412, 0.1170, 1.0000]
 Predicted: [-0.0027, -0.0085, -0.0093, -0.0040, -0.0055, -0.0178, 0.9961]
 Time: 761.5s
 MAE: 0.0341, MSE: 0.0030, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0292, -0.0060, 0.0005, 0.0036, -0.0735, 0.1049, 1.0000]
 Predicted: [0.0083, -0.0043, -0.0093, 0.0018, -0.0075, -0.1000, 0.9961]
 Time: 771.0s
 MAE: 0.0465, MSE: 0.0068, Task Success:

Sample 272: traj7

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0061, 0.0266, -0.0047, -0.0005, -0.0235, -0.6790, 0.9969]
 Predicted: [0.0083, 0.0158, 0.0218, 0.0145, -0.0423, 0.0483, 0.0000]

⌚ Time: 752.9s
📊 MAE: 0.2568, MSE: 0.2178, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0088, 0.0240, 0.0018, 0.0051, -0.0229, -0.6567, 1.0000]
🎯 Predicted: [0.0002, 0.0038, 0.0231, 0.0452, -0.0524, 0.0418, 0.0000]
⌚ Time: 746.4s
📊 MAE: 0.2597, MSE: 0.2130, Task Success: ✗

📸 Sample 273: traj0
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [-0.0028, -0.0266, 0.0017, 0.0072, -0.0213, 0.5659, 0.9966]
🎯 Predicted: [0.0014, 0.0022, 0.0057, 0.0005, 0.0012, 0.0048, 0.0000]
⌚ Time: 748.7s
📊 MAE: 0.2320, MSE: 0.1871, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0027, -0.0257, -0.0058, 0.0210, -0.0400, 0.5553, 0.9970]
🎯 Predicted: [-0.0089, 0.0077, -0.0015, 0.0816, 0.0260, 0.0741, 0.0000]
⌚ Time: 761.5s
📊 MAE: 0.2355, MSE: 0.1764, Task Success: ✗

📸 Sample 274: traj1
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg

Ground Truth: [-0.0099, 0.0525, -0.0138, 0.0001, -0.0403, -0.0703, 1.0000]

Predicted: [0.0108, -0.0111, 0.0151, -0.0014, -0.0296, -0.0226, 0.9961]

Time: 1044.8s

MAE: 0.0253, MSE: 0.0011, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0102, 0.0549, -0.0076, -0.0091, -0.0466, -0.0634, 0.9954]

Predicted: [0.0002, -0.0105, -0.0054, -0.0193, -0.0001, -0.0549, 0.9961]

Time: 8410.8s

MAE: 0.0206, MSE: 0.0010, Task Success:

Sample 275: traj6

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0188, -0.0494, 0.0019, 0.0075, -0.0191, -0.1267, 1.0000]

Predicted: [0.0081, -0.0072, 0.0252, 0.0452, -0.0617, -0.0162, 0.9961]

Time: 1329.0s

MAE: 0.0410, MSE: 0.0026, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0091, -0.0523, 0.0039, 0.0106, -0.0391, -0.1267, 1.0000]

Predicted: [0.0083, -0.0079, 0.0309, -0.0225, -0.0691, 0.0144, 0.9961]

Time: 825.8s

MAE: 0.0424, MSE: 0.0036, Task Success:

Sample 276: traj8

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0238, 0.0119, 0.0043, 0.0209, -0.0227, -0.8472, 0.9964]

Predicted: [-0.0065, -0.0001, -0.0023, 0.0088, 0.0126, 0.0209, 0.9961]

Time: 751.0s

MAE: 0.1360, MSE: 0.1079, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0154, 0.0036, -0.0010, 0.0248, -0.0443, -0.8219, 1.0000]

Predicted: [0.0002, 0.0038, 0.0003, 0.0184, -0.0015, 0.0209, 0.9961]

Time: 743.6s

MAE: 0.1304, MSE: 0.1018, Task Success: ✓

📸 Sample 277: traj17

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [0.0097, -0.0166, -0.0020, 0.0027, -0.0188, -0.7775, 0.9952]

Predicted: [0.0096, 0.0135, -0.0083, -0.0078, -0.0055, -0.0226, 0.0000]

Time: 761.7s

MAE: 0.2586, MSE: 0.2231, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0227, -0.0183, -0.0008, 0.0028, -0.0285, -0.7704, 1.0000]

Predicted: [0.0081, 0.0070, -0.0091, 0.0152, 0.0629, -0.0355, 0.0000]

Time: 802.7s

MAE: 0.2695, MSE: 0.2213, Task Success: ✗

📸 Sample 278: traj28

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0187, 0.0656, 0.0134, -0.0049, -0.0318, 0.3641, 1.0000]
 Predicted: [0.0002, 0.0009, -0.0031, 0.0024, 0.0200, -0.0001, 0.9961]
 Time: 764.0s
 MAE: 0.0753, MSE: 0.0200, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0214, 0.0767, -0.0009, -0.0146, -0.0461, 0.3512, 0.9919]
 Predicted: [0.0002, 0.0009, -0.0078, 0.0018, 0.0200, 0.0032, 0.9961]
 Time: 756.2s
 MAE: 0.0769, MSE: 0.0189, Task Success:

Sample 279: traj10

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0247, -0.0366, -0.0067, -0.0020, -0.0268, 0.8570, 1.0000]
 Predicted: [-0.0007, -0.0143, 0.0198, 0.0088, -0.0550, -0.0226, 0.9961]
 Time: 756.5s
 MAE: 0.1422, MSE: 0.1109, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0168, -0.0244, -0.0074, -0.0085, -0.0408, 0.8361, 0.9971]
 Predicted: [0.0014, 0.0061, -0.0010, 0.0126, 0.0012, -0.0097, 0.9961]
 Time: 4326.8s
 MAE: 0.1378, MSE: 0.1027, Task Success:

Sample 280: traj26

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0197, -0.0007, 0.0049, 0.0061, -0.0339, 0.7407, 1.0000]
 Predicted: [-0.0076, 0.0018, 0.0231, 0.0177, -0.0148, -0.0001, 0.0000]
 Time: 763.0s
 MAE: 0.2599, MSE: 0.2215, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0219, -0.0123, -0.0049, 0.0035, -0.0368, 0.7188, 1.0000]
 Predicted: [-0.0065, -0.0004, 0.0089, -0.0014, 0.0086, -0.0516, 0.0000]
 Time: 768.3s
 MAE: 0.2678, MSE: 0.2281, Task Success: ✗

Sample 281: traj19

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0301, 0.0243, 0.0041, -0.0081, -0.0162, -0.4444, 0.9931]
 Predicted: [-0.0045, 0.0180, -0.0015, 0.0816, 0.0776, 0.0112, 0.0000]
 Time: 769.2s
 MAE: 0.2398, MSE: 0.1731, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0260, 0.0143, -0.0003, -0.0116, -0.0372, -0.4266, 0.9978]
 Predicted: [0.0085, -0.0098, -0.0065, -0.0148, -0.0035, -0.0081, 0.0000]
 Time: 755.1s
 MAE: 0.2145, MSE: 0.1676, Task Success: ✗

📸 Sample 282: traj21

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [-0.0111, -0.0202, -0.0031, 0.0037, -0.0204, 0.2746, 1.0000]

🎯 Predicted: [-0.0060, -0.0173, -0.0015, -0.0225, 0.0059, -0.0500, 0.0000]

⌚ Time: 760.8s

📊 MAE: 0.1981, MSE: 0.1581, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [-0.0038, -0.0203, 0.0077, 0.0125, -0.0461, 0.2467, 1.0000]

🎯 Predicted: [-0.0049, -0.0186, -0.0015, 0.0356, 0.0140, 0.2030, 0.0000]

⌚ Time: 765.4s

📊 MAE: 0.1627, MSE: 0.1437, Task Success: ✗

📸 Sample 283: traj44

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [0.0259, -0.0483, 0.0029, 0.0129, -0.0341, -0.9760, 0.9972]

🎯 Predicted: [0.0000, 0.0051, 0.0361, 0.0452, -0.0617, 0.0709, 0.0000]

⌚ Time: 763.1s

📊 MAE: 0.3167, MSE: 0.2995, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [0.0159, -0.0482, -0.0009, 0.0309, -0.0383, -0.9731, 1.0000]

🎯 Predicted: [-0.0051, -0.0004, 0.0166, -0.0014, -0.0148, 0.0257, 0.9961]

⌚ Time: 760.2s

📊 MAE: 0.1636, MSE: 0.1432, Task Success: ✗

📸 Sample 284: traj43

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [0.0079, 0.0077, -0.0053, 0.0011, -0.0259, -0.5634, 0.9967]

🎯 Predicted: [0.0005, 0.0054, -0.0008, 0.0050, -0.0061, 0.0177, 0.9961]

⌚ Time: 749.5s

📊 MAE: 0.0885, MSE: 0.0483, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [0.0065, 0.0019, 0.0048, 0.0094, -0.0453, -0.5586, 0.9984]

🎯 Predicted: [0.0000, 0.0018, 0.0034, 0.0101, 0.0126, 0.0209, 0.9961]

⌚ Time: 760.6s

📊 MAE: 0.0926, MSE: 0.0485, Task Success: ✓

📸 Sample 285: traj20

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [0.0285, 0.0542, -0.0030, 0.0029, -0.0152, 0.2553, 1.0000]

🎯 Predicted: [-0.0065, -0.0050, 0.0140, 0.0062, -0.0289, -0.0178, 0.0000]

⌚ Time: 750.9s

📊 MAE: 0.2002, MSE: 0.1543, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [0.0476, 0.0521, 0.0064, -0.0066, -0.0314, 0.2290, 0.9997]

🎯 Predicted: [-0.0027, 0.0038, 0.0268, -0.0225, -0.0570, 0.0144, 0.0000]

⌚ Time: 744.8s

📊 MAE: 0.1964, MSE: 0.1502, Task Success: ✗

📸 Sample 286: traj27

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0220, -0.0356, -0.0049, 0.0157, -0.0250, 0.6651, 0.9896]

🎯 Predicted: [-0.0033, -0.0020, 0.0276, 0.0216, -0.0617, -0.0081, 0.9961]

⌚ Time: 753.1s

📊 MAE: 0.1162, MSE: 0.0654, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [0.0268, -0.0356, 0.0042, 0.0170, -0.0435, 0.6563, 1.0000]

🎯 Predicted: [-0.0031, 0.0028, -0.0039, -0.0219, -0.0088, 0.0064, 0.9961]

⌚ Time: 762.2s

📊 MAE: 0.1148, MSE: 0.0611, Task Success: ✓

📸 Sample 287: traj18

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0282, 0.0249, -0.0051, 0.0036, -0.0201, -0.0720, 0.9962]

🎯 Predicted: [0.0018, 0.0009, -0.0008, -0.0033, -0.0115, 0.0225, 0.0000]

⌚ Time: 742.6s

📊 MAE: 0.1659, MSE: 0.1433, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg
 Ground Truth: [0.0250, 0.0123, -0.0001, 0.0003, -0.0469, -0.0671, 0.9993]
 Predicted: [0.0002, -0.0007, 0.0000, -0.0052, -0.0008, -0.0081, 0.0000]
 Time: 761.1s
 MAE: 0.1640, MSE: 0.1436, Task Success: X

 Sample 288: traj11

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0006, 0.0199, -0.0015, 0.0027, -0.0152, -0.6705, 0.9951]

 Predicted: [-0.0013, 0.0018, 0.0021, -0.0084, -0.0001, 0.0064, 0.0000]

 Time: 749.5s

 MAE: 0.2460, MSE: 0.2070, Task Success: X

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0041, 0.0195, -0.0045, 0.0005, -0.0302, -0.6451, 0.9928]

 Predicted: [-0.0018, 0.0057, 0.0190, 0.0331, -0.0202, 0.0112, 0.0000]

 Time: 750.1s

 MAE: 0.2478, MSE: 0.2026, Task Success: X

 Sample 289: traj16

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [-0.0081, 0.0016, -0.0036, 0.0037, -0.0333, -0.7314, 1.0000]

 Predicted: [0.0061, 0.0268, -0.0091, 0.0120, -0.0249, 0.0418, 0.9961]

 Time: 776.4s

 MAE: 0.1198, MSE: 0.0856, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0050, 0.0083, 0.0073, 0.0090, -0.0527, -0.7282, 0.9959]
 Predicted: [0.0157, 0.0083, -0.0031, 0.0254, -0.0135, 0.0193, 0.9961]
 Time: 755.9s
 MAE: 0.1192, MSE: 0.0801, Task Success: 

Sample 290: traj29

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0003, -0.0138, -0.0025, 0.0039, -0.0358, 0.4553, 1.0000]
 Predicted: [0.0027, 0.0035, 0.0229, 0.0254, -0.0617, 0.0418, 0.0000]
 Time: 756.5s
 MAE: 0.2151, MSE: 0.1676, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0010, -0.0088, -0.0009, 0.0113, -0.0512, 0.4396, 0.9979]
 Predicted: [0.0081, -0.0134, 0.0166, 0.0075, -0.0524, -0.0371, 0.0000]
 Time: 741.4s
 MAE: 0.2158, MSE: 0.1748, Task Success: 

Sample 291: traj42

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0046, -0.0105, 0.0016, 0.0048, -0.0169, 0.4101, 1.0000]
 Predicted: [-0.0029, -0.0001, -0.0062, 0.0018, 0.0294, -0.0049, 0.9961]
 Time: 765.2s
 MAE: 0.0706, MSE: 0.0249, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0019, -0.0114, 0.0022, 0.0058, -0.0370, 0.4009, 1.0000]
 Predicted: [0.0011, 0.0164, 0.0016, 0.0094, -0.0135, 0.0644, 0.9961]
 Time: 751.3s
 MAE: 0.0570, MSE: 0.0164, Task Success: 

 Sample 292: traj45
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0043, 0.0212, 0.0047, -0.0047, -0.0407, -0.1562, 0.9998]
 Predicted: [0.0007, 0.0009, 0.0005, -0.0027, 0.0347, -0.0210, 0.9961]
 Time: 757.4s
 MAE: 0.0349, MSE: 0.0035, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0093, 0.0190, -0.0026, 0.0061, -0.0475, -0.1396, 0.9992]
 Predicted: [-0.0007, 0.0009, 0.0070, 0.0043, -0.0142, 0.0080, 0.9961]
 Time: 1729.3s
 MAE: 0.0319, MSE: 0.0033, Task Success: 

 Sample 293: traj216
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0012, -0.0459, 0.0005, 0.0042, -0.0206, -0.2456, 1.0000]
 Predicted: [0.0009, 0.0018, -0.0109, 0.0069, 0.0253, -0.0001, 0.9961]
 Time: 5221.7s

📊 MAE: 0.0511, MSE: 0.0093, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0025, -0.0510, 0.0054, -0.0014, -0.0342, -0.2187, 0.9913]
🎯 Predicted: [0.0027, -0.0007, -0.0080, -0.0040, -0.0028, -0.0162, 0.9961]
⌚ Time: 1176.6s
📊 MAE: 0.0436, MSE: 0.0064, Task Success: ✗

📸 Sample 294: traj30
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [-0.0017, 0.0587, 0.0030, -0.0130, -0.0258, -0.7289, 1.0000]
🎯 Predicted: [0.0110, 0.0106, 0.0083, 0.0241, -0.0236, 0.0128, 0.0000]
⌚ Time: 2628.0s
📊 MAE: 0.2639, MSE: 0.2220, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0022, 0.0484, 0.0029, -0.0049, -0.0446, -0.6623, 0.9990]
🎯 Predicted: [0.0061, -0.0092, 0.0140, 0.0241, -0.0081, -0.0323, 0.0000]
⌚ Time: 4875.2s
📊 MAE: 0.2524, MSE: 0.2001, Task Success: ✗

📸 Sample 295: traj229
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [-0.0160, 0.0202, 0.0019, 0.0038, -0.0457, -0.8651, 1.0000]

🎯 Predicted: [0.0065, 0.0022, -0.0041, 0.0069, 0.0086, 0.0080, 0.0000]
⌚ Time: 770.5s
📊 MAE: 0.2824, MSE: 0.2523, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0113, 0.0205, 0.0030, -0.0041, -0.0650, -0.8248, 0.9975]
🎯 Predicted: [-0.0024, 0.0022, -0.0008, 0.0082, 0.0408, -0.0307, 0.9961]
⌚ Time: 771.6s
📊 MAE: 0.1349, MSE: 0.0918, Task Success: ✓

📸 Sample 296: traj211
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [0.0094, -0.0487, 0.0106, 0.0158, -0.0323, 0.3187, 1.0000]
🎯 Predicted: [0.0081, 0.0112, -0.0083, 0.0094, -0.0021, 0.0273, 0.9961]
⌚ Time: 772.0s
📊 MAE: 0.0589, MSE: 0.0128, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [0.0097, -0.0374, 0.0006, 0.0097, -0.0571, 0.2875, 0.9983]
🎯 Predicted: [-0.0089, -0.0173, -0.0065, 0.0024, 0.0274, -0.0500, 0.9961]
⌚ Time: 784.6s
📊 MAE: 0.0682, MSE: 0.0174, Task Success: ✓

📸 Sample 297: traj37
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)

 Image 1: im_42.jpg
 Ground Truth: [-0.0055, 0.0141, 0.0024, 0.0064, -0.0201, 0.5816, 1.0000]
 Predicted: [0.0007, 0.0103, -0.0052, -0.0219, -0.0162, 0.0161, 0.9961]
 Time: 796.2s
 MAE: 0.0885, MSE: 0.0458, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0137, 0.0160, 0.0036, 0.0103, -0.0444, 0.5587, 1.0000]
 Predicted: [0.0036, 0.0031, -0.0130, 0.0133, 0.0113, -0.0049, 0.9961]
 Time: 797.0s
 MAE: 0.0961, MSE: 0.0459, Task Success: 

 Sample 298: traj227
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0108, 0.0494, 0.0030, -0.0002, -0.0185, 0.2972, 1.0000]
 Predicted: [0.0090, 0.0122, -0.0052, 0.0094, -0.0209, 0.0080, 0.0000]
 Time: 803.8s
 MAE: 0.1952, MSE: 0.1551, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0082, 0.0458, 0.0036, 0.0024, -0.0547, 0.2665, 0.9993]
 Predicted: [0.0074, 0.0106, -0.0065, -0.0008, -0.0356, 0.0225, 0.0000]
 Time: 794.2s
 MAE: 0.1895, MSE: 0.1514, Task Success: 

 Sample 299: traj218
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [0.0059, 0.0013, -0.0252, 0.0117, -0.0543, -0.5579, 0.9941]
🎯 Predicted: [0.0025, 0.0154, 0.0239, 0.0248, -0.0617, 0.0805, 0.9961]
 Time: 821.3s
 MAE: 0.1040, MSE: 0.0586, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [0.0076, -0.0026, -0.0091, 0.0226, -0.0648, -0.5354, 0.9991]
🎯 Predicted: [-0.0031, -0.0004, 0.0070, -0.0033, -0.0236, 0.0112, 0.9961]
 Time: 2020.4s
 MAE: 0.0923, MSE: 0.0431, Task Success: ✓

 Sample 300: traj220
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0206, -0.0115, 0.0028, -0.0024, -0.0292, 0.0620, 1.0000]
🎯 Predicted: [-0.0083, -0.0027, -0.0080, -0.0225, 0.0032, 0.0032, 0.9961]
 Time: 762.3s
 MAE: 0.0210, MSE: 0.0008, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0128, -0.0164, -0.0007, 0.0112, -0.0461, 0.0613, 0.9979]
🎯 Predicted: [0.0036, 0.0018, -0.0065, 0.0120, -0.0303, -0.0242, 0.9961]
 Time: 769.2s
 MAE: 0.0206, MSE: 0.0012, Task Success: ✓

 Sample 301: traj39
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0172, 0.0055, 0.0042, -0.0012, -0.0241, 0.5622, 1.0000]
🎯 Predicted: [-0.0007, -0.0001, -0.0021, -0.0001, -0.0028, -0.0001, 0.9961]
 Time: 760.9s
 MAE: 0.0882, MSE: 0.0453, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0203, 0.0119, 0.0022, -0.0051, -0.0490, 0.5366, 1.0000]
🎯 Predicted: [-0.0024, -0.0001, -0.0117, -0.0001, 0.0320, 0.0015, 0.9961]
 Time: 789.5s
 MAE: 0.0955, MSE: 0.0419, Task Success: ✓

Sample 302: traj52

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0297, 0.0166, 0.0011, -0.0004, -0.0166, -0.4536, 1.0000]
🎯 Predicted: [0.0076, -0.0040, 0.0008, -0.0174, -0.0081, 0.0032, 0.9961]
 Time: 770.3s
 MAE: 0.0777, MSE: 0.0301, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0234, 0.0219, 0.0088, 0.0068, -0.0468, -0.4330, 1.0000]
🎯 Predicted: [-0.0007, -0.0001, -0.0026, 0.0005, -0.0001, 0.0080, 0.9961]
 Time: 796.0s
 MAE: 0.0791, MSE: 0.0283, Task Success: ✓

Sample 303: traj274

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0100, -0.0255, 0.0072, 0.0054, -0.0259, -0.1123, 0.9957]
 Predicted: [-0.0024, -0.0007, -0.0065, -0.0091, 0.0253, -0.0017, 0.9961]
 Time: 790.6s
 MAE: 0.0325, MSE: 0.0023, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0054, -0.0226, 0.0009, 0.0124, -0.0358, -0.0957, 0.9972]
 Predicted: [-0.0004, 0.0018, -0.0080, 0.0126, -0.0303, -0.0597, 0.9961]
 Time: 852.8s
 MAE: 0.0117, MSE: 0.0003, Task Success:

Sample 304: traj99
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0364, 0.0375, -0.0069, -0.0061, -0.0227, -0.5328, 0.9996]
 Predicted: [-0.0085, -0.0082, -0.0010, 0.0165, -0.0309, 0.1063, 0.0000]
 Time: 767.1s
 MAE: 0.2499, MSE: 0.2016, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0327, 0.0365, 0.0087, -0.0125, -0.0568, -0.4696, 0.9964]
 Predicted: [-0.0029, 0.0229, 0.0091, 0.0280, -0.0336, 0.1063, 0.0000]
 Time: 752.8s
 MAE: 0.2400, MSE: 0.1897, Task Success:

Sample 305: traj280

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [-0.0086, 0.0228, -0.0038, 0.0043, -0.0312, -0.9302, 1.0000]

 Predicted: [-0.0004, 0.0038, 0.0065, 0.0005, -0.0061, 0.0128, 0.0000]

 Time: 755.7s

 MAE: 0.2871, MSE: 0.2701, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [-0.0078, 0.0160, -0.0013, 0.0065, -0.0443, -0.8853, 0.9989]

 Predicted: [-0.0022, 0.0018, -0.0008, 0.0075, 0.0113, 0.0064, 0.9961]

 Time: 788.4s

 MAE: 0.1388, MSE: 0.1141, Task Success: 

Sample 306: traj55

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [-0.0061, -0.0136, -0.0009, -0.0029, -0.0576, 0.1289, 1.0000]

 Predicted: [-0.0016, 0.0018, -0.0015, 0.0120, 0.0059, -0.0033, 0.9961]

 Time: 1007.0s

 MAE: 0.0336, MSE: 0.0031, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [-0.0110, -0.0263, 0.0037, -0.0061, -0.0783, 0.0989, 0.9968]

 Predicted: [0.0000, 0.0002, 0.0000, -0.0008, -0.0008, -0.0130, 0.0000]

Time: 764.2s
 MAE: 0.1761, MSE: 0.1447, Task Success: X

Sample 307: traj287

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [0.0204, 0.0229, -0.0010, 0.0138, -0.0313, -0.3488, 0.9920]
⌚ Predicted: [0.0067, -0.0127, 0.0234, 0.0209, -0.0785, -0.0162, 0.0000]

Time: 754.4s
 MAE: 0.2075, MSE: 0.1570, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [0.0316, 0.0293, -0.0011, 0.0216, -0.0387, -0.3112, 1.0000]
⌚ Predicted: [0.0101, 0.0086, 0.0011, 0.0133, -0.0122, 0.0273, 0.9961]
 Time: 765.0s
 MAE: 0.0602, MSE: 0.0166, Task Success: ✓

Sample 308: traj273

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [0.0212, -0.0251, -0.0001, 0.0023, -0.0291, -0.2904, 0.9984]
⌚ Predicted: [-0.0047, 0.0268, -0.0109, 0.0209, 0.0032, 0.0966, 0.9961]
 Time: 743.3s
 MAE: 0.0755, MSE: 0.0221, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg

✓ Ground Truth: [0.0156, -0.0220, 0.0054, 0.0068, -0.0475, -0.2634, 0.9940]
⌚ Predicted: [0.0031, 0.0067, -0.0008, 0.0229, -0.0262, 0.0902, 0.9961]
⌚ Time: 751.9s
📊 MAE: 0.0629, MSE: 0.0181, Task Success: ✓

📸 Sample 309: traj97

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0300, 0.0405, -0.0084, -0.0002, -0.0164, -0.0047, 1.0000]
⌚ Predicted: [-0.0024, 0.0193, -0.0088, -0.0110, -0.0195, -0.0065, 0.9961]
⌚ Time: 764.9s
📊 MAE: 0.0098, MSE: 0.0002, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0150, 0.0359, 0.0063, 0.0093, -0.0443, 0.0097, 1.0000]
⌚ Predicted: [-0.0020, -0.0040, -0.0036, -0.0276, 0.0274, -0.0194, 0.9961]
⌚ Time: 750.5s
📊 MAE: 0.0292, MSE: 0.0013, Task Success: ✓

📸 Sample 310: traj63

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0107, -0.0658, -0.0001, 0.0060, -0.0238, 0.6496, 1.0000]
⌚ Predicted: [0.0087, -0.0169, 0.0255, 0.0452, -0.0236, 0.2030, 0.0000]
⌚ Time: 754.4s
📊 MAE: 0.2257, MSE: 0.1721, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)

Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [-0.0049, -0.0548, -0.0031, 0.0221, -0.0399, 0.6147, 1.0000]
Predicted: [-0.0027, 0.0051, -0.0057, 0.0478, 0.0488, -0.0726, 0.0000]
Time: 746.1s
MAE: 0.2666, MSE: 0.2121, Task Success: ✗

📸 Sample 311: traj245

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [-0.0230, -0.0125, 0.0090, 0.0083, -0.0312, 0.4244, 0.9968]
Predicted: [0.0000, 0.0106, 0.0231, 0.0292, -0.0524, 0.0418, 0.0000]
Time: 756.9s
MAE: 0.2117, MSE: 0.1632, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [-0.0178, -0.0078, 0.0026, 0.0024, -0.0474, 0.3911, 0.9950]
Predicted: [-0.0047, 0.0022, 0.0034, 0.0075, 0.0046, 0.0096, 0.0000]
Time: 756.1s
MAE: 0.2082, MSE: 0.1626, Task Success: ✗

📸 Sample 312: traj64

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [-0.0027, -0.0122, -0.0016, -0.0001, -0.0334, 0.4523, 1.0000]
Predicted: [0.0034, 0.0005, 0.0198, 0.0075, -0.0343, 0.0128, 0.0000]
Time: 745.5s
MAE: 0.2126, MSE: 0.1706, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0038, -0.0104, 0.0075, 0.0093, -0.0468, 0.4135, 1.0000]
 Predicted: [-0.0065, 0.0038, 0.0109, 0.0209, 0.0032, 0.0161, 0.0000]
 Time: 746.8s
 MAE: 0.2124, MSE: 0.1658, Task Success: X

 Sample 313: traj289
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0012, 0.0068, 0.0022, 0.0032, -0.0408, 0.1439, 1.0000]
 Predicted: [0.0009, 0.0022, 0.0000, 0.0120, -0.0061, 0.0080, 0.0000]
 Time: 763.3s
 MAE: 0.1695, MSE: 0.1457, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0031, 0.0121, -0.0141, -0.0157, -0.0539, 0.1232, 0.9913]
 Predicted: [0.0009, 0.0022, 0.0000, 0.0120, -0.0081, 0.0096, 0.0000]
 Time: 757.3s
 MAE: 0.1721, MSE: 0.1427, Task Success: X

 Sample 314: traj90
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0223, -0.0218, 0.0020, 0.0032, -0.0327, 0.8028, 1.0000]
 Predicted: [-0.0078, -0.0059, -0.0093, -0.0187, -0.0108, -0.1467, 0.9961]
 Time: 765.9s
 MAE: 0.1506, MSE: 0.1291, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0071, -0.0183, -0.0050, 0.0071, -0.0463, 0.7673, 0.9973]
 Predicted: [-0.0078, 0.0022, -0.0158, 0.0126, 0.0146, 0.0354, 0.9961]
 Time: 756.1s
 MAE: 0.1208, MSE: 0.0772, Task Success:

Sample 315: traj242

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0134, -0.0581, 0.0015, 0.0067, -0.0200, 0.2078, 1.0000]
 Predicted: [-0.0150, 0.0216, 0.0083, 0.0024, 0.0086, 0.0435, 0.9961]
 Time: 768.6s
 MAE: 0.0413, MSE: 0.0049, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0068, -0.0615, 0.0001, 0.0040, -0.0439, 0.1709, 1.0000]
 Predicted: [-0.0058, -0.0105, -0.0109, 0.0011, -0.0061, -0.0146, 0.9961]
 Time: 764.5s
 MAE: 0.0419, MSE: 0.0055, Task Success:

Sample 316: traj38

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0033, -0.0457, -0.0015, 0.0009, -0.0260, 0.1294, 1.0000]
 Predicted: [0.0027, -0.0017, -0.0054, 0.0120, 0.0099, 0.0032, 0.9961]

⌚ Time: 762.3s
📊 MAE: 0.0330, MSE: 0.0028, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0053, -0.0354, -0.0064, 0.0024, -0.0485, 0.0871, 1.0000]
🎯 Predicted: [0.0007, 0.0015, -0.0101, 0.0120, -0.0135, -0.0146, 0.9961]
⌚ Time: 768.0s
📊 MAE: 0.0281, MSE: 0.0019, Task Success: ✓

📸 Sample 317: traj221
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0079, 0.0675, -0.0009, -0.0098, -0.0334, -0.1160, 0.9968]
🎯 Predicted: [0.0011, 0.0015, -0.0026, 0.0120, -0.0075, -0.0033, 0.9961]
⌚ Time: 787.5s
📊 MAE: 0.0337, MSE: 0.0026, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0198, 0.0711, 0.0073, -0.0136, -0.0639, -0.0709, 1.0000]
🎯 Predicted: [0.0083, -0.0004, -0.0065, -0.0027, -0.0028, -0.0065, 0.9961]
⌚ Time: 764.5s
📊 MAE: 0.0339, MSE: 0.0019, Task Success: ✗

📸 Sample 318: traj226
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg

✓ Ground Truth: [-0.0080, -0.0328, -0.0002, 0.0122, -0.0266, -0.3059, 1.0000]
🎯 Predicted: [-0.0107, -0.0114, 0.0148, -0.0263, -0.0403, -0.0355, 0.9961]
⌚ Time: 759.5s
📊 MAE: 0.0522, MSE: 0.0108, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0037, -0.0266, 0.0060, 0.0121, -0.0503, -0.2805, 0.9948]
🎯 Predicted: [-0.0051, -0.0121, -0.0002, -0.0429, 0.0140, -0.1032, 0.9961]
⌚ Time: 755.7s
📊 MAE: 0.0457, MSE: 0.0055, Task Success: ✓

📸 Sample 319: traj219
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [0.0373, -0.0527, -0.0045, 0.0120, -0.0280, 0.5307, 1.0000]
🎯 Predicted: [-0.0033, -0.0001, 0.0135, -0.0129, -0.0148, 0.0161, 0.0000]
⌚ Time: 759.3s
📊 MAE: 0.2377, MSE: 0.1815, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [0.0308, -0.0422, 0.0030, 0.0153, -0.0415, 0.4783, 1.0000]
🎯 Predicted: [-0.0056, 0.0041, 0.0000, -0.0231, 0.0173, 0.0161, 0.0000]
⌚ Time: 762.5s
📊 MAE: 0.2350, MSE: 0.1746, Task Success: ✗

📸 Sample 320: traj210
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0222, 0.0222, 0.0018, 0.0091, -0.0469, 0.3690, 1.0000]

Predicted: [0.0016, 0.0002, -0.0122, 0.0190, -0.0202, -0.0081, 0.9961]

Time: 798.2s

MAE: 0.0682, MSE: 0.0206, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0116, 0.0203, 0.0078, 0.0035, -0.0633, 0.3435, 0.9980]

Predicted: [0.0002, -0.0001, -0.0114, 0.0056, -0.0309, -0.0275, 0.9961]

Time: 1522.0s

MAE: 0.0655, MSE: 0.0199, Task Success: ✓

📸 Sample 321: traj36

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [0.0118, -0.0212, -0.0050, 0.0062, -0.0182, -0.5277, 1.0000]

Predicted: [-0.0002, -0.0007, -0.0093, -0.0001, 0.0247, -0.0049, 0.9961]

Time: 804.1s

MAE: 0.0875, MSE: 0.0394, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0219, -0.0199, 0.0054, 0.0097, -0.0301, -0.4826, 0.9961]

Predicted: [-0.0002, -0.0007, -0.0093, -0.0001, 0.0247, -0.0049, 0.9961]

Time: 4167.9s

MAE: 0.0855, MSE: 0.0332, Task Success: ✓

📸 Sample 322: traj217

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0058, -0.0012, -0.0035, -0.0010, -0.0346, -0.2659, 1.0000]
 Predicted: [-0.0031, 0.0086, 0.0011, 0.0024, -0.0035, 0.0128, 0.0000]
 Time: 28244.5s
 MAE: 0.1910, MSE: 0.1541, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0072, 0.0014, -0.0057, 0.0054, -0.0483, -0.2503, 0.9977]
 Predicted: [0.0081, 0.0038, -0.0002, 0.0024, -0.0148, -0.0017, 0.0000]
 Time: 772.8s
 MAE: 0.1845, MSE: 0.1512, Task Success: 

 Sample 323: traj228
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0006, 0.0333, 0.0075, -0.0178, -0.0290, -0.8902, 0.9901]
 Predicted: [-0.0065, 0.0012, 0.0380, 0.0382, -0.0617, 0.0064, 0.0000]
 Time: 763.7s
 MAE: 0.2920, MSE: 0.2558, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0015, 0.0294, -0.0051, -0.0167, -0.0480, -0.8757, 1.0000]
 Predicted: [0.0081, -0.0202, 0.0216, 0.0075, -0.0550, -0.0404, 0.0000]
 Time: 756.0s
 MAE: 0.2785, MSE: 0.2431, Task Success: 

 Sample 324: traj31
Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0024, 0.0258, 0.0014, -0.0103, -0.0158, -0.7188, 0.9973]
 Predicted: [0.0014, 0.0035, 0.0003, 0.0043, -0.0068, 0.0096, 0.9961]
 Time: 764.2s
 MAE: 0.1111, MSE: 0.0759, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0100, 0.0238, 0.0115, 0.0019, -0.0441, -0.6648, 0.9984]
 Predicted: [0.0014, 0.0099, 0.0000, -0.0135, 0.0052, 0.0338, 0.9961]
 Time: 753.0s
 MAE: 0.1142, MSE: 0.0702, Task Success:

Sample 325: traj91

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0040, -0.0192, 0.0035, -0.0002, -0.0370, -0.9381, 0.9964]
 Predicted: [-0.0078, 0.0054, 0.0146, 0.0094, 0.0140, -0.0194, 0.9961]
 Time: 757.1s
 MAE: 0.1467, MSE: 0.1211, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0099, -0.0159, -0.0025, -0.0067, -0.0538, -0.8995, 0.9940]
 Predicted: [0.0036, 0.0064, 0.0005, 0.0299, 0.0032, 0.0096, 0.9961]
 Time: 815.9s
 MAE: 0.1481, MSE: 0.1188, Task Success:

📸 Sample 326: traj288

Instruction: pick up the object and place it in the bowl

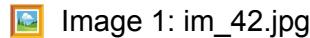
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [0.0152, 0.0408, 0.0013, 0.0080, -0.0303, 0.6578, 0.9988]

🎯 Predicted: [0.0011, -0.0024, -0.0065, -0.0212, 0.0173, -0.0452, 0.0000]



📊 MAE: 0.2634, MSE: 0.2139, Task Success: ✗

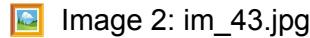
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [0.0108, 0.0449, -0.0005, 0.0022, -0.0464, 0.6165, 1.0000]

🎯 Predicted: [0.0011, 0.0145, -0.0117, -0.0084, -0.0570, 0.1563, 0.0000]



📊 MAE: 0.2190, MSE: 0.1733, Task Success: ✗

📸 Sample 327: traj65

Instruction: pick up the object and place it in the bowl

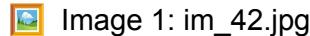
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0027, 0.0172, -0.0035, -0.0020, -0.0371, 0.7344, 1.0000]

🎯 Predicted: [0.0036, 0.0012, -0.0057, 0.0101, 0.0052, 0.0112, 0.9961]



📊 MAE: 0.1151, MSE: 0.0750, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0070, 0.0127, 0.0037, -0.0042, -0.0494, 0.7097, 0.9965]

🎯 Predicted: [0.0054, 0.0009, -0.0083, 0.0069, 0.0052, 0.0015, 0.9961]



 MAE: 0.1158, MSE: 0.0721, Task Success: 

 Sample 328: traj243

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0056, 0.0584, 0.0034, -0.0057, -0.0244, -0.0517, 1.0000]

 Predicted: [0.0007, 0.0009, -0.0104, 0.0075, 0.0066, 0.0096, 0.9961]

 Time: 803.6s

 MAE: 0.0265, MSE: 0.0012, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0005, 0.0616, 0.0086, -0.0069, -0.0470, -0.0445, 0.9999]

 Predicted: [0.0007, -0.0020, -0.0026, -0.0123, -0.0075, -0.0033, 0.9961]

 Time: 802.5s

 MAE: 0.0236, MSE: 0.0011, Task Success: 

 Sample 329: traj62

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0079, 0.0244, 0.0078, -0.0113, -0.0335, -0.1419, 0.9971]

 Predicted: [0.0108, 0.0132, -0.0088, 0.0241, -0.0249, -0.0097, 0.9961]

 Time: 775.0s

 MAE: 0.0297, MSE: 0.0027, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0089, 0.0184, -0.0031, -0.0140, -0.0511, -0.1156, 0.9958]

🎯 Predicted: [-0.0042, -0.0114, 0.0081, -0.0072, -0.0229, -0.0468, 0.9961]
⌚ Time: 772.8s
📊 MAE: 0.0226, MSE: 0.0010, Task Success:

📸 Sample 330: traj96

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0046, 0.0421, 0.0025, -0.0033, -0.0240, -0.1590, 0.9934]

🎯 Predicted: [0.0027, 0.0018, -0.0044, 0.0752, -0.0001, -0.0226, 0.9961]

⌚ Time: 807.6s

📊 MAE: 0.0415, MSE: 0.0039, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [0.0165, 0.0536, 0.0024, -0.0078, -0.0320, -0.1321, 1.0000]

🎯 Predicted: [-0.0004, 0.0018, -0.0127, 0.0043, 0.0106, 0.0144, 0.9961]

⌚ Time: 826.6s

📊 MAE: 0.0413, MSE: 0.0038, Task Success:

📸 Sample 331: traj244

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0082, -0.0364, -0.0037, 0.0064, -0.0575, -0.0388, 1.0000]

🎯 Predicted: [0.0005, -0.0066, -0.0008, -0.0091, -0.0055, -0.0130, 0.9961]

⌚ Time: 822.2s

📊 MAE: 0.0197, MSE: 0.0007, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [0.0085, -0.0300, 0.0022, 0.0075, -0.0818, -0.0421, 1.0000]
Predicted: [0.0078, -0.0043, -0.0101, 0.0018, -0.0035, -0.0033, 0.9961]
Time: 787.6s
MAE: 0.0236, MSE: 0.0012, Task Success: ✓

 Sample 332: traj54

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [-0.0116, 0.0121, -0.0092, -0.0029, -0.0125, -0.5502, 1.0000]
Predicted: [-0.0013, 0.0041, -0.0052, -0.0110, -0.0135, 0.0241, 0.9961]
Time: 812.9s
MAE: 0.0871, MSE: 0.0472, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [-0.0135, 0.0078, -0.0043, 0.0096, -0.0386, -0.4903, 1.0000]
Predicted: [-0.0013, 0.0041, -0.0002, 0.0050, 0.0006, 0.0241, 0.9961]
Time: 815.4s
MAE: 0.0831, MSE: 0.0381, Task Success: ✓

 Sample 333: traj272

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [0.0147, 0.0131, 0.0059, 0.0096, -0.0506, 0.5854, 0.9968]
Predicted: [0.0038, 0.0070, -0.0054, 0.0171, -0.0008, -0.0162, 0.0000]
Time: 791.9s
MAE: 0.2406, MSE: 0.1940, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0109, 0.0017, 0.0030, -0.0017, -0.0590, 0.5701, 1.0000]
 Predicted: [-0.0024, -0.0147, 0.0159, -0.0321, 0.0113, 0.0241, 0.0000]
 Time: 799.9s
 MAE: 0.2413, MSE: 0.1864, Task Success:

Sample 334: traj286

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0019, -0.0377, -0.0010, 0.0059, -0.0345, -0.5556, 0.9933]
 Predicted: [0.0038, 0.0012, 0.0000, 0.0024, -0.0035, -0.0146, 0.9961]
 Time: 776.0s
 MAE: 0.0886, MSE: 0.0422, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0078, -0.0403, -0.0032, 0.0125, -0.0440, -0.5373, 0.9850]
 Predicted: [0.0045, -0.0092, 0.0021, 0.0120, -0.0148, -0.0275, 0.9961]
 Time: 787.7s
 MAE: 0.0843, MSE: 0.0374, Task Success:

Sample 335: traj53

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0310, -0.0060, -0.0024, -0.0039, -0.0332, -0.7163, 1.0000]
 Predicted: [-0.0004, -0.0001, 0.0000, -0.0008, -0.0001, 0.0048, 0.0000]
 Time: 829.8s
 MAE: 0.2567, MSE: 0.2174, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0341, -0.0034, -0.0033, -0.0087, -0.0436, -0.6873, 0.9991]
 Predicted: [-0.0002, 0.0015, 0.0000, 0.0088, -0.0015, -0.0017, 0.0000]
 Time: 855.6s
 MAE: 0.2553, MSE: 0.2102, Task Success:

Sample 336: traj281

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0261, -0.0066, -0.0045, 0.0033, -0.0258, 0.7730, 0.9989]
 Predicted: [-0.0031, 0.0035, 0.0203, 0.0177, -0.0236, 0.0257, 0.0000]
 Time: 820.0s
 MAE: 0.2601, MSE: 0.2225, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0210, -0.0046, -0.0003, 0.0117, -0.0678, 0.7302, 1.0000]
 Predicted: [0.0072, 0.0116, 0.0140, 0.0018, -0.0222, 0.0580, 0.0000]
 Time: 818.5s
 MAE: 0.2552, MSE: 0.2079, Task Success:

Sample 337: traj98

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0139, 0.0105, -0.0104, -0.0023, -0.0257, -0.3796, 0.9917]
 Predicted: [0.0087, 0.0015, -0.0028, 0.0190, -0.0416, -0.0291, 0.9961]

⌚ Time: 825.1s
📊 MAE: 0.0616, MSE: 0.0178, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0199, 0.0039, 0.0030, 0.0116, -0.0343, -0.3406, 0.9978]
🎯 Predicted: [-0.0042, 0.0051, -0.0091, 0.0478, 0.0247, 0.0870, 0.9961]
⌚ Time: 831.6s
📊 MAE: 0.0790, MSE: 0.0269, Task Success: ✓

📸 Sample 338: traj275
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0021, 0.0492, 0.0031, -0.0147, -0.0263, 0.0781, 0.9964]
🎯 Predicted: [0.0025, 0.0054, 0.0166, -0.0135, -0.0517, 0.0547, 0.0000]
⌚ Time: 812.9s
📊 MAE: 0.1577, MSE: 0.1423, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0141, 0.0464, -0.0144, -0.0124, -0.0402, 0.0776, 0.9940]
🎯 Predicted: [-0.0031, 0.0038, -0.0057, 0.0375, 0.0019, 0.0096, 0.0000]
⌚ Time: 841.1s
📊 MAE: 0.1747, MSE: 0.1427, Task Success: ✗

📸 Sample 339: traj307
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg

✓ Ground Truth: [0.0192, -0.0249, -0.0025, 0.0118, -0.0226, 0.6420, 1.0000]
🎯 Predicted: [-0.0016, 0.0090, -0.0013, 0.0024, 0.0046, 0.0289, 0.9961]
⌚ Time: 861.1s
📊 MAE: 0.1013, MSE: 0.0540, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [0.0153, -0.0240, -0.0022, 0.0163, -0.0439, 0.5902, 1.0000]
🎯 Predicted: [0.0081, 0.0041, -0.0013, 0.0075, -0.0135, 0.0128, 0.9961]
⌚ Time: 877.2s
📊 MAE: 0.0938, MSE: 0.0479, Task Success: ✓

📸 Sample 340: traj135
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0106, -0.0074, -0.0013, 0.0040, -0.0411, 0.9405, 1.0000]
🎯 Predicted: [-0.0024, -0.0024, -0.0109, -0.0110, 0.0575, -0.0065, 0.9961]
⌚ Time: 822.8s
📊 MAE: 0.1553, MSE: 0.1296, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0142, -0.0152, 0.0024, 0.0102, -0.0611, 0.8965, 1.0000]
🎯 Predicted: [-0.0029, -0.0033, -0.0047, 0.0152, 0.0119, -0.0017, 0.9961]
⌚ Time: 803.5s
📊 MAE: 0.1443, MSE: 0.1161, Task Success: ✓

📸 Sample 341: traj132
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0133, -0.0341, -0.0006, 0.0073, -0.0543, 0.8859, 0.9974]

Predicted: [0.0076, -0.0105, 0.0140, -0.0321, -0.0430, 0.0596, 0.0000]

Time: 792.8s

MAE: 0.2762, MSE: 0.2401, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0214, -0.0197, -0.0019, -0.0084, -0.0704, 0.8320, 0.9928]

Predicted: [0.0092, 0.0015, -0.0075, -0.0046, -0.0028, -0.0146, 0.9961]

Time: 807.2s

MAE: 0.1398, MSE: 0.1032, Task Success: ✓

📸 Sample 342: traj300

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [0.0372, -0.0227, -0.0092, 0.0195, -0.0424, 0.8200, 0.9929]

Predicted: [-0.0016, -0.0192, -0.0078, 0.0011, 0.0052, -0.0581, 0.9961]

Time: 799.1s

MAE: 0.1416, MSE: 0.1107, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0295, -0.0193, -0.0053, 0.0149, -0.0533, 0.7622, 1.0000]

Predicted: [-0.0016, -0.0163, -0.0018, -0.0052, -0.0075, -0.0436, 0.9961]

Time: 820.2s

MAE: 0.1305, MSE: 0.0933, Task Success: ✓

📸 Sample 343: traj104

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0244, 0.0386, 0.0005, 0.0039, -0.0318, -0.3777, 0.9978]
 Predicted: [-0.0013, 0.0041, -0.0041, 0.0050, -0.0035, 0.0322, 0.9961]
 Time: 775.7s
 MAE: 0.0719, MSE: 0.0244, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0197, 0.0357, -0.0008, 0.0070, -0.0459, -0.3198, 1.0000]
 Predicted: [-0.0022, 0.0018, -0.0135, 0.0120, 0.0374, -0.0081, 0.9961]
 Time: 812.2s
 MAE: 0.0668, MSE: 0.0151, Task Success:

Sample 344: traj3

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0185, 0.0296, -0.0007, 0.0073, -0.0372, 0.7931, 0.9985]
 Predicted: [0.0083, -0.0024, 0.0198, 0.0267, -0.0008, -0.0033, 0.0000]
 Time: 801.0s
 MAE: 0.2757, MSE: 0.2336, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0264, 0.0347, -0.0036, 0.0024, -0.0507, 0.7758, 0.9986]
 Predicted: [-0.0004, 0.0099, 0.0218, 0.0075, -0.0490, 0.0338, 0.0000]
 Time: 802.1s
 MAE: 0.2605, MSE: 0.2214, Task Success:

Sample 345: traj309

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0358, 0.0249, -0.0036, -0.0046, -0.0234, 0.5141, 0.9946]
 Predicted: [-0.0031, -0.0111, 0.0224, -0.0295, -0.0524, -0.0130, 0.0000]
 Time: 825.8s
 MAE: 0.2395, MSE: 0.1817, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0363, 0.0322, 0.0054, -0.0012, -0.0449, 0.4851, 0.9939]
 Predicted: [-0.0062, -0.0127, 0.0146, 0.0062, -0.0296, -0.0307, 0.0000]
 Time: 812.1s
 MAE: 0.2327, MSE: 0.1797, Task Success:

Sample 346: traj103

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0078, -0.0086, 0.0019, 0.0051, -0.0363, 0.1160, 0.9951]
 Predicted: [-0.0009, -0.0040, -0.0093, 0.0056, 0.0173, -0.0226, 0.0000]
 Time: 845.2s
 MAE: 0.1730, MSE: 0.1446, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0015, -0.0136, 0.0058, 0.0135, -0.0474, 0.0971, 1.0000]
 Predicted: [0.0014, 0.0012, 0.0166, -0.0110, -0.0423, 0.0177, 0.9961]
 Time: 815.0s
 MAE: 0.0198, MSE: 0.0010, Task Success:

 Sample 347: traj4

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0007, 0.0614, 0.0034, -0.0075, -0.0280, 0.8729, 1.0000]

 Predicted: [0.0108, 0.0035, 0.0146, -0.0276, -0.0262, 0.0015, 0.0000]

 Time: 813.6s

 MAE: 0.2818, MSE: 0.2519, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [-0.0040, 0.0597, -0.0057, -0.0135, -0.0431, 0.8651, 1.0000]

 Predicted: [0.0069, -0.0095, 0.0187, -0.0174, -0.0262, -0.0097, 0.0000]

 Time: 856.4s

 MAE: 0.2857, MSE: 0.2530, Task Success: 

 Sample 348: traj168

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0204, -0.0012, 0.0063, 0.0046, -0.0302, -0.7001, 0.9960]

 Predicted: [-0.0109, 0.0093, 0.0265, 0.0133, -0.0336, 0.0902, 0.0000]

 Time: 832.4s

 MAE: 0.2658, MSE: 0.2312, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0226, -0.0033, -0.0004, 0.0041, -0.0438, -0.6603, 0.9927]

 Predicted: [-0.0060, -0.0085, -0.0151, 0.0075, 0.0347, -0.0178, 0.0000]

 Time: 803.1s

📊 MAE: 0.2522, MSE: 0.2008, Task Success: ✗

📸 Sample 349: traj157

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [0.0228, 0.0675, -0.0076, -0.0086, -0.0191, -0.5981, 1.0000]

🎯 Predicted: [-0.0004, -0.0001, 0.0000, -0.0014, -0.0001, -0.0065, 0.0000]

⌚ Time: 825.6s

📊 MAE: 0.2452, MSE: 0.1936, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [0.0402, 0.0618, 0.0029, -0.0152, -0.0334, -0.5601, 1.0000]

🎯 Predicted: [0.0014, 0.0035, -0.0104, 0.0126, 0.0039, 0.0096, 0.0000]

⌚ Time: 776.6s

📊 MAE: 0.2493, MSE: 0.1903, Task Success: ✗

📸 Sample 350: traj150

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [0.0030, -0.0367, -0.0028, 0.0088, -0.0255, 0.5634, 0.9954]

🎯 Predicted: [0.0072, 0.0015, -0.0018, 0.0318, 0.0193, 0.0112, 0.9961]

⌚ Time: 787.0s

📊 MAE: 0.0949, MSE: 0.0441, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [0.0130, -0.0280, 0.0044, 0.0202, -0.0453, 0.5007, 1.0000]

🎯 Predicted: [-0.0056, -0.0059, 0.0148, -0.0333, -0.0336, 0.0161, 0.9961]
⌚ Time: 797.9s
📊 MAE: 0.0864, MSE: 0.0341, Task Success: ✓

📸 Sample 351: traj159

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0114, 0.0130, 0.0065, 0.0022, -0.0154, -0.0827, 1.0000]

🎯 Predicted: [0.0007, -0.0131, 0.0187, 0.0216, -0.0336, -0.0162, 0.9961]

⌚ Time: 795.9s

📊 MAE: 0.0224, MSE: 0.0009, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [0.0012, 0.0135, -0.0053, -0.0019, -0.0321, -0.0712, 0.9977]

🎯 Predicted: [0.0034, 0.0080, -0.0052, 0.0082, 0.0140, 0.0015, 0.9961]

⌚ Time: 793.1s

📊 MAE: 0.0197, MSE: 0.0011, Task Success: ✓

📸 Sample 352: traj192

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0232, -0.0208, 0.0041, 0.0024, -0.0277, 0.3358, 1.0000]

🎯 Predicted: [-0.0076, -0.0296, 0.0018, -0.0206, -0.0015, -0.0420, 0.0000]

⌚ Time: 2812.8s

📊 MAE: 0.2098, MSE: 0.1636, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg
 Ground Truth: [0.0337, -0.0140, -0.0053, 0.0020, -0.0415, 0.2752, 0.9988]
 Predicted: [-0.0101, -0.0208, -0.0028, -0.0231, -0.0182, -0.0307, 0.0000]
 Time: 788.1s
 MAE: 0.2009, MSE: 0.1563, Task Success: X

 Sample 353: traj166

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0018, 0.0208, -0.0052, -0.0062, -0.0310, 0.0384, 0.9950]

 Predicted: [0.0000, -0.0037, -0.0028, 0.0056, 0.0119, -0.0275, 0.9961]

 Time: 773.1s

 MAE: 0.0215, MSE: 0.0010, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [-0.0024, 0.0126, 0.0009, -0.0114, -0.0553, 0.0464, 0.9978]

 Predicted: [-0.0051, -0.0079, 0.0187, -0.0276, -0.0336, -0.0226, 0.9961]

 Time: 788.4s

 MAE: 0.0214, MSE: 0.0009, Task Success: ✓

 Sample 354: traj161

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [-0.0122, 0.0206, 0.0047, 0.0108, -0.0261, -0.8562, 0.9994]

 Predicted: [0.0072, 0.0051, 0.0104, 0.0082, -0.0577, 0.0870, 0.0000]

 Time: 792.0s

 MAE: 0.2882, MSE: 0.2700, Task Success: X

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0199, 0.0165, 0.0011, 0.0083, -0.0333, -0.8086, 1.0000]
 Predicted: [0.0014, 0.0145, 0.0122, 0.0018, -0.0303, 0.0515, 0.0000]
 Time: 816.2s
 MAE: 0.2720, MSE: 0.2486, Task Success: 

Sample 355: traj195

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0022, -0.0049, -0.0319, 0.0022, -0.0500, 0.1128, 1.0000]
 Predicted: [-0.0056, -0.0131, -0.0047, -0.0104, -0.0035, -0.0500, 0.9961]
 Time: 801.2s
 MAE: 0.0384, MSE: 0.0042, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0026, 0.0041, -0.0274, -0.0000, -0.0567, 0.0910, 0.9983]
 Predicted: [-0.0045, -0.0004, -0.0078, 0.0011, 0.0294, -0.0017, 0.9961]
 Time: 845.0s
 MAE: 0.0297, MSE: 0.0023, Task Success: 

Sample 356: traj102

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0119, 0.0253, -0.0036, -0.0056, -0.0172, 0.6677, 1.0000]
 Predicted: [-0.0022, -0.0030, -0.0018, 0.0062, 0.0079, -0.0194, 0.9961]
 Time: 789.5s
 MAE: 0.1097, MSE: 0.0677, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0085, 0.0246, -0.0028, -0.0005, -0.0391, 0.6476, 1.0000]
 Predicted: [-0.0065, -0.0037, -0.0106, -0.0104, 0.0260, -0.0097, 0.9961]
 Time: 769.9s
 MAE: 0.1106, MSE: 0.0625, Task Success:

Sample 357: traj5

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0278, -0.0403, 0.0037, -0.0011, -0.0148, -0.7543, 1.0000]
 Predicted: [0.0108, 0.0064, -0.0101, 0.0197, -0.0215, 0.0080, 0.0000]
 Time: 769.8s
 MAE: 0.2698, MSE: 0.2265, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0331, -0.0250, -0.0021, 0.0055, -0.0512, -0.7254, 1.0000]
 Predicted: [0.0074, 0.0015, -0.0067, -0.0231, -0.0309, 0.0451, 0.0000]
 Time: 756.3s
 MAE: 0.2701, MSE: 0.2282, Task Success:

Sample 358: traj105

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0189, -0.0119, -0.0024, -0.0046, -0.0254, 0.1135, 1.0000]
 Predicted: [0.0016, 0.0035, -0.0091, -0.0046, 0.0079, -0.0001, 0.9961]
 Time: 759.9s

📊 MAE: 0.0272, MSE: 0.0021, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [0.0168, -0.0043, -0.0036, 0.0044, -0.0410, 0.0935, 1.0000]

🎯 Predicted: [0.0016, 0.0122, -0.0158, -0.0110, -0.0102, 0.0338, 0.9961]

⌚ Time: 758.3s

📊 MAE: 0.0220, MSE: 0.0008, Task Success: ✓

📸 Sample 359: traj2

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [0.0293, 0.0346, -0.0049, -0.0140, -0.0419, -0.5229, 0.9952]

🎯 Predicted: [0.0121, 0.0151, -0.0052, 0.0235, -0.0222, 0.0418, 0.0000]

⌚ Time: 768.4s

📊 MAE: 0.2363, MSE: 0.1874, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [0.0294, 0.0326, -0.0001, -0.0073, -0.0554, -0.5027, 0.9962]

🎯 Predicted: [-0.0040, 0.0077, -0.0021, 0.0126, -0.0785, 0.0338, 0.0000]

⌚ Time: 758.0s

📊 MAE: 0.2337, MSE: 0.1833, Task Success: ✗

📸 Sample 360: traj308

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [-0.0017, -0.0149, 0.0072, 0.0106, -0.0268, 0.9307, 1.0000]

🎯 Predicted: [-0.0047, -0.0205, -0.0062, -0.0014, 0.0146, -0.0097, 0.9961]
⌚ Time: 764.8s
📊 MAE: 0.1457, MSE: 0.1267, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [0.0027, -0.0044, -0.0010, 0.0210, -0.0431, 0.9062, 0.9957]
🎯 Predicted: [-0.0179, -0.0173, 0.0050, -0.0014, -0.0336, -0.0887, 0.9961]
⌚ Time: 767.3s
📊 MAE: 0.1524, MSE: 0.1416, Task Success: 

📸 Sample 361: traj301
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [0.0003, -0.0394, -0.0020, 0.0167, -0.0398, 0.4137, 1.0000]
🎯 Predicted: [-0.0190, -0.0273, 0.0037, 0.0069, -0.0048, -0.0371, 0.9961]
⌚ Time: 764.9s
📊 MAE: 0.0767, MSE: 0.0293, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [0.0014, -0.0404, -0.0059, 0.0092, -0.0602, 0.3656, 0.9940]
🎯 Predicted: [-0.0060, -0.0195, 0.0042, -0.0014, -0.0229, -0.0468, 0.9961]
⌚ Time: 761.6s
📊 MAE: 0.0715, MSE: 0.0246, Task Success: 

📸 Sample 362: traj133
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)

 Image 1: im_42.jpg
 Ground Truth: [-0.0271, -0.0454, 0.0030, 0.0112, -0.0270, -0.9719, 1.0000]
 Predicted: [0.0025, -0.0024, -0.0065, 0.0075, 0.0026, 0.0289, 0.0000]
 Time: 749.3s
 MAE: 0.3023, MSE: 0.2865, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0254, -0.0359, -0.0022, 0.0121, -0.0535, -0.9524, 0.9968]
 Predicted: [0.0025, -0.0024, -0.0013, -0.0212, 0.0059, -0.0162, 0.0000]
 Time: 768.4s
 MAE: 0.2983, MSE: 0.2681, Task Success: X

 Sample 363: traj134
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0015, -0.0617, -0.0058, 0.0158, -0.0402, 0.0363, 0.9981]
 Predicted: [0.0014, 0.0005, -0.0026, 0.0056, -0.0135, 0.0144, 0.9961]
 Time: 763.4s
 MAE: 0.0181, MSE: 0.0007, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0002, -0.0486, 0.0022, 0.0121, -0.0550, 0.0218, 0.9947]
 Predicted: [0.0014, 0.0002, 0.0000, 0.0062, -0.0102, -0.0017, 0.9961]
 Time: 765.1s
 MAE: 0.0182, MSE: 0.0007, Task Success: ✓

 Sample 364: traj306
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0085, 0.0153, -0.0000, -0.0051, -0.0219, -0.1835, 0.9906]
 Predicted: [0.0108, 0.0086, 0.0000, 0.0094, -0.0021, 0.0032, 0.9961]
 Time: 756.2s
 MAE: 0.0336, MSE: 0.0051, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0118, 0.0301, -0.0071, -0.0061, -0.0403, -0.1515, 0.9961]
 Predicted: [-0.0013, -0.0007, -0.0205, -0.0123, 0.0079, -0.0081, 0.9961]
 Time: 764.7s
 MAE: 0.0364, MSE: 0.0035, Task Success: 

Sample 365: traj194

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0085, 0.0607, 0.0080, -0.0167, -0.0451, 0.2913, 0.9906]
 Predicted: [0.0114, 0.0031, -0.0002, 0.0101, -0.0497, -0.0146, 0.9961]
 Time: 776.5s
 MAE: 0.0588, MSE: 0.0140, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0040, 0.0600, -0.0011, -0.0143, -0.0619, 0.2677, 1.0000]
 Predicted: [0.0108, 0.0086, 0.0047, 0.0050, -0.0423, -0.0017, 0.9961]
 Time: 771.1s
 MAE: 0.0537, MSE: 0.0109, Task Success: 

Sample 366: traj160

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0107, 0.0598, -0.0004, -0.0077, -0.0232, 0.1056, 1.0000]
🎯 Predicted: [0.0081, -0.0105, 0.0250, 0.0299, -0.0617, 0.0660, 0.0000]
 Time: 762.5s
 MAE: 0.1757, MSE: 0.1443, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0012, 0.0609, -0.0003, -0.0094, -0.0446, 0.0977, 0.9875]
🎯 Predicted: [0.0101, -0.0302, 0.0231, 0.0216, -0.0289, 0.0902, 0.0000]
 Time: 768.7s
 MAE: 0.1668, MSE: 0.1408, Task Success: ✗

Sample 367: traj158
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0224, -0.0035, 0.0044, -0.0017, -0.0218, -0.1006, 0.9969]
🎯 Predicted: [0.0007, 0.0051, -0.0091, -0.0212, 0.0066, 0.0128, 0.9961]
 Time: 756.6s
 MAE: 0.0296, MSE: 0.0021, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0177, -0.0094, -0.0055, -0.0066, -0.0496, -0.0845, 1.0000]
🎯 Predicted: [0.0007, 0.0103, -0.0008, 0.0190, -0.0061, 0.0547, 0.9961]
 Time: 756.2s
 MAE: 0.0364, MSE: 0.0032, Task Success: ✓

Sample 368: traj167

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0580, -0.0032, -0.0050, 0.0129, -0.0260, -0.7991, 0.9978]
 Predicted: [-0.0009, -0.0292, -0.0083, -0.0193, 0.0166, -0.0952, 0.0000]
 Time: 750.6s
 MAE: 0.2661, MSE: 0.2140, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0473, -0.0055, 0.0041, 0.0094, -0.0515, -0.7682, 1.0000]
 Predicted: [-0.0029, -0.0318, -0.0130, -0.0238, 0.0019, -0.0968, 0.0000]
 Time: 757.3s
 MAE: 0.2637, MSE: 0.2082, Task Success:

Sample 369: traj193
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0214, -0.0360, 0.0010, -0.0005, -0.0268, -0.1039, 0.9904]
 Predicted: [0.0112, -0.0004, -0.0086, 0.0011, -0.0303, -0.0130, 0.9961]
 Time: 756.3s
 MAE: 0.0224, MSE: 0.0014, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0183, -0.0304, -0.0038, 0.0054, -0.0402, -0.0931, 0.9976]
 Predicted: [0.0128, 0.0161, -0.0083, 0.0056, -0.0075, 0.0499, 0.9961]
 Time: 761.0s
 MAE: 0.0334, MSE: 0.0034, Task Success:

📸 Sample 370: traj151

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0257, 0.0674, -0.0001, -0.0036, -0.0285, 0.2569, 1.0000]

⌚ Predicted: [0.0043, -0.0095, 0.0096, -0.0225, -0.0323, -0.0242, 0.0000]

⌚ Time: 753.3s

📊 MAE: 0.2017, MSE: 0.1551, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [0.0273, 0.0656, -0.0011, -0.0077, -0.0549, 0.2225, 0.9913]

⌚ Predicted: [0.0011, 0.0002, -0.0002, -0.0097, -0.0081, 0.0048, 0.0000]

⌚ Time: 767.3s

📊 MAE: 0.1929, MSE: 0.1482, Task Success: ✗

📸 Sample 371: traj169

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [-0.0329, 0.0587, 0.0034, -0.0029, -0.0213, -0.3516, 1.0000]

⌚ Predicted: [0.0108, -0.0063, -0.0021, -0.0308, -0.0396, -0.0323, 0.9961]

⌚ Time: 752.3s

📊 MAE: 0.0691, MSE: 0.0156, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [-0.0330, 0.0648, 0.0026, -0.0148, -0.0499, -0.3207, 1.0000]

⌚ Predicted: [0.0099, 0.0015, -0.0067, -0.0078, 0.0032, -0.0033, 0.9961]

Time: 760.0s
 MAE: 0.0710, MSE: 0.0157, Task Success: X

Sample 372: traj156

Instruction: pick up the object and place it in the bowl

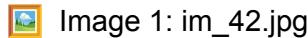
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0371, 0.0313, 0.0021, -0.0011, -0.0263, -0.7850, 0.9870]

⌚ Predicted: [0.0063, 0.0018, -0.0034, 0.0190, -0.0343, 0.0418, 0.9961]

Time: 759.4s

MAE: 0.1346, MSE: 0.0982, Task Success: X

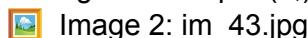
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0347, 0.0187, 0.0019, 0.0001, -0.0517, -0.7555, 1.0000]

⌚ Predicted: [0.0078, 0.0051, -0.0101, -0.0110, 0.0086, -0.0001, 0.9961]

Time: 766.8s

MAE: 0.1284, MSE: 0.0824, Task Success: ✓

Sample 373: traj180

Instruction: pick up the object and place it in the bowl

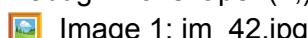
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0060, -0.0288, -0.0013, 0.0060, -0.0270, -0.8447, 1.0000]

⌚ Predicted: [0.0011, 0.0048, -0.0109, 0.0177, -0.0169, 0.0080, 0.0000]

Time: 765.4s

MAE: 0.2750, MSE: 0.2469, Task Success: X

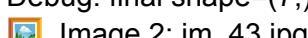
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)



✓ Ground Truth: [-0.0081, -0.0187, -0.0008, 0.0106, -0.0460, -0.8060, 0.9983]
⌚ Predicted: [-0.0007, 0.0054, -0.0091, -0.0110, 0.0213, 0.0112, 0.9961]
⌚ Time: 756.7s
📊 MAE: 0.1355, MSE: 0.0962, Task Success: ✓

📸 Sample 374: traj174

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼 Image 1: im_42.jpg

✓ Ground Truth: [0.0095, -0.0132, 0.0075, 0.0157, -0.0195, -0.2354, 0.9977]

⌚ Predicted: [-0.0065, -0.0001, 0.0213, 0.0165, -0.0336, 0.0289, 0.0000]

⌚ Time: 766.4s

📊 MAE: 0.1885, MSE: 0.1523, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼 Image 2: im_43.jpg

✓ Ground Truth: [0.0206, -0.0194, 0.0088, 0.0096, -0.0319, -0.2166, 1.0000]

⌚ Predicted: [-0.0065, 0.0077, -0.0049, 0.0024, 0.0086, 0.0483, 0.9961]

⌚ Time: 767.5s

📊 MAE: 0.0549, MSE: 0.0105, Task Success: ✓

📸 Sample 375: traj173

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼 Image 1: im_42.jpg

✓ Ground Truth: [0.0149, -0.0363, -0.0069, -0.0005, -0.0271, -0.2998, 1.0000]

⌚ Predicted: [-0.0060, -0.0131, -0.0119, 0.0069, -0.0008, -0.0581, 0.9961]

⌚ Time: 753.4s

📊 MAE: 0.0469, MSE: 0.0086, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [0.0193, -0.0276, 0.0065, 0.0004, -0.0434, -0.2857, 1.0000]
Predicted: [-0.0147, -0.0173, -0.0047, -0.0244, 0.0146, -0.0436, 0.9961]
Time: 761.1s
MAE: 0.0549, MSE: 0.0091, Task Success: ✓

 Sample 376: traj187

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [0.0272, 0.0088, 0.0070, 0.0001, -0.0281, -0.4422, 0.9972]
Predicted: [-0.0036, -0.0095, -0.0047, 0.0050, 0.0173, -0.0226, 0.9961]
Time: 761.6s
MAE: 0.0760, MSE: 0.0256, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 2: im_43.jpg
Ground Truth: [0.0239, 0.0142, -0.0031, 0.0102, -0.0411, -0.4338, 1.0000]
Predicted: [0.0005, -0.0147, -0.0052, -0.0052, 0.0073, -0.0404, 0.9961]
Time: 752.5s
MAE: 0.0737, MSE: 0.0227, Task Success: ✓

 Sample 377: traj145

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
Image 1: im_42.jpg
Ground Truth: [0.0209, 0.0081, -0.0030, -0.0133, -0.0340, 0.5840, 1.0000]
Predicted: [-0.0080, -0.0131, 0.0143, -0.0014, -0.0356, -0.0468, 0.9961]
Time: 758.2s
MAE: 0.1022, MSE: 0.0571, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0168, -0.0073, 0.0105, -0.0099, -0.0450, 0.5631, 0.9987]
 Predicted: [-0.0040, -0.0007, -0.0099, -0.0027, 0.0320, 0.0048, 0.9961]
 Time: 748.5s
 MAE: 0.0990, MSE: 0.0455, Task Success:

Sample 378: traj142

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0139, 0.0234, -0.0002, -0.0147, -0.0192, 0.6870, 0.9991]
 Predicted: [-0.0087, -0.0004, 0.0190, -0.0065, -0.0316, 0.0289, 0.0000]
 Time: 772.1s
 MAE: 0.2490, MSE: 0.2047, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0277, 0.0271, -0.0012, -0.0163, -0.0463, 0.6493, 1.0000]
 Predicted: [-0.0016, -0.0001, 0.0159, 0.0101, -0.0148, 0.0161, 0.0000]
 Time: 766.5s
 MAE: 0.2521, MSE: 0.2007, Task Success:

Sample 379: traj189

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0201, -0.0152, 0.0021, 0.0041, -0.0175, -0.3690, 1.0000]
 Predicted: [-0.0078, -0.0228, -0.0031, -0.0059, 0.0146, -0.0581, 0.9961]
 Time: 765.4s
 MAE: 0.0546, MSE: 0.0140, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0092, -0.0034, 0.0067, 0.0002, -0.0371, -0.3505, 0.9978]
 Predicted: [0.0007, 0.0002, -0.0093, -0.0001, 0.0153, -0.0146, 0.9961]
 Time: 763.5s
 MAE: 0.0600, MSE: 0.0166, Task Success:

Sample 380: traj129

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0155, 0.0002, -0.0017, 0.0055, -0.0262, -0.8542, 0.9963]
 Predicted: [0.0007, 0.0057, -0.0096, 0.0165, 0.0207, 0.0096, 0.9961]
 Time: 758.9s
 MAE: 0.1359, MSE: 0.1070, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0033, -0.0084, -0.0092, 0.0234, -0.0357, -0.8356, 1.0000]
 Predicted: [0.0108, 0.0038, -0.0018, -0.0116, -0.0303, -0.0468, 0.9961]
 Time: 761.0s
 MAE: 0.1238, MSE: 0.0891, Task Success:

Sample 381: traj116

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0178, 0.0298, 0.0027, -0.0023, -0.0224, -0.2400, 1.0000]
 Predicted: [0.0072, -0.0059, -0.0138, -0.0155, 0.0106, -0.0242, 0.9961]

⌚ Time: 745.1s
📊 MAE: 0.0490, MSE: 0.0071, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0135, 0.0162, -0.0055, 0.0023, -0.0549, -0.1840, 0.9972]
🎯 Predicted: [-0.0038, -0.0137, -0.0047, 0.0145, 0.0173, -0.0436, 0.9961]
⌚ Time: 775.0s
📊 MAE: 0.0381, MSE: 0.0037, Task Success: ✓

📸 Sample 382: traj111
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0094, 0.0245, -0.0009, -0.0031, -0.0412, -0.5760, 1.0000]
🎯 Predicted: [-0.0033, -0.0001, -0.0047, 0.0120, -0.0048, -0.0645, 0.9961]
⌚ Time: 746.7s
📊 MAE: 0.0869, MSE: 0.0377, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0085, 0.0216, -0.0016, -0.0015, -0.0547, -0.5493, 0.9949]
🎯 Predicted: [-0.0027, 0.0018, -0.0062, 0.0152, -0.0195, -0.0452, 0.9961]
⌚ Time: 767.9s
📊 MAE: 0.0847, MSE: 0.0366, Task Success: ✓

📸 Sample 383: traj118
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg

✓ Ground Truth: [-0.0108, -0.0183, 0.0032, 0.0046, -0.0304, -0.4986, 0.9999]
🎯 Predicted: [0.0087, -0.0007, -0.0138, -0.0059, -0.0081, 0.0096, 0.9961]
⌚ Time: 769.1s
📊 MAE: 0.0855, MSE: 0.0371, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0087, -0.0254, -0.0017, 0.0073, -0.0445, -0.4866, 0.9896]
🎯 Predicted: [0.0000, -0.0024, -0.0086, -0.0110, 0.0207, 0.0161, 0.9961]
⌚ Time: 760.0s
📊 MAE: 0.0902, MSE: 0.0368, Task Success: ✓

📸 Sample 384: traj127
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [0.0018, -0.0111, 0.0054, 0.0130, -0.0183, -0.2372, 0.9947]
🎯 Predicted: [0.0000, 0.0031, -0.0080, -0.0110, 0.0066, 0.0080, 0.9961]
⌚ Time: 761.9s
📊 MAE: 0.0464, MSE: 0.0088, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [0.0012, -0.0025, -0.0065, 0.0094, -0.0270, -0.2103, 0.9913]
🎯 Predicted: [0.0061, 0.0038, -0.0106, 0.0120, -0.0135, -0.0081, 0.9961]
⌚ Time: 771.1s
📊 MAE: 0.0340, MSE: 0.0059, Task Success: ✓

📸 Sample 385: traj315
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [0.0158, -0.0323, -0.0061, 0.0136, -0.0437, -0.7500, 1.0000]

Predicted: [0.0016, -0.0001, 0.0003, -0.0040, 0.0019, -0.0097, 0.0000]

Time: 783.4s

MAE: 0.2652, MSE: 0.2217, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0166, -0.0285, 0.0028, 0.0051, -0.0629, -0.7212, 0.9969]

Predicted: [0.0025, -0.0066, -0.0062, -0.0059, -0.0075, -0.0226, 0.0000]

Time: 769.7s

MAE: 0.2581, MSE: 0.2123, Task Success: ✗

📸 Sample 386: traj312

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_4.jpg

Ground Truth: [0.0154, 0.0034, 0.0029, -0.0039, -0.0260, 0.8303, 0.9998]

Predicted: [-0.0078, 0.0041, 0.0091, 0.0197, -0.0015, 0.0612, 0.9961]

Time: 806.3s

MAE: 0.1216, MSE: 0.0848, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_5.jpg

Ground Truth: [0.0200, -0.0028, 0.0008, -0.0161, -0.0338, 0.7791, 1.0000]

Predicted: [0.0110, 0.0200, -0.0028, 0.0484, -0.0343, 0.2030, 0.9961]

Time: 800.1s

MAE: 0.0972, MSE: 0.0481, Task Success: ✓

📸 Sample 387: traj120

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0076, -0.0478, -0.0054, 0.0073, -0.0292, -0.6679, 0.9947]
 Predicted: [0.0016, -0.0134, 0.0231, 0.0286, -0.0061, 0.0128, 0.0000]
 Time: 770.5s
 MAE: 0.2560, MSE: 0.2080, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0089, -0.0494, 0.0015, 0.0090, -0.0513, -0.6531, 1.0000]
 Predicted: [0.0000, 0.0012, 0.0005, 0.0082, -0.0015, 0.0080, 0.0000]
 Time: 775.7s
 MAE: 0.2532, MSE: 0.2060, Task Success:

Sample 388: traj143

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0014, 0.0109, -0.0030, -0.0121, -0.0371, 0.6155, 1.0000]
 Predicted: [0.0108, -0.0037, -0.0021, -0.0116, -0.0169, -0.0130, 0.9961]
 Time: 782.7s
 MAE: 0.0969, MSE: 0.0565, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0170, 0.0034, -0.0022, -0.0132, -0.0635, 0.5854, 0.9994]
 Predicted: [0.0105, 0.0015, -0.0086, -0.0021, -0.0028, -0.0146, 0.9961]
 Time: 833.5s
 MAE: 0.0985, MSE: 0.0520, Task Success:

Sample 389: traj188

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0348, -0.0028, -0.0031, 0.0124, -0.0225, 0.1392, 0.9985]
 Predicted: [-0.0027, 0.0061, 0.0128, 0.0254, 0.0140, 0.0161, 0.0000]
 Time: 800.4s
 MAE: 0.1754, MSE: 0.1450, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0366, 0.0080, -0.0011, 0.0144, -0.0579, 0.1236, 1.0000]
 Predicted: [0.0002, 0.0038, 0.0091, 0.0209, -0.0135, 0.0161, 0.0000]
 Time: 3692.3s
 MAE: 0.1728, MSE: 0.1450, Task Success: ✗

Sample 390: traj144

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0097, -0.0350, 0.0029, 0.0033, -0.0256, 0.5193, 1.0000]
 Predicted: [-0.0221, 0.0067, -0.0208, -0.0806, -0.0035, 0.0676, 0.0000]
 Time: 775.4s
 MAE: 0.2336, MSE: 0.1734, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0145, -0.0356, -0.0034, 0.0065, -0.0468, 0.4747, 0.9967]
 Predicted: [-0.0156, -0.0004, 0.0203, 0.0145, -0.0356, -0.0162, 0.0000]
 Time: 776.7s
 MAE: 0.2238, MSE: 0.1766, Task Success: ✗

 Sample 391: traj186

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [-0.0126, -0.0334, -0.0039, 0.0043, -0.0305, -0.4136, 0.9989]

 Predicted: [-0.0004, 0.0002, -0.0112, 0.0056, 0.0294, -0.0033, 0.9961]

 Time: 776.4s

 MAE: 0.0753, MSE: 0.0248, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [-0.0038, -0.0200, -0.0050, -0.0009, -0.0423, -0.3919, 1.0000]

 Predicted: [-0.0011, -0.0024, -0.0130, -0.0052, 0.0106, -0.0194, 0.9961]

 Time: 761.7s

 MAE: 0.0660, MSE: 0.0203, Task Success: 

 Sample 392: traj172

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0157, -0.0004, 0.0016, 0.0230, -0.0391, 0.1711, 1.0000]

 Predicted: [-0.0027, 0.0005, -0.0021, 0.0024, 0.0079, -0.0130, 0.9961]

 Time: 758.5s

 MAE: 0.0398, MSE: 0.0053, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0235, -0.0051, -0.0054, 0.0246, -0.0500, 0.1436, 1.0000]

 Predicted: [-0.0011, -0.0017, -0.0047, -0.0104, 0.0066, -0.0033, 0.9961]

 Time: 759.1s

📊 MAE: 0.0387, MSE: 0.0038, Task Success: 

📸 Sample 393: traj175

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [-0.0330, -0.0034, 0.0093, 0.0021, -0.0396, -0.9074, 1.0000]

🎯 Predicted: [-0.0011, -0.0011, -0.0091, -0.0052, 0.0207, 0.0048, 0.9961]

⌚ Time: 763.2s

📊 MAE: 0.1480, MSE: 0.1196, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [-0.0316, 0.0013, 0.0013, 0.0046, -0.0590, -0.8716, 0.9917]

🎯 Predicted: [-0.0045, -0.0050, -0.0047, -0.0014, 0.0073, -0.0049, 0.9961]

⌚ Time: 777.7s

📊 MAE: 0.1404, MSE: 0.1081, Task Success: 

📸 Sample 394: traj181

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [-0.0109, 0.0053, 0.0090, -0.0019, -0.0381, 0.3741, 1.0000]

🎯 Predicted: [0.0083, 0.0009, 0.0086, 0.0018, -0.0349, 0.0032, 0.9961]

⌚ Time: 759.7s

📊 MAE: 0.0580, MSE: 0.0197, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [-0.0108, 0.0085, 0.0012, 0.0018, -0.0586, 0.3228, 1.0000]

🎯 Predicted: [-0.0074, 0.0022, 0.0055, 0.0695, 0.0260, 0.1224, 0.9961]
⌚ Time: 764.2s
📊 MAE: 0.0530, MSE: 0.0074, Task Success: ✓

📸 Sample 395: traj121

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [-0.0243, -0.0165, 0.0070, 0.0088, -0.0237, 0.0479, 1.0000]

🎯 Predicted: [-0.0013, -0.0105, 0.0200, 0.0101, -0.0316, -0.0162, 0.9961]

⌚ Time: 764.9s

📊 MAE: 0.0170, MSE: 0.0007, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [-0.0218, -0.0169, -0.0044, 0.0210, -0.0449, 0.0416, 0.9997]

🎯 Predicted: [-0.0065, 0.0022, 0.0205, 0.0241, -0.0282, 0.0128, 0.9961]

⌚ Time: 768.3s

📊 MAE: 0.0159, MSE: 0.0003, Task Success: ✓

📸 Sample 396: traj313

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [-0.0043, -0.0250, -0.0044, 0.0150, -0.0245, 0.3686, 1.0000]

🎯 Predicted: [-0.0150, -0.0001, 0.0070, 0.0056, 0.0173, 0.0144, 0.0000]

⌚ Time: 770.2s

📊 MAE: 0.2075, MSE: 0.1612, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg
 Ground Truth: [0.0078, -0.0228, 0.0003, 0.0133, -0.0514, 0.3204, 1.0000]

^R

 Predicted: [-0.0156, 0.0061, 0.0094, 0.0771, 0.0019, 0.1676, 0.0000]
 Time: 779.9s
 MAE: 0.1902, MSE: 0.1474, Task Success: 

 Sample 397: traj119

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [-0.0159, -0.0023, 0.0006, 0.0015, -0.0173, -0.4777, 1.0000]

 Predicted: [-0.0056, -0.0198, -0.0054, 0.0101, -0.0115, -0.1484, 0.9961]

 Time: 790.9s

 MAE: 0.0545, MSE: 0.0156, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [-0.0153, -0.0104, -0.0003, 0.0010, -0.0360, -0.4468, 0.9935]

 Predicted: [0.0121, -0.0043, -0.0054, -0.0225, -0.0008, -0.1500, 0.9961]

 Time: 766.5s

 MAE: 0.0567, MSE: 0.0130, Task Success: 

 Sample 398: traj314

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0210, -0.0417, 0.0049, 0.0113, -0.0161, 0.1339, 0.9930]

 Predicted: [-0.0004, -0.0001, 0.0182, 0.0152, -0.0423, -0.0065, 0.9961]

 Time: 761.7s

 MAE: 0.0357, MSE: 0.0033, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0110, -0.0444, 0.0022, -0.0030, -0.0428, 0.0947, 0.9960]
 Predicted: [-0.0013, -0.0114, 0.0068, 0.0145, -0.0236, -0.0130, 0.9961]
 Time: 753.1s
 MAE: 0.0278, MSE: 0.0019, Task Success: 

Sample 399: traj126

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0340, 0.0217, 0.0126, 0.0139, -0.0548, 0.0115, 1.0000]
 Predicted: [0.0069, 0.0057, -0.0052, 0.0158, -0.0262, 0.0080, 0.9961]
 Time: 769.9s
 MAE: 0.0161, MSE: 0.0004, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0136, 0.0193, 0.0004, 0.0137, -0.0905, 0.0283, 0.9930]
 Predicted: [0.0108, 0.0051, -0.0054, 0.0043, -0.0128, 0.0032, 0.9961]
 Time: 782.5s
 MAE: 0.0228, MSE: 0.0011, Task Success: 

Sample 400: traj110

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0016, 0.0083, -0.0274, -0.0081, -0.0290, -0.6395, 0.9974]
 Predicted: [-0.0085, -0.0007, -0.0080, 0.0107, 0.0213, -0.0081, 0.9961]
 Time: 777.6s
 MAE: 0.1053, MSE: 0.0574, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0022, 0.0005, -0.0147, -0.0018, -0.0455, -0.6171, 0.9955]
 Predicted: [-0.0009, 0.0002, -0.0080, -0.0027, 0.0213, -0.0049, 0.9961]
 Time: 786.4s
 MAE: 0.0984, MSE: 0.0542, Task Success:

Sample 401: traj128

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0212, 0.0028, -0.0000, -0.0049, -0.0175, 0.3525, 1.0000]
 Predicted: [-0.0033, -0.0127, 0.0091, 0.0254, -0.0081, -0.0162, 0.0000]
 Time: 821.6s
 MAE: 0.2082, MSE: 0.1626, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0189, 0.0129, 0.0084, 0.0024, -0.0469, 0.3228, 1.0000]
 Predicted: [-0.0013, -0.0004, -0.0021, -0.0001, -0.0008, -0.0081, 0.0000]
 Time: 792.9s
 MAE: 0.2034, MSE: 0.1589, Task Success:

Sample 402: traj117

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0037, -0.0219, 0.0056, 0.0140, -0.0537, 0.4267, 0.9967]
 Predicted: [0.0108, 0.0086, -0.0057, -0.0052, 0.0012, 0.0306, 0.9961]

⌚ Time: 790.9s
📊 MAE: 0.0753, MSE: 0.0231, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0017, -0.0234, 0.0021, -0.0020, -0.0753, 0.3850, 0.9989]
🎯 Predicted: [0.0061, 0.0083, -0.0086, 0.0056, 0.0086, 0.0161, 0.9961]
⌚ Time: 786.8s
📊 MAE: 0.0728, MSE: 0.0206, Task Success: ✓

📸 Sample 403: traj257
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [-0.0148, 0.0163, 0.0042, -0.0010, -0.0231, -0.0478, 1.0000]
🎯 Predicted: [0.0085, -0.0101, -0.0101, 0.0031, -0.0135, -0.0226, 0.9961]
⌚ Time: 762.2s
📊 MAE: 0.0153, MSE: 0.0003, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0164, 0.0184, 0.0023, -0.0032, -0.0561, -0.0305, 0.9893]
🎯 Predicted: [-0.0089, -0.0040, -0.0086, -0.0027, 0.0093, 0.1756, 0.9961]
⌚ Time: 774.1s
📊 MAE: 0.0456, MSE: 0.0068, Task Success: ✓

📸 Sample 404: traj85
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg

✓ Ground Truth: [-0.0043, 0.0059, -0.0304, 0.0053, -0.0217, 0.7157, 1.0000]
🎯 Predicted: [-0.0109, 0.0054, -0.0093, 0.0286, 0.0207, -0.1403, 0.9961]
⌚ Time: 782.6s
📊 MAE: 0.1363, MSE: 0.1051, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0015, 0.0006, -0.0334, 0.0118, -0.0441, 0.6901, 1.0000]
🎯 Predicted: [-0.0004, 0.0135, 0.0018, 0.0050, 0.0153, -0.0887, 0.9961]
⌚ Time: 761.9s
📊 MAE: 0.1283, MSE: 0.0874, Task Success: ✓

📸 Sample 405: traj268
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [0.0170, 0.0350, -0.0010, 0.0036, -0.0255, 0.4832, 0.9968]
🎯 Predicted: [-0.0022, 0.0141, -0.0002, -0.0148, -0.0477, 0.1079, 0.9961]
⌚ Time: 847.6s
📊 MAE: 0.0653, MSE: 0.0203, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [0.0104, 0.0320, -0.0002, -0.0084, -0.0584, 0.4637, 1.0000]
🎯 Predicted: [-0.0002, 0.0180, 0.0008, 0.0241, 0.0032, 0.0531, 0.9961]
⌚ Time: 794.7s
📊 MAE: 0.0763, MSE: 0.0248, Task Success: ✓

📸 Sample 406: traj71
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0240, -0.0395, 0.0056, 0.0047, -0.0177, 0.6145, 1.0000]

Predicted: [-0.0002, 0.0035, -0.0052, -0.0308, -0.0155, -0.0065, 0.0000]

Time: 794.4s

MAE: 0.2480, MSE: 0.1985, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0167, -0.0340, -0.0086, 0.0127, -0.0521, 0.5579, 1.0000]

Predicted: [0.0011, 0.0051, -0.0093, -0.0110, -0.0155, -0.0049, 0.0000]

Time: 789.5s

MAE: 0.2401, MSE: 0.1886, Task Success: ✗

📸 Sample 407: traj250

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0186, 0.0013, -0.0009, -0.0045, -0.0415, -0.2437, 0.9990]

Predicted: [-0.0011, -0.0114, 0.0125, 0.0241, 0.0026, 0.0499, 0.0000]

Time: 778.7s

MAE: 0.2013, MSE: 0.1554, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0109, 0.0081, -0.0035, -0.0014, -0.0557, -0.2092, 1.0000]

Predicted: [0.0027, -0.0011, 0.0231, -0.0078, -0.0524, -0.0210, 0.0000]

Time: 780.8s

MAE: 0.1782, MSE: 0.1481, Task Success: ✗

📸 Sample 408: traj49

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0017, 0.0159, 0.0028, 0.0002, -0.0175, -0.2255, 1.0000]
 Predicted: [0.0081, -0.0092, -0.0093, 0.0126, 0.0119, -0.0323, 0.9961]
 Time: 773.1s
 MAE: 0.0408, MSE: 0.0056, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0019, 0.0073, 0.0076, -0.0104, -0.0355, -0.1771, 0.9919]
 Predicted: [-0.0051, 0.0132, 0.0068, 0.0458, 0.0119, 0.1917, 0.9961]
 Time: 767.5s
 MAE: 0.0701, MSE: 0.0202, Task Success:

Sample 409: traj76

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0173, -0.0029, -0.0049, -0.0185, -0.0363, -0.4554, 0.9950]
 Predicted: [-0.0139, 0.0048, -0.0021, 0.0216, 0.0568, 0.0080, 0.9961]
 Time: 767.3s
 MAE: 0.0874, MSE: 0.0322, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0171, -0.0009, 0.0060, 0.0076, -0.0557, -0.4087, 0.9972]
 Predicted: [-0.0062, -0.0043, -0.0086, -0.0244, 0.0032, 0.0386, 0.9961]
 Time: 783.8s
 MAE: 0.0812, MSE: 0.0293, Task Success:

Sample 410: traj82

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0223, -0.0115, -0.0013, -0.0010, -0.0313, -0.0392, 1.0000]
 Predicted: [0.0027, 0.0022, 0.0104, 0.0682, 0.0153, 0.1434, 0.9961]
 Time: 799.3s
 MAE: 0.0496, MSE: 0.0059, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0141, -0.0025, 0.0081, 0.0084, -0.0583, -0.0497, 1.0000]
 Predicted: [0.0087, 0.0025, -0.0109, 0.0120, -0.0222, -0.0033, 0.9961]
 Time: 838.8s
 MAE: 0.0171, MSE: 0.0006, Task Success:

Sample 411: traj266

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0286, -0.0062, -0.0037, 0.0086, -0.0254, -0.3774, 1.0000]
 Predicted: [0.0043, 0.0002, -0.0065, -0.0052, -0.0028, -0.0162, 0.9961]
 Time: 791.6s
 MAE: 0.0634, MSE: 0.0189, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0180, -0.0024, -0.0059, 0.0227, -0.0659, -0.3370, 1.0000]
 Predicted: [0.0099, 0.0057, -0.0127, 0.0133, 0.0086, 0.0096, 0.9961]
 Time: 790.4s
 MAE: 0.0682, MSE: 0.0181, Task Success:

📸 Sample 412: traj292

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0046, 0.0285, 0.0014, -0.0090, -0.0307, 0.1368, 0.9987]

🎯 Predicted: [0.0011, 0.0213, -0.0015, -0.0314, 0.0200, -0.0678, 0.0000]

⌚ Time: 798.3s

📊 MAE: 0.1843, MSE: 0.1489, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [0.0104, 0.0318, -0.0020, -0.0091, -0.0460, 0.1209, 0.9956]

🎯 Predicted: [-0.0011, -0.0224, 0.0094, -0.0365, -0.0001, -0.0387, 0.0000]

⌚ Time: 780.4s

📊 MAE: 0.1865, MSE: 0.1461, Task Success: ✗

📸 Sample 413: traj40

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [-0.0111, -0.0014, 0.0016, -0.0069, -0.0239, -0.8583, 0.9990]

🎯 Predicted: [0.0047, 0.0122, -0.0018, 0.0248, -0.0242, 0.0418, 0.9961]

⌚ Time: 791.8s

📊 MAE: 0.1383, MSE: 0.1159, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [-0.0018, -0.0011, 0.0087, 0.0027, -0.0525, -0.8369, 0.9988]

🎯 Predicted: [-0.0085, 0.0099, -0.0062, 0.0056, 0.0213, 0.0338, 0.9961]

⌚ Time: 780.4s

 MAE: 0.1404, MSE: 0.1091, Task Success: 

 Sample 414: traj259

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [-0.0029, -0.0224, 0.0009, 0.0153, -0.0226, 0.7130, 1.0000]

 Predicted: [0.0025, 0.0057, -0.0008, 0.0107, 0.0186, -0.0097, 0.9961]

 Time: 784.8s

 MAE: 0.1154, MSE: 0.0750, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [-0.0032, -0.0158, 0.0036, -0.0006, -0.0382, 0.6648, 0.9928]

 Predicted: [-0.0024, -0.0007, -0.0096, 0.0209, -0.0035, -0.0275, 0.9961]

 Time: 783.1s

 MAE: 0.1115, MSE: 0.0688, Task Success: 

 Sample 415: traj295

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0295, 0.0445, -0.0007, -0.0091, -0.0468, 0.3247, 1.0000]

 Predicted: [0.0002, 0.0009, 0.0143, -0.0027, -0.0336, 0.0144, 0.9961]

 Time: 769.1s

 MAE: 0.0602, MSE: 0.0142, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0234, 0.0370, 0.0085, -0.0152, -0.0665, 0.2880, 1.0000]

🎯 Predicted: [0.0005, 0.0103, 0.0013, -0.0333, -0.0329, 0.0902, 0.9961]
⌚ Time: 762.0s
📊 MAE: 0.0443, MSE: 0.0060, Task Success: ✓

📸 Sample 416: traj78

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [-0.0137, 0.0338, 0.0012, -0.0057, -0.0290, -0.9006, 1.0000]

🎯 Predicted: [0.0014, 0.0064, 0.0008, 0.0254, 0.0106, -0.1193, 0.9961]

⌚ Time: 775.7s

📊 MAE: 0.1284, MSE: 0.0877, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [-0.0224, 0.0328, -0.0061, -0.0029, -0.0572, -0.8437, 1.0000]

🎯 Predicted: [0.0029, 0.0035, -0.0021, 0.0248, 0.0186, 0.0128, 0.9961]

⌚ Time: 763.4s

📊 MAE: 0.1461, MSE: 0.1060, Task Success: ✓

📸 Sample 417: traj261

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [-0.0263, 0.0027, 0.0021, 0.0022, -0.0277, -0.2808, 0.9963]

🎯 Predicted: [0.0025, 0.0119, 0.0000, 0.0082, -0.0229, 0.0177, 0.9961]

⌚ Time: 764.8s

📊 MAE: 0.0499, MSE: 0.0129, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg
 Ground Truth: [-0.0305, -0.0061, -0.0049, 0.0063, -0.0556, -0.2638, 0.9995]
 Predicted: [0.0061, 0.0051, -0.0054, 0.0120, -0.0088, -0.0001, 0.9961]
 Time: 775.6s
 MAE: 0.0526, MSE: 0.0105, Task Success: 

 Sample 418: traj47
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0007, -0.0500, -0.0030, 0.0253, -0.0373, -0.4193, 1.0000]
 Predicted: [-0.0045, 0.0041, 0.0195, 0.0037, -0.0550, 0.0467, 0.0000]
 Time: 754.2s
 MAE: 0.2267, MSE: 0.1745, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0006, -0.0492, -0.0027, 0.0270, -0.0580, -0.3920, 0.9989]
 Predicted: [-0.0051, 0.0054, 0.0000, -0.0244, -0.0021, 0.0289, 0.9961]
 Time: 760.6s
 MAE: 0.0849, MSE: 0.0266, Task Success: 

 Sample 419: traj13
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0033, -0.0383, 0.0018, 0.0056, -0.0256, -0.0424, 0.9984]
 Predicted: [-0.0007, 0.0018, -0.0101, -0.0014, 0.0200, -0.0307, 0.9961]
 Time: 761.0s
 MAE: 0.0175, MSE: 0.0006, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0108, -0.0347, 0.0041, 0.0026, -0.0336, -0.0629, 1.0000]
 Predicted: [-0.0007, -0.0001, -0.0044, -0.0008, -0.0095, 0.0128, 0.9961]
 Time: 754.2s
 MAE: 0.0231, MSE: 0.0011, Task Success: 

Sample 420: traj235

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0200, 0.0173, 0.0049, 0.0002, -0.0454, -0.9515, 1.0000]
 Predicted: [-0.0033, 0.0035, -0.0057, -0.0008, 0.0073, -0.1500, 0.9961]
 Time: 756.3s
 MAE: 0.1296, MSE: 0.0923, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0169, 0.0330, 0.0037, -0.0167, -0.0571, -0.8901, 0.9972]
 Predicted: [-0.0007, 0.0018, -0.0075, 0.0075, 0.0079, 0.0048, 0.9961]
 Time: 761.4s
 MAE: 0.1493, MSE: 0.1153, Task Success: 

Sample 421: traj14

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0004, -0.0239, -0.0011, 0.0155, -0.0286, 0.5627, 0.9982]
 Predicted: [0.0009, 0.0044, -0.0052, 0.0190, 0.0079, -0.0017, 0.9961]
 Time: 751.9s
 MAE: 0.0913, MSE: 0.0458, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [0.0037, -0.0234, 0.0010, 0.0208, -0.0402, 0.5244, 0.9889]
🎯 Predicted: [0.0065, 0.0009, 0.0063, -0.0001, -0.0021, -0.0146, 0.9961]
 Time: 760.0s
 MAE: 0.0911, MSE: 0.0419, Task Success: ✓

Sample 422: traj232

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0095, 0.0338, -0.0070, -0.0079, -0.0286, -0.0080, 1.0000]
🎯 Predicted: [0.0016, -0.0030, -0.0073, -0.0033, -0.0028, -0.0162, 0.9961]
 Time: 769.0s
 MAE: 0.0130, MSE: 0.0003, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0093, 0.0322, 0.0008, -0.0071, -0.0496, 0.0044, 0.9984]
🎯 Predicted: [0.0016, -0.0004, -0.0065, 0.0005, -0.0028, -0.0210, 0.9961]
 Time: 755.8s
 MAE: 0.0190, MSE: 0.0006, Task Success: ✓

Sample 423: traj22

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0223, 0.0571, -0.0004, -0.0070, -0.0356, -0.2086, 0.9960]
🎯 Predicted: [-0.0029, 0.0038, -0.0002, -0.0238, 0.0207, 0.0322, 0.9961]
 Time: 754.8s

📊 MAE: 0.0553, MSE: 0.0092, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0153, 0.0504, -0.0011, -0.0151, -0.0622, -0.1654, 0.9963]
🎯 Predicted: [-0.0051, -0.0004, 0.0156, -0.0148, -0.0215, 0.0273, 0.0000]
⌚ Time: 762.3s
📊 MAE: 0.1868, MSE: 0.1478, Task Success: ✗

📸 Sample 424: traj204
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0014, -0.0091, -0.0091, 0.0042, -0.0317, -0.0139, 0.9963]
🎯 Predicted: [-0.0051, -0.0173, -0.0028, -0.0436, 0.0099, -0.0597, 0.9961]
⌚ Time: 767.9s
📊 MAE: 0.0223, MSE: 0.0009, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0162, 0.0058, 0.0067, -0.0052, -0.0435, -0.0185, 0.9970]
🎯 Predicted: [-0.0051, -0.0059, 0.0153, -0.0257, -0.0336, -0.0065, 0.9961]
⌚ Time: 756.7s
📊 MAE: 0.0121, MSE: 0.0002, Task Success: ✓

📸 Sample 425: traj25
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [-0.0140, 0.0148, 0.0057, -0.0123, -0.0348, -0.4294, 0.9991]

🎯 Predicted: [-0.0009, 0.0145, 0.0400, 0.0101, -0.0926, 0.0338, 0.9961]
⌚ Time: 768.9s
📊 MAE: 0.0849, MSE: 0.0314, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [0.0009, 0.0059, 0.0012, -0.0185, -0.0647, -0.3793, 1.0000]
🎯 Predicted: [-0.0004, 0.0057, -0.0002, 0.0050, -0.0061, 0.0080, 0.9961]
⌚ Time: 754.1s
📊 MAE: 0.0680, MSE: 0.0220, Task Success: ✓

📸 Sample 426: traj203
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [0.0058, -0.0278, 0.0087, 0.0037, -0.0145, 0.6653, 0.9906]
🎯 Predicted: [0.0078, -0.0017, -0.0122, -0.0225, 0.0006, -0.0130, 0.9961]
⌚ Time: 754.2s
📊 MAE: 0.1106, MSE: 0.0660, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [0.0241, -0.0217, 0.0026, -0.0048, -0.0417, 0.6060, 0.9975]
🎯 Predicted: [0.0078, -0.0017, -0.0093, -0.0225, 0.0180, -0.0146, 0.9961]
⌚ Time: 762.0s
📊 MAE: 0.1068, MSE: 0.0557, Task Success: ✓

📸 Sample 427: traj260
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)

 Image 1: im_42.jpg
 Ground Truth: [-0.0193, -0.0316, 0.0019, -0.0020, -0.0399, -0.9181, 1.0000]
 Predicted: [0.0072, 0.0083, -0.0122, 0.0114, 0.0032, -0.0049, 0.9961]
 Time: 763.1s
 MAE: 0.1506, MSE: 0.1198, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0155, -0.0363, -0.0028, 0.0103, -0.0564, -0.9102, 0.9968]
 Predicted: [0.0025, 0.0057, -0.0008, 0.0299, -0.0055, 0.0064, 0.9961]
 Time: 761.7s
 MAE: 0.1500, MSE: 0.1207, Task Success: 

 Sample 428: traj79
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0103, 0.0405, -0.0032, -0.0058, -0.0519, -0.5486, 0.9927]
 Predicted: [0.0007, 0.0067, -0.0034, 0.0056, -0.0075, 0.0080, 0.9961]
 Time: 756.4s
 MAE: 0.0942, MSE: 0.0447, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0178, 0.0422, 0.0011, -0.0058, -0.0578, -0.5048, 0.9932]
 Predicted: [-0.0027, 0.0038, -0.0156, 0.0152, 0.0434, -0.0275, 0.9961]
 Time: 763.9s
 MAE: 0.0968, MSE: 0.0344, Task Success: 

 Sample 429: traj294
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0148, 0.0182, -0.0040, -0.0076, -0.0276, 0.4870, 1.0000]
 Predicted: [0.0065, 0.0002, -0.0122, 0.0018, -0.0209, -0.0323, 0.9961]
 Time: 769.2s
 MAE: 0.0820, MSE: 0.0386, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0067, 0.0112, -0.0043, -0.0082, -0.0420, 0.4546, 0.9941]
 Predicted: [0.0092, 0.0086, -0.0086, 0.0075, -0.0135, -0.0065, 0.9961]
 Time: 780.0s
 MAE: 0.0738, MSE: 0.0305, Task Success:

Sample 430: traj46

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0058, 0.0628, 0.0017, -0.0061, -0.0157, -0.3489, 0.9980]
 Predicted: [0.0014, -0.0007, -0.0080, -0.0040, 0.0106, -0.0017, 0.9961]
 Time: 758.8s
 MAE: 0.0650, MSE: 0.0179, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0119, 0.0524, 0.0067, -0.0031, -0.0424, -0.3025, 1.0000]
 Predicted: [-0.0002, -0.0004, -0.0091, 0.0050, 0.0160, -0.0017, 0.9961]
 Time: 773.2s
 MAE: 0.0645, MSE: 0.0139, Task Success:

Sample 431: traj293

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [0.0335, -0.0129, 0.0002, -0.0004, -0.0264, -0.1595, 1.0000]
🎯 Predicted: [0.0014, 0.0167, 0.0104, 0.0350, -0.0148, 0.0644, 0.0000]
 Time: 751.8s
 MAE: 0.1918, MSE: 0.1505, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [0.0378, -0.0020, 0.0062, -0.0021, -0.0391, -0.1496, 0.9991]
🎯 Predicted: [0.0040, 0.0015, 0.0179, 0.0031, -0.0490, 0.0193, 0.0000]
 Time: 754.0s
 MAE: 0.1760, MSE: 0.1469, Task Success: ✗

Sample 432: traj267

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0113, -0.0089, 0.0040, 0.0107, -0.0132, 0.1489, 1.0000]
🎯 Predicted: [0.0027, 0.0018, -0.0075, 0.0069, 0.0213, -0.0065, 0.9961]
 Time: 758.6s
 MAE: 0.0334, MSE: 0.0037, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0081, -0.0195, 0.0074, 0.0166, -0.0401, 0.1312, 1.0000]
🎯 Predicted: [0.0083, 0.0057, -0.0109, 0.0133, 0.0086, -0.0065, 0.9961]
 Time: 755.9s
 MAE: 0.0362, MSE: 0.0032, Task Success: ✓

📸 Sample 433: traj258

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0232, -0.0290, 0.0015, 0.0218, -0.0390, 0.1598, 1.0000]

🎯 Predicted: [0.0029, 0.0005, -0.0054, 0.0011, -0.0028, -0.0001, 0.9961]

⌚ Time: 763.5s

📊 MAE: 0.0396, MSE: 0.0041, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [0.0111, -0.0337, -0.0074, 0.0264, -0.0490, 0.1177, 1.0000]

🎯 Predicted: [0.0108, 0.0057, -0.0052, 0.0043, -0.0135, -0.0001, 0.9961]

⌚ Time: 760.1s

📊 MAE: 0.0316, MSE: 0.0025, Task Success: ✓

📸 Sample 434: traj41

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0245, 0.0152, -0.0003, 0.0173, -0.0374, -0.1085, 1.0000]

🎯 Predicted: [0.0108, 0.0015, -0.0028, 0.0101, -0.0262, -0.0130, 0.9961]

⌚ Time: 785.0s

📊 MAE: 0.0211, MSE: 0.0014, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [0.0238, 0.0005, -0.0031, 0.0091, -0.0372, -0.0928, 1.0000]

🎯 Predicted: [0.0069, 0.0015, -0.0036, 0.0011, -0.0336, 0.0015, 0.9961]

⌚ Time: 806.1s
📊 MAE: 0.0183, MSE: 0.0013, Task Success:

📸 Sample 435: traj48

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0289, 0.0138, 0.0048, -0.0109, -0.0367, -0.5167, 0.9978]
🎯 Predicted: [0.0007, -0.0027, -0.0140, -0.0110, 0.0207, -0.0242, 0.9961]

⌚ Time: 791.4s
📊 MAE: 0.0881, MSE: 0.0353, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0179, 0.0028, -0.0003, -0.0023, -0.0588, -0.4582, 1.0000]
🎯 Predicted: [0.0061, 0.0041, -0.0052, 0.0094, 0.0012, -0.0081, 0.9961]
⌚ Time: 800.3s
📊 MAE: 0.0794, MSE: 0.0296, Task Success:

📸 Sample 436: traj251

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [0.0206, 0.0473, 0.0089, -0.0101, -0.0318, 0.7714, 0.9973]
🎯 Predicted: [-0.0062, 0.0018, 0.0008, 0.0050, -0.0035, 0.0225, 0.0000]
⌚ Time: 783.3s
📊 MAE: 0.2672, MSE: 0.2228, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg

✓ Ground Truth: [0.0109, 0.0497, 0.0000, -0.0146, -0.0432, 0.7384, 0.9986]
⌚ Predicted: [0.0034, -0.0160, 0.0148, -0.0250, -0.0336, -0.0049, 0.0000]
⌚ Time: 811.1s
📊 MAE: 0.2643, MSE: 0.2221, Task Success: ✗

📸 Sample 437: traj83

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0128, 0.0350, -0.0028, -0.0058, -0.0219, -0.0542, 0.9939]
⌚ Predicted: [0.0009, -0.0004, 0.0037, 0.0005, 0.0066, -0.0081, 0.0000]
⌚ Time: 800.8s
📊 MAE: 0.1615, MSE: 0.1417, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [-0.0075, 0.0329, 0.0036, -0.0006, -0.0386, -0.0413, 0.9966]
⌚ Predicted: [0.0056, -0.0059, 0.0263, 0.0216, -0.0557, -0.0017, 0.0000]
⌚ Time: 789.1s
📊 MAE: 0.1643, MSE: 0.1425, Task Success: ✗

📸 Sample 438: traj77

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [-0.0259, 0.0303, 0.0097, 0.0046, -0.0188, 0.7186, 1.0000]
⌚ Predicted: [0.0011, 0.0015, -0.0114, 0.0126, 0.0032, 0.0015, 0.9961]
⌚ Time: 780.0s
📊 MAE: 0.1183, MSE: 0.0738, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)

Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0212, 0.0307, -0.0003, 0.0118, -0.0469, 0.6939, 1.0000]
🎯 Predicted: [0.0002, 0.0012, -0.0018, 0.0056, 0.0294, 0.0209, 0.9961]
⌚ Time: 796.1s
 MAE: 0.1160, MSE: 0.0657, Task Success: ✓

Sample 439: traj256

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0229, 0.0156, -0.0033, 0.0094, -0.0246, -0.8551, 1.0000]
🎯 Predicted: [0.0040, 0.0041, -0.0091, 0.0075, -0.0075, 0.0338, 0.9961]
⌚ Time: 805.4s
 MAE: 0.1366, MSE: 0.1130, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0208, 0.0220, -0.0005, 0.0098, -0.0422, -0.8215, 0.9981]
🎯 Predicted: [0.0092, -0.0069, -0.0023, -0.0155, -0.0343, -0.0549, 0.9961]
⌚ Time: 821.0s
 MAE: 0.1232, MSE: 0.0843, Task Success: ✓

Sample 440: traj70

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0323, -0.0195, -0.0078, -0.0096, -0.0218, 0.4622, 1.0000]
🎯 Predicted: [-0.0033, -0.0020, -0.0036, -0.0155, 0.0019, 0.0080, 0.9961]
⌚ Time: 789.8s
 MAE: 0.0769, MSE: 0.0297, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0278, -0.0196, -0.0119, 0.0073, -0.0474, 0.4230, 1.0000]
 Predicted: [0.0029, 0.0002, -0.0065, 0.0011, 0.0046, -0.0001, 0.9961]
 Time: 816.6s
 MAE: 0.0773, MSE: 0.0262, Task Success:

Sample 441: traj269
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0046, 0.0265, 0.0032, 0.0008, -0.0393, -0.3426, 1.0000]
 Predicted: [0.0114, 0.0086, -0.0086, 0.0120, 0.0032, -0.0065, 0.9961]
 Time: 770.7s
 MAE: 0.0614, MSE: 0.0165, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0041, 0.0273, -0.0027, 0.0152, -0.0606, -0.2959, 0.9944]
 Predicted: [0.0108, 0.0083, -0.0122, 0.0133, 0.0086, -0.0001, 0.9961]
 Time: 776.0s
 MAE: 0.0589, MSE: 0.0133, Task Success:

Sample 442: traj84
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0248, -0.0423, 0.0001, 0.0068, -0.0102, -0.6461, 0.9986]
 Predicted: [0.0110, 0.0086, 0.0070, 0.0356, -0.0490, -0.0291, 0.0000]
 Time: 783.4s
 MAE: 0.2538, MSE: 0.1977, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0224, -0.0395, -0.0021, 0.0251, -0.0422, -0.6040, 1.0000]
 Predicted: [0.0061, 0.0083, 0.0107, -0.0052, -0.0423, 0.0257, 0.0000]
 Time: 841.0s
 MAE: 0.2499, MSE: 0.2001, Task Success:

Sample 443: traj24

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0331, 0.0116, 0.0022, 0.0038, -0.0188, 0.9361, 0.9959]
 Predicted: [-0.0011, -0.0276, 0.0255, 0.0075, -0.0343, -0.0275, 0.0000]
 Time: 788.7s
 MAE: 0.2965, MSE: 0.2748, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0204, 0.0139, 0.0010, -0.0078, -0.0299, 0.9078, 0.9947]
 Predicted: [0.0130, -0.0234, 0.0104, -0.0321, -0.0416, -0.0645, 0.0000]
 Time: 802.7s
 MAE: 0.2939, MSE: 0.2767, Task Success:

Sample 444: traj202

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0095, -0.0185, -0.0008, 0.0049, -0.0266, -0.0904, 0.9967]
 Predicted: [0.0130, -0.0325, 0.0138, -0.0353, -0.0597, -0.0952, 0.0000]

⌚ Time: 780.6s
📊 MAE: 0.1608, MSE: 0.1424, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0086, -0.0134, -0.0024, 0.0023, -0.0475, -0.0813, 0.9993]
🎯 Predicted: [0.0099, 0.0086, 0.0159, 0.0165, -0.0524, 0.0338, 0.0000]
⌚ Time: 773.3s
📊 MAE: 0.1703, MSE: 0.1447, Task Success: ✗

📸 Sample 445: traj23
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0173, -0.0162, -0.0038, 0.0081, -0.0371, 0.3745, 1.0000]
🎯 Predicted: [-0.0002, -0.0007, -0.0031, 0.0005, 0.0046, -0.0001, 0.0000]
⌚ Time: 1686.4s
📊 MAE: 0.2082, MSE: 0.1632, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0155, -0.0137, 0.0071, -0.0059, -0.0534, 0.3285, 0.9926]
🎯 Predicted: [0.0002, 0.0002, 0.0003, -0.0225, -0.0329, -0.0597, -0.1176]
⌚ Time: 2647.8s
📊 MAE: 0.2245, MSE: 0.1978, Task Success: ✗

📸 Sample 446: traj205
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg

Ground Truth: [0.0129, -0.0407, 0.0080, 0.0082, -0.0198, 0.1749, 1.0000]

Predicted: [-0.0013, 0.0051, -0.0010, 0.0299, 0.0052, 0.0289, 0.0000]

Time: 6278.8s

MAE: 0.1802, MSE: 0.1464, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0133, -0.0410, 0.0013, 0.0076, -0.0331, 0.1345, 1.0000]

Predicted: [0.0029, 0.0005, -0.0091, 0.0011, 0.0052, -0.0065, 0.9961]

Time: 2400.8s

MAE: 0.0360, MSE: 0.0033, Task Success:

Sample 447: traj15

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [0.0014, -0.0033, 0.0103, 0.0246, -0.0313, -0.1794, 0.9976]

Predicted: [-0.0060, 0.0135, 0.0138, -0.0257, -0.0081, 0.0338, 0.9961]

Time: 765.0s

MAE: 0.0451, MSE: 0.0070, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0037, -0.0181, -0.0086, 0.0191, -0.0386, -0.1534, 0.9952]

Predicted: [-0.0078, 0.0119, 0.0122, -0.0078, 0.0113, 0.0289, 0.9961]

Time: 787.3s

MAE: 0.0460, MSE: 0.0054, Task Success:

Sample 448: traj233

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [0.0418, 0.0069, -0.0062, 0.0049, -0.0262, -0.6377, 1.0000]

Predicted: [-0.0011, 0.0061, 0.0156, 0.0043, 0.0113, 0.0418, 0.0000]

Time: 801.4s

MAE: 0.2547, MSE: 0.2093, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0455, 0.0088, 0.0049, 0.0224, -0.0375, -0.5918, 0.9981]

Predicted: [0.0023, 0.0061, 0.0102, -0.0391, -0.0001, 0.0193, 0.0000]

Time: 775.3s

MAE: 0.2513, MSE: 0.1967, Task Success: ✗

📸 Sample 449: traj12

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0043, 0.0402, -0.0040, 0.0058, -0.0382, -0.1269, 1.0000]

Predicted: [-0.0009, 0.0041, -0.0109, 0.0126, -0.0095, 0.0289, 0.9961]

Time: 787.8s

MAE: 0.0345, MSE: 0.0038, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0005, 0.0437, 0.0066, 0.0086, -0.0361, -0.0855, 1.0000]

Predicted: [0.0110, 0.0112, -0.0083, 0.0133, 0.0032, 0.0209, 0.9961]

Time: 802.1s

MAE: 0.0305, MSE: 0.0020, Task Success: ✓

📸 Sample 450: traj234

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0027, -0.0410, -0.0010, 0.0078, -0.0277, -0.3227, 1.0000]
 Predicted: [-0.0051, -0.0046, -0.0130, -0.0148, 0.0032, -0.0194, 0.9961]
 Time: 779.6s
 MAE: 0.0596, MSE: 0.0136, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0091, -0.0429, 0.0040, 0.0146, -0.0408, -0.3040, 1.0000]
 Predicted: [-0.0051, -0.0007, -0.0156, -0.0097, 0.0394, 0.0048, 0.9961]
 Time: 775.5s
 MAE: 0.0705, MSE: 0.0150, Task Success: 

Sample 451: traj56

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0239, -0.0513, 0.0082, 0.0013, -0.0079, -0.0579, 1.0000]
 Predicted: [0.0076, 0.0090, -0.0052, 0.0241, 0.0079, 0.0015, 0.9961]
 Time: 804.5s
 MAE: 0.0274, MSE: 0.0012, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0189, -0.0346, 0.0010, 0.0097, -0.0252, -0.0494, 1.0000]
 Predicted: [0.0000, -0.0001, -0.0088, 0.0005, 0.0200, -0.0033, 0.9961]
 Time: 776.8s
 MAE: 0.0240, MSE: 0.0008, Task Success: 

Sample 452: traj284

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0246, 0.0492, -0.0031, -0.0048, -0.0191, -0.9712, 0.9919]
 Predicted: [0.0056, -0.0105, 0.0091, -0.0250, -0.0329, -0.0130, 0.0000]
 Time: 788.6s
 MAE: 0.2965, MSE: 0.2724, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0495, 0.0516, 0.0098, -0.0021, -0.0477, -0.9101, 0.9963]
 Predicted: [-0.0013, -0.0266, 0.0174, 0.0171, -0.0329, -0.0162, 0.0000]
 Time: 766.8s
 MAE: 0.2944, MSE: 0.2573, Task Success: ✗

Sample 453: traj69
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0543, -0.0603, 0.0014, 0.0043, -0.0288, 0.9646, 1.0000]
 Predicted: [0.0090, -0.0140, -0.0075, -0.0570, 0.0052, -0.0404, 0.0000]
 Time: 769.4s
 MAE: 0.3170, MSE: 0.2887, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0456, -0.0546, -0.0012, 0.0133, -0.0627, 0.9189, 1.0000]
 Predicted: [0.0069, -0.0131, -0.0075, -0.0570, 0.0052, -0.0404, 0.0000]
 Time: 768.0s
 MAE: 0.3140, MSE: 0.2763, Task Success: ✗

📸 Sample 454: traj270

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [0.0103, 0.0315, -0.0050, 0.0044, -0.0226, 0.5814, 1.0000]

🎯 Predicted: [-0.0045, -0.0127, 0.0024, -0.0244, -0.0303, 0.0370, 0.0000]

⌚ Time: 762.8s

📊 MAE: 0.2353, MSE: 0.1856, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [0.0123, 0.0258, 0.0052, -0.0067, -0.0387, 0.5496, 0.9920]

🎯 Predicted: [-0.0045, -0.0007, 0.0140, -0.0021, -0.0162, 0.0048, 0.0000]

⌚ Time: 762.9s

📊 MAE: 0.2309, MSE: 0.1832, Task Success: ✗

📸 Sample 455: traj51

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 1: im_42.jpg

✓ Ground Truth: [0.0292, -0.0259, 0.0087, 0.0134, -0.0297, 0.1009, 0.9970]

🎯 Predicted: [-0.0074, -0.0221, 0.0153, -0.0065, -0.0356, -0.0339, 0.0000]

⌚ Time: 752.6s

📊 MAE: 0.1721, MSE: 0.1448, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

📷 Image 2: im_43.jpg

✓ Ground Truth: [0.0387, -0.0238, 0.0051, 0.0088, -0.0418, 0.0796, 0.9993]

🎯 Predicted: [0.0253, 0.0193, -0.0125, 0.0209, -0.0081, 0.0725, 0.9961]

⌚ Time: 762.5s

 MAE: 0.0186, MSE: 0.0005, Task Success: ✓

 Sample 456: traj248

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

✓ Ground Truth: [-0.0014, -0.0235, -0.0023, 0.0137, -0.0185, -0.3063, 0.9969]

✖ Predicted: [-0.0065, 0.0187, -0.0088, 0.0037, -0.0001, 0.1015, 0.9961]

 Time: 763.2s

 MAE: 0.0701, MSE: 0.0241, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

✓ Ground Truth: [0.0081, -0.0322, 0.0011, 0.0128, -0.0364, -0.2849, 0.9995]

✖ Predicted: [0.0016, 0.0242, 0.0068, 0.0318, -0.0209, 0.0644, 0.9961]

 Time: 747.2s

 MAE: 0.0651, MSE: 0.0180, Task Success: ✖

 Sample 457: traj277

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

✓ Ground Truth: [0.0019, 0.0308, 0.0012, -0.0050, -0.0468, 0.1286, 0.9955]

✖ Predicted: [-0.0027, 0.0028, 0.0005, 0.0094, 0.0160, 0.0338, 0.9961]

 Time: 753.0s

 MAE: 0.0294, MSE: 0.0020, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

✓ Ground Truth: [0.0018, 0.0293, 0.0025, -0.0147, -0.0652, 0.1207, 1.0000]

🎯 Predicted: [-0.0040, 0.0009, -0.0114, 0.0088, 0.0394, 0.0048, 0.9961]
⌚ Time: 761.2s
📊 MAE: 0.0423, MSE: 0.0037, Task Success: ✓

📸 Sample 458: traj283

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [-0.0131, 0.0476, -0.0018, -0.0067, -0.0298, 0.4430, 0.9954]

🎯 Predicted: [-0.0143, -0.0173, 0.0078, 0.0126, -0.0336, 0.1885, 0.9961]

⌚ Time: 749.2s

📊 MAE: 0.0506, MSE: 0.0099, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 2: im_43.jpg

✓ Ground Truth: [-0.0109, 0.0456, 0.0054, -0.0102, -0.0437, 0.4083, 0.9987]

🎯 Predicted: [-0.0011, -0.0218, 0.0182, 0.0062, -0.0490, -0.0130, 0.9961]

⌚ Time: 768.9s

📊 MAE: 0.0765, MSE: 0.0261, Task Success: ✗

📸 Sample 459: traj67

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

🖼️ Image 1: im_42.jpg

✓ Ground Truth: [0.0273, -0.0310, 0.0039, 0.0194, -0.0352, 0.7312, 1.0000]

🎯 Predicted: [-0.0022, -0.0014, -0.0039, 0.0018, -0.0061, -0.0017, 0.9961]

⌚ Time: 764.8s

📊 MAE: 0.1215, MSE: 0.0772, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg
 Ground Truth: [0.0171, -0.0335, -0.0110, 0.0182, -0.0509, 0.6832, 1.0000]
 Predicted: [-0.0016, -0.0079, -0.0041, -0.0008, -0.0001, -0.0242, 0.9961]
 Time: 759.6s
 MAE: 0.1189, MSE: 0.0721, Task Success: 

Sample 460: traj93

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0256, 0.0065, -0.0045, 0.0031, -0.0337, 0.3232, 0.9982]

 Predicted: [0.0110, 0.0041, 0.0005, 0.0197, -0.0591, -0.0097, 0.9961]

 Time: 750.7s

 MAE: 0.0570, MSE: 0.0160, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

 Ground Truth: [0.0227, 0.0161, -0.0000, 0.0053, -0.0442, 0.2913, 1.0000]

 Predicted: [0.0023, 0.0051, 0.0018, 0.0184, 0.0026, -0.0033, 0.9961]

 Time: 752.7s

 MAE: 0.0559, MSE: 0.0128, Task Success: 

Sample 461: traj241

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

 Ground Truth: [0.0207, -0.0322, -0.0010, 0.0017, -0.0228, 0.9442, 1.0000]

 Predicted: [0.0121, -0.0169, 0.0021, -0.0091, -0.0329, -0.0500, 0.0000]

 Time: 747.4s

 MAE: 0.2917, MSE: 0.2842, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0286, -0.0308, -0.0057, 0.0054, -0.0467, 0.9030, 1.0000]
 Predicted: [0.0121, -0.0169, 0.0021, -0.0244, -0.0329, -0.0500, 0.0000]
 Time: 755.5s
 MAE: 0.2907, MSE: 0.2728, Task Success: X

Sample 462: traj58

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0131, -0.0177, -0.0051, 0.0052, -0.0244, 0.0402, 0.9956]
 Predicted: [-0.0051, -0.0014, 0.0140, 0.0056, 0.0052, -0.0178, 0.0000]
 Time: 750.8s
 MAE: 0.1625, MSE: 0.1423, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0117, 0.0004, -0.0002, 0.0167, -0.0336, 0.0315, 0.9979]
 Predicted: [0.0029, -0.0360, 0.0289, 0.0324, -0.0557, -0.0742, 0.0000]
 Time: 764.2s
 MAE: 0.1737, MSE: 0.1443, Task Success: X

Sample 463: traj94

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0057, -0.0025, -0.0030, 0.0109, -0.0187, 0.1448, 1.0000]
 Predicted: [-0.0027, -0.0007, -0.0075, -0.0027, 0.0274, -0.0049, 0.9961]
 Time: 766.7s
 MAE: 0.0318, MSE: 0.0035, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0093, -0.0120, -0.0049, 0.0099, -0.0415, 0.1078, 0.9967]
 Predicted: [-0.0027, 0.0051, -0.0002, -0.0193, 0.0153, -0.0097, 0.9961]
 Time: 772.8s
 MAE: 0.0332, MSE: 0.0026, Task Success: 

Sample 464: traj279

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0275, 0.0223, 0.0117, -0.0022, -0.0212, -0.7177, 1.0000]
 Predicted: [0.0005, -0.0202, -0.0104, -0.0091, -0.0169, 0.1192, 0.0000]
 Time: 768.8s
 MAE: 0.2772, MSE: 0.2434, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0174, 0.0210, -0.0003, -0.0121, -0.0555, -0.6810, 0.9937]
 Predicted: [0.0130, 0.0018, 0.0278, -0.0295, 0.0253, 0.0161, 0.0000]
 Time: 781.2s
 MAE: 0.2666, MSE: 0.2117, Task Success: 

Sample 465: traj60

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0173, 0.0294, 0.0087, -0.0068, -0.0085, 0.4726, 1.0000]
 Predicted: [0.0034, -0.0007, -0.0122, 0.0037, -0.0262, -0.0323, 0.9961]
 Time: 757.5s

📊 MAE: 0.0860, MSE: 0.0367, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0213, 0.0304, 0.0055, -0.0164, -0.0157, 0.4472, 1.0000]
🎯 Predicted: [-0.0004, 0.0041, -0.0132, 0.0222, -0.0262, -0.1081, 0.9961]
⌚ Time: 759.4s
📊 MAE: 0.0964, MSE: 0.0445, Task Success: ✓

📸 Sample 466: traj246
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0081, -0.0110, 0.0037, 0.0074, -0.0218, -0.6438, 0.9957]
🎯 Predicted: [0.0014, -0.0007, 0.0000, -0.0059, -0.0068, 0.0112, 0.0000]
⌚ Time: 760.9s
📊 MAE: 0.2428, MSE: 0.2030, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0032, -0.0174, -0.0038, 0.0024, -0.0467, -0.6387, 1.0000]
🎯 Predicted: [0.0061, -0.0040, -0.0065, 0.0177, -0.0262, -0.0291, 0.9961]
⌚ Time: 773.0s
📊 MAE: 0.0955, MSE: 0.0532, Task Success: ✓

📸 Sample 467: traj212
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0024, 0.0258, 0.0072, 0.0041, -0.0201, 0.3751, 1.0000]

🎯 Predicted: [0.0020, 0.0028, 0.0003, 0.0120, -0.0021, -0.0033, 0.0000]
⌚ Time: 760.7s
📊 MAE: 0.2049, MSE: 0.1634, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [0.0089, 0.0153, -0.0028, 0.0003, -0.0403, 0.3349, 0.9952]
🎯 Predicted: [0.0072, 0.0093, -0.0091, 0.0094, -0.0309, 0.0499, 0.9961]
⌚ Time: 758.8s
📊 MAE: 0.0455, MSE: 0.0116, Task Success: ✓

📸 Sample 468: traj34
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 1: im_42.jpg
✓ Ground Truth: [0.0145, -0.0054, -0.0029, -0.0089, -0.0347, 0.8016, 1.0000]
🎯 Predicted: [0.0027, 0.0015, 0.0016, 0.0082, -0.0068, -0.0097, 0.0000]
⌚ Time: 770.6s
📊 MAE: 0.2685, MSE: 0.2371, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
🖼️ Image 2: im_43.jpg
✓ Ground Truth: [0.0120, 0.0020, 0.0054, -0.0008, -0.0411, 0.7751, 1.0000]
🎯 Predicted: [-0.0033, 0.0015, -0.0080, -0.0097, 0.0481, -0.0097, 0.9961]
⌚ Time: 777.1s
📊 MAE: 0.1309, MSE: 0.0892, Task Success: ✓

📸 Sample 469: traj215
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)

 Image 1: im_42.jpg
 Ground Truth: [-0.0051, 0.0030, 0.0016, 0.0028, -0.0211, -0.2815, 0.9967]
 Predicted: [-0.0036, -0.0030, -0.0135, -0.0148, 0.0334, -0.0049, 0.9961]
 Time: 757.5s
 MAE: 0.0531, MSE: 0.0114, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0007, 0.0083, -0.0320, 0.0276, -0.0402, -0.2463, 0.9895]
 Predicted: [-0.0024, 0.0073, -0.0052, 0.0082, -0.0035, 0.0918, 0.9961]
 Time: 766.7s
 MAE: 0.0617, MSE: 0.0167, Task Success: 

 Sample 470: traj33
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0001, 0.0027, -0.0321, 0.0128, -0.0208, 0.6079, 1.0000]
 Predicted: [-0.0031, 0.0009, 0.0042, 0.0018, 0.0079, 0.0257, 0.9961]
 Time: 765.6s
 MAE: 0.0953, MSE: 0.0487, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0035, -0.0011, -0.0227, 0.0174, -0.0506, 0.5710, 0.9979]
 Predicted: [0.0027, 0.0336, 0.0182, 0.0209, -0.0604, 0.1079, 0.0000]
 Time: 751.7s
 MAE: 0.2215, MSE: 0.1733, Task Success: 

 Sample 471: traj223
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [-0.0206, 0.0069, 0.0012, 0.0110, -0.0220, 0.5111, 1.0000]
🎯 Predicted: [0.0074, 0.0041, -0.0002, 0.0184, 0.0193, 0.0128, 0.9961]
 Time: 756.2s
 MAE: 0.0833, MSE: 0.0358, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [-0.0238, 0.0027, 0.0036, 0.0162, -0.0365, 0.4899, 1.0000]
🎯 Predicted: [0.0056, 0.0022, 0.0008, 0.0222, -0.0296, 0.0080, 0.9961]
 Time: 769.4s
 MAE: 0.0759, MSE: 0.0333, Task Success: ✓

Sample 472: traj224

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [0.0086, 0.0060, 0.0001, -0.0017, -0.0243, 0.0712, 1.0000]
🎯 Predicted: [-0.0004, 0.0022, -0.0044, 0.0120, 0.0066, 0.0096, 0.9961]
 Time: 754.4s
 MAE: 0.0182, MSE: 0.0007, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [0.0224, 0.0089, -0.0060, 0.0009, -0.0363, 0.0576, 0.9940]
🎯 Predicted: [-0.0004, 0.0022, -0.0080, 0.0120, 0.0200, 0.0096, 0.9961]
 Time: 767.7s
 MAE: 0.0213, MSE: 0.0009, Task Success: ✓

Sample 473: traj61

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [0.0432, -0.0360, -0.0040, 0.0205, -0.0279, 0.7410, 1.0000]
🎯 Predicted: [-0.0094, -0.0040, -0.0013, -0.0302, -0.0356, 0.2030, 0.9961]
 Time: 746.4s
 MAE: 0.0982, MSE: 0.0423, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [0.0374, -0.0282, 0.0001, 0.0125, -0.0515, 0.6975, 0.9911]
🎯 Predicted: [0.0154, 0.0057, -0.0109, 0.0056, -0.0135, -0.0162, 0.9961]
 Time: 757.4s
 MAE: 0.1186, MSE: 0.0732, Task Success: ✓

 Sample 474: traj278
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
✓ Ground Truth: [0.0096, -0.0108, 0.0055, 0.0185, -0.0314, 0.4154, 0.9936]
🎯 Predicted: [0.0083, -0.0050, -0.0031, -0.0397, -0.0175, -0.0130, 0.9961]
 Time: 776.7s
 MAE: 0.0741, MSE: 0.0267, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
✓ Ground Truth: [0.0070, -0.0050, 0.0030, 0.0173, -0.0321, 0.3554, 0.9964]
🎯 Predicted: [-0.0002, 0.0018, 0.0213, 0.0145, -0.0390, 0.0386, 0.9961]
 Time: 757.1s
 MAE: 0.0513, MSE: 0.0144, Task Success: ✓

 Sample 475: traj95

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0144, 0.0176, 0.0057, -0.0026, -0.0494, 0.7567, 0.9899]
 Predicted: [0.0005, 0.0054, -0.0002, 0.0401, 0.0113, -0.0194, 0.9961]
 Time: 751.4s
 MAE: 0.1312, MSE: 0.0869, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0144, 0.0287, -0.0029, -0.0042, -0.0593, 0.7148, 0.9965]
 Predicted: [0.0005, 0.0122, -0.0049, 0.0248, 0.0032, -0.0339, 0.9961]
 Time: 751.8s
 MAE: 0.1249, MSE: 0.0808, Task Success:

Sample 476: traj247

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0052, -0.0345, 0.0020, 0.0146, -0.0273, -0.9289, 0.9921]
 Predicted: [-0.0024, -0.0101, 0.0182, 0.0056, -0.0148, -0.0162, 0.0000]
 Time: 761.2s
 MAE: 0.2814, MSE: 0.2598, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0031, -0.0370, -0.0015, 0.0266, -0.0541, -0.8953, 0.9969]
 Predicted: [0.0000, 0.0012, -0.0008, -0.0014, 0.0260, -0.0097, 0.0000]
 Time: 759.8s
 MAE: 0.2904, MSE: 0.2553, Task Success:

Sample 477: traj92

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0011, -0.0167, -0.0045, -0.0026, -0.0350, -0.1137, 0.9890]

Predicted: [0.0081, -0.0173, 0.0270, 0.0088, -0.0765, -0.0404, 0.0000]

Time: 753.5s

MAE: 0.1652, MSE: 0.1409, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0013, -0.0163, -0.0020, 0.0045, -0.0389, -0.1066, 1.0000]

Predicted: [-0.0027, 0.0009, -0.0067, 0.0050, 0.0227, 0.0032, 0.9961]

Time: 761.7s

MAE: 0.0284, MSE: 0.0023, Task Success:

Sample 478: traj66

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [0.0062, -0.0435, 0.0039, 0.0107, -0.0508, -0.7411, 1.0000]

Predicted: [0.0045, -0.0020, -0.0057, -0.0040, -0.0162, -0.0323, 0.9961]

Time: 753.8s

MAE: 0.1164, MSE: 0.0722, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0002, -0.0492, 0.0044, 0.0179, -0.0722, -0.7231, 0.9958]

Predicted: [0.0108, -0.0202, 0.0034, -0.0065, -0.0135, -0.0404, 0.9961]

Time: 762.2s
 MAE: 0.1153, MSE: 0.0673, Task Success: ✓

Sample 479: traj59

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

✓ Ground Truth: [-0.0095, 0.0120, 0.0046, -0.0103, -0.0475, 0.8552, 0.9953]

⌚ Predicted: [0.0038, 0.0077, 0.0166, -0.0116, -0.0316, 0.0241, 0.0000]

Time: 759.4s

MAE: 0.2676, MSE: 0.2403, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

✓ Ground Truth: [-0.0087, 0.0058, 0.0010, 0.0022, -0.0781, 0.8083, 1.0000]

⌚ Predicted: [-0.0045, 0.0086, 0.0224, 0.0267, 0.0026, 0.0161, 0.0000]

Time: 762.0s

MAE: 0.2751, MSE: 0.2336, Task Success: ✗

Sample 480: traj240

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

✓ Ground Truth: [-0.0434, 0.0213, 0.0048, -0.0015, -0.0249, -0.0143, 0.9954]

⌚ Predicted: [0.0000, -0.0024, -0.0093, 0.0133, 0.0106, -0.0081, 0.9961]

Time: 767.5s

MAE: 0.0198, MSE: 0.0006, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

✓ Ground Truth: [-0.0342, 0.0157, 0.0069, -0.0069, -0.0647, -0.0013, 1.0000]
⌚ Predicted: [-0.0007, -0.0024, 0.0003, -0.0065, 0.0039, -0.0146, 0.9961]
⌚ Time: 787.1s
📊 MAE: 0.0206, MSE: 0.0009, Task Success: ✓

📸 Sample 481: traj249

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [-0.0233, -0.0178, -0.0024, -0.0037, -0.0219, 0.1070, 1.0000]
⌚ Predicted: [-0.0013, 0.0035, -0.0075, 0.0075, -0.0236, 0.0257, 0.9961]
⌚ Time: 781.5s
📊 MAE: 0.0209, MSE: 0.0011, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [-0.0139, -0.0167, -0.0020, 0.0020, -0.0523, 0.0782, 1.0000]
⌚ Predicted: [-0.0060, -0.0011, -0.0106, -0.0052, 0.0428, -0.0017, 0.9961]
⌚ Time: 787.5s
📊 MAE: 0.0312, MSE: 0.0023, Task Success: ✓

📸 Sample 482: traj50

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [-0.0202, 0.0137, 0.0088, 0.0051, -0.0122, 0.5088, 0.9923]
⌚ Predicted: [0.0072, -0.0131, 0.0400, 0.0101, -0.0926, -0.0049, 0.0000]
⌚ Time: 784.1s
📊 MAE: 0.2395, MSE: 0.1796, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)

Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0146, 0.0267, -0.0096, -0.0045, -0.0294, 0.4635, 0.9976]
 Predicted: [-0.0022, 0.0048, -0.0088, 0.0107, 0.0032, 0.0080, 0.0000]
 Time: 795.2s
 MAE: 0.2194, MSE: 0.1721, Task Success: X

Sample 483: traj282

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0025, -0.0126, 0.0010, 0.0017, -0.0420, 0.8355, 0.9977]
 Predicted: [0.0096, -0.0043, -0.0023, 0.0145, -0.0122, -0.0355, 0.9961]
 Time: 787.6s
 MAE: 0.1341, MSE: 0.1086, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0016, -0.0015, -0.0063, 0.0060, -0.0646, 0.7798, 0.9943]
 Predicted: [0.0101, -0.0121, -0.0065, -0.0040, -0.0423, -0.0307, 0.9961]
 Time: 2795.7s
 MAE: 0.1234, MSE: 0.0939, Task Success: ✓

Sample 484: traj276

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0212, -0.0203, -0.0027, 0.0060, -0.0301, 0.3083, 0.9971]
 Predicted: [0.0016, -0.0011, -0.0083, -0.0219, -0.0169, -0.0162, 0.0000]
 Time: 826.5s
 MAE: 0.2015, MSE: 0.1574, Task Success: X
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0170, -0.0207, 0.0084, 0.0146, -0.0714, 0.2650, 1.0000]
 Predicted: [0.0029, 0.0041, -0.0002, -0.0148, -0.0303, 0.0467, 0.9961]
 Time: 827.1s
 MAE: 0.0495, MSE: 0.0073, Task Success: 

Sample 485: traj57

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0197, -0.0350, 0.0066, 0.0029, -0.0258, 0.3555, 1.0000]
 Predicted: [0.0025, 0.0057, -0.0039, 0.0120, -0.0088, 0.0064, 0.9961]
 Time: 815.5s
 MAE: 0.0647, MSE: 0.0178, Task Success: 
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0238, -0.0254, -0.0031, 0.0027, -0.0402, 0.3092, 0.9970]
 Predicted: [-0.0007, 0.0022, -0.0083, 0.0126, 0.0106, 0.0096, 0.9961]
 Time: 785.1s
 MAE: 0.0596, MSE: 0.0134, Task Success: 

Sample 486: traj271

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0011, 0.0112, -0.0112, -0.0034, -0.0390, 0.5430, 1.0000]
 Predicted: [-0.0051, 0.0086, -0.0013, 0.0050, 0.0160, 0.0161, 0.0000]
 Time: 807.3s
 MAE: 0.2299, MSE: 0.1830, Task Success: 

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0088, 0.0115, -0.0032, -0.0135, -0.0554, 0.5205, 1.0000]
 Predicted: [-0.0051, -0.0004, 0.0034, 0.0088, 0.0140, 0.0015, 0.9961]
 Time: 788.2s
 MAE: 0.0924, MSE: 0.0393, Task Success:

Sample 487: traj68

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0259, -0.0518, -0.0023, 0.0099, -0.0205, 0.8609, 0.9899]
 Predicted: [-0.0130, 0.0086, 0.0156, 0.0101, -0.0410, 0.0563, 0.0000]
 Time: 814.5s
 MAE: 0.2723, MSE: 0.2331, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0229, -0.0472, -0.0031, 0.0157, -0.0459, 0.8396, 1.0000]
 Predicted: [-0.0076, 0.0125, 0.0112, 0.0050, -0.0276, 0.0918, 0.0000]
 Time: 823.4s
 MAE: 0.2666, MSE: 0.2234, Task Success:

Sample 488: traj285

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0245, 0.0542, -0.0038, -0.0095, -0.0210, 0.9181, 1.0000]
 Predicted: [0.0121, 0.0235, 0.0143, 0.0318, -0.0926, 0.0338, 0.0000]

⌚ Time: 869.3s
📊 MAE: 0.2940, MSE: 0.2557, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0249, 0.0549, 0.0005, -0.0100, -0.0400, 0.8986, 1.0000]
🎯 Predicted: [0.0130, 0.0116, -0.0018, 0.0184, -0.0557, 0.0660, 0.0000]
⌚ Time: 757.8s
📊 MAE: 0.2763, MSE: 0.2423, Task Success: ✗

📸 Sample 489: traj225
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg
✓ Ground Truth: [0.0021, -0.0350, -0.0006, 0.0041, -0.0329, 0.5191, 0.9914]
🎯 Predicted: [-0.0076, 0.0077, -0.0018, -0.0276, 0.0320, 0.1095, 0.9961]
⌚ Time: 758.3s
📊 MAE: 0.0806, MSE: 0.0250, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 2: im_43.jpg
✓ Ground Truth: [0.0209, -0.0219, -0.0013, 0.0078, -0.0495, 0.4634, 1.0000]
🎯 Predicted: [-0.0056, -0.0140, -0.0047, 0.0075, 0.0200, -0.0371, 0.9961]
⌚ Time: 772.1s
📊 MAE: 0.0874, MSE: 0.0366, Task Success: ✓

📸 Sample 490: traj222
Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
📷 Image 1: im_42.jpg

Ground Truth: [-0.0085, 0.0269, -0.0001, 0.0033, -0.0269, -0.5398, 0.9955]

Predicted: [-0.0092, -0.0001, -0.0078, -0.0276, 0.0160, -0.0242, 0.9961]

Time: 760.5s

MAE: 0.0893, MSE: 0.0385, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0071, 0.0225, -0.0064, 0.0035, -0.0347, -0.4711, 1.0000]

Predicted: [-0.0013, 0.0031, -0.0026, 0.0101, 0.0032, 0.0096, 0.9961]

Time: 769.6s

MAE: 0.0797, MSE: 0.0333, Task Success:

Sample 491: traj214

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [0.0019, -0.0475, 0.0079, 0.0009, -0.0246, -0.1027, 1.0000]

Predicted: [0.0034, 0.0116, -0.0093, 0.0056, -0.0008, 0.0161, 0.9961]

Time: 805.1s

MAE: 0.0327, MSE: 0.0026, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0115, -0.0483, 0.0015, 0.0041, -0.0481, -0.0957, 1.0000]

Predicted: [0.0034, 0.0103, -0.0156, -0.0135, 0.0253, 0.0144, 0.9961]

Time: 770.6s

MAE: 0.0413, MSE: 0.0031, Task Success:

Sample 492: traj32

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [0.0051, 0.0050, -0.0027, 0.0034, -0.0373, -0.8999, 0.9952]

Predicted: [0.0007, 0.0099, 0.0120, -0.0193, -0.0323, 0.0289, 0.9961]

Time: 837.1s

MAE: 0.1402, MSE: 0.1234, Task Success: ✓

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [0.0132, 0.0015, -0.0027, -0.0037, -0.0529, -0.8761, 0.9916]

Predicted: [0.0034, 0.0022, 0.0000, 0.0088, -0.0236, 0.0128, 0.9961]

Time: 974.1s

MAE: 0.1355, MSE: 0.1131, Task Success: ✓

📸 Sample 493: traj213

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0088, -0.0416, -0.0030, 0.0069, -0.0286, -0.7167, 1.0000]

Predicted: [0.0078, -0.0004, 0.0198, 0.0471, 0.0026, 0.0112, 0.0000]

Time: 870.3s

MAE: 0.2686, MSE: 0.2193, Task Success: ✗

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0017, -0.0329, 0.0020, 0.0061, -0.0474, -0.6961, 1.0000]

Predicted: [-0.0109, 0.0077, 0.0208, 0.0458, 0.0374, 0.0161, 0.0000]

Time: 866.3s

MAE: 0.2722, MSE: 0.2169, Task Success: ✗

📸 Sample 494: traj35

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0268, 0.0155, 0.0040, -0.0101, -0.0293, 0.7183, 0.9966]
 Predicted: [-0.0049, -0.0218, -0.0026, 0.0286, 0.0059, -0.1016, 0.0000]
 Time: 895.1s
 MAE: 0.2795, MSE: 0.2386, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [-0.0221, 0.0077, -0.0006, -0.0098, -0.0564, 0.6858, 1.0000]
 Predicted: [-0.0101, 0.0239, 0.0143, 0.0031, 0.0032, 0.0886, 0.0000]
 Time: 877.8s
 MAE: 0.2447, MSE: 0.1944, Task Success:

Sample 495: traj198

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0175, 0.0425, -0.0066, -0.0019, -0.0196, -0.0045, 0.9942]
 Predicted: [-0.0009, -0.0092, -0.0088, -0.0014, -0.0075, -0.0178, 0.9961]
 Time: 809.0s
 MAE: 0.0143, MSE: 0.0005, Task Success:
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0199, 0.0528, 0.0077, -0.0046, -0.0414, 0.0182, 0.9918]
 Predicted: [0.0009, -0.0043, 0.0380, 0.0082, -0.0926, 0.0499, 0.9961]
 Time: 809.2s
 MAE: 0.0295, MSE: 0.0012, Task Success:

Sample 496: traj153

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [0.0062, -0.0277, 0.0037, -0.0010, -0.0337, 0.5635, 1.0000]
 Predicted: [-0.0121, 0.0141, 0.0159, 0.0299, 0.0039, 0.1176, 0.0000]
 Time: 800.5s
 MAE: 0.2267, MSE: 0.1719, Task Success: ✗
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0046, -0.0241, -0.0028, -0.0014, -0.0453, 0.5116, 0.9992]
 Predicted: [-0.0163, 0.0187, -0.0109, 0.0043, -0.0262, 0.1063, 0.0000]
 Time: 796.0s
 MAE: 0.2144, MSE: 0.1665, Task Success: ✗

Sample 497: traj154

Instruction: pick up the object and place it in the bowl
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 1: im_42.jpg
 Ground Truth: [-0.0065, -0.0250, -0.0005, 0.0069, -0.0411, 0.2652, 1.0000]
 Predicted: [-0.0047, 0.0015, -0.0047, 0.0241, 0.0019, -0.0178, 0.9961]
 Time: 874.9s
 MAE: 0.0542, MSE: 0.0119, Task Success: ✓
Debug: gt_action type=<class 'dict'>, shape=N/A
Debug: gt_action keys=['actions']
Debug: extracted using key 'actions'
Debug: after conversion shape=(7,)
Debug: final shape=(7,)
 Image 2: im_43.jpg
 Ground Truth: [0.0015, -0.0200, -0.0023, -0.0042, -0.0486, 0.2239, 1.0000]
 Predicted: [-0.0054, -0.0085, -0.0093, -0.0276, 0.0274, 0.0483, 0.9961]
 Time: 799.9s
 MAE: 0.0435, MSE: 0.0053, Task Success: ✓

Sample 498: traj162

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0136, -0.0353, -0.0093, 0.0138, -0.0311, 0.2692, 0.9951]

Predicted: [0.0087, 0.0116, -0.0091, -0.0219, -0.0162, 0.0161, 0.9961]

Time: 811.1s

MAE: 0.0534, MSE: 0.0098, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0003, -0.0393, -0.0021, 0.0136, -0.0481, 0.2329, 0.9914]

Predicted: [-0.0020, 0.0009, -0.0078, 0.0024, 0.0294, -0.0017, 0.9961]

Time: 785.7s

MAE: 0.0536, MSE: 0.0090, Task Success:

Sample 499: traj196

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 1: im_42.jpg

Ground Truth: [-0.0376, -0.0044, -0.0016, 0.0010, -0.0199, 0.1149, 1.0000]

Predicted: [-0.0009, 0.0009, -0.0002, 0.0043, 0.0006, 0.0032, 0.0000]

Time: 793.0s

MAE: 0.1684, MSE: 0.1449, Task Success:

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

Image 2: im_43.jpg

Ground Truth: [-0.0327, 0.0002, -0.0040, -0.0050, -0.0437, 0.0830, 0.9972]

Predicted: [0.0000, -0.0007, -0.0044, -0.0040, 0.0046, -0.0146, 0.0000]

Time: 806.0s

 MAE: 0.1683, MSE: 0.1439, Task Success: X

 Sample 500: traj191

Instruction: pick up the object and place it in the bowl

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 1: im_42.jpg

✓ Ground Truth: [0.0148, -0.0136, -0.0018, 0.0031, -0.0308, -0.6123, 1.0000]

○ Predicted: [-0.0004, -0.0169, 0.0198, 0.0395, -0.0524, 0.0418, 0.0000]

 Time: 833.3s

 MAE: 0.2503, MSE: 0.2043, Task Success: X

Debug: gt_action type=<class 'dict'>, shape=N/A

Debug: gt_action keys=['actions']

Debug: extracted using key 'actions'

Debug: after conversion shape=(7,)

Debug: final shape=(7,)

 Image 2: im_43.jpg

✓ Ground Truth: [0.0154, -0.0053, 0.0062, 0.0094, -0.0423, -0.5700, 0.9978]

○ Predicted: [-0.0011, -0.0105, 0.0348, 0.0165, -0.0812, -0.0162, 0.9961]

 Time: 823.9s

 MAE: 0.0931, MSE: 0.0442, Task Success: ✓

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 EVALUATION SUMMARY

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○ Overall Performance:

MAE: 0.1437 ± 0.0881

MSE: 0.1039 ± 0.0870

Task Completion Rate: 43.8% (438/1000)

 Timing:

Total predictions: 1000

Avg prediction time: 862.5s