Lab Session 1:

Law of Propagation of Uncertainty (LPU)

Exercise A1 Comparison of two gauge blocks

The observation equation associated with the measurement of a gauge block takes the form:

$$y = \emptyset(L, t, c) = L(1 + c(t - t_0)),$$

$$z = y + e$$

where

z = indication returned by a length measuring device;

 $L = length at temperature t_0;$

t = temperature at time of measurement;

c = coefficient of thermal expansion;

 $\phi(L, t, c)$ model the length of the gauge block as a function of L, t and c;

e = random effect.

Measurement equation:

$$L = \varphi(t, c, y) = \frac{y}{1 + c(t - t_0)} \approx y(1 - c(t - t_0)).$$

Suppose two gauge blocks of the same material and nominal length L₀ are measured. Calculate the 2×2 variance matrix V_L associated with their lengths

 $L = (L_1, L_2)^T$ for data:

 $z_1 = 100.000 090 \text{ mm}, z_2 = 100.000 050 \text{ mm},$

 $u(z_1) = u(z_2) = u(z) = 0.000 050 \text{ mm},$

 $t_1 = 20.5$ °C, $t_2 = 20.3$ °C,

 $u(t_1) = u(t_2) = u(t) = 0.1$ °C,

 $c = 10 \times 10^{-6} \text{ m K}^{-1}$

 $u(c) = 1 \times 10^{-6}$

• Use V_L to calculate the uncertainties associated with $L_1 \pm L_2$.

Calculations:

$$L_1 = \frac{y_1}{1 + c(t_1 - t_0)}, L_2 = \frac{y_2}{1 + c(t_2 - t_0)}.$$

Best estimate of y_1 is z_1 ,

Best estimate of y_1 is z_2 ,

 $u(y_1)=u(y_2)=u(z)=0.000~050~mm$

Influence factors $\alpha = (y_1, y_2, t_1, t_2, c)^T$.

Variance matrix for influence factors:

$$V = \begin{bmatrix} u^{2}(y) & & & & \\ & u^{2}(y) & & & \\ & & u^{2}(t) & & \\ & & & u^{2}(t) & \\ & & & u^{2}(c) \end{bmatrix}$$

Let C be the 2×5 sensitivity matrix

$$C_{kj} = \frac{\partial L_k}{\partial \alpha_i}$$

Then $V_L = CVC^T$.

• Study the Matlab code R GAUGE BLOCK A.m to understand how the uncertainty evaluation is implemented.

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% -----
% R GAUGE BLOCK A Different temperatures.
% v1A 2010-03-08 A B Forbes NPL (c) Crown Copyright.
 format compact
 L0 = 100;
                 % Nominal length in mm
                % Fixed temperature in degrees C
 t0 = 20;
% Length indications
 z1 = L0 + 90e-6;
 z2 = L0 + 50e-6;
 uz = 50e-6;
% Temperature
 t1 = 20.5;
 t2 = 20.3;
 ut = 0.1;
% Coefficient of thermal expansion
 c = 10e-6;
 uc = 1e-6;
% Estimates of y1, y2
 y1 = z1;
 y2 = z2;
 uy = uz;
% alpha = (y1, y2, t1, t2, c)';
% Variance matrix for inputs
 ualpha = [uy uy ut ut uc]';
 V = diag(ualpha.*ualpha)
% Measurement equations
  L1 = y1*(1-c*(t1-t0));
  L2 = y2*(1-c*(t2-t0));
% Difference from nominal
  L1 - L0
  L2 - L0
% Sensitivity matrix
 C = zeros(2,5);
 C(1,1) = (1-c*(t1-t0));
 C(1,2) = 0;
 C(1,3) = -y1*c;
 C(1,4) = 0;
 C(1,5) = -y1*(t1-t0);
 C(2,2) = (1-c*(t2-t0));
 C(2,1) = 0;
 C(2,4) = -y2*c;
 C(2,3) = 0;
 C(2,5) = -y2*(t2-t0);
% Apply LPU
 VL = C*V*C'
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```
uL = sqrt(diag(VL))
 uL1 = uL(1);
 uL2 = uL(2);
% Variance components
 v1 = C(1,:).*ualpha';
 vv1 = v1.*v1;
 v2 = C(2,:).*ualpha';
 vv2 = v2.*v2;
 Var_decom= [vv1;vv2]
% Uncertainty in A = L1+L2
  cA = [1 1]';
   A = L1 + L2;
  vA = cA'*VL*cA;
  uA = sqrt(vA)
% Uncertainty in B = L1-L2
  cB = [1 -1]';
  B = L1-L2;
  vB = cB'*VL*cB;
  uB = sqrt(vB)
```

Exercise A2 Mass calculations

Modify the file R_GAUGE_BLOCK_A.m to evaluate the following exercise.

The mass of a cylindrical artefact is given by

$$M = \pi \rho h r^2$$
,

where ρ is the density at 20° C, r is the radius, h is the height.

- Suppose r and h are measured at temperature t and that the coefficient of thermal expansion is c.
 Express the uncertainty associated with M in terms of the uncertainties associated with ρ, r, h, t and c.
- Determine the 2×2 variance matrix $V_{\rm M}$ for the masses M_1 and M_2 of two cylindrical artefacts made from the same material from the following data:

 r_1 = 25.005 mm is the radius measured at temperature t_1 = 20.5 °C,

 h_1 = 63.510 mm is the height measured at temperature t_1 .

 r_2 = 25.020 mm is the radius measured at temperature t_2 = 20.8 °C,

 h_2 = 63.515 mm is the height measured at temperature t_2 .

 ρ = 8000 kg m⁻³; c = 10 \times 10⁻⁶ m K⁻¹; $u(r_1) = u(r_2) = u(h_1) = u(h_2) = 0.001$ mm,

 $u(t_1) = u(t_2) = 0.1$ °C; $u(\rho) = 0.05$ kg m⁻³; $u(c) = 1 \times 10^{-6}$ K⁻¹

• Use V_M to evaluate the uncertainties associated with M1 ± M2.

Notes:

The mass of a cylindrical artefact is given by

$$M = \pi \rho h r^2$$

Taking into account temperature, we have:

$$M = \pi \rho h r^2 (1 + c(t - t_0))^3$$

• Sensitivity coefficients:

$$c_h = \frac{\partial M}{\partial h} = \pi \rho r^2 (1 + c(t - t_0))^3$$

$$c_r = \frac{\partial M}{\partial r} = 2\pi \rho h r (1 + c(t - t_0))^3$$

$$c_t = \frac{\partial M}{\partial t} = 3\pi \rho h r^2 (1 + c(t - t_0))^2 c$$

$$c_c = \frac{\partial M}{\partial c} = 3\pi \rho h r^2 (1 + c(t - t_0))^2 (t - t_0)$$

$$c_\rho = \frac{\partial M}{\partial \rho} = \pi h r^2 (1 + c(t - t_0))^3$$

For two masses M1 and M2, we have:

$$M_1 = \pi \rho h_1 r_1^2 (1 + c(t_1 - t_0))^3$$

$$M_2 = \pi \rho h_2 r_2^2 (1 + c(t_2 - t_0))^3$$

• **X** = (h1,h2,r1,r2,t1,t2,c,rho)';

$$C_{1} = [c_{h} \ 0 \ c_{r} \ 0 \ c_{t} \ 0 \ c_{c} \ c_{rho}]$$

$$C_{2} = [0 \ c_{h} \ 0 \ c_{r} \ 0 \ c_{t} \ c_{c} \ c_{rho}]$$

$$C = \begin{bmatrix} C_{1} \\ C_{2} \end{bmatrix}$$

$$Y = \begin{bmatrix} M_{1} \\ M_{2} \end{bmatrix}$$

 $\begin{aligned} V_X &= diag[u_h^2, \, u_h^2, \, u_r^2, \, u_r^2, \, u_t^2, \, u_t^2, \, u_c^2, \, u_{rho}^2] \\ V_Y &= V(Y) \approx C V_X C^T \end{aligned}$

• $S = M_1 + M_2 = [1 \ 1] \begin{bmatrix} M_1 \\ M_2 \end{bmatrix}$

$$u^2(S) = V(S) \approx \mathbf{c}^T V_Y \mathbf{c} = [1 \ 1] V_Y \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$