

# **CSE/ECE 848**

## **Introduction to**

# **Evolutionary Computation**

### **Module 3 - Lecture 10 - Part 2**

## **Evolutionary Strategies -**

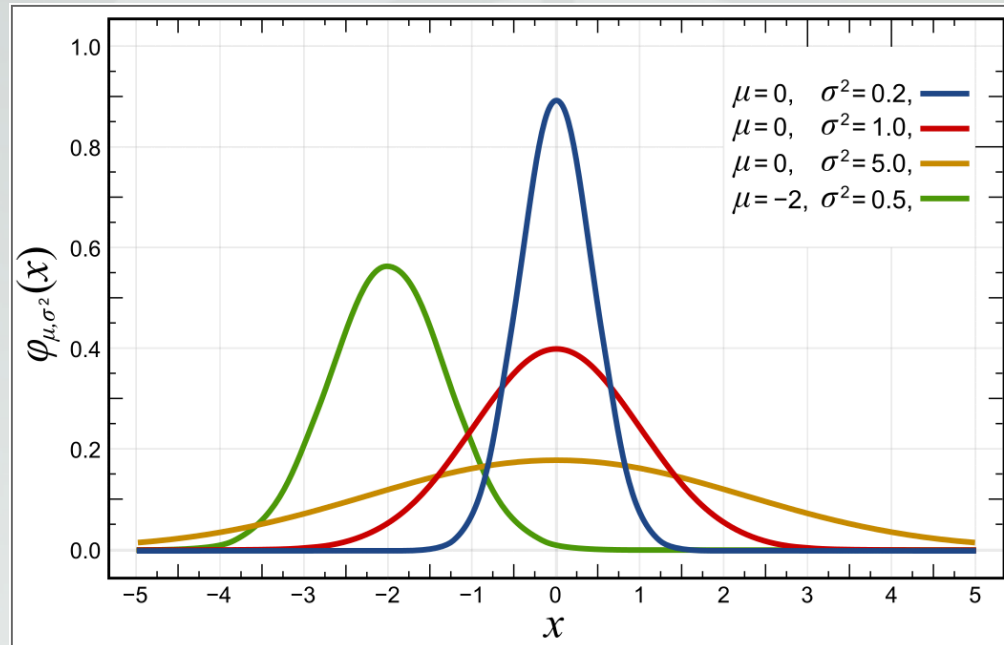
# **Mutation and Recombination**

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# Mutation

- As mentioned previously, mutation is the driving force
- $x$  is the individual parameter value
- $x'_i = x_i + \sigma * N(0,1)$
- where  $\sigma$  is the stepsize, and  $N(0,1)$  represents a single standard Gaussian random variable

# Normal Distribution, modified by $\sigma$



# Mutation Strategies

- Early ES were concerned with the concept of stepsize  $\sigma$
- “Stepsize” meant the strength of mutations
- However, the rate of change of each element of vector  $x$  should change over time as the element “converges” to better and better answers
- The issue of stepsize is the same as for any gradient hillclimber: If the step size is too small, little progress is made in exploring the space. If the stepsize is too big, the answer is missed because of overstepping in the space

# Heuristic Mutation Strategy

- Rechenberg used two common functions to estimate optimal step sizes:

- Linear corridor

$$f_1(x) = F(x_1) = c_0 + c_1 x_1$$
$$\forall_i \in \{2, \dots, n\} : -b/2 \leq x_i \leq b/2$$

- The sphere

$$f_2(x) = c_0 + c_1 * \sum_{i=1}^n (x_i - x_i^*)^2$$

# The 1/5 Rule

- He solved the optimal expected convergence rates stepsizes for those two (which were respectively)

$$p_{opt} \approx 0.184 \quad p_{opt} \approx 0.270$$

- and decided that the best rate of successful mutations to failed mutations should be about 0.20, or one fifth.

# 1/5 Rule II

This led to the basic mutation rule:

- If more than 1/5th of the mutations cause an improvement (in the objective function) then multiply  $\sigma$  by a factor  $1+s$
- If less than 1/5th of the mutations cause an improvement, then multiply  $\sigma$  by  $(1+s)^{-1/4}$

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**Algorithm:** (1+1)-ES with 1/5 success-rule

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1. Initialize  $\mathbf{X}_0, \sigma_0$
  2. **repeat**
  3.  $\widetilde{\mathbf{X}}_n = \mathbf{X}_n + \sigma_n \mathcal{N}(\mathbf{0}, \mathbf{I})$       Sample one offspring
  4. **if**  $f(\widetilde{\mathbf{X}}_n) \leq f(\mathbf{X}_n)$  **then**      If  $f(\text{offsp.}) \leq f(\text{parent})$
  5.      $\mathbf{X}_{n+1} = \widetilde{\mathbf{X}}_n$       New parent = offsp.
  6.      $\sigma_{n+1} = 1.5 \sigma_n$       Step-size is increased
  7. **else**      If offspring strictly worse
  8.      $\mathbf{X}_{n+1} = \mathbf{X}_n$       New parent = old parent
  9.      $\sigma_{n+1} = 1.5^{-1/4} \sigma_n$       Step-size is decreased
  10. **until** stopping criteria is met
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After one successful and 4 unsuccessful mutations, this results in:

$$E(\sigma_{n+1} | \sigma_n) = \left( (1.5)^{-1/4} \right)^{4/5} (1.5)^{1/5} \sigma_n$$

$$E(\sigma_{n+1} | \sigma_n) = \sigma_n$$

# First ES

- The first ES was based on a (1+1)-ES strategy, where the child competes with the parent, and mutation is driven by the 1/5 rule.
- Note, population size is 1, and  $\sigma$  is global
- This is a kind of stochastic gradient method, best characterized as a local hill climber



# 1/5<sup>th</sup> rule and what it's good for

The 1/5 rule was derived for unimodal linear functions

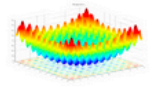
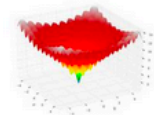
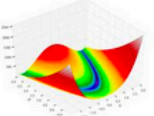
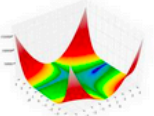
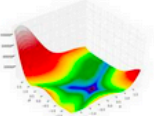
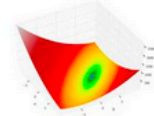
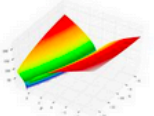
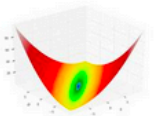
Thus not particularly useful for practical problems but indicative of a requirement:

One should adapt as the problem difficulty changes!

# Test Functions

[http://en.wikipedia.org/wiki/Test\\_functions\\_for\\_optimization](http://en.wikipedia.org/wiki/Test_functions_for_optimization)

Test functions for single-objective optimization [ edit ]

Name	Plot	Formula	Global minimum	Search domain
Rastrigin function		$f(\mathbf{x}) = An + \sum_{i=1}^n [x_i^2 - A \cos(2\pi x_i)]$ where: $A = 10$	$f(0, \dots, 0) = 0$	$-5.12 \leq x_i \leq 5.12$
Ackley's function		$f(x, y) = -20 \exp \left[ -0.2 \sqrt{0.5 (x^2 + y^2)} \right] - \exp[0.5 (\cos 2\pi x + \cos 2\pi y)] + e + 20$	$f(0, 0) = 0$	$-5 \leq x, y \leq 5$
Sphere function		$f(\mathbf{x}) = \sum_{i=1}^n x_i^2$	$f(x_1, \dots, x_n) = f(0, \dots, 0) = 0$	$-\infty \leq x_i \leq \infty, 1 \leq i \leq n$
Rosenbrock function		$f(\mathbf{x}) = \sum_{i=1}^{n-1} [100(x_{i+1} - x_i^2)^2 + (x_i - 1)^2]$	$\text{Min} = \begin{cases} n=2 \rightarrow f(1, 1) = 0, \\ n=3 \rightarrow f(1, 1, 1) = 0, \\ n>3 \rightarrow \underbrace{f(1, \dots, 1)}_{n \text{ times}} = 0 \end{cases}$	$-\infty \leq x_i \leq \infty, 1 \leq i \leq n$
Beale's function		$f(x, y) = (1.5 - x + xy)^2 + (2.25 - x + xy^2)^2 + (2.625 - x + xy^3)^2$	$f(3, 0.5) = 0$	$-4.5 \leq x, y \leq 4.5$
Goldstein-Price function		$f(x, y) = \left[ 1 + (x + y + 1)^2 (19 - 14x + 3x^2 - 14y + 6xy + 3y^2) \right] \left[ 30 + (2x - 3y)^2 (18 - 32x + 12x^2 + 48y - 36xy + 27y^2) \right]$	$f(0, -1) = 3$	$-2 \leq x, y \leq 2$
Booth's function		$f(x, y) = (x + 2y - 7)^2 + (2x + y - 5)^2$	$f(1, 3) = 0$	$-10 \leq x, y \leq 10$
Bukin function N.6		$f(x, y) = 100 \sqrt{ y - 0.01x^2 } + 0.01  x + 10 .$	$f(-10, 1) = 0$	$-15 \leq x \leq -5, -3 \leq y \leq 3$
Matyas function		$f(x, y) = 0.26 (x^2 + y^2) - 0.48xy$	$f(0, 0) = 0$	$-10 \leq x, y \leq 10$

# Recombination in $(\mu+1)$ -ES

- $(\mu+1)$ -ES allows the possibility of creating new individuals based on a combination of features of the parents, where  $\mu > 1$
- Choose  $p$  parent vectors ( $1 \leq p \leq n$ ), and mix characters from these  $p$  parent vectors to create a child
- Thus  $p=2$  is similar to GA crossover

# Recombination II

- Global intermediary recombination: Position  $i$  is average over all  $p$  parents
- Local intermediary recombination: Select two out of  $p$  parents for each child position  $i$  and take a weighted average
- Discrete recombination: copy a value from a randomly chosen parent for each child position
- Other scenarios are possible, too
- While recombination is used in ES, it is not the primary driving force, which is the previously described mutation