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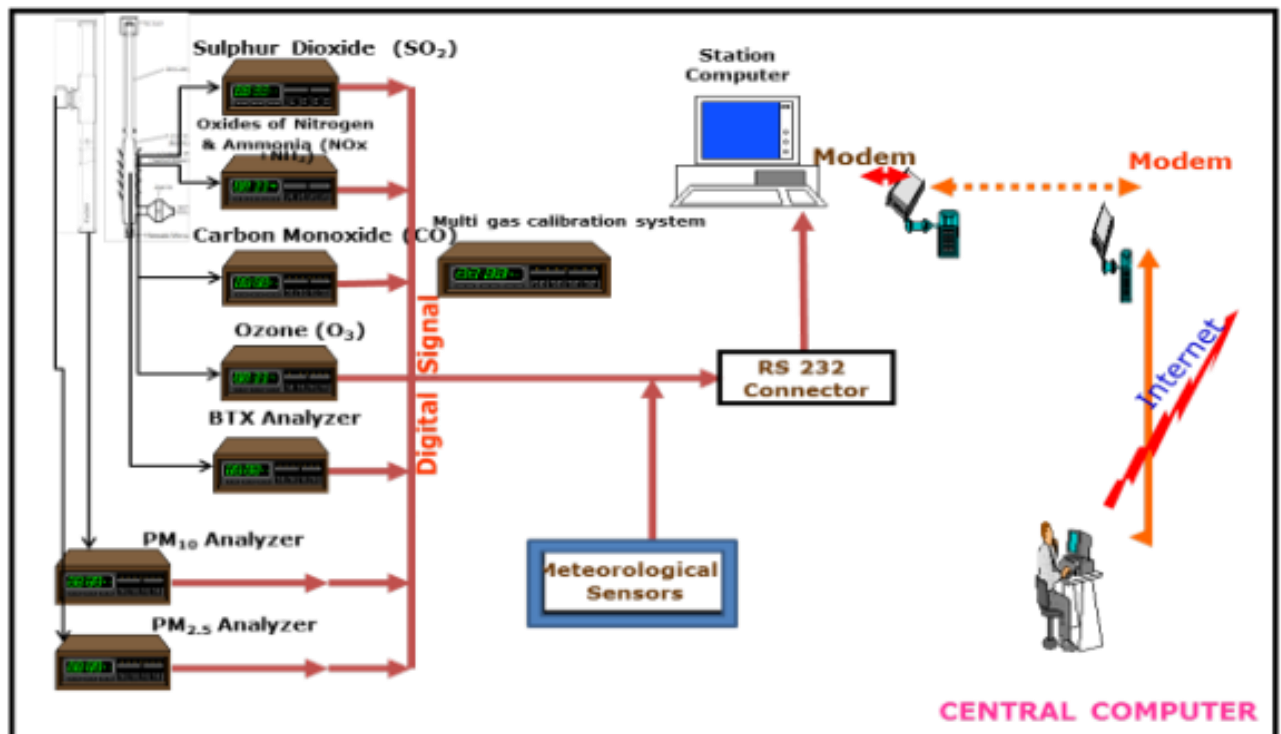
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Architecture

Overall Architecture

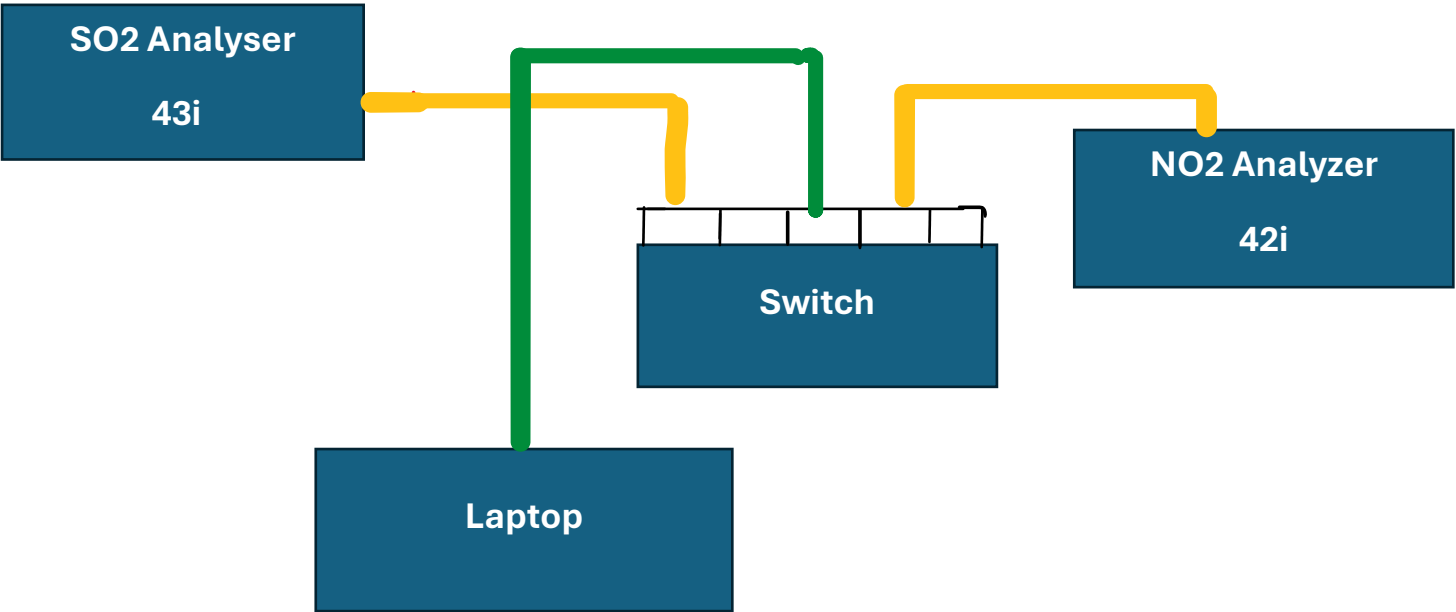


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POC Architecture



Objective: Establish communication with the analyzers using Modbus protocol and develop software to communicate with the DAS.

Software

Frontend

S.No	Technology	Version	Purpose
1.	HTML	HTML5	Blueprint of webpage

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2.	CSS	CSS3	Styling the webpage
3.	JavaScript	ES6	Dynamic functionality

Backend

S.no	Technology	Version	Purpose
1.	Python	3.9.11	Establishing a connection to the instrument using Python
2.	Axios	0.21.4	Integrating Frontend & Backend
3.	Fast API	0.0.4	Framework to perform rest calls in Python
4.	Uvicorn server	0.29.0	To handle incoming HTTP requests and manage communication between clients & server

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Lab Setup



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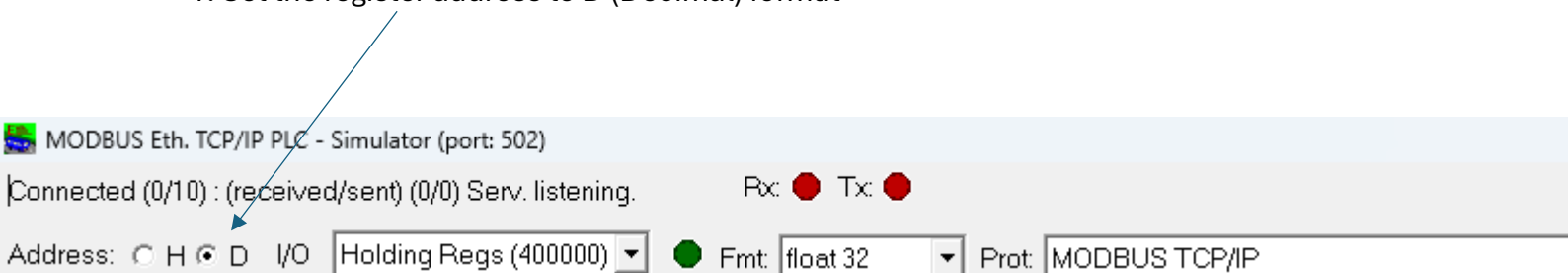
IP addresses for each control unit

Control Unit	IP address	Subnet mask
Laptop	192.168.0.200	255.255.254.0
SO2 Analyzer-43i	192.168.0.201	255.255.255.0
NO2 Analyzer-42i	192.168.0.202	255.255.254.0

System startup

Modbus protocol setup using ModRSim2 Stimulator.

1. Set the register address to D (Decimal) format



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2. Set I/O to the Holding registers in the Dropdown

Connected (0/10) : (received/sent) (0/0) Serv. listening. Rx: ● Tx: ●

Address: ☐ H ☒ D ☐ I/O Fmt: Prot:

Address	+0	+1	+2	+3	+4	+5	+6	+7
400001-400010	0.180901	0.180901	0.180901	0.180901	0.180901	0.180901	0.180901	0.180901
400011-400020	0.180901	0.180901	0.180901	0.180901	0.180901	0.180901	0.180901	0.180901
400021-400030	0.180901	0.180901	0.180901	0.180901	0.180901	0.180901	0.180901	0.180901

3. Set the format of data to float from the dropdown

Connected (0/10) : (received/sent) (0/0) Serv. listening. Rx: ● Tx: ●

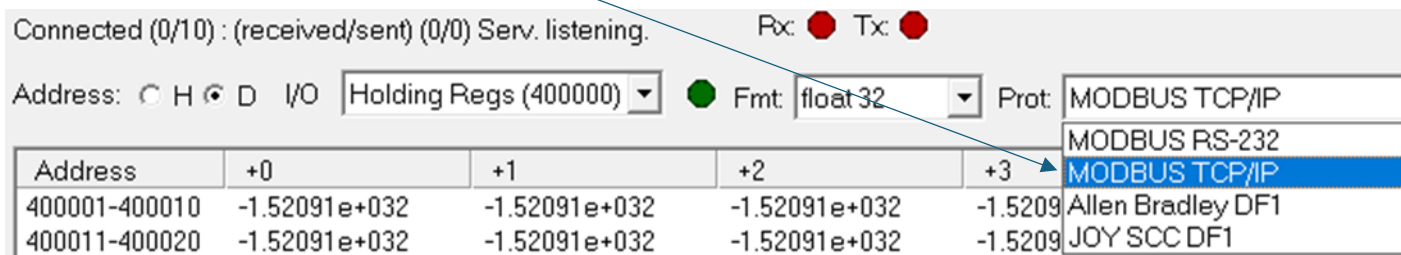
Address: ☐ H ☒ D ☐ I/O Fmt: Prot:

Address	+0	+1	+2	+3	+4
400001-400010	-2.02211e-008	-2.02211e-008	-2.02211e-008	-2.02211e-008	-2.02211e-008
400011-400020	-2.02211e-008	-2.02211e-008	-2.02211e-008	-2.02211e-008	-2.02211e-008
400021-400030	-2.02211e-008	-2.02211e-008	-2.02211e-008	-2.02211e-008	-2.02211e-008
400031-400040	-2.02211e-008	-2.02211e-008	-2.02211e-008	-2.02211e-008	-2.02211e-008
400041-400050	-2.02211e-008	-2.02211e-008	-2.02211e-008	-2.02211e-008	-2.02211e-008

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4. Now set the prototype as Modbus TCP/IP for communication of registers.



Run the following commands in the command prompt

1. Set the virtual environment path in your laptop where it is installed e.g.,
C:\Users\ritesh.ogety\.virtualenvs\TFS_SCADA_Backend-DC0gT6eI

```

Command Prompt
Microsoft Windows [Version 10.0.22631.3737]
(c) Microsoft Corporation. All rights reserved.

C:\Users\ritesh.ogety>cd C:\Users\ritesh.ogety\.virtualenvs\TFS_SCADA_Backend-DC0gT6eI
C:\Users\ritesh.ogety\.virtualenvs\TFS_SCADA_Backend-DC0gT6eI>
  
```


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- Now enter the Scripts/activate command in the context of the virtual environment in Python for the above-created virtual environment.

```
C:\Users\ritesh.ogety\.virtualenvs\TFS_SCADA_Backend-DC0gT6eI>Scripts\activate
C:\Users\ritesh.ogety\.virtualenvs\TFS_SCADA_Backend-DC0gT6eI>()
(TFS_SCADA_Backend) C:\Users\ritesh.ogety\.virtualenvs\TFS_SCADA_Backend-DC0gT6eI>
```

- Now change the path where your project is located say e.g.,

C:\Users\ritesh.ogety\OneDrive - Thermo Fisher Scientific\Desktop\DAS PROJECT

```
(TFS_SCADA_Backend) C:\Users\ritesh.ogety\.virtualenvs\TFS_SCADA_Backend-DC0gT6eI>cd C:\Users\ritesh.ogety\OneDrive - Thermo Fisher Scientific\Desktop\DAS PROJECT
(TFS_SCADA_Backend) C:\Users\ritesh.ogety\OneDrive - Thermo Fisher Scientific\Desktop\DAS PROJECT>
```

- Now run the uvicorn command to start the server

```
(TFS_SCADA_Backend) C:\Users\ritesh.ogety\OneDrive - Thermo Fisher Scientific\Desktop\DAS PROJECT>uvicorn index:app --host 127.0.0.1 --port 8000
INFO: Started server process [18788]
INFO: Waiting for application startup.
INFO: Application startup complete.
INFO: Uvicorn running on http://127.0.0.1:8000 (Press CTRL+C to quit)
```

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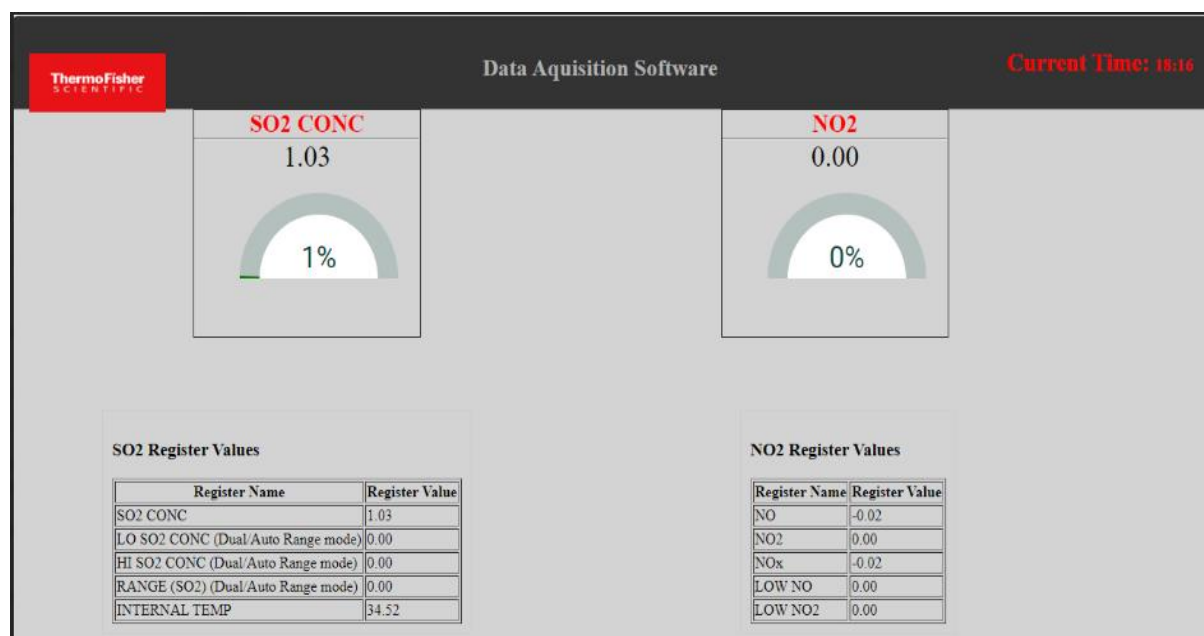
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Note: Now the connection to the server is successful as you can see in the above screenshot as “ INFO: Started Server process.”

Then load your respective webpage and then you can see your real-time data display of the instrument on the software.

Results

Dashboard

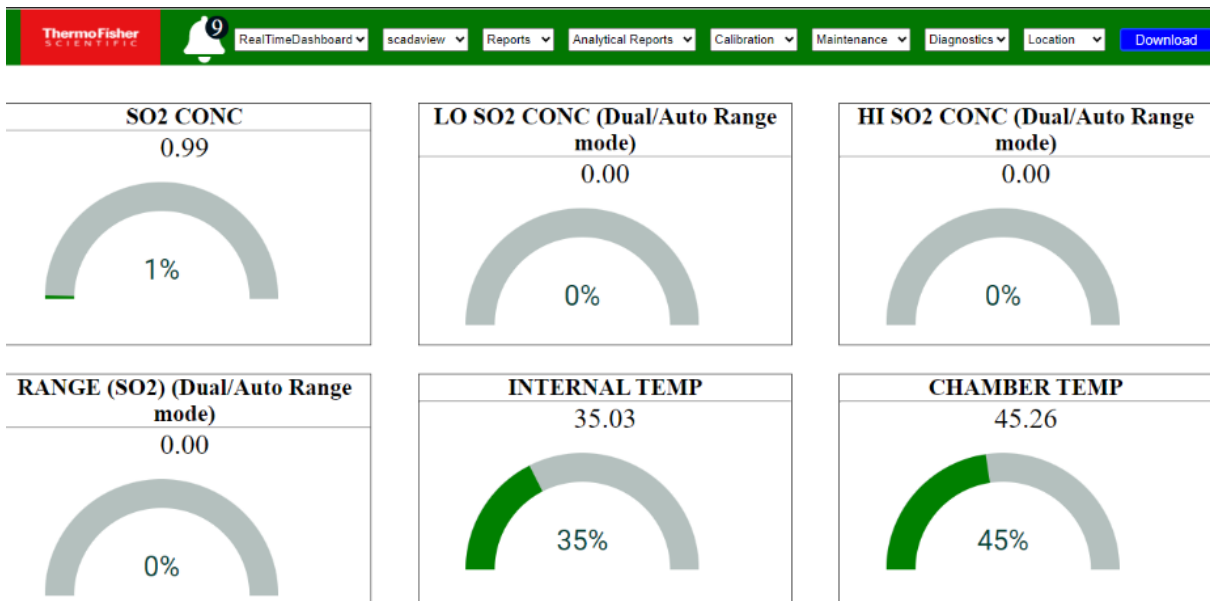


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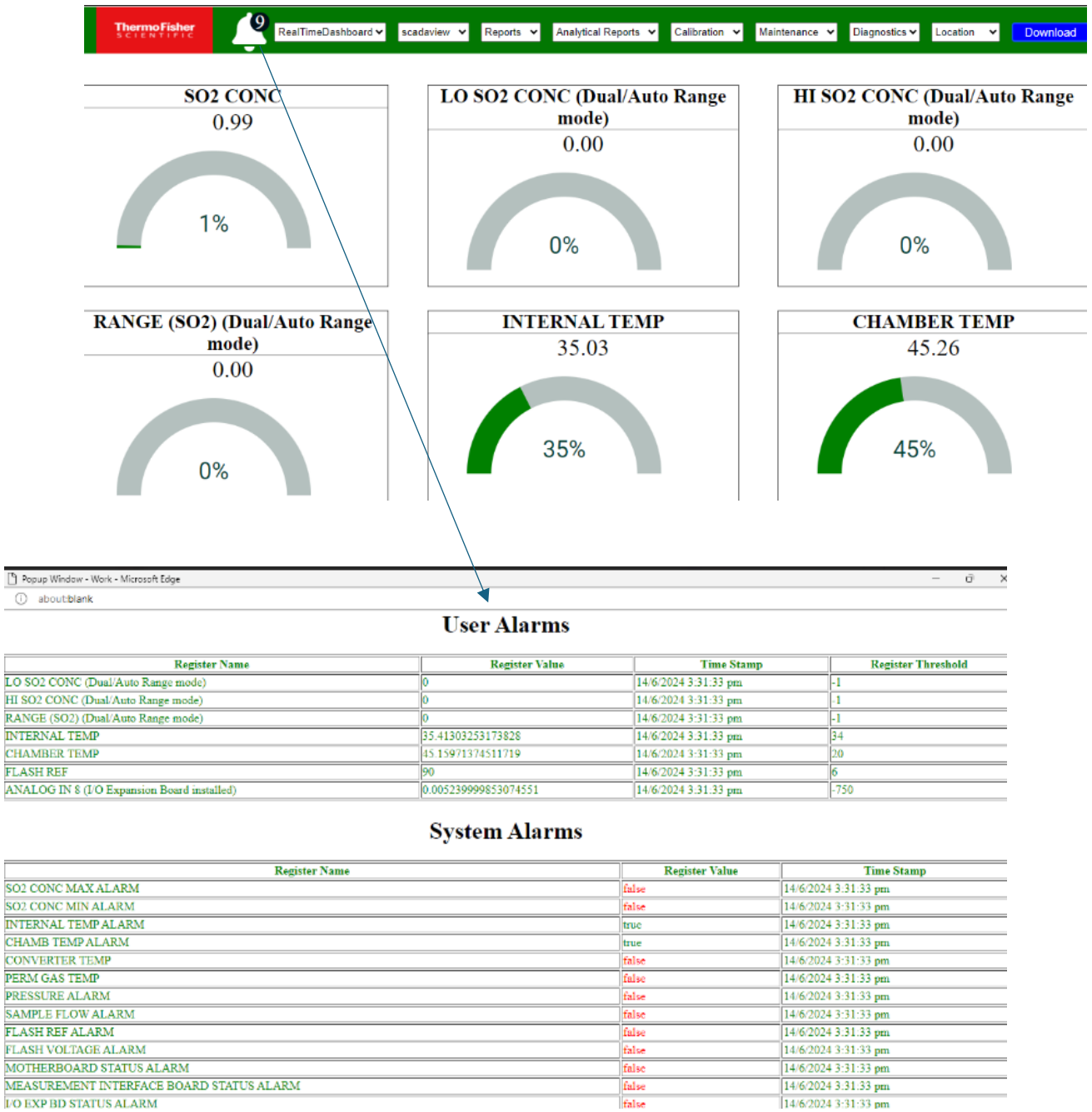
SO2 home page



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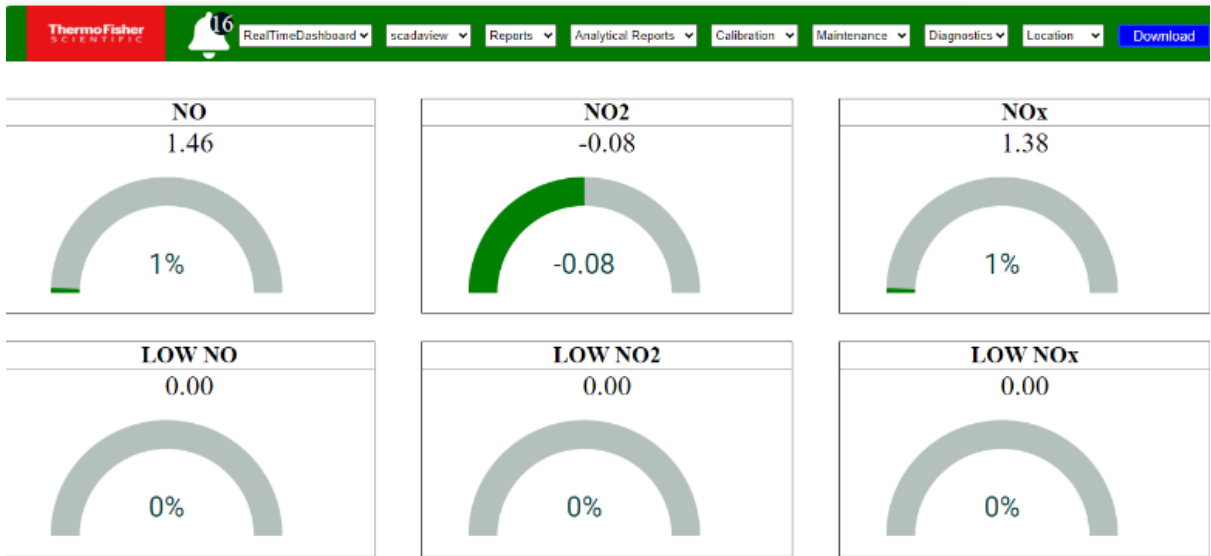


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NO2 home page

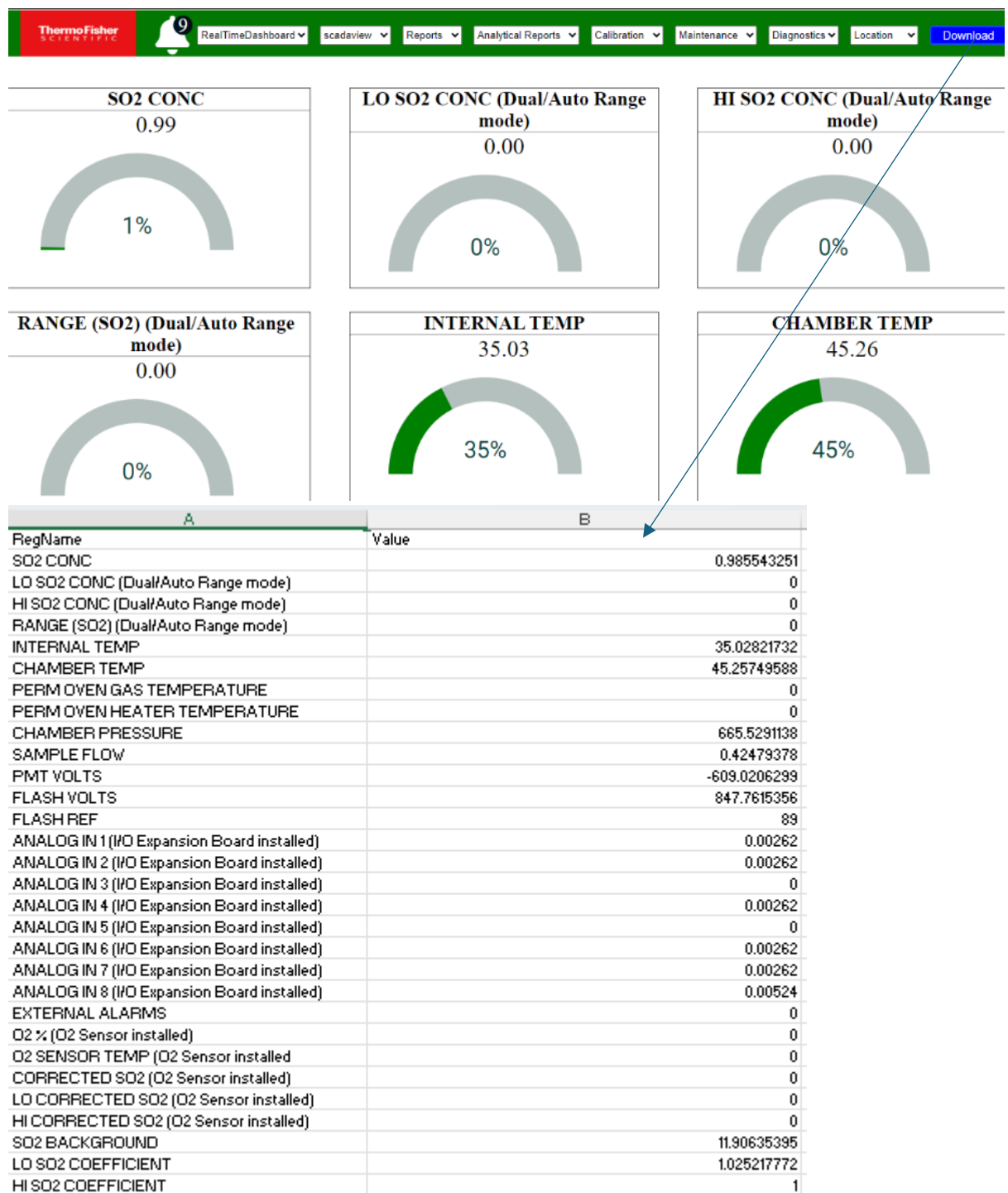


Downloaded CSV file

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Code Snippets

```
import { setGaugeValue } from "../util/gauge.js";
let SO2reg=[];
let newScreen='';
let newScreen2='';
let a='';
axios.get('http://localhost:8000/getRegVal')
.then(response => {
    let dashboardSO2HTML='';
    console.log(response.data);
    SO2reg = response.data.formatted_data;
    let firstKey = Object.keys(SO2reg)[0];
    let firstValue = SO2reg[firstKey];
    // console.log(firstKey);
    console.log(firstValue.RegName);

    dashboardSO2HTML+=`<div class="grid-item">
    <p>
        ${firstValue.RegName}
    </p>
    <hr>
    <div class="data">
        <div class="regvalue">
            ${parseFloat(firstValue.Value).toFixed(2)}
        </div>
        <div class="gauge_SO2">
            <div class="gauge__body">
                <div class="gauge__fill">

                </div>

                <div class="gauge__cover">

                    ${parseFloat(firstValue.Value).toFixed(2)}

                </div>
            </div>
        </div>
    </div>`;
    document.querySelector(".js-regvalueSO2").innerHTML = dashboardSO2HTML;
```

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```
for (let regName in S02reg) {
  if (S02reg.hasOwnProperty(regName)) {
    let value = S02reg[regName];

    newScreen += `
      <tr>
        <td>${value.RegName}</td>
        <td>${value.Value.toFixed(2)}</td>
      </tr>`;

    count++;
    if (count === 5) {
      break; // Exit the loop after 5 iterations
    }
  }
}
document.querySelector(".js-S02registervalues").innerHTML=newScreen;
```

Figure 1 Dynamic display of 5 register values

```
document.querySelector(".js-regvalueS02").innerHTML = dashboardS02HTML;
let gaugeElement = document.querySelectorAll(".gauge_S02");
console.log(gaugeElement);
// gaugeElement.forEach((item)=>{
//   setGaugeValue(item,(S02reg["Value"][i]))/100;})
gaugeElement.forEach((item) => {
  setGaugeValue(item, firstValue.Value / 100); // Assuming setGaugeValue function expects a value between 0 and 1.
});

newScreen = `
<h3> S02 Register Values </h3>

<table border="1">

  <tr>

    <th> Register Name </th>
    <th> Register Value</th>

  </tr>
`;
```

Figure 2 Display of data with Gauge

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```

axios.get('http://localhost:8000/getNo2RegVal')
.then(response => {
  let dashboardS02HTML='';
  console.log(response.data);
  S02reg = response.data.formatted_data;
  let firstKey = Object.keys(S02reg)[1];
  let firstValue1 = S02reg[firstKey];
  // console.log(firstKey);
  console.log(firstValue1.RegName);

  dashboardS02HTML+=`<div class="grid-item">
    <p>
      ${firstValue1.RegName}
    </p>
    <hr>
    <div class="data">
      <div class="regvalue">
        ${parseFloat(firstValue1.Value).toFixed(2)}
      </div>
      <div class="gauge_N02">
        <div class="gauge__body">
          <div class="gauge__fill">

          </div>

          <div class="gauge__cover">

            ${parseFloat(firstValue1.Value).toFixed(2)}

          </div>
        </div>
      </div>
    </div>
  </div>`;
  document.querySelector(".js-regvalueNO2").innerHTML = dashboardS02HTML;
  let gaugeElement = document.querySelectorAll(".gauge_N02");
  console.log(gaugeElement);
  // gaugeElement.forEach((item)=>{
  //   setGaugeValue(item,(S02reg["Value"][i]))/100;})
  gaugeElement.forEach((item1) => {
    setGaugeValue(item1, firstValue1.Value / 100); // Assuming setGaugeValue function expects a value between 0 and 1.
  });
});

```

Figure 3 URL generation for the webpage

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```
from pymodbus.client import AsyncModbusTcpClient
from pymodbus.payload import BinaryPayloadDecoder
from pymodbus.constants import Endian
from pymodbus.exceptions import ModbusException
```

Figure 4 Import Statements to use standard libraries

```
def __init__(self, host, port, slave):
    self.client = AsyncModbusTcpClient(host, port)
    self.slave = slave

async def connect(self):
    try:
        await self.client.connect()
        if self.client.connected:
            print("Connected to Modbus Server")
            status = "Connected"
    except ModbusException:
        raise Exception("Could not connect to Modbus Server")
        status = "Could not connect to Modbus Server"
    return status

def close(self):
    self.client.close()
    print("Disconnected from Modbus Server")
    status = "Disconnected"

async def readHoldingReg(self) -> object:
    decoded_values = []
    responseObj = {}
    try:
        result = await self.client.read_holding_registers(0, 86, slave=self.slave)
        for i in range(0, len(result.registers), 2):
            decoder = BinaryPayloadDecoder.fromRegisters(result.registers[i:i+2], Endian.BIG, wordorder=Endian.LITTLE)
            print("decoder" + str(decoder))
            value = decoder.decode_32bit_float()
            print("value" + str(value))
            decoded_values.append(value)
        for i in range(0, len(decoded_values)):
            if (So2ReadReg.registerVariables[i] == 'NOT USED'):
                continue
            responseObj[So2ReadReg.registerVariables[i]] = decoded_values[i]

        alarmreg = await self.client.read_coils(0, 30, slave=self.slave)
        print("Coil values:", alarmreg.bits)

        formatted_data = [{"RegName": key, "Value": value,} for key, value in responseObj.items()]
        response_to_return = {"Formatted_data": formatted_data, "Alarms": alarmreg.bits}

        return response_to_return
    except ModbusException as exc:
        print(f"Received ModbusException({exc}) from library")
        raise exc
    except Exception as exc:
        print(f"An exception occurred: {exc}")
        raise exc
```

Figure 5 Logic for communicating to the instrument from Backend

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```

from fastapi import FastAPI
from Backend.SO2ReadReg import So2ReadReg
import time
from asyncio import Event
from fastapi.middleware.cors import CORSMiddleware
from Backend.NO2ReadReg import No2ReadReg
app = FastAPI()

app.add_middleware(
    CORSMiddleware,
    allow_origins=["*"],
    allow_credentials=True,
    allow_methods=["GET", "POST", "PUT", "DELETE"],
    allow_headers=["*"],
)

So2Device = So2ReadReg(["192.168.0.201",502,43])
@app.get("/getRegVal")
async def sendSo2Data():
    response = None
    try:
        print("Got get data request from client")
        devConStat = await So2Device.connect()

        if(devConStat == "Connected"):
            response = await So2Device.readHoldingReg()
            print(response)
        else:
            response = devConStat
        time.sleep(1)
    except Exception as ex:
        print("Some error occurred")
    return response

No2Device = No2ReadReg(["192.168.0.202",502,42])
@app.get("/getNo2RegVal")
async def sendNo2Data():
    response = None
    try:
        print("Got get data request from client")
        devConStat = await No2Device.connect()

        if(devConStat == "Connected"):
            response = await No2Device.readHoldingReg()
            print(response)
        else:
            response = devConStat
        time.sleep(1)
    except Exception as ex:
        print("Some error occurred")
    return response

```

Figure 6 fast API library for connection establishment

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JavaScript to React

We can convert the JavaScript code to React by using the JSX converter, which mainly helps us convert JS's logical part to React.

<https://codepen.io/zenbrent/pen/vYQLXb>

The JS2 flowchart converts the JavaScript code to a flowchart representation which mainly helps in visualizing the logical flow so that the plan becomes easy to structure the React components.

The React converter as a tool helps us to convert the JavaScript code to React components.

Finally, the above-mentioned points provide an overview, of how to transform the code of JS to React components by understanding the flow of code in JS and its logical representation through flowcharts which provides a keen way of building the logic to React components.