

# PROJECT REPORT

Electronic Circuits Lab | Smart Cleaning System

# Group Members

B. Laxmi Sreenivas	IMT2020510	<a href="mailto:Laxmi.Sreenivas@iiitb.ac.in">Laxmi.Sreenivas@iiitb.ac.in</a>
T. V. N Sai Teja	IMT2020538	<a href="mailto:Naga.SaiTeja@iiitb.ac.in">Naga.SaiTeja@iiitb.ac.in</a>
B. Sashank Reddy	IMT2020542	<a href="mailto:Sashank.Budideti@iiitb.ac.in">Sashank.Budideti@iiitb.ac.in</a>
Rithvik Ramasani	IMT2020543	<a href="mailto:Rithvik.Ramasani@iiitb.ac.in">Rithvik.Ramasani@iiitb.ac.in</a>
K. Surya Vamsi	IMT2020552	<a href="mailto:Surya.Vamsi@iiitb.ac.in">Surya.Vamsi@iiitb.ac.in</a>
Ram Yerra	IMT2020558	<a href="mailto:Ram.Yerra@iiitb.ac.in">Ram.Yerra@iiitb.ac.in</a>

## Introduction

Our project consists of three major independent units:

- Scrap Collection Unit
- Mopping Unit
- Obstacle Detection Unit

## Components Used

1. Arduino Uno
2. Motor Sheild (L293D)
3. Water Pump (12 V)
4. Geared Motors
5. Ultrasonic sensors
6. Servo motor

7. Battery holders
8. 9 V battery
9. AA battery
10. Chassis

## Functionalities

Scrap Collection Unit – Dust and dirt is drawn up by the vacuum created by this unit. Vacuum is generated by creating pressure difference using a fan inside the suction chamber.

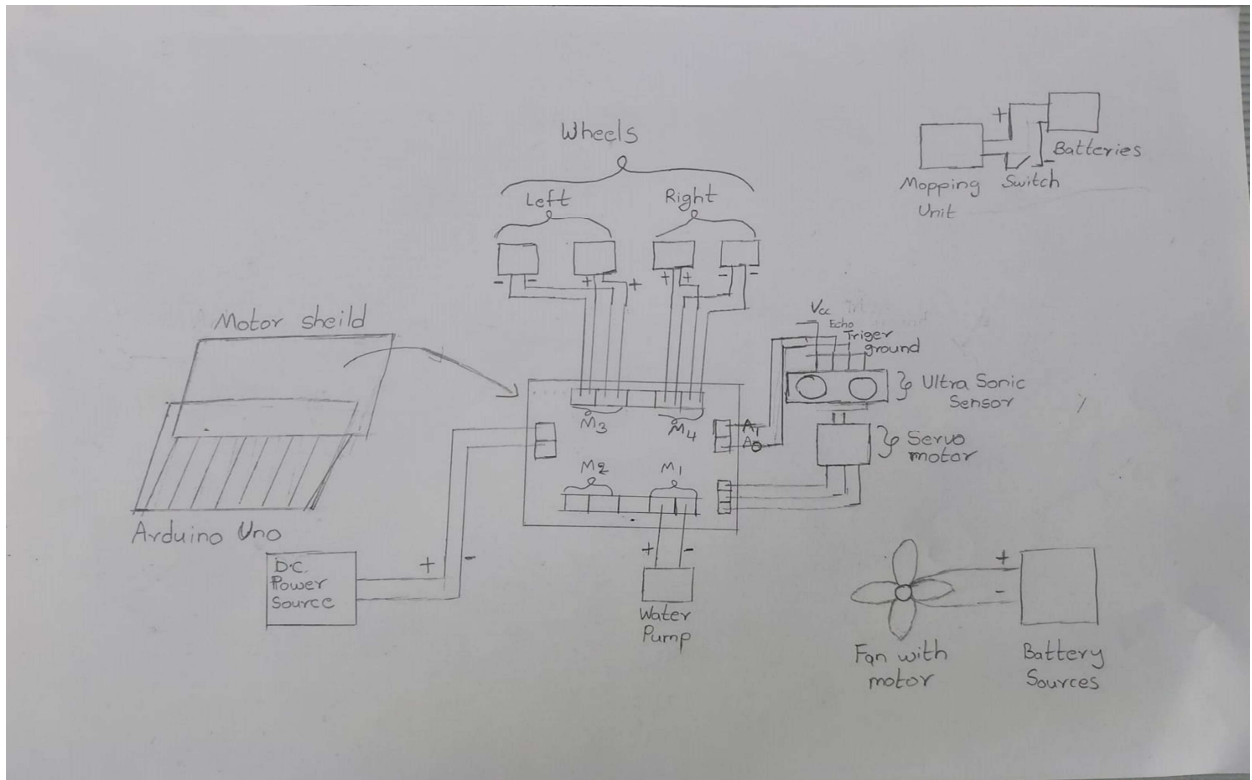
Mopping Unit - Water is sprinkled occasionally by water pump, which is then cleaned by rotating floor mops.

Obstacle Detection Unit – Detects objects in path using ultrasonic sensors and re-routes accordingly.

## Problems Faced

- Finding an appropriate power source.
- Dealing with friction generated by moping unit.
- Regulating the flow of water.
- General problems faced during turnings.
- Dealing with the inaccurate readings provided by Ultrasonic sensors.

# Circuit Diagram



## Future Aspects

- Integrated motion sensors and a well-designed structure.
- Powerful suction unit.