```
"Name - Ritik Vishwakarma \nRoll no - 1773 \nBatch : B")
    A-[4 19 26 13 28 1,33,27]
    search=int[imput("Enter the number to be searched : "))
    for i in range(len(A)):
    if (search==A[i]):
     found=True
     print("Number found at index ",i)
   if (found==False):
   print("Number not found in the list")
  Case 1 (When Number is there in the list):
  ***************
  Name : Ritik Vishwakarma
  Roll no : 1773
 Enter the number to be searched: 26
 Number found at index 2
 Case 2 (When Number is not there in the list):
Name : Ritik Vishwakarma
Enter the number to be searched : 34
Number not found in the list
```

## PRACTICAL NO. 1 Aim: To search a number from the unearted list using linear search. Theory: The process of identifying or finding a particular record is called searching. There are two types of search: @ Linear Search OBinary Search The linear search is further classified as: (i) Sorted (ii) Unsorted. Here we will look on the Unsorted linear Linear search, also known as sequential search, is a process that ducks every element in the list sequentially until the desired element is found. When the elements to be searched are not specifically arranged in ascending or descending order. They are arranged in random manner, that is what it calls unsorted linear search. Unsorted Linear Search: The data is entered in random manner. @ lier needs to specify the clonent to be searched in the list. The condition is checked that whollow entered number is equal to the clarent observice it proceeds to next elements. If element is not found then

appropriate message is displayed.

Alm: To search a number from the sorted list waing linear Search.

Theory: - Seasoning and Sorting are two different modes or types of data structures. Sorting - To basically awange the inputed data in Searching - To search elements and to display the

In searching that too in linear sorted search, the data is arranged in according or decarding order.
That is all what it meant by searching through

'sorted that is well arranged data.

Sorted Linear Search: The user is supposed to enter the data in sorted

Olser has to give anxelement for seasching through sorted list.

The dements are checked whether they are those in the list.

@ In sorted list we at can check that element to be searched lies in the between the starting and the ending point of list.

print("Name : Ritik Vishwakarma \nRoll no : 1773 \nBatch : B") found=False A=[1,4,13,19,26,27,28,33] search=int(input("Enter the number to be searched: "]) if (search<A[0] or search>A[len(A)-1]): print("Number does not exist in the list") for i in range(len(A)): if (search==A[i]): found=True print("Number found at index ",i) break if (found==False): print("Number not found in the list") Output: Case 1 (When number is there in the list) \*\*\*\*\*\*\* Enter the number to be searched: 27 Number found at index 5 Case 2 (When number is out of range of the list): Name : Ritik Vishwakarma

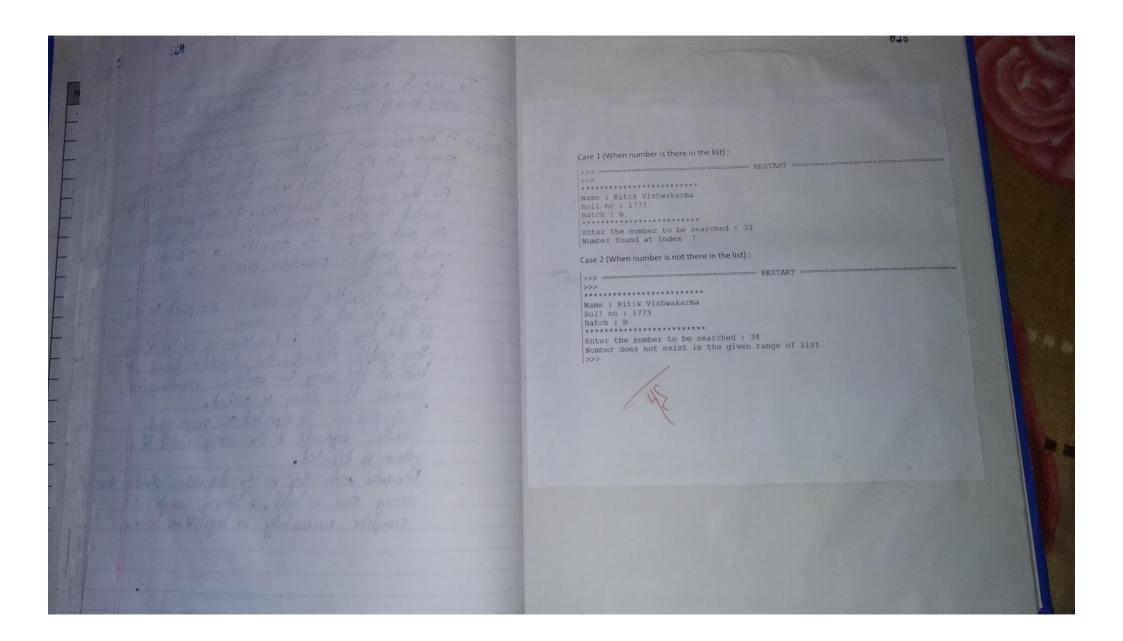
```
print("*******)
  print("Name : Ritik Vishwakarma \nRoll no : 1773 \nBatch : B")
   A=[1,4,13,19,26,27,28,33]
  search=int(input("Enter the number to be searched - "))
  r=len(A)-1
  m=int((1+r)/2)
 if (search<A[I] or search>A[r]):
  print("Number does not exist in the given range of list")
 elif (search==A[I]):
  print("Number found at index ",I)
 elif (search==A[r]):
  print("Number found at index ",r)
  while True:
   if (search==A[m]):
    print("Number found at index ",m)
     break
     if (search<A[m]):
    m=int((I+r)/2)
if (search!=A[m]):
```

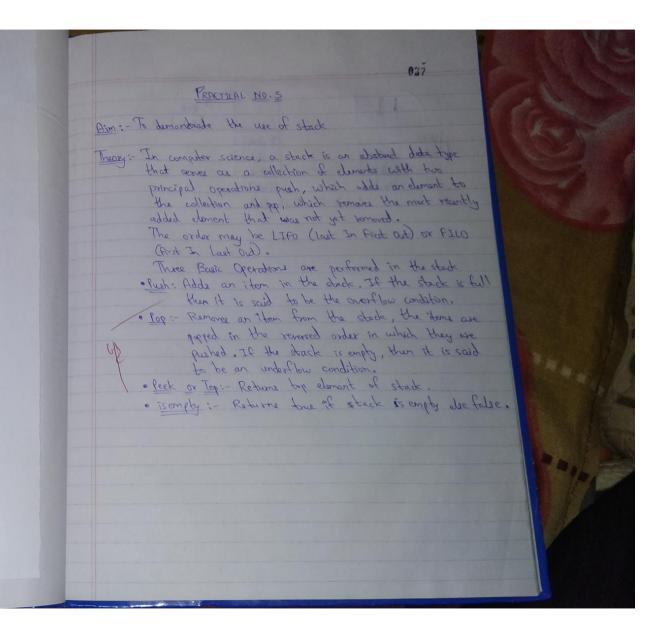
print("Number not found in the list")

## PRACITICAL NO. 3

Aim: To search a number from the given corted list using binary search.

Theory: A binary search also known as a half-interval search, is an algorithm used in computer science to locate a specified value (key) within an array. For the search to be binary, the array must be sorted in either ascerding or descending order. At each step of the algorithm a comparison is made and the procedure brenches into one of two directions. Specifically, the key value is compared to the middle elevent of the array. If the key value is less than or greater than this middle clement, the algorithm knows which half of the array to combinue searching in because the array is corted. This process is repeated on progressively smaller segments of the array until the value is located. Because each step in the algorithm divides the array size in half, a binary search will complète successfully in logarithmic bine.





class stack:
global tos
def \_\_init\_\_(self):
self.l=[0,0,0,0,0,0,0]
self.tos=-1
def.push(self.data):

def push(self,data): n=len(self.l)

if self.tos==n-1: print("Stack is full")

else:

self.tos=self.tos+1 self.t[self.tos]=data

def pop(self):

if self.tos<0: print("Stack is empty")

else:

k=self.l[self.tos]

print("Data = ",k)

self.tos=self.tos-1

s=stack()

s.push(10)

s.push(20)

s.push(30)

s.push(40)

s.pusi(50)

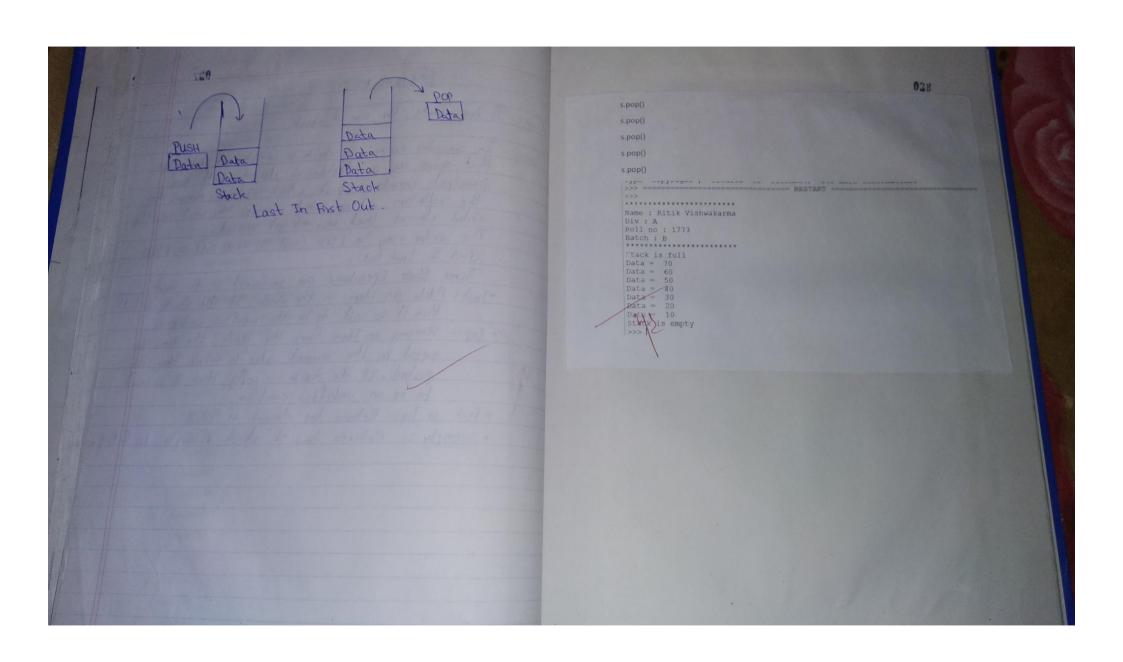
- mai

s.push(80)

s.pop(

s.pop(

()qoq.



global r global f def\_init\_(self) self.r=0 self.f=0 self.l=[0,0,0,0,0,0] def add(self,data): n=len(self.l) is self.r<n: self.l[self.r]=data self.r=self.r+1 else: print("Queue is full") def remove(self): n=len(self.l) if self.f<n: print(self.l[self.f]) self.f=self.f+1 print("Queue is empty") q=queue() g.add(30) q.add(40) q.add(80) q.remove()

PRACTICAL NO. 6

Aim: To demonstrate gues add and delete.

Theory: - Queue is a linear data structure where the first element is inserted from one end called REAR and deleted from the other end called as FRONT.

FRONT points to the beginning of the queue and REAR points to the ord of the queue.

Queue follows the FIFO (First In Frest Out) structure.

According to its FIFO structure, element inverted first will also be removed first.

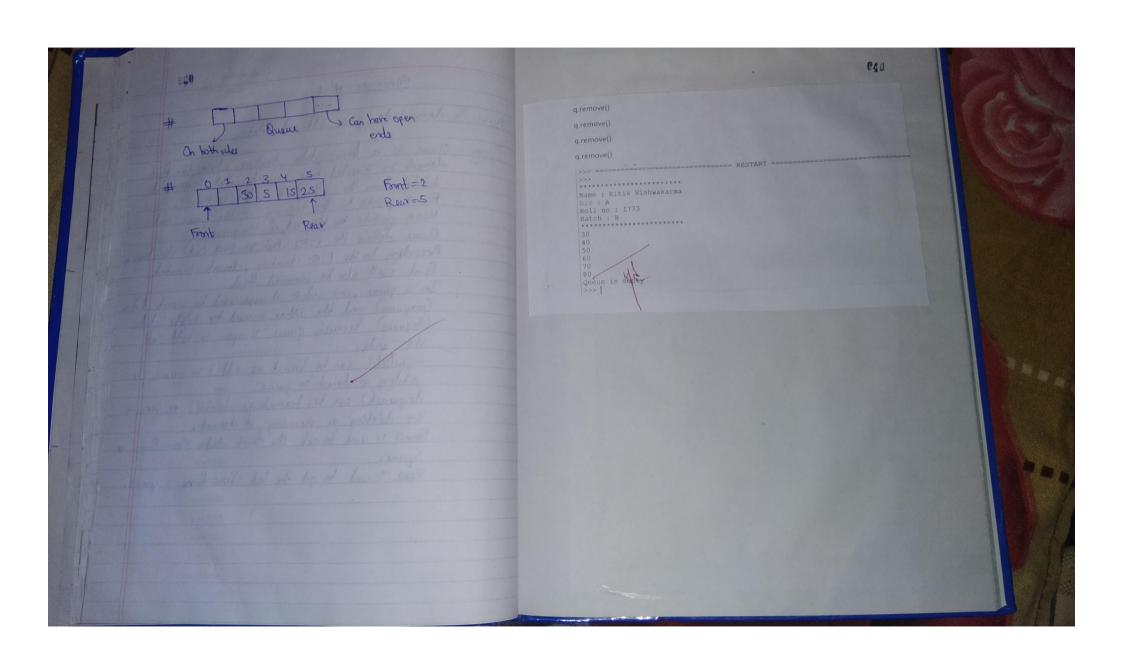
In a queue, one end is always used to insert data (enqueue) and the other is used to delete data (dequeue) because queue is open or both of its ends.

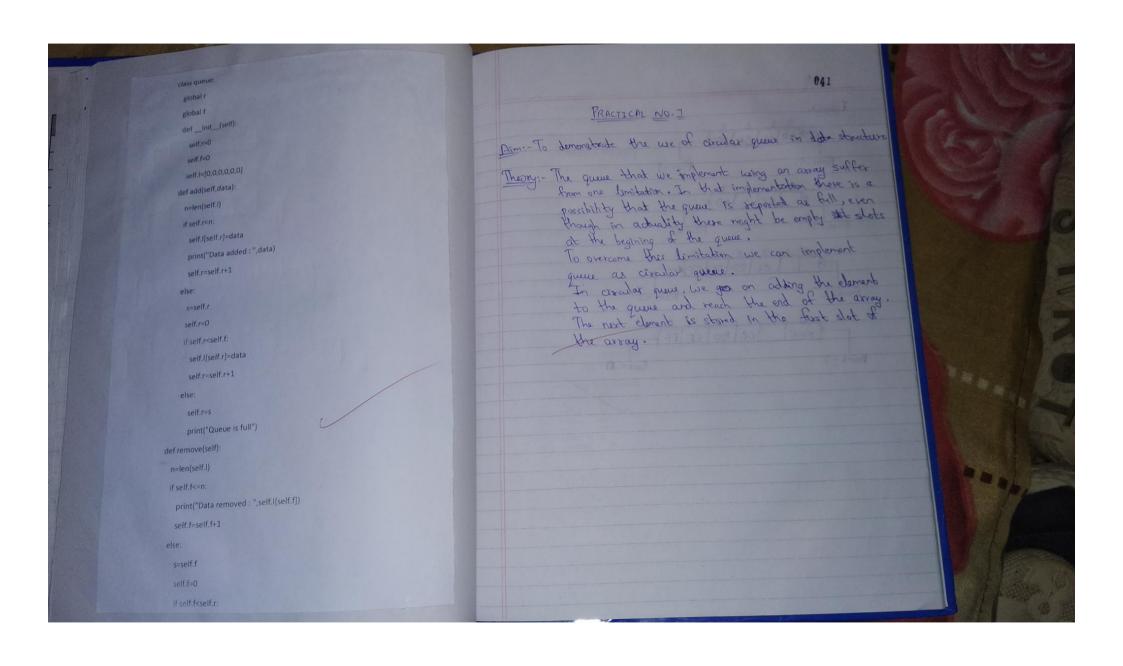
enquete() can be termed as add() in queue i ending an element in queue.

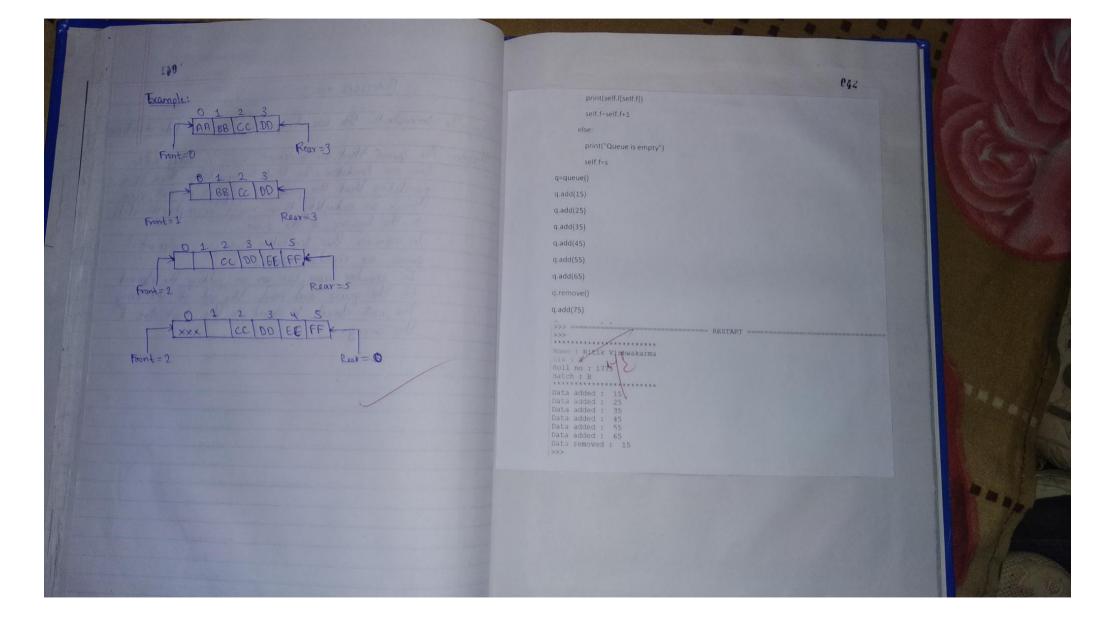
dequeue() can be termed as delete() or remove

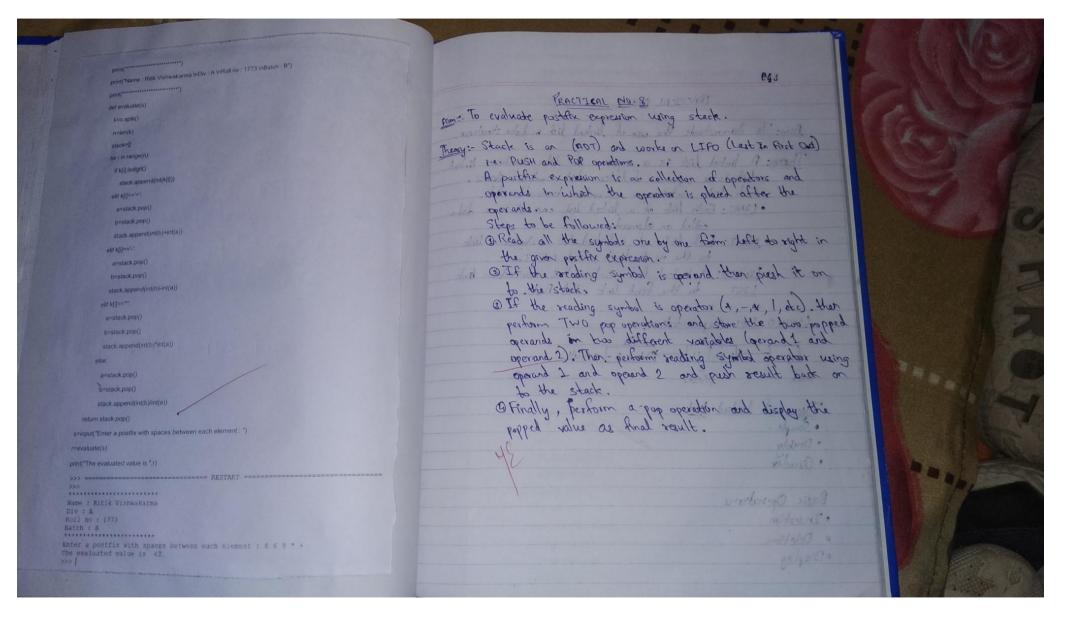
Trans is used to get the front data Hern from a

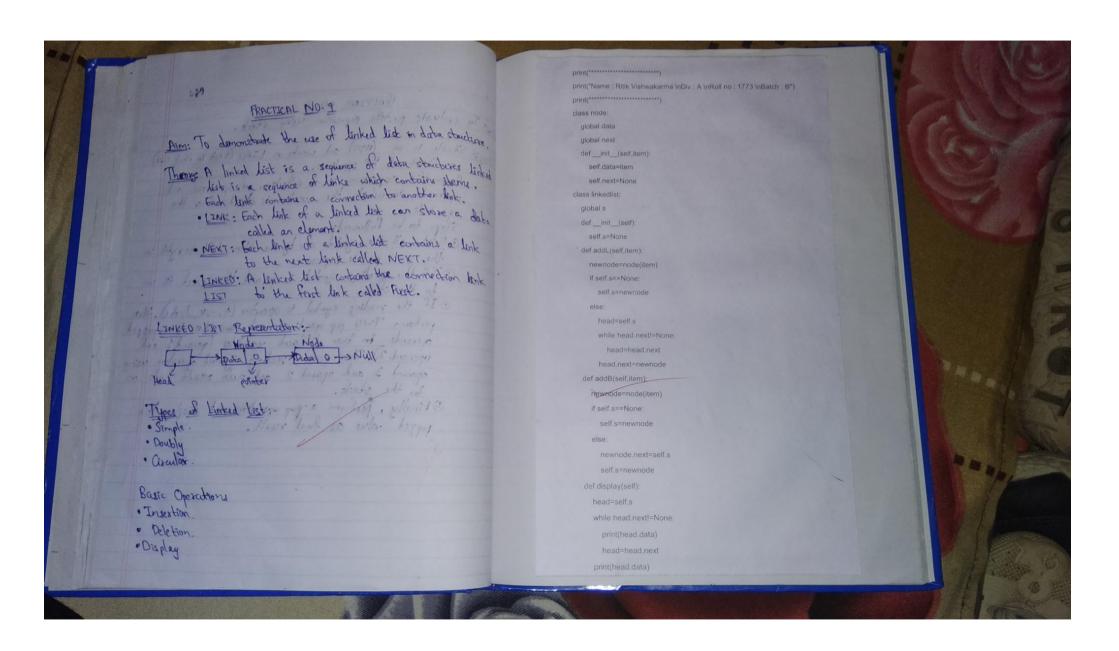
queue.
REAR is used to get the last item from a queue.

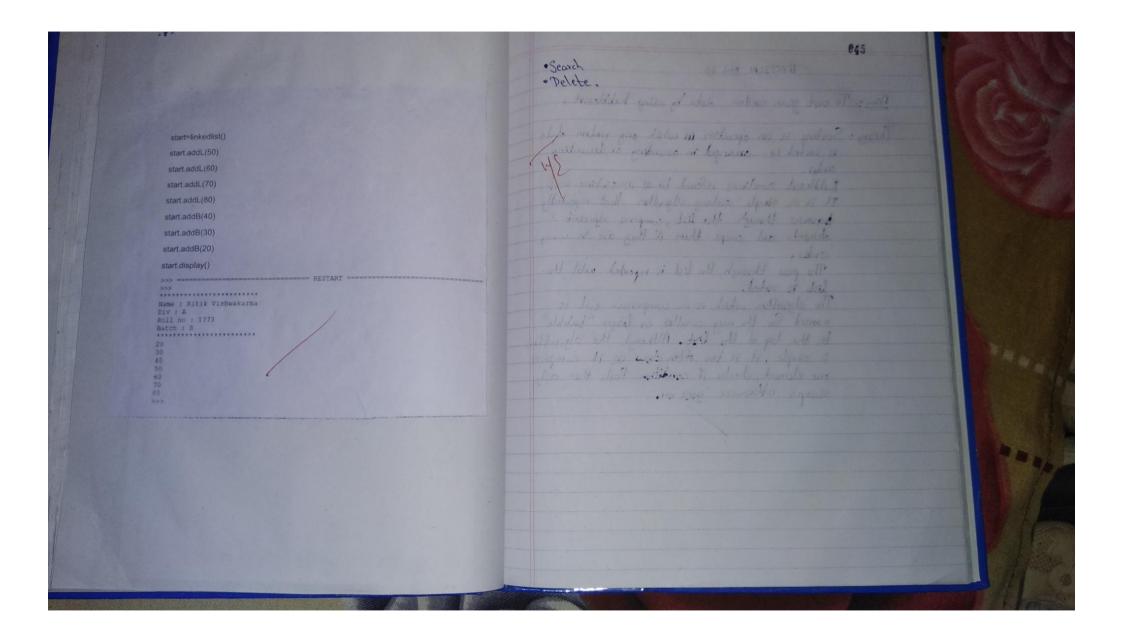












Theory: Sorting is an operation in which any random data is sorted in arranged in ascending or descending

Bubblesort sometimes referred to as a sinking sort.

Bubblesort sometimes referred to as a sinking sort.

It is a simple sorting algorithm that repeatedly to a simple sorting algorithm that repeatedly to a sometimes. Though the list, compares adjacent advances through they are in wang order.

The pass through the list is repeated until the list is sorted.

The algorithm which is a comparison sort is named for the way smaller or larger "babble"

named for the way smaller or larger "bubble" to the top of the list. Although the algorithm is simple, it is too after slow as it comparer one element, checks if condition fails then only

swaps otherwise goes on.

```
print("Name: Ritik Vishwakarma \nDiv: A \nRoll no: 1773 \nBach: 8")

print("The elements before sorting are: ",a)

for i in range(len(a)-1):

    if (a[j]>a[j+1]:

        temp=a[j]

        a[j]=a[j+1]

        a[j+1]=temp

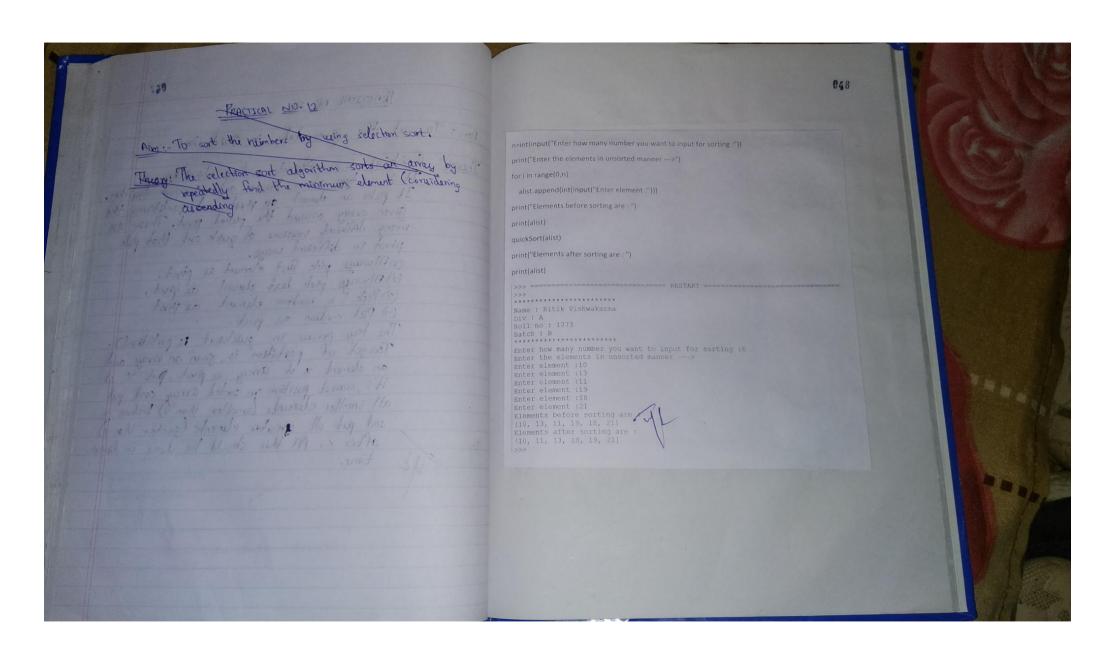
print("The elements after sorting are: ",a)

>>>

Name: Ritik Vishwakarma
Div: A
Roll no: 1773
Batch: B
The elements before a sorting are: [4, 33, 19, 26, 73, 71]
The elements before sorting are: [4, 19, 26, 33, 71, 731]
>>> |
```

845

def quickSort(alist): quickSortHelper(alist,0,len(alist)-1) def quickSortHelper(alist, first, last). splitpoint=partition(alist\_first\_last) quickSortHelper(alist,first,splitpoint-1) quickSortHelper(alist,splitpoint+1,last) def partition(alist, first, last): pivotvalue=alist[first] leftmark=first+1 rightmark=last done=False while leftmark<=rightmark and alist[leftmark]<=pivotvalue: leftmark=leftmark+1 while alist[rightmark]>=pivotvalue and rightmark>=leftmark: rightmark=rightmark-1 if rightmark<leftmark: done=True temp=alist[leftmark] alist[leftmark]=alist[rightmark] alist[rightmark]=temp temp=alist[first] alist[first]=alist[rightmark] alist[rightmark]=temp return rightmark print("Name: Ritik Vishwakarma \nDiv: A \nRoll no: 1773 \nBatch: B") 



Theory: Binary tree is a tree which supports maximum of two child for any node within the tree, thus any particular node can have either 0 or 1 or 2 tild Leaf Node: Nodes which do not have any shild.

Toternal Node: Nodes which are non-leaf nodes.

Traversing can be defined as a process of visiting every node of the tree exactly once.

Breorder: (1) Visit the root node.

(2) Traverse the left subbree. The subbree in turn might have left and right subbrees.

(3) Traverse the right subtree. The right subtree inturn might have left and right subtrees.

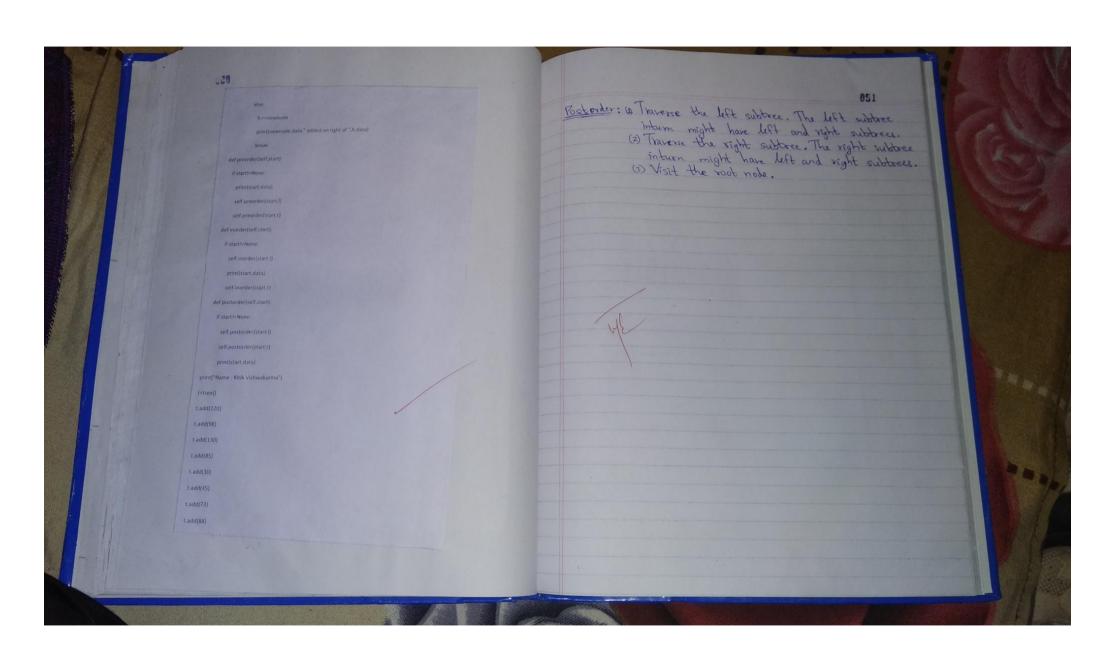
Inorder: (1) Traverse the left subtree. The left subtree intum
might have left and right subtree.

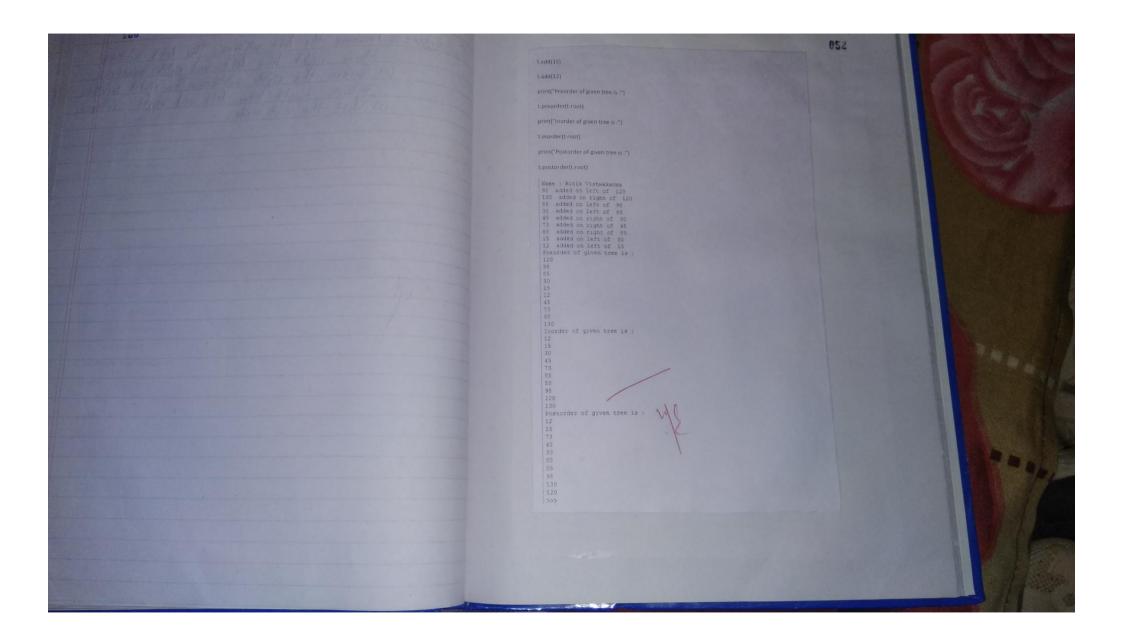
(2) Visit the root node.

(3) Traverse the right subtree. The right subtree inturn might have left and right subtrees.

if h II=Nonif h.rl=None

050





for j in range(0,n2) while(j<n2):

