Open Drone ID

Implementation Specification

Specification Version 0.58

Protocol version 0

Apr 24, 2018

 © 2018 Intel Corporation

Contents

1 Introduction 4
2 Selection of the technical solution 4
3 BLE (Bluetooth 4.x compatible) Advertisements 5
Beacon Definition 5
Additional BLE 4.x Frame Details 5
Transmitting Frequency 6
4 Bluetooth 5.0 Extended Advertisements 8
Bluetooth 5 Extended Advertisement Primary (Pointer) Packet 9
Aux Ptr Field Details 10
Bluetooth 5 Extended Advertising Secondary Packet 10
5 Message Definitions 12
Message Header 12
Basic ID Message 12
Location Message 13
Authentication Message 13
Self ID Message 14
Enumerated Field Definitions 14
6 Compliance and Interoperability 14

 © 2018 Intel Corporation

Update History

Version	Date	Changes	Author
0.54	3/1/2018	Started Change Control (initial version baseline)	G. Cox, Jan S.
0.55	4/3/2018	* Changed all Messages Modes S field from 28 bit, to 32 bit UniqueID * Base ID Message: Moved Sub-Type up to after under Drone Type * Location Message: Changed final reserved field to 4 bits since the Unique ID went from 24 to 32 bits.	G. Cox
0.56	4/20/2018	Added BT5 Extended Advertisements	G. Cox
0.57	4/24/2018	Added Additional Packet Detail Tables, Moved Message Definitions to end	G. Cox
0.58	4/25/2018	Location Message: Moved “Reserved” up to after “Status”	G. Cox

© 2018 Intel Corporation

1 Introduction

On December 19th 2017 the Federal Aviation Administration (FAA) published the UAS Remote Tracking & ID ARC Report[1] to update the public about the latest results from the Aviation Rulemaking Committee (ARC) chartered by the FAA.

Within the ARC recommendation were some options for "Broadcasting" a Drone ID. This specification is designed to meet such needs expressed in the ARC Report.

2 Selection of the technical solution

The solution outlined in this specification is for the broadcasting category of drone identification. In the ARC, several solutions were discussed. After considering all inputs from the ARC and an internal decision process the proposal is to use the Bluetooth Low Energy (BLE) standard V4.2 Advertisements and 5.0 Advertising Extensions as the underlying technology for the Intel Open Drone ID implementation. The primary factors justifying this technology are:

- Commoditized open standard supported by most modern smartphones as a receiving device
- Very low BOM cost to add to a drone
- Very low weight with solutions below 10g
- Robust protocol implementation with congestion handling and up to 1km range (v5.0 AE).
- Very easy to retrofit to existing drones

The range of Bluetooth V4.0 is depending on the transmit power, as well as the exact transmitter and receiver setup including the antenna. In typical scenarios a range to a smartphone of over 250m is realistic. For better antenna installations at critical sides the range could be increased to more than 1km. Based on the specifications, with Bluetooth V5.0, the range will quadruple. This range will be suitable for most scenarios while providing 2 huge benefits:

1. Public Safety Departments cost of acquiring receivers could potentially be minimized to the cost of their available smartphones.
2. The general public can use their smartphone to read the Drone IDs and help by accurately reporting airspace contention or security problems.

Bluetooth uses three different beacon channels that can broadcast messages to non-specific endpoints. Although the remaining 37 channels operate in the 2.4 Ghz range, where WiFi resides, the channels are much narrower and specifically the beacon channels are outside of the bands most WiFi traffic and generally do not compete against WiFi (see Figure 1 below).

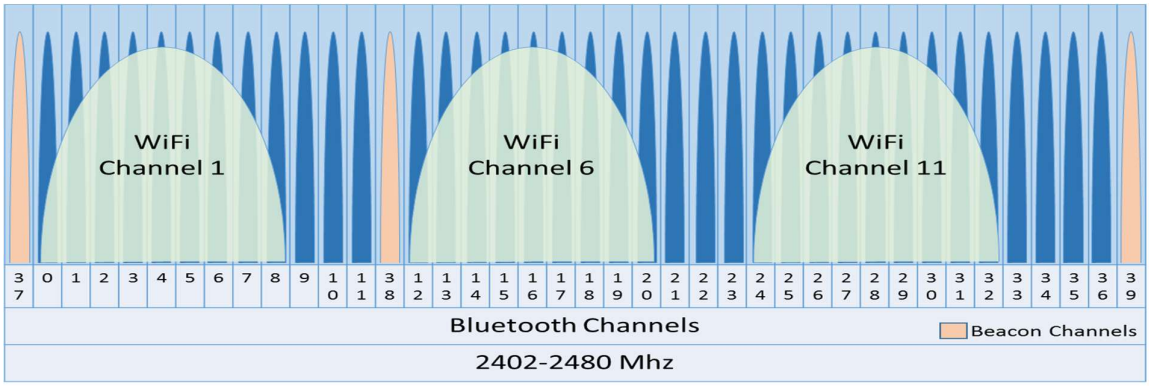

Figure 1 – Bluetooth Channels

[1] https://www.faa.gov/news/updates/?newsId=89404

 © 2018 Intel Corporation

3 Implementation Overview

In this specification, the intent is to use a Bluetooth radio to send connectionless broadcast frames (Advertisements) that work with both BT 4.x and 5.x receivers. Supporting both architectures allows for compatibility with existing BT4 receivers (like most cell phones as of 2018), yet can still take advantage of the range enhancements (4x) of BT5 which is starting to ship with newer cell phones and can also be installed as external receivers.

4 BLE (Bluetooth 4.x compatible) Advertisements

BLE supports a "Broadcast Frame" to go out on the beacon channels with a custom message length limit of 26 bytes. These broadcast messages shall be "uncoded" and conform to Bluetooth Core Specification 5.0, Volume 6, Part B, Sections 2.1 and 2.3.1.[2]

Beacon Definition

These BLE frames shall be sent as illustrated below in Figure 2.

BLE4 Advertisement Frame							
Preamble (1 Byte)	Acc Addr (4 Bytes)	PDU Hdr (2 Bytes)	AD Addr (6 Bytes)	AD Flags (4 Bytes)	AD Counter (1 Byte)	Open Drone ID Message (26 Bytes)	CRC (3 Bytes)
0xAA	0x8E89BED6	0x2025	<public>	0x1FFF0200	0x00	<message>	<calculated>

Open Drone ID Message			
Msg Type (4 bits)	Version (4 bits)	UniqueID	Message (21 Bytes)
0x1 – 0x4	0x0-0xF	4 Bytes	<Open Drone ID message>

Figure 2 –BLE Advertisement Frame Format

Additional BLE 4.x Frame Details

Field	Size*	Value	Contents
Preamble	1	0xAA	LE 1M Packet
Acc Address	6	0x8E89BED6	Broadcast Packet
PDU Hdr	2	0x2025	PDU Type: 0x2 – ADV_NONCONN_IND – Connectionless Advertisement RFU: 0 – Reserved ChSel: 0 – Reserved TxAdd: 0 – Indicates AD Addr is HW Address (rather than random) RxAdd: 0 – Reserved Len: 0x25 – 37 Bytes
AD Addr	6	0xXXXXXX	Unique Hardware Address of Bluetooth MAC
AD Flags	4	0x1FFF0200	Length: 0x1F – 31 Bytes (excluding this field) Type: 0xFF – Manufacturer Specific Mfg Code: 0x02 – Intel Mfg Flags: 0x00 – Reserved
AD Counter	1	0xXX	Msg Counter: Start at 0, increment for each message of the same type
ODID Msg	26	<26 Bytes>	Open Drone ID Message – see section 0 (*Message* Definitions)
CRC	3	<calculated>	CRC Error Correction Data as defined in Bluetooth Core Specification 5.0, Volume 6, Part B, Section 3.1.1

[2] https://www.bluetooth.com/specifications/bluetooth-core-specification

 © 2018 Intel Corporation

Transmitting Frequency

These 26 byte long messages, as defined in section 0 (

© 2018 Intel Corporation

Message Definitions), shall be sent by each drone Bluetooth beacon. Depending on whether the data is static or dynamic, the messages will be sent at a low or higher frequency (respectively).

As such, the following message frequencies shall be maintained:
Static: Every 3 seconds.
Dynamic: 3 per second.

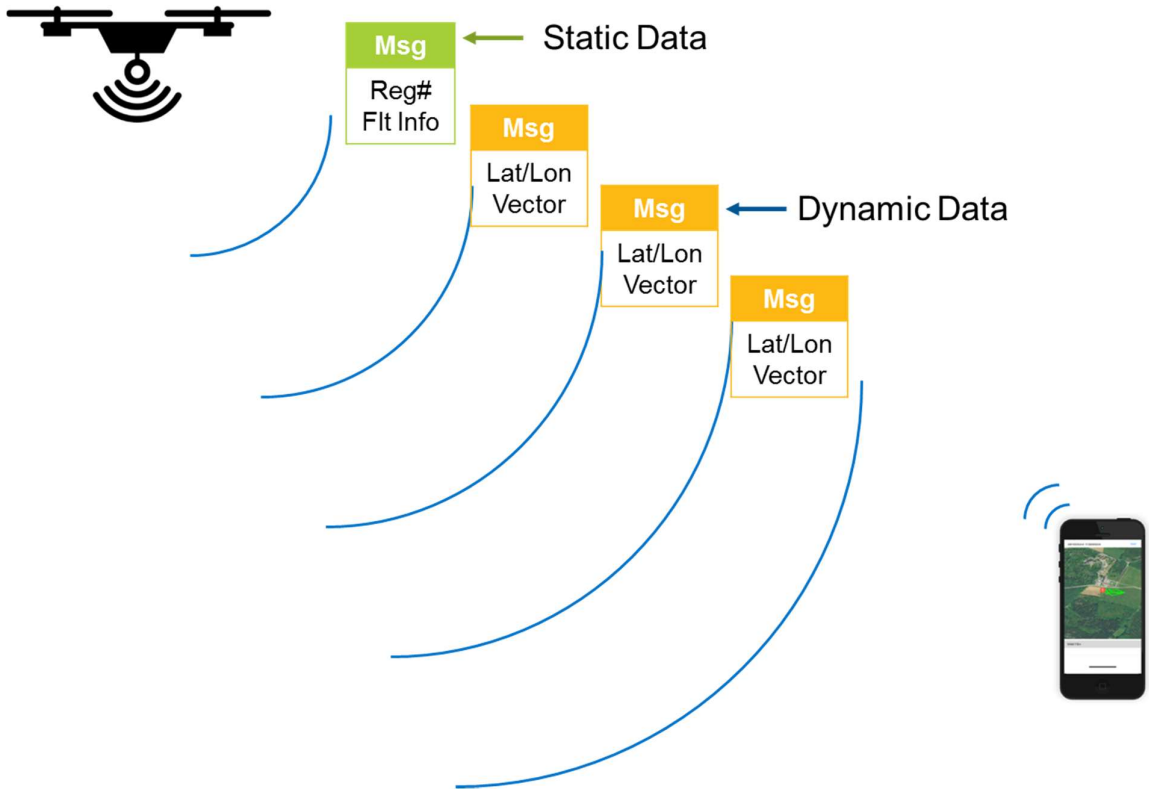

Figure 3 - Static and Dynamic Messages

© 2018 Intel Corporation

5 Bluetooth 5.0 Extended Advertisements

In addition to sending standard (ADV_NONCONN_IND) BLE (4.2) advertisements, Bluetooth 5 Extended Advertisements (ADV_EXT_IND + AUX_ADV_IND) must be sent as well at the same rate as Dynamic Data (see Section 3 *Transmitting Frequency*) and they must be sent on an LE Coded (S=8) PHY. This will add Forward Error Correction (FEC) and increase the range of the advertisements by 4x. These messages shall conform to Bluetooth Core Specification 5.0, Volume 6, Part B, Sections 2.2 (LE Coded PHY, S=8).

While BLE (4.2) advertisements broadcast on the beacon channels 37,38,39, Bluetooth 5 adds Extended Advertising that allow for up to 255 byte advertisements on the "non-beacon" channels by implementing a pointer in the primary beacons directing the receiver to read from the secondary channel.

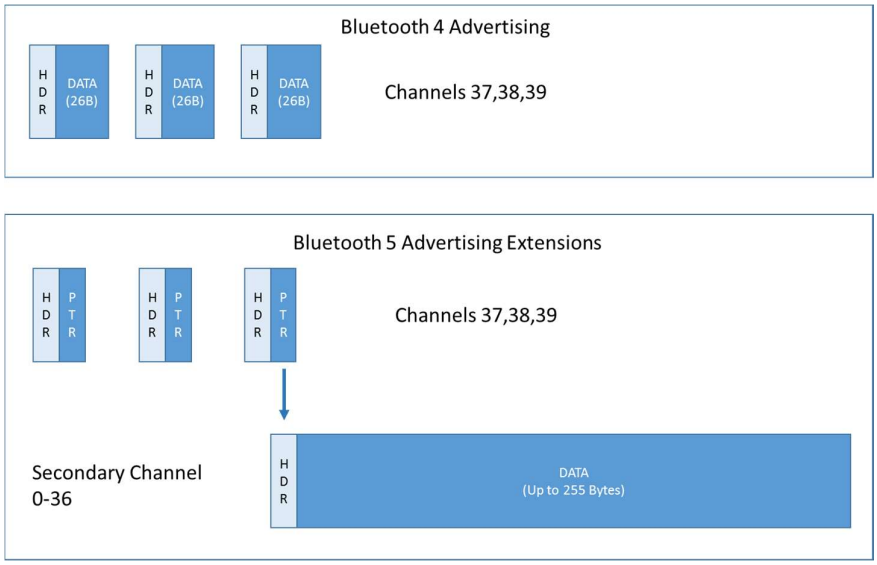

Figure 4 - Bluetooth 4 and 5 Extended Advertising Comparison

When performing a Bluetooth 5 Advanced Advertisement, all messages must be sent together as a single "message pack" as illustrated below in Figure 5Figure 1.

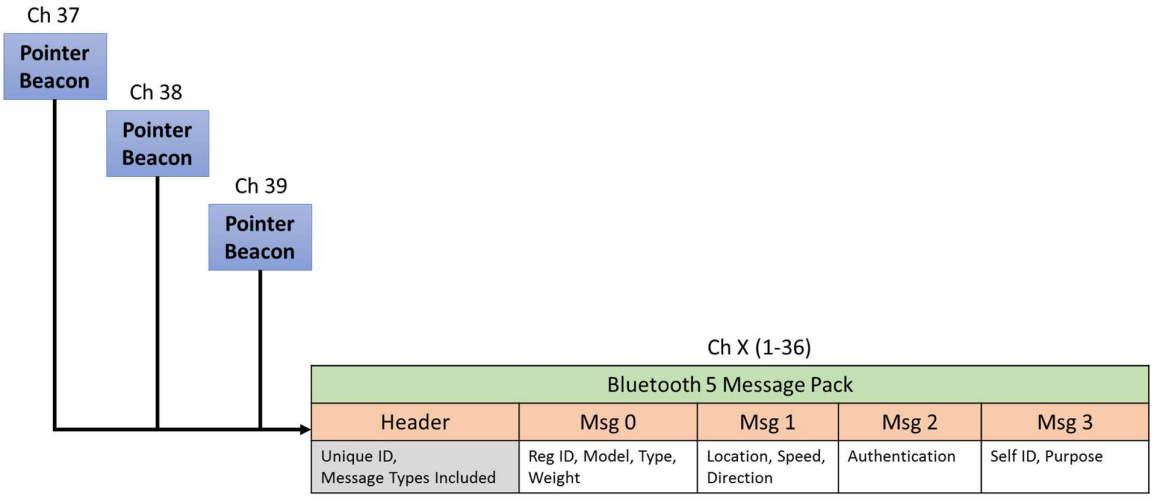

Figure 5 -- Bluetooth 5 Message Pack

© 2018 Intel Corporation

Bluetooth 5 Extended Advertisement Primary (Pointer) Packet

The Bluetooth 5 Extended Advertisement Primary packet includes a pointer to the Secondary Packet as illustrated below. Therefore, the Primary packet shall be broadcast through all 3 beacon channels, followed by the Secondary packet on the remaining channels (see <reference to packet spreading algorithm).

BLE5 Long Range Advertisement Pointer Frame (LE Coded)										
Preamble (1 Byte) [Coded Phy]	Acc Addr (4 Bytes)	CI (2bits) [S=8]	TERM1 (3bits)	PDU Hdr (2 Bytes)	Ext Hdr Len (6 Bits)	Adv Mode (2 bits) non-scan undirect	Ext Header (12 Bytes)	Adv Data	CRC (3 Bytes)	Term2 (3bits)
0x3C	0x8E89BED6	00b	<xxx>b	0x700D	0x0C	00b	<12 bytes>	N/A	<calculated>	<xxx>b

Additional Primary Packet Details

Name	Size*	Value	Value Description
Preamble	1	0x3C	LE Coded PHY
Acc Addr	6	0x8E89BED6	Broadcast Packet
CI	2 bits	00b	Coding Indication: FEC Block 2 is coded using S=8 (longest range)
Term1	3 bits	xxxb	FEC Block 1 Termination as defined in Bluetooth Core Specification 5.0, Volume 6, Part B, Section 3.3.1
PDU Hdr	2	0x700D	
Ext Hdr	12		
CRC	3		CRC Error Correction Data as defined in Bluetooth Core Specification 5.0, Volume 6, Part B, Section 3.1.1
Term2	3bits		FEC Block 2 Termination as defined in Bluetooth Core Specification 5.0, Volume 6, Part B, Section 3.3.1

PDU Hdr:

Field	Bits	Hex	Desc
PDU Type	0111	0x7	ADV_EXT_IND (Primary)
RFU	0	0x0	Reserved
ChSel	0		Reserved
TxAdd	0		Reserved
RxAdd	0		Reserved
Len	0010 0101	0x0D	13 Bytes

Ext Hdr:

Field	Size*	Bits (binary)	Hex	Desc
Flags	1	0001 1001	0x19	Field Selection (AdvA, ADI, Aux Ptr)
AdvA	6	<HW ADDR>	0xXXXXXX	Adv Address (HW Addr)
ADI	2	0000 0000 0000 xxxx	0x0000 – 0x000F	Advertising Data ID (12bits) = 0 Advertising Set ID (4bits): Increment each time data changes
Aux Ptr	3	cccc cca0 dddd dddd dddd d010	0xXXXXXX	ccccc = Channel a = clock accuracy 0 = 30us offset multiplier dddddd = offset/delay 010 =LE Coded Phy ** See Aux Ptr Field Details below.

* Bytes

© 2018 Intel Corporation

Aux Ptr Field Details

The Aux Ptr Field in the Primary Packet shall be implemented in accordance to the Bluetooth Core Specification 5.0, Volume 6, Part B, Section 2.3.4.5 with the following guidance.

Channel Index	Shall be calculated using the following formula: Channel = (Current Channel + 9) % 36 This will ensure some entropy by hopping through the channels and spreading out the beacons to minimize the effects of external interference.
Clock Accuracy (CA)	0: 51 – 500ppm 1: 0 - 50ppm
Offset Units	0: 30us
Aux Offset/Delay	This represents the time offset from when the primary packet is sent and the secondary packet. Since all 3 primary packets are sent prior to the secondary packet, the offset is different for each one. This offset should be calculated based on the Bluetooth Core Specification 5.0 specification. The following offsets may be used as guidance : Beacon 1: 166 us Beacon 2: 114 us Beacon 3: 62 us These calculations are based on a primary packet time of 1552us + a T_MAFS (minimum aux frame space) of 300us divided by the offset multiplier unit of 30us. The time of sending the current beacon + remaining beacons must be included. Thus, Beacon 1 includes the time of itself + 2 more beacons + T_MAFS.
Aux PHY	010: LE Coded Phy

Bluetooth 5 Extended Advertising Secondary Packet

The secondary packet contains the actual desired advertisement. Additionally this packet contains a 16 bit “Message Type Mask” which includes bit representing that message types included. All message types supported shall be represented within a single Secondary Packet in the order of lowest message type (index) first. Only the messages selected in the Message Type mask shall be presented within the single Secondary Advertising Packet (with a capacity of up to 255 bytes).

BLE5 Long Range Advertisement Data Frame (LE Coded)										
Preamble (1 Byte) [Coded Phy]	Acc Addr (4 Bytes)	CI (2bits) [S=8]	TERM1 (3bits)	PDU Hdr (2 Bytes)	Ext Hdr Len (6 Bits)	Adv Mode (2 bits) non-scan undirect	Ext Header (12 Bytes)	Adv Data	CRC (3 Bytes)	Term2 (3bits)
0x3C	0x8E89BED6	00b	<xxx>b	0x7025	0x09	00b	<9 Bytes>	<7 + N*21 Bytes>	<calculated>	<xxx>b

*N = Number of Message Types in Message Pack

Open Drone ID BLE5 Message Pack							
MsgType (4 bits) [BT5hd]	Version (4 bits)	UniqueID	Msg Types Mask (16 bits)	Counter	Message (Type 0)	Message (Type 1)	....
0xF	0x0-0xF	4 Bytes	0x000F	<1 Byte>	<21Bytes>	<21Bytes>	....

Name	Size*	Value	Value Description
Preamble	1	0x3C	LE Coded PHY
Acc Addr	6	0x8E89BED6	Broadcast Packet
CI	2 bits	00b	Coding Indication: FEC Block 2 is coded using S=8 (longest range)
Term1	3 bits	xxxb	FEC Block 1 Termination as defined in Bluetooth Core Specification 5.0, Volume 6, Part B, Section 3.3.1

 © 2018 Intel Corporation

<table>
<tr><td>PDU Hdr</td><td>2</td><td>0x70XX</td><td>
<table>
<tr><th>Field</th><th>Bits</th><th>Hex</th><th>Desc</th></tr>
<tr><td>PDU Type</td><td>0111</td><td>0x7</td><td>AUX_ADV_IND (Secondary)</td></tr>
<tr><td>RFU</td><td>0</td><td rowspan="4">0x0</td><td>Reserved</td></tr>
<tr><td>ChSel</td><td>0</td><td>Reserved</td></tr>
<tr><td>TxAdd</td><td>0</td><td>Reserved</td></tr>
<tr><td>RxAdd</td><td>0</td><td>Reserved</td></tr>
<tr><td>Length</td><td>xxxx xxxx</td><td>0xXX</td><td>18 + N*21 Bytes where N is the number of Messages in the Message Pack</td></tr>
</table>
</td></tr>
<tr><td>Ext Hdr</td><td>12</td><td></td><td>
<table>
<tr><th>Field</th><th>Size*</th><th>Bits (binary)</th><th>Hex</th><th>Desc</th></tr>
<tr><td>Flags</td><td>1</td><td>0000 1001</td><td>0x09</td><td>Field Selection (AdvA, ADI)</td></tr>
<tr><td>AdvA</td><td>6</td><td><HW ADDR></td><td>0xXXXXXX</td><td>Adv Address (HW Addr)</td></tr>
<tr><td>ADI</td><td>2</td><td>0000 0000
0000 xxxx</td><td>0x0000 – 0x000F</td><td>Advertising Data ID (12bits) = 0

Advertising Set ID (4bits): Increment each time data changes</td></tr>
</table>
</td></tr>
<tr><td>CRC</td><td>3</td><td></td><td>CRC Error Correction Data as defined in Bluetooth Core Specification 5.0, Volume 6, Part B, Section 3.1.1</td></tr>
<tr><td>Term2</td><td>3bits</td><td></td><td>FEC Block 2 Termination as defined in Bluetooth Core Specification 5.0, Volume 6, Part B, Section 3.3.1</td></tr>
</table>

 © 2018 Intel Corporation

6 Message Definitions

Message Header

Each 26 byte message shall begin with a 5 header bytes including the Message Type, Protocol Version and Unique ID. If the first byte of the Unique ID is 0x00, then the remaining 3 bytes shall be the ICAO 24-Bit Aircraft Address (Mode-S Code).

Header (5 bytes)			Message (21 Bytes)
Message Type (4bits)	Protocol Version (4bits)	Unique ID (4 Bytes)	Message Fields based on Message Type
0x1-0xF	0x0	Ex: 0x00A79E9F	< Message Data >

Figure 6 - Message Format

Basic ID Message

Message Type: 0x0, Static

The BasicID message includes the ICAO registration (eg: N-Number) as well as a 32bit unique ID. Additionally, other static data about the aircraft (Make/Model, Type, etc). It is sent at a low frequency. This message is **mandatory**.

Data Field	Details	Length (bits)	Limitations	Example
RegID	ICAO Registration ID	64	8 Byte Reg#/N#	N590NM
Make/Model	Make/Model AC (Abbreviated)	72	9 Bytes	Intel F8+
Drone Type	VTOL, fixed wing, hybrid, etc. (See *Figure 11* below for more details.)	8	Max. 255 types	
Drone Sub Type	More information about the drone (e.g. weight, size)	8	Limits depending on the category. Categories can be defined to overcome limits for today's unknown systems	
Gross Weight Mult	Multiplier: 0=1, 1=1kg, 2=10kg, 3=100kg	2	Allows up to 163,840kg	
Drone Gross Weight	Weight in Grams	14	0-16384	

Figure 7 - Basic ID Message

© 2018 Intel Corporation

Location Message

Message Type: 0x1, Dynamic

The Location/Vector message provides the location, altitude, direction and speed of the drone. This message is **mandatory**. Note: When using the "multiplier" fields, the values shall be expressed in the most specific value possible. Therefore, moving to the next available multiplier shall only happen after the maximum integer value has been reached for the base value field. For Example: 2047 MSL shall be expressed as Altitude=2047, Altitude Multiplier = 0 (1). For 2048 MSL, Altitude=205 (round), Altitude Multiplier=1 (10) which gives an interpreted value of 2050.

Data Field	Details	Length (bits)	Limitations	Example
Status	Status: 0=Ground, 1=Airborne (manual control) 2=Returning Home 5=Automated Mission 8=Emergency Landing 9=Control Loss	4	0..15 statuses	
Reserved	Reserved	4		
Latitude	Current latitude of the drone	26	In signed deg*10^6	48123987
Speed North/South	Speed in m/s in NED system	6	Up to 6400 m/s	5 m/s
Longitude	Current longitude of the drone	26	In signed deg*10^6	11389298
Speed East/West	Speed in m/s in NED system	6	Up to 6400 m/s	2 m/s
Operator Latitude	Latitude of pilot or start pt	26	In signed deg*10^6	
Speed Down/Up	Speed in m/s in NED system	6	Up to 6400 m/s	0 m/s
Operator Longtitude	Longtitude of pilot or start pt	26	In signed deg*10^6	
H-Speed Multiplier	Horizontal Speed Multiplier 0=*1, 1=*10, 2=*25, 3=*100	2		
True/Magnetic Heading	0=True heading, 1=Magnetic heading	1		
Altitude Multiplier	Altitude Multiplier: 0=1,1=10	1	Allows up to 20470m (67k ft)	
HeightAGL Multiplier	AGL Multiplier: 0=1, 1=10	1	Allows up to 20470m (67k ft)	
Reserved	For Alignment	1		
Altitude (MSL)	Pressure Altitude	12	+-2047m (6715ft)	
HeightAGL	Height above ground or start pt	12	+-2047m (6715ft)	65
Heading	Heading in 2*Degrees (Mag-N)	8	0-360	

Figure 8 - Location Message

Authentication Message

Message Type: 0x2, Static

An Authentication message can provide an authentication token to prove the authenticity of these messages. For now, this is an optional placeholder to accommodate future authentication schemes and requirements.

Data Field	Details	Length (bits)	Limitations	Example
Authentication Data	Opaque Authentication Data	128	16 Bytes	
Reserved	Reserved for future versions	40	5 Bytes left	

Figure 9 - Authentication Message

© 2018 Intel Corporation

Self ID Message

Message Type: 0x3, Static

The Self-ID message is an opportunity for the Drone Pilot to (**optionally**) declare their identity and purpose of the flight. This can serve the purpose of putting people at ease if concerns exist as to why a drone is flying in a particular area. For Example: A Realtor may want to declare that they are taking photos of a client's house to put the neighbors at ease.
This message is **optional**

Data Field	Details	Length (bits)	Limitations	Example
Operation Description	Text of Operator and Purpose	168	21 Bytes	DronesRus: Survey

Figure 10 - Self ID Message

Enumerated Field Definitions

In the data structures above, some fields are enumerated values. The table below assigns meaning to those enumerations. This can be updated as needed.

Field Name	Details	Length (bits)	Notes
Drone Type	Values: 0: None 1: Fixed Wing Powered 2: Rotorcraft/Multirotor 3: LTA (Lighter than Air) Powered 4: LTA Unpowered (Balloon) 5: VTOL 6: Free Fall/Parachute 7: Rocket 8: Glider 9: Other	8	Up to 255 Types
Drone Sub-Type	Values: (Examples) 0: None 1: IFR Rated 2: Night Compliant 3…: Other types that may fit into a regulatory category that permit certain types of operations.	8	Up to 255 Sub-Types

Figure 11 - Enumerated Field Definitions

7 Compliance and Interoperability

As of this version, compliance can be "self-certified" using the following means:

1. Every "shall", "must" and any other logical directive in this document must be implemented.
2. Interoperability shall be verified against "known working" clients for both BLE 4 and Bluetooth 5 Extended Advertising receivers.
3. Hardware/RF/Signal compliance TBD.
4. If a system is not compliant with this spec, then it may not claim, advertise or display references to "Open Drone ID".

 © 2018 Intel Corporation