

STAT 641: BOOTSTRAPPING METHODS

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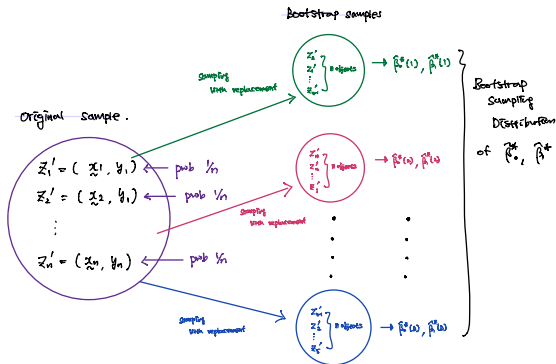
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Review

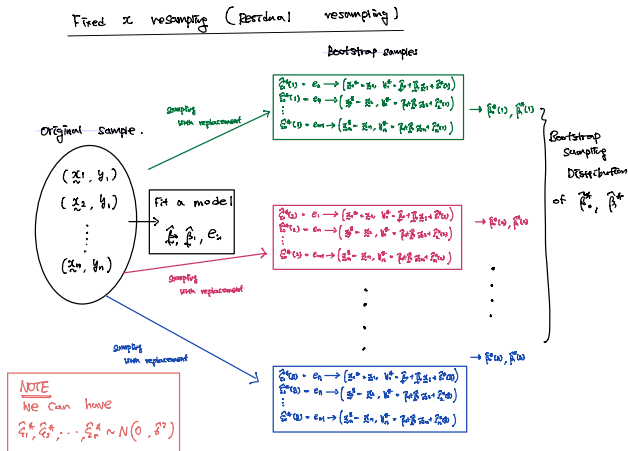
Random x resampling (Observation resampling)

Random x resampling (observation resampling)



Review

Fixed x resampling (Residual resampling)



Comparison

Resampling	Observations	Residuals
Model-dependent		
Fixed design (X)		
Maintains (X, Y) association		

Differences are obvious when the regression model or data is peculiar or if there is a severe outlier.

Example

Florida 2000 US Presidential election results

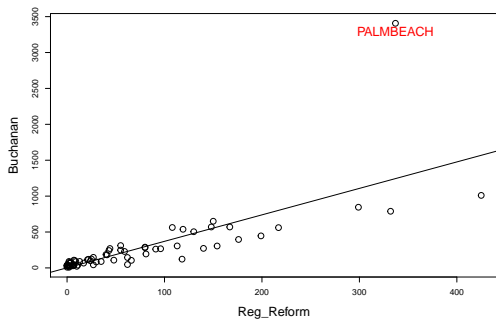
```
# "County by county returns for the 2000 US Presidential election."  
fl <- read.table("florida2000.txt", header = TRUE)  
names(fl)
```

```
## [1] "County"      "Gore"         "Bush"         "Buchanan"     "Nader"  
## [6] "Total_Votes" "Reg_Reform"   "Reg_Rep"      "Reg_Ind"      "Reg_Grn"  
## [11] "Reg_Dem"     "Total_Reg"
```

Data show by county:

- predictor: number of people registered to Reform Party.
- response: number of votes received by Buchanan.

Florida 2000 US Presidential election results



Florida 2000 US Presidential election results

Slope Estimate and estimated standard error

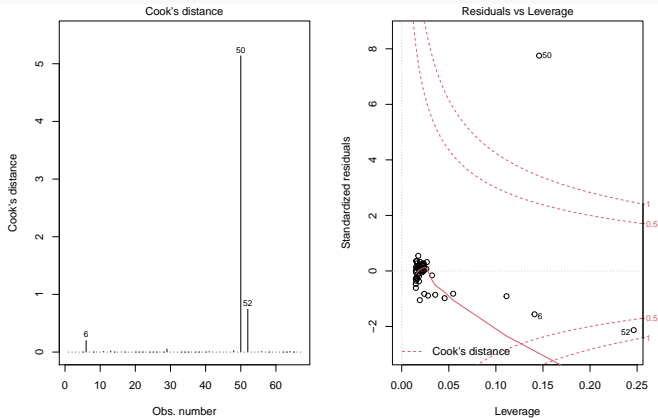
```
x <- fl$Reg_Reform  
y <- fl$Buchanan  
fit <- lm(y ~ x)  
round(coef(summary(fit))[2,], 2)
```

##	Estimate	Std. Error	t value	Pr(> t)
##	3.69	0.41	9.02	0.00

Florida 2000 US Presidential election results

Leverage and influential points

```
par(mfrow= c(1, 2))  
plot(fit, 5:4)
```



Palm Beach is not so leveraged, but is “influential.”

Florida 2000 US Presidential election results

Observation Resampling vs Residual Resampling

Observation Resampling

```
##  
## ORDINARY NONPARAMETRIC BOOTSTRAP  
##  
##  
## Call:  
## boot(data = fl, statistic = boot.fl, R = 5000)  
##  
##  
## Bootstrap Statistics :  
##      original      bias    std. error  
## t1*  1.532519  0.56700841   47.652449  
## t2*  3.686713 -0.02172581    1.158437
```

Residual Resampling

```
##  
## ORDINARY NONPARAMETRIC BOOTSTRAP  
##  
##  
## Call:  
## boot(data = fl, statistic = boot.fl.fixed, R = 5000)  
##  
##  
## Bootstrap Statistics :  
##      original      bias    std. error  
## t1*  1.532519 -0.049059902  45.4159421  
## t2*  3.686713  0.000824195   0.3903628
```

Florida 2000 US Presidential election results

R code for previous page

Observation Resampling

```
library(boot)

boot.fl <- function(data, indices){
  # select obs. in bootstrap sample
  data <- data[indices,]
  mod <- lm(Buchanan ~ Reg_Reform, data = data)
  # return coefficient vector
  coefficients(mod)
}

fl.boot <- boot(fl, boot.fl, 5000)
fl.boot
```

Residual Resampling

```
fits <- fitted(fit)
e <- residuals(fit)
X <- model.matrix(fit)

boot.fl.fixed = function(data, indices) {
  y_b <- fits + e[indices]
  mod <- lm(y_b ~ X - 1)
  coefficients(mod)
}

fl.fixed.boot <- boot(fl, boot.fl.fixed, 5000)
fl.fixed.boot
```

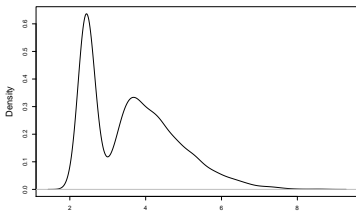
Observation Resampling vs Residual Resampling

Observation Resampling vs Residual Resampling

Observation Resampling

```
plot(density(fl.boot$t[,2]))
```

density.default(x = fl.boot\$t[, 2])

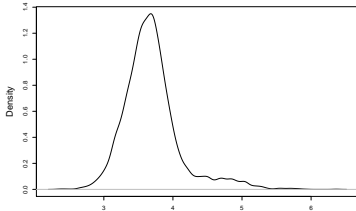


N = 5000 Bandwidth = 0.1902

Residual Resampling

```
plot(density(fl.fixed.boot$t[,2]))
```

density.default(x = fl.fixed.boot\$t[, 2])



N = 5000 Bandwidth = 0.04929

Which bootstrap method is better? The answer depends on how far we trust the linear regression model.

Observation Resampling vs Residual Resampling

- **Observation resampling** is a good choice when we are modeling observational data in which the explanatory variables are observed randomly from a population.
- **Residual resampling** is a good choice if we are analyzing data from a designed experiment in which the explanatory variables have a small number of specified values.
- Residual resampling requires a “true” model in order to obtain the residuals which are resampled. Observation (or random) resampling does not. Residual resampling keeps the same X 's in every bootstrap sample.
- As the sample size grows (with other conditions), two methods become similar, assuming the model is correctly identified.
- Random resampling usually leads to a larger estimate of standard error (with enough bootstrap replications) since it allows for more sources of variation (from randomness in X 's).
- Bootstrap SE of residual resampling will be close to classical SE (OLS formula) as $B \rightarrow \infty$. But, Bootstrap SE of observation resampling does not always agree with classical SE.

Your Turn

Dataset **catsM** contains a set of data on the heart weights and body weights of 97 male cats. We investigate the dependence of **heart weight** (g) on **body weight** (kg). The data set is available in the **boot** package.

- (a) Investigate the data set by first fitting a straight line regression and creating diagnostic plots.
- (b) Next, perform model-based bootstrap regression (residual resampling). Are the bootstrap estimates for intercept and slopes appear normal? Is the model-based standard error for the original fit accurate?
- (c) Do you think the results are effected by any single observation?
- (d) Perform the observation resampling method. And compare the results with (b) and (c).