

Capítulo 3 - Bifurcaciones

[revisado]

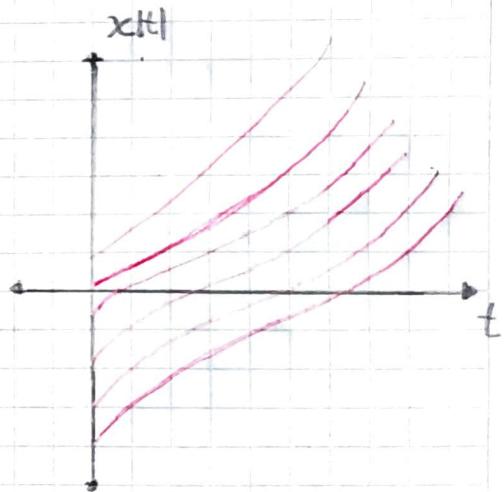
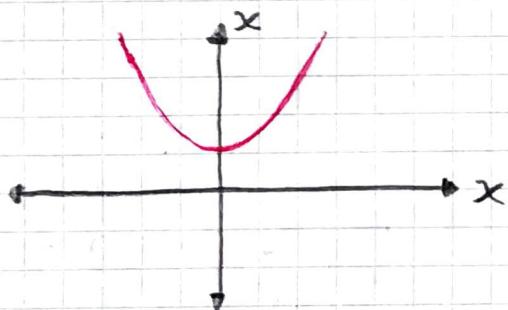
3.1 Saddle-Node Bifurcation

for each of the following exercises, sketch all the qualitatively different vector fields that occur as r is varied. Show that a saddle-node bifurcation occurs at a critical value of r , to be determined. Finally, sketch the bifurcation diagram of fixed points, x^* versus r .

$$\underline{3.1.1} \quad \dot{x} = 1 + rx + x^2$$

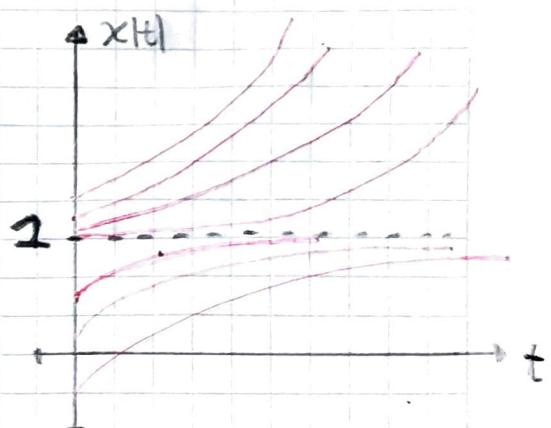
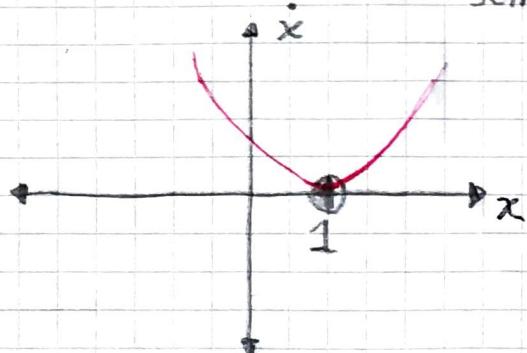
Para $r = 0$:

$$\dot{x} = 1 + x^2 \rightarrow \text{No hay equilibrios}$$



Para $r = -2$

$$\dot{x} = x^2 - 2x + 1 \rightarrow \text{Un punto de equilibrio semiestable}$$

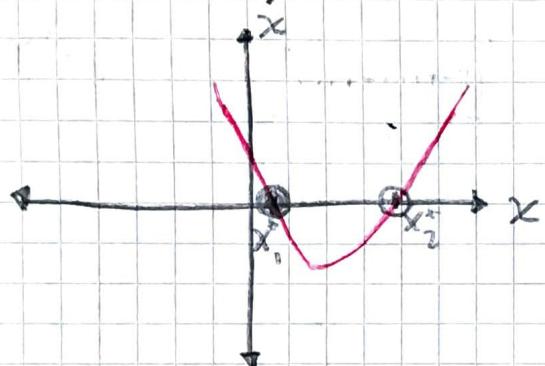


Para $r < -2$

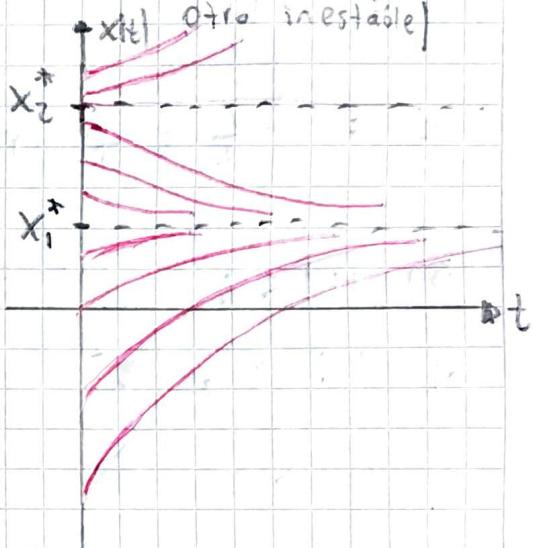
$$\dot{x} = x^2 + rx + 1$$

$$x^2 + rx + 1 = 0$$

$$x^* = \frac{-r}{2} \pm \frac{1}{2}\sqrt{r^2 - 4}$$



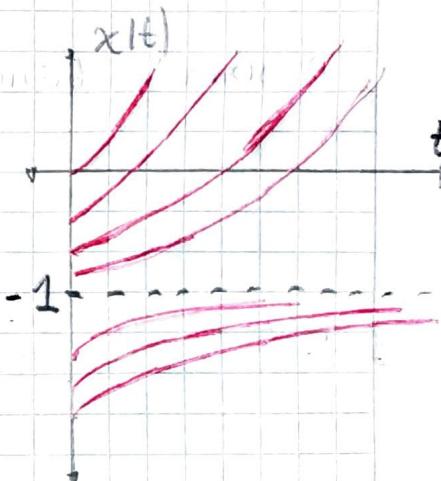
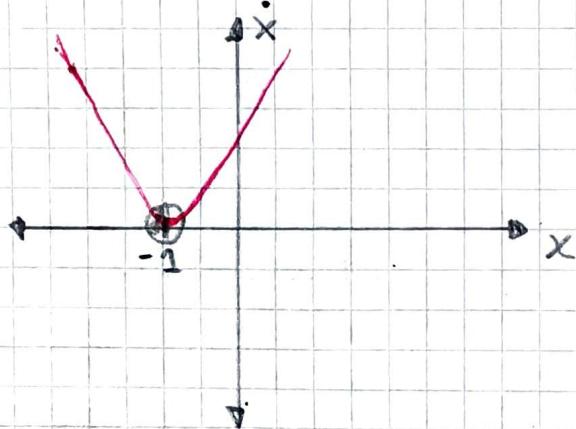
→ Puntos de equilibrio (uno estable y otro inestable)



Para $r = 2$

$$x^* = -1$$

→ semi estable



En examen:

Para $|r| = \pm 2 \rightarrow$ Un punto de equilibrio semiestable

Para $|r| > 2 \rightarrow$ Dos puntos de equilibrio (uno estable y otro inestable)

Para $|r| < 2 \rightarrow$ No hay puntos de equilibrio

$$\dot{x} = x^2 + rx + 1$$

$$x^* = -\frac{r}{2} \pm \frac{1}{2}\sqrt{r^2 - 4}$$

Si $|r| < 2$, x^* es complejo

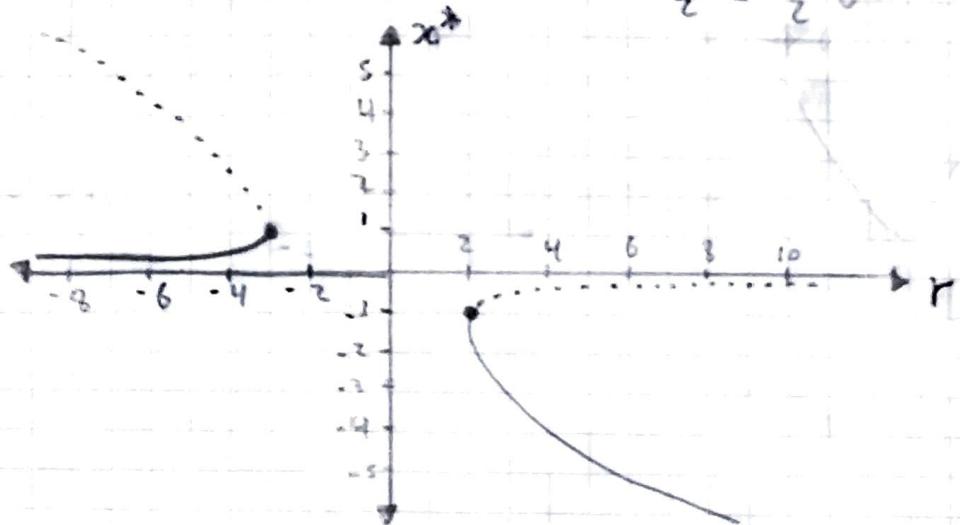
Si $|r| = 2$, x^* es una solución real única

Si $|r| > 2$, x^* es real (doble)

Hay una bifurcación en $r = \pm 2$

Diagrama de bifurcación:

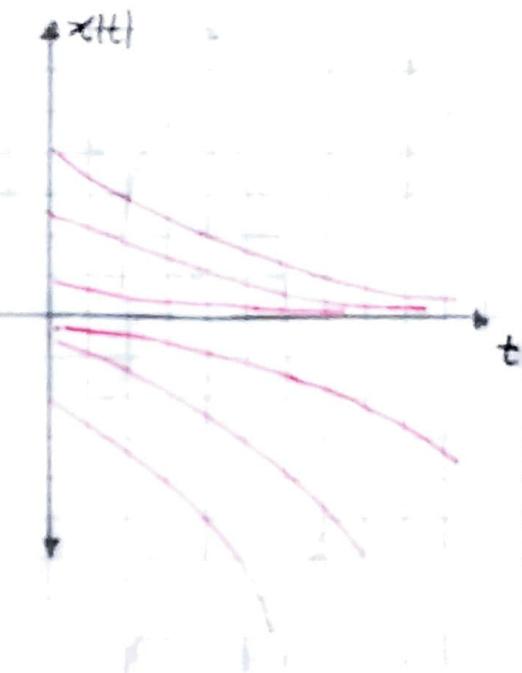
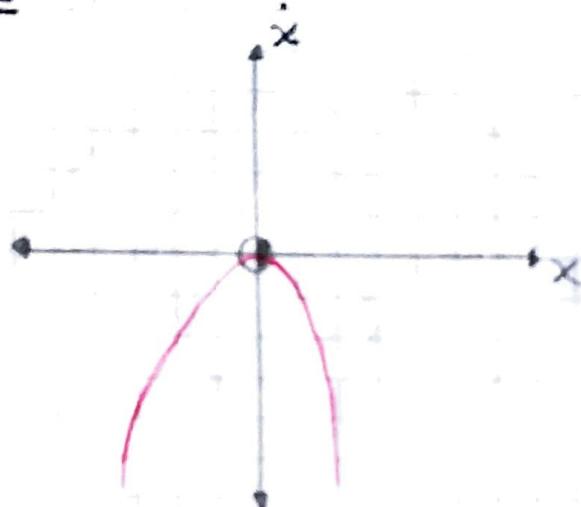
$$x^* = -\frac{r}{2} \pm \frac{1}{2}\sqrt{r^2 - 4}$$



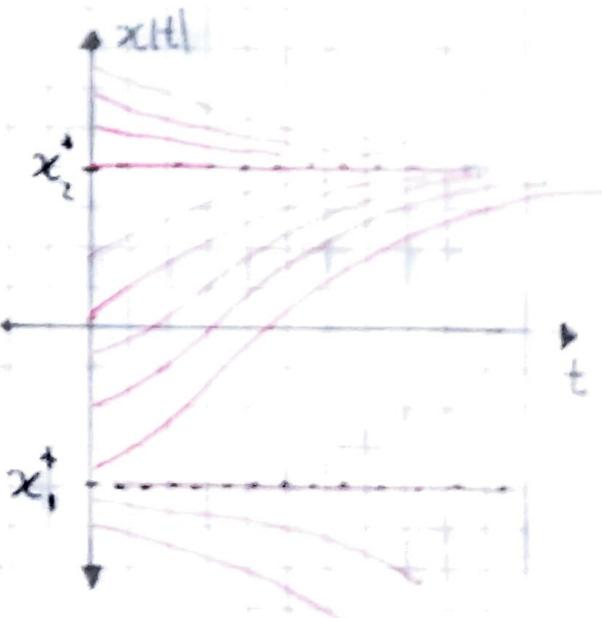
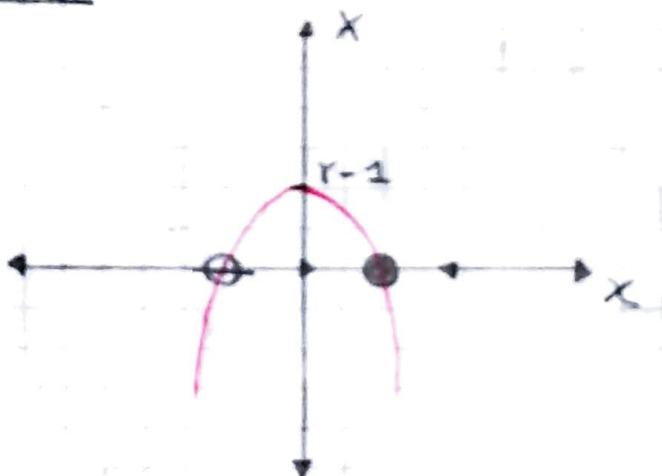
3.1.2

$$\dot{x} = r - \cosh x$$

$$r = 1$$



$$r > 1$$

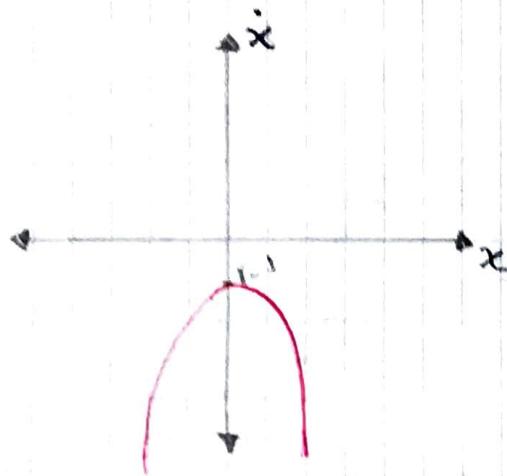


$$\dot{x} = 0$$

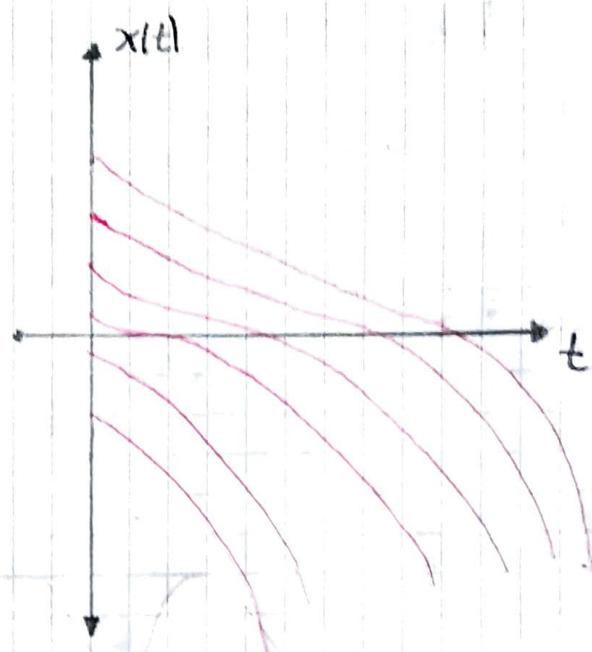
$$r - \cosh(x) = 0$$

$$\cosh(x^*) = r$$

$r < 1$



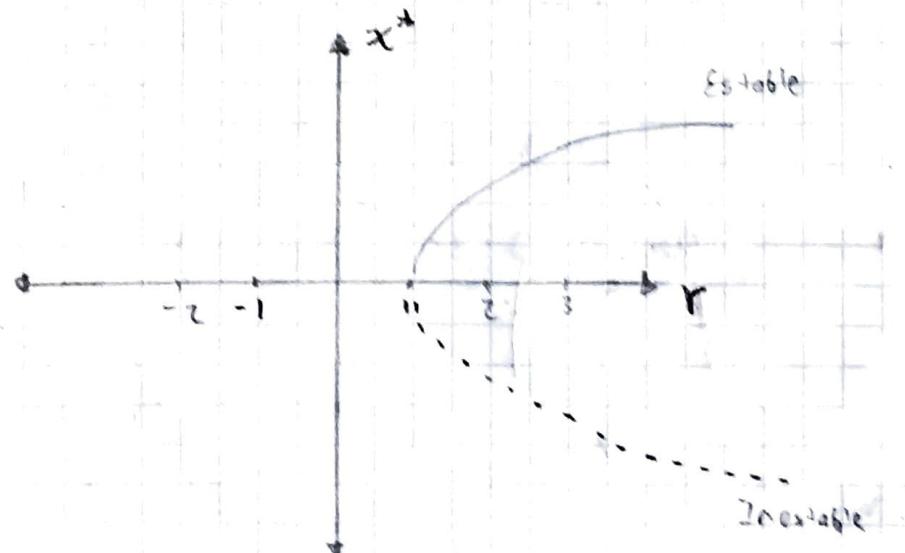
NO hay puntos de equilibrio



En $r = 1$ ocurre una bifurcación Silla-nodo

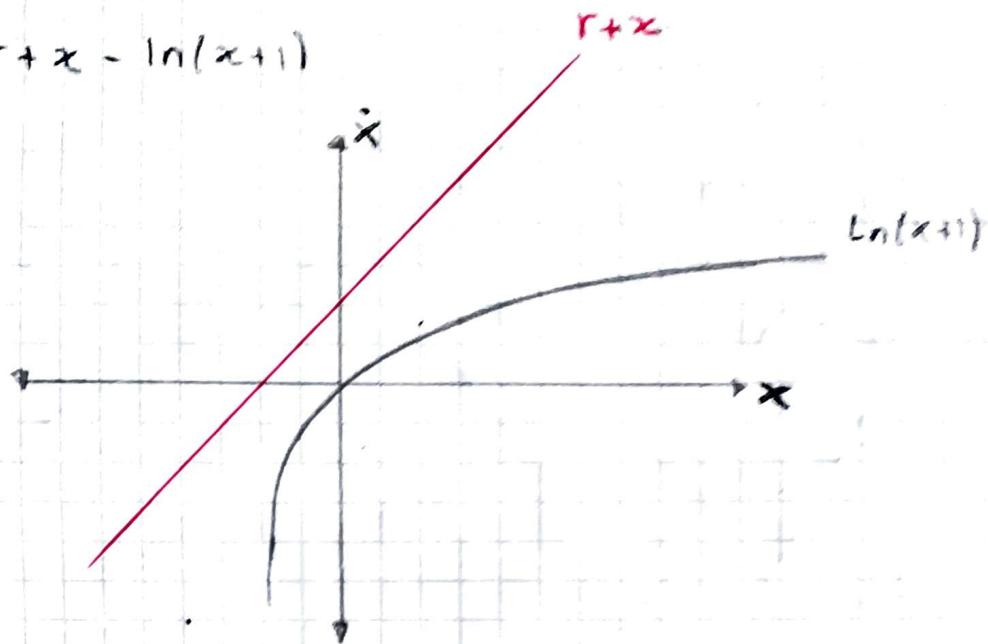
$$r - \cosh x = 0$$

$$r = \cosh x$$



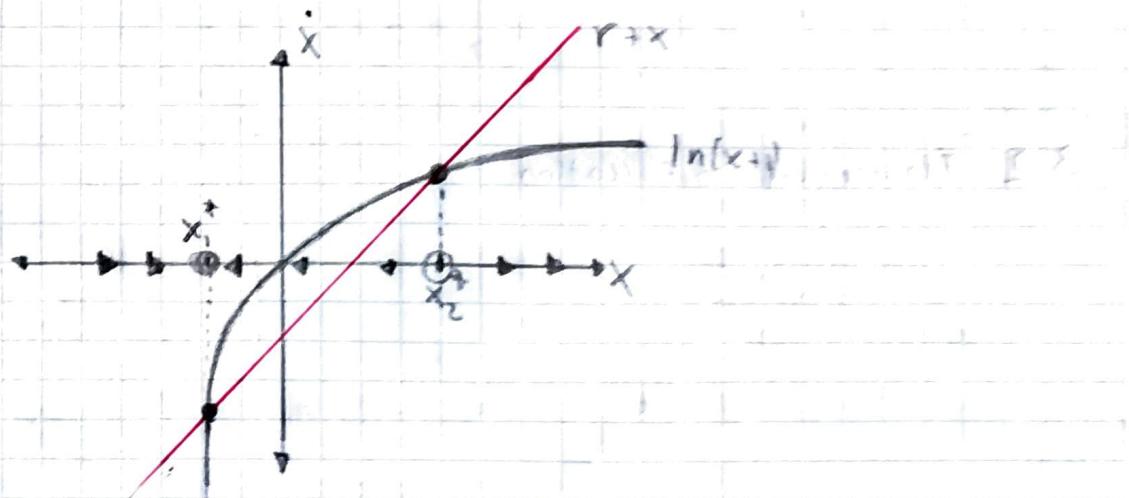
3.1.3

$$\dot{x} = r + x - \ln(x+1)$$



Puede verse que para $r > 0$, no hay ningún punto de equilibrio. Cuando $r=0$, hay un único punto de equilibrio en $x=0$.

Cuando $r < 0$, existen dos puntos de equilibrio:



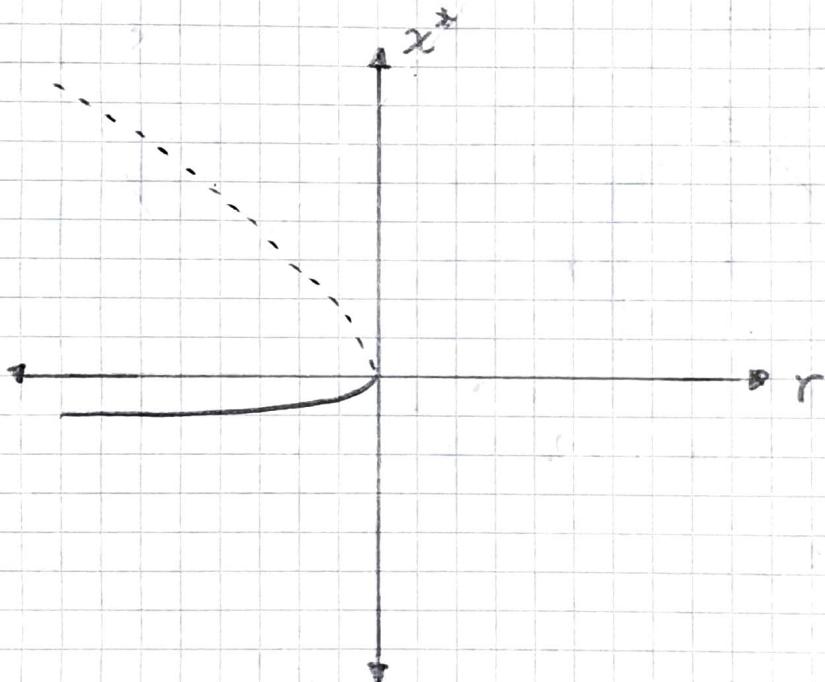
El punto de equilibrio menor a cero (x_1^*) es estable, mientras que el otro es inestable.

Claramente hay una bifurcación Silla-Nodo para $r = 0$

$$\dot{x} = r + x - \ln(x+1)$$

$$r + x - \ln(x+1) = 0$$

$$r = \ln(x+1) - x$$



3.2 Transcritical Bifurcation

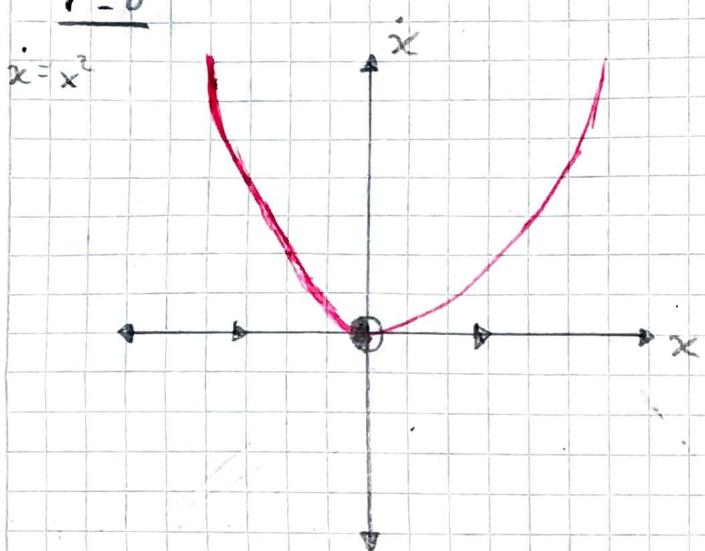
For each of the following exercises, sketch all the qualitatively different vector fields that occur at a critical value of r to be determined. Finally, sketch the bifurcation diagram of fixed points x^* vs r .

3.2.1

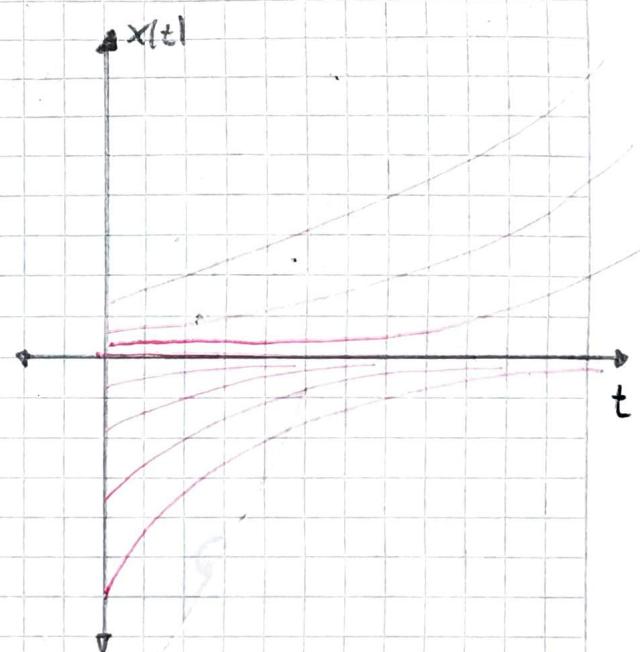
$$\dot{x} = rx + x^2$$

$r = 0$

$$\dot{x} = x^2$$



$$x(t)$$

 $r > 0$

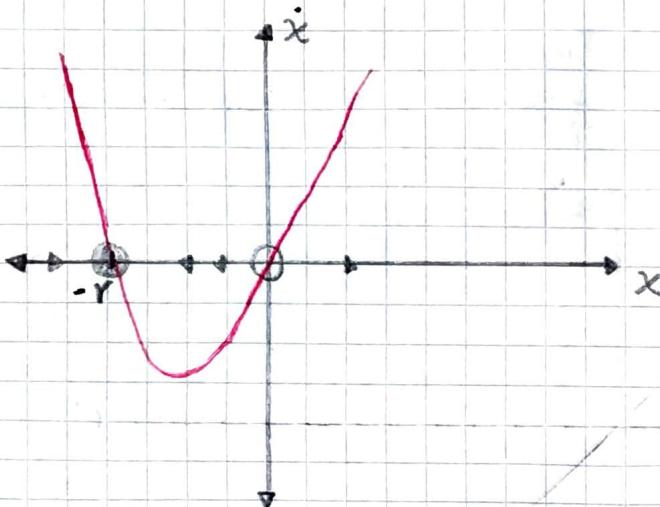
$$\dot{x} = rx + x^2$$

$$rx + x^2 = 0$$

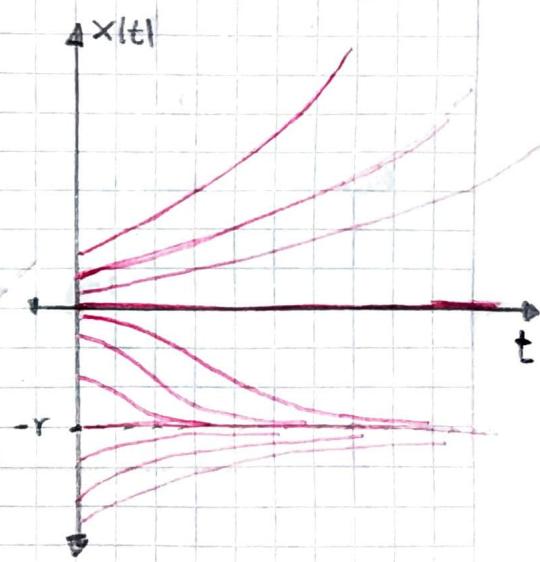
$$x(r+x) = 0$$

$$x_1^* = 0$$

$$x_2^* = -r, \quad r > 0$$



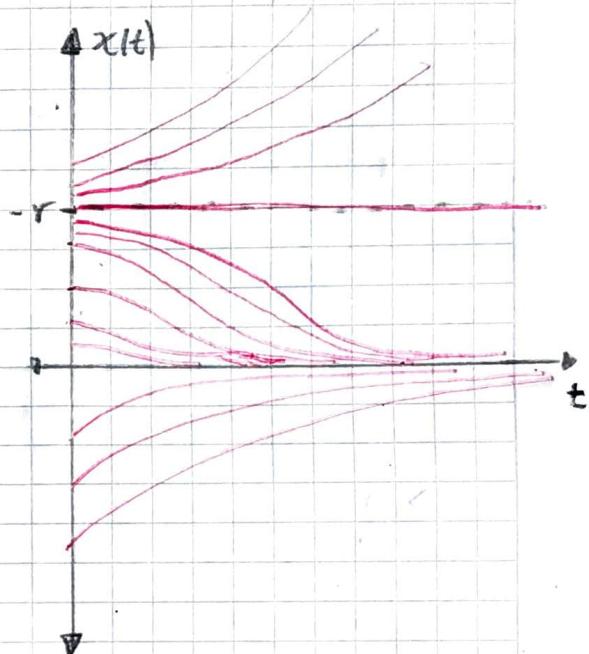
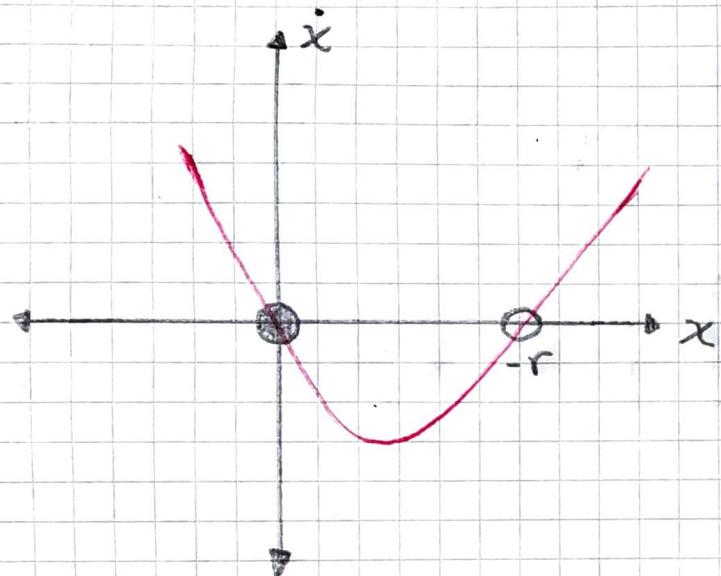
$$x(t)$$



$$r < 0$$

$$x^* = 0$$

$$x^* = -r, r < 0$$

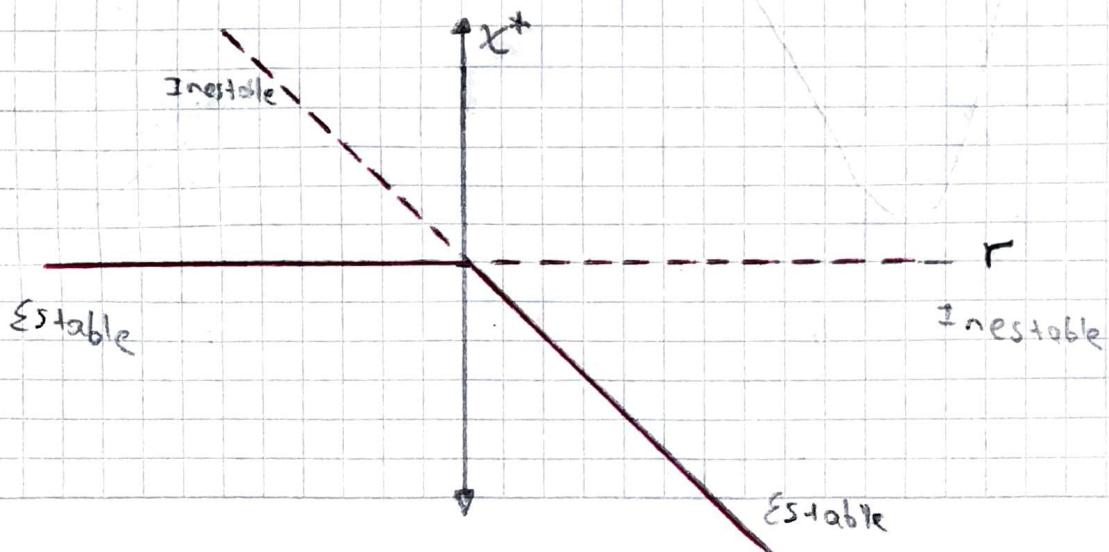


$x^* = 0$ es un punto de equilibrio para todos los valores de r . Sin embargo, su estabilidad cambia:

$r < 0 \rightarrow x^* = 0$ es estable

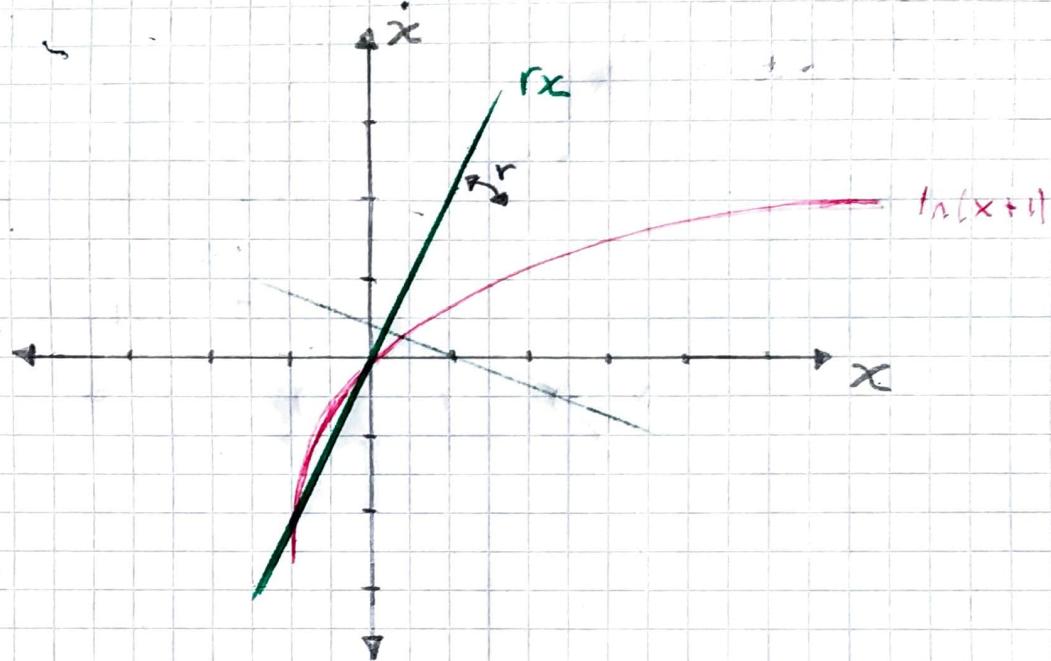
$r = 0 \rightarrow x^* = 0$ es semi estable

$r > 0 \rightarrow x^* = 0$ es inestable



3.2.2

$$\dot{x} = rx - \ln(x+1)$$



Es evidente que para cualquier r hay un punto de equilibrio $\boxed{x^* = 0}$.

Dependiendo del valor de r existe otro punto de equilibrio.

Existe un valor de r que hace que solo exista el punto de equilibrio $x^* = 0$, este se da cuando la recta rx es tangente a la curva $\ln(x+1)$:

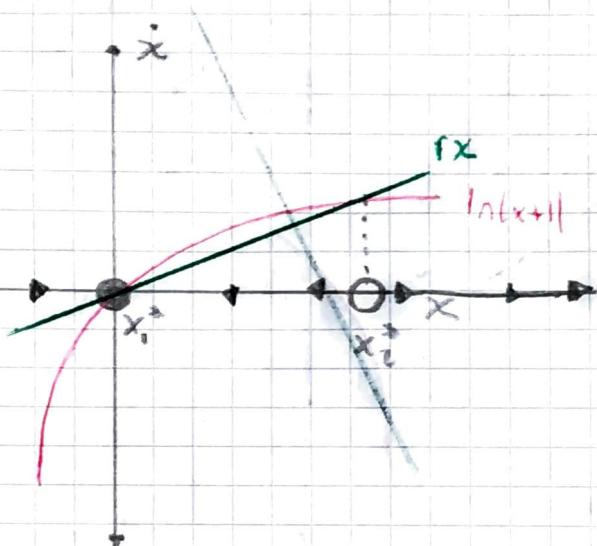
$$r_{cr} = \frac{d(\ln(x+1))}{dx} \Big|_{x=0}$$

$$r_{cr} = \frac{1}{x+1} \Big|_{x=0} = 1$$

$$\boxed{r_{cr} = 1}$$

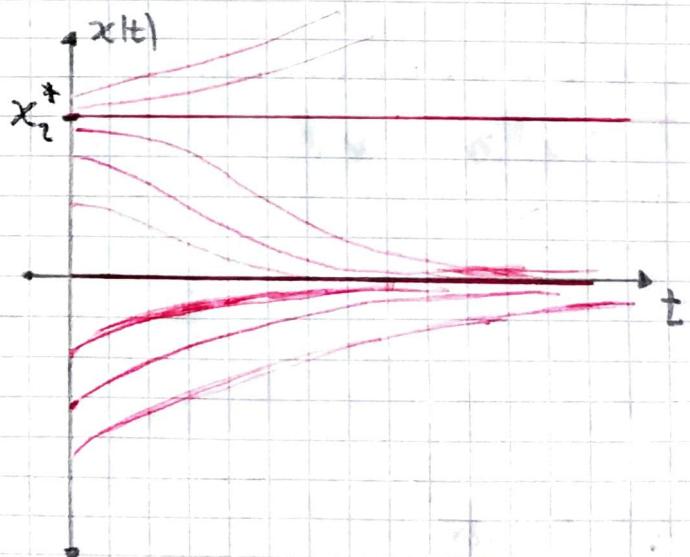
Existe sólo $r < 1$ a partir del cual el único punto de equilibrio es $\boxed{x^* = 0}$. Este sirve para determinar (r_{cr})

Para $r_{cr} < r < 1$

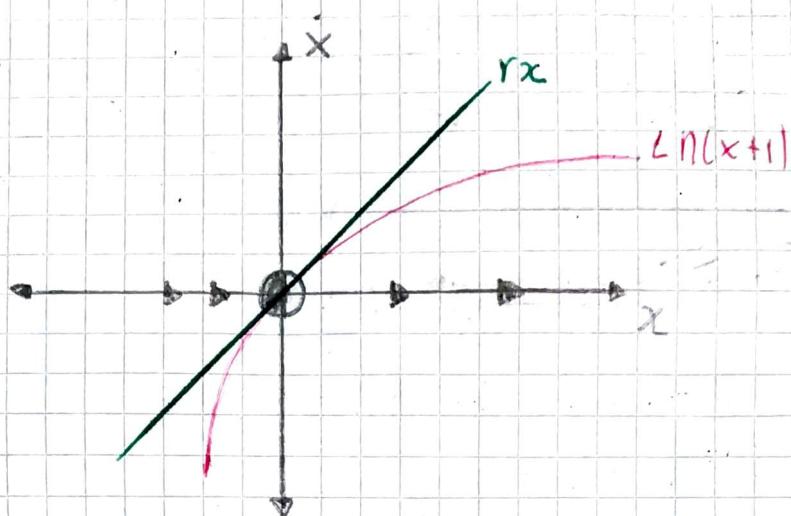


$$x_1^* = 0$$

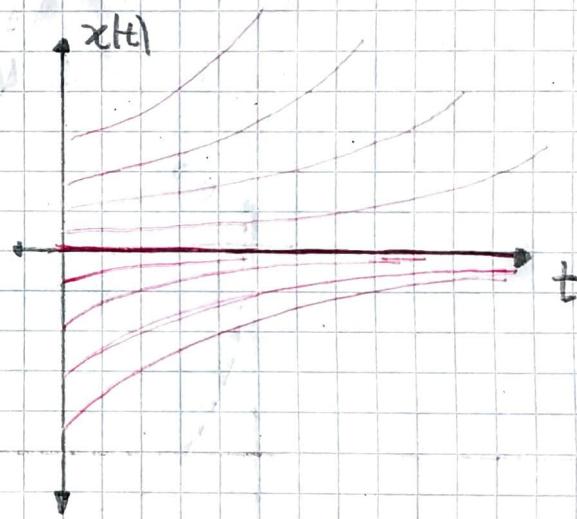
$$rx^* = \ln(x^* + 1)$$



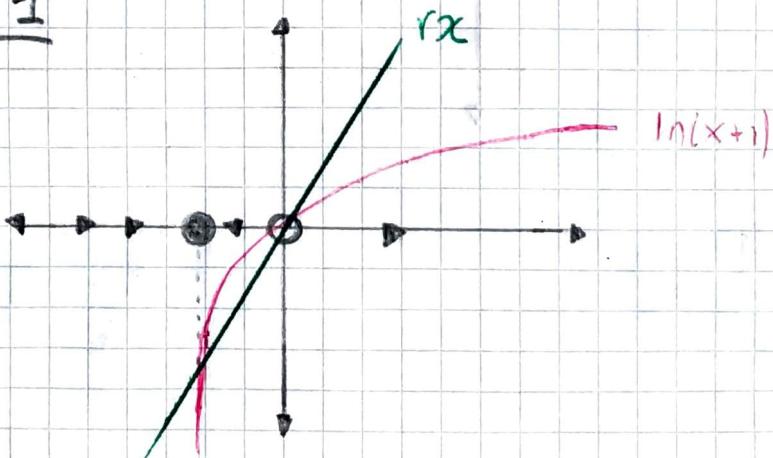
Para $r = 1$



$x^* = 0 \rightarrow$ Semi estable

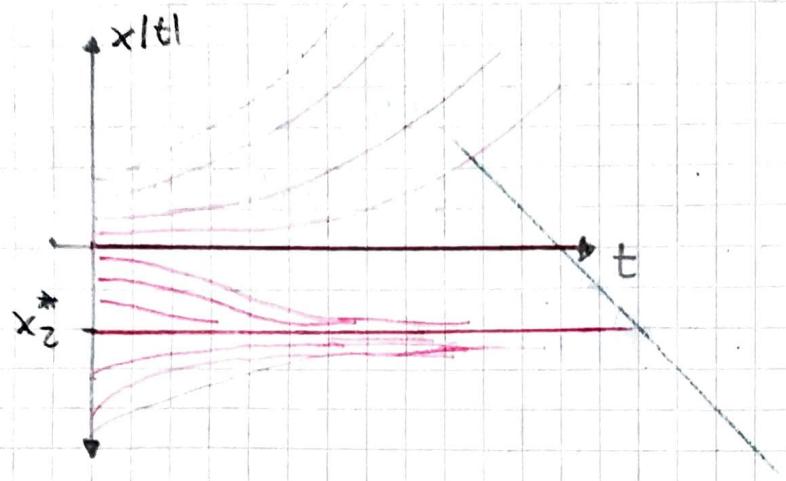


Para $r > 1$



$x_1^* = 0 \rightarrow$ Inestable

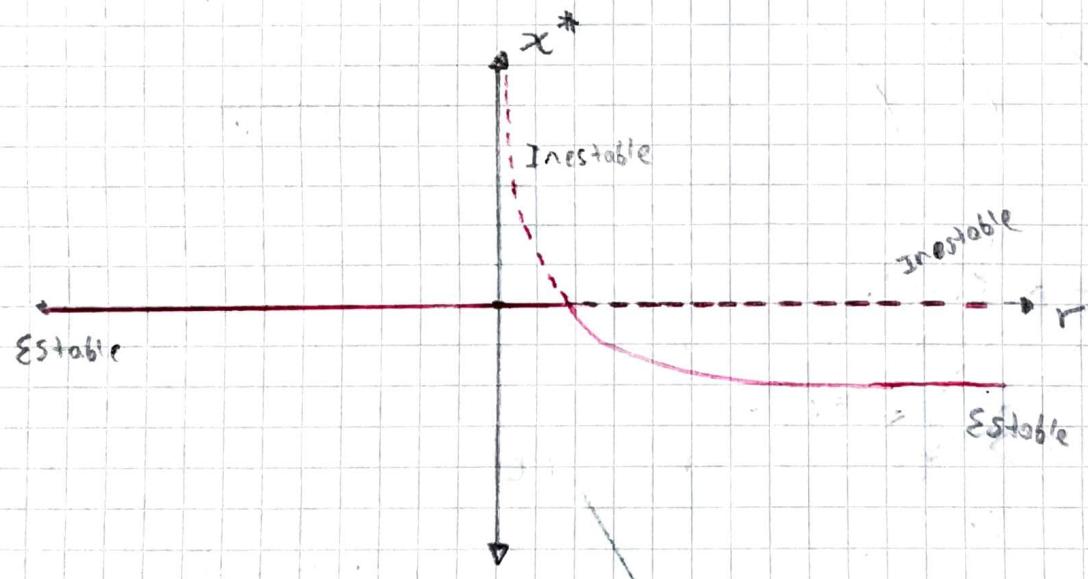
$x_2^* \rightarrow$ Estable



$x^* = 0$ es: inestable para $r > 1$

Semiestable para $r = 1$

estable para $r < 1$

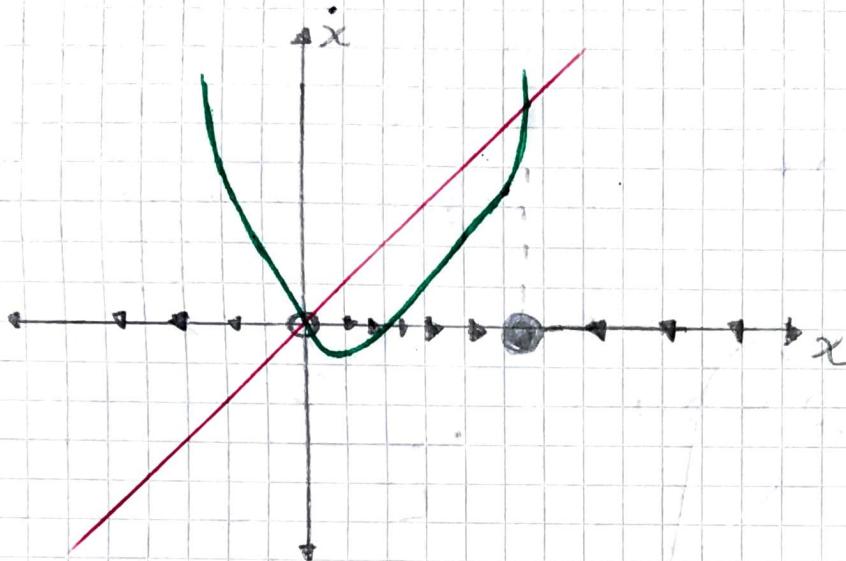


$$rx = \ln(x+1)$$

$$r = \frac{\ln(x+1)}{x}$$

3.2.3

$$\dot{x} = x - rx(1-x)$$



$x^* = 0$ siempre es un punto de equilibrio. Para evaluar el r

$$\dot{x} = x - rx(1-x)$$

$$\dot{x} = x[1 - r(1-x)]$$

$$x[1 - r(1-x)] = 0$$

$$\boxed{x^* = 0}$$

$$1 - r(1-x) = 0$$

$$r(1-x) = 1$$

$$1-x = \frac{1}{r}$$

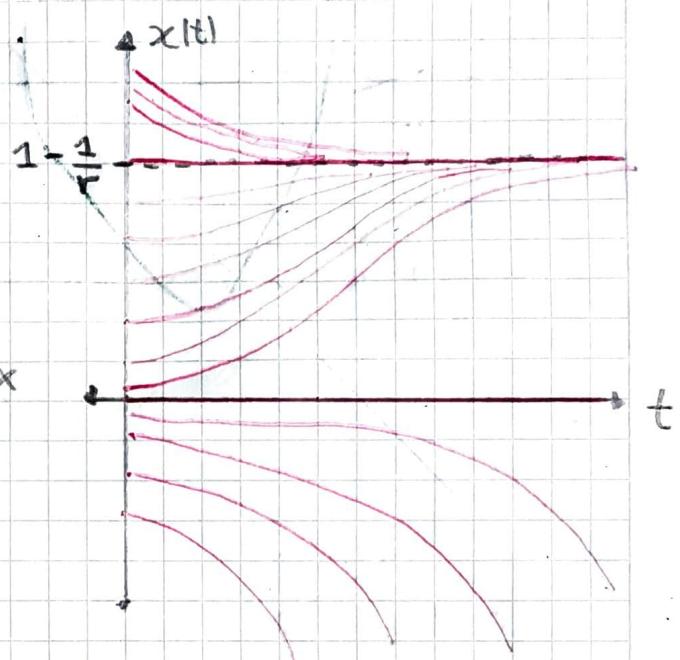
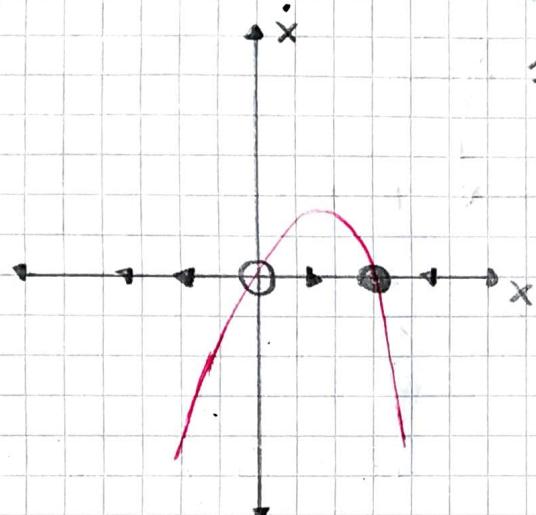
$$\boxed{x^* = 1 - \frac{1}{r}}$$

→ Cuando $r=1$ este punto de equilibrio se encuentra con el otro

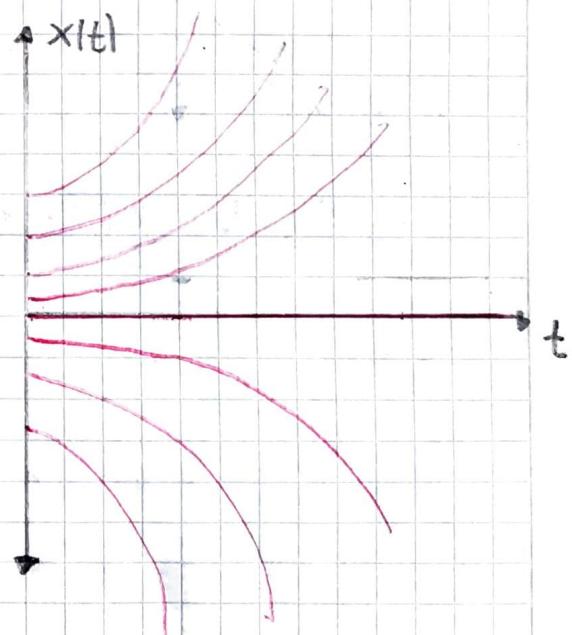
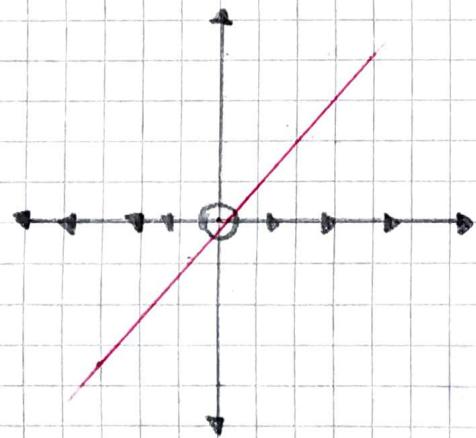
Para $r=1$ solo hay un punto de equilibrio semi estable

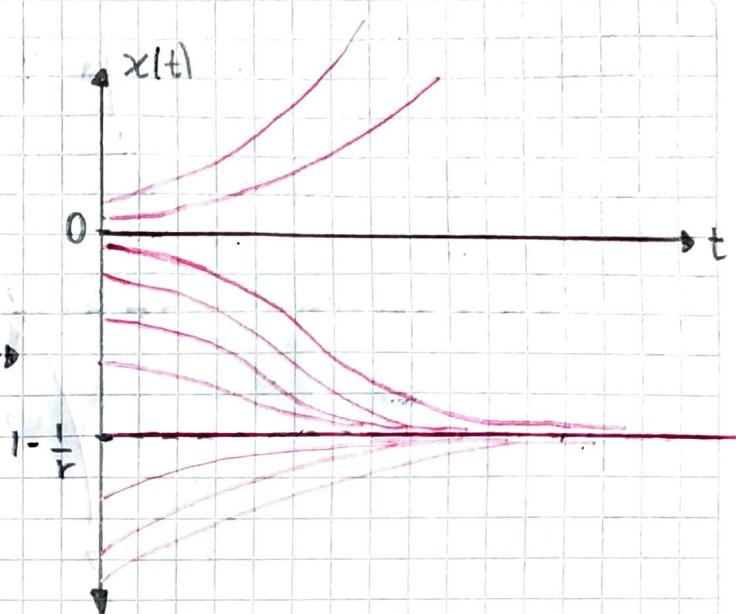
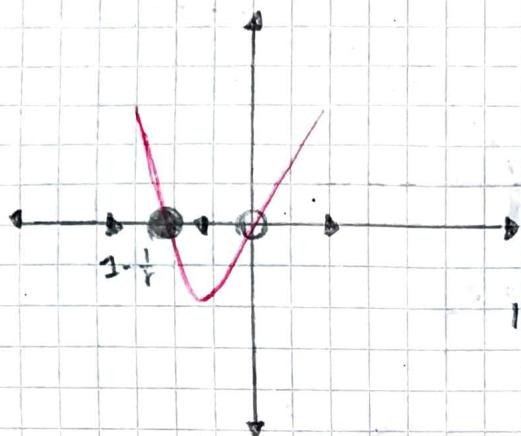
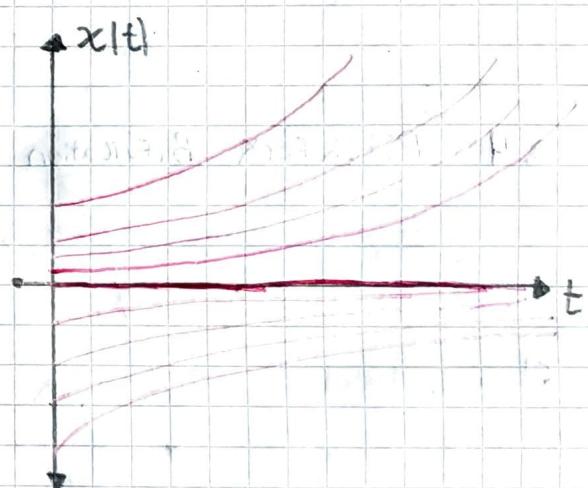
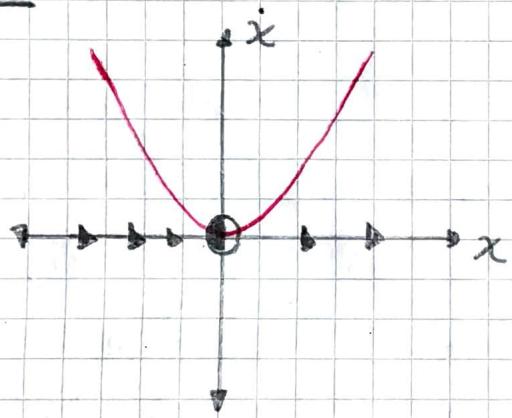
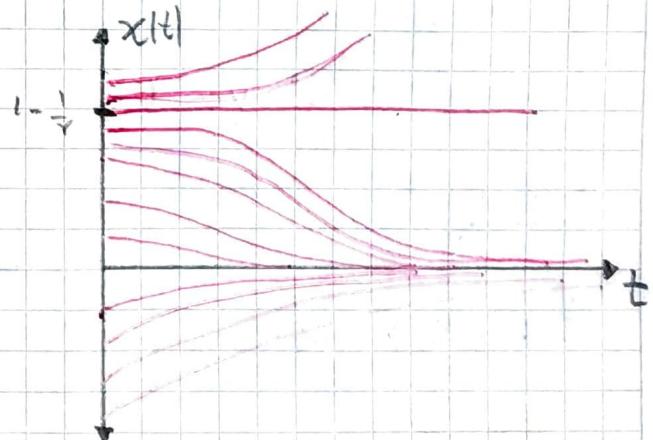
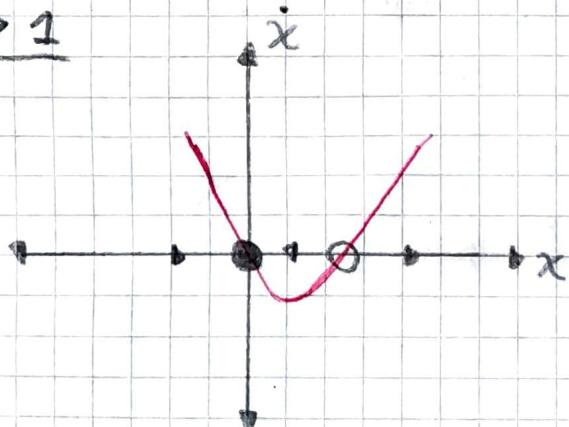
Para $r=0$ hay un punto de equilibrio inestable

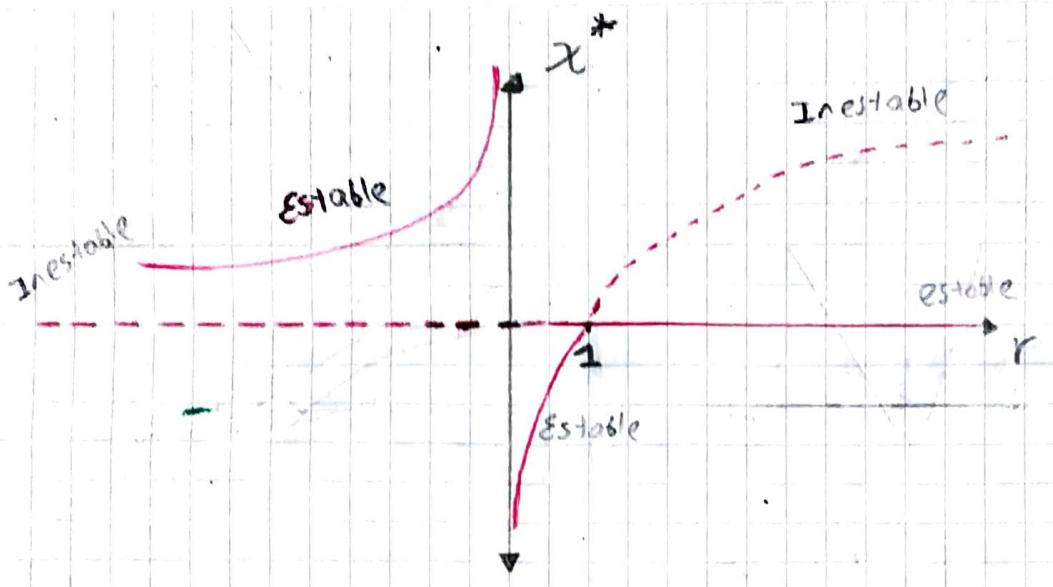
$r < 0$



$r = 0$



$0 < r < 1$  $r = 1$  $r > 1$ 



$$x^* = 1 - \frac{1}{r}$$

3.4 Pitchfork Bifurcation

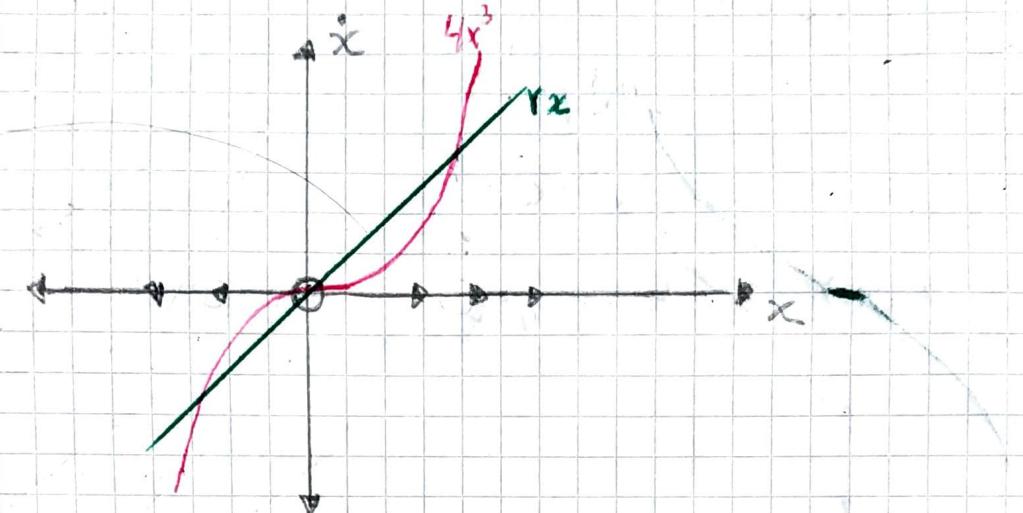
In the following exercises, sketch all the Qualitatively different vector fields that occur as r is varied.

Show that a pitchfork bifurcation occurs at a critical value of r (to be determined) and classify the bifurcation as supercritical or subcritical. Finally, sketch the bifurcation diagram of x^* vs r^* .

3.4.1

$$\dot{x} = rx + 4x^3$$

$$\dot{x} = rx + 4x^3$$



$$x^* = 0$$

$$rx + 4x^3 = 0$$

$$x(r + 4x^2) = 0$$

$$x_1^* = 0$$

$$r + 4x^2 = 0$$

$$4x^2 = -r$$

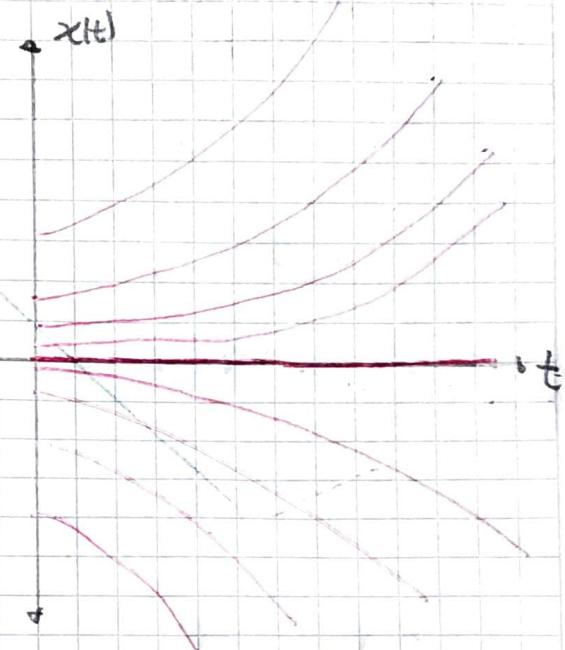
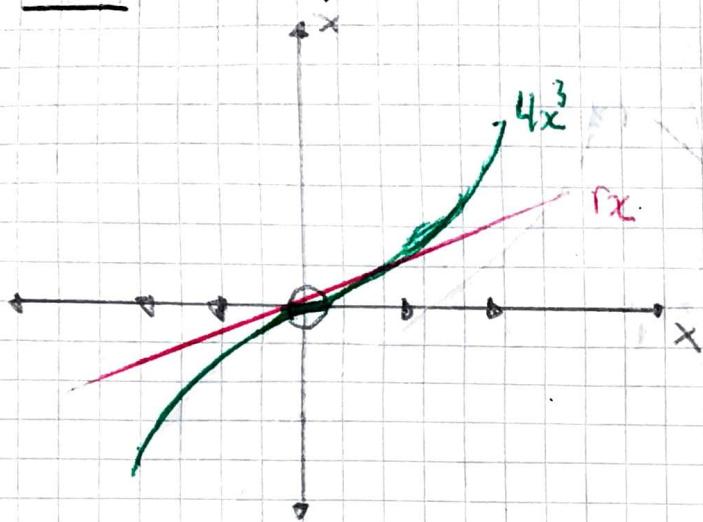
$$x^2 = -\frac{r}{4} \rightarrow \text{Para } r > 0 \text{ no existen más puntos de equilibrio}$$

Si $r < 0$:

$$x^2 = -\frac{r}{4}$$

$$x = \frac{\sqrt{-r}}{2} \quad [r < 0]$$

$r \geq 0$



$r < 0$

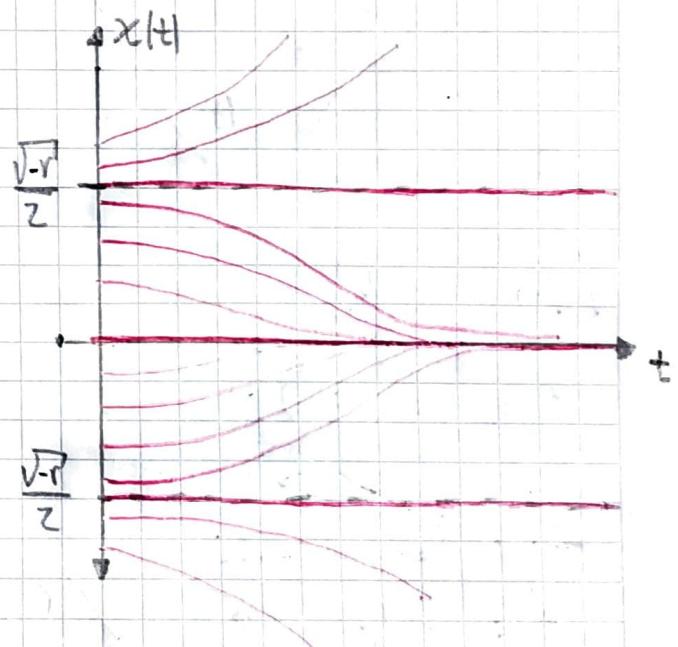
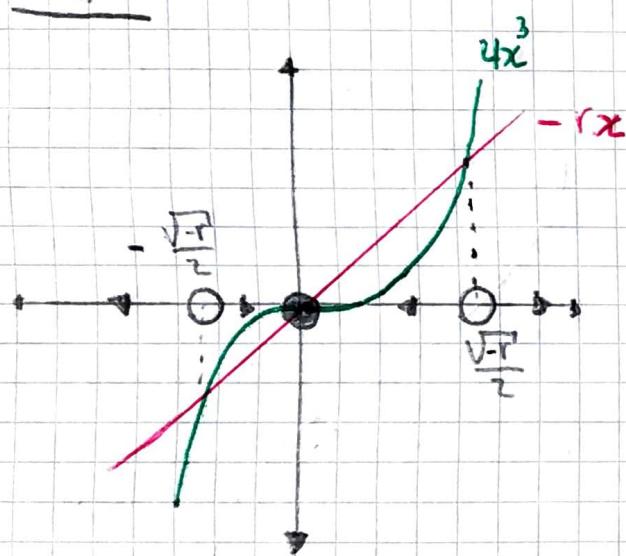
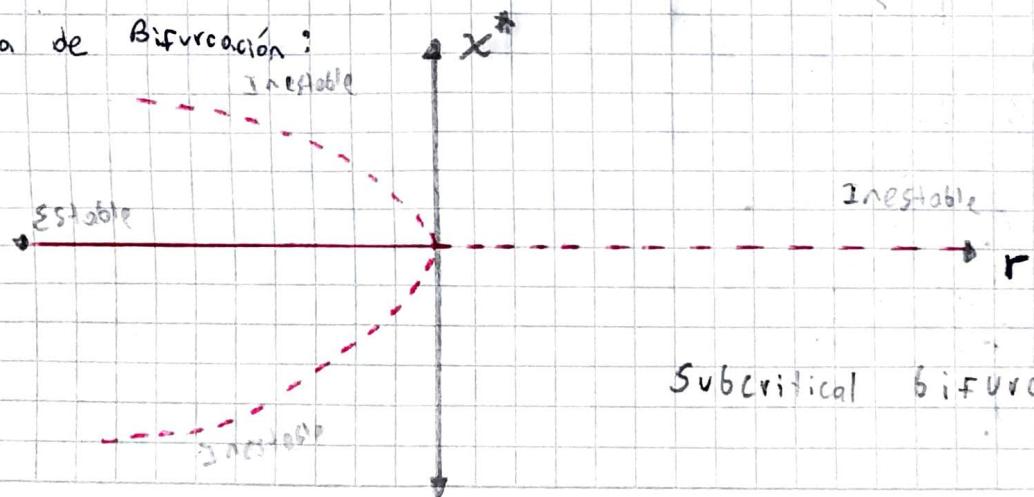


Diagrama de Bifurcación:



Subcritical bifurcation

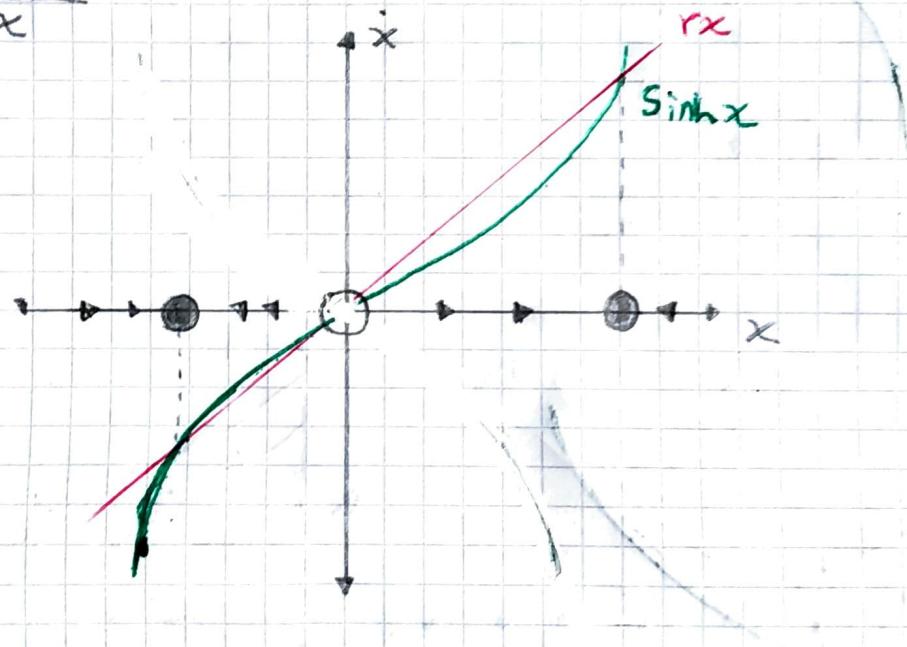
3.4.2

$$\dot{x} = rx - \sinh x$$

$$rx - \sinh x = 0$$

$$rx = \sinh x$$

$$r = \frac{\sinh x}{x}$$



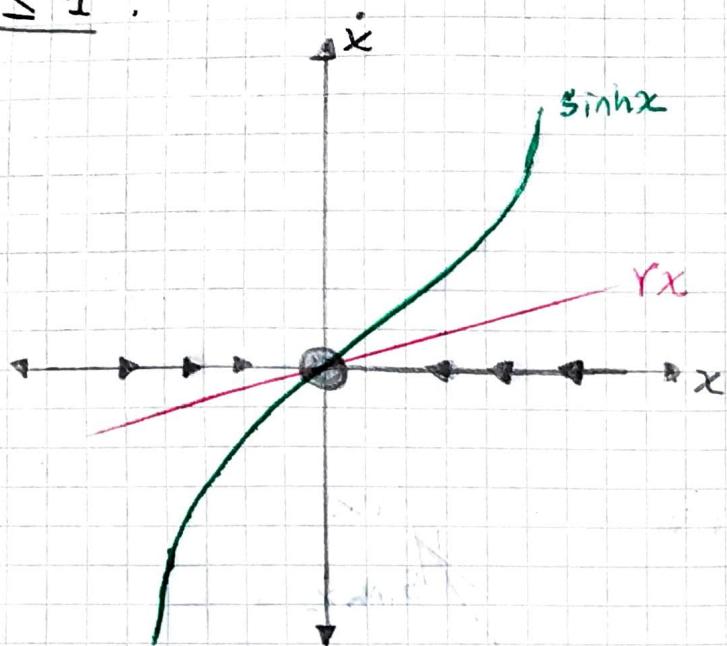
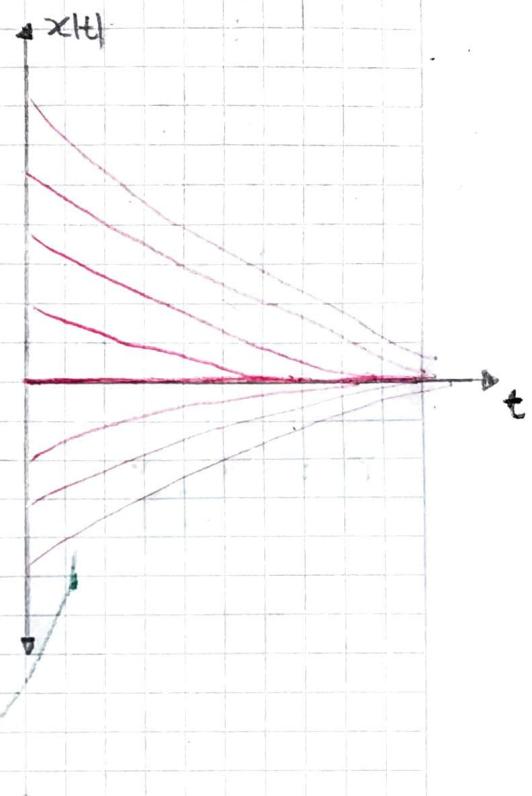
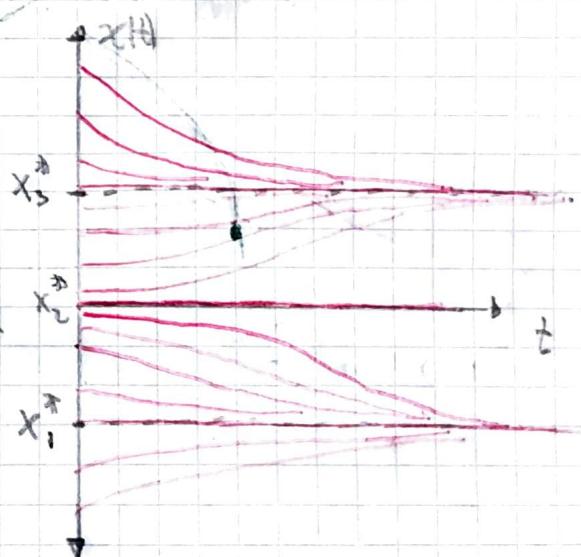
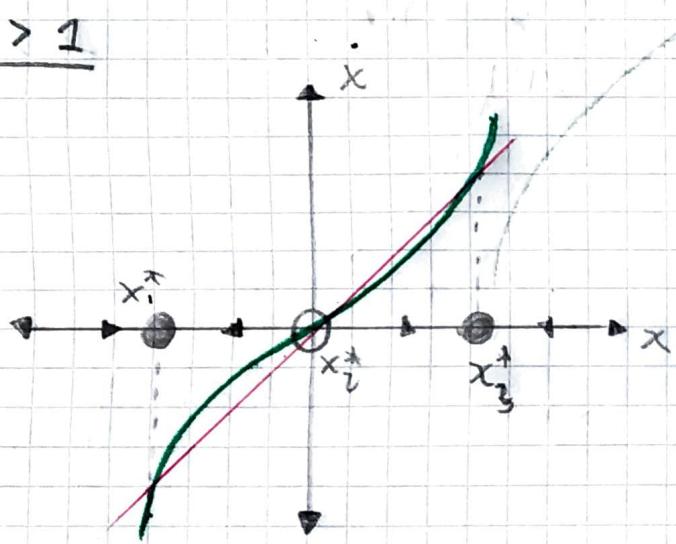
$x^* = 0 \rightarrow$ Punto de equilibrio para cualquier r . Su estabilidad varía.

Cuando rx es tangente a $\sinh x$ en el origen, es el punto crítico en el cual aparecen los nuevos puntos de equilibrio.

$$r = \left. \frac{d \sinh x}{dx} \right|_{x=0}$$

$$r = \left. \cosh x \right|_{x=0}$$

$$r = 1$$

$r \leq 1$: $x(t)$  $r > 1$:

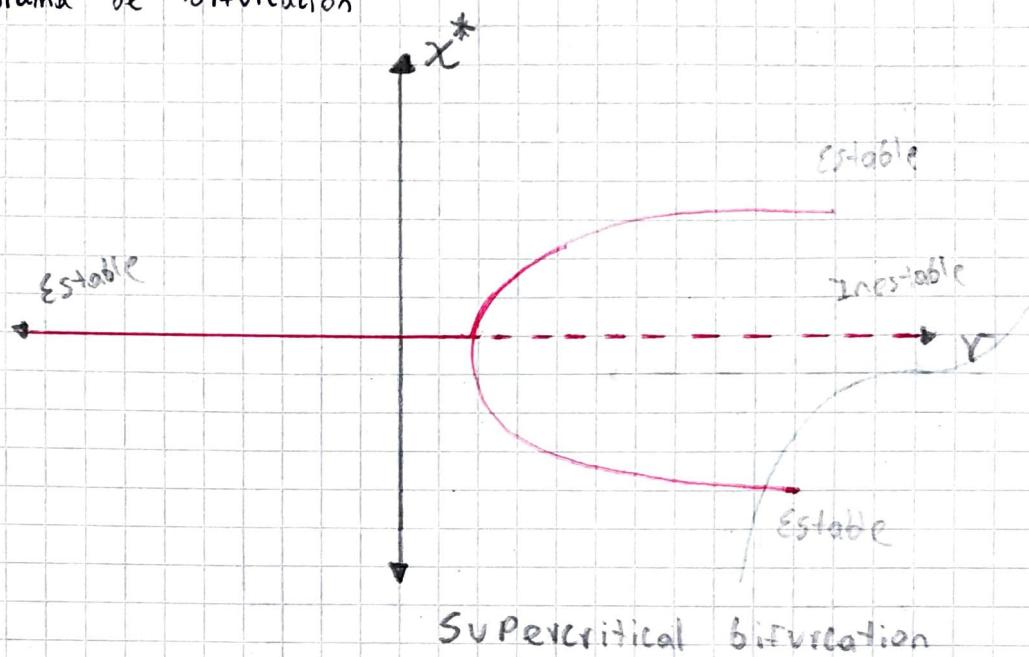
$$rx - \sinh x = 0$$

$$rx = \sinh x$$

$$r = \frac{\sinh x^*}{x^*} \rightarrow \text{Puntos de equilibrio}$$

(forma implícita)

Diagrama de Bifurcación



3.4.3

$$\dot{x} = rx - 4x^3$$

$$\dot{x} = x(r - 4x^2)$$

Puntos de equilibrio

$$x(r - 4x^2) = 0$$

$$x^* = 0 \rightarrow \text{Para cualquier } r$$

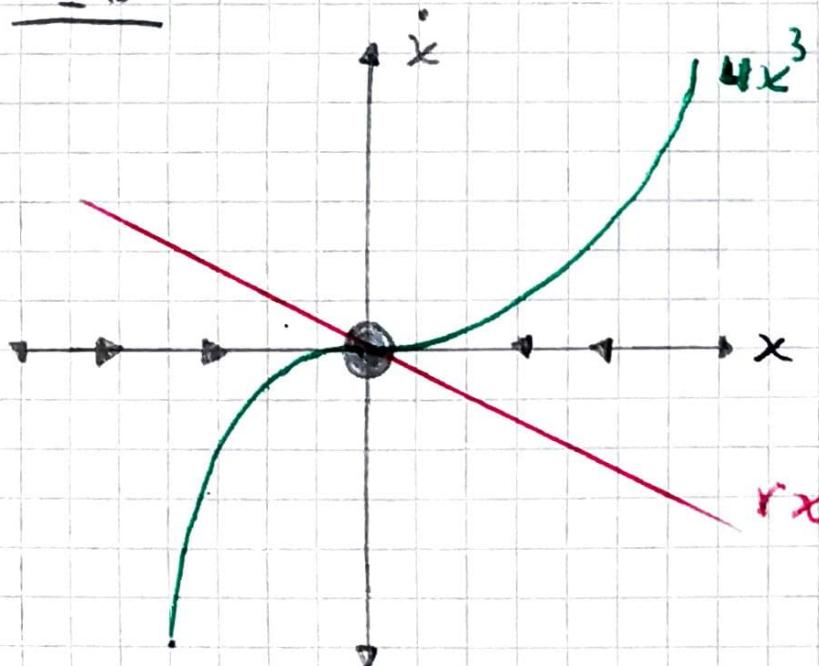
$$r - x^2 = 0$$

$$4x^2 = r$$

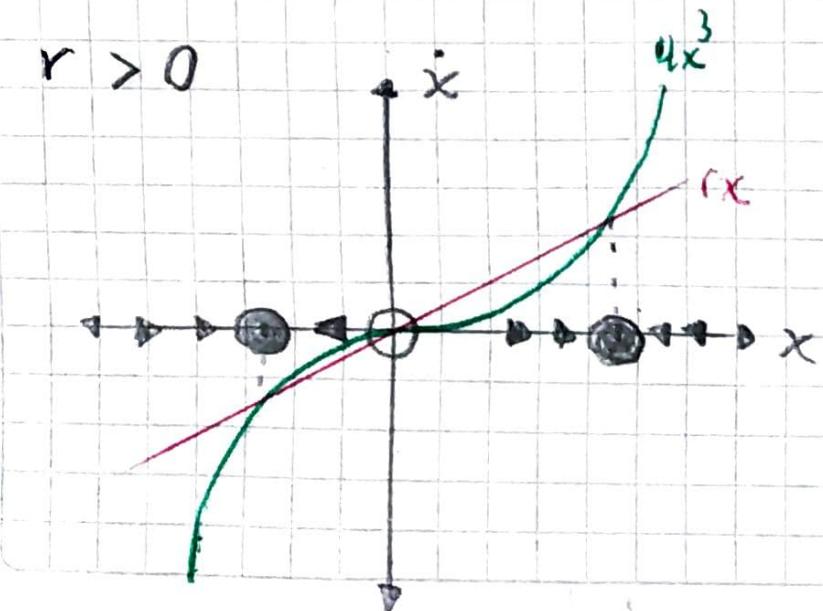
$$x^2 = \frac{r}{4}$$

$$x^* = \frac{\sqrt{r}}{2} \rightarrow \text{Solo existe para } r > 0$$

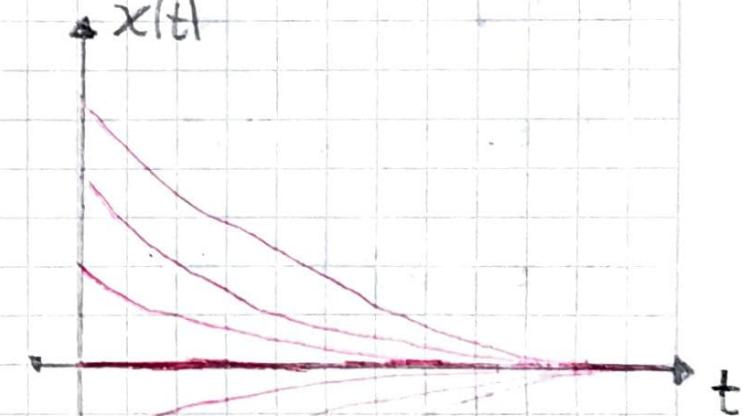
$r \leq 0$



$r > 0$



$x(t)$



$x(t)$

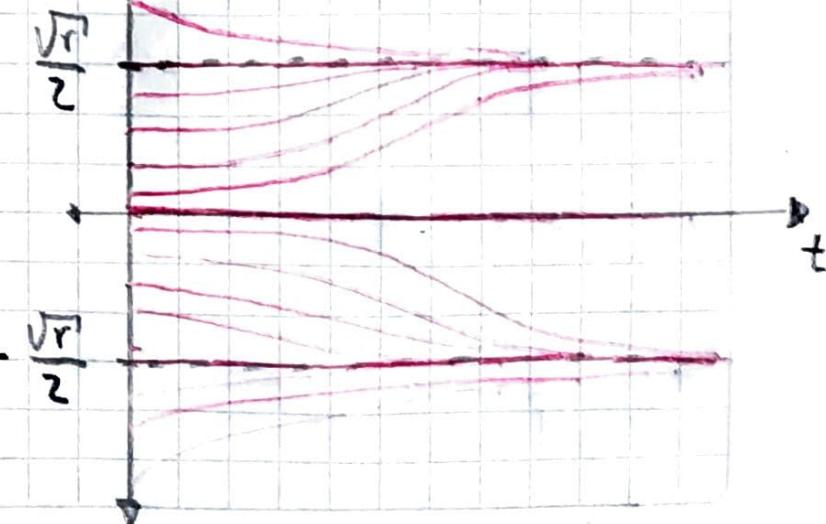


Diagrama de Bifurcación

