



Hochschule
Bonn-Rhein-Sieg
University of Applied Sciences



Master's Thesis

Multi-View Temporal Fusion in Semantic Segmentation

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Department of Computer Science
in partial fulfillment of the requirements for the degree
of Master of Science in Autonomous Systems

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Month 20XX

I, the undersigned below, declare that this work has not previously been submitted to this or any other university and that it is, unless otherwise stated, entirely my own work.

Date

Manoj Kolpe Lingappa

Abstract

Your abstract

Acknowledgements

Thanks to

Contents

List of Figures	xv
List of Tables	xvii
1 Introduction	1
1.1 Motivation	1
1.1.1 Temporal fusion	1
1.1.2 Semantic segmentation	1
1.2 Challenges and Difficulties	1
1.2.1	1
1.2.2	2
1.2.3	2
1.3 Problem Statement	2
1.3.1	2
1.3.2	4
1.3.3	4
2 State of the Art	5
2.1 Deep Learning	5
2.2 Temporal Fusion	5
2.3 Segmentation	5
2.4 Semantic Segmentation	5
2.4.1 Classical Semantic Segmentation	5
2.4.2 Deep Learning based Semantic Segmentation	5
2.5 Temporal Fusion in Semantic Segmentation	5
2.6 Limitations of previous work	5
3 Methodology	7
3.1 Dataset	7
3.1.1 ScanNet	7
3.1.2 Virtual KITTI 2	7
3.1.3 VIODE	7
3.2 Data Collection and Preprocessing	7
3.3 Experimental Design	7
3.3.1 U-Net Vanilla model	7
3.3.2 U-Net with Temporal Fusion	7

3.3.3	W-Net Vanilla model	7
3.3.4	W-Net with Temporal Fusion	7
3.4	Training and Evaluation Pipeline	7
3.5	Training Procedure	7
3.6	Hardware Configuration	7
4	Evaluation and Experimental Result	9
4.1	Evaluation Metric	10
4.1.1	Pixel Accuracy	10
4.1.2	Precision	10
4.1.3	Recall	10
4.1.4	ROC and AUC	10
4.1.5	IOU	10
4.2	Experiment1: Scannet Dataset	10
4.2.1	Experiment1.1: U-Net and W-Net model with single sequence data	10
4.2.2	Experiment1.2: U-Net and W-Net model with two sequence data	10
4.2.3	Experiment1.3: U-Net and W-Net model with three sequence data	10
4.2.4	Experiment1.4: U-Net and W-Net model with four sequence data	10
4.2.5	Experiment1.5: U-Net and W-Net model with all sequence data	10
4.3	Experiment2: Virtual KITTI 2	10
4.3.1	Experiment1.1: U-Net and W-Net model with single sequence data	10
4.3.2	Experiment1.2: U-Net and W-Net model with two sequence data	10
4.3.3	Experiment1.3: U-Net and W-Net model with three sequence data	10
4.3.4	Experiment1.4: U-Net and W-Net model with four sequence data	10
4.3.5	Experiment1.5: U-Net and W-Net model with all sequence data	10
4.4	Experiment3: VIODE	10
4.4.1	Experiment1.1: U-Net and W-Net model with single sequence data	10
4.4.2	Experiment1.2: U-Net and W-Net model with two sequence data	10
4.4.3	Experiment1.3: U-Net and W-Net model with three sequence data	10
4.4.4	Experiment1.4: U-Net and W-Net model with four sequence data	10
4.4.5	Experiment1.5: U-Net and W-Net model with all sequence data	10
5	Android Deployment	11
5.1	Framework	11
5.2	Pipeline	11
5.3	Deployment and Results	11
6	Conclusions	13
6.1	Contributions	13
6.2	Lessons learned	13

6.3 Future work	13
Appendix A Design Details	15
Appendix B Parameters	17

List of Figures

List of Tables

1

Introduction

Temporal fusion is a process of adding the information from other sources to the current step to make the prediction better at each timestamp. Fusion of information can be observed in various different fields such as time series prediction, video based depth estimation, segmentation and so on.

1.1 Motivation

1.1.1 Temporal fusion

Fusion of information in a temporal fashion improves the prediction at every timestamp. Data can be fused in the temporal fusion fashion to improve the prediction at each and every step.

1.1.2 Semantic segmentation

Semantic segmentation is a process of classifying the each pixel of the input frame into a predefined specific class.

1.2 Challenges and Difficulties

1.2.1 ...

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1.3 Problem Statement

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1.3.2 ...

1.3.3 ...

2

State of the Art

2.1 Deep Learning

2.2 Temporal Fusion

2.3 Segmentation

2.4 Semantic Segmentation

2.4.1 Classical Semantic Segmentation

2.4.2 Deep Learning based Semantic Segmentation

2.5 Temporal Fusion in Semantic Segmentation

Use as many sections as you need in your related work to group content into logical groups
Don't forget to correctly cite your sources [?].

2.6 Limitations of previous work

3

Methodology

Semantic segmentation can be evaluated using the

How you are planning to test/compare/evaluate your research. Criteria used.

3.1 Dataset

3.1.1 ScanNet

3.1.2 Virtual KITTI 2

3.1.3 VIODE

3.2 Data Collection and Preprocessing

3.3 Experimental Design

3.3.1 U-Net Vanilla model

3.3.2 U-Net with Temporal Fusion

3.3.3 W-Net Vanilla model

3.3.4 W-Net with Temporal Fusion

3.4 Training and Evaluation Pipeline

3.5 Training Procedure

3.6 Hardware Configuration

4

Evaluation and Experimental Result

Implementation and measurements.

4.1 Evaluation Metric

4.1.1 Pixel Accuracy

4.1.2 Precision

4.1.3 Recall

4.1.4 ROC and AUC

4.1.5 IOU

4.2 Experiment1: Scannet Dataset

4.2.1 Experiment1.1: U-Net and W-Net model with single sequence data

4.2.2 Experiment1.2: U-Net and W-Net model with two sequence data

4.2.3 Experiment1.3: U-Net and W-Net model with three sequence data

4.2.4 Experiment1.4: U-Net and W-Net model with four sequence data

4.2.5 Experiment1.5: U-Net and W-Net model with all sequence data

4.3 Experiment2: Virtual KITTI 2

4.3.1 Experiment1.1: U-Net and W-Net model with single sequence data

4.3.2 Experiment1.2: U-Net and W-Net model with two sequence data

4.3.3 Experiment1.3: U-Net and W-Net model with three sequence data

4.3.4 Experiment1.4: U-Net and W-Net model with four sequence data

4.3.5 Experiment1.5: U-Net and W-Net model with all sequence data

4.4 Experiment3: VIODE

4.4.1 Experiment1.1: U-Net and W-Net model with single sequence data

4.4.2 Experiment1.2: U-Net and W-Net model with two sequence data

4.4.3 Experiment1.3: U-Net and W-Net model with three sequence data

5

Android Deployment

5.1 Framework

Describe results and analyse them

5.2 Pipeline

5.3 Deployment and Results

6

Conclusions

6.1 Contributions

6.2 Lessons learned

6.3 Future work



Design Details

Your first appendix

B

Parameters

Your second chapter appendix
