

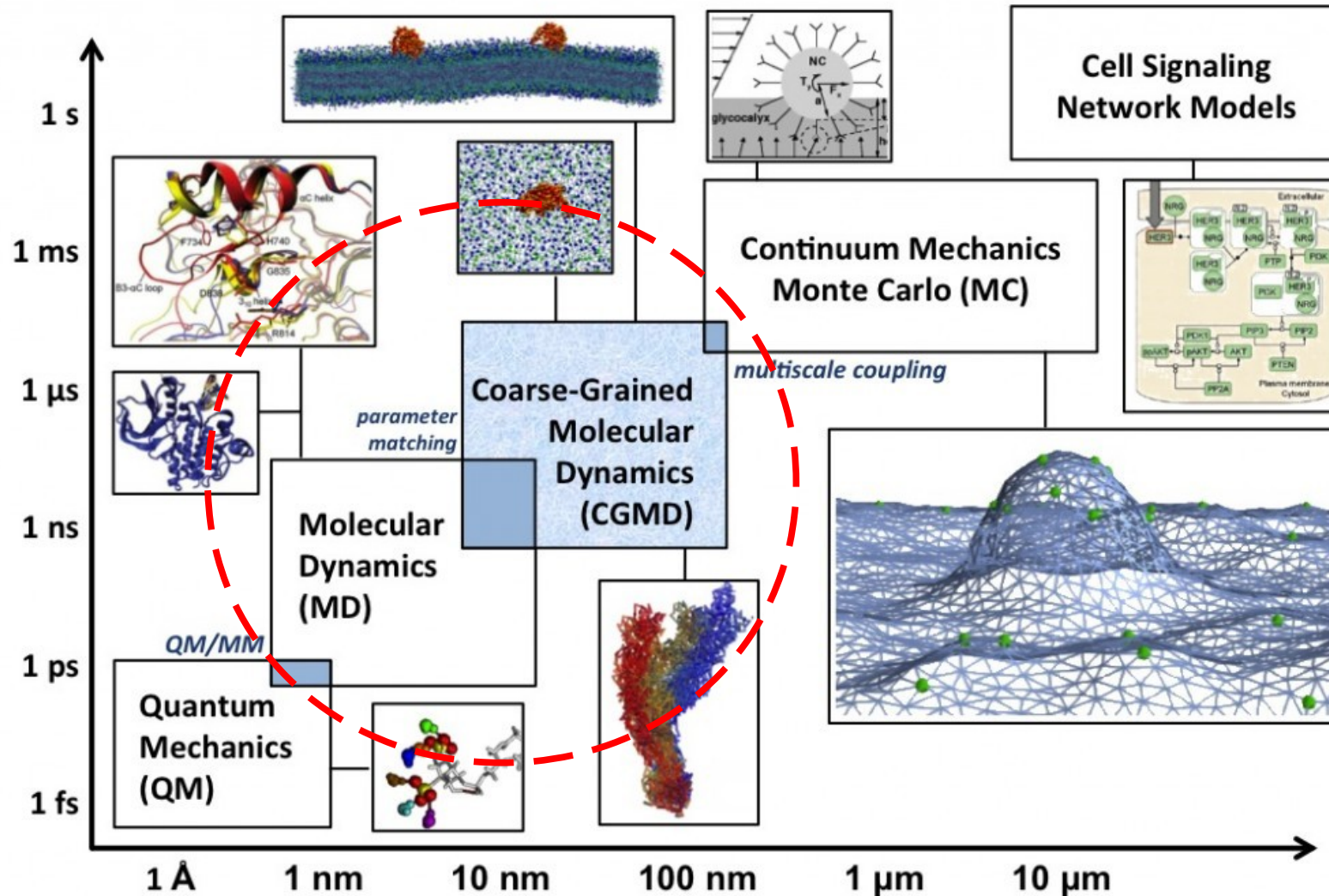
Computational Physics 2023

Sommersemester, 3th April, 2022 – 14th Juli, 2022

- 1) Introduction
- 2) Numbers and errors
- 3) Differentiation and integration
- 4) Ordinary differential equations
- 5) Molecular dynamics simulations**
- 6) Partial differential equations
- 7) Iteration processes
- 8) Matrixdiagonalisation & Eigenvalue problems
- 9) Minimization
- 10) Random numbers
- 11) Monte Carlo (MC) Simulations
- 12) Perkolation
- 13) Stochastic Dynamics

The field of molecular simulations

Multiscale modeling enables spanning range of time and length scales

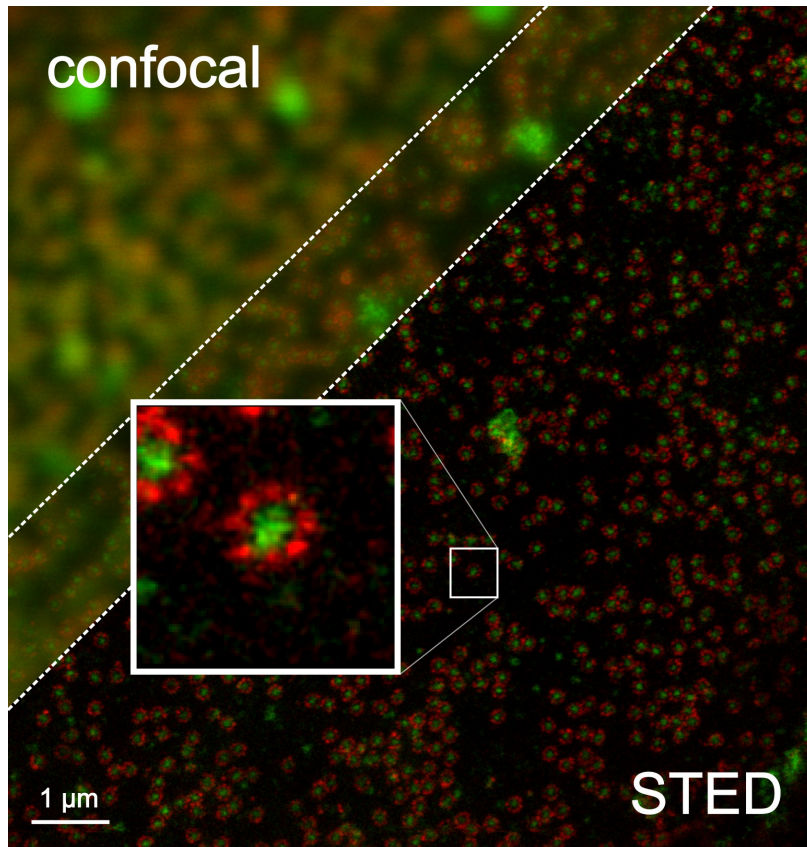


Different methods for different scales: This course will mainly focus on the molecular scale

The idea of an “computational microscope”

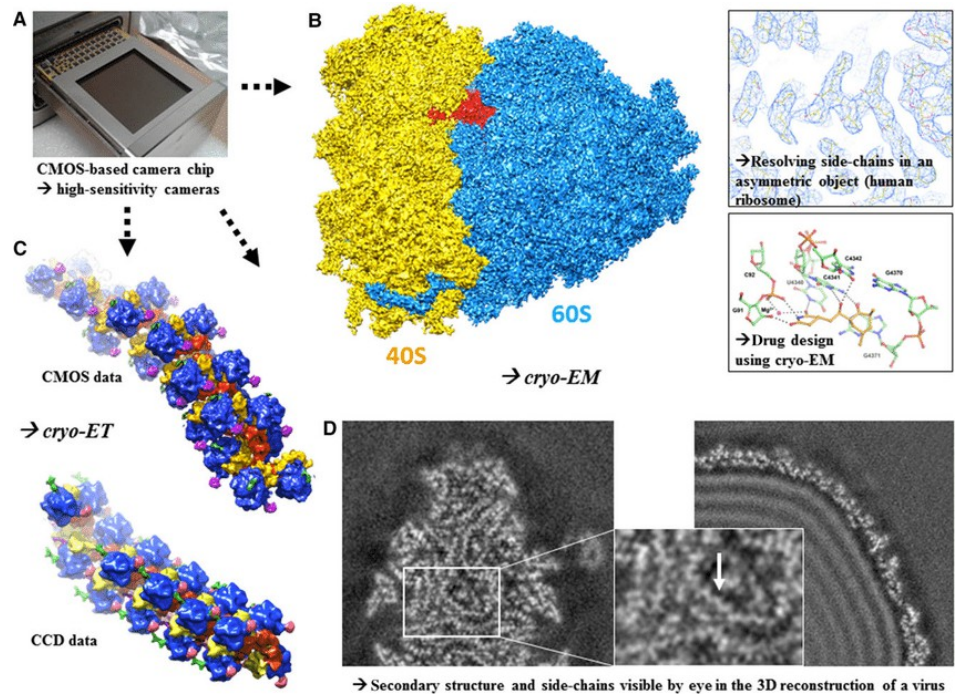
Recent “high” resolution microscopic techniques:

Stimulated emission depletion (STED)
microscopy (dynamic)



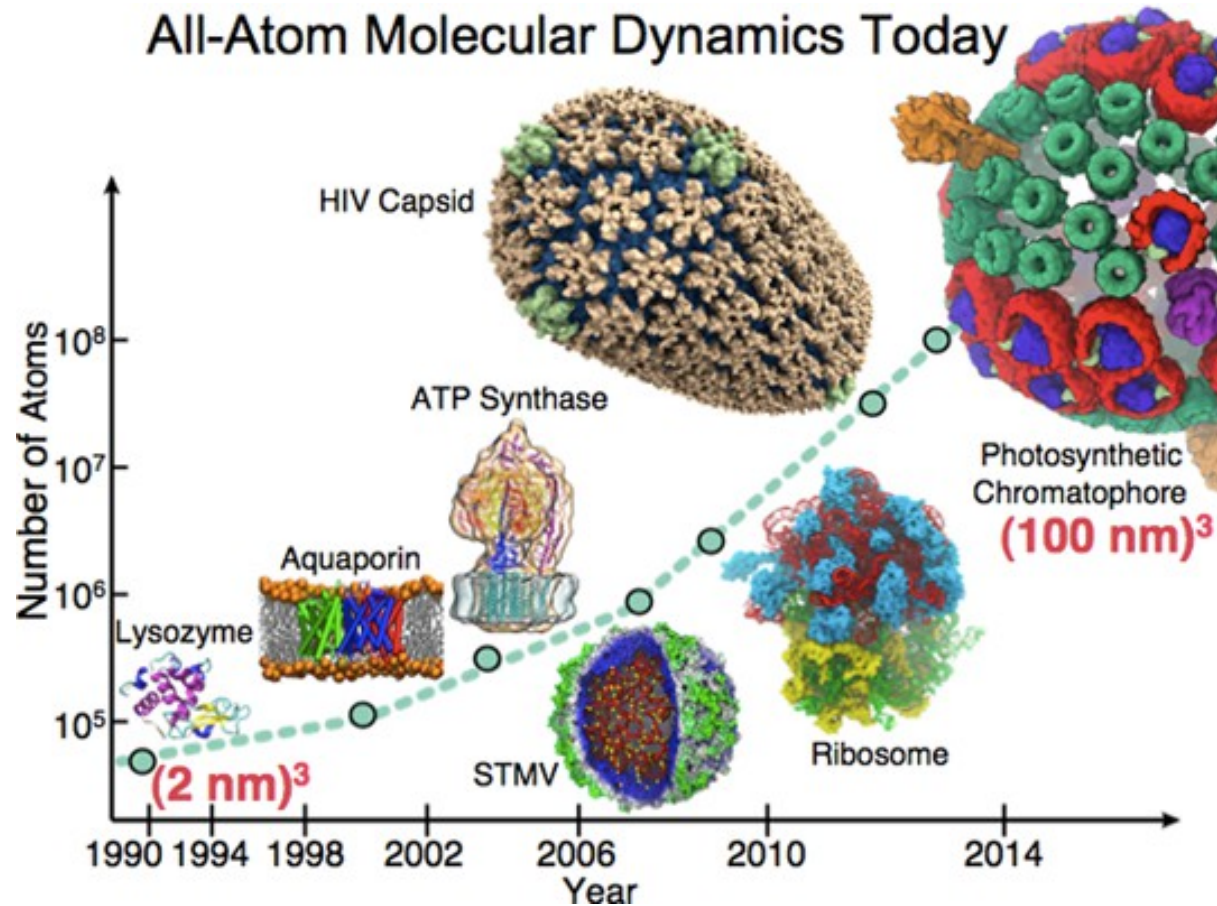
Nobel Prize chemistry 2014

cryo-electron microscopy (static)



Nobel Prize chemistry 2017

The idea of a “computational microscope”



The Nobel Prize in Chemistry 2013 was awarded jointly to Martin Karplus (left), Michael Levitt (middle) and Arieh Warshel (right) *"for the development of multiscale models for complex chemical systems."*



SARS-COV2 (art+MD simulation)



SARS-COV-2

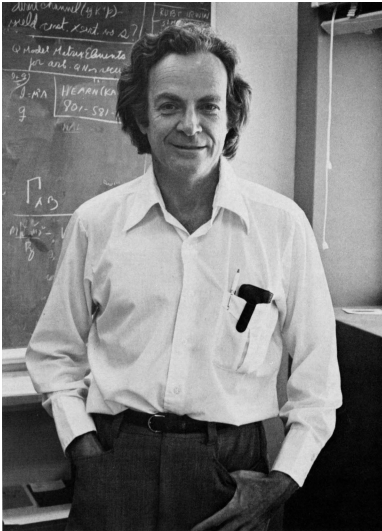
VIRAL ENTRY ANIMATION

We make the invisible enemy visible

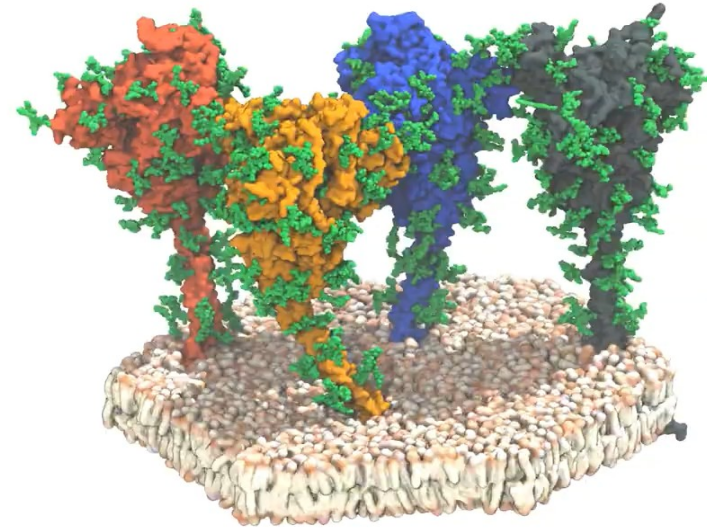
Picture: Thomas Splettstößer / SciStyle.com



MD simulation



Richard Feynman



“everything that living things do can be understood in terms of the jiggings and wiggings of atoms.”


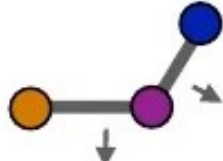

<https://www.youtube.com/watch?v=v3pYRn5j7ol>



Molecular models/force fields

Typical energy function

$$E = \sum_{b \in \text{bonds}} k_b (r_b - r_b^0)^2 + \sum_{a \in \text{angles}} \kappa_a (\theta_a - \theta_a^0)^2 + \sum_{d \in \text{dihedrals}} \sum_n l_{dn} \cos(n\pi)$$

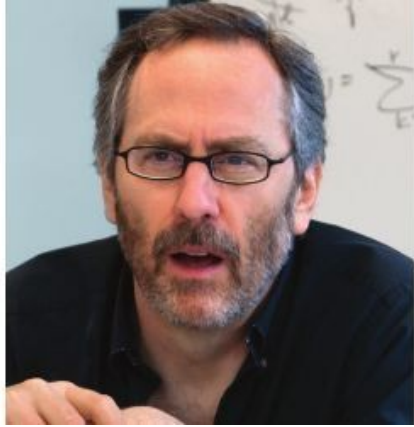
bond stretch
angle torsion
dihedrals

$$+ \sum_{i < j \in \text{atoms}} \frac{q_i q_j}{r_{ij}} + \sum_{i < j \in \text{atoms}} 4\epsilon_{ij} \left(\left(\frac{\sigma_{ij}}{r_{ij}} \right)^{12} - \left(\frac{\sigma_{ij}}{r_{ij}} \right)^6 \right)$$

electrostatics
dispersion

Usually fixed charges

MD simulation & \$\$\$\$\$\$\$\$\$\$



David E. \$haw
(PhD student: Jeff Bezo\$)



$$U(R) = \sum_{\text{bonds}} k_r (r - r_{eq})^2 + \sum_{\text{angles}} k_\theta (\theta - \theta_{eq})^2 + \sum_{\text{dihedrals}} k_\phi (1 + \cos[n\phi - \gamma]) + \sum_{\text{impropers}} k_\omega (\omega - \omega_{eq})^2 + \sum_{i < j}^{\text{atoms}} \epsilon_{ij} \left[\left(\frac{r_m}{r_{ij}} \right)^{12} - 2 \left(\frac{r_m}{r_{ij}} \right)^6 \right] + \sum_{i < j}^{\text{atoms}} \frac{q_i q_j}{4\pi\epsilon_0 r_{ij}}$$

<i>bond</i>	
<i>angle</i>	
<i>dihedral</i>	
<i>improper</i>	
<i>van der Waals</i>	
<i>electrostatic</i>	

- Anton2 is a dedicated GPU being a factor 1000x faster than consumer GPUs.
Motivation?: Plausibly demonstration and \$\$ (big pharma)

The Euler scheme (otherwise “known” as “the high school method”):

$$\mathbf{r}_i(t + \Delta t) = \mathbf{r}_i(t) + \Delta t \mathbf{v}_i(t) + \frac{\Delta t^2}{2m_i} \mathbf{f}_i(t) + \mathcal{O}(\Delta t^3)$$

$$\mathbf{v}_i(t + \Delta t) = \mathbf{v}_i(t) + \frac{\Delta t}{m_i} \mathbf{f}_i(t) + \mathcal{O}(\Delta t^2)$$

What is the problem?

Time integration: Operators

Lets derive a proper scheme.....

$$i\hbar \frac{\partial}{\partial t} \Psi = H\Psi \rightarrow |\Psi(t)\rangle = e^{-iHt} |\Psi(0)\rangle$$

$$e^{-iH} e^{iH} = I$$



Erwin Schrödinger

$$\dot{A} = \{A, H\} \rightarrow A(t) = A(0) e^{\{A, H\}t}$$



Joseph Liouville

$$\{.., H\} := i\mathcal{L} \quad (\text{Liouville operator})$$

$$A(t) = A(0) e^{i\mathcal{L}t}$$

Time integration: Operators

Lets split the Liouville operator in a position and momentum dependent part:

$$i\mathcal{L} = i\mathcal{L}_{\mathbf{r}} + i\mathcal{L}_{\mathbf{p}},$$

$$i\mathcal{L}_{\mathbf{r}} = \sum_i \dot{\mathbf{r}}_i \frac{\partial}{\partial \mathbf{r}_i} \quad i\mathcal{L}_{\mathbf{p}} = \sum_i \dot{\mathbf{p}}_i \frac{\partial}{\partial \mathbf{p}_i}.$$

■ Lets now construct a symmetric version of this operator (Trotter decomposition):

$$e^{i(\mathcal{L}_{\mathbf{r}} + \mathcal{L}_{\mathbf{p}})\Delta t} = e^{i\frac{\Delta t}{2}\mathcal{L}_{\mathbf{p}}} e^{i\Delta t\mathcal{L}_{\mathbf{r}}} e^{i\frac{\Delta t}{2}\mathcal{L}_{\mathbf{p}}} + \mathcal{O}(\Delta t^3).$$

This sequence of operators commutes due to symmetry!

Time integration: Operators

$$e^{a \frac{\partial}{\partial x}} x \rightarrow \left(1 + a \frac{\partial}{\partial x}\right) x = x + a \quad (a \ll 1)$$

$$e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!} = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots$$

$$i\mathcal{L} = i\mathcal{L}_r + i\mathcal{L}_p,$$

$$i\mathcal{L}_r = \sum_i \dot{\mathbf{r}}_i \frac{\partial}{\partial \mathbf{r}_i}$$

$$i\mathcal{L}_p = \sum_i \dot{\mathbf{p}}_i \frac{\partial}{\partial \mathbf{p}_i}.$$

These are the rules!

$$e^{i\frac{\Delta t}{2}\mathcal{L}_p} \mathbf{r}_i = \mathbf{r}_i$$

$$e^{i\frac{\Delta t}{2}\mathcal{L}_p} \mathbf{p}_i = \mathbf{p}_i + \frac{\Delta t}{2} \dot{\mathbf{p}}_i$$

$$e^{i\Delta t\mathcal{L}_r} \mathbf{r}_i = \mathbf{r}_i + \Delta t \dot{\mathbf{r}}_i$$

$$e^{i\Delta t\mathcal{L}_r} \mathbf{p}_i = \mathbf{p}_i.$$

Time integration: Operators

These are the rules!

$$e^{i\frac{\Delta t}{2}\mathcal{L}_P} \mathbf{r}_i = \mathbf{r}_i$$

$$e^{i\frac{\Delta t}{2}\mathcal{L}_P} \mathbf{p}_i = \mathbf{p}_i + \frac{\Delta t}{2} \dot{\mathbf{p}}_i$$

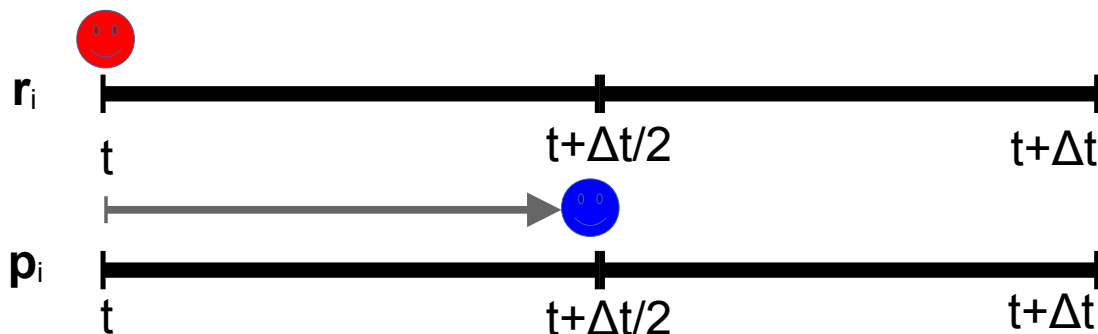
$$e^{i\Delta t\mathcal{L}_r} \mathbf{r}_i = \mathbf{r}_i + \Delta t \dot{\mathbf{r}}_i$$

$$e^{i\Delta t\mathcal{L}_r} \mathbf{p}_i = \mathbf{p}_i.$$

The first operator:

$$e^{i\frac{\Delta t}{2}\mathcal{L}_P} e^{i\Delta t\mathcal{L}_r} e^{i\frac{\Delta t}{2}\mathcal{L}_P} \mathbf{r}_i(t) \rightarrow \mathbf{r}_i(t)$$

$$e^{i\frac{\Delta t}{2}\mathcal{L}_P} e^{i\Delta t\mathcal{L}_r} e^{i\frac{\Delta t}{2}\mathcal{L}_P} \mathbf{p}_i(t) \rightarrow \mathbf{p}_i(t + \frac{\Delta t}{2}) = \mathbf{p}_i(t) + \frac{\Delta t}{2} \dot{\mathbf{p}}_i(t)$$



Time integration: Operators

These are the rules!

$$e^{i\frac{\Delta t}{2}\mathcal{L}_P} \mathbf{r}_i = \mathbf{r}_i$$

$$e^{i\frac{\Delta t}{2}\mathcal{L}_P} \mathbf{p}_i = \mathbf{p}_i + \frac{\Delta t}{2} \dot{\mathbf{p}}_i$$

$$e^{i\Delta t\mathcal{L}_r} \mathbf{r}_i = \mathbf{r}_i + \Delta t \dot{\mathbf{r}}_i$$

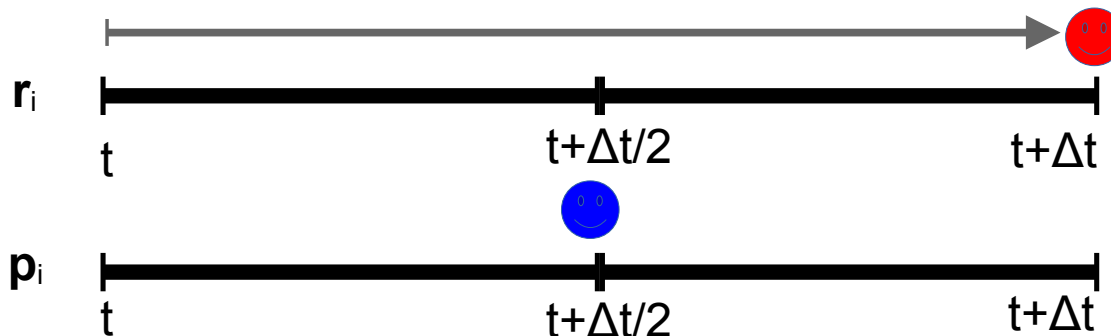
$$e^{i\Delta t\mathcal{L}_r} \mathbf{p}_i = \mathbf{p}_i.$$

The second operator:

$$e^{i\frac{\Delta t}{2}\mathcal{L}_P} e^{i\Delta t\mathcal{L}_r} \mathbf{r}_i(t) \rightarrow \mathbf{r}_i(t + \Delta t) = \mathbf{r}_i(t) + \Delta t \dot{\mathbf{r}}_i(t + \frac{\Delta t}{2})$$

velocities already 'live' at $\Delta t/2$!

$$e^{i\frac{\Delta t}{2}\mathcal{L}_P} e^{i\Delta t\mathcal{L}_r} \mathbf{p}_i(t + \frac{\Delta t}{2}) \rightarrow \mathbf{p}_i(t + \frac{\Delta t}{2})$$



Time integration: Operators

These are the rules!

$$e^{i\frac{\Delta t}{2}\mathcal{L}_P} \mathbf{r}_i = \mathbf{r}_i$$

$$e^{i\frac{\Delta t}{2}\mathcal{L}_P} \mathbf{p}_i = \mathbf{p}_i + \frac{\Delta t}{2} \dot{\mathbf{p}}_i$$

$$e^{i\Delta t\mathcal{L}_r} \mathbf{r}_i = \mathbf{r}_i + \Delta t \dot{\mathbf{r}}_i$$

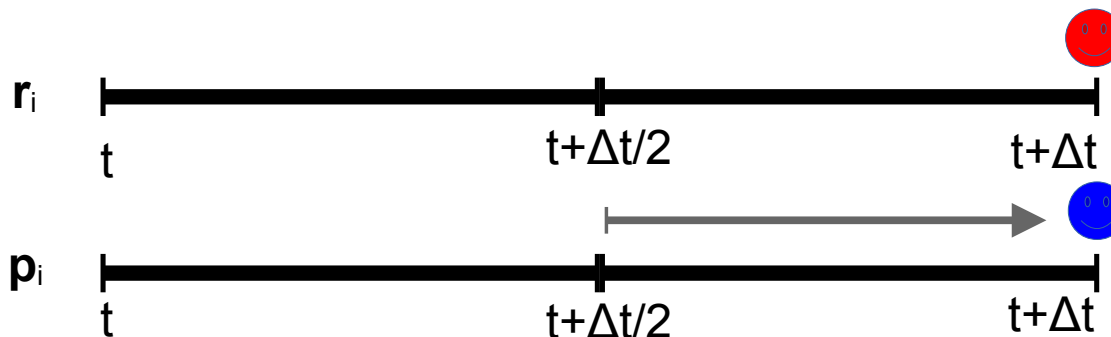
$$e^{i\Delta t\mathcal{L}_r} \mathbf{p}_i = \mathbf{p}_i.$$

The last operator:

$$e^{i\frac{\Delta t}{2}\mathcal{L}_P} \mathbf{r}_i(t + \Delta t) \rightarrow \mathbf{r}_i(t + \Delta t) = \mathbf{r}_i(t) + \Delta t \dot{\mathbf{r}}(t + \frac{\Delta t}{2})$$

$$e^{i\frac{\Delta t}{2}\mathcal{L}_P} \mathbf{p}_i(t + \frac{\Delta t}{2}) \rightarrow \mathbf{p}_i(t + \Delta t) = \mathbf{p}_i(t + \frac{\Delta t}{2}) + \frac{\Delta t}{2} \dot{\mathbf{p}}_i(t + \Delta t)$$

Position dependent forces
already 'live' at $t+\Delta t$!



Time integration: Operators

These are the rules!

$$e^{i\frac{\Delta t}{2}\mathcal{L}_p} \mathbf{r}_i = \mathbf{r}_i$$

$$e^{i\frac{\Delta t}{2}\mathcal{L}_p} \mathbf{p}_i = \mathbf{p}_i + \frac{\Delta t}{2} \dot{\mathbf{p}}_i$$

$$e^{i\Delta t\mathcal{L}_r} \mathbf{r}_i = \mathbf{r}_i + \Delta t \dot{\mathbf{r}}_i$$

$$e^{i\Delta t\mathcal{L}_r} \mathbf{p}_i = \mathbf{p}_i.$$

$$e^{i\frac{\Delta t}{2}\mathcal{L}_p} e^{i\Delta t\mathcal{L}_r} e^{i\frac{\Delta t}{2}\mathcal{L}_p} \mathbf{r}_i(t) = \mathbf{r}_i(t) + \Delta t \dot{\mathbf{r}}_i\left(\frac{\Delta t}{2}\right)$$

$$= \mathbf{r}_i(t) + \Delta t \mathbf{v}_i(t) + \frac{\Delta t^2}{2m_i} \mathbf{f}_i(t)$$

$$e^{i\frac{\Delta t}{2}\mathcal{L}_p} e^{i\Delta t\mathcal{L}_r} e^{i\frac{\Delta t}{2}\mathcal{L}_p} \mathbf{p}_i(t) = \mathbf{p}_i(t) + \frac{\Delta t}{2} (\dot{\mathbf{p}}_i(t) + \dot{\mathbf{p}}_i(t + \Delta t))$$

$$= \mathbf{p}_i(t) + \frac{\Delta t}{2} (\mathbf{f}_i(t) + \mathbf{f}_i(t + \Delta t)).$$

This is called the **Velocity-Verlet algorithm**. It is time reversible and phase-space conserving by construction (Hamiltonian flow conserves phase-space = Liouville theorem).

Time integration: Operators

These are the rules!

$$e^{i\frac{\Delta t}{2}\mathcal{L}_\mathbf{p}} \mathbf{r}_i = \mathbf{r}_i$$

$$e^{i\frac{\Delta t}{2}\mathcal{L}_\mathbf{p}} \mathbf{p}_i = \mathbf{p}_i + \frac{\Delta t}{2} \dot{\mathbf{p}}_i$$

$$e^{i\Delta t\mathcal{L}_\mathbf{r}} \mathbf{r}_i = \mathbf{r}_i + \Delta t \dot{\mathbf{r}}_i$$

$$e^{i\Delta t\mathcal{L}_\mathbf{r}} \mathbf{p}_i = \mathbf{p}_i.$$

$$e^{i\frac{\Delta t}{2}\mathcal{L}_\mathbf{p}} e^{i\Delta t\mathcal{L}_\mathbf{r}} e^{i\frac{\Delta t}{2}\mathcal{L}_\mathbf{p}} \mathbf{r}_i(t) = \mathbf{r}_i(t) + \Delta t \dot{\mathbf{r}}_i\left(\frac{\Delta t}{2}\right)$$

$$= \mathbf{r}_i(t) + \Delta t \mathbf{v}_i(t) + \frac{\Delta t^2}{2m_i} \mathbf{f}_i(t)$$

$$e^{i\frac{\Delta t}{2}\mathcal{L}_\mathbf{p}} e^{i\Delta t\mathcal{L}_\mathbf{r}} e^{i\frac{\Delta t}{2}\mathcal{L}_\mathbf{p}} \mathbf{p}_i(t) = \mathbf{p}_i(t) + \frac{\Delta t}{2} (\dot{\mathbf{p}}_i(t) + \dot{\mathbf{p}}_i(t + \Delta t))$$

$$= \mathbf{p}_i(t) + \frac{\Delta t}{2} (\mathbf{f}_i(t) + \mathbf{f}_i(t + \Delta t)).$$

Velocity-Verlet looks like the Euler scheme except for the force averaging!

Time integration: Atomic magnitudes

Velocity-Verlet scheme:

typical atomic magnitudes:

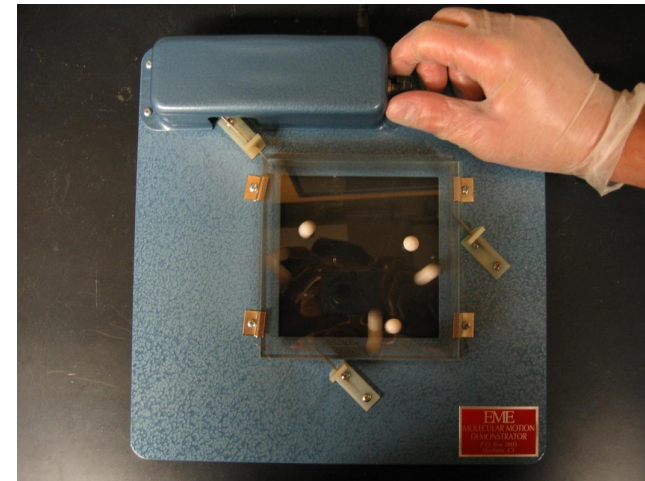
x (10^{-9} m)
 v (+/- 600 m/s !!)
 F (10^{-11} N)
 a (10^{13} g !!!!!)
 Δt (10^{-15} s)

$$x_{i+1} = x_i + v_i \Delta t + \frac{1}{2} a_i \Delta t^2$$

$$v_{i+1} = v_i + \frac{1}{2} (a_i + a_{i+1}) \Delta t$$

$t + \Delta t$

- Note that gravity (1 vs 10^{13} g) does not play a significant role on the motion of individual atom.
- Speed of sound relates to the atomic velocities.



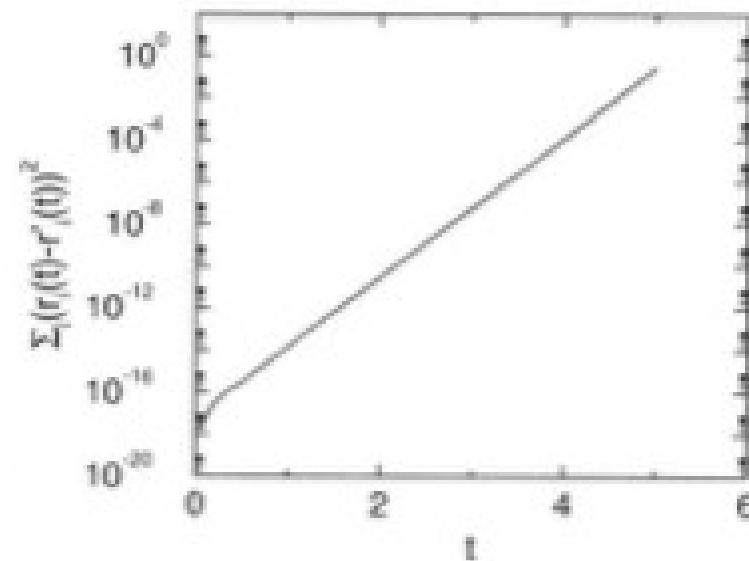


Figure 4.1: Illustration of the Lyapunov instability in a simulation of a Lennard-Jones system. The figure shows the time dependence of the sum of squared distances between two trajectories that were initially very close (see text). The total length of the run in reduced units was 5, which corresponds to 1000 time steps. Note that, within this relatively short time, the two trajectories become essentially uncorrelated.