



LS160/160A/162/162A: BCD DECADE COUNTERS LS161/161A/163/163A: 4-BIT BINARY COUNTERS

DESCRIPTION

The LS160/160A/161/161A/162/162A/163/163A are high-speed 4-bit synchronous counters. They are edge-triggered, synchronously presettable, and cascadable MSI building, blocks for counting, memory addressing, frequency division and other applications. The LS160 and LS162 count modulo 10 (BCD). The LS161 and LS163 count modulo 16 (binary).

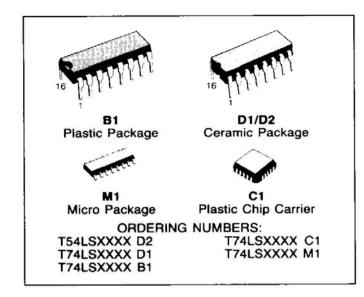
The LS160/160A and LS161/161A have an asynchronous Master Reset (Clear) input that overrides, and is independent of, the clock and all other control inputs. The LS162/162A and LA163/163A have a Synchronous Reset (Clear) input that overrides all other control inputs, but is active only during the rising clock edge.

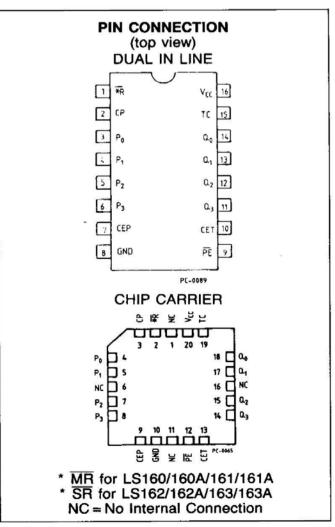
- SYNCHRONOUS COUNTING AND LOADING
- TWO COUNT ENABLE INPUTS FOR HIGH-SPEED SYNCHRONOUSLY EXPANSION
- EDGE-TRIGGERED OPERATION
- TYPICAL COUNT RATE OF 35 MHz
- FULLY TTL AND CMOS COMPATIBLE
- VERSION "A" PRELIMINARY DATA

	BCD Modulo 10	Binary (Modulo 16)
Asynchronous Reset	LS160/160A	LS161/161A
Synchronous Reset	LS162/162A	LS163/163A

PIN NAMES

	7
PE	Parallel Enable (Active LOW) Input
P ₀ -P ₃	Parallel Inputs
CEP	Count Enable Parallel Input
CET	Count Enable Trickle Input
СР	Clock (Active HIGH Going Edge) Input
MR	Master Reset (Active LOW) Input
SR	Synchronous Reset (Active LOW) Input
Q ₀ -Q ₃	Parallel Outputs
TC	Terminal Count Output

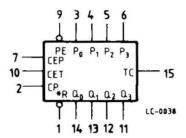






LOGIC SYMBOL AND TRUTH TABLE

- * MR for LS160/160A/161/161A
- * SR for LS162/162A/163/163A



V_{CC} = Pin 16 GND = Pin 8

*SR	PE	CET	CEP	Action on the Rising Clock Edge (I)
L	Х	Х	х	RESET (Clear)
н	L	Х	X	LOAD $(P_0 \rightarrow Q_0)$
н	Н	Н	н	COUNT (Increment)
н	Н	L	X	NO CHANGE (Hold)
н	Н	X	L	NO CHANGE (Hold)
0.0		10.54(5)	1	ATTACHMENTALS TOPOGRAPHICAL SHOP SHOP SHOP SHOP SHOP SHOP SHOP SHOP

* For the LS162/162A and LS163/163A only

H = HIGH Voltage Level

L = LOW Voltage Level

X = Don't Care

ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Value	Unit
V _{CC}	Supply Voltage	-0.5 to 7	V
VI	Input Voltage, Applied to Input	- 0.5 to 15	V
Vo	Output Voltage, Applied to Output	- 0.5 to 10	V
I _I Input Current, Into Inputs		-30 to 5	mA
IO Output Current, Into Outputs		50	mA

Stresses in excess of those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions in excess of those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

GUARANTEED OPERATING RANGES

Part Numbers		Tomporatura		
	Min	Тур	Max	Temperature
T54LS160/161/162/163D2	4.5 V	5.0 V	5.5 V	-55°C to +125°C
T74LS160/161/162/163XX	4.75 V	5.0 V	5.25 V	0°C to +70°C

XX = package type.

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FUNCTIONAL DESCRIPTION

The LS160/160A/161/161A/162/162A/163/163A are 4-bit synchronous counters with a synchronous Parallel Enable (Load) feature. These counters consist of four edge-triggered D flip-flops with the appropriate data routing networks feeding the D inputs. All changes of the Q outputs (except due to the asynchronous Master Reset in the LS160/160A and LS161/161A) occur as a result of, and synchronous with, the LOW to HIGH transition of the Clock input (CP). As long as the set-up time requirements are met, there are no special timing or activity constraints on any of the mode control or data inputs.

Three control inputs - Parallel Enable (PE), Count Enable Parallel (CEP) and Count Enable Trickle (CET) - select the mode of operation as shown in the tables. The Count Mode is enabled when the CEP, CET, and PE inputs are HIGH.

When the PE is LOW, the counters will synchronously load the data from the parallel inputs into the flip-flops on the LOW to HIGH transition of the clock. Either the CEP or CET inputs can be used to inhibit the count sequence. With the PE held HIGH, a LOW on either the CEP or CET inputs at least one set-up time prior to the LOW to HIGH clock transition will cause the existing output states to be retained. The AND feature of the two Count Enable inputs (CET-CEP) allows synchronous cascading without external gating and without delay accumulation over any pratical number of bits or digits.

The Terminal Count (TC) output is HIGH when the Count Enable Trickle (CET) input is HIGH while the counter is in its maximum count state (HLLH for the BCD counters, HHHH for the Binary counters). Note that TC is fully decoded and will, therefore, be HIGH only for one count state.

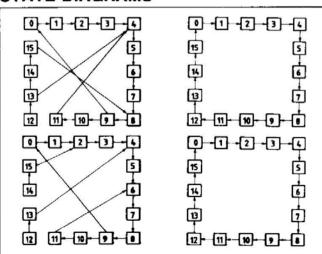
The LS160/160A and LS162/162A count modulo 10 following a binary coded decimal (BCD) sequence. They generate a TC output when the CET input is HIGH while the counter is in state 9 (HLLH). From this state they increment to state 0 (LLLL). If loaded with a code in excess of 9 they return to their legitimate sequence within two counts, as explained in the state diagram. States 10 through 15 do not generated a TC output.

The LS161/161A and LS163/163A count modulo 16 following a binary sequence. They generated a TC when the CET input is HIGH while the counter is in state 15 (HHHH). From this state they increment to state 0 (LLLL).

The Master Reset ($\overline{\text{MR}}$) of the LS160/160A and LS161/161A is asynchronous. When the $\overline{\text{MR}}$ is LOW, it overrides all other input conditions and sets the outputs LOW. The $\overline{\text{MR}}$ pin should never be left open. If not used, the $\overline{\text{MR}}$ pin should be tied through a resistor to V_{CC} , or to a gate output which is permanently set to a HIGH logic level.

The active LOW Synchronous Reset (SR) input of the LS162/162A and LS163/163A acts as an edge-triggered control input, overriding CET, CEP and PE, and resetting the four counter flip-flops on the LOW to HIGH transition of the clock. This simplifies the design from race-free logic controlled reset circuits, e.g. to reset the counter synchronously after reaching a predetermined value.

STATE DIAGRAMS



LOGIC EQUATIONS

Count Enable = CEP•CET•PE

TC for LS160 & LS162 = CET• $Q_0 \bullet \overline{Q_1} \bullet \overline{Q_2} \bullet Q_3$ TC for LS161 & LS163 = CET• $Q_0 \bullet Q_1 \bullet Q_2 \bullet Q_3$ Preset = $\overline{PE} \bullet CP + (rising clock edge)$

Preset = PE • CP + (rising clock edge Reset = MR (LS160 & LS161)

Reset = SR • CP + (rising clock edge) (LS162 & LS163)

LOGIC EQUATIONS

Count Enable = CEP•CET•PE

TC for LS160A & LS162A = CET•Q₀• $\overline{Q_1}$ • $\overline{Q_2}$ • $\overline{Q_3}$ TC for LS161A & LS163A = CET•Q₀• $\overline{Q_1}$ • $\overline{Q_2}$ • $\overline{Q_3}$ Preset = \overline{PE} •CP + (rising clock edge)

Reset = \overline{MR} (LS160A & LS161A)

Reset = \overline{SR} •CP + (rising clock edge (LS162A & LS163A)

NOTE: The LS160/160A and LS162/162A can be preset to any state, but will not count beyond 9. If preset to state 10, 11, 12, 13, 14 or 15, it will return to its normal sequence within two clock pulses.



DC CHARACTERISTICS OVER OPERATING TEMPERATURE RANGE (LS160/161/162/163).

O L - I	Parameter		Limits			Test Conditions		
Symbol			Min.	Тур.	Max.	(Note 1)		Units
V _{IH}	Input HIGH Voltage		2.0			Guaranteed in for all inputs	nput HIGH Voltage	V
VIL	Input LOW Voltage	54			0.7	The state of the s	nput LOW Voltage	V
		74			0.8	for all Inputs		
V _{CD}	Input Clamp Diode Vo	Itage		-0.65	- 1.5	V _{CC} = MIN,I _{IN}	= - 18mA	V
V _{OH}	Output HIGH Voltage	54	2.5	3.4		V _{CC} = MIN,I _O	$_{H} = -400 \mu A, V_{IN} = V_{IH} \text{ or }$	V
		74	2.7	3.4		VIL per Truth	Table	*
V _{OL}	Output LOW Voltage	54,74		0.25	0.4	$I_{OL} = 4.0 \text{mA}$	V _{CC} = MIN, V _{IN} = V _{IH} or	
		74		0.35	0.5	I _{OL} = 8.0mA	V _{IL} per Truth Table	\ \
I _{tH}	Input HIGH Current P ₀ -P ₃ , MR, SR PE, CEP, CP CET				20 24 40	V _{CC} = MAX, \	/ _{IN} = 2.7V	μА
	P ₀ -P ₃ , MR, SR, PE, CEP, CP CET				0.1 0.2	V _{CC} = MAX, \	/ _{IN} = 7.0V	mA
I _{IL}	Input LOW Current P ₀ -P ₃ , MR, SR PE, CEP, CP CET				-0.40 -0.48 -0.80	V _{CC} = MAX, \	/ _{IN} = 0.4V	mA
los	Output Short Circuit C (Note 2)	urrent	-20		- 100	$V_{CC} = MAX, V_{OUT} = 0V$		mA
ICCH ICCL	Power Supply Current			18 19	31 32	V _{CC} = MAX		mA

AC CHARACTERISTICS: T_A = 25°C (LS160/161/162/163)

Symbol			Limits		Test Conditions		Units
	Parameter	Min.	Тур.	Max.			
t _{PLH}	Turn Off Delay CP to Q Turn On Delay CP to Q		13 18	25 27	Fig. 1		ns
t _{PLH}	Turn Off Delay CP to TC Turn On Delay CP to TC		15 14	25 21	Fig. 4]	ns
t _{PLH}	Turn Off Delay CET to TC Turn On Delay CET to TC		9.0 16	14 23	Fig. 3	V _{CC} = 5.0V C _L = 15pF	ns
t _{PHL}	Turn On Delay MR to Q (LS160 and LS161 only)		18	28	Fig. 2		ns
f _{count}	Input Count Frequency	25	35		Fig. 1	1	MHz

Notes:

¹⁾ Conditions for testing, not shown in the Table, are chosen to guarantee operation under "worst case" conditions.

²⁾ Not more than one output should be shorted at a time.

³⁾ Typical values are at $V_{CC} = 5.0V$, $T_A = 25$ °C



AC SET-UP REQUIREMENTS: TA = 25°C (LS160/161/162/163)

Symbol Parameter	B		Limits		Test Conditions		I I mid-	
	Min.	Тур.	Max.	rest C	Units			
t _{rec}	Recovery Time for MR (LS160 and LS161 Only)	20			Fig. 1		ns	
t _W MR(L)	Master Reset Pulse width (LS160 and LS161 Only)	15			Fig. 2		ns	
t _W CP(H)	Clock Pulse Width (HIGH) Clock Pulse Width (LOW)	15 25			Fig. 1		ns	
t _s (H)	Set-up Time (HIGH), Data to Clock Set-up Time (LOW), Data to Clock	20					ns	
t _h (H)	Hold Time (HIGH), Data to Clock Hold Time (LOW), Data to Clock	3.0			Fig. 5		ns	
t _s (H)	Set-up Time (HIGH), PE or SR to Clock Set-up Time (LOW), PE or SR to Clock	25 25			F: 0	V _{CC} = 5.0V	ns	
t _h (H)	Hold Time (HIGH), PE or SR to Clock Hold Time (LOW), PE or SR to Clock	0			Fig. 7		ns	
t _s (H)	Set-up Time (HIGH), CE to Clock Set-up Time (LOW), CE to Clock	25 25					ns	
t _h (H)	Hold Time (HIGH), CE to Clock Hold Time (LOW), CE to Clock	0					ns	

DEFINITION OF TERMS:

SET-UP TIME (t_s) - is defined as the minimum time required for the correct logic level to be present at the logic input prior to the clock transition from LOW to HIGH in order to be recognized and transferred to the outputs.

HOLD TIME (t_h) - is defined as the minimum time following the clock transition from LOW to HIGH that the logic level must be maintained at the input in order to ensure continued recognition. A negative HOLD TIME indicates that the correct logic level may be released prior to the clock transition from LOW to HIGH and still be recognized.

RECOVERY TIME (t_{rec}) - is defined as the minimim time required between the end of the reset pulse and the clock transition from LOW to HIGH in order to recognize and transfer HIGH Data to the Q outputs.



DC CHARACTERISTICS OVER OPERATING TEMPERATURE RANGE (LS160A/161A/162A/163A).

Complete!	Davamatas			Limits		Test Conditions		I I miam
Symbol Paramet			Min.	Тур.	Max.	(Note	1)	Units
V _{IH}	Input HIGH Voltage		2.0			Guaranteed input HIGH Voltage for all Inputs		V
VIL	Input LOW Voltage	54			0.7	Guaranteed input LOV	W Voltage	V
		74			0.8	for all Inputs		
V_{CD}	Input Clamp Diode Vo	Itage		- 0.65	- 1.5	$V_{CC} = MIN, I_{IN} = -18m$	ıA	V
V _{OH}	Output HIGH Voltage	54	2.5	3.5		V _{CC} = MIN,I _{OH} = -400	$0\mu A, V_{IN} = V_{IH}$ or	V
		74	2.7	3.5		V _{IL} per Truth Table		
V _{OL}	Output LOW Voltage	54,74		0.25	0.4	I _{OL} = 4.0mA V _{CC} = I	MIN, V _{IN} = V _{IL} or	V
		74		0.35	0.5	I _{OL} = 8.0mA V _{IH} pe	V _{IH} per Truth Table	
^ј ін	Input HIGH Current MR, Data, CEP, Clo PE, CET (LS160A/10				20 40	V _{CC} = MAX, V _{IN} = 2.7V		μА
	MR, Data, CEP, Clo PE, CET (LS160A/10				0.1 0.2	$V_{CC} = MAX, V_{IN} = 7.0$	V _{IN} = 7.0V	
l _{iH}	Input HIGH Current Data, CEP, Clock PE, CET, SR (LS1604	V161A)			20 40	$V_{CC} = MAX, V_{IN} = 2.7$	I	μΑ
	Data, CEP, Clock PE, CET, SR (LS162A	V/163A)			0.1 0.2	$V_{CC} = MAX, V_{IN} = 7.0$	/	mA
I _{IL}	Input LOW Current MR, Data, CEP, Clo PE, CET (LS160A/10				-0.4 -0.8	1 00		mA
I _{IL}	Input LOW Current Data, CEP, Clock PE, CET, SR (LS162)	V163A)			-0.4 -0.8			μΑ
los	Output Short Circuit C (Note 2)	urrent	- 20		- 100	V _{CC} = MAX, V _{OUT} = 0	V	mA
ICCH ICCL	Power Supply Current		i ic	18 19	31 32	V _{CC} = MAX		mA

Notes:

¹⁾ Conditions for testing, not shown in the Table, are chosen to guarantee operation under "worst case" conditions.

²⁾ Not more than one output should be shorted at a time.

³⁾ Typical values are at $V_{CC} = 5.0V$, $T_A = 25$ °C



AC CHARACTERISTICS: TA = 25°C (LS160A/161A/162A/163A)

0	D		Limits		T 0 1141	Haisa
Symbol	Parameter	Min.	Тур.	Max.	Test Conditions	Units
t _{PLH}	Propagation Delay, Clock to TC		20 18	35 35		ns
t _{PLH}	Propagation Delay, Clock to Q		13 18	24 27	V _{CC} = 5.0V	ns
t _{PLH}	Propagation Delay, CET to TC		9.0 9.0	14 14	C _L = 15pF	ns
t _{PHL}	MR or SR to Q		20	28		ns
f _{MAX}	Maximum Clock Frequency	25	32			MHz

AC CHARACTERISTICS: TA = 25°C (LS160A/161A/162A/163A)

Symbol	D	Limits			Took Conditions	
	Parameter	Min.	Тур.	Max.	Test Conditions	Units
twCP	Clock Pulse Width	25				ns
tw	MR or SR Pulse Width	20			V = F O V	ns
t _s	Set-up Time, Any Input	20			$V_{CC} = 5.0V$	ns
t _h	Hold Time, Any Input	0				ns

DEFINITION OF TERMS:

SET-UP TIME (t_s) - is defined as the minimum time required for the correct logic level to be present at the logic input prior to the clock transition from LOW to HIGH in order to be recognized and transferred to the outputs.

HOLD TIME (t_h) - is defined as the minimum time following the clock transition from LOW to HIGH that the logic level must be maintained at the input in order to ensure continued recognition. A negative HOLD TIME indicates that the correct logic level may be released prior to the clock transition from LOW to HIGH and still be recognized.

RECOVERY TIME (t_{rec}) - is defined as the minimim time required between the end of the reset pulse and the clock transition from LOW to HIGH in order to recognized and transfer HIGH Data to the Q outputs.



AC WAVEFORMS

Fig. 1 Clock to Output Delays, Count Frequency, and Clock Pulse Width

Other Conditions: $\overline{PE} = \overline{MR} (\overline{SR}) = H$

CEP = CET = H

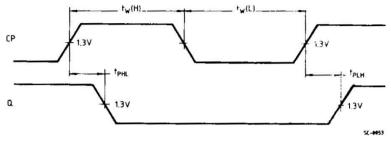


Fig. 2 Master Reset to Output Delay, Master Reset Pulse Width, and Master Reset Recovery Time

Other Conditions: $\overline{PE} = L$ $P_0 = P_1 = P_2 = P_3 = H$

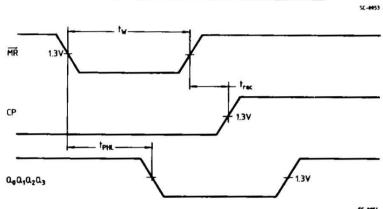


Fig. 3 Count Enable Trickle Input to Terminal Count Output Delays

The positive TC pulse occurs when the outputs are in the $(Q_0 \bullet \overline{Q_1} \bullet \overline{Q_2} \bullet Q_3)$ state for the LS160/160A and LS162/162A and the $(Q_0 \bullet Q_1 \bullet Q_2 \bullet Q_3)$ state for the LS161/161A and LS163/163A.

Other Conditions: CP = PE = CEP = MR = H

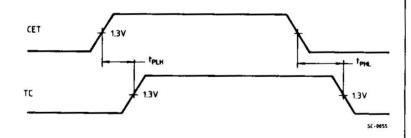
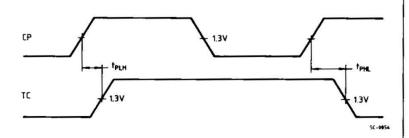


Fig. 4 Clock to Terminal Count Delays

The positive TC pulse in coincident with the output state $(Q_0 \bullet \overline{Q_1} \bullet \overline{Q_2} \bullet Q_3)$ for the LS160/160A and LS162/162A and $(Q_0 \bullet Q_1 \bullet Q_2 \bullet Q_3)$ state for the LS161/161A and LS163/163A.

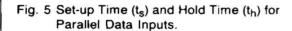
Other Conditions:

PE = CEP = CET = MR = H





AC WAVEFORMS (Continued)



Other Conditions: PE = L, MR = H

The shaded areas indicate when the input is permitted to change for predictable output performance.

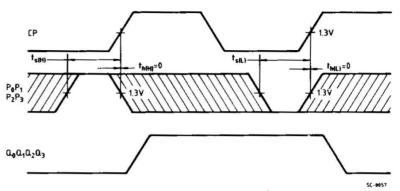


Fig. 6 Set-up Time (t_s) and Hold Time (t_h) for Count Enable (CEP) and (CET) and Parallel Enable (PE) Inputs.

Other Conditions: $\overline{PE} = L$, $\overline{MR} = H$

The shaded areas indicate when the input is permitted to change for predictable output performance.

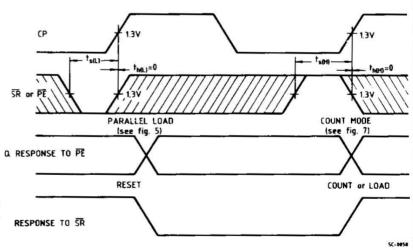
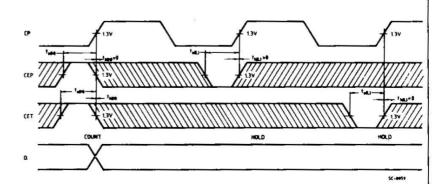


Fig. 7



Other Conditions: PE = H, MR = H