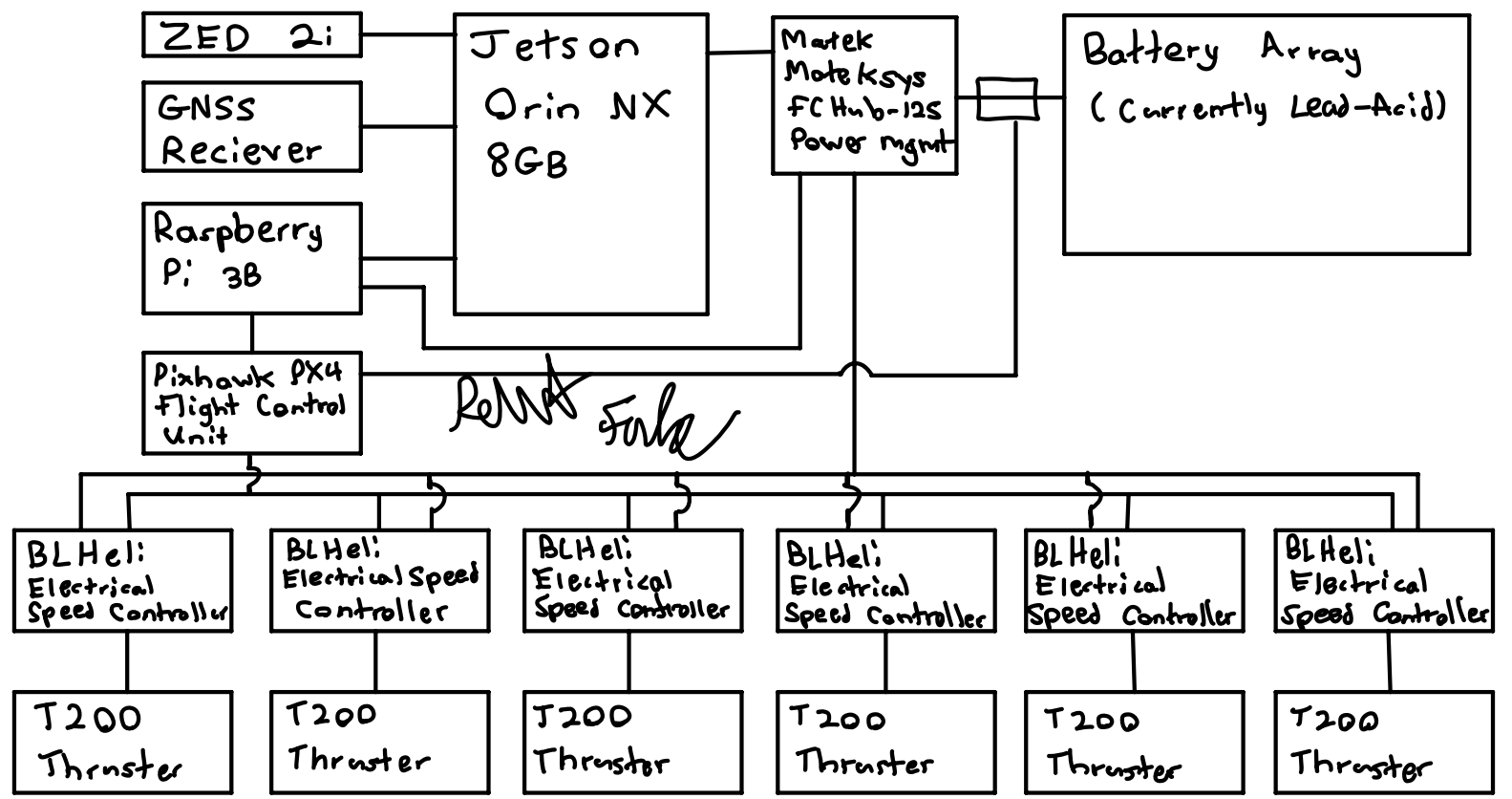


Initial Design: (May - Aug 2024)

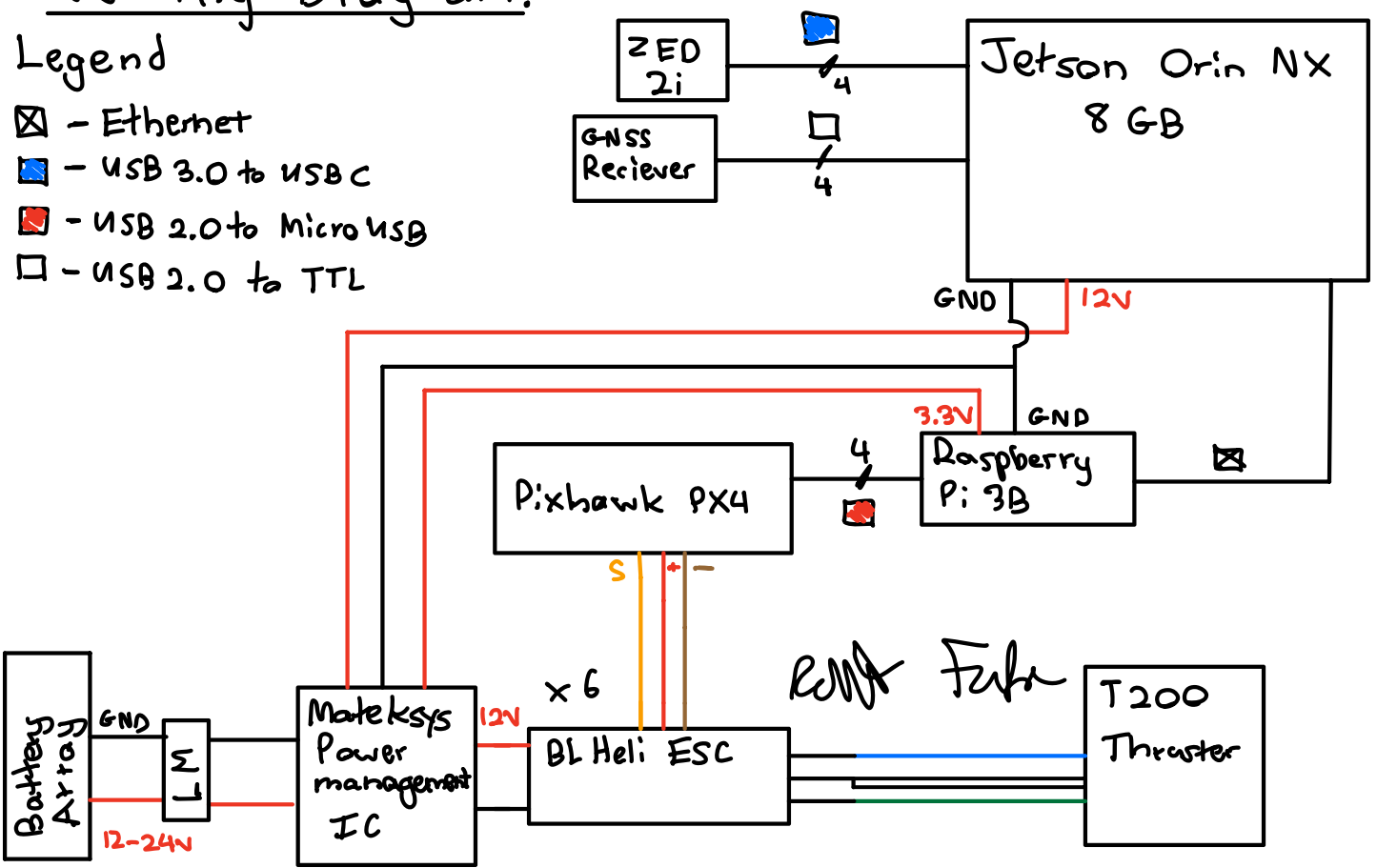
Block Diagram:



Wiring Diagram:

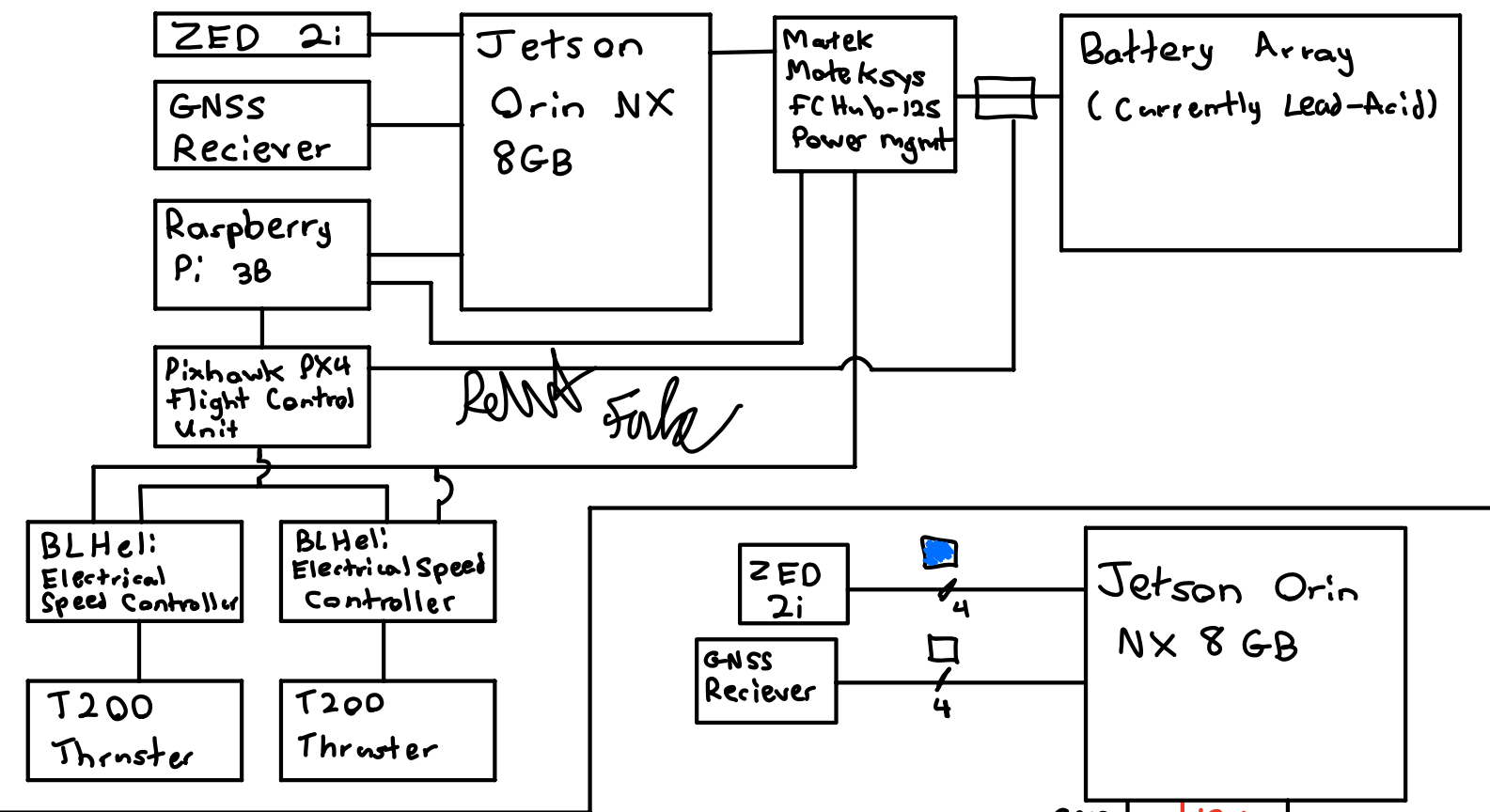
Legend

- ⊠ - Ethernet
- - USB 3.0 to USB C
- - USB 2.0 to Micro USB
- - USB 2.0 to TTL



Prototype Iteration/Revision (Sept-Dec 2024)

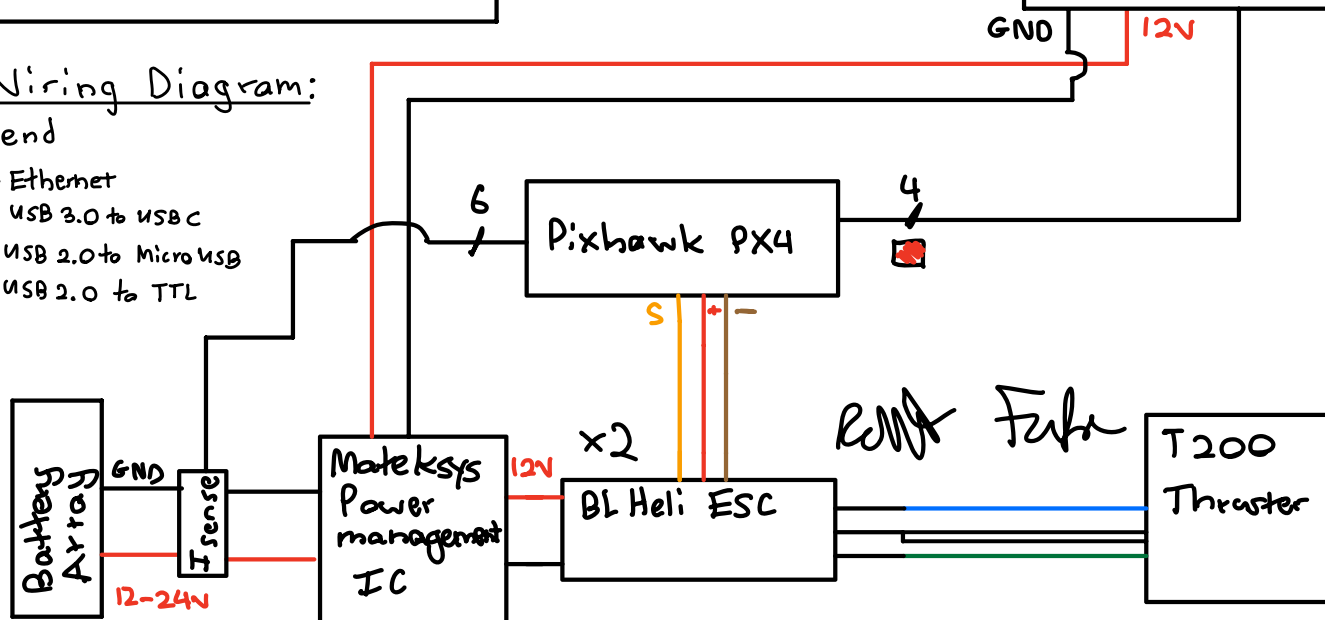
Block Diagram:



Wiring Diagram:

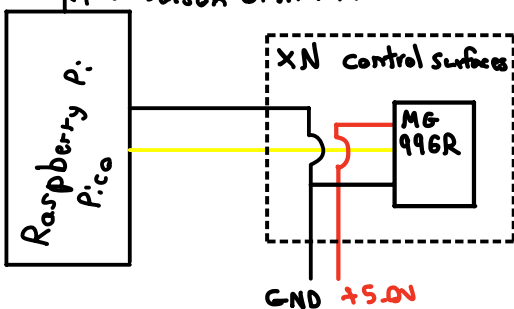
Legend

- ⊠ - Ethernet
- - USB 3.0 to USB C
- - USB 2.0 to Micro USB
- - USB 2.0 to TTL



Potential Improvements:

4 To Jetson Orin NX



- Would continue with hull design, FEA to optimize physical parameters
- Could perform Ros2 integration, Gazebo for simulation, etc...

Renk Fuku

- Pico is powered by USB VDD on Jetson.
- Use + 5.0V from Mateksys FCHUB. for servo actuation VDD, PWM from Orin.

- Example servos: MG996R (4.8-6.0V, 13kg) (0°-180°, Pulse length 500µs-2500µs)
- GPIO pin used for PWM generation shouldn't matter, consider PWM clock scaling in signal generation (1.25MHz)