

11.9) In Hoffman Vol II

Consider the system of partial differential equations given by:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + \frac{1}{\rho} \frac{\partial p}{\partial x} = 0$$

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + \frac{1}{\rho} \frac{\partial p}{\partial y} = 0$$

Where ρ is constant

a) Write the system in a vector form where the unknown vector Q :

$$Q = \begin{bmatrix} u \\ v \\ p \end{bmatrix}$$

Solution

$$\begin{bmatrix} 1 & 0 & 0 \\ u & 0 & \frac{1}{\rho} \\ 0 & u & 0 \end{bmatrix} \frac{\partial}{\partial x} \begin{bmatrix} u \\ v \\ p \end{bmatrix} + \begin{bmatrix} 0 & 1 & 0 \\ v & 0 & 0 \\ 0 & v & \frac{1}{\rho} \end{bmatrix} \frac{\partial}{\partial y} \begin{bmatrix} u \\ v \\ p \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

b) Recast the system of equations to a conservative form

Conservative Form System:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$\frac{\partial}{\partial x} \left(u^2 + \frac{p}{\rho} \right) + \frac{\partial}{\partial y} (uv) = 0$$

$$\frac{\partial}{\partial x} (uv) + \frac{\partial}{\partial y} \left(u^2 + \frac{p}{\rho} \right) = 0$$

Vector Form:

$$\frac{\partial E}{\partial x} + \frac{\partial F}{\partial y} = 0$$

$$\frac{\partial}{\partial x} \begin{bmatrix} u \\ u^2 + \frac{p}{\rho} \\ uv \end{bmatrix} + \frac{\partial}{\partial y} \begin{bmatrix} v \\ uv \\ v^2 + \frac{p}{\rho} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

to get $[A] \& [B]$

we should put the system in the following form :

$$\frac{\partial E}{\partial Q} \frac{\partial Q}{\partial x} + \frac{\partial F}{\partial Q} \frac{\partial Q}{\partial y} = 0$$

Where

$$[A] = \frac{\partial E}{\partial Q}, \quad [B] = \frac{\partial F}{\partial Q}, \quad [E] = \begin{bmatrix} u \\ u^2 + \frac{p}{\rho} \\ uv \end{bmatrix}, \quad [F] = \begin{bmatrix} v \\ uv \\ v^2 + \frac{p}{\rho} \end{bmatrix}, \quad [Q] = \begin{bmatrix} u \\ v \\ p \end{bmatrix}$$

$$\rightarrow [E] = \begin{bmatrix} Q_1 \\ Q_1^2 + \frac{Q_3}{\rho} \\ Q_1 Q_2 \end{bmatrix}$$

$$\rightarrow [F] = \begin{bmatrix} Q_2 \\ Q_1 Q_2 \\ Q_2^2 + \frac{Q_3}{\rho} \end{bmatrix}$$

$$[A] = \begin{bmatrix} \frac{\partial E_1}{\partial Q_1} & \frac{\partial E_1}{\partial Q_2} & \frac{\partial E_1}{\partial Q_3} \\ \frac{\partial E_2}{\partial Q_1} & \frac{\partial E_2}{\partial Q_2} & \frac{\partial E_2}{\partial Q_3} \\ \frac{\partial E_3}{\partial Q_1} & \frac{\partial E_3}{\partial Q_2} & \frac{\partial E_3}{\partial Q_3} \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2Q_1 & 0 & \frac{1}{\rho} \\ Q_2 & Q_1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2u & 0 & \frac{1}{\rho} \\ v & u & 0 \end{bmatrix}$$

$$[B] = \begin{bmatrix} \frac{\partial F_1}{\partial Q_1} & \frac{\partial F_1}{\partial Q_2} & \frac{\partial F_1}{\partial Q_3} \\ \frac{\partial F_2}{\partial Q_1} & \frac{\partial F_2}{\partial Q_2} & \frac{\partial F_2}{\partial Q_3} \\ \frac{\partial F_3}{\partial Q_1} & \frac{\partial F_3}{\partial Q_2} & \frac{\partial F_3}{\partial Q_3} \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ Q_2 & Q_1 & 0 \\ 0 & 2Q_2 & \frac{1}{\rho} \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ v & u & 0 \\ 0 & 2v & \frac{1}{\rho} \end{bmatrix}$$

Conservative Form System:

$$\begin{bmatrix} 1 & 0 & 0 \\ 2u & 0 & \frac{1}{\rho} \\ v & u & 0 \end{bmatrix} \frac{\partial}{\partial x} \begin{bmatrix} u \\ v \\ p \end{bmatrix} + \begin{bmatrix} 0 & 1 & 0 \\ v & u & 0 \\ 0 & 2v & \frac{1}{\rho} \end{bmatrix} \frac{\partial}{\partial y} \begin{bmatrix} u \\ v \\ p \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

c) Transform the vector form obtained in (b) to (ξ, η) coordinates

$$\frac{\partial E}{\partial x} + \frac{\partial F}{\partial y} = 0$$

Substitute by:

$$\begin{aligned}\frac{\partial E}{\partial x} &= \xi_x \frac{\partial E}{\partial \xi} + \eta_x \frac{\partial E}{\partial \eta} \\ \frac{\partial F}{\partial y} &= \xi_y \frac{\partial F}{\partial \xi} + \eta_y \frac{\partial F}{\partial \eta}\end{aligned}$$

We obtain:

$$\xi_x \frac{\partial E}{\partial \xi} + \eta_x \frac{\partial E}{\partial \eta} + \xi_y \frac{\partial F}{\partial \xi} + \eta_y \frac{\partial F}{\partial \eta} = 0$$

Divide by Jacobian $J = \frac{1}{x_\xi y_\eta - x_\eta y_\xi}$ and add & subtract some terms

$$\begin{aligned}& \frac{1}{J} \xi_x \frac{\partial E}{\partial \xi} + \frac{1}{J} \eta_x \frac{\partial E}{\partial \eta} + \left[E \frac{\partial}{\partial \xi} \left(\frac{\xi_x}{J} \right) - E \frac{\partial}{\partial \xi} \left(\frac{\xi_x}{J} \right) \right] + \left[E \frac{\partial}{\partial \eta} \left(\frac{\eta_x}{J} \right) - E \frac{\partial}{\partial \eta} \left(\frac{\eta_x}{J} \right) \right] \\ & + \frac{1}{J} \xi_y \frac{\partial F}{\partial \xi} + \frac{1}{J} \eta_y \frac{\partial F}{\partial \eta} + \left[F \frac{\partial}{\partial \xi} \left(\frac{\xi_y}{J} \right) - F \frac{\partial}{\partial \xi} \left(\frac{\xi_y}{J} \right) \right] + \left[F \frac{\partial}{\partial \eta} \left(\frac{\eta_y}{J} \right) - F \frac{\partial}{\partial \eta} \left(\frac{\eta_y}{J} \right) \right] = 0\end{aligned}$$

The added terms would help us to obtain a conservative form

Rearrange the equation

$$\begin{aligned}& \left[\frac{1}{J} \xi_x \frac{\partial E}{\partial \xi} + E \frac{\partial}{\partial \xi} \left(\frac{\xi_x}{J} \right) \right] + \left[\frac{1}{J} \eta_x \frac{\partial E}{\partial \eta} + E \frac{\partial}{\partial \eta} \left(\frac{\eta_x}{J} \right) \right] - E \left[\frac{\partial}{\partial \xi} \left(\frac{\xi_x}{J} \right) + \frac{\partial}{\partial \eta} \left(\frac{\eta_x}{J} \right) \right] \\ & + \left[\frac{1}{J} \xi_y \frac{\partial F}{\partial \xi} + F \frac{\partial}{\partial \xi} \left(\frac{\xi_y}{J} \right) \right] + \left[\frac{1}{J} \eta_y \frac{\partial F}{\partial \eta} + F \frac{\partial}{\partial \eta} \left(\frac{\eta_y}{J} \right) \right] - F \left[\frac{\partial}{\partial \xi} \left(\frac{\xi_y}{J} \right) + \frac{\partial}{\partial \eta} \left(\frac{\eta_y}{J} \right) \right] = 0\end{aligned}$$

Substitute by the following 4 relations in the **red brackets**:

$$\xi_x = J y_\eta$$

$$\eta_x = -J y_\xi$$

$$\xi_y = -J x_\eta$$

$$\eta_y = J x_\xi$$

$$\left[\frac{1}{J} \xi_x \frac{\partial E}{\partial \xi} + E \frac{\partial}{\partial \xi} \left(\frac{\xi_x}{J} \right) \right] + \left[\frac{1}{J} \eta_x \frac{\partial E}{\partial \eta} + E \frac{\partial}{\partial \eta} \left(\frac{\eta_x}{J} \right) \right] - E \left[\frac{\partial}{\partial \xi} (y_\eta) + \frac{\partial}{\partial \eta} (-y_\xi) \right] \\ + \left[\frac{1}{J} \xi_y \frac{\partial F}{\partial \xi} + F \frac{\partial}{\partial \xi} \left(\frac{\xi_y}{J} \right) \right] + \left[\frac{1}{J} \eta_y \frac{\partial F}{\partial \eta} + F \frac{\partial}{\partial \eta} \left(\frac{\eta_y}{J} \right) \right] - F \left[\frac{\partial}{\partial \xi} (-x_\eta) + \frac{\partial}{\partial \eta} (x_\xi) \right] = 0$$

$$\left[\frac{1}{J} \xi_x \frac{\partial E}{\partial \xi} + E \frac{\partial}{\partial \xi} \left(\frac{\xi_x}{J} \right) \right] + \left[\frac{1}{J} \eta_x \frac{\partial E}{\partial \eta} + E \frac{\partial}{\partial \eta} \left(\frac{\eta_x}{J} \right) \right] - E (y_{\eta\xi} - y_{\xi\eta}) \\ + \left[\frac{1}{J} \xi_y \frac{\partial F}{\partial \xi} + F \frac{\partial}{\partial \xi} \left(\frac{\xi_y}{J} \right) \right] + \left[\frac{1}{J} \eta_y \frac{\partial F}{\partial \eta} + F \frac{\partial}{\partial \eta} \left(\frac{\eta_y}{J} \right) \right] - F (-x_{\xi\eta} + x_{\eta\xi}) = 0$$

$$\left[\frac{1}{J} \xi_x \frac{\partial E}{\partial \xi} + E \frac{\partial}{\partial \xi} \left(\frac{\xi_x}{J} \right) \right] + \left[\frac{1}{J} \eta_x \frac{\partial E}{\partial \eta} + E \frac{\partial}{\partial \eta} \left(\frac{\eta_x}{J} \right) \right] \\ + \left[\frac{1}{J} \xi_y \frac{\partial F}{\partial \xi} + F \frac{\partial}{\partial \xi} \left(\frac{\xi_y}{J} \right) \right] + \left[\frac{1}{J} \eta_y \frac{\partial F}{\partial \eta} + F \frac{\partial}{\partial \eta} \left(\frac{\eta_y}{J} \right) \right] = 0$$

Now Each bracket can be considered as one derivative

$$\frac{\partial}{\partial \xi} \left(\xi_x \frac{E}{J} \right) + \frac{\partial}{\partial \eta} \left(\eta_x \frac{E}{J} \right) + \frac{\partial}{\partial \xi} \left(\xi_y \frac{F}{J} \right) + \frac{\partial}{\partial \eta} \left(\eta_y \frac{F}{J} \right) = 0$$

Rearranging:

$$\frac{\partial}{\partial \xi} \left(\xi_x \frac{E}{J} + \xi_y \frac{F}{J} \right) + \frac{\partial}{\partial \eta} \left(\eta_x \frac{E}{J} + \eta_y \frac{F}{J} \right) = 0$$

Simplify:

$$\frac{\partial \bar{E}}{\partial \xi} + \frac{\partial \bar{F}}{\partial \eta} = 0$$

Where

$$\bar{E} = \frac{1}{J} (\xi_x E + \xi_y F)$$

$$\bar{F} = \frac{1}{J} (\eta_x E + \eta_y F)$$

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