# Chapter 2: Vectors: Force & Position

#### **Basic Concepts** (2.1)

### Performing vector operations

Law of sines

$$\frac{A}{\sin \alpha} = \frac{B}{\sin \beta} = \frac{C}{\sin \gamma}$$

Law of cosines

$$A = \sqrt{B^2 + C^2 - 2BC \cos \alpha}$$

$$B = \sqrt{A^2 + C^2 - 2AC \cos \beta}$$

$$C = \sqrt{A^2 + B^2 - 2AB \cos \gamma}$$

## **Cartesian Representation of Vectors in 2D** (2.2)

#### Unit vector notation

$$\hat{u} = \frac{\vec{v}}{|\vec{v}|} = \cos\theta \,\hat{\imath} + \sin\theta \,\hat{\jmath}$$

#### General vector notation

$$\vec{v} = \vec{v}_x + \vec{v}_y = v_x \hat{\imath} + v_y \hat{\jmath}$$

$$\vec{v} = v(\cos\theta \, \hat{\imath} + \sin\theta \, \hat{\jmath}) = v(\cos\theta_x \, \hat{\imath} + \cos\theta_y \, \hat{\jmath})$$

$$|\vec{v}| = \sqrt{v_x^2 + v_y^2}$$

$$\theta = \tan^{-1} \frac{v_y}{v_x}$$

#### Vector transformations

$$\vec{v} = v_x \hat{\imath} + v_y \hat{\jmath} = v_t \hat{t} + v_n \hat{n}$$

To x and y...

$$v_x = v_t \cos \phi - v_n \sin \phi$$

$$v_y = v_t \sin \phi + v_n \cos \phi$$

To t and n...

$$v_t = v_x \cos \phi + v_y \sin \phi$$
$$v_n = -v_x \sin \phi + v_y \cos \phi$$

### **Cartesian Representation of Vectors in 3D (2.3)**

#### General vector notation

$$\vec{v} = \vec{v}_x + \vec{v}_y + \vec{v}_z = v_x \hat{\imath} + v_y \hat{\jmath} + v_z \hat{k}$$

$$v = \sqrt{v_x^2 + v_y^2 + v_z^2}$$

$$\vec{F} = F \frac{\vec{r}}{r}$$

## **Direction cosines**

$$\vec{v} = v(\cos \theta_x \,\hat{\imath} + \cos \theta_y \,\hat{\jmath} + \cos \theta_z \,\hat{k})$$

$$\cos^2 \theta_x + \cos^2 \theta_y + \cos^2 \theta_z = 1$$

$$\cos \theta_x = \frac{v_x}{v}; \cos \theta_y = \frac{v_y}{v}; \cos \theta_z = \frac{v_z}{v}$$

### **Vector Dot Product** (2.4)

#### Base definition

$$\vec{A} \cdot \vec{B} = A \cos \theta B$$

## **Properties**

$$\vec{A} \cdot \vec{B} = \vec{B} \cdot \vec{A}$$

$$s(\vec{A} \cdot \vec{B}) = (s\vec{A}) \cdot \vec{B} = \vec{A} \cdot (s\vec{B})$$

$$(\vec{A} + \vec{B}) \cdot \vec{C} = (\vec{A} \cdot \vec{C}) + (\vec{B} \cdot \vec{C})$$

### Cartesian coordinates

$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$$
$$\vec{A} \cdot \vec{B} = \begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} \cdot \begin{bmatrix} B_x \\ B_y \\ B_z \end{bmatrix}$$

## Component of a vector in a particular direction

$$\begin{split} F_{parallel} &= F_{||} = \vec{F} \cdot \frac{\vec{r}}{r} \\ F^2 &= F_{\perp}^2 + F_{||}^2 \\ \vec{F} &= \vec{F}_{\perp} + \vec{F}_{||} \end{split}$$

## **Vector Cross Product** (2.5)

### Base definition

$$|\vec{A} \times \vec{B}| = A \sin \theta B$$

## **Properties**

$$\vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$$

$$s(\vec{A} \times \vec{B}) = (s\vec{A}) \times \vec{B} = \vec{A} \times (s\vec{B})$$

$$(\vec{A} + \vec{B}) \times \vec{C} = (\vec{A} \times \vec{C}) + (\vec{B} \times \vec{C})$$

## Cartesian coordinates

$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{\imath} & \hat{\jmath} & \hat{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

### Scalar triple product

$$(\vec{A} \times \vec{B}) \cdot \vec{C} = \begin{vmatrix} C_x & C_y & C_z \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$