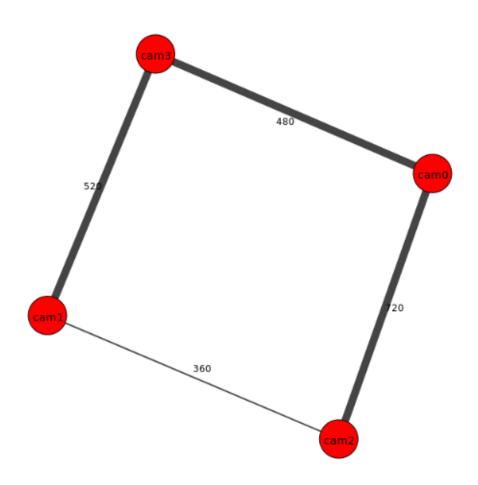
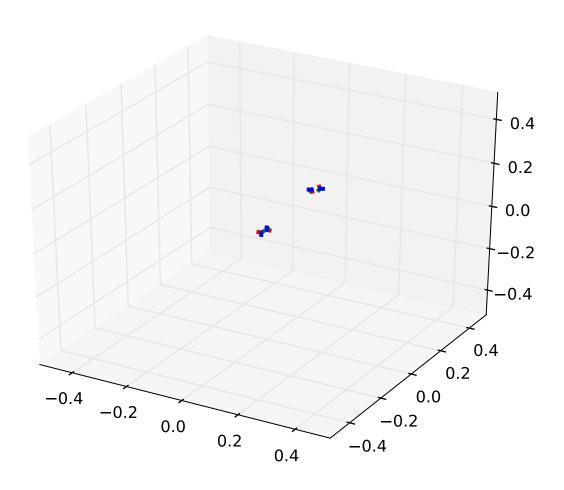
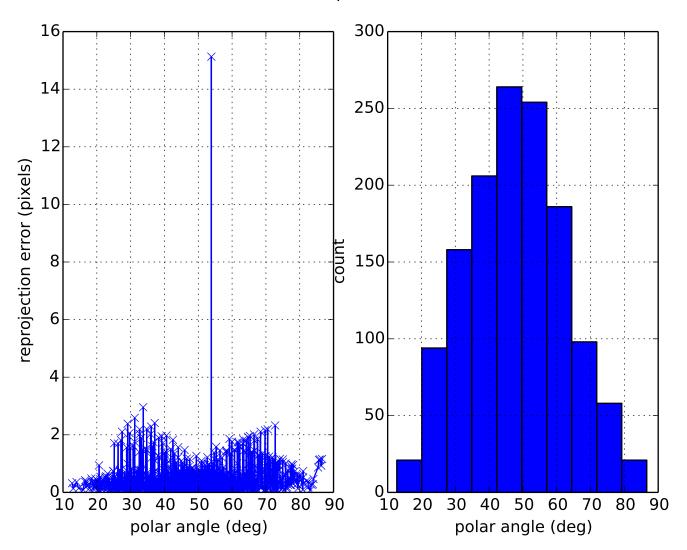
Inter-camera observations graph (edge weight=#mutual obs.)



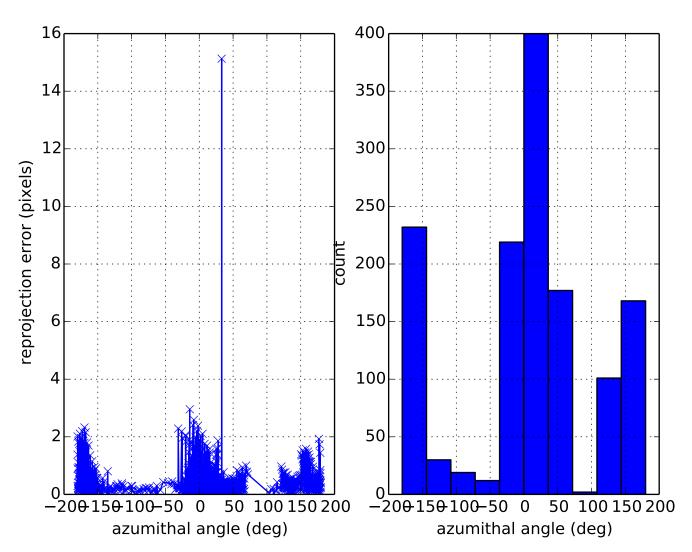
camera system



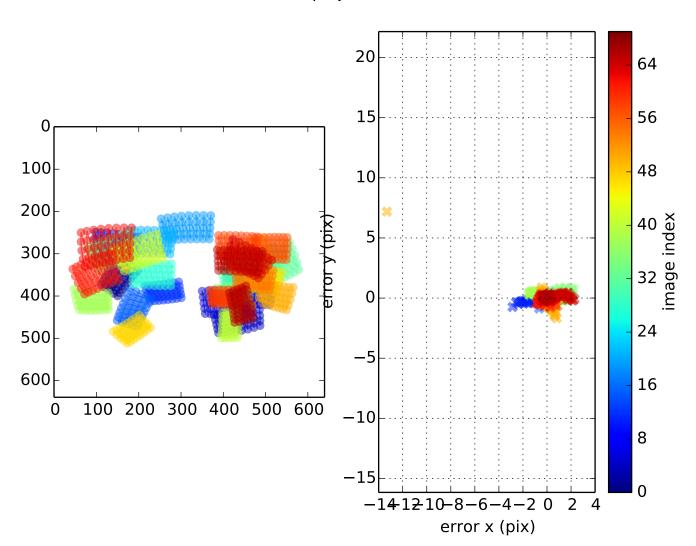
cam0: polar error



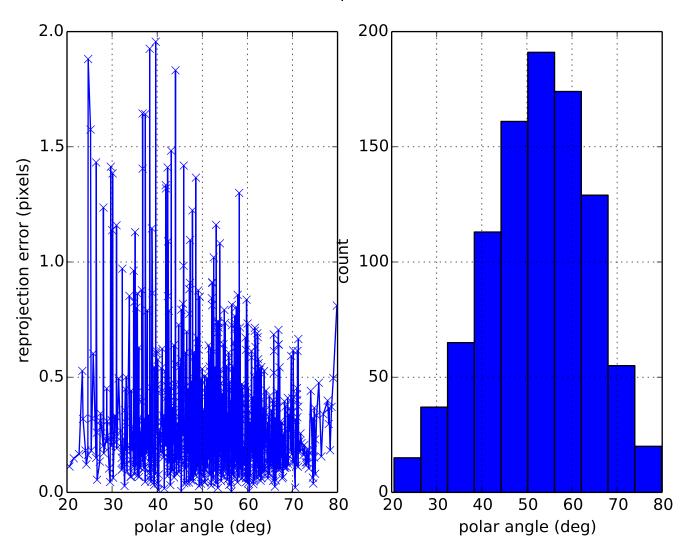
cam0: azimutal error



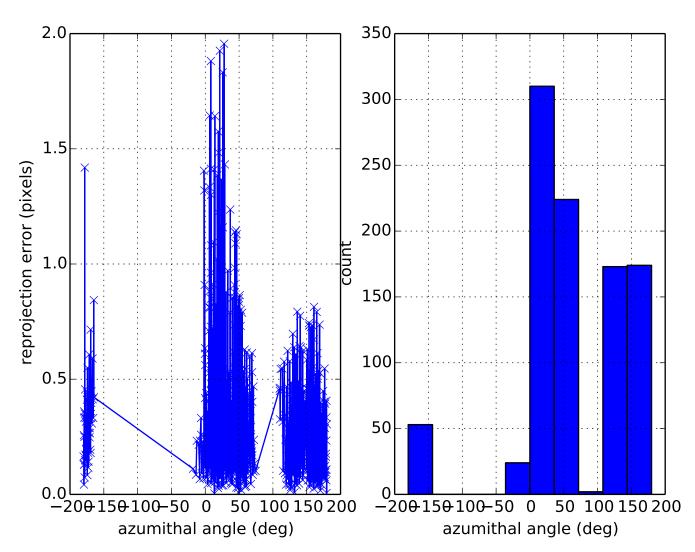
cam0: reprojection errors



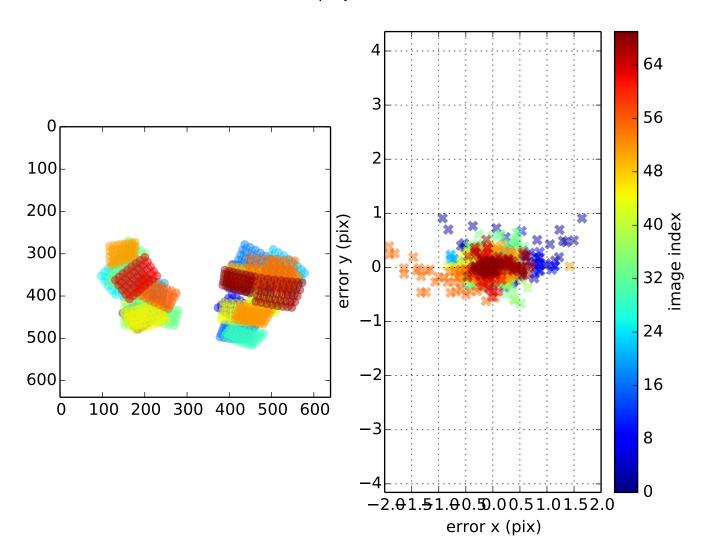
cam1: polar error



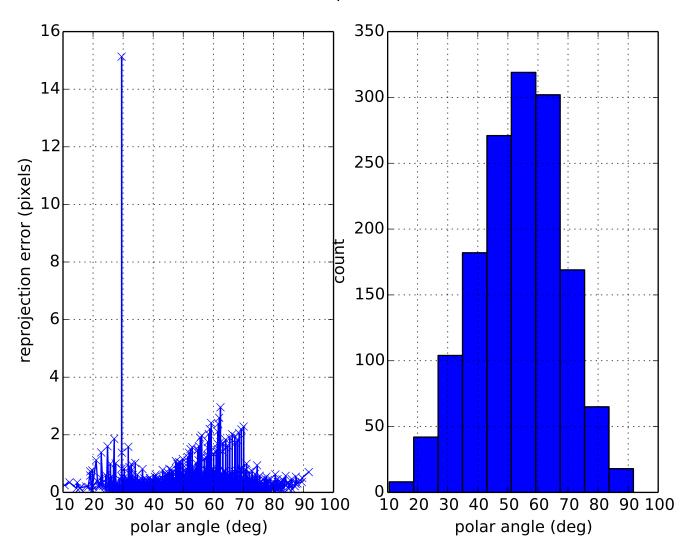
cam1: azimutal error



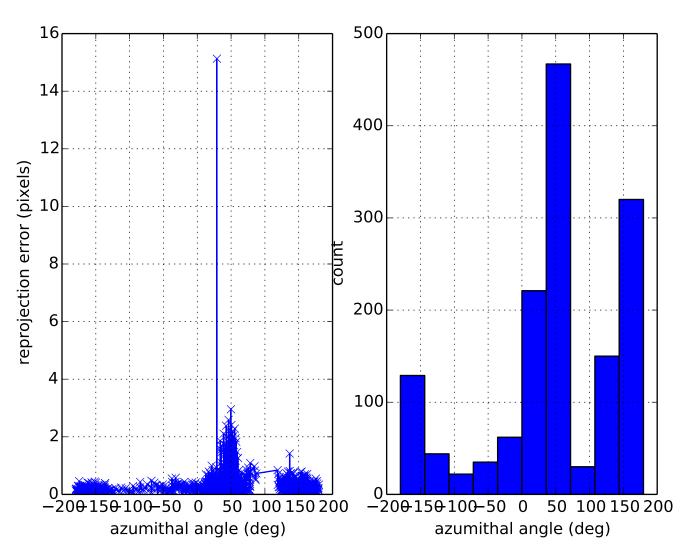
cam1: reprojection errors



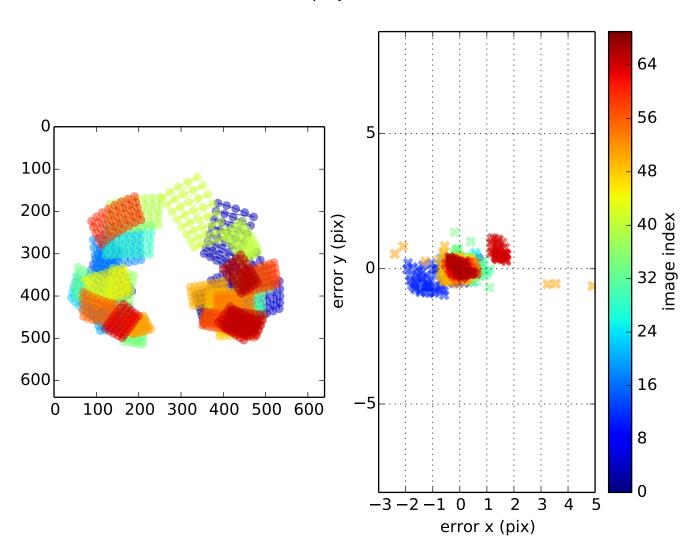
cam2: polar error



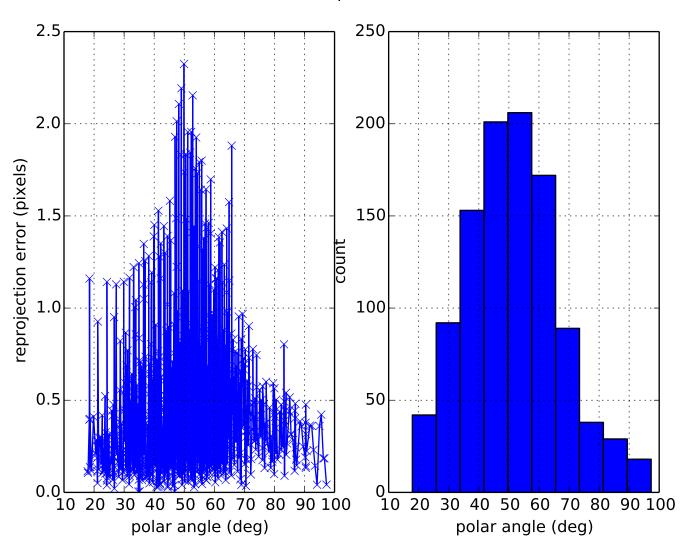
cam2: azimutal error



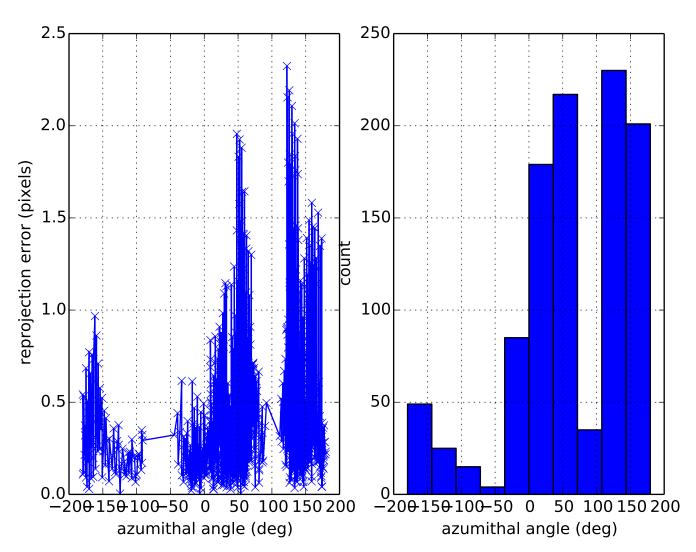
cam2: reprojection errors



cam3: polar error



cam3: azimutal error



cam3: reprojection errors

