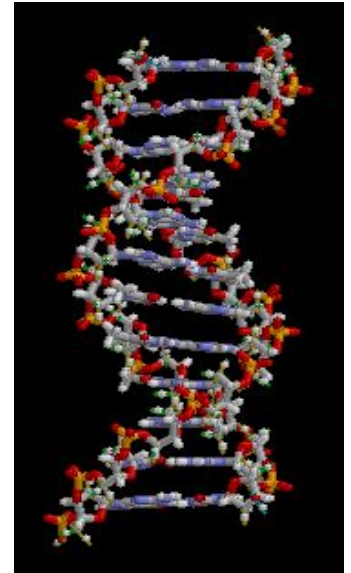
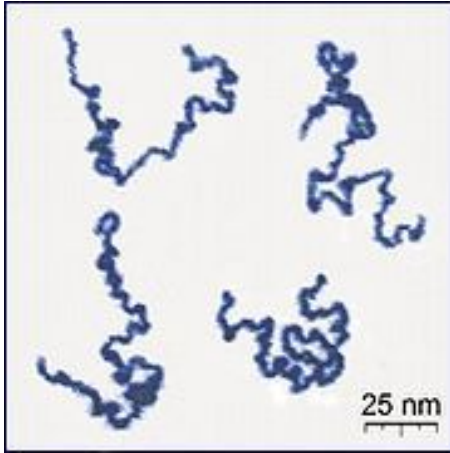


Modelling Polymer Dynamics

Robert Jomar Malate
PS10 Final Project

Polymers

- “Substance or material consisting of large macromolecules with repeating subunits” ([Wikipedia](#))



Movement

- Based on Boltzmann Distribution
- Due to thermal fluctuations

$$P(X) = Ae^{\frac{-\epsilon_i}{k_B T}}$$

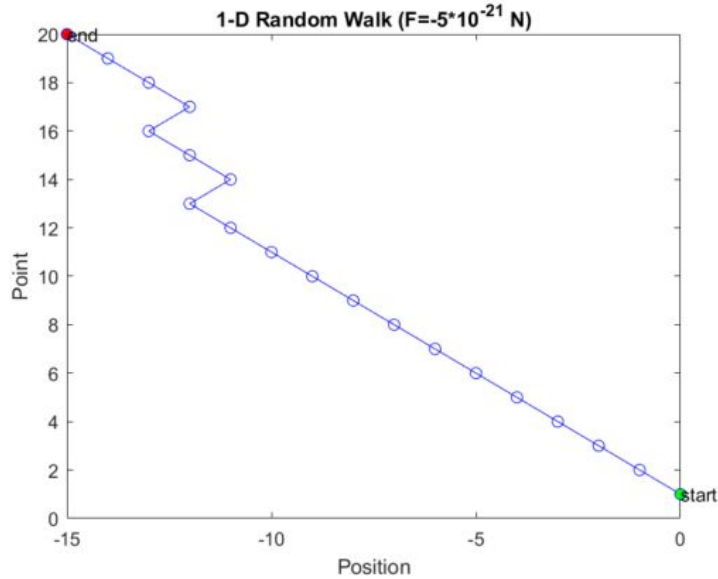
1D Polymer Dynamics

Probability Distribution (1D)

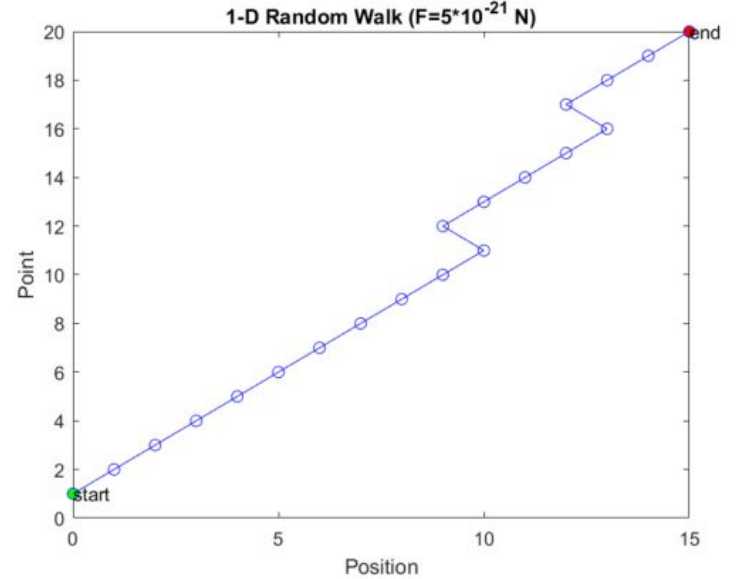
$$P(L|R) = \frac{e^{\frac{-\epsilon_i}{k_B T}}}{2 \cosh\left(\frac{FL}{k_B T}\right)}$$

$$\epsilon_i = \pm FL$$

Polymer 1D Simulation Results



**Leftward
Force**



**Rightward
Force**

2D Polymer Dynamics

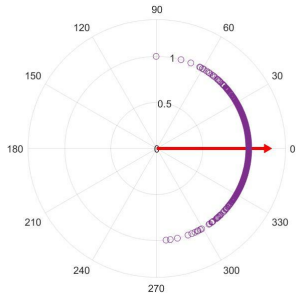
Probability Distribution (2D)

$$P(\theta) = A e^{\frac{-\epsilon_i}{k_B T}}$$

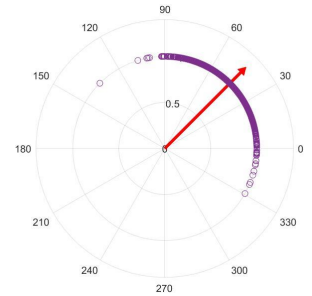
$$A = \frac{1}{\int_0^{2\pi} e^{\frac{-\epsilon_i}{k_B T}} d\theta}$$

$$\epsilon_i = -\vec{L} \cdot \vec{F} = -L \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix} \cdot \begin{bmatrix} F_x \\ F_y \end{bmatrix}$$

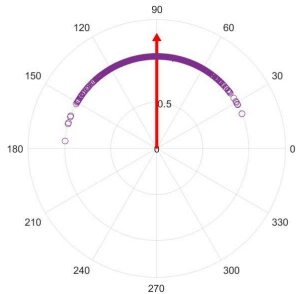
Probability Distribution (2D)



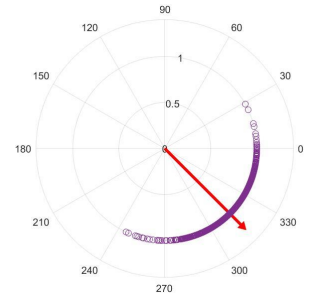
Rightward Force
 $\theta=0$ rad.



Up-Right Force
 $\theta=\pi/4$ rad.



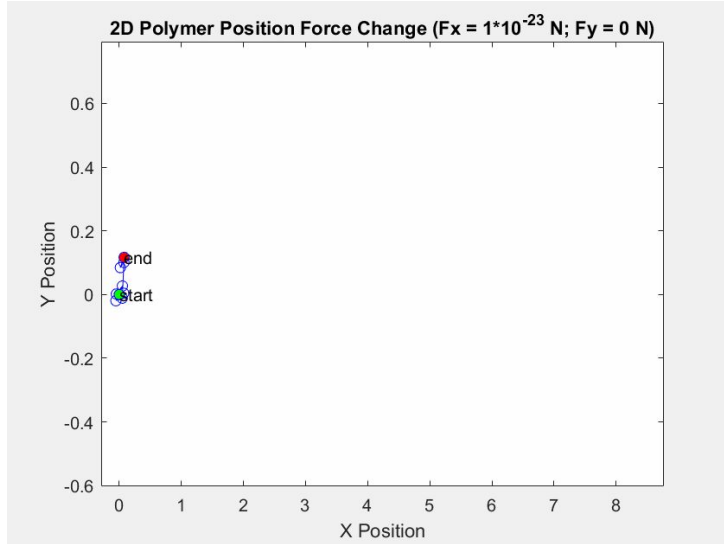
Upward Force
 $\theta=\pi/2$ rad.



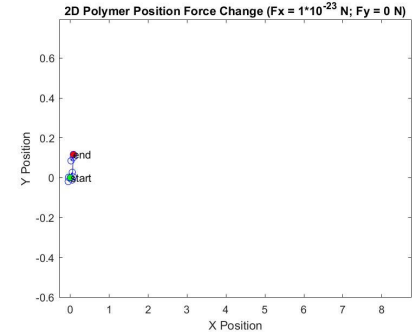
Down-Right Force
 $\theta=-\pi/4$ rad.

Increasing Force (2D)

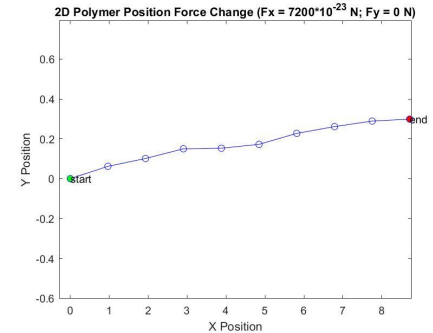
$$P(\theta) = Ae^{\frac{-\vec{L} \cdot \vec{F}}{k_B T}}$$



Start
position

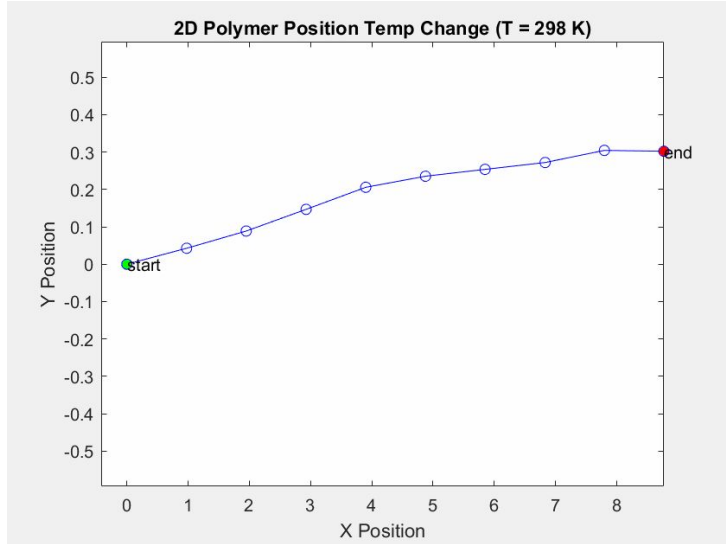


End
position

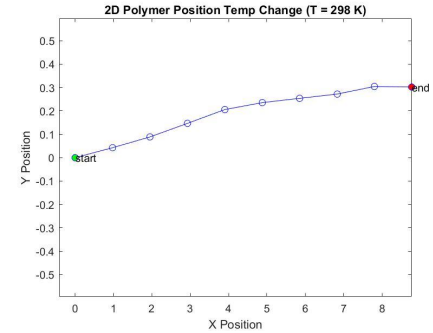


Increasing Temperature (2D)

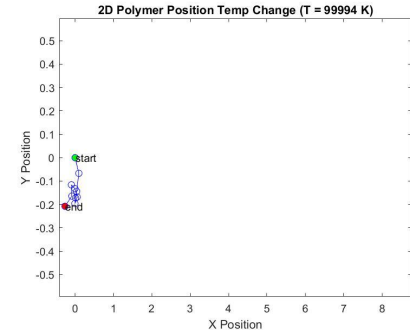
$$P(\theta) = Ae^{\frac{-\vec{L} \cdot \vec{F}}{k_B T}}$$



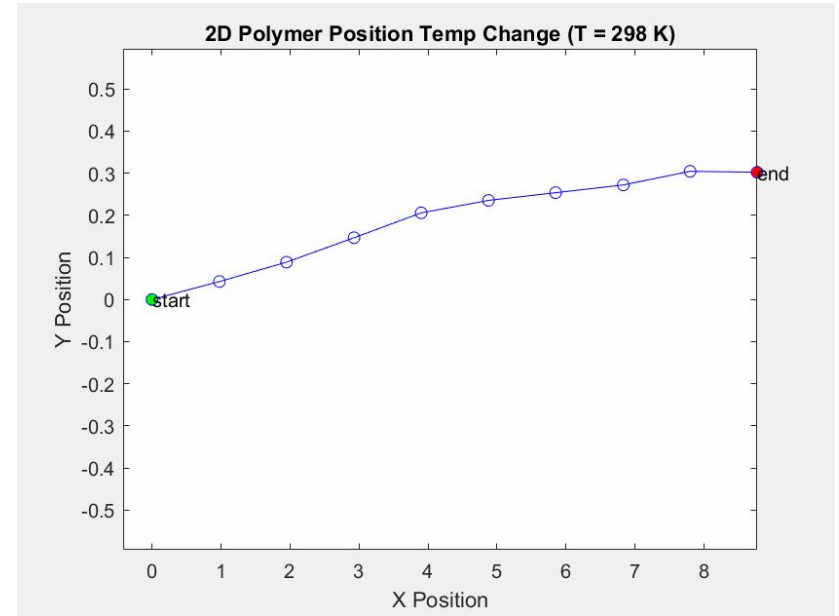
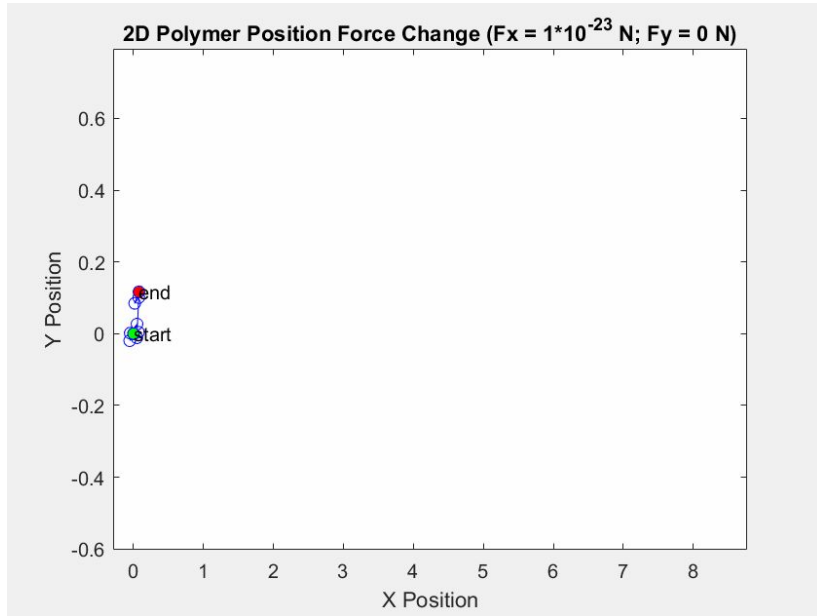
Start
position



End
position



Polymer 2D Simulation Results



3D Polymer Dynamics

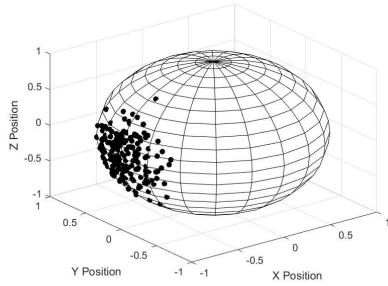
Probability Distribution (3D)

$$P(\theta) = A e^{\frac{-\epsilon_i}{k_B T}}$$

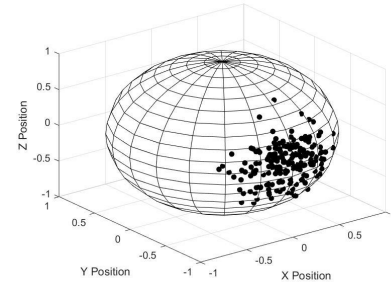
$$A = \frac{1}{\int_0^\pi \int_0^{2\pi} e^{\frac{-\epsilon_i}{k_B T}} d\theta d\phi}$$

$$\epsilon_i = -\vec{L} \cdot \vec{F} = -L \begin{bmatrix} \sin \phi \cos \theta \\ \sin \phi \sin \theta \\ \cos \phi \end{bmatrix} \cdot \begin{bmatrix} F_x \\ F_y \\ F_z \end{bmatrix}$$

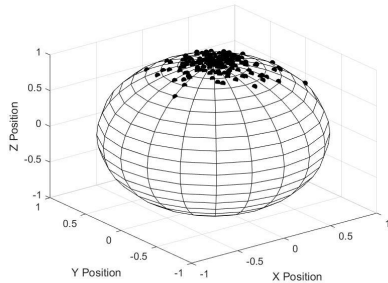
Probability Distribution (3D)



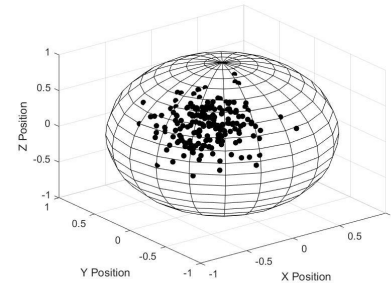
X Force
 $[F \ 0 \ 0]^T$



Y Force
 $[0 \ F \ 0]^T$



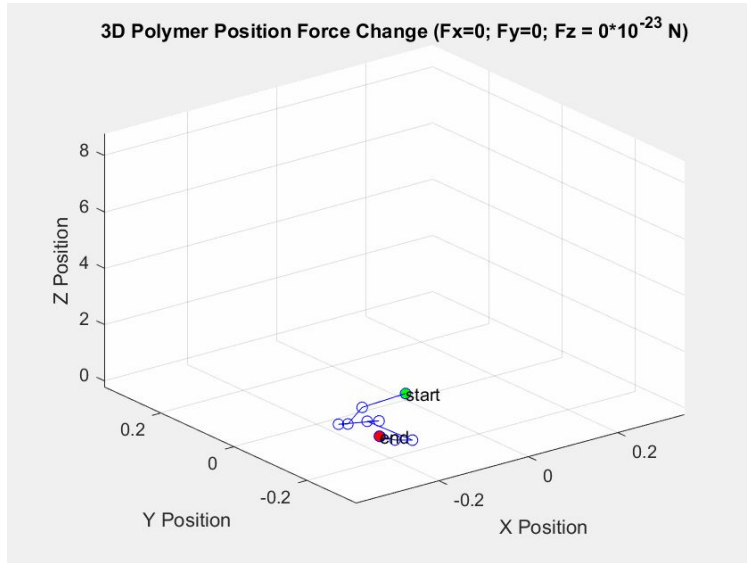
Z Force
 $[0 \ 0 \ F]^T$



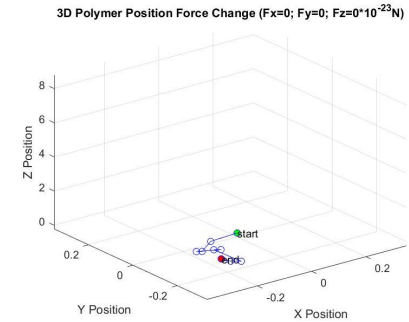
XYZ Force
 $[-F \ -F \ F]^T$

Increasing Force (3D)

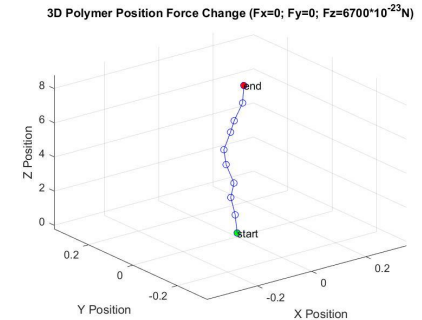
$$P(\theta, \phi) = A e^{\frac{-\vec{L} \cdot \vec{F}}{k_B T}}$$



Start
position

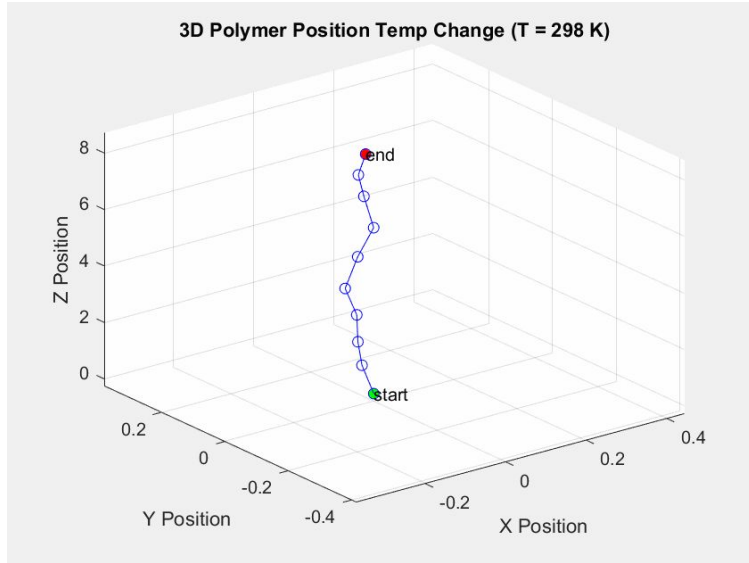


End
position

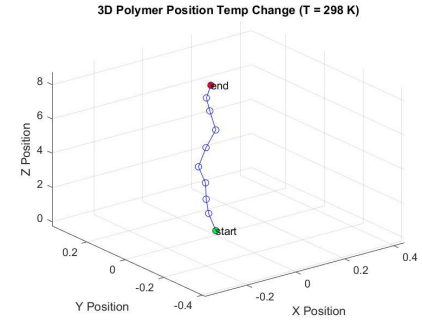


Increasing Temperature (3D)

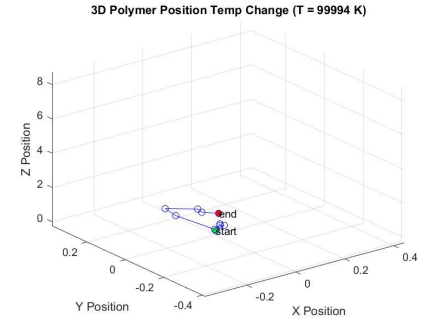
$$P(\theta, \phi) = A e^{\frac{-\vec{L} \cdot \vec{F}}{k_B T}}$$



**Start
position**



**End
position**



Polymer 3D Simulation Results

